

# Nhan (Steve) Nguyen

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## PROFILE SUMMARY

Mechanical Engineering graduate with 1.5 years of experience in manufacturing operations and R&D software development, specializing in reliability engineering, process improvement, and engineering tools using Python and MATLAB.

## TECHNICAL SKILLS

- Programming & Simulation:** MATLAB, Python, Simulink, Finite Element Analysis (FEA)
- Design & CAD:** SolidWorks, CNC Trajectory Modeling, Carsim, MSC ADAMS, GD&T
- Process & Manufacturing:** Lean Manufacturing, 5S/Kaizen, Continuous Improvement, Root Cause Analysis, Reliability Engineering
- Dev & Tools:** DevOps, Jira, PyCharm, VS Code, Jenkins, CI/CD, Microsoft Office

## WORK EXPERIENCE

<b>Manufacturing Engineer</b> <i>Procter &amp; Gamble</i>	Sep. 2024 – Apr. 2025
<ul style="list-style-type: none"><li>Standardized packaging equipment maintenance across 7 production lines, saving \$70,000 annually.</li><li>Developed and maintained 2,200+ equipment standards, increasing MTBF by 50%.</li><li>Standardized alarm configurations for 28 machines (3,500+ parameters), boosting line efficiency by 15%.</li></ul>	
<b>Software Tool Developer</b> <i>Bosch R&amp;D Automotive</i>	Aug. 2022 – Aug. 2023
<ul style="list-style-type: none"><li>Enhanced MATLAB/Python simulation tools for electric motor design, optimizing fatigue analysis workflows.</li><li>Increased automated test coverage from 40% to 90% via MATLAB testing scripts.</li><li>Applied DevOps and CI/CD to integrate new features while preserving backward compatibility.</li></ul>	

## ENGINEER PROJECTS

<b>Vehicle Dynamics System</b>   <i>MATLAB, Simulink, Carsim</i>	Apr. 2024 – Aug. 2024
<ul style="list-style-type: none"><li>Designed a PID-based path tracking controller for an autonomous race car using a 2-DOF linear vehicle dynamics model, incorporating lateral error and yaw dynamics.</li><li>Optimized PID gains using a Genetic Algorithm, reducing manual tuning effort and improving tracking performance across multiple vehicle speeds.</li><li>Validated controller performance through MATLAB/Simulink and CarSim co-simulation on circular paths and the Monza race track, identifying stability limits at high-speed conditions.</li></ul>	
<b>Precision Control System</b>   <i>MATLAB, Simulink</i>	Aug. 2023 – Dec. 2023
<ul style="list-style-type: none"><li>Developed multi-axis trajectory generator for a virtual CNC system, using cubic splines and jerk-limited profiling.</li><li>Modeled feed drive dynamics via Least Squares and Kalman filter friction modeling.</li><li>Designed PID + feedforward controllers with loop-shaping to enhance tracking performance.</li></ul>	
<b>Product Designer in a CAE Environment</b>   <i>MATLAB, SolidWorks</i>	Aug. 2021 – Jun. 2022
<ul style="list-style-type: none"><li>Created dimensionally accurate 3D models and GD&amp;T drawings of a scissor jack.</li><li>Performed FEA to determine factor of safety.</li><li>Redesigned a component that improved the load capacity of the scissor jack by 10%.</li></ul>	

## EDUCATION

<b>University of Waterloo</b> <i>Master of Engineering in Mechanical and Mechatronics Engineering</i>	Waterloo, ON
	Aug. 2023 – Aug. 2025
<b>University at Buffalo</b> <i>Bachelor of Science in Mechanical Engineering, Magna Cum Laude</i>	Buffalo, NY
	Aug. 2018 – Jun. 2022