NHAN H. PHAM

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RESEARCH INTERESTS

Stochastic methods for machine learning, deep learning, reinforcement learning, and federated learning.

EDUCATION

Ph.D. in Operations Research 2017–2022
Department of Statistics and Operations Research
University of North Carolina at Chapel Hill · Chapel Hill, NC, USA

Graduate Study in Computer Engineering 2015–2017
Department of Computer Science and Engineering
University of Nevada, Reno · Reno, NV, USA

Bachelor of Engineering (Honor Program) in Computer Engineering 2008–2013
Department of Computer Science and Engineering
Ho Chi Minh City University of Technology · Ho Chi Minh City, Vietnam

RESEARCH EXPERIENCES

Federated Learning with Randomized Douglas-Rachford Splitting Methods *Aug. 2020–Feb. 2021*
Graduate Research Assistant, Supervisor: Dr. Quoc Tran-Dinh, Dr. Lam M. Nguyen.
Under review, eprint.

- ◇ Propose two new algorithms, FedDR and asyncFedDR, to solve finite-sum nonconvex problems in federated learning by combining Douglas-Rachford splitting, randomized strategy, and asynchronous update.
- ◇ Achieve best-known communication complexity and handle data heterogeneity.
- ◇ Conduct experiments on federated learning examples using synthetic and real datasets.

Regression Optimization for System-level Production Control *Jun. 2020–Aug. 2020*
IBM Research Intern, Supervisor: Dr. Roman Vaculin, Dr. Dzung T. Phan, Dr. Lam M. Nguyen.
Accepted for the 2021 American Control Conference (ACC).

Stochastic Gauss-Newton Algorithms for Nonconvex Compositional Optimization *Sept. 2019–Feb. 2020*
Graduate Research Assistant, Supervisors: Dr. Quoc Tran-Dinh, Dr. Lam M. Nguyen.
Accepted for the 37th International Conference on Machine Learning, eprint.

- ◇ Propose two new Stochastic Gauss-Newton algorithms to solve stochastic nonconvex compositional problems that use both classical stochastic and SARAH estimators for function values and Jacobian estimators.
- ◇ Give first stochastic Gauss-Newton algorithm with global complexity analysis.
- ◇ Conduct numerical experiments on two examples: stochastic nonlinear equations and asset allocation problem.

Regularization Techniques on Deep Learning *Sept. 2019–Dec. 2019*
SAMSI Research Fellow, Supervisor: Dr. Quoc Tran-Dinh.

- ◇ Study the principle of different regularization techniques on training Deep Neural Networks (DNNs).
- ◇ Conduct numerical experiments on different DNN models consisting two or more regularizers on both model parameters (e.g., ℓ_2-norm, max-norm constraint, etc.) and training process (dropout, batch normalization, etc.).

Hybrid Stochastic Policy Gradient Algorithm for Reinforcement Learning *Jul. 2019–Dec. 2019*
Graduate Research Assistant, Supervisors: Dr. Quoc Tran-Dinh, Dr. Lam M. Nguyen.
Accepted for the 23rd International Conference on Artificial Intelligence and Statistics (AISTATS 2020), eprint.

- ◇ Propose new biased policy gradient estimator from REINFORCE/GPOMDP and adopted SARAH estimators and use it to derive first algorithm that has convergence guarantee to solve a composite policy optimization problem in reinforcement learning.
- ◇ Prove proposed algorithm achieves best-known convergence rate over existing methods and conduct experiments to verify the advantage using OpenAI `gym` environments.

Hybrid Optimization Framework for Composite Nonconvex Optimization *Feb. 2019–Aug. 2019*
Graduate Research Assistant, Supervisors: Dr. Quoc Tran-Dinh, Dr. Lam M. Nguyen.
Accepted for Mathematical Programming, eprint.

- ◇ Introduce a new stochastic gradient estimator that combines SGD and SARAH estimators and use it to develop a new algorithm for composite nonconvex optimization problems which achieves best-known convergence rate.
- ◇ Verify the effectiveness of the proposed algorithm via numerical experiments using Python and Tensorflow.

ProxSARAH: A Framework for Stochastic Composite Nonconvex Optimization *Aug. 2018–Feb. 2019*
Graduate Research Assistant, Supervisors: Dr. Quoc Tran-Dinh, Dr. Lam M. Nguyen.
Accepted for Journal of Machine Learning Research (JMLR), eprint.

- ◇ Develop new stochastic algorithm for composite nonconvex optimization problems which utilizes existing SARAH estimator and achieves the best-known convergence rate.
- ◇ Conduct numerical experiments to illustrate advantage of proposed algorithms on three examples: Non-negative PCA, classification with 3 nonconvex losses, and neural network training using Python and Tensorflow.

Autonomous Robots for Bridge Inspection *Aug. 2015–Feb. 2017*
Graduate Research Assistant, Supervisor: Dr. Hung M. La.
In Proceedings of the 54th Annual Allerton Conference on Communication, Control, and Computing, eprint.
In Proceedings of the 2017 IEEE International Conference on Robotics and Automation (ICRA), eprint.
The 33rd International Symposium on Automation and Robotics in Construction and Mining (ISARC), eprint.

- ◇ Propose four-wheeled robot for steel bridge inspection with permanent magnets embedded inside each wheel equipped with different type of sensors: visual camera, 3D sensor, IMU for localization and mapping purposes.
- ◇ Build controller unit with minicomputer (Intel NUC) running Robot Operating System communicating with low-level controller (Arduino-based) for sensory data collection, implement sensor fusion and mapping algorithms.

INDUSTRY EXPERIENCES

Summer Machine Learning Intern *2021*
Blue River Technology Inc. · Sunnyvale, CA

- ◇ Analyse effectiveness of training with random augmentation versus baseline performance.
- ◇ Investigate whether instance segmentation can improve model performance than semantic segmentation by using transfer learning on existing models.

Summer Research Intern *2020*
IBM T. J. Watson Research Center · Yorktown Heights, NY

- ◇ Develop prediction-optimization framework to maximize the prediction output over different possible options on control variables, where the relationship in each plant is captured via a regression model.
- ◇ Implement primal-dual algorithms under different types of regression model with or without derivative information.

PREPRINTS

1. **N. H. Pham**, L. M. Nguyen, D. T. Phan, and Q. Tran-Dinh. Federated Learning with Randomized Douglas-Rachford Splitting Methods. *arXiv:2103.03452*, 2021.
2. T. T. Doan, L. M. Nguyen, **N. H. Pham**, and J. Romberg. Convergence Rates of Accelerated Markov Gradient Descent with Applications in Reinforcement Learning. *arXiv:2002.02873*, 2020.
3. T. T. Doan, L. M. Nguyen, **N. H. Pham**, and J. Romberg. Finite-Time Analysis of Stochastic Gradient Descent under Markov Randomness. *arXiv:2003.10973*, 2020.

PUBLICATIONS

1. D. T. Phan, L. M. Nguyen, P. Murali, **N. H. Pham**, H. Liu, and J. R. Kalagnanam. Regression Optimization for System-level Production Control. *American Control Conference (ACC)*, 2021.
2. Q. Tran-Dinh, **N. H. Pham**, D. T. Phan, and L. M. Nguyen. A Hybrid Stochastic Optimization Framework for Composite Nonconvex Optimization. *Mathematical Programming*, 2021.
3. Q. Tran-Dinh, **N. H. Pham**, and L. M. Nguyen. Stochastic Gauss-Newton Algorithms for Nonconvex Compositional Optimization. *Proceedings of the 37th International Conference on Machine Learning*, PMLR 119:9572-9582, 2020.
4. **N. H. Pham**, L. M. Nguyen, D. T. Phan, and Q. Tran-Dinh. ProxSARAH: An Efficient Algorithmic Framework for Stochastic Composite Nonconvex Optimization. *Journal of Machine Learning Research*, 2020.
5. **N. H. Pham**, L. M. Nguyen, D. T. Phan, P. H. Nguyen, M. van Dijk, and Q. Tran-Dinh. A Hybrid Stochastic Policy Gradient Algorithm for Reinforcement Learning. *The 23rd International Conference on Artificial Intelligence and Statistics (AISTATS)*, 2020, Palermo, Italy.
6. H. M. La, T. H. Dinh, **N. H. Pham**, Q. P. Ha, and A. Q. Pham. Automated Robotic Monitoring and Inspection of Steel Structures and Bridges. *Robotica*, Cambridge University Press, 1-21, 2018.

7. T. D. Le, S. Gibb, **N. H. Pham**, H. M. La, L. Falk, and T. Berendsen. Autonomous Robotic System using Non-Destructive Evaluation methods for Bridge Deck Inspection. In *Proceedings of the 2017 IEEE International Conference on Robotics and Automation (ICRA)*, May 29-June 3, 2017, Singapore.
8. **N. H. Pham** and H. M. La. Design and Implementation of an Autonomous Robot for Steel Bridge Inspection. In *Proceedings of the 54th Annual Allerton Conference on Communication, Control, and Computing*, pages 1-8, Sept. 27-30, 2016, Urbana-Champaign, Illinois, USA.
9. **N. H. Pham**, H. M. La, Q. P. Ha, S. N. Dang, A. H. Vo, and Q. H. Dinh. Visual and 3D Mapping for Steel Bridge Inspection Using a Climbing Robot. *The 33rd International Symposium on Automation and Robotics in Construction and Mining (ISARC)*, pages 1-8, July 18-21, 2016, Auburn, Alabama, USA.
10. T.-D. D. Phan, **N. H. Pham**, K.-N. Le-Huu, and A.-V. D. Dinh. Quadrotor Helicopter: A Practical Design Approach. *IEICE International Conference on Integrated Circuits, Design and Verification*, pp.156-163, 2013, Ho Chi Minh, Vietnam.

INVITED TALKS

MIT-IBM Guest Seminar *Jul. 2021*
Title: *Stochastic Recursive Gradient Algorithms for Stochastic Composite Nonconvex Optimization and Policy Optimization.*

INFORMS Annual Meeting 2020 Virtual *Nov. 2020*
Title: *A Hybrid Stochastic Policy Gradient Algorithm for Reinforcement Learning.*

INFORMS Annual Meeting 2019 Seattle *Oct. 2019*
Title: *ProxSARAH: An Efficient Algorithmic Framework for Stochastic Composite Nonconvex Optimization.*

SKILLS & QUALIFICATIONS

Technical	Python, Tensorflow, Keras, Pytorch, Scikit-learn, C/C++, Matlab, Data Structures & Algorithms
Other skills	Linux Development Environment, Robotics, Embedded Systems

OTHER EXPERIENCES

Graduate Teaching Assistant *2020-current*
STOR 455: Methods of Data Analysis
STOR 155: Introduction to Data Models and Inference
Department of Statistics and Operations Research · University of North Carolina at Chapel Hill

Graduate Teaching Fellow *2019*
STOR 113: Decision Models for Business and Economics
Department of Statistics and Operations Research · University of North Carolina at Chapel Hill

Graduate Teaching Assistant *2017–2018*
STOR 113: Decision Models for Business and Economics
STOR 155: Introduction to Data Models and Inference
Department of Statistics and Operations Research · University of North Carolina at Chapel Hill

Graduate Teaching Assistant *2015–2017*
CPE 301: Embedded Systems Design
CS 302: Data Structures
Department of Computer Science and Engineering · University of Nevada, Reno

Lab Assistant *2013–2015*
Renesas SuperH Lab
Department of Computer Science and Engineering · Ho Chi Minh City University of Technology

Organizing Assistant *2014*
BKIT Car Rally
Department of Computer Science and Engineering · Ho Chi Minh City University of Technology

Robot Control Software Developer *2013*
BK4 aka BKIT Number One Team · Vietnam National Robot Contest
Department of Computer Science and Engineering · Ho Chi Minh City University of Technology

Embedded Software Developer *2012*
ChipFC Team · Texas Instruments National MCU Design Contest–**1st Place Winner**

HONORS & AWARDS

Graduate Access Grant *2016–2017*
Regents' Higher Education Opportunity Award
University of Nevada, Reno · Reno, NV

International Graduate Student Award *2016–2017*
Regents' Higher Education Opportunity Award
University of Nevada, Reno · Reno, NV

Poster Exhibition–1st Place Winner *2016*
CSE Graduate Club–Department of Computer Science and Engineering
University of Nevada, Reno · Reno, NV

Outstanding Academic Student Scholarship *2008–2013*
Department of Computer Science and Engineering
Ho Chi Minh City University of Technology · Ho Chi Minh City, Vietnam