

Data3401 Week 1

January 16, 2020

Probability: experiments, outcomes, sample spaces, events

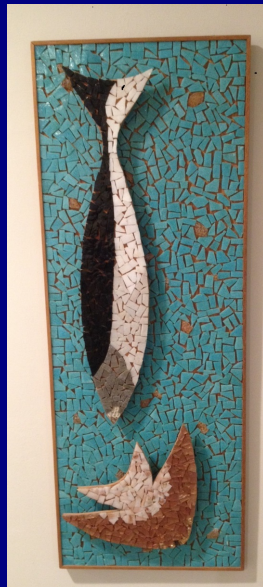
- ▶ Experiments (or trials) generate outcomes.
- ▶ Outcomes are random.
- ▶ Probability is a way to describe randomness.
- ▶ S or Ω ("big omega") \equiv the sample space \equiv the set of all possible outcomes.
- ▶ Outcomes are elements of Ω . Call them $\omega_1, \omega_2, \omega_3, \dots$
- ▶ Events are subsets of Ω . Call them A, B, C etc.
- ▶ ω membership \equiv event occurrence: suppose an experiment generates outcome ω and $\omega \in A, \omega \in B, \omega \notin C$
- ▶ We say events A and B occurred, event C did not occur, $A \cap B$ occurred; $A \cap C$ did not; $B \cup C$ _____

Handmade example

What are the ω 's?

What are some events?

What type of diagram does this remind you of?

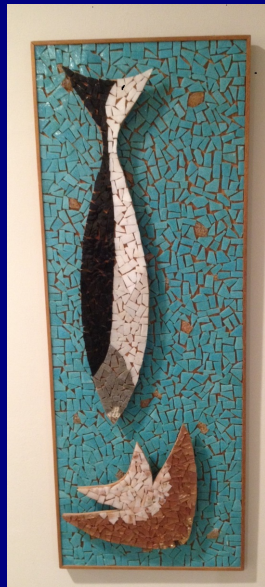


Expressing probabilities

- ▶ Lots of ways to write the probability of an event
- ▶ **prob of event A** $= P(A) = P(\{\omega \in \Omega : \omega \in A\}) = P(\omega \in A)$
all mean the same thing
- ▶ prob events A and B both occur =
 $P(\omega \in A \text{ and } \omega \in B) = P(\omega \in A \cap B) = P(A \cap B) \equiv P(AB)$
- ▶ prob event A or B occurs =
 $P(\omega \in A \text{ or } \omega \in B) = P(\omega \in A \cup B) = P(A \cup B)$

Example cont'd

Use your eyeball to calculate probabilities of events from previous slide.



Probability is math...

- ▶ ... but mathematicians claimed it only recently. In the 1930's, A. N. Kolmogorov formulated probability as a branch of measure theory.
- ▶ Probability is a measure defined on sets (events).
- ▶ Guess which guy is Kolmogorov ...



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The three K axioms, some first principles

1. For any event A , $P(A) \geq 0$
2. $P(\Omega) = 1$
3. If A_1, A_2, A_3, \dots are disjoint, then $P(\cup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$
4. $P(\emptyset) = 0$
5. For any event A , $0 \leq P(A) \leq 1$
6. $P(A^C) = \underline{\hspace{2cm}}$ = the rule of complements or
the one minus trick.
7. $P(A \cup B) = \underline{\hspace{2cm}}$

Math notation for sets

- ▶ $\emptyset \equiv \{\} \equiv$ **the empty set** \equiv the set with no elements.
- ▶ Elements versus subsets: $\omega_1 \in \Omega, \omega_1 \in A, A \subset \Omega$.
- ▶ Every set is a subset of itself; \emptyset is a subset of every set.
- ▶ $2^A \equiv$ **the power set of A** \equiv the set of all subsets of A . It's a set of sets, so: $A \in 2^A, \emptyset \in 2^A, \{\emptyset, A\} \subset 2^A$.
- ▶ $A^C \equiv$ **the complement of A** \equiv "A complement" \equiv "not A" \equiv all the elements of Ω which are not in A
- ▶ Intersection: $A \cap B \equiv$ the set of all ω 's in _____
- ▶ Union: $A \cup B \equiv$ the set of all ω 's in _____
- ▶ A and B are **disjoint** if they do not intersect $\equiv A \cap B = \emptyset$.
Remember _____ for representing sets?
- ▶ Disjoint unions: sometimes we write $A \uplus B$ instead of $A \cup B$ to emphasize that A and B are disjoint.
- ▶ BIG set operators work like this:
 $\bigcap_{i=1}^n A_i = A_1 \cap A_2 \cap \dots \cap A_n$.

Conditional probability adjusts $P(A)$ conditional on information about event B .

'given information' is usually $\omega \in B$

'conditional' \equiv 'given'

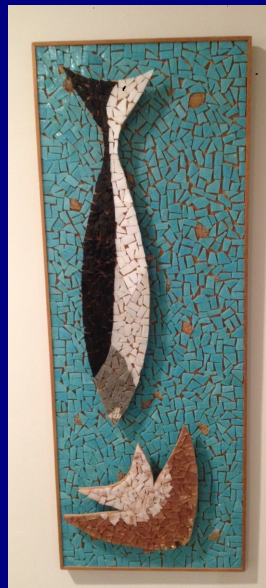
Definition

The **conditional probability** of event A given event B is

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

- ▶ It's a good exercise to rewrite this with the ω 's.
- ▶ Consider fish example again ...

(Unconditional) probability vs. conditional probability



Rearranging the definition of $P(A|B)$

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

$$P(A|B)P(B) = \frac{P(A \cap B)}{P(B)}P(B)$$

$$P(A|B)P(B) = P(A \cap B)$$

- ▶ Same thing for B given A:

$$P(B|A)P(A) = P(B \cap A)$$

- ▶ Right hand sides (RHS) are equal, so:

$$P(A|B)P(B) = P(B|A)P(A)$$

Conditional probability: Bayes' rule

- ▶ Continuing from previous slide:

$$\begin{aligned} P(A|B)P(B) &= P(B|A)P(A) \\ \frac{P(A|B)P(B)}{P(B)} &= \frac{P(B|A)P(A)}{P(B)} \\ P(A|B) &= P(B|A) \frac{P(A)}{P(B)} \end{aligned}$$

- ▶ This formula shows how to 'reverse' the conditioning.
- ▶ We can make it go the other way:

$$P(B|A) = P(A|B) \frac{P(B)}{P(A)}$$

- ▶ This result is **Bayes' rule**.

Reverend Thomas Bayes (1702-1761). Everyone uses Bayes's rule; his name is also associated with *Bayesian statistics* which relies on an alternative interpretation of probability. This was the subject of some disagreement in the past; not so much now.

A portrait of Reverend Thomas Bayes, a man with a high forehead, receding hair, and a serious expression, wearing clerical robes. The portrait is in a classic, slightly grainy style.
$$P(A|B) = \frac{P(B|A) P(A)}{P(B)}$$

Random variables

- ▶ Random variables are functions of ω . They extract the (quantitative) information which is carried by each ω .
- ▶ Let the sample space $\Omega =$ all the fish in the sea.
- ▶ Then each ω is one of the fish.
- ▶ Random variables are the (quantitative) questions you can ask a fish:
 - ▶ How long are you? How many siblings do you have?
 - ▶ Are you carnivorous? What percentage of your diet is vegetable matter?
 - ▶ How long was your commute today?
 - ▶ What's your favorite color?
- ▶ Before sampling, rv's live in math land. Sampling a fish and asking the question(s) generates **data** \equiv **a realization of the rv.**
- ▶ In this setting, events look like $\{X < 12\}$ or $\{X < 12 \ \& \ X \geq 9\} = \{9 \leq X < 12\}$
- ▶ RV's can be **discrete** or **continuous** (chunky or smooth)

Continuous rv's are grouped into families (ch4)

- ▶ uniform
- ▶ normal (Gaussian)
- ▶ gamma, exponential, χ^2
- ▶ beta

Families defined by their probability density function (pdf)

pdf usually called $f_X(x)$ or $f(x)$

pdf depends on **parameters**

A family is a set of pdf's; this set indexed by the parameters

Parameter space \equiv set of possible parameter values

Support \equiv set of possible x -values

R functions for pdf's:

- ▶ `dunif(x, ...)`
- ▶ `dnorm(x, ...)`
- ▶ type **help(distributions)** to see them all
- ▶ parameter values replace ...

Let X be any continuous rv with pdf $f()$

- ▶ Expected value (mean) of X :

$$E[X] \equiv \mu_X \equiv \mu \equiv \int_{-\infty}^{\infty} x f(x) dx$$

- ▶ Variance of X is also an expected value:

$$\text{Var}[X] \equiv E[(X - \mu)^2] \equiv \sigma_X^2 \equiv \sigma^2 \equiv \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx$$

- ▶ Cumulative distribution function (cdf):

$$F(x) = P(X \leq x) = \int_{-\infty}^x f(t) dt = \int_{-\infty}^x f(t) dt$$

- ▶ The **inverse** of the cdf is the **quantile function** of X :

$$F_X^{-1}(p) \text{ or just } F^{-1}(p)$$

$F^{-1}(p)$ returns the x value which has prob = p to its **left**.

Properties of expected value $E[\cdot]$

- ▶ $E[c] = c$
- ▶ $E[cX] = cE[X]$
- ▶ $E[X + c] = E[X] + E[c] = E[X] + c$
- ▶ $E[X + Y] = E[X] + E[Y]$
- ▶ $E[aX + bY + c] = aE[X] + bE[Y] + c$
- ▶ $\text{Var}[X + Y] = \text{Var}[X] + \text{Var}[Y]$ if X, Y are independent.
- ▶ $\text{Var}[aX] = a^2 \text{Var}[X]$

Some discrete rv's

- ▶ D_1 and D_2
- ▶ Binary trials: heads or tails? Houston or Dallas? I need an umbrella or I don't.
- ▶ Definition: $X \sim \text{Bernoulli}(p)$ means X has the distribution of a binary trial with $\Omega = \{0, 1\}$ and parameter $p = P(X = 1)$. By the rule of complements $P(X = 0) = 1 - p \equiv q$.
- ▶ Example from basketball: Let the rv JH = the outcome when James Harden shoots a free throw.



More discrete rv's

- ▶ Let $X_1, X_2, \dots, X_n \stackrel{iid}{\sim} \text{Bernoulli}(p)$.
- ▶ The \sim means 'is distributed as'. The *iid* means 'independent, identically distributed'. So the X_i 's are independent Bernoulli trials all with the same success prob.
- ▶ Let $Y = \sum_{i=1}^n X_i$. So Y counts the successes.
- ▶ Definition: $Y \sim \text{binomial}(n, p)$ means Y has the distribution of the sum of n independent *Bernoulli*(p) trials.
- ▶ Example with $n = 4$ and $p = 1/3$
- ▶ The pmf of Y is

$$p(k) = \binom{n}{k} p^k (1-p)^{n-k} = \frac{n!}{k!(n-k)!} p^k q^{n-k}$$

- ▶ $\binom{n}{k}$ = 'n choose k' = number of size k sets you can select from n objects. Also called a binomial coefficient.
- ▶ Mean of Y : $\mu_Y = np$.
- ▶ Variance of Y : $\sigma_Y^2 = np(1-p) = npq$

General facts about discrete rv's

- ▶ Let X be any discrete rv (think of D_1 or a binomial rv)
- ▶ Let R be the set of possible values for X .
- ▶ Probability mass function is $p(k) = P(X = k)$ for $k \in R$
- ▶ Mean of X :

$$\mu \equiv E[X] = \sum_{k \in R} kp(k)$$

- ▶ Variance of X :

$$\sigma^2 \equiv Var[X] = \sum_{k \in R} (k - \mu)^2 p(k)$$

- ▶ Cumulative distribution function (cdf):

$$F(k) = P(X \leq k) = \sum_{j \leq k} p(j)$$

- ▶ **Quantile function** gets messier, have to be careful when we talk about

$$F_X^{-1}(p)$$

for discrete rv's.

Some math to recall

- ▶ $e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!}$
- ▶ product rule: $(uv)' = u'v + uv'$
- ▶ integration by parts: $\int uv' = uv - \int u'v$
- ▶ foil
- ▶ binomial theorem: $(a + b)^n = \sum_{k=0}^n \binom{n}{k} a^k b^{n-k}$
- ▶ alternative formula for variance:
$$\text{Var}[X] \equiv E[(X - \mu)^2] = E[X^2] - \mu^2 = E[X^2] - E[X]^2$$
- ▶ the one-minus trick
- ▶ start with Wikipedia