Trong N. Nguyen

Contact Information

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Summary

I have had a passion for vision system and AI since I was a undergraduate student. I am currently a Ph.D. candidate in Computer Vision. My current goal is to improve my knowledge as well as technical and communication skills by looking for opportunities working on realistic projects. I am friendly, self-motivated, and independent.

Education

Present — Ph.D. in Computer Science, **University of Montreal**, Montreal, QC, Canada
Dissertation: "Human gait analysis using a depth camera and mirrors"
Supervisor: Prof. Jean Meunier
Project focuses on:
- Examining depth estimation in a setup of a depth camera and 2 mirrors
- Reconstructing 3D point cloud in this setup
- Estimating human walking gait normality index
- Technique: OpenCV, PCL, deep learning

Jan 2015 — M.Sc. in Computer Science, **The University of Danang**, Danang, Vietnam
Thesis: "Human gait analysis using one camera"
Advisor: Huu Hung Huynh, PhD
Thesis score 8.9/10 - rank 1st
Project focuses on:
- Feature extraction on a sequence of 2D human gait silhouettes
- Building a model of normal gait cycles
- Detecting abnormal walking gaits
- Technique: Matlab, HMM

Jun 2012 — B.Sc. in Information Technology, **University of Science & Technology**
Thesis: "Detecting fake-folder executable files using neural network"
Advisor: Huu Hung Huynh, PhD
Thesis score 9.6/10
Project focuses on:
- Typical methods related to Image Processing and Machine Learning
- Designing neural network working on hand-crafted color features
- Technique: C#, OOP

Scholarships by University of Montreal

Excellence	Department of Computer Science and Operations Research Fall (2015, 2016, 2017, 2018), Winter (2016, 2017, 2018, 2019)
End of Doctoral	Faculty of Graduate and Postdoctoral Studies 12 months for the academic year 2018-2019

Work Experience

Jul 2014 - Aug 2015 — Research assistant at Vision Laboratory
University of Science and Technology (Danang, Vietnam)
Project: Vision-based hand gesture recognition
Developed algorithms for recognizing hand gestures in both static and dynamic forms. These methods worked on depth images and 2D silhouettes.

Mar 2014 - Jun 2014 — Intern at Vision Laboratory
University of Montreal (Montreal, QC, Canada)
Project: Abnormal gait detection with one camera using HMM
Developed an algorithm for detecting various types of anomalous walking gaits given a sequence of side-view silhouettes.

Languages

Vietnamese: Mothertongue
English: Fluent

Computer Skills

Programming: C#, C++, Matlab, Mathematica, Python
Technologies: Accord.NET, OpenCV, Point Cloud Library, TensorFlow, Scikit-learn

Services

I have been an external reviewer for the following journals: IEEE Access (IEEE), Sensors (MDPI), Applied Sciences (MDPI), SN Applied Sciences (Springer).

References

Jean Meunier
Full Professor | Vision laboratory
DIRO, University of Montreal (Montreal, QC, Canada)
Room 2387, André-Aisenstadt Building
Contact: meunier@iro.umontreal.ca

Hoang Anh Nguyen
PhD, Sr. Perception Engineer
Aeva Inc., Mountain View, CA, US
Contact: hoang@aeva.ai

Academic publications

Journal

Estimation of gait normality index based on point clouds through deep auto-encoder (Accepted)
T. N. Nguyen and J. Meunier
EURASIP Journal on Image and Video Processing, SpringerOpen, 2019

Applying adversarial auto-encoder for estimating human walking gait abnormality index
T. N. Nguyen and J. Meunier
Pattern Analysis and Applications, Springer, 2019

Measurement of human gait symmetry using body surface normals extracted from depth maps
T. N. Nguyen, H. H. Huynh and J. Meunier
Sensors, MDPI, vol. 19, issue 4 (891), 2019

Human gait symmetry assessment using a depth camera and mirrors
T. N. Nguyen, H. H. Huynh and J. Meunier
Computers in Biology and Medicine, Elsevier, vol. 101, pp. 174-183, 2018

3D reconstruction with time-of-flight depth camera and multiple mirrors
T. N. Nguyen, H. H. Huynh and J. Meunier
IEEE Access, IEEE, vol. 6, pp. 38106-38114, 2018

Skeleton-based abnormal gait detection
T. N. Nguyen, H. H. Huynh and J. Meunier
Sensors, MDPI, vol. 16, issue 11 (1792), 2016

Conference

Assessment of gait normality using a depth camera and mirrors
T. N. Nguyen, H. H. Huynh and J. Meunier
IEEE Conf. on Biomedical and Health Informatics, USA, 2018

Matching-based depth camera and mirrors for 3D reconstruction
T. N. Nguyen, H. H. Huynh and J. Meunier
SPIE 3D Imaging, Visualization, and Display, USA, 2018

Skeleton-based gait index estimation with LSTMs
T. N. Nguyen, H. H. Huynh and J. Meunier
IEEE Int. Conf. on Computer and Information Science, Singapore, 2018

Estimating skeleton-based gait abnormality index by sparse deep auto-encoder
T. N. Nguyen, H. H. Huynh and J. Meunier
IEEE Int. Conf. on Communications and Electronics, Vietnam, 2018

Abnormal gait detection with one camera using hidden Markov model
T. N. Nguyen, H. H. Huynh and J. Meunier
IEEE Int. Conf. on Computing and Communication Tech., Vietnam, 2015

Conference (cont.)

Recognizing Vietnamese sign language based on rank matrix
D. H. Vo, **T. N. Nguyen**, H. H. Huynh and J. Meunier
IEEE Int. Conf. on Advanced Technologies for Communications, Vietnam, 2015

Geometry-based static hand gesture recognition using support vector machine
T. N. Nguyen, D. H. Vo, H. H. Huynh and J. Meunier
IEEE Int. Conf. on Control Auto. Robotics & Vision, Singapore, 2014

Extracting silhouette-based characteristics for human gait analysis using one camera
T. N. Nguyen, H. H. Huynh and J. Meunier
ACM Sym. on Information and Communication Technology, Vietnam, 2014

Modeling dynamic hand gesture based on geometric features
D. H. Vo, H. H. Huynh and **T. N. Nguyen**
IEEE Int. Conf. on Advanced Tech. for Communications, Vietnam, 2014

Traffic sign recognition using gabor filters and artificial neural network
H. H. Huynh, **T. N. Nguyen** and J. Meunier
IEEE Int. Conf. on Computing and Communication Tech., Vietnam, 2013

Real-time video-based fall detection using motion gradients
H. H. Huynh, **T. N. Nguyen** and J. Meunier
IEEE Int. Sym. on Signal Proc. and Information Technology, Vietnam, 2012