

Topics

1. Bifurcation Normal Forms + Taylor Series
2. Non-dimensionalization

Logistics: Extra review OTI: <http://whenisgood.net/www3www> next week

Bifurcation Normal Forms + Taylor Series

Bifurcation Normal Form - Polynomial examples of different bifurcation types. All examples of a specific bifurcation "looks like" the corresponding prototype.

Normal Forms:

Saddle Node - $\dot{x} = r - x^2$
 $\ddot{x} = r + x^2$

Transcritical - $\dot{x} = rx - x^2$
 $\ddot{x} = rx + x^2$

Supercritical Pitchfork - $\dot{x} = rx - x^3$
Subcritical Pitchfork - $\dot{x} = rx + x^3$

- What do we mean when we say $f(x)$ looks like one of these polynomials?
- We mean the Taylor Series of $f(x)$ looks like one of these polynomials.

- Conversely, if the Taylor Series does not look like a normal form, then we have a new bifurcation.

2D Taylor's Theorem:

Taylor's Theorem
[where $(x^*, r^*) = (0, 0) \dots]$

Theorem: Suppose that all partial derivatives of $f(x, r)$ up to order $N+1$ are continuous. Then,

$$f(x, r) = \sum_{n=0}^N \sum_{j=0}^n \frac{1}{(n-j)! j!} \frac{\partial^n f}{\partial x^{n-j} \partial r^j}(0, 0) x^{n-j} r^j + R_N(x, r),$$

where the remainder term can be written as

$$R_N(x, r) = \sum_{j=0}^{N+1} \frac{1}{(N+1-j)! j!} \frac{\partial^{N+1} f}{\partial x^{N+1-j} \partial r^j}(tx, tr) x^{N+1-j} r^j,$$

for some $0 < t < 1$.

Ex: Find the 2nd order Taylor polynomial of $f(x, r) = r + 2x - 1 - 2e^{x-1}$ around the possible bifurcation point.

- We do this via Taylor series

- First look for possible bifurcation points:

$$\begin{aligned} 0 &= f(x, r) = r + 2x - 1 - 2e^{x-1} \quad \rightarrow r = 1 \\ 0 &= \frac{\partial f}{\partial x}(x, r) = 2 - 2e^{x-1} \quad \rightarrow 1 = e^{x-1}, \quad x = 1 \end{aligned}$$

$$\begin{aligned} f(x, r) &= \sum_{n=0}^2 \sum_{j=0}^n \frac{1}{(n-j)! j!} \cdot \frac{\partial^n f}{\partial x^{n-j} \partial r^j}(0, 0) (x-1)^{n-j} (r-1)^j - \text{How to "unwind" this?} \\ &= f(1, 1) + \frac{\partial f}{\partial x}(1, 1)(x-1)^1 + \frac{\partial f}{\partial r}(1, 1)(r-1)^1 \\ &\quad + \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(1, 1)(x-1)^2 + \frac{\partial f}{\partial x} \frac{\partial f}{\partial r}(1, 1)(x-1)(r-1) + \frac{\partial^2 f}{\partial r^2}(1, 1)(r-1)^2 \\ &= (r-1) + \frac{1}{2} (r-2)(x-1)^2 \\ &= (r-1) - (x-1)^2 \end{aligned}$$

Saddle Node Theorem

Theorem: Suppose that

$$\dot{x} = f(x, r)$$

has a bifurcation at $(x, r) = (x^*, r^*)$. If

$$\frac{\partial f}{\partial r}(x^*, r^*) \neq 0 \quad \text{and} \quad \frac{\partial^2 f}{\partial x^2}(x^*, r^*) \neq 0.$$

Then (x^*, r^*) is a saddle-node bifurcation.

Intuition:

$$f(x, r) = f(x^*, r^*) + \frac{\partial f}{\partial x}(x^*, r^*)(x-x^*) + \frac{\partial f}{\partial r}(x^*, r^*)(r-r^*)$$

$$+ \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(x^*, r^*)(x-x^*)^2 + \frac{\partial f}{\partial x}(x^*, r^*)(r-r^*) + \frac{\partial^2 f}{\partial r^2}(r-r^*)^2 + \text{higher order terms}$$

"sufficiently small"

Transcritical Theorem

Theorem: Suppose that

$$\dot{x} = f(x, r)$$

Transcritical Theorem

Theorem: Suppose that

$$\dot{x} = f(x, r)$$

has a bifurcation at $(x, r) = (x^*, r^*)$. If

$$\frac{\partial^n f}{\partial r^n}(x^*, r^*) = 0 \text{ for all } n, \quad \frac{\partial^2 f}{\partial x \partial r}(x^*, r^*) \neq 0, \quad \frac{\partial^2 f}{\partial x^2}(x^*, r^*) \neq 0.$$

Then (x^*, r^*) is a transcritical bifurcation.

$$2 \frac{\partial x^*}{\partial r}$$

$$\frac{\partial x^*}{\partial r} \frac{\partial f}{\partial x} \frac{\partial f}{\partial r} = \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(x^*, r^*)$$

"sufficiently small"

If saddle node case:

$$f(x, r) = \frac{\partial f}{\partial r}(x^*, r^*) \cdot (r - r^*) + \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(x^*, r^*) (x - x^*)^2$$

If transcritical case:

$$f(x, r) = \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(x^*, r^*) (x - x^*)^2 + \frac{\partial f}{\partial x}(x^*, r^*) (x - x^*) (r - r^*)$$

$$\text{Let } X = x - x^*, R = r - r^*$$

Recall

$$f(x, r) = (r - 1) - (x - 1)^2 + \text{H.O.T.}$$

$$= R - X^2, \text{ so the bifurcation at } r = 1 \text{ is a}$$

saddle node.

Saddle node:

$$f(x, r) = A \cdot R + B \cdot X^2$$

Transcritical:

$$f(x, r) = C \cdot R \cdot X + B \cdot X^2$$

Dimensionalization

Dimensionless Analysis: Removes dimension from ODE

1. Rescales by ϵ and makes it easier to understand scale

$$\text{Ex: } y(t) = e^{t/L} \text{ seconds} \quad \text{Ex: } R = \frac{v \cdot u}{L} \quad v = \text{velocity (m/s)} \\ \uparrow \quad \uparrow \quad \uparrow \quad u = \text{flow speed (m/s)}$$

Population is

1,000,000

Reynolds
Number

$L = \text{layer (m)}$

$t = \text{dynamic viscosity (kg/m-s)}$

t is large ($t \approx 10$)

- Population is 1,000,000 $\approx 10^{10}$

2. Reduces # of parameters by grouping them into dimensionless groups

Ex: " $\dot{g} = k_1 s_0 - k_2 \cdot g + \frac{k_3 g^2}{k_4^2 + g^2}$ ". Here, $g(t), s_0$ are chemical concentrations. Show this system can be put

$k > 0$) constants

s_0 into dimensionless form $\frac{dx}{dt} = s - rx + \frac{x^2}{1+x^2}$ where r, s, x are dimensionless groups."

1. Let $x = \frac{g}{M}, t = \frac{t}{T}$ where M and T are TBD. We also get the relations in derivatives:

$$\begin{aligned} dx &= \frac{dg}{dt} = \frac{dg}{d\tau} \cdot \frac{d\tau}{dt} = \frac{1}{T} \cdot \frac{dg}{d\tau} \\ \frac{d}{dt} &= \left(\frac{d}{d\tau} \right) \cdot \frac{d\tau}{dt} = \frac{1}{T} \cdot \frac{d}{d\tau} \end{aligned} \quad \left. \begin{aligned} \frac{dx}{dt} &= \frac{1}{T} \cdot \frac{dg}{d\tau} \\ \frac{dx}{dt} &= \frac{1}{T} \cdot \frac{d\tau}{dt} \cdot \frac{dg}{d\tau} \end{aligned} \right\}$$

2. Substitute and plug into ODE:

$$\frac{M}{T} \cdot \frac{dx}{dt} = k_1 s_0 - k_2 \cdot (Mg) + \frac{k_3 (Mx)^2}{k_4^2 + (Mx)^2}$$

$$\frac{dx}{dt} = \frac{T \cdot k_1 s_0}{M} - \frac{k_2 \cdot M \cdot x}{T} + \frac{T \cdot k_3 \cdot M^2 \cdot x^2}{M \cdot k_4^2 + M^2 \cdot x^2}$$

3. Force M, T to be what you want

$$\text{Let } s = \frac{I}{m} \cdot k_1 \cdot s_0$$

$$r = k_2 / T$$

Now look at the fraction:

$$\frac{T \cdot k_3 \cdot M \cdot x^2}{k_4^2 + M^2 \cdot x^2} = \frac{T \cdot k_3 \cdot M \cdot x^2}{k_4^2 \left(1 + \frac{M^2}{k_4^2} x^2 \right)} \quad \text{Let } \frac{M^2}{k_4^2} = 1 \quad (M = k_4)$$

$$\text{Let } \frac{T \cdot k_3 \cdot M}{k_4^2} = 1 \quad (T = \frac{k_4}{k_3})$$

$$\text{So, } \frac{dx}{dt} = s - rx + \frac{x^2}{1+x^2}$$