



CE437 – CHUYÊN ĐỀ THIẾT KẾ HỆ THỐNG NHƯNG 1 Lab Section Introduction

6/28/23



Lecturer: Minh-Quan Pham

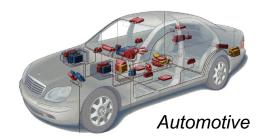


Bosch Global Software Technologies alt future



Car model:

- Cyber + Physical
- Computation + Dynamics
- Security + Safety

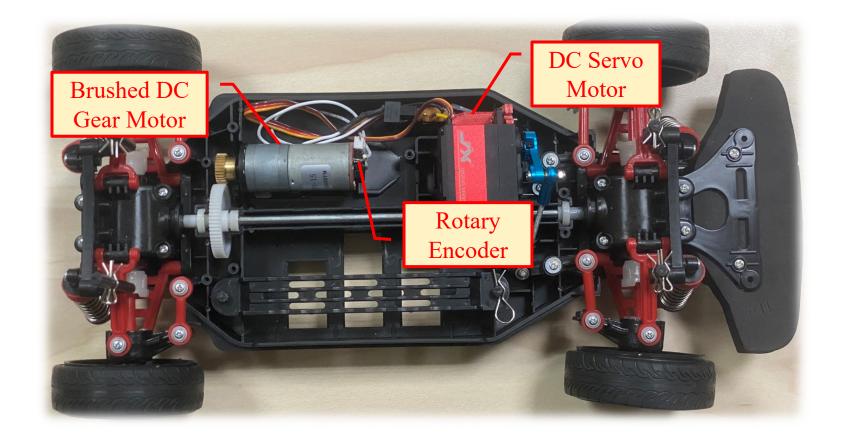








Car model:





CAN BUS

Electrical system:

Wifi Node

MCU: ESP32

Monitor: LED 128x64 (1.3 inches)

Firmware OTA (UART)

AI Node (Reserved)

Jetson Nvidia Kit

Sensor: Camera, Lidar, ...

Sensor Node

MCU: STM32F103C8T6

Obstacle sensors: VL53L01X (I2C)

MPU sensor: GY-91

(MPU9250 + BMP280)

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POWER sensor: INA219

- Battery Voltage

- Working Current

- Working Voltage

Actuator Node

MCU: STM32F103C8T6

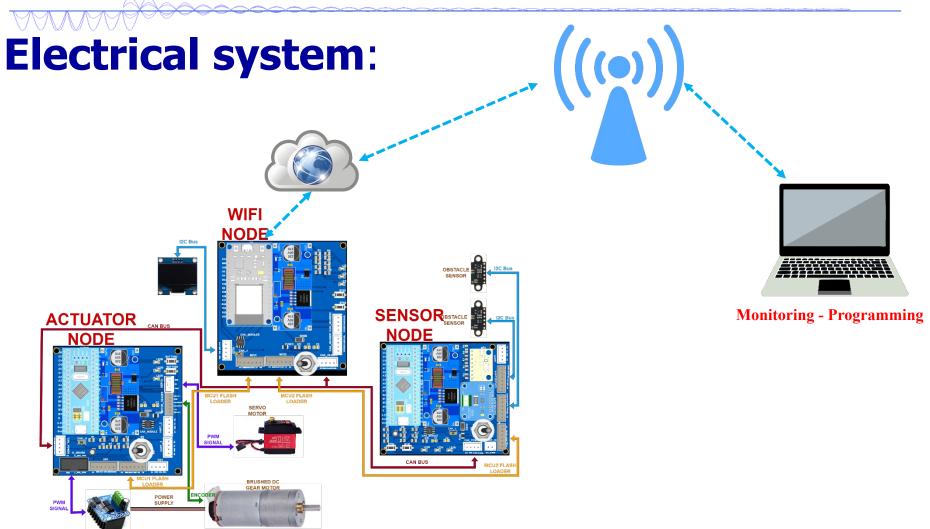
Motors: - 1 DC servo motor

- 1 12V DC motor

Driver: H-bridge

Sensor: Rotary Encoder







WIFI NODE: works as the gateway of the whole system with all the tasks processed by an esp32 processor

ESP32 functions:

- Manage Wi-fi Connection
- Web-server
- Download the firmware to STM32
 MCUs by UART bus
- Communicate with the other nodes by CAN BUS
- Display important data on OLED

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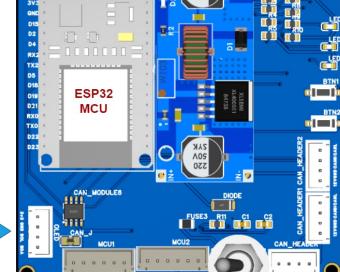
Connections:

Wi-fi/Bluetooth 2.4GHz

WIFI

- CAN
- UART







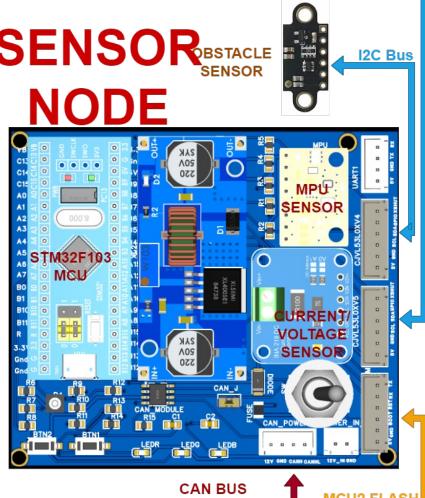


SENSOR NODE: has various types sensors such as MPUSENSORBSTA sensor(including accelerometer, gyroscope), electric current and voltage sensor, and two obstacle sensors

Main processor: ARM Cortex-M3, STM32F103

STM32F103 functions:

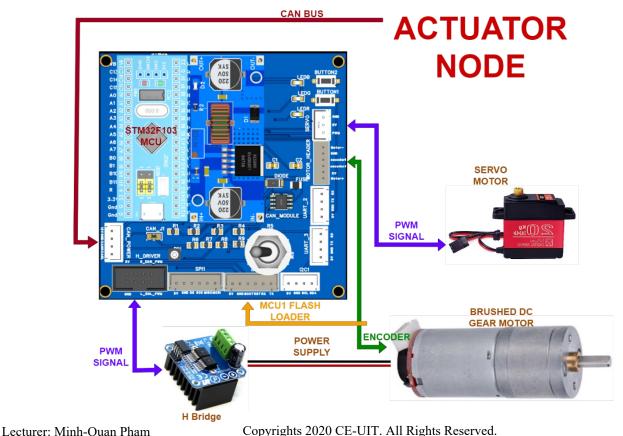
- Collect sensors data by I2C bus
- Communicate with the other nodes by CAN BUS





ACTUATOR NODE: controls a DC servo motor (steering angle) and a brushed DC gear motor

Main processor: ARM Cortex-M3, STM32F103



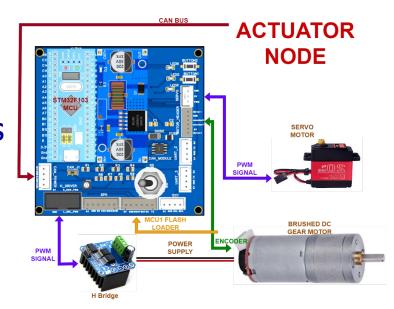


ACTUATOR NODE:

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STM32F103 functions:

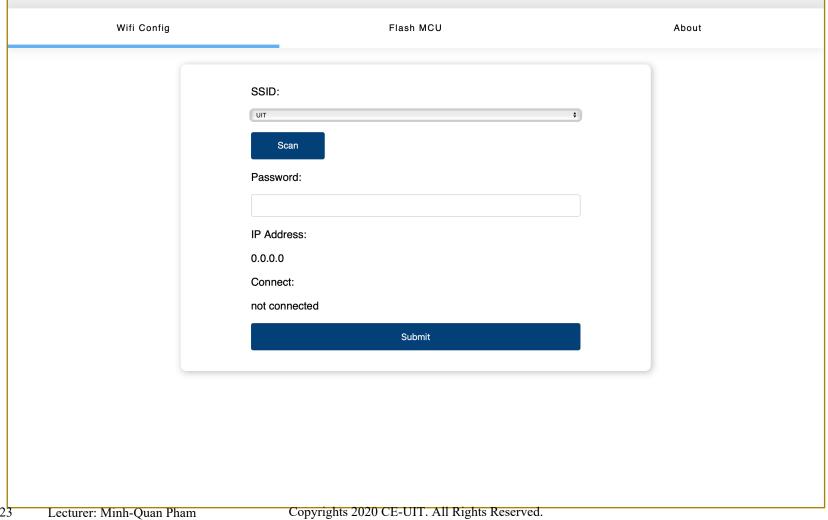
- Communicate with the other nodes by CAN BUS
- Create PWM signal to control DC servo motor
- Read rotary encoder from DC gear motor and create PWM signal to control its speed





CE437- ESP32 Web-server:

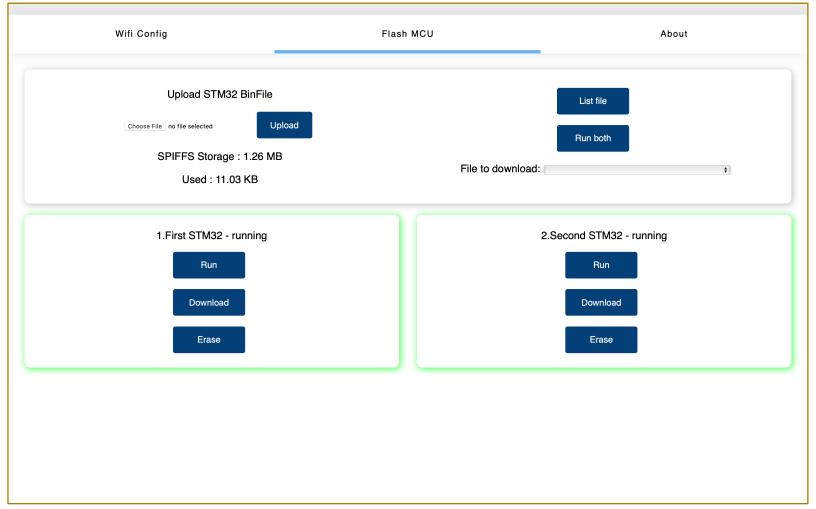
WIFI Management Page:





CE437- ESP32 Web-server:

STM32 Firmware OTA Page:





CE437- ESP32 Web-server:

About Page:

Wifi Config Flash MCU About

CE437-Chuyên đề thiết kế hệ thống nhúng 1

Khoa Kỹ thuật Máy tính Trường Đại học Công nghệ Thông tin phối hợp cùng với công ty Bosch Global Software Technologies Việt Nam để tổ chức khóa đào tạo lập trình nhúng trong xe ô tô

Đến với khóa học, các bạn sẽ có cơ hội:

- Tích lũy kiến thức tổng quan và chuyên sâu về Lập trình Nhúng trong Ô tô
- Trải nghiệm các bài thực hành sát với thực tế thị trường ngành ô tô
- Được hướng dẫn bởi đội ngũ các chuyên gia kỹ thuật giàu kinh nghiệm tại Bosch



Exercises:

Automotive Functions:

- Design and implement CAN API
- Implement motor control ECU
- Implement safety functions: obstacle avoidance

Extended Functions:

- Design and implement data monitoring page
- Design and implement UX/UI on OLED
- Implement security standards for OTA
- Research and implement security standards for CAN Bus





Q&A



