

Date Submitted: 11/11/2019**Task 01:**

Youtube Link: N/A

Modified Schematic (if applicable): N/A

Modified Code:

```
//-----
// BIOS header files
//-----
#include <xdc/std.h>           //mandatory - have to include first, for BIOS types
#include <ti/sysbios/BIOS.h>   //mandatory - if you call APIs like BIOS_start()
#include <xdc/runtime/Log.h>    //needed for any Log_info() call
#include <xdc/cfg/global.h>     //header file for statically defined objects/handles

#include <ti/sysbios/knl/Semaphore.h> //when using Semaphores (dynamically)
#include <ti/sysbios/knl/Task.h>      //when using Tasks (dynamically)

//-----
// TivaWare Header Files
//-----
#include <stdint.h>
#include <stdbool.h>

#include "inc/hw_types.h"
#include "inc/hw_memmap.h"
#include "driverlib/sysctl.h"
#include "driverlib/gpio.h"
#include "inc/hw_ints.h"
#include "driverlib/interrupt.h"
#include "driverlib/timer.h"

//-----
// Prototypes
//-----
void hardware_init(void);
void ledToggle(void);
void Timer_ISR(void);

//-----
// Globals
//-----
volatile int16_t i16ToggleCount = 0;

Semaphore_Handle LEDSem;
Task_Handle ledToggleTask;
```

Grading scheme: 30% Coding, 30% Documentation, 40% Execution/Video.

```
//-----
// main()
//-----
void main(void)
{

    //-----
    // [START] - DYNAMIC CREATION OF TASK AND SEMAPHORE
    //-----

    Task_Params taskParams;

    LEDSem = Semaphore_create(0, NULL, NULL);
    // create ledToggleSem Semaphore

    Task_Params_init(&taskParams);
    // create ledToggleTask Task
    taskParams.priority = 2;
    ledToggleTask = Task_create((Task_FuncPtr)ledToggle, &taskParams, NULL);

    //-----
    // [END] - DYNAMIC CREATION OF TASK AND SEMAPHORE
    //-----

    //previous main() contents follow...

    hardware_init();                                     // init hardware via Xware

    BIOS_start();

}

//-----
// hardware_init()
//
// inits GPIO pins for toggling the LED
//-----
void hardware_init(void)
{
    uint32_t ui32Period;

    //Set CPU Clock to 40MHz. 400MHz PLL/2 = 200 DIV 5 = 40MHz
    SysCtlClockSet(SYSCTL_SYSDIV_5|SYSCTL_USE_PLL|SYSCTL_XTAL_16MHZ|SYSCTL_OSC_MAIN);

    // ADD Tiva-C GPIO setup - enables port, sets pins 1-3 (RGB) pins for output
    SysCtlPeripheralEnable(SYSCTL_PERIPH_GPIOF);
    GPIOPinTypeGPIOOutput(GPIO_PORTF_BASE, GPIO_PIN_1|GPIO_PIN_2|GPIO_PIN_3);

    // Turn on the LED

```

```

    GPIOPinWrite(GPIO_PORTF_BASE, GPIO_PIN_1|GPIO_PIN_2|GPIO_PIN_3, 4);

    // Timer 2 setup code
    SysCtlPeripheralEnable(SYSCTL_PERIPH_TIMER2);           // enable Timer 2
    periph_clks
    TimerConfigure(TIMER2_BASE, TIMER_CFG_PERIODIC);         // cfg Timer 2 mode
    - periodic

    ui32Period = (SysCtlClockGet() / 2);                     //
    period = CPU_clk_div 2 (500ms)
    TimerLoadSet(TIMER2_BASE, TIMER_A, ui32Period);         // set Timer
    2 period

    TimerIntEnable(TIMER2_BASE, TIMER_TIMA_TIMEOUT);        // enables Timer 2
    to interrupt CPU

    TimerEnable(TIMER2_BASE, TIMER_A);                       //
    enable Timer 2

}

//-----
// ledToggle()
//
// toggles LED on Tiva-C LaunchPad
//-----
void ledToggle(void)
{
    while(1)
    {
        Semaphore_pend(LEDSem, BIOS_WAIT_FOREVER);         //
        wait for Sem from ISR

        // LED values - 2=RED, 4=BLUE, 8=GREEN
        if(GPIOPinRead(GPIO_PORTF_BASE, GPIO_PIN_2))
        {
            GPIOPinWrite(GPIO_PORTF_BASE, GPIO_PIN_1|GPIO_PIN_2|GPIO_PIN_3,
0);
        }
        else
        {
            GPIOPinWrite(GPIO_PORTF_BASE, GPIO_PIN_2, 4);
        }

        i16ToggleCount += 1;
        // keep track of #toggles

        Log_info1("LED TOGGLED [%u] TIMES", i16ToggleCount); // send
        toggle count to UIA

    }
}

```

```
//-----  
// Timer ISR - called by BIOS Hwi (see app.cfg)  
//  
// Posts Swi (or later a Semaphore) to toggle the LED  
//-----  
void Timer_ISR(void)  
{  
    TimerIntClear(TIMER2_BASE, TIMER_TIMA_TIMEOUT);           // must clear timer  
    flag FROM timer  
  
    Semaphore_post(LEDSem);  
    // post LEDSwi  
}  
-----
```