In Summaker motorism

$$\hat{\beta} = \underbrace{\sum x_i y_i}_{i} , \quad SE(\hat{\beta}) = \sqrt{\underbrace{\sum (y_i - x_i \hat{\beta})^2}_{(m-1)}} \times \underbrace{x_i^2}_{(m-1)} \times \underbrace{x_i^2}_{i}$$

$$\frac{1}{5 \text{ sabspic}} = \frac{\hat{\beta}}{SE(\hat{\beta})} = \frac{\hat{\beta}}{\sqrt{\sum (y_i - x_i \hat{\beta})^2}} \times \underbrace{\frac{1}{\sqrt{\sum (y_i - x_i \hat{\beta})^2}}}_{\sqrt{\sum (y_i - x_i \hat{\beta})^2}} \times \underbrace{\frac{1}{\sqrt{\sum (y_i - x_i \hat{\beta})^2}}}_{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}} \times \underbrace{\frac{1}{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}}}_{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}} \times \underbrace{\frac{1}{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}}}_{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}} \times \underbrace{\frac{1}{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}}}_{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}} \times \underbrace{\frac{1}{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}}}_{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}} \times \underbrace{\frac{1}{\sqrt{\sum (y_i - \hat{\beta} x_i)^2}}}_{\sqrt{y_i - x_i - x_i}} \times \underbrace{\frac{1}{\sqrt{y_i - x_i}}}_{\sqrt{y_i - x_i - x_i}} \times \underbrace{\frac{1}{\sqrt{y_i - x_i}}}_{\sqrt{y_i - x_i}} \times \underbrace{\frac{1}{\sqrt{x_i - x_i}}}_{\sqrt{x_i - x_i}}} \times \underbrace{\frac{1}{\sqrt{x_i - x_i}}}_{\sqrt{x_i - x_i}} \times$$