

Research Note

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Introduction

Composite adaptive control combines *direct* and *indirect* schemes of adaptive control [6]. The purpose is

- to obtain the global asymptotic stability of *both* tracking and parameter estimation errors with proper exciting conditions and a matching condition, or
- to simply improve the tracking performance, where the matching condition or the exciting conditions are not satisfied.

FUNDAMENTAL IDEA is to exploit a current estimation of the parameter estimation error. Consider¹

$$\dot{e}(t) = Ae(t) + B(u(t) + \Delta(t)).$$

¹ We define $\Delta(t) = W^{*T}\phi(t) + \varepsilon(t)$.

Convert this system into²

$$y(t) = W^{*T}\phi(t) + \varepsilon(t), \quad (1)$$

² Sometimes we filter the system as

$$y_f = W^{*T}\phi_f(t) + \varepsilon_f(t),$$

where $y(t)$ is measured using

$$y(t) = B^T(\dot{e}(t) - Ae(t)) - u(t).$$

Observation 1.

1. equation (1) is merely a linear regression form, and
2. almost all composite adaptive control schemes [6, 2, 3] use the update law of standard least square regression, which are represented by

$$\dot{W}(t) = \Gamma_1 \phi(t) e^T P B - \int_0^t c(t, \tau) \phi(\tau) \varepsilon^T(t, \tau) d\tau, \quad (2)$$

where

$$\varepsilon(t, \tau) = W^T(t) \phi(\tau) - y(\tau).$$

Observation 2. Consider $c(t, \tau)$ in equation (2),

1. **Standard Least Square Update [9]:** If $c(t, \tau) = \delta(t - \tau)$ where δ is a Dirac delta function, then the update law is a standard least square form, which requires the PE condition for exponential convergence.

2. **Concurrent Learning [3]:** If $c(t, \tau) = \sum_{i=1}^p \delta(t_i - \tau)$ for $0 \leq t_i \leq t$, then the update law is a concurrent learning form, which requires the exciting over finite interval condition.
3. **Y. Pan [8] and N. Cho [2]:** If $c(t, \tau) = \exp\left(-\int_{\tau}^{t_i} k(\nu) d\nu\right)$ for $t_0 \leq t_i \leq t$, then the update law is the form suggested in, which requires the IE or FE condition.

Motivation

- **Without the PE Condition:** The standard least square update is valid only with the PE condition.
- **Time-Varying Parameters:** Concurrent learning, Y. Pan and N. Cho's algorithms are not suited for time-varying parameter estimation, as it can be stuck in the past time where the minimum singular/eigenvalue are dominant.
- **Stochastic Estimation:** The standard least square update can deal with the stochastic estimation³ only when the PE condition is satisfied. Concurrent learning and its variations are sensitive to such noises, as the history stack algorithms are heavily dependent on the singular values.
- **Smooth Estimation:** Parameter estimation in concurrent learning, Y. Pan and N. Cho's algorithms are not smooth, as the update is piecewise constant in time.

³ $\varepsilon(t)$ is a random variable

Preliminaries

Theorem 1 (Weyl, see [4]). Let A and B be n -by- n Hermitian matrix and let the respective eigenvalues of A , B , and $A + B$ be $\{\lambda_i(A)\}_{i=1}^n$, $\{\lambda_i(B)\}_{i=1}^n$, and $\{\lambda_i(A + B)\}_{i=1}^n$, ordered algebraically as $\lambda_{\max} = \lambda_n \geq \lambda_{n-1} \geq \dots \geq \lambda_2 \geq \lambda_1 = \lambda_{\min}$. Then,

$$\lambda_i(A + B) \leq \lambda_{i+j}(A) + \lambda_{n-j}(B), \quad j = 0, 1, \dots, n - i$$

for each $i = 1, \dots, n$. Also,

$$\lambda_{i-j+1}(A) + \lambda_j(B) \leq \lambda_i(A + B), \quad j = 1, \dots, i$$

for each $i = 1, \dots, n$.

Definition 1 (Additive spread, see [7]). Let A be n -by- n matrix and let the eigenvalues of A be $\{\lambda_i\}_{i=1}^n$. The *additive spread* is defined as

$$\text{ads } A = \max_{i,j} |\lambda_i - \lambda_j|.$$

Corollary 1 (Merikoski, see [7]). *Let A and B be Hermitian n -by- n matrices. Then,*

$$\text{ads}(A + B) \leq \text{ads } A + \text{ads } B$$

Theorem 2 (Bhatia, see [1]). *Let $A, B \in \mathcal{M}_n(\mathbb{C})$ be compact operators. Then for $j = 1, 2, \dots$, we have*

$$2s_j(A^*B) \leq s_j(AA^* + BB^*)$$

where $s_j(A)$, $j = 1, 2, \dots$ denote the singular values of A in increasing order.

Problem Formulation

Consider the second term of (2), which can be represented by

$$\dot{U}(t) = -p_1(t)U(t) + p_2(t)\phi(t)\phi^T(t), \quad U(0) = 0.$$

With slight abuse of notations for simplicity, the discrete counterpart can be written as

$$A^{k+1} = a_k A^k + b_k v_k v_k^T, \quad A^0 = 0, \quad (3)$$

for $a_k \in (0, 1]$, $b_k \geq 0$, and $A^k := U(t_0 + k\Delta t)$, $v_k := \phi(t_0 + k\Delta t)$.

THE PURPOSE is to design a_k and b_k

1. to increase the minimum eigenvalue of A^k as k increases, and
2. to bound, simultaneously, the maximum eigenvalue of A^k .

for given v_k at each step k .

Main Results

Let A be an n -by- n positive semidefinite matrix, and v be an n -dimensional real vector, and $\{\lambda_i(\cdot)\}$ be the eigenvalues of (\cdot) ordered algebraically as $\lambda_{\max} = \lambda_n \geq \lambda_{n-1} \geq \dots \geq \lambda_2 \geq \lambda_1 = \lambda_{\min}$.

Let Λ and X be the diagonal matrix of eigenvalues of A , and the corresponding matrix of eigenvectors, i.e.

$$A = X\Lambda X^T.$$

Finally, let

$$A' = aA + bv v^T,$$

which is an abbreviated form of (3).

Lemma 1. *If there exist $r \in [0, 1]$ such that*

$$a \cdot \text{ads } A + b\|v\|^2 \leq r \cdot \text{ads } A. \quad (4)$$

for some $a \in (0, r]$ and $b \geq 0$, then,

$$\text{ads } A' \leq r \cdot \text{ads } A.$$

Proof. From Corollary 2 of [7],

$$\begin{aligned} \text{ads } A' &= \text{ads}(aA + bvv^T) \\ &\leq \text{ads}(aA) + \text{ads}(bvv^T) \\ &= a \text{ads } A + b\|v\|^2 \\ &\leq r \cdot \text{ads } A \end{aligned}$$

□

Lemma 2. *For all $a, b \geq 0$, and $j = 1, \dots, n$,*

$$2\sqrt{ab}\lambda_j\left(\Lambda^{1/2} \text{diag}(X^T v)\right) \leq \lambda_j(A').$$

Proof. Observe that $A = X\Lambda^{1/2}(X\Lambda^{1/2})^T$ and $vv^T = XC(XC)^T$ where $C := \text{diag}(X^T v)$. From Bhatia's theorem [1], we have

$$\begin{aligned} \lambda_j(A') &= s_j\left((\sqrt{a}X\Lambda^{1/2})(\sqrt{a}X\Lambda^{1/2})^T + (\sqrt{b}XC)(\sqrt{b}XC)^T\right) \\ &\geq 2s_j\left(\sqrt{ab}\Lambda^{1/2}X^T XC\right) \\ &= 2\sqrt{ab}\lambda_j\left(\Lambda^{1/2}C\right). \end{aligned}$$

□

Lemma 3. *For all $a, b \geq 0$,*

$$2\sqrt{ab}\left\|\Lambda^{1/2}X^T v\right\|_\infty \leq \lambda_{\max}(A') \leq a\lambda_{\max}(A) + b\|v\|^2. \quad (5)$$

Proof. The right inequality (5) is directly derived from Weyl's theorem [4] as

$$\lambda_n(A') \leq a\lambda_n(A) + b\lambda_n(vv^T),$$

and the left inequality is from Lemma 2 for $j = n$. □

Now, we want to derive an algorithm that

1. increases the minimum eigenvalue,

$$\lambda_1(A') \geq \lambda_1(A),$$

2. and bounding the maximum eigenvalue as

$$\lambda_{\max}(A') \leq \lambda_{\max}(A).$$

Given r , from Lemma 1, we have the following condition

$$(\text{ads } A)a + \|V\|^2 b \leq r \cdot \text{ads } A. \quad (6)$$

Moreover, from Lemma 3, we have following two conditions

$$ab \geq \frac{\lambda_1(A) + r \cdot \text{ads } A}{4\|\Lambda^{1/2}X^T v\|_\infty^2} \quad (7)$$

$$\lambda_n(A)a + \|v\|^2 b \leq \lambda_n(A)$$

Theorem 3. Let A be an n -by- n positive semidefinite matrix with $\text{ads } A > 0$, and v be an n -dimensional vector. Also, let $A' = aA + bvv^T$, for $a \in (0, 1]$ and $b \geq 0$. Suppose that there exists (a, b, r) such that

$$a \leq r \leq 1, \quad (8a)$$

$$\text{ads } A \cdot a + \|v\|^2 b \leq \text{ads } A \cdot r, \quad (8b)$$

$$ab \leq \frac{(\lambda_1(A) + \text{ads } A \cdot r)^2}{4\|\Lambda^{1/2}X^T v\|_\infty^2} \quad (8c)$$

Then,

$$\lambda_{\min}(A') \geq \lambda_{\min}(A), \quad (9a)$$

$$\lambda_{\max}(A') \leq \lambda_{\max}(A). \quad (9b)$$

Proof. From Lemma 1, and Lemma 3, we have

$$\begin{aligned} \lambda_1(A') &\geq \lambda_n(A') - \text{ads } A \cdot r \\ &\geq 2\sqrt{ab}\|\Lambda^{1/2}X^T v\|_\infty - \text{ads } A \cdot r. \end{aligned}$$

Since ab satisfies the condition (8c), $\lambda_1(A') \geq \lambda_1(A)$.

Now, from the second inequality of Lemma (3), and the condition (8a),

$$\begin{aligned} \lambda_n(A') &\leq a\lambda_n(A) + b\|v\|^2 \\ &= \text{ads } A \cdot a + \|v\|^2 b + a\lambda_1(A) \\ &\leq \text{ads } A \cdot r + a\lambda_1(A) \\ &= r\lambda_n(A) - (r - a)\lambda_1(A) \end{aligned}$$

From the condition (8b),

$$\lambda_n(A')$$

□

Another Approach

Theorem 4 (Ipsen, see [5]). Let $A \in \mathbb{C}^{n \times n}$ be Hermitian, $y \in \mathbb{C}^n$.

1. (smallest eigenvalue). Let

$$L_{\pm} := \begin{pmatrix} \lambda_2(A) & 0 \\ 0 & \lambda_1(A) \end{pmatrix} \pm \begin{pmatrix} \|y_{2:n}\| \\ y_1 \end{pmatrix} \begin{pmatrix} \|y_{2:n}\| & \bar{y}_1 \end{pmatrix},$$

$$U_{\pm} := \begin{pmatrix} \lambda_2(A) & 0 \\ 0 & \lambda_1(A) \end{pmatrix} \pm \begin{pmatrix} y_2 \\ y_1 \end{pmatrix} \begin{pmatrix} \bar{y}_2 & \bar{y}_1 \end{pmatrix}.$$

Then

$$\lambda_{\min}(L_{\pm}) \leq \lambda_{\min}(A \pm yy^*) \leq \lambda_{\min}(U_{\pm}),$$

where

$$\lambda_{\min}(A) \leq \lambda_{\min}(L_+) \leq \lambda_{\min}(U_+) \leq \lambda_2(A),$$

$$\lambda_{\min}(A) - \|y\|^2 \leq \lambda_{\min}(L_-) \leq \lambda_{\min}(U_-) \leq \lambda_{\min}(A).$$

2. (largest eigenvalue). Let

$$L_{\pm} := \begin{pmatrix} \lambda_n(A) & 0 \\ 0 & \lambda_{n-1}(A) \end{pmatrix} \pm \begin{pmatrix} \|y_n\| \\ y_{n-1} \end{pmatrix} \begin{pmatrix} \bar{y}_n & \bar{y}_{n-1} \end{pmatrix},$$

$$U_{\pm} := \begin{pmatrix} \lambda_n(A) & 0 \\ 0 & \lambda_{n-1}(A) \end{pmatrix} \pm \begin{pmatrix} y_n \\ \|y_{1:n-1}\| \end{pmatrix} \begin{pmatrix} \bar{y}_n & \|y_{1:n-1}\| \end{pmatrix}.$$

Then

$$\lambda_{\max}(L_{\pm}) \leq \lambda_{\max}(A \pm yy^*) \leq \lambda_{\max}(U_{\pm}),$$

where

$$\lambda_{\max}(A) \leq \lambda_{\max}(L_+) \leq \lambda_{\max}(U_+) \leq \lambda_{\max}(A) + \|y\|^2,$$

$$\lambda_{n-1}(A) \leq \lambda_{\max}(L_-) \leq \lambda_{\max}(U_-) \leq \lambda_{\max}(A).$$

Lemma 4. Let $A \in \mathbb{C}^{n \times n}$ be Hermitian, $v \in \mathbb{C}^n$, and $A' := aA + bv v^T$ for $a, b \geq 0$. Then,

$$\lambda_{\min}(A') \geq a\lambda_1(A) + \frac{1}{2} \left(a \operatorname{gap}_1(A) + b\|v\|^2 - \sqrt{(a \operatorname{gap}_1(A) + b\|v\|^2)^2 - 4ab \operatorname{gap}_1(A)|v_1|^2} \right), \quad (10)$$

and

$$\lambda_{\max}(A') \leq a\lambda_n(A) + \frac{1}{2} \left(-a \operatorname{gap}_n(A) + b\|v\|^2 + \sqrt{(a \operatorname{gap}_n(A) + b\|v\|^2)^2 - 4ab \operatorname{gap}_n(A)|v_{1:n-1}|^2} \right), \quad (11)$$

Proof. With the fact that $\lambda_i(aA) = a\lambda_i(A)$, and $\operatorname{gap}_i(aA) = a \operatorname{gap}_i(A)$, the proof directly follows Theorem 2.1, and Corollary 2.2 of [5]. \square

For simplicity, we abbreviate $\lambda_i := \lambda_i(A)$, and $\operatorname{gap}_i := \operatorname{gap}_i(A)$. Define a function $f : \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$, such that

$$f(a, b) := a\lambda_1 + \frac{1}{2} \left(a \operatorname{gap}_1 + b\|v\|^2 - \sqrt{(a \operatorname{gap}_1 + b\|v\|^2)^2 - 4ab \operatorname{gap}_1 |v_1|^2} \right). \quad (12)$$

Lemma 5. $f(a, b)$ is a monotonically increasing function for each $a \geq 0$ and $b \geq 0$.

Moreover, given a ,

$$\lim_{b \rightarrow \infty} f(a, b) = a \left(\lambda_1(A) + \text{gap}_1(A) \frac{|v_1|^2}{\|v\|^2} \right).$$

Lemma 6. Suppose that there exist $a, b \geq 0$, such that $f(a, b) \geq \lambda_1(A)$. Then

$$a \geq \frac{\lambda_1(A)}{\lambda_2(A)}. \quad (13)$$

Theorem 5. Suppose that there exist $a \in (0, 1]$ and $b \geq 0$ satisfying the following two hyperbolic inequalities

$$a^2 + \frac{k_1 \|v\|^2}{\lambda_1} ab - \frac{2\lambda_1 + \text{gap}_1}{\lambda_1 + \text{gap}_1} a - \frac{\|v\|^2}{\lambda_1 + \text{gap}_1} b + \frac{\lambda_1}{\lambda_1 + \text{gap}_1} \geq 0, \quad (14)$$

$$a^2 + \frac{k_n \|v\|^2}{\lambda_n} ab - \frac{2\lambda_n - \text{gap}_n}{\lambda_n - \text{gap}_n} a - \frac{\|v\|^2}{\lambda_n - \text{gap}_n} b + \frac{\lambda_n}{\lambda_n - \text{gap}_n} \geq 0, \quad (15)$$

where

$$\begin{aligned} \frac{\lambda_1}{\lambda_1 + \text{gap}_1} &\leq k_1 := \frac{\lambda_1 + \frac{|v_1|^2}{\|v\|^2} \text{gap}_1}{\lambda_1 + \text{gap}_1} \leq 1, \\ 1 &\leq k_n := \frac{\lambda_n - \frac{|v_n|^2}{\|v\|^2} \text{gap}_n}{\lambda_n - \text{gap}_n} \leq \frac{\lambda_n}{\lambda_n - \text{gap}_n}. \end{aligned}$$

Then,

$$\lambda_{\min}(aA + bvv^T) \geq \lambda_{\min}(A), \quad (16)$$

$$\lambda_{\max}(aA + bvv^T) \leq \lambda_{\max}(A). \quad (17)$$

Proof. The proof is direct result from Lemma 4, \square

Corollary 2. Suppose that $v \in \mathbb{R}^n$ satisfies

$$\frac{|v_1|^2}{\lambda_{\min}(A)} > \frac{|v_n|^2}{\lambda_{\max}(A)}. \quad (18)$$

Then, there exist $a \in (0, 1)$ and $b > 0$ such that

$$\lambda_{\min}(aA + bvv^T) > \lambda_{\min}(A), \quad (19)$$

$$\lambda_{\max}(aA + bvv^T) < \lambda_{\max}(A). \quad (20)$$

Proof. Let $f_1, f_n : [0, 1] \times \mathbb{R}_+ \rightarrow \mathbb{R}$ be

$$\begin{aligned} f_1(a, b) &:= a^2 + \frac{k_1 \|v\|^2}{\lambda_1} ab - \frac{2\lambda_1 + \text{gap}_1}{\lambda_1 + \text{gap}_1} a - \frac{\|v\|^2}{\lambda_1 + \text{gap}_1} b + \frac{\lambda_1}{\lambda_1 + \text{gap}_1}, \\ f_n(a, b) &:= a^2 + \frac{k_n \|v\|^2}{\lambda_n} ab - \frac{2\lambda_n - \text{gap}_n}{\lambda_n - \text{gap}_n} a - \frac{\|v\|^2}{\lambda_n - \text{gap}_n} b + \frac{\lambda_n}{\lambda_n - \text{gap}_n}. \end{aligned}$$

Note that $f_1(1,0) = f_n(c/\lambda_n,0) = 0$, and

$$\begin{aligned}\nabla f_1(1,0) &= \frac{\text{gap}_1}{\lambda_1 + \text{gap}_1} \begin{bmatrix} 1 & \frac{|v_1|^2}{\lambda_1} \end{bmatrix}^T, \\ \nabla f_n(1,0) &= -\frac{\text{gap}_n}{\lambda_n - \text{gap}_n} \begin{bmatrix} 1 & \frac{|v_n|^2}{\lambda_n} \end{bmatrix}^T.\end{aligned}$$

There exists a region $\mathcal{D} \subset [0,1] \times \mathbb{R}_+$ satisfying both $f_1(a,b) > 0$ and $f_n(a,b) > 0$ for $(a,b) \in \mathcal{D}$, if only

$$\nabla f_1(1,0) \times \nabla f_n(1,0) = \frac{\text{gap}_1 \text{gap}_n}{(\lambda_1 + \text{gap}_1)(\lambda_n - \text{gap}_n)} \left(\frac{|v_1|^2}{\lambda_1} - \frac{|v_n|^2}{\lambda_n} \right) > 0,$$

which completes the proof. \square

Analytic Solution

For $\lambda_{\min}(A') \geq \lambda_1$ for all v , the following conditions are necessary:

$$\left((a\lambda_2 - \lambda_1)|v_1|^2 - (1-a)\lambda_1\|v_{2:n}\|^2 \right) b - (1-a)(a\lambda_2 - \lambda_1)\lambda_1 \geq 0, \quad (21)$$

$$a = 1, \quad \forall v \quad \text{s.t.} \quad v_1 = 0. \quad (22)$$

asf

$$\begin{aligned}\left(a \text{ads}_1 + b\|v\|^2 \right)^2 - 4ab \text{ads}_1 |v_1|^2 &\leq \left(\left(a \text{ads}_1 + b\|v\|^2 \right) - 2(1-a)\lambda_1 \right)^2 \\ -4ab \text{ads}_1 |v_1|^2 &\leq -4(1-a)\lambda_1 \left(a \text{ads}_1 + b\|v\|^2 \right) + 4(1-a)^2 \lambda_1^2 \\ \left(a \text{ads}_1 |v_1|^2 - (1-a)\lambda_1\|v\|^2 \right) b - (1-a)\lambda_1 \text{ads}_1 a + (1-a)^2 \lambda_1^2 &\geq 0\end{aligned}$$

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