

# HOMEWORK (2)

Solutions.

$$\underline{1 - (1-b)}$$

## Question ①

a)  $y(t) = \int_{-\infty}^{2t} x(z+3) dz$

Linearity  $x_1(t) \rightarrow y_1(t) = \int_{-\infty}^{2t} x_1(z+3) dz$

$x_2(t) \rightarrow y_2(t) = \int_{-\infty}^{2t} x_2(z+3) dz$

$$\therefore \int_{-\infty}^{2t} [x_1(z+3) + \beta x_2(z+3)] dz = \alpha \int_{-\infty}^{2t} x_1(z+3) dz + \beta \int_{-\infty}^{2t} x_2(z+3) dz \\ = \alpha y_1(t) + \beta y_2(t).$$

$\therefore$  linear

Time Invariance  $x(t-t_0) \rightarrow [S] \rightarrow y_0(t)$

$$y_0(t) = S \{ x(t-t_0) \} = \int_{-\infty}^{2t} x(z - t_0 + 3) dz$$

$$\begin{aligned} \text{let } z - t_0 &= \tilde{z} \Rightarrow z = 2t \\ dz &= d\tilde{z} \Rightarrow \tilde{z} = 2t - t_0. \end{aligned}$$

$$\therefore y_0(t) = \int_{-\infty}^{2t-t_0} x(\tilde{z} + 3) d\tilde{z}$$

$$y(t-t_0) = \int_{-\infty}^{2(t-t_0)} x(z+3) dz$$

T.V

Causality

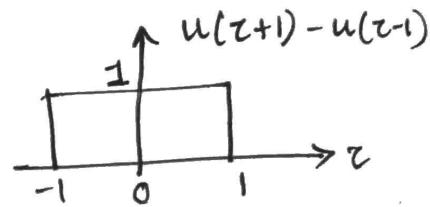
$$y(t) = \int_{-\infty}^{t-3} x(z+3) dz + \int_{t-3}^{2t} x(z+3) dz$$

depends on future inputs

Non Causal

$$0 \text{ or } 2 \quad x(t) = u(t-2) - u(t-4)$$

$$y(t) = \int_{-\infty}^{2t} [u(t+1) - u(t-1)] dt$$



$$y(t) = \begin{cases} 0 & t < \frac{1}{2} \\ \int_{-1}^{2t} 1 \cdot dt & -\frac{1}{2} \leq t < \frac{1}{2} \\ -\int_{-1}^t 1 \cdot dt & t \geq \frac{1}{2} \end{cases}$$

$$y(t) = \begin{cases} 0 & t < -\frac{1}{2} \\ 2t+1 & -\frac{1}{2} \leq t < \frac{1}{2} \\ 2 & t \geq \frac{1}{2} \end{cases}$$

b)  $y(t) = x(t) \sin(\pi t)$

i) Linearity

$$\begin{aligned} s\{x_1(t) + x_2(t)\} &= (\alpha x_1(t) + \beta x_2(t)) \sin(\pi t) \\ &= \alpha y_1(t) + \beta y_2(t) \end{aligned}$$

∴ Linear

ii) Time Invariance

$$\begin{aligned} s\{x(t-t_0)\} &= x(t-t_0) \sin(\pi t) \\ y(t-t_0) &= x(t-t_0) \sin(\pi t - \pi t_0) \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{Time varying}$$

iii) Causality:

For all instances of time  $t$ ,  $y(t)$  depends on present values of  $x(t)$ .

⇒ Causal

iv)  $n(t) = u(t-2) - u(t-4)$

$$y(t) = [u(t-2) - u(t-4)] \sin(\pi t)$$

$$y(t) = \begin{cases} \sin(\pi t) & 2 \leq t < 4 \\ 0 & \text{elsewhere} \end{cases}$$

$$y(t) = \frac{d}{dt} x(t) \cdot = \dot{x}(t)$$

i) Linearity

$$\begin{aligned} S\{\alpha x_1(t) + \beta x_2(t)\} &= \frac{d}{dt} \frac{d}{dt} \{ \alpha x_1(t) + \beta x_2(t) \} \\ &= \alpha \dot{x}_1(t) + \beta \dot{x}_2(t) ; \quad \dot{x} = \frac{d}{dt} \\ &= \alpha y_1(t) + \beta y_2(t) \\ &\therefore \boxed{\text{Linear}} \end{aligned}$$

ii) Time Invariance :

$$S\{x(t-t_0)\} = \frac{d}{dt} x(t-t_0) = y(t-t_0) \quad \therefore \boxed{\text{TI}}$$

iii) Causality : Causal  $\because$  depends on present values of input at  $t \in (-\infty, \infty)$

iv)  $x(t) = u(t-2) - u(t-4)$

$$\begin{aligned} y(t) &= \frac{d}{dt} \{ u(t-2) - u(t-4) \} \\ &\boxed{y(t) = \delta(t-2) - \delta(t-4)} \end{aligned}$$

(a)  $y(t) = x(2-t) + x(2+t)$

i) Linear :  $S\{\alpha x_1(t) + \beta x_2(t)\} = \cancel{\beta x_1(t)} + \alpha S\{x_1(t)\} + \beta S\{x_2(t)\}$

ii) Time varying :

$$S\{x(t-t_0)\} = x(2-t-t_0) + x(2+t-t_0) \quad \boxed{\text{T.V}}$$

$$y(t-t_0) = x(2-t+t_0) + x(2+t-t_0)$$

iii) Non-causal :  $y(t)$  depends on  $x(t+2)$  at  $t$ .

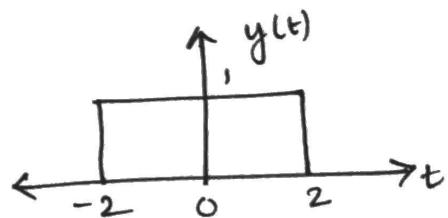
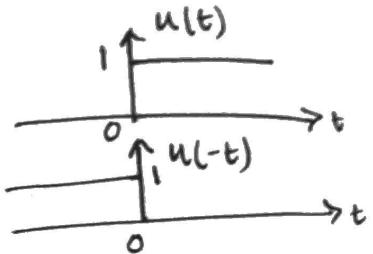
iv)  $x(t) = u(t-2) - u(t-4)$

$$\begin{aligned} x(2-t) &= u(-t) - u(-t-2) ; \\ x(2+t) &= u(t) - u(t-2) \end{aligned}$$

$$\Rightarrow y(t) = u(-t) - u(-t-2) + u(t) - u(t-2)$$

$$\begin{aligned}
 y(t) &= \underbrace{u(t) + u(-t)} - u(-t-2) - u(t-2) \\
 &= \underbrace{1 - u(-t-2) - u(t-2)} \\
 &= u(t+2) - u(t-2)
 \end{aligned}$$

$y(t) = u(t+2) - u(t-2)$



question ②

$$y(t) = x(t) - \int_{t-1}^{t+1} e^{|t-\tau|} x(\tau) d\tau$$

Write  $x(t)$  as  $x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau = x(t) * \delta(t)$

$$(a) \quad y(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau - \underbrace{\int_{t-1}^{t+1} e^{|t-\tau|} x(\tau) d\tau}_{I_2}$$

$I_2$ : Integral over  $(t-1, t+1)$ .

We can change limits of  $I_2$  to  $(-\infty, \infty)$  if we restrict the integrand to the range  $(t-1, t+1)$  by multiplying with rectangular block

$$[u(\tau - (t-1)) - u(\tau - (t+1))]$$

$$\therefore y(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau - \int_{-\infty}^{\infty} e^{|t-\tau|} x(\tau) [u(\tau - t+1) - u(\tau - t-1)] d\tau$$

$$= \int_{-\infty}^{\infty} x(\tau) [\underbrace{\delta(t-\tau) - e^{|t-\tau|} u(\tau - (t-1)) + e^{|t-\tau|} u(\tau - (t+1))}_{h(t,\tau)}] d\tau$$

$$\boxed{h(t,\tau) = \delta(t-\tau) - e^{|t-\tau|} u(1-(t-\tau)) + e^{|t-\tau|} u(1+(t-\tau))}$$

$$= \delta(t-\tau) - e^{t-\tau} u(\tau - (t-1)) u(t-\tau) - e^{\tau-t} u(-\tau + (t+1)) u(\tau - t)$$

(b)  $\rightarrow h(t,\tau)$  is a fn of  $|t-\tau|$  only  
 $\therefore$  System is time invariant (TI).

$$\Rightarrow \boxed{h(t,\tau) = h(t-\tau, 0)}$$

$\rightarrow$  Linearity can be confirmed from the input/output relation

Further, since  $h(t, \tau) = h(t-\tau, 0) = h(t-\tau)$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \rightarrow \text{This re-affirms that the system is linear}$$

Proof of Linearity:

$$\begin{aligned} \text{Define } y_3(t) &= S\{ \alpha x_1(t) + \beta x_2(t) \} \\ &= \int_{-\infty}^{\infty} (\alpha x_1(\tau) + \beta x_2(\tau)) h(t-\tau) d\tau \\ &= \alpha \int_{-\infty}^{\infty} x_1(\tau) h(t-\tau) d\tau + \beta \int_{-\infty}^{\infty} x_2(\tau) h(t-\tau) d\tau \\ &= \alpha y_1(t) + \beta y_2(t). \end{aligned}$$

Proof of Time Invariance:

$$\text{Define } y_4(t) = S\{ \alpha t - t_0 \}$$

$$\Rightarrow y_4(t) = x(t-t_0) + \int_{t-1}^{t+1} e^{1(t-\tau)} x(\tau-t_0).$$

$$y_4(t) = \int_{-\infty}^{\infty} x(\tau-t_0) h(t-\tau) d\tau \quad \text{--- (1)}$$

$$y_4(t) y(t-t_0) = \int_{-\infty}^{\infty} x(\tau) h(t-t_0-\tau) d\tau$$

$$\begin{array}{l} \text{Let } t-t_0 = \tilde{t} \\ \Rightarrow dt = d\tilde{t} \end{array} \quad \left| \begin{array}{l} \text{Let } \tau+t_0 = \tilde{\tau} \\ \Rightarrow d\tau = d\tilde{\tau} \end{array} \right.$$

$$\text{Thus, } y(t-t_0) = \int_{-\infty}^{\infty} x(\tilde{\tau}-t_0) \cdot h(t-\tilde{\tau}) d\tilde{\tau} \quad \text{--- (2)}$$

$$\text{Thus } y_4(t) = \boxed{S\{ \alpha t - t_0 \}} = y(t-t_0)$$

$\Rightarrow$  Time Invariant

## Causality :

Since the system is LTI,

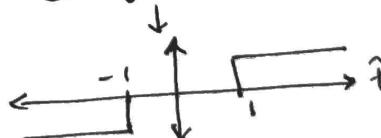
we can express  $h(t, \tau) = h(t-\tau, 0)$

$\therefore$  System can be expressed as  $h(\tilde{t})$ . ;  $\tilde{t} = t - \tau$

Condition for causality for LTV system :-

$$h(t, \tau) = h(t, \tau) u(t-\tau)$$

now reduces to  $\boxed{h(\tilde{t}) = h(\tilde{t}) u(\tilde{t})}$

$$\begin{aligned}
 \therefore RHS &= h(\tilde{t}) u(\tilde{t}) \\
 &= \left[ \delta(\tilde{t}) - e^{|\tilde{t}|} u(1-\tilde{t}) + e^{|\tilde{t}|} u(1+\tilde{t}) \right] u(\tilde{t}) \\
 &= \delta(\tilde{t}) u(\tilde{t}) - e^{|\tilde{t}|} u(1-\tilde{t}) u(\tilde{t}) + e^{|\tilde{t}|} u(\tilde{t}) u(1+\tilde{t}) \\
 &= \cancel{\delta(\tilde{t})} + \cancel{e^{|\tilde{t}|} [u(\tilde{t}) - u(\tilde{t}-1)]} + \cancel{e^{|\tilde{t}|} u(\tilde{t})} \\
 &= \cancel{\delta(\tilde{t})} + e^{|\tilde{t}|} u(\tilde{t}-1) \\
 &= \delta(\tilde{t}) \cdot 1 - e^{|\tilde{t}|} u(\tilde{t}) [u(1-\tilde{t}) - u(1+\tilde{t})] \\
 &= \delta(\tilde{t}) + e^{|\tilde{t}|} u(\tilde{t}) \underbrace{[u(\tilde{t}+1) - u(1-\tilde{t})]}_{\downarrow}
 \end{aligned}$$


$$\therefore \neq \delta(\tilde{t}) + e^{|\tilde{t}|} [u(\tilde{t}+1) - u(1-\tilde{t})]$$

$$\therefore \boxed{h(\tilde{t}) u(\tilde{t}) \neq h(\tilde{t})}$$

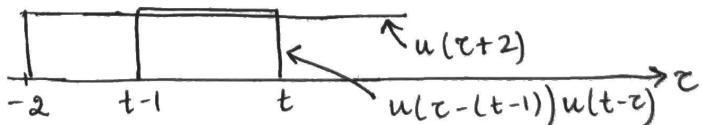
$\therefore$  System is Non-causal

$$h(t, \tau) = \delta(t, \tau) - e^{|t-\tau|} [u(1-t+\tau) - u(1+t-\tau)] \\ = \delta(t-\tau) - e^{t-\tau} [u(1-t+\tau) - u(1+t-\tau)] u(t-\tau) \\ - e^{\tau-t} [u(1-t-\tau) - u(1+t-\tau)] u(\tau-t)$$

$$h(t, \tau) = \delta(t-\tau) - e^{t-\tau} u(\tau-(t-1)) u(t-\tau) - e^{\tau-t} u(-\tau+(t+1)) u(\tau-t) \quad 5.$$

$$\begin{aligned}
 y(t) &= \int_{-\infty}^{\infty} e^{-\tau} u(\tau+2) h(t-\tau) d\tau \\
 &= \int_{-\infty}^{\infty} e^{-\tau} u(\tau+2) \delta(t-\tau) d\tau - \int_{-\infty}^{\infty} e^{-\tau} u(\tau+2) \cdot e^{t-\tau} u(\tau-(t-1)) u(t-\tau) d\tau \\
 &\quad - \int_{-\infty}^{\infty} e^{-\tau} e^{\tau-t} u(\tau+2) u(-\tau+(t+1)) u(\tau-t) d\tau \\
 &= e^{-t} u(t+2) - \underbrace{\int_{-\infty}^t e^{\tau} \cdot e^{-2\tau} u(\tau+2) u(\tau-(t-1)) u(t-\tau) d\tau}_{y_1(t)} \\
 &\quad - \underbrace{\int_{-\infty}^t e^{-\tau} e^{\tau-t} u(\tau+2) u(-\tau+(t+1)) u(\tau-t) d\tau}_{y_2(t)}
 \end{aligned}$$

$$\begin{aligned}
 y_1(t) &= \int_{-\infty}^{\infty} e^{\tau} \cdot e^{-2\tau} u(\tau+2) u(\tau-(t-1)) u(t-\tau) d\tau \\
 &\quad u(\tau+2) u(\tau-(t-1)) u(t-\tau) \\
 &\quad \text{non-zero only in } \tau \in [t-1, t]
 \end{aligned}$$



3 cases i)  $-2 < t-1 \Rightarrow$   $t > -1$

$$\Rightarrow y_1(t) = e^t \int_{t-1}^t e^{-2\tau} d\tau = \frac{1}{2} (e^{-t} - e^{-t+2})$$

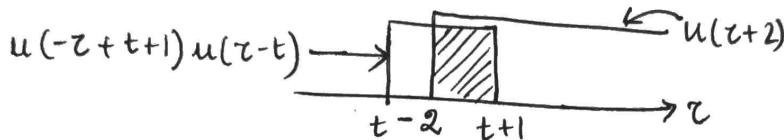
ii)  $t-1 \leq -2 \leq t$  i.e.  $-2 \leq t \leq -1$

$$\Rightarrow y_1(t) = e^t \int_{-2}^t e^{-2\tau} d\tau = \frac{1}{2} (e^{-2t} - e^{t+4})$$

iii)  $\boxed{t < -2}$   $y_1(t) = 0$ . Thus,  $y_1(t) = \begin{cases} 0 & t < -2 \\ \frac{1}{2}(e^{-t} - e^{t+4}) & -2 \leq t < -1 \\ \frac{1}{2}(e^{-t} - e^{-t+2}) & t \geq -1 \end{cases}$

Consider  $y_2(t)$ :

$$y_2(t) = \int_{-\infty}^{\infty} e^{-\tau} u(\tau+2) \underbrace{u(-\tau+(t+1))}_{\text{non-zero in } \tau \in [t, t+1]} u(t-\tau) d\tau.$$



If  $\boxed{t > -2} \Rightarrow y_2(t) = \int_t^{t+1} e^{-\tau} d\tau = e^{-t} (1)$

If  $t \in [-3, -2] \Rightarrow y_2(t) = \int_{-2}^{-1} e^{-\tau} d\tau = e^{-t} (t+3)$

If  $\cancel{t > -3} \Rightarrow y_2(t) = 0$ .

$$y_2(t) = \begin{cases} 0 & t \leq -3 \\ e^{-t}(t+3) & -3 < t \leq -2 \\ e^{-t} & t > -2 \end{cases}$$

We have:

$$y(t) = e^{-t} u(t+2) - y_1(t) - y_2(t)$$

$$y(t) = \begin{cases} 0 & t < -3 \\ -e^{-t}(t+3) & -3 \leq t < -2 \\ e^{-t} - \frac{1}{2}(e^{-t} - e^{t+4}) - e^{-t} & -2 \leq t < -1 \\ e^{-t} - \frac{1}{2}(e^{-t} - e^{-t+2}) - e^{-t} & t \geq -1 \end{cases}$$

Thus,  $y(t) = \begin{cases} 0 & t \in (-\infty, -3) \\ -e^{-t}(t+3) & t \in [-3, -2] \\ -\frac{1}{2}(e^{-t} - e^{t+4}) & t \in [-2, -1] \\ -\frac{1}{2}e^{-t}(1 - e^2) & t \in [-1, \infty) \end{cases}$

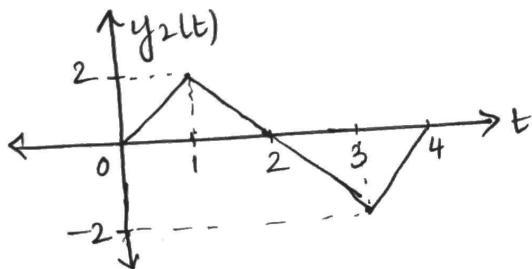
motion (3)

a)  $x_2(t) = x_1(t) - x_1(t-2)$

∴ By linearity:  $S\{x_1(t) - x_1(t-2)\} = S\{x_1(t)\} - S\{x_1(t-2)\}$

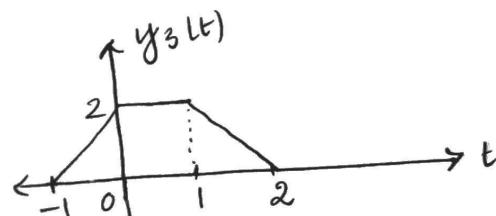
By time invariance:  $S\{x_1(t-2)\} = y_1(t-2)$

∴  $\text{opp} = y_1(t) - y_1(t-2)$



(b)  $x_3(t) = x_1(t) + x_1(t+1)$

⇒  $y_3(t) = y_1(t) + y_1(t+1)$



(c)  $y(t) = \int_{t-2}^t x(\tau) d\tau = \int_{-\infty}^{\infty} x(\tau) u(\tau - (t-2)) \cdot u(t-\tau) d\tau$

$$\therefore h(t) = \int_{-\infty}^{\infty} \delta(\tau) u(\tau - (t-2)) u(t-\tau) d\tau$$

$$= \boxed{u(-t+2) u(t)} = u(-t+2) [1 - u(-t)]$$

$$= u(-t+2) - \underbrace{u(-t+2) u(-t)}_{u(-t)}$$

$$= \boxed{u(-t+2) - u(-t)}$$

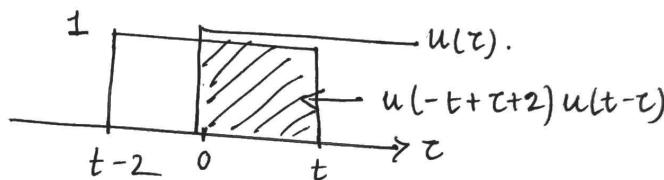
$$\boxed{h(t) = u(-t+2) u(t) = u(-t+2) - u(-t)}$$

Both are correct.

$$\text{Input } u(t) = u(t+2) + u(t) - 2u(t-1) + \delta(t-1)$$

Consider input  $\tilde{u}(t) = u(t)$

$$\begin{aligned}\tilde{y}(t) &= \int_{-\infty}^{\infty} u(\tau) h(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} u(\tau) \underbrace{u(-t+\tau+2) u(t-\tau)}_{\text{non-zero in the range } \tau \in [t-2, t]} d\tau\end{aligned}$$



If  $0 \leq t-2 \Rightarrow [t \geq 2]$

$$\tilde{y}(t) = \int_{t-2}^t 1 \cdot d\tau = 2$$

If  $0 \leq t < 2$

$$\tilde{y}(t) = \int_0^t 1 \cdot d\tau = t$$

If  $t < 0$   $\tilde{y}(t) = 0$

$$\begin{aligned}\tilde{y}(t) &= \begin{cases} t & t \in [0, 2] \\ 2 & t \in [2, \infty) \\ 0 & t \in (-\infty, 0) \end{cases} \\ \Rightarrow \tilde{y}(t) &= t u(t) + -(t-2) u(t-2) \\ &= [t u(t) - (t-2) u(t-2)]\end{aligned}$$

Thus, using Time-invariance property :-

$$s\{u(t+2)\} = \tilde{y}(t+2) = (t+2)u(t+2) - tu(t)$$

$$s\{u(t-1)\} = \tilde{y}(t-1) = (t-1)u(t-1) - (t-3)u(t-3)$$

$$s\{\delta(t-1)\} = h(t-1) = u(-t+3)u(t-1)$$

$$\begin{aligned}\therefore y(t) &= (t+2)u(t+2) - (t-2)u(t-2) - 2(t-1)u(t-1) + 2(t-3)u(t-3) \\ &\quad + u(t-1)u(-t+3)\end{aligned}$$

question 4

$$y(t) = \int_{-\infty}^{\infty} e^{-\sigma} (t-\sigma)^2 u(\sigma+t) \alpha(\sigma-2) d\sigma \quad ; t \in (-\infty, \infty)$$

$$h(t, \tau) = \int_{-\infty}^{\infty} e^{-\sigma} (t-\sigma)^2 u(\sigma+t) \delta(\sigma-\tau-2) d\sigma$$

sifting property :  $\delta \sigma = \tau + 2$

$$\therefore h(t, \tau) = e^{-\tau} (t-\tau-2)^2 u(\tau+2+t)$$

i)  $h(t, \tau) \neq h(t-\tau, 0) \Rightarrow$  ~~Non~~ Time Variant

ii)  $h(t, \tau) u(t-\tau) = e^{-\tau} (t-\tau-2)^2 u(\tau+2+t) u(t-\tau)$   
 $\neq e^{-\tau} (t-\tau-2)^2 u(\tau+2+t) \Rightarrow$  Non-causal

(b)

$$y(t) = \underbrace{\int_{-\infty}^{\infty} e^{-\sigma} (t-\sigma)^2 u(\sigma+t) \delta(\sigma-4) d\sigma}_{y_1} - \underbrace{\int_{-\infty}^{\infty} e^{-\sigma} (t-\sigma)^2 u(\sigma+t) e^{-(\sigma-2)} u(\sigma-1) d\sigma}_{y_2}$$

$$y_1(t) = e^{-t} (t-4)^2 u(t+4)$$

$$y_2(t) = \int_{-\infty}^{\infty} e^{-\sigma} (t-\sigma)^2 \underbrace{u(\sigma+t)}_{e^{-\sigma}} e^2 \cdot \underbrace{u(\sigma-1)}_{e^{\sigma}} d\sigma$$

$$u(\sigma+t) u(\sigma-1) = \begin{cases} u(\sigma-1) & \cancel{t > -1} \\ u(\sigma+t) & t < -1 \end{cases}$$

$$\text{If } t > -1 \Rightarrow y_2(t) = \int_{-1}^{\infty} e^{-t+2} (t-\sigma)^2 e^{-\sigma} d\sigma$$

$$\text{If } t < -1 \Rightarrow y_2(t) = \int_{-t}^{\infty} e^{-t+2} (t-\sigma)^2 e^{-\sigma} d\sigma$$


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$$\int e^2 \cdot e^{-t} \cdot (t-\sigma)^2 \cdot e^{-(\sigma-t)} \cdot e^{-t} \cdot d\sigma$$

$$= \int e^{2-2t} (\sigma-t)^2 e^{-(\sigma-t)} d\sigma$$

$$\text{Let } \sigma-t = \gamma \Rightarrow d\sigma = d\gamma$$

$$\Rightarrow \int e^{2-2t} \cdot \gamma^2 e^{-\gamma} d\gamma$$

$$= -e^{2-2t} [\gamma^2 e^{-\gamma} + 2\gamma e^{-\gamma} + 2e^{-\gamma}]$$

$$= e - e^{2-2t} [(\sigma-t)^2 e^{-(\sigma-t)} + 2(\sigma-t)e^{-(\sigma-t)} + 2e^{-(\sigma-t)}]$$

$$= -e^{2-t} \cdot e^{-\sigma} [(\sigma-t)^2 + 2(\sigma-t) + 2]$$

$$\therefore \text{If } t > -1 : y_2(t) = +e^{2-t} [e^{-1} [(1-t)^2 + 2(1-t) + 2]] \\ = e^{1-t} [t^2 - 4t + 5] = e^{1-t} [(t-2)^2 + 1] u(t+1)$$

$$\text{If } t < -1 : y_2(t) = e^{2-t} \cdot e^{+t} [4t^2 - 4t + 2] \\ = e^2 [(2t-1)^2 + 1] u(-t-1)$$

$$\boxed{\therefore y(t) = y_1(t) - y_2(t) = e^{-t}(t-4)^2 u(t-4) - e^{1-t} ((t-2)^2 + 1) u(t+1) \\ - e^2 [(2t-1)^2 + 1] u(-t-1)}$$