Auditability model for Intent-based SDN Applications

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I. CONFORMANCE CHECKING ALGORITHM

- I The Intents model
- F The Flows model
- T Topology
- T Hosts
- ullet C The security policiy configuration
- S_b^f: the set of host pairs for which at least one host is blocked and flows are still in place in the topology
- S_c^f: the set of host pairs none of which is blocked by the configuration for which the connectivity flows are missing
- S_bⁱ: the set of hosts pairs for which at least one host is blocked and intents are not installed
- S_cⁱ: the set of host pairs none of which is blocked by the configuration for which the intents are not installed.

During the conformance-checking phase, we repeat algorithm 1 for each log and each SCO configuration, to report $S_b^f,\,S_c^f,\,S_b^i,\,S_c^i$

In algorithm 1, the $K_shortest_simple_path$ function is implemented from [1] with a complexity of $\mathcal{O}(KN^3)$, and generates all the non-looping path from two hosts, starting with the smallest. Assuming that there exist a cache of paths, the path lookup function complexity is assumed $\mathcal{O}(1)$. We can see that the conformance algorithm of flow conformance has $\mathcal{O}(KLN^2)$ with N the number of hosts and devices, K the number of simple paths between 2 hosts and L the average size of the K-shortest path, depending on the topology characteristics. The conformance checking of flow-based security and connectivity is at least cubic \square .

Intent conformance, on the other hand, is straightforward, since it involves looking up the intent list composed of host pairs to assure that no intent grant connectivity to a blocked host $(\mathcal{O}(n))$ and making sure that for each non-blocked host pair, there exist an intent $(\mathcal{O}(n^2))$. The conformance checking of intent-based security and connectivity is quadratic \square .

REFERENCES

 J. Y. Yen, "Finding the K Shortest Loopless Paths in a Network," Management Science, vol. 17, no. 11, pp. 712–716, jul 1971.

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Data: (\mathbb{F}, \mathbb{I}, \mathbb{T}, \mathbb{C}, \mathbb{H})
Result: S_b^f, S_c^f, S_b^i, S_c^f
 C, \overline{C}, S_b^f, S_c^f, S_b^i, S_c^f \leftarrow \{\};
for (h_{src}, h_{dst}) \in \mathbb{H} \times \mathbb{H} \setminus \{h_{src} \neq h_{dst}\} do
       if "block h_{src} h_{dst}" \in \mathbb{C} then
              \overline{C} \leftarrow \overline{C} \cup \{(h_{src}, h_{dst})\};
       else
             C \leftarrow C \cup \{(h_{src}, h_{dst})\};
       for p \in K\_shortest\_simple\_path(\mathbb{T}, \mathbb{F}, h_{src}, h_{dst})
              connected \leftarrow true;
              for (s,d) \in p do
                     if f_{s,d} \notin \mathbb{F} then
                            connected \leftarrow false;
                             continue outter For;
                     end
              end
              if connected \wedge (h_{src}, h_{dst}) \in \overline{C} then
               | S_b^f \leftarrow S_b^f \cup \{(h_{src}, h_{dst})\} 
 \textbf{else if } \neg \ connected \land (h_{src}, h_{dst}) \in C \ \textbf{then} 
 | S_c^f \leftarrow S_c^f \cup \{(h_{src}, h_{dst})\} 
       end
end
if \mathbb{I} \neq \{\} then
       for (h_{src}, h_{dst}) \in \mathbb{H} \times \mathbb{H} \setminus \{h_{src} \neq h_{dst}\} do
              if (h_{src}, h_{dst}) \in \mathbb{I} \wedge (h_{src}, h_{dst}) \in \mathbb{C} then
                     S_b^i \leftarrow S_b^i \cup \{(h_{src}, h_{dst})\}
              else if (h_{src}, h_{dst}) \notin \mathbb{I} \wedge (h_{src}, h_{dst}) \in \overline{C} then
                S_c^i \leftarrow S_c^i \cup \{(h_{src}, h_{dst})\}
       end
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Algorithm 1: Conformance checking algorithm

end