## DIP HW2 Report

# R07922036 邱能賢 March 27, 2019

### Problem 1: Edge Detection

(a) Perform first order edge detection as image  $E_1$ .

To perform first order edge detection, I used Roberts cross differentiation and only kept its magnitude.

The threshold is calculated by first calculate the CDF and set the threshold at the intensity at 80% of pixels.

(b) Perform second order edge detection as image  $E_2$ .

To perform second order edge detection, I first convolute the image with a low-pass filter then with a separable 8-neighbor laplacian filter.

$$Gaussian = \frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}, H = \frac{1}{8} \begin{bmatrix} -2 & 1 & -2 \\ 1 & 4 & 1 \\ -2 & 1 & -2 \end{bmatrix}$$

Then, with a threshold of  $\pm 2.5$ , set the value to  $\pm 1$  if above the threshold, otherwise 0. At last, check zero-crossing considering the 8-neighbor (four directions).

(c) Perform Canny edge detection as image  $E_2$ .

Canny edge detection is done as the following method:

(a) Noise reduction with Gaussian filter:

$$Gaussian = \frac{1}{159} \begin{bmatrix} 2 & 4 & 5 & 4 & 2 \\ 4 & 9 & 12 & 9 & 4 \\ 5 & 12 & 15 & 12 & 5 \\ 4 & 9 & 12 & 9 & 4 \\ 2 & 4 & 5 & 4 & 2 \end{bmatrix}$$

(b) Compute gradient magnitude and orientation with Sobel filter:

$$G_x = \begin{bmatrix} -1 & 0 & 1 \\ -2 & 0 & 2 \\ -1 & 0 & 1 \end{bmatrix}, G_y = \begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{bmatrix}$$

(c) Non-maximal suppression:

The orientation is modded to  $[0, \pi/128]$  and the nearest neighbor is calculate by interpolation of the 8-neighbor.

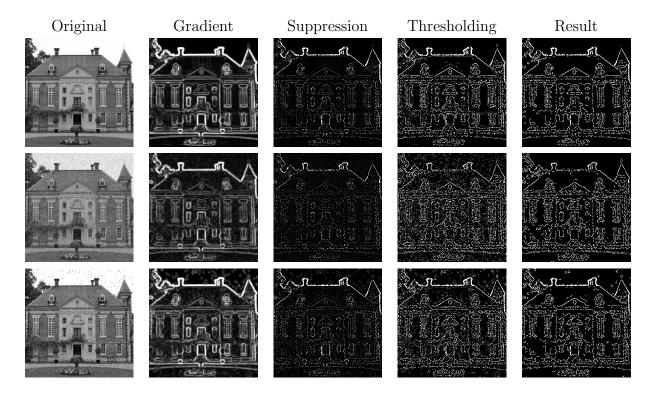


Table 1: Result after each step of Canny edge detection.

### (d) Hysteretic thresholding:

The higher threshold is set to the intensity at 90% of CDF, and the lower threshold is the half of the higher value.

#### (e) Connected component labeling method:

Using breadth-first search considering all the 8-neighbor.

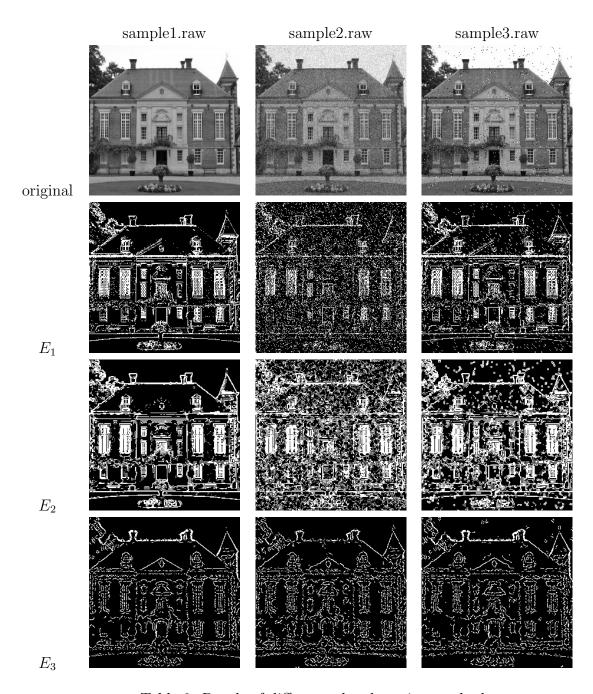


Table 2: Result of different edge detecting method.

#### Problem 2: Noise Removal

(a) Perform edge crispening on  $I_2$  as image C.

To perform edge crispening, I simple convolute the image with the following high pass filter, which showed the best result in the textbook:

$$H = \begin{bmatrix} -1 & -1 & -1 \\ -1 & 9 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$

As a result, I think not only the edge is crispened, but also the contrast is increased.



 $I_2$ , sample4.raw



image C

(b) Design a warping method to produce D from C. D is a swirled disk with diameter of 256 pixels.

For coordinate (i, j) relative to the center of the image:

(a) Wrap to a circle:

$$r = \sqrt{i^2 + j^2}, \theta = atan(\frac{j}{i})$$

$$(r, \theta) \to (r \times \max(|\cos(\theta)|, |\sin(\theta)|), \theta)$$

(b) Swirl transformation,  $\rho$  is the radius of the image:

