

Assignments

Report Jennrich's Algorithm Nhat-Nam Nguyen

Jennrich's algorithm is an efficient approach to decompose a third-order tensor \mathcal{X} under the assumption that the factor matrices \mathbf{A} , \mathbf{B} , and \mathbf{C} are all of full column rank. The tensor decomposition is represented as follows:

$$\mathcal{X} = \sum_{r=1}^R \lambda_r \mathbf{a}_r \otimes \mathbf{b}_r \otimes \mathbf{c}_r$$

where:

- - R is the rank of the tensor.
- - λ_r are scalar coefficients.
- - \mathbf{a}_r , \mathbf{b}_r , and \mathbf{c}_r are the r -th columns of matrices \mathbf{A} , \mathbf{B} , and \mathbf{C} respectively.
- - \otimes denotes the outer product, forming a rank-1 tensor from vectors.

The core idea behind Jennrich's algorithm is to exploit the independence of factor matrices by applying random projections to reduce the tensor to a matrix form that retains the essential information of the original tensor. Firstly, we choose random vectors \mathbf{x} and \mathbf{y} and hit the tensor \mathcal{X} with these vectors. The resulting matrices encode the factor matrix structure and allow us to use eigendecomposition to isolate each matrix component.

1. Choose two random vectors \mathbf{x} and \mathbf{y} .
2. Contract the tensor \mathcal{X} along the third mode with \mathbf{x} and \mathbf{y} , resulting in two matrices M_x and M_y :

$$M_x = \sum_{r=1}^R \langle \mathbf{c}_r, \mathbf{x} \rangle \mathbf{a}_r \otimes \mathbf{b}_r = \mathbf{A} D_x \mathbf{B}^T$$

$$M_y = \sum_{r=1}^R \langle \mathbf{c}_r, \mathbf{y} \rangle \mathbf{a}_r \otimes \mathbf{b}_r = \mathbf{A} D_y \mathbf{B}^T$$

where D_x and D_y are diagonal matrices with diagonal entries $\langle \mathbf{c}_1, \mathbf{x} \rangle, \dots, \langle \mathbf{c}_R, \mathbf{x} \rangle$ and $\langle \mathbf{c}_1, \mathbf{y} \rangle, \dots, \langle \mathbf{c}_R, \mathbf{y} \rangle$, respectively. Here, \mathbf{A} has columns \mathbf{a}_r and \mathbf{B} has columns \mathbf{b}_r .

3. Since M_y is not necessarily full rank, we use the Moore-Penrose pseudoinverse M_y^+ , which has the property that:

$$M_y M_y^+ = I$$

This allows us to handle non-invertible matrices effectively. The pseudoinverse of M_y can be expressed as:

$$M_y^+ = (\mathbf{B}^T)^+ D_y^+ \mathbf{A}^+$$

where D_y^+ is the pseudoinverse of the diagonal matrix D_y , and $(\mathbf{B}^T)^+$ and \mathbf{A}^+ are the pseudoinverses of \mathbf{B}^T and \mathbf{A} , respectively.

4. To exploit the structure of the matrices, we compute the product $M_x M_y^+$ to find \mathbf{A} :

$$M_x M_y^+ = \mathbf{A} D_x \mathbf{B}^T (\mathbf{B}^T)^+ D_y^+ \mathbf{A}^+ = \mathbf{A} D \mathbf{A}^+$$

where D is a diagonal matrix with entries $D_{rr} = \frac{\langle \mathbf{c}_r, \mathbf{x} \rangle}{\langle \mathbf{c}_r, \mathbf{y} \rangle}$. The reason for choosing \mathbf{x} and \mathbf{y} as random vectors is to ensure, with high probability, that the values D_{rr} are distinct and well-defined. Respectively we can find \mathbf{B} :

$$M_x^+ M_y = \mathbf{B} D_x \mathbf{A}^T (\mathbf{A}^T)^+ D_y^+ \mathbf{B}^+ = \mathbf{B} D \mathbf{B}^+$$

5. When we have \mathbf{A} and \mathbf{B} we can solve the linear system to find \mathbf{C} .

$$(\mathbf{B} \odot \mathbf{A})\mathbf{C}^\top = \mathcal{X}_{(3)}$$

and

$$\mathbf{C} = \mathbf{X}_{(3)} [(\mathbf{B} \odot \mathbf{A})^T]^\dagger = \mathbf{X}_{(3)} (\mathbf{B} \odot \mathbf{A}) (\mathbf{B}^T \mathbf{B} * \mathbf{A}^T \mathbf{A})^\dagger$$

Below is the MATLAB code implementing Jennrich's algorithm

```

1 function [A_hat, B_hat, C_hat, lambda] = jennrich(X, R)
2     % Jennrich decomposition function
3     % Input:
4     %   X - input tensor of size (I, J, K)
5     %   R - target rank
6     % Output:
7     %   A_hat, B_hat, C_hat - estimated factor matrices
8     %   lambda - scaling factors
9
10    % Get dimensions of the tensor
11    I = size(X, 1);
12    J = size(X, 2);
13    K = size(X, 3);
14
15    % Generate random vectors x and y of size K
16    x = rand(K, 1);
17    y = rand(K, 1);
18
19    % Initialize matrices Xx and Xy
20    Xx = zeros(I, J);
21    Xy = zeros(I, J);
22
23    % Step 1: Contract the tensor along the third mode with x and y
24    for i = 1:R
25        Xx = Xx + (C(:, i))' * x * (A(:, i) * B(:, i)');
26        Xy = Xy + (C(:, i))' * y * (A(:, i) * B(:, i)');
27    end
28
29    % Step 2: Eigendecomposition to find A_hat
30    [Vx, Dx] = eig(Xx * Xx');
31    A_hat = Vx;
32
33    % Step 3: Eigendecomposition to find B_hat
34    [Vy, Dy] = eig(Xy' * Xy);
35    B_hat = Vy;
36
37    % Step 4: Compute C_hat
38    V3 = (B_hat' * B_hat) .* (A_hat' * A_hat);
39    X3 = ndim_unfold(X, 3); % Unfold X along the third mode
40    C_hat = X3 * khatri_rao_prod(B_hat, A_hat) * pinv(V3);
41
42    % Step 5: Calculate lambda as scaling factors
43    lambda = zeros(1, R);
44    for r = 1:R
45        lambda(r) = norm(A_hat(:, r)) * norm(B_hat(:, r)) * norm(C_hat(:, r));
46
47        % Normalize A_hat, B_hat, and C_hat
48        A_hat(:, r) = A_hat(:, r) / norm(A_hat(:, r));
49        B_hat(:, r) = B_hat(:, r) / norm(B_hat(:, r));
50        C_hat(:, r) = C_hat(:, r) / norm(C_hat(:, r));
51    end
52 end

```

Func 1: Jennrich's Algorithm MATLAB Implementation