


Lecture 2

① odd and even signals

$$x(t) = x(-t) \text{ even}$$

$$x(t) = -x(-t) \text{ odd}$$

Theorem: Any signal can be decomposed into odd and even components.

$$\underline{x(t) = x_e(t) + x_o(t)}$$

$$x_e(t) = \frac{x(t) + x(-t)}{2}$$

$$x_o(t) = \frac{x(t) - x(-t)}{2}$$

$$\begin{aligned} x_e(-t) &= \frac{x(-t) + x(-(-t))}{2} \\ &= \frac{x(-t) + x(t)}{2} = x_e(t) \end{aligned}$$

Proof: $x_e(t) + x_o(t) =$

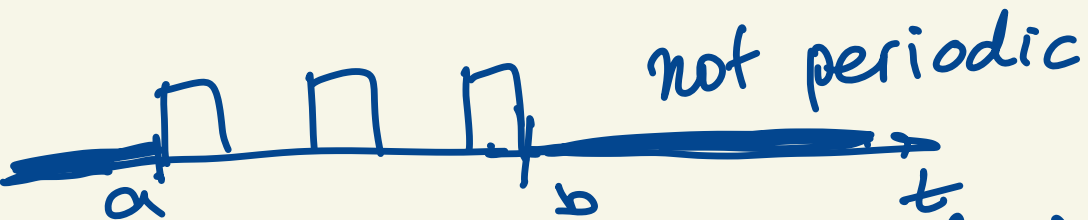
$$= \frac{x(t) + x(-t)}{2} + \frac{x(t) - x(-t)}{2}$$

$$= \frac{x(t) + \cancel{x(-t)} + x(t) - \cancel{x(-t)}}{2}$$

$$= \frac{2x(t)}{2}$$

$$= x(t)$$

Periodic signals



① Periodic signals have infinite support.

Finite support signals have property:

$$\underline{\exists a, b} \text{ s.t. } x(t) = 0 \\ t < a \text{ \& } t > b$$

②

$$\exists T_0 : x_p(t + kT_0) = x_p(t) \\ \forall k \in \mathbb{Z}$$

T_0 - fundamental period.

Properties of periodic signals

case

a) $x(t)$ is periodic w/ T_0

Then

$$y(t) = A + x(t)$$

$\Rightarrow y(t)$ is periodic w/ T_0

$$\begin{aligned}
 y(t + kT_0) &= A + x(t + kT_0) \\
 &= A + x(t) \\
 &= y(t)
 \end{aligned}$$

case

b) $x(t)$ periodic w/ T_0
 $y(t)$ periodic w/ $T_1 = NT_0$
 N is integer

$$z(t) = x(t) + y(t)$$

$z(t)$ is periodic w/ $NT_0 = T_1$

Proof:

$$\begin{aligned}
 z(t + k \cdot NT_0) &= x(t + \underline{kN} \boxed{T_0}) \\
 &\quad + y(t + k \boxed{NT_0})
 \end{aligned}$$

$$= x(t) + y(t)$$

$$= z(t) \Rightarrow z(t) \text{ is periodic w/ } NT_0$$

c) $x(t)$ periodic w/ T_0 .
 $y(t)$ periodic w/ T_1 .

s.t. $\boxed{\frac{T_1}{T_0} = \frac{M}{N}}$ M, N are integers

$$MT_0 = NT_1$$

$$w(t) = x(t) + y(t)$$

$$\Rightarrow w(t) \text{ periodic w/ } MT_0 = \underbrace{NT_1}$$

Proof:

$$\begin{aligned}
 w(t + \underbrace{kNT_1}) &= x(t + kNT_1) \\
 &+ y(t + \underline{\underline{kNT_1}}) \\
 &= x(t + \underline{\underline{kMT_0}}) + y(t) \\
 &= x(t) + y(t) \\
 &= w(t)
 \end{aligned}$$

Example

$$x(t) = e^{j2t} = \cos(2t) + j\sin(2t)$$

$$y(t) = e^{j\pi t}$$

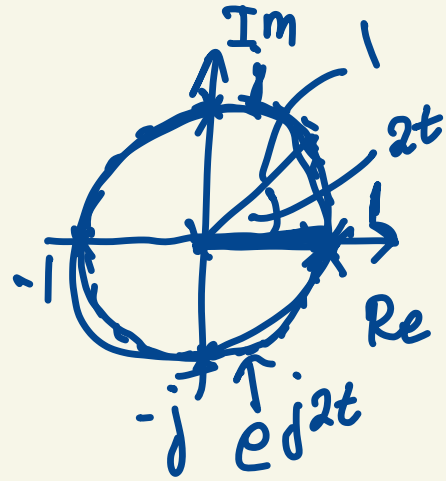
$x(t)$ is periodic w/ $T_0 =$

$$e^{j2(t+T_0)} = e^{j2t}$$

$$e^{j2t} \cdot e^{j2T_0} = e^{j2t}$$

$$\Rightarrow e^{j2T_0} = 1$$

$$e^{j2T_0} = e^{j2\pi}$$



$$\boxed{T_0 = \pi}$$

$$e^{j2t} \text{ w/ } T_0 = \pi$$

$$e^{j\pi t} \text{ w/ } T_1 = 2$$

$$z(t) = x(t) + y(t) = e^{j2t} + e^{j\pi t}$$

$$\frac{T_1}{T_0} = \frac{2}{\pi} \neq \frac{M}{N}$$

$z(t)$ is not periodic

Ex. $x(t) = e^{j2t}$
 $y(t) = e^{j\pi t}$

$$w(t) = x(t) \cdot y(t) = e^{j2t} \cdot e^{j\pi t}$$

$$= e^{j \underbrace{(2+\pi)}_a t}$$

\Rightarrow periodic w/ $T_2 = \frac{2\pi}{2+\pi}$

product of two periodic signals is not necessarily.

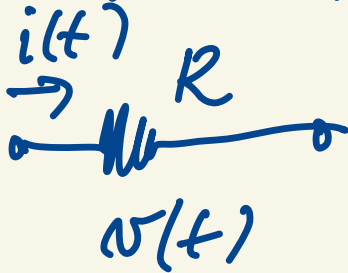
periodic!
 counterexample

$$v(t) = \underbrace{(1 + e^{j2t})} \cdot \underbrace{(1 + e^{j\pi t})}$$

$$\begin{aligned}
 &= 1 + e^{j2t} + e^{j\pi t} + e^{j2t} \cdot e^{j\pi t} \\
 &= \underbrace{1 + e^{j2t}}_{T_0 = \pi} + \underbrace{e^{j\pi t}}_{T_1 = 2} + \underbrace{e^{j(2\pi)t}}_{T_2 = \frac{2\pi}{2+\pi}}
 \end{aligned}$$

$$\frac{T_0}{T_1} \neq \frac{M}{N}$$

Signal power



$$v(t) = i(t) \cdot R$$

$$\begin{aligned}
 p(t) &= i(t) \cdot v(t) \\
 &\uparrow = i^2(t) \cdot R
 \end{aligned}$$

instantaneous power

$$= \frac{v^2(t)}{R}$$

Energy of the signal.

$$E = \int_{t_0}^{t_1} p(t) dt \quad \text{over } t \in [t_0, t_1]$$

$x(t) \rightarrow$ signal

$$E_x \triangleq \int_{-\infty}^{+\infty} x^2(t) dt$$

\nearrow finite energy
 \searrow infinite energy

In general we have complex signals.

$$E_x \triangleq \int_{-\infty}^{+\infty} |x(t)|^2 dt$$

Average power of $x(t)$

$$P_x \triangleq \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

e.g. $x(t) = \cos\left(\frac{\pi}{2}t + \frac{\pi}{4}\right)$

what is P_x ?

$x(t)$ periodic / ω $T_0 = 4$

$$\frac{\pi}{2} \cdot T_0 = 2\pi \quad \underline{T_0 = 4}$$

$$P_x = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T \cos^2\left(\frac{\pi}{2}t + \frac{\pi}{4}\right) dt$$

$$= \lim_{\substack{T \rightarrow \infty \\ NT_0}} \frac{1}{2T_0} \cdot 2 \int_0^{NT_0} \cos^2 \left(\frac{\pi}{2} t + \frac{\pi}{4} \right) dt$$

$$T = N \cdot T_0 \quad T \rightarrow \infty \Rightarrow N \rightarrow \infty$$

$$= \lim_{N \rightarrow \infty} \frac{1}{NT_0} \int_0^{NT_0} \cos^2 \left(\frac{\pi}{2} t + \frac{\pi}{4} \right) dt$$

$$= \lim_{N \rightarrow \infty} \frac{1}{NT_0} \cdot N \cdot \int_0^{NT_0} \cos^2 \left(\frac{\pi}{2} t + \frac{\pi}{4} \right) dt$$

$$= \frac{1}{T_0} \int_0^{T_0} \cos^2 \left(\frac{\pi}{2} t + \frac{\pi}{4} \right) dt$$

$$\cos^2 x = \frac{1 + \cos(2x)}{2}$$

$$= \frac{1}{T_0} \int_0^{T_0} \frac{1 + \cos\left[2\left(\frac{T_0}{2}t + \frac{\pi}{4}\right)\right]}{2} dt$$

$$= \frac{1}{T_0} \int_0^{T_0} \frac{1}{2} dt + \frac{1}{2T_0} \int_0^{T_0} \cos\left(\pi t + \frac{\pi}{2}\right) dt$$

$\textcircled{T_0} = 4$

$$\approx \frac{1}{T_0} \cdot \frac{1}{2} T_0$$

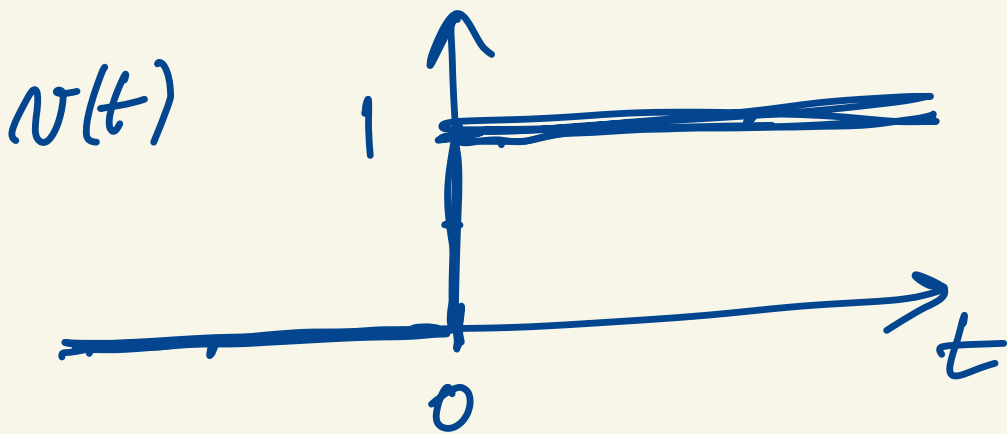
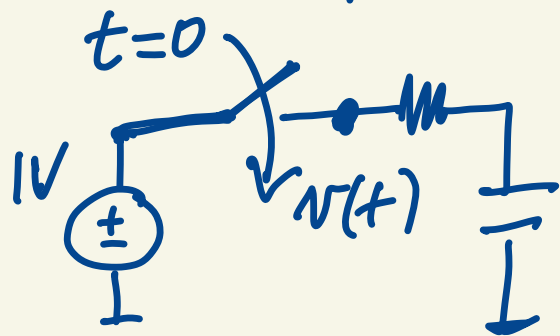
$$= \frac{1}{2}$$

$$\pi \cdot T_1 = 2\pi$$

$$T_1 = 2$$

$$x(t) = \cos(\alpha t + \underline{\underline{\beta}}) \Rightarrow P_x = \frac{1}{2}$$

Unit Step, Unit Impulse and Unit Ramp Signals

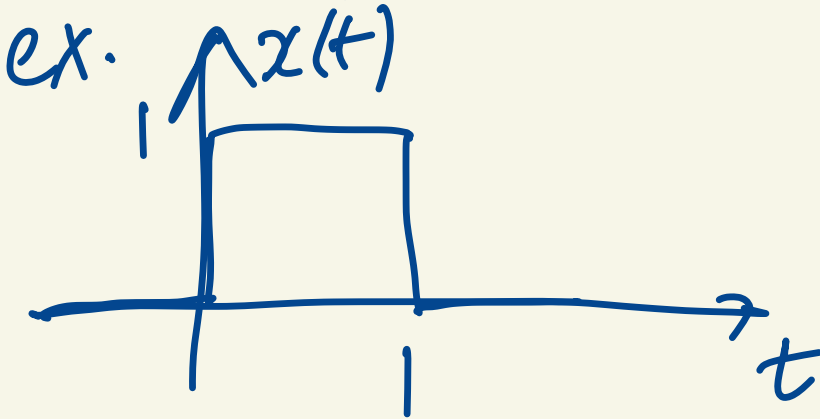
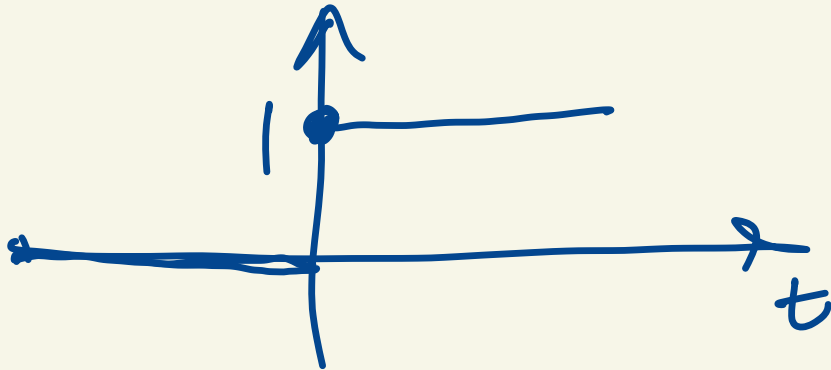


Unit Step $u(t)$

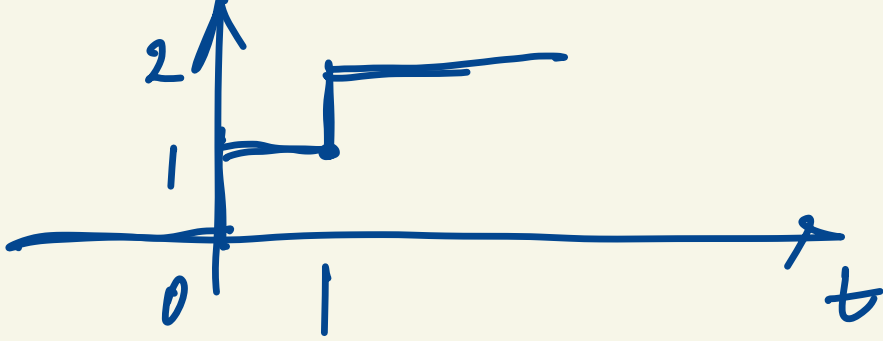
$$u(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$$

in some textbook you may see.

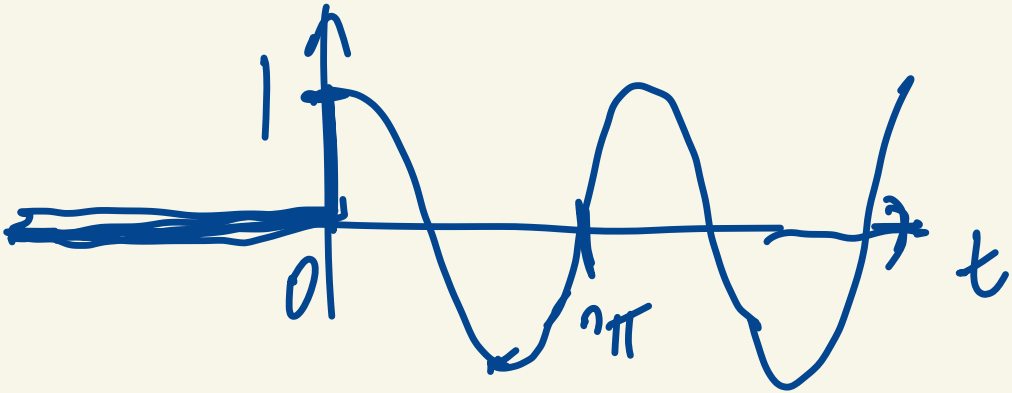
$$u(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$



$$x(t) = u(t) - u(t-1)$$

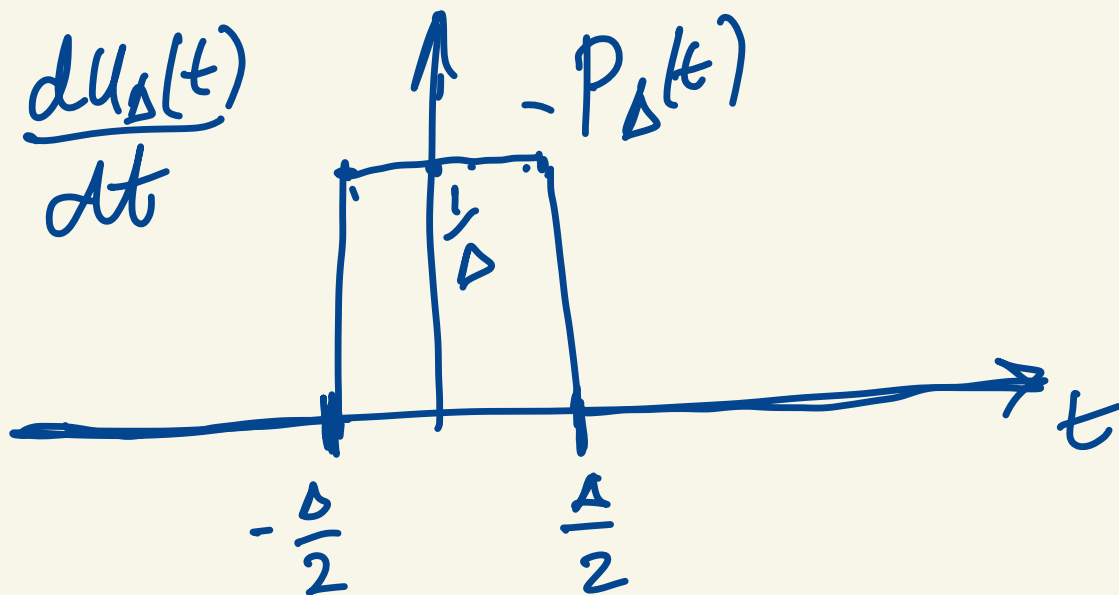
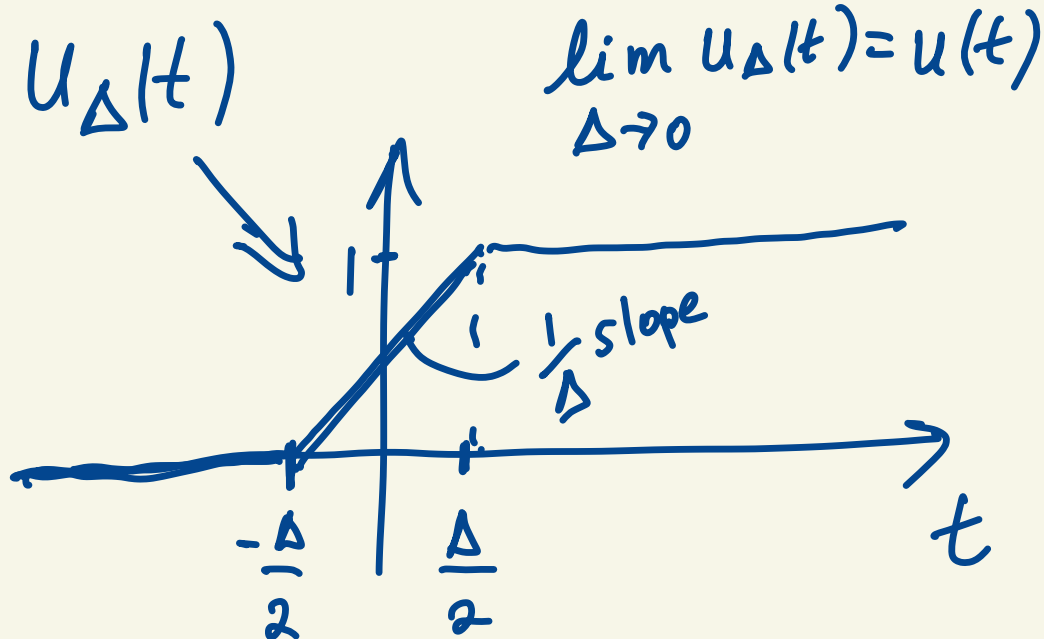


$$x(t) = u(t) + u(t-1)$$



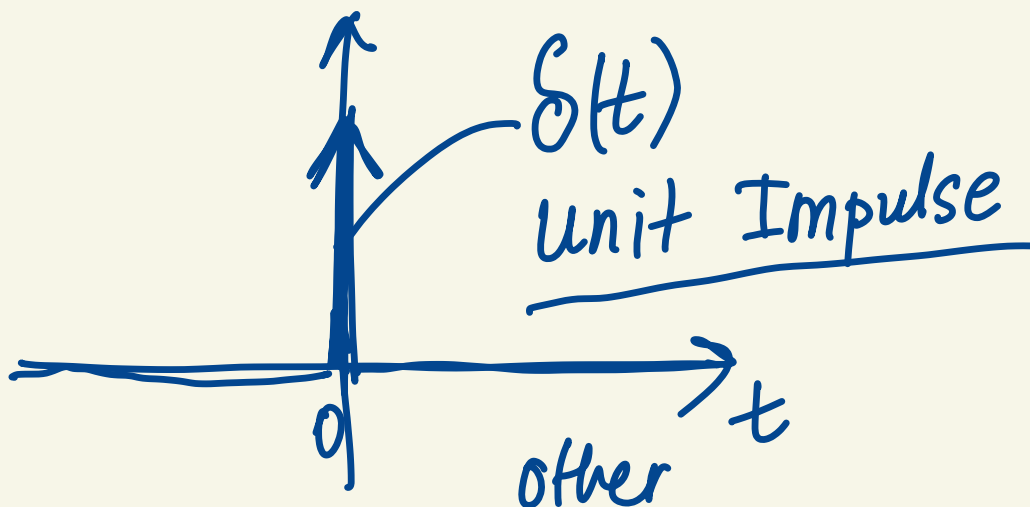
$$x(t) = \cos(t) \cdot u(t)$$

$$\frac{du(t)}{dt} = ?$$



$\Delta \rightarrow 0 \quad u_{\Delta}(t) \rightarrow u(t)$

$P_{\Delta}(t) = \frac{du_{\Delta}(t)}{dt} \rightarrow \delta(t)$



Dirac Delta
function

Delta function

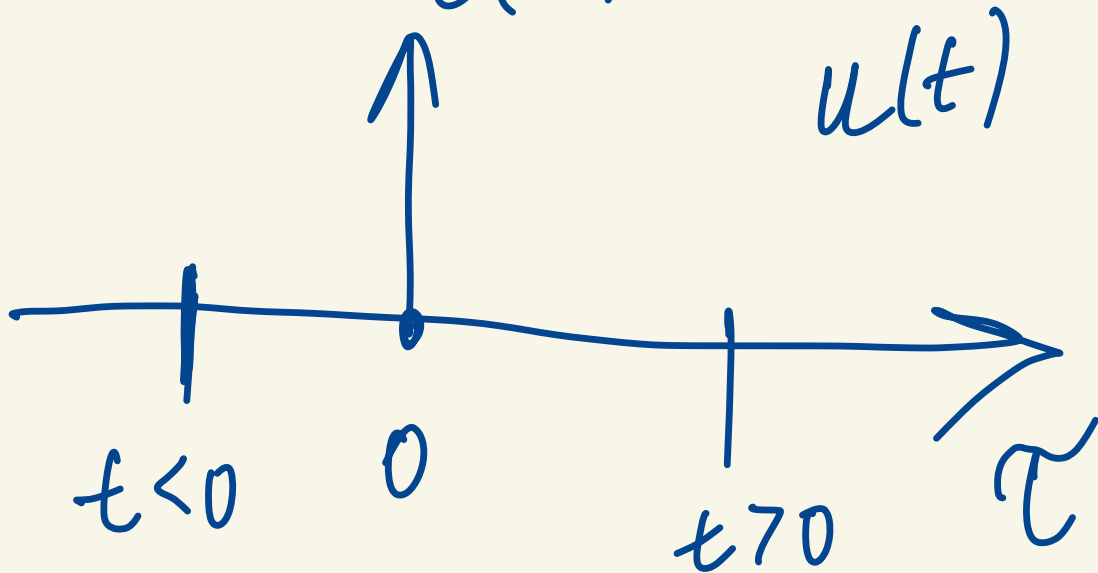
$$\delta(t) \triangleq \frac{d u(t)}{dt}$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

$$\int_{-\infty}^t \delta(\tau) d\tau = \begin{cases} 0 & t < 0 \\ 1 & t > 0 \end{cases}$$

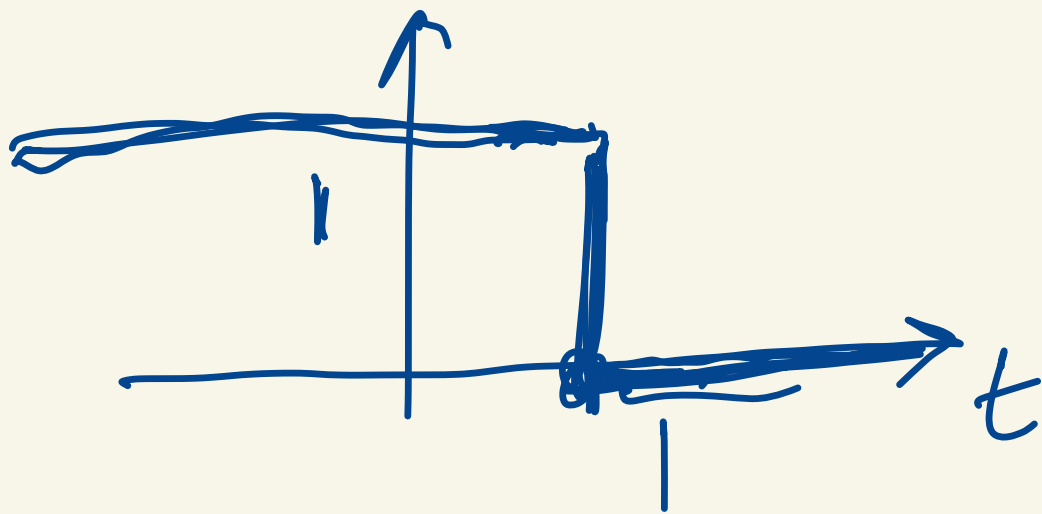
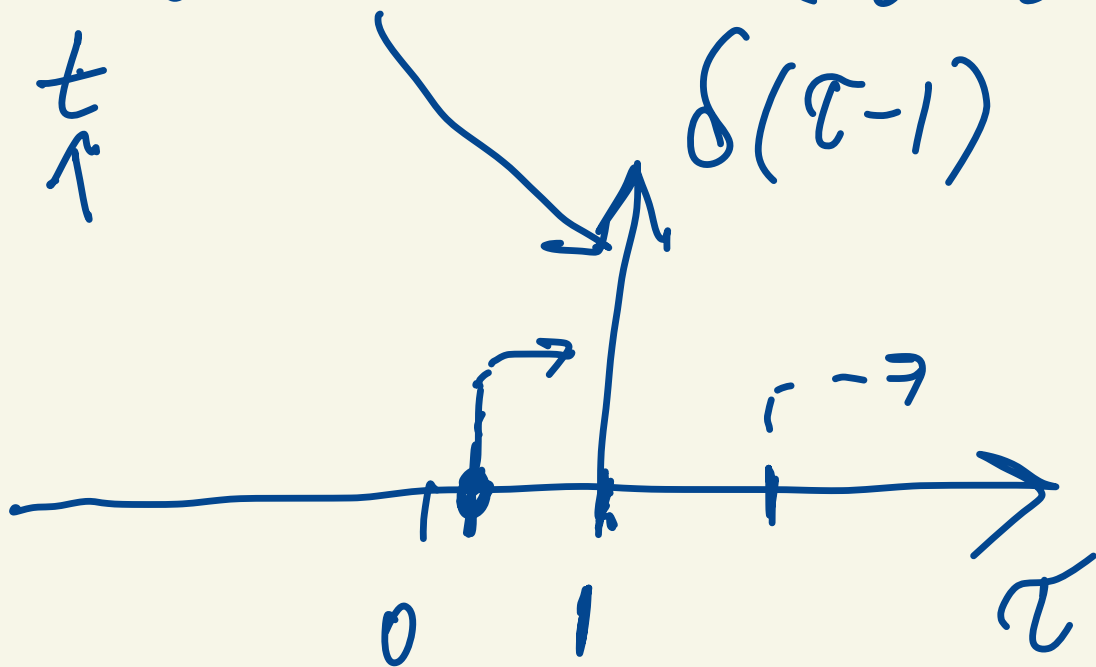
$\delta(\tau)$

$u(t)$



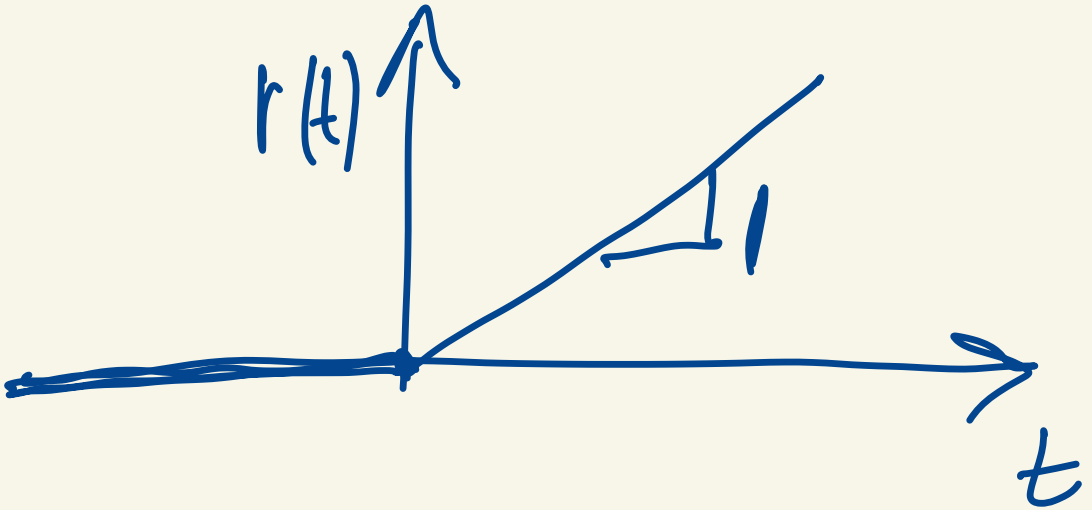
$$\int_{-\infty}^t \delta(\tau) d\tau = u(t)$$

$$\int_{-\infty}^{\infty} \delta(\tau-1) d\tau = \begin{cases} 1 & t < 1 \\ 0 & t > 1 \end{cases}$$



$$u(-t+1)$$

Unit ramp $r(t)$



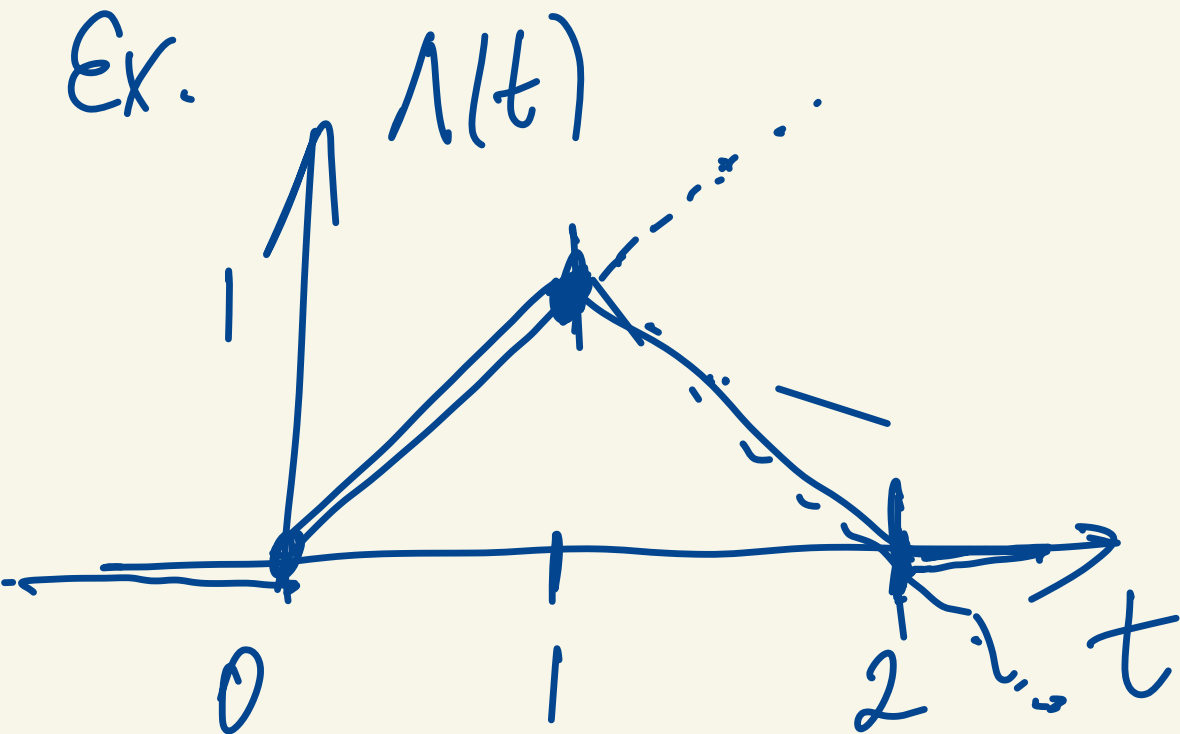
$$r(t) = \begin{cases} t & t > 0 \\ 0 & t < 0 \end{cases}$$

$$r(t) = t \cdot u(t)$$

$$\frac{dr(t)}{dt} = u(t)$$

$$\frac{d^2 r(t)}{dt^2} = \delta(t)$$

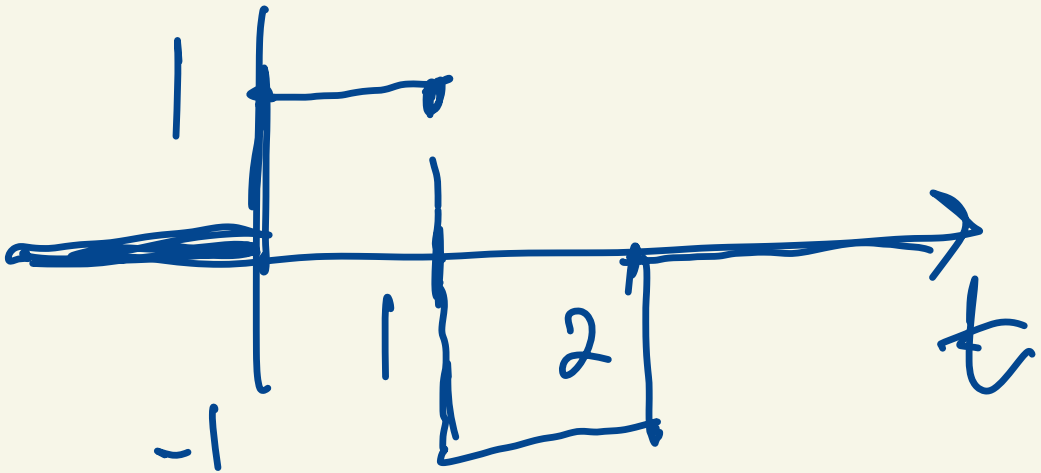
Ex.



$$\lambda(t) = \begin{cases} 0 & t < 0 \\ t & 0 \leq t \leq 1 \\ -t+2 & 1 \leq t < 2 \\ 0 & \text{o.w.} \end{cases}$$

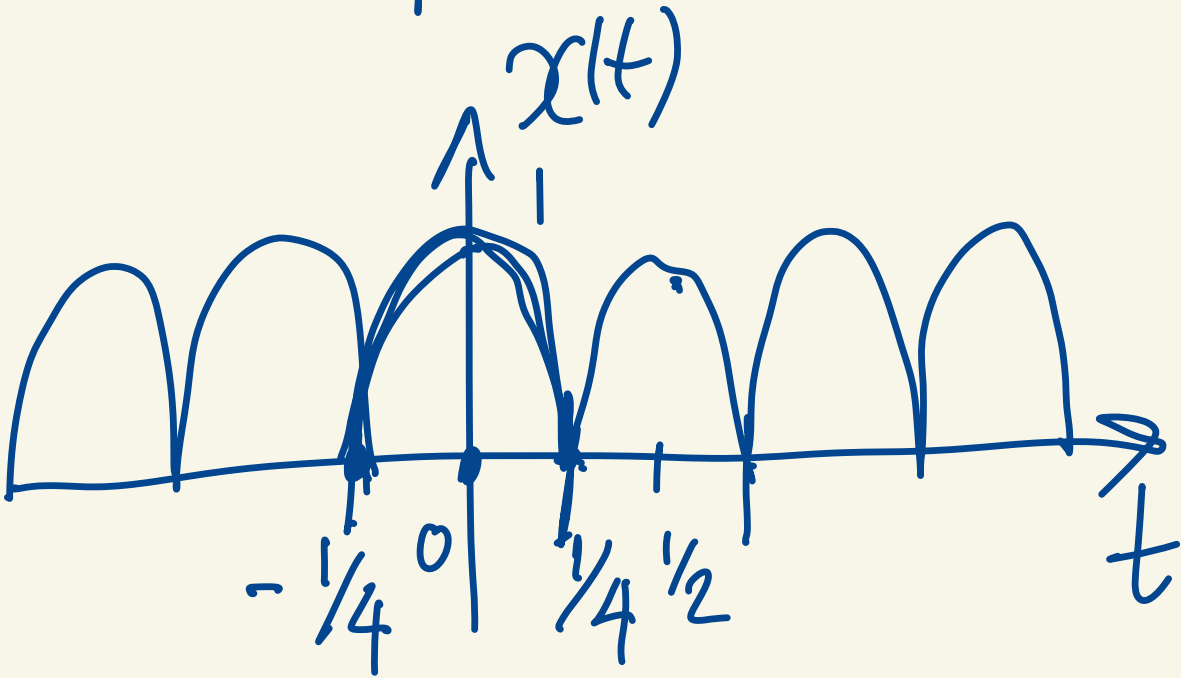
$$\Lambda(t) = r(t) - 2r(t-1) + r(t-2)$$

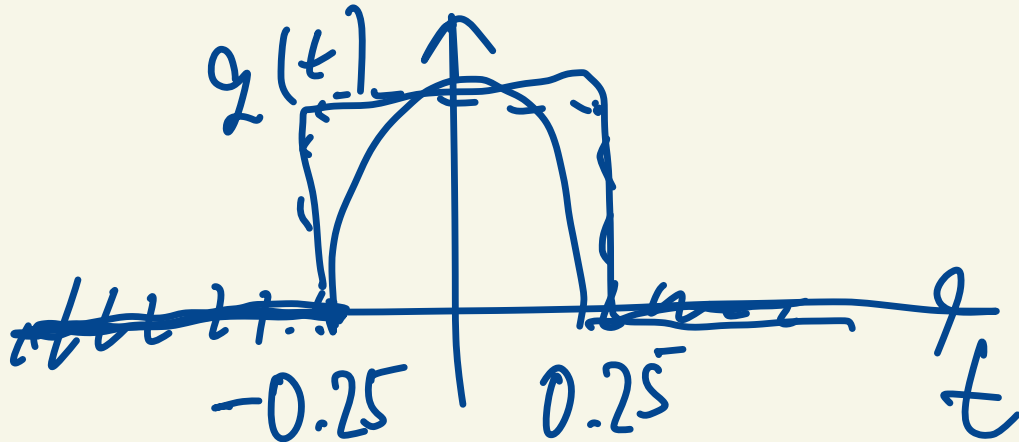
$$\frac{d\Lambda(t)}{dt} = u(t) - 2u(t-1) + u(t-2)$$



Ex. rectified signal

$$x(t) = |\cos(2\pi t)|$$





$$\underline{g(t)} = \cos(2\pi t) \cdot$$

$$\cdot [u(t+0.25) - u(t-0.25)]$$

$$x(t) = \sum_{k=-\infty}^{+\infty} g(t + k \cdot \underline{0.5})$$