

# MSA 8200 - Econometrics Homework 5

1 a) Given  $X_t = \phi X_{t-1} + w_t$  and  $w_t \sim N(0, \sigma_w^2)$

$$\begin{aligned} X_t &= \phi X_{t-1} + w_t \\ &= \phi(\phi X_{t-2} + w_{t-1}) + w_t \\ &= \phi^2 X_{t-2} + \phi w_{t-1} + w_t \\ &\quad \vdots \\ &= \phi^k X_{t-k} + \sum_{j=0}^{k-1} \phi^j \cdot w_{t-j} \end{aligned}$$

If  $|\phi| < 1$  and  $k \rightarrow \infty$ , then  $\phi^k \rightarrow 0$ , thus

$$X_t = \sum_{j=0}^{k-1} \phi^j w_{t-j}.$$

$$\begin{aligned} \text{b) } E(X_t) &= \sum_{j=0}^{k-1} \phi^j E(w_{t-j}) \\ &= 0. \end{aligned}$$

$$\begin{aligned} \text{c) } \text{Var}(X_t) &= \text{Var}\left(\sum_{j=0}^{k-1} \phi^j \cdot w_{t-j}\right) \\ &= \sum_{j=0}^t \phi^{2j} \cdot \text{Var}(w_{t-j}) \\ &= \sum_{j=0}^t \phi^{2j} \cdot \sigma_w^2 = \sigma_w^2 \cdot \sum_{j=0}^t \phi^{2j} \\ &\Rightarrow \sigma_w^2 \cdot \left(\frac{1 - \phi^{2(t+1)}}{1 - \phi^2}\right) \end{aligned}$$

$$d) \text{cov}(X_t, X_{t+h}) = E[(X_t - \mu_{X_t})(X_{t+h} - \mu_{X_{t+h}})]$$

→ Given  $X$   $E(X_t) = E(X_{t+h}) = 0$ ,

$$\text{cov}(X_t; X_{t+h}) = E[X_t \cdot X_{t+h}]$$

$$\Rightarrow E\left[\sum_{j=0}^t \phi^j \omega_{t-j} \cdot \sum_{j=0}^{t+h} \phi^j \cdot \omega_{t+h-j}\right]$$

Lets set  $i = j+h$  to re-index the second summation.

$$\Rightarrow E\left[\sum_{j=0}^t \phi^j \omega_{t-j} \cdot \sum_{i=0}^t \phi^i \cdot \omega_{t+h-i}\right]$$

$$= E\left[\sum_{j=0}^t \phi^{j+i} \cdot \omega_{t-j} \cdot \omega_{t+h-i}\right]$$

$$= \sum \phi^{2j} \cdot \phi^h \cdot E(\omega_{t-j} \cdot \omega_{t-j})$$

$$= \phi^h \sigma_\omega^2 \cdot \sum_{j=0}^t \phi^{2j} = \phi^h \cdot \text{var}(X_t)$$

e) Since  $\text{var}(X_t)$  depends on  $t$ ,  $X_t$  is not stationary.

f) As  $t \rightarrow \infty$ :

$$i) E(X_t) \rightarrow 0 \quad [\text{from part b}]$$

$$ii) \text{Var}(X_t) \rightarrow \frac{\sigma_w^2}{1-\phi^2} \quad [\text{given } |\phi| < 1]$$

$$iii) \text{Cov}(X_t, X_{t+h}) \rightarrow \frac{\phi^h \sigma_w^2}{1-\phi^2}$$

Since the  $E(X_t) = 0$  and  $\text{Var}(X_t)$  does not depend on  $t$ ,  $X_t$  becomes stationary as  $t \rightarrow \infty$ .

$$3 \text{ a) } X_t = 0.8X_{t-1} - 0.15X_{t-2} + \omega_t - 0.3\omega_{t-1}$$

$$0.15X_{t-2} - 0.8X_{t-1} + X_t = \omega_t - 0.3\omega_{t-1}$$

$$\Rightarrow (1 - 0.8B + 0.15B^2)X_t = (1 - 0.3B)\omega_t$$

$$(1 - 0.3B)(1 - 0.5B)X_t = (1 - 0.3B)\omega_t$$

Since  $\phi(B) = (1 - 0.5B)\theta(B)$ , this is an AR(1) model, not an ARMA(2,1).

Causality:

$$\phi(z) = 1 - 0.5z = 0$$

$$\therefore z = 2$$

As  $|z| > 1$ , this is causal

Invertible:

The model can be written as

$(1 - 0.5B)X_t = \omega_t$ , thus it is invertible.

$$b) X_t = X_{t-1} - 0.5X_{t-2} + w_t - w_{t-1}$$

$$0.5X_{t-2} - X_{t-1} + X_t = w_t - w_{t-1}$$

$$\Rightarrow (1 - B + 0.5B^2) X_t = (1 - B) w_t$$

Since  $\phi(B)$  and  $\theta(B)$  share no factors, this is an ARMA(2,1) model.

Causality:

$$(i) \phi(z) = 1 - z + 0.5z^2 = 0$$

$$\therefore z = \frac{1 \pm \sqrt{1-2}}{1} = 1 \pm \sqrt{-1}$$

As  $|z| > 1$ , this is causal.

$$(ii) \theta(z) = 1 - z = 0$$

$$\therefore z = 1$$

As  $|z| \not> 1$ , this is not causal.

Invertible:

The model cannot ~~be~~ be written in the form  $\pi(B) X_t = w_t$ , thus it is not invertible.