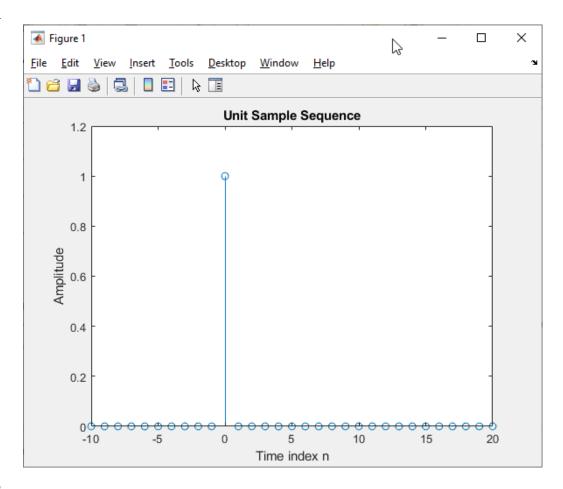
MDISCRETE-TIME SIGNALS: TIME-DOMAIN REPRESENTATION

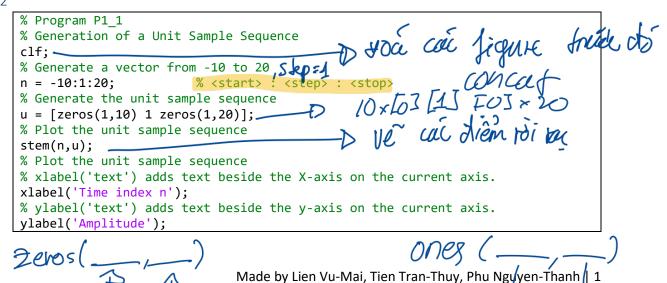
GENERATION OF SEQUENCES

1.1 UNIT SAMPLE AND UNIT STEP SEQUENCES

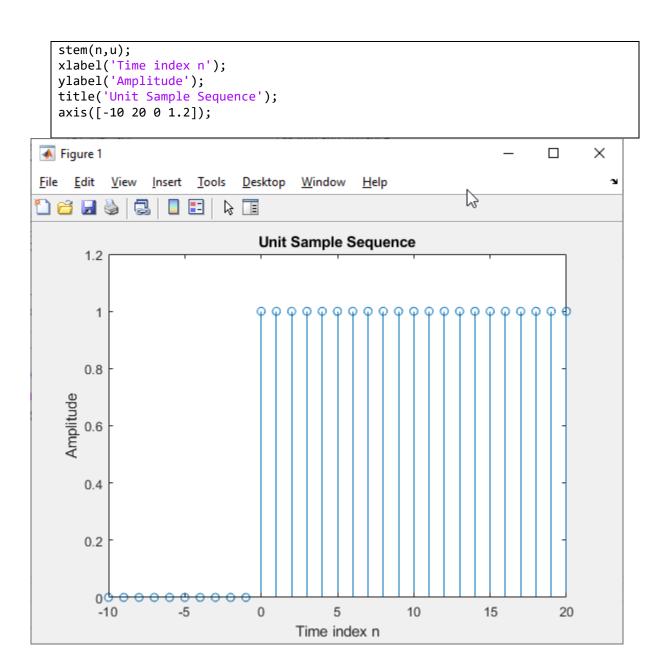
Q1.1



Q1.2

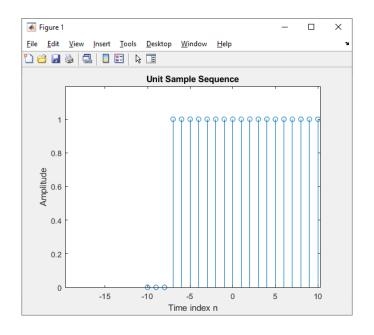


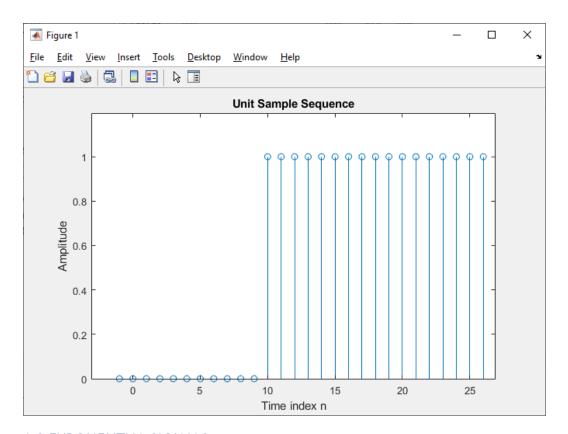
```
title('txt') adds the specified title to the axes or chart returned by
      %
            the gca command. Reissuing the title command causes the new title to
      %
            replace the old title.
      title('Unit Sample Sequence');
      % Control axis scaling and appearance.
      axis([-10 20 0 1.2]);
Q1.3
      clf;
      n = 0:1:20;
      u = [zeros(1,11) \ 1 \ zeros(1,10)];
      stem(n,u);
      xlabel('Time index n');
      ylabel('Amplitude');
      title('Unit Sample Sequence');
      axis([-10 20 0 1.2]);
      📣 Figure 1
          <u>E</u>dit
                <u>V</u>iew
                      Insert
                             Tools
                                    Desktop
                                             Window
                                                      <u>H</u>elp
                                    I
                                    Unit Sample Sequence
            1.2
             1
            0.8
            0.4
            0.2
             0
                         -5
              -10
                                    0
                                               5
                                                          10
                                                                     15
                                                                               20
                                          Time index n
Q1.4
      clf;
      n = -10:1:20;
      u = [zeros(1,10) \ 1 \ ones(1,20)];
```



The modified Program P1_1 to generate a unit step sequence sd[n] with an advance of 7 samples is given below along with the sequence generated by running this program.

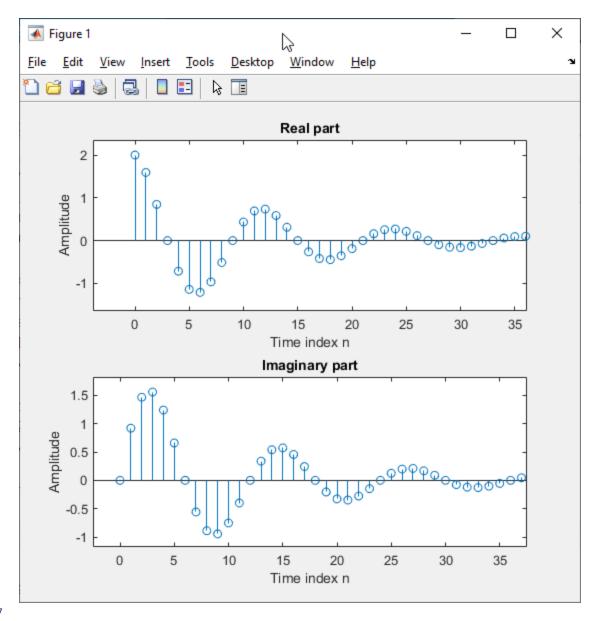
```
clf;
n = -10:1:10;
u = [zeros(1,3) ones(1,7) 1 ones(1,10)];
stem(n,u);
xlabel('Time index n');
ylabel('Amplitude');
title('Unit Sample Sequence');
axis([-10 20 0 1.2]);
```





1.2 EXPONENTIAL SIGNALS

Q1.6 The complex-valued exponential sequence generated by running Program P1_2 is shown below:

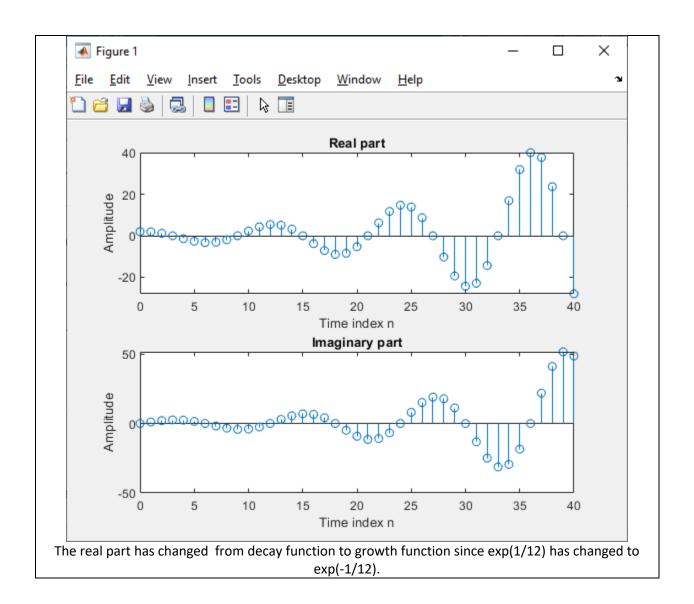


Q1.7

The parameter controlling the rate of growth or decay of this sequence is: c The parameter controlling the amplitude of this sequence is: K

Q1.8

The result of changing the parameter c to (1/12)+(pi/6)*i is:



The purpose of the operator real is – to extract the real part of a Matlab vector.

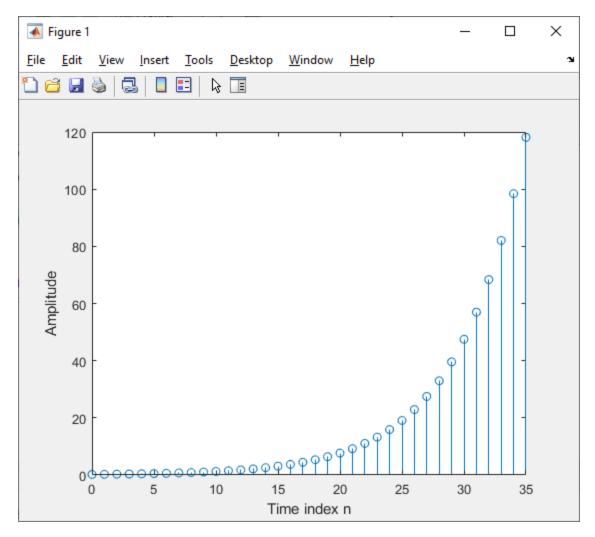
The purpose of the operator imag is – to extract the imaginary part of a Matlab vector.

Q1.10

The purpose of the command subplot is – to plot more than one graph in the same Matlab figure.

Q1.11

The real-valued exponential sequence generated by running Program P1_3 is shown below:



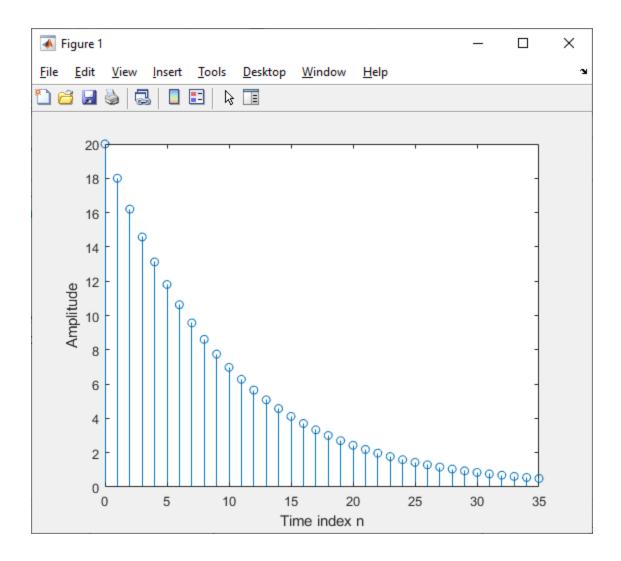
The parameter controlling the rate of growth or decay of this sequence is - a The parameter controlling the amplitude of this sequence is - K

Q1.13

The difference between the arithmetic operators ^ and _ is - "^" raises a square matrix to a power using matrix multiplication. ".^" raises the elements of a matrix or vector to a power; this is a "pointwise" operation.

Q1.14

The sequence generated by running Program P1_3 with the parameter a changed to 0.9 and the parameter K changed to 20 is shown below:



The length of this sequence is: 36 elemets – since n has 36 items.

It is controlled by the following MATLAB command line: n = 0:35; 30 35

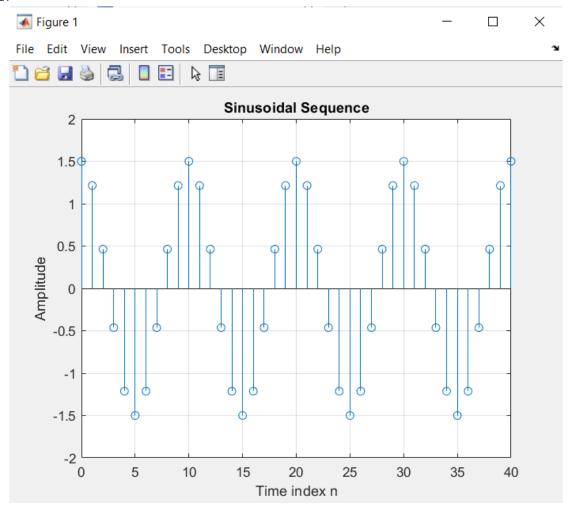
It can be changed to generate sequences with different lengths as follows (give an example command line and the corresponding length): n = 0.99; makes the length 100.

Q1.16

The energies of the real-valued exponential sequences x[n]generated in Q1.11 and Q1.14 and computed using the command sum are - 4.5673e+004 and 2.1042e+003.

1.3 SINUSOIDAL SEQUENCES

Q1.17



Q1.18

The frequency of this sequence is f = 0.1

It is controlled by following MATLAB command line: f = 0.1

A sequence with new length 0.2 can be generated by the following command line: f = 0.2

The parameter controlling the phase of this sequence is: phase

The parameter controlling the amplitude of this sequence is: A

The period of this sequence is 1/f = 10

Q1.19

The length of this sequence is 41 elemets

It is controlled by following MATLAB command line: n = 0:40

A sequence with new length 20 can be generated by the following command line: n = 0:19

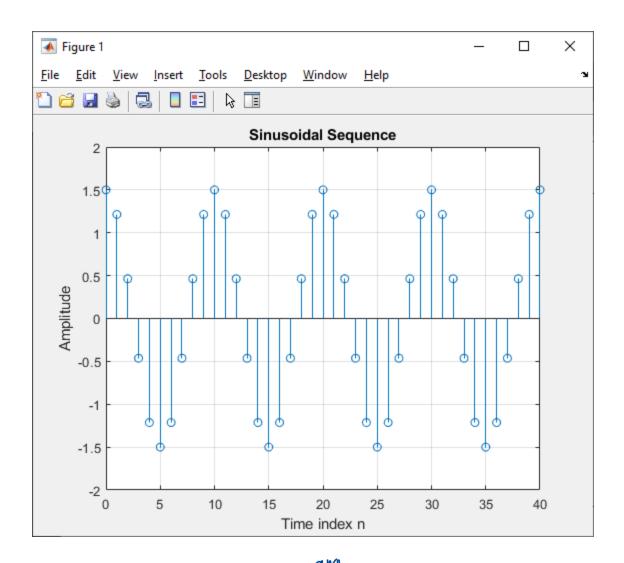
The average power of the generated sinusoidal sequence is 1.152439024390244 (unit of power)

Q1.21

The purpose of *axis* command is to set the range of the x-axis to [0,40] and the range of the y-axis to [-2,2].

The purpose of *grid* command is to turn on the drawing of grid lines on the graph.

```
Q1.22
% Program P1_4
% Generation of a sinusoidal sequence
 n = 0:40;
 f = 0.9;
 phase = 0;
 A = 1.5;
 arg = 2*pi*f*n - phase;
x)= A*cos(arg);
ćlf; 🛑
                     % Clear old graph
 stem(n,x);
                     % Plot the generated sequence
axis([0 40 -2 2]);
 grid;
 title('Sinusoidal Sequence');
 xlabel('Time index n');
 ylabel('Amplitude');
 axis;
 %n = 0:9;
 y = x.^2;
 P = (1/length(y))*sum(y);
```



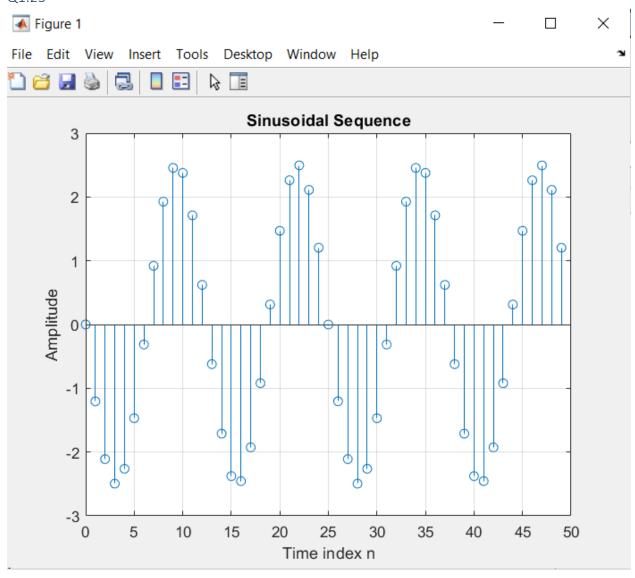
A comparison of this new sequence with the one generated in Question Q1.17 shows: the two graphs are identical. Since the arg in both case (f=0,1) and f=0,9 is opposite $(\cos(x) = \cos(-x))$.

 $\frac{1}{2} \cos(2n \cdot 0.1 \cdot n)$ $\frac{1}{4} \cos(2n \cdot 0.9 \cdot n)$ $\frac{1}{4} \cos(2n \cdot 0.9 \cdot n)$ $\frac{1}{4} \cos(2n \cdot 0.9 \cdot n)$ $\frac{1}{4} \cos(2n \cdot 0.1 \cdot n)$ $\frac{1}{4} \cos(2n \cdot 0.1 \cdot n)$ $\frac{1}{4} \cos(2n \cdot n) \cos(2n \cdot n)$ $\frac{1}{4} \cos(2n$

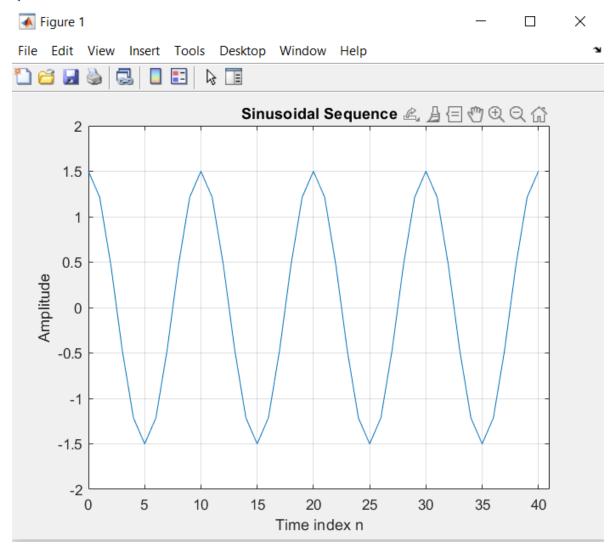
Made by Lien Vu-Mai, Tien Tran-Thuy, Phu Nguyen-Thanh | 11

cos (2010,1)



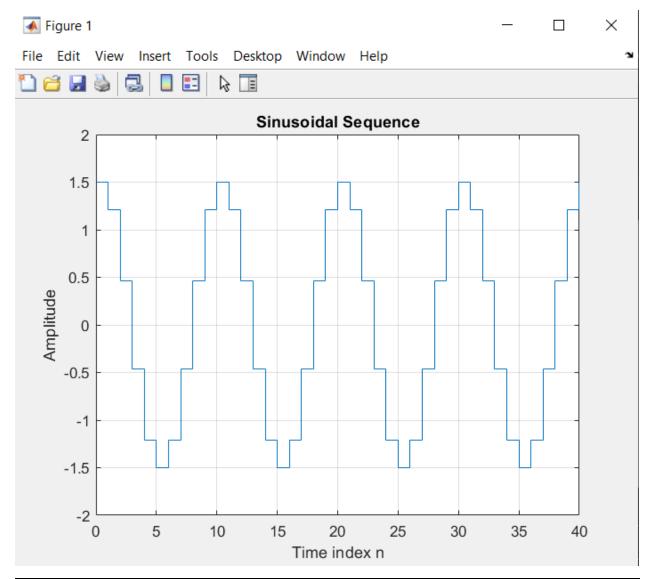


The period of this sequence is 1/f = 12,5



The difference between the new plot and those generated in Question Q1.17 and Q1.24 is discrete to continuous

Q1.25 By replacing the stem command in Program P1_4 with the stairs command the plot obtained is as shown below:



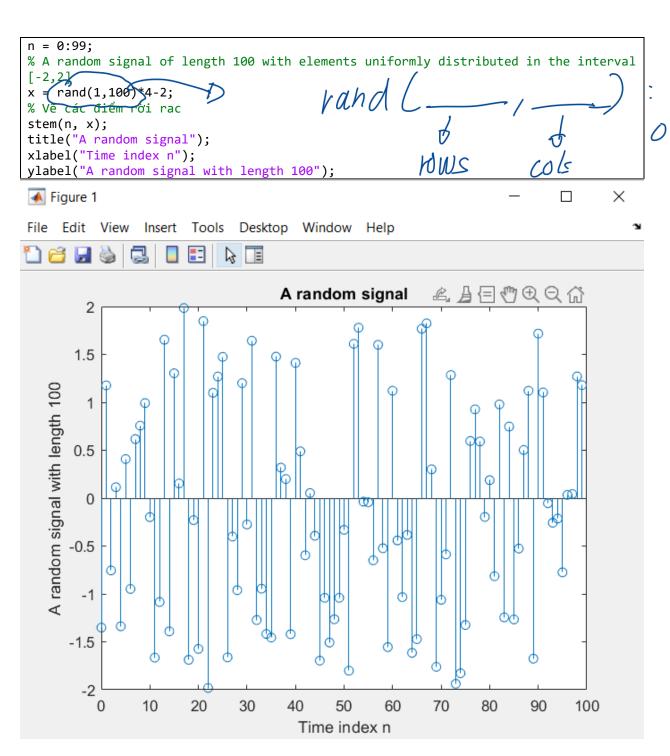
The difference between the new plot and those generated in Question Q1.17 and Q1.24 is from discrete to continuous

1.4 RANDOM SIGNALS

Q1.26

The MATLAB program to generate and display a random signal of length 100 with elements uniformly distributed in the interval [-2,2] is given below along with the plot of the random sequence generated by running the program:

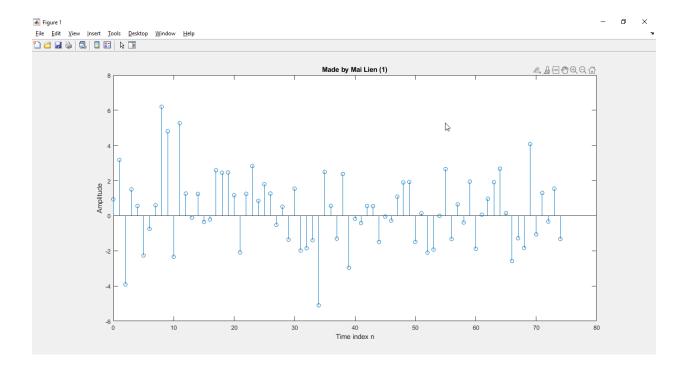
```
% Xoá các figure cũ đã vẽ (clear figure)
clf;
% Xoá các lệnh cũ (clear command) trong cửa sổ lệnh
clc;
% Xoá các biến đã tạo
clear;
% Time index n
```

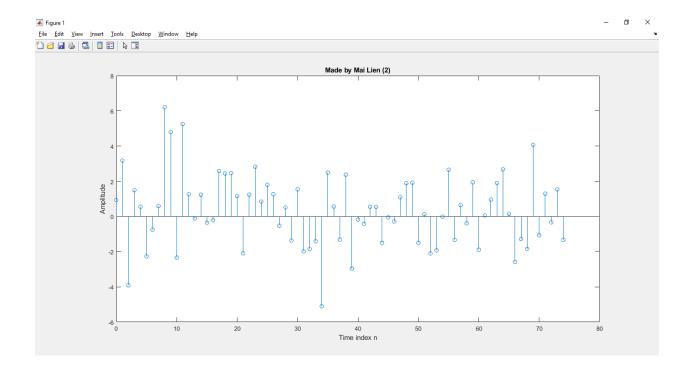


Q1.27
The MATLAB program to generate and display a Gaussian radom signal of length 75 with elements normally distributed with zero mean and variance of 3 is given below along with the plot of the random sequence generated by running the program:

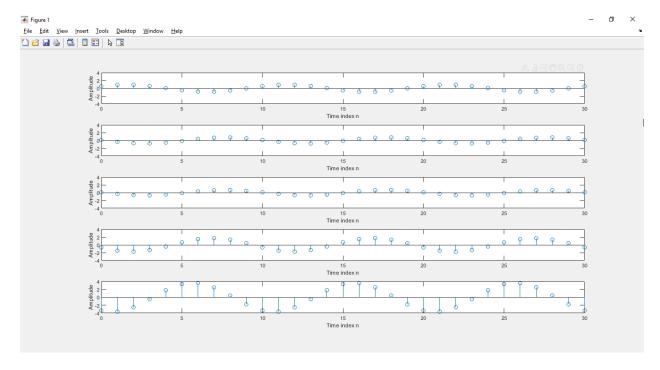
```
n = 0:74;
% For reproducibility
rng('default');
n = 0:74;
% For reproducibility
rng('default');
```

```
x = randn(1, 75).*sqrt(3) + 0;
mu = 0;
sigma = sqrt(3);
                                              stem(n, x);
x = random('Normal', mu, sigma, 1, 75);
                                             title("Made by Mai Lien (2)");
                                             xlabel("Time index n");
stem(n, x);
title("Made by Mai Lien (1)");
xlabel("Time index n");
                                             ylabel("Amplitude");
                                             % axis([XMIN XMAX YMIN YMAX]) sets
ylabel("Amplitude");
                                             scaling for the x- and y-axes
XMIN = 0;
                                             XMIN = 0;
XMAX = 74;
                                             XMAX = 74;
YMIN = -6;
                                             YMIN = -6;
YMAX = 6;
                                             YMAX = 6;
                                        ١
xlim([XMIN XMAX]);
                                             xlim([XMIN XMAX]);
ylim([YMIN YMAX]);
                                             ylim([YMIN YMAX]);
```



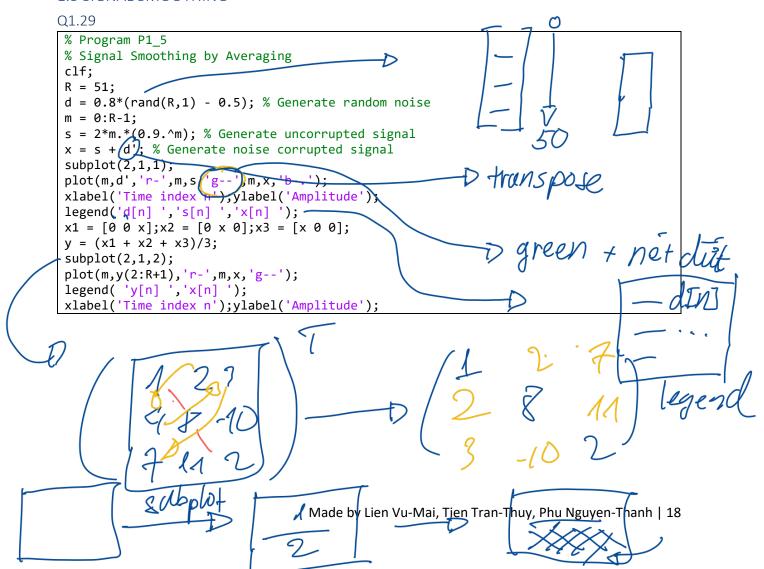


```
Q1.28
clf;clc;clear;
n = 0:30;
 for var = 1:5
     subplot(5, 1, var);
     A = rand*4;
     phi = rand*2*pi;
     freq = 0.1;
     omegaZero = 2*pi*freq;
     arg = omegaZero * n + phi;
     x = A * cos(arg);
     stem(n, x)
     axis([0 30 -4 4])
     xlabel("Time index n")
    ylabel("Amplitude")
end
```

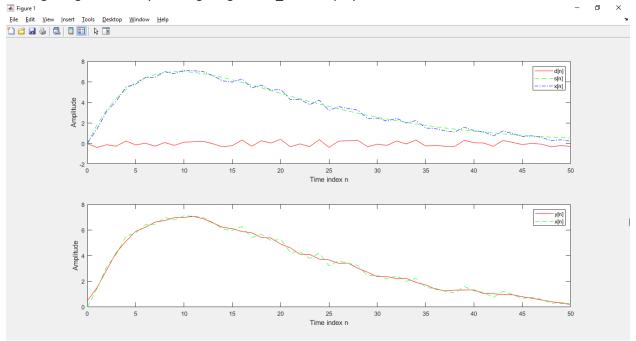


SIMPLE OPERATIONS ON SEQUENCES

1.5 SIGNAL SMOOTHING



The signals generated by running Program P1_5 are displayed below:



Modified

```
% Program P1 5
% Signal Smoothing by Averaging
clf;
R = 51;
% Generate random noise
d = 0.8*(rand(R,1) - 0.5);
m = 0:R-1;
% Generate uncorrupted signal
s = 2*m.*(0.9.^m);
% Generate noise corrupted signal
% d' equivalent transpose(d)
x = s + d';
subplot(3,1,1);
plot(m,d','r-',m,s,'g-',m,x,'b-');
xlabel('Time index n');ylabel('Amplitude');
legend('d[n] ','s[n] ','x[n] ');
                                     Mở rộng mã X
x1 = [0 \ 0 \ x];
x2 = [0 \times 0];
x3 = [x \ 0 \ 0];
% TO DE-NOISE
y = (x1+x2+x3)/3;
subplot(3,1,2);
title("Before Denoise")
plot(m, x, 'r-');
legend( 'x[n] ');
```

The uncorrupted signal s[n] is: tích từng phần tử của hàm tăng tưởng m với hàm suy giảm (0.9.^m) The additive noise d[n] is - là chuỗi nhiễu ngẫu nhiên được sinh từ hàm rand (phân phối xác suất đồng đều) biên độ từ $-0.4 \rightarrow 0.4$.

Q1.31

The statement x = s + d CANNOT be used to generate the noise corrupted signal because - s là một vector hàng (kích thước 1x51) và d là một vector cột (kích thước 51x1).

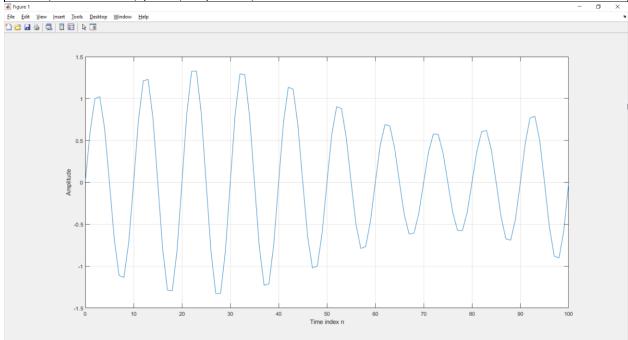
Q1.32

The relations between the signals x1, x2, and x3, and the signal x are – x2 là mở rộng của x (thêm '0' ở phía trước và phía sau)
X1 là trễ 1 mẫu của x2 (thêm '0' ở phía trước x)
X3 là sớm 1 mẫu của x2(thêm '0' ở phía sau x)

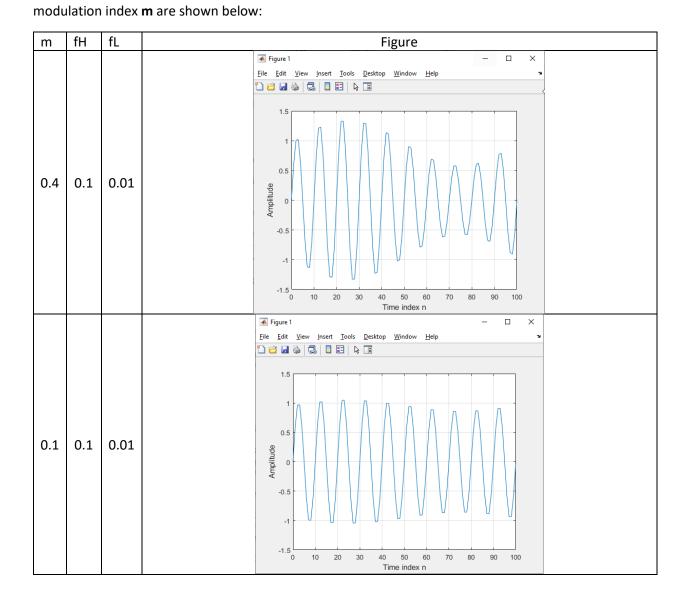
The purpose of the *legend* command is to create a legend for the graphs. In P1_5, the signals are plotted using different colors and line types; the legend provides information about which color and line type is associated with each signal.

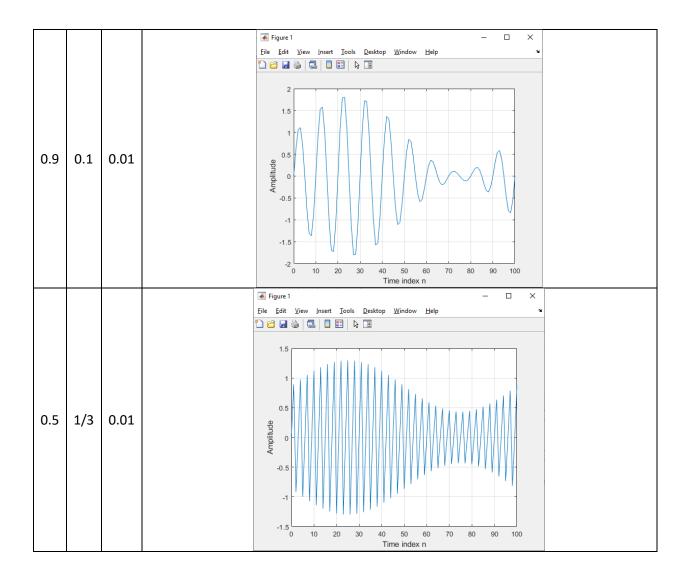
1.6 Generation of Complex Signals

```
% Program P1_6
% Generation of amplitude modulated sequence
n = 0:100;
% ???
m = 0.4;
% Tần số sóng mang
fH = 0.1;
% Tần số tín hiệu
fL = 0.01;
% Sóng mang
xH = sin(2*pi*fH*n);
% Tín hiệu
xL = sin(2*pi*fL*n);
% Tín hiệu AM đã điều chế
y = (1+m*xL).*xH;
% Vẽ tín hiệu
plot(n,y);grid;
xlabel('Time index n');ylabel('Amplitude');
```



Q1.34 The amplitude modulated signals y[n] generated by running Program P1_6 for various values of the frequencies of the carrier signal xH[n] and the modulating signal xL[n], and various values of the





The difference between the arithmetic operators * and .* is:

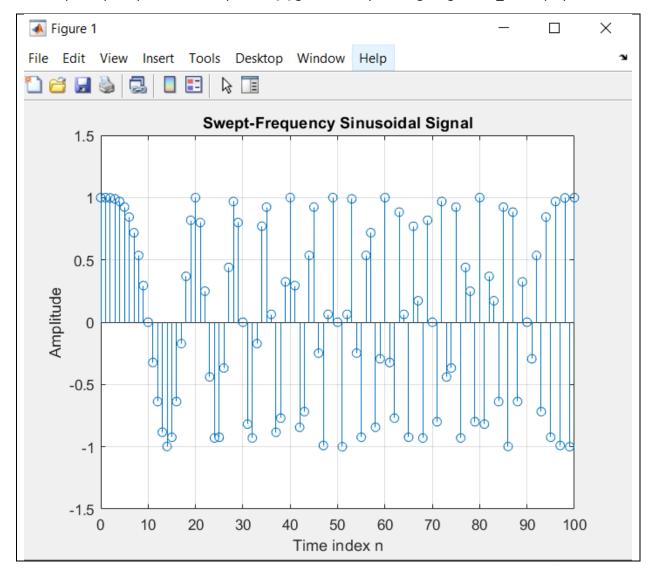
- * là phép nhân giữa hai ma trận
- .* là áp dụng phép nhân của các phần tử ở bên trong ma trận cùng kích thước(ai,j * bi,j)

Program P1_7 is given below:

```
% Program P1_7
% Generation of a swept frequency sinusoidal sequence
n = 0:100;
a = pi/2/100;
b = 0;
arg = a*n.*n + b*n;
x = cos(arg);
clf;
stem(n, x);
```

```
axis([0,100,-1.5,1.5]);
title('Swept-Frequency Sinusoidal Signal');
xlabel('Time index n');
ylabel('Amplitude');
grid;
axis;
```

Q1.36
The swept-frequency sinusoidal sequence x[n] generated by running Program P1_7 is displayed below:



 ${\rm Q}1.37$ The minimum and maximum frequencies of this signal are

$$arg = \frac{72}{200} \cdot n_i^2 \rightarrow \omega_i = (arg)' = \frac{77}{100} n_i$$

$$\Rightarrow f_i = \frac{\omega_i}{270} = \frac{n_i}{200}$$

$$\Rightarrow n_i = 0 \text{ at } n_0 = 0$$

$$\Rightarrow n_i = \frac{1}{2} \text{ at } n_i = 100$$

01.38

The Program 1_7 modified to generate a swept sinusoidal signal with a minimum frequency of 0.1 and a maximum frequency of 0.3 is given below:

$$\int_{i}^{0.3} 0.2 \cdot \frac{n_{i}}{100} + 0.1 \rightarrow w_{0} : \frac{7}{250} n_{i} + \frac{7}{5}$$

$$\Rightarrow arg = \int w_{i} dn_{i} = \frac{77}{500} n_{i}^{2} + \frac{77}{5} n_{i} + 0$$

```
% Program P1_7
% Generation of a swept frequency sinusoidal sequence
n = 0:01:100;
a = pi/500;
b = pi/5;
arg = a*n.*n + b*n;
x = cos(arg);
clf;
stem(n, x);
axis([0,100,-1.5,1.5]);
title('Swept-Frequency Sinusoidal Signal');
xlabel('Time index n');
ylabel('Amplitude');
grid; axis;
```

WORKSPACE INFORMATION

Q1.39

The information displayed in the command window as a result of the who command is:

Liệt kê tất cả các tên biến đang tồn tại trong bộ nhớ

Q1.40

The information displayed in the command window as a result of the whos command is:

Liệt kê tên biến, kích thước, số phần tử và xét các phần ảo có khác 0 hay không.

OTHER TYPES OF SIGNALS (Optional)

1.8 Squarewave and Sawtooth Signals

Q1.41

