

iMPACT User Guide



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About This Manual

This guide describes the iMPACT configuration tool, a command line and GUI based tool that enables you to configure your PLD designs using Boundary-Scan, Slave Serial, and Select MAP configuration modes, as well as the MultiPRO Desktop Programmer. You can also generate programming files using iMPACT's System ACE, PROM Formatter, SVF, and STAPL file generation modes.

Manual Contents

This book contains the following chapters.

- [“Introduction”](#)
- [“Cables”](#)
- [“Designing Boundary-Scan and ISP Systems”](#)
- [“Using iMPACT to Configure Devices”](#)
- [“Using iMPACT to Generate Files”](#)
- [“Troubleshooting for Boundary-Scan Chains”](#)
- [“Glossary of Terms”](#)
- [“Boundary Scan Basics” appendix](#)
- [“Parallel Cable III \(DLC 5\) Schematic” appendix](#)
- [“Command Line and Batch Mode Commands” appendix](#)

Additional Resources

For additional information, go to <http://support.xilinx.com>. The following table lists some of the resources you can access from this Web site. You can also directly access these resources using the provided URLs.

Resource	Description/URL
Tutorials	Tutorials covering Xilinx design flows, from design entry to verification and debugging http://support.xilinx.com/support/techsup/tutorials/index.htm
Answers Database	Current listing of solution records for the Xilinx software tools Search this database using the search function at http://support.xilinx.com/support/searchtd.htm
Application Notes	Descriptions of device-specific design techniques and approaches http://support.xilinx.com/apps/appswb.htm
Data Book	Pages from <i>The Programmable Logic Data Book</i> , which contains device-specific information on Xilinx device characteristics, including readback, boundary scan, configuration, length count, and debugging http://support.xilinx.com/partinfo/databook.htm
Xcell Journals	Quarterly journals for Xilinx programmable logic users http://support.xilinx.com/xcell/xcell.htm
Technical Tips	Latest news, design tips, and patch information for the Xilinx design environment http://support.xilinx.com/support/techsup/journals/index.htm

Conventions

This manual uses the following conventions. An example illustrates most conventions.

Typographical

The following conventions are used for all documents.

- `Courier font` indicates messages, prompts, and program files that the system displays.

```
speed grade: - 100
```

- **Courier bold** indicates literal commands that you enter in a syntactical statement. However, braces “{ }” in Courier bold are not literal and square brackets “[]” in Courier bold are literal only in the case of bus specifications, such as bus [7:0].

```
rpt_del_net=
```

Courier bold also indicates commands that you select from a menu.

File → Open

- *Italic font* denotes the following items.
 - ♦ Variables in a syntax statement for which you must supply values

```
edif2ngd design_name
```

- ♦ References to other manuals

See the *Development System Reference Guide* for more information.

- ◆ Emphasis in text

If a wire is drawn so that it overlaps the pin of a symbol, the two nets are *not* connected.

- Square brackets “[]” indicate an optional entry or parameter. However, in bus specifications, such as bus [7:0], they are required.

```
edif2ngd [option_name] design_name
```

- Braces “{ }” enclose a list of items from which you must choose one or more.

```
lowpwr = {on | off}
```

- A vertical bar “|” separates items in a list of choices.

```
lowpwr = {on | off}
```

- A vertical ellipsis indicates repetitive material that has been omitted.

```
IOB #1: Name = QOUT'
```

```
IOB #2: Name = CLKIN'
```

```
.  
.   
.
```

- A horizontal ellipsis “...” indicates that an item can be repeated one or more times.

```
allow block block_name loc1 loc2 ... locn;
```

Online Document

The following conventions are used for online documents.

- [Blue text](#) indicates cross-references within a book. [Red text](#) indicates cross-references to other books. Click the colored text to jump to the specified cross-reference.
- [Blue, underlined text](#) indicates a Web site. Click the link to open the specified Web site. You must have a Web browser and internet connection to use this feature.

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Introduction

This chapter introduces you to the basic concepts of the iMPACT software and related Xilinx in-system programmable products. You can use iMPACT to download, read back and verify design configuration data as well as to create PROM, SVF, STAPL, System ACE CF and System ACE MPM programming files. This chapter contains the following sections:

- “Configuration Device Operation Options Available to Users”
- “Non-Volatile Device Data Security”
- “Required Files”
- “iMPACT Features”
- “iMPACT Platform Support”
- “Starting iMPACT”
- “Using the Interface”
- “Using Help”
- “Architecture Support”

Configuration Device Operation Options Available to Users

Program. Downloads the contents of the JEDEC, BIT or PROM file to the device.

Verify. Reads back the contents of the device configuration and compares them with the JEDEC, BIT or PROM file.

Erase. Clears device configuration information.

Functional Test. Applies user-specified functional vectors from the JEDEC file to the device using the JTAG INTEST instruction, comparing results obtained against expected values. Reports any differences to the user.

Blank Check. Checks whether a device is in a programmed or erased state.

Readback. Reads back the contents of the device configuration and creates a new JEDEC/ MCS/EXO file with the results.

Program XPLA UES. This is a Coolrunner only option. Programs the user electronic signature of the selected devices.

Get Device ID. Reads the contents of the JTAG IDCODE register. Displays contents for the user.

Get Device Checksum. Reads back the contents of device programming registers and calculates a checksum for comparison against the expected value.

Get Device Signature/Usercode. For FPGAs and CPLDs this value is selected by the user during program file generation. The specified value is translated to binary values in the JEDEC file. During device programming these values are loaded into the JTAG USERCODE register. This function reads the contents of the USERCODE register and displays the result.

Get XPLA Device UES. This is a Coolrunner only option. Gets the user electronic signature from the selected devices in the JTAG chain.

IDCODE Looping. Performs IDCODE operations a specified number of times.

Non-Volatile Device Data Security

Any Xilinx XC9500 family device selected for programming can be secured with the Write Protect or Read Protect or both. CoolRunner and PROM devices can be secured with the Read Protect only.

When enabled, Read Protect disables reading the programmed contents of a device (the IDCODE, USERCODE and all boundary-scan registers remain readable).

Write Protect allows only the reading of the programmed data. The device contents cannot be altered or re-programmed.

When both Read Protect and Write Protect are enabled, the device can be neither read nor re-programmed.

User Feedback

When using the graphical user interface, immediate feedback is provided by a scrolling log file and alert boxes. Detailed information regarding operation history and status is displayed in the status window and collected in the iMPACT log file.

Required Files

For Boundary-Scan programming, you need to provide JEDEC files for each XC9500 family device, BIT files for each Xilinx FPGA device (4K Virtex or Spartan), .mcs or .exo files for each PROM device, and BSDL files for the remaining devices.

For Slave Serial programming, you must provide a single bit file if there is only one FPGA, or an .MCS/.EXO file for Serial daisy chains with multiple FPGAs.

For SelectMAP programming, you must provide a bit file for each target device.

JEDEC Files

JEDEC files are XC9500 family programming files generated by the Xilinx fitter. They are ASCII text files containing programming information that can be used to verify the correct functional behavior of the programmed device. One JEDEC file is required for each XC9500 family device in the JTAG programming chain.

BSDL Summary

The Boundary-Scan Description Language (BSDL) files use a subset of VHDL to describe the boundary scan features of a device. iMPACT automatically extracts the length of the instruction register from the BSDL file to place non-Xilinx devices in bypass mode. Xilinx BSDL files are located automatically by iMPACT.

BIT Files

Bit files are Xilinx FPGA configuration files generated by the Xilinx FPGA design software. They are proprietary format binary files containing configuration information. One BIT file is required for each Xilinx FPGA in a boundary-scan chain, for a single Slave Serial connected device, or for each Select MAP connected device.

PROM Files

PROM files are PROM programming files generated by iMPACT using the PROM Formatter tab in the File Generation mode. They are ASCII text files used to specify configuration data. PROM files are also used to download a serial daisy-chain of multiple FPGAs in a Slave Serial daisy.

A Xilinx PROM file consists of one or more data streams. In this context, a data stream represents all the configuration data required to implement a given application. Each data stream contains one or more BIT files and once saved, will have a separate preamble and length count.

The PROM file can be formatted in one of three industry standard formats: Intel MCS-86®, Tektronix TEKHEX, and Motorola EXOR-macs.

Note You can store PROM files in PROM devices or on your computer. In turn, you can use the files to program your FPGA devices either from a PROM device on your board or from your computer using a serial or parallel cable.

RBT Files

A Raw Bit File is an ASCII version of the Bit file. The only difference is that the header information in a Bit File is removed from the Raw Bit File. This is also created by Bitgen and is used to program a single FPGA.

Chain Description Files

A Chain Description file is used to save and restore information about the composition of device configuration chains. It stores information about the order of devices in the chain and the configuration data file associated with each device.

iMPACT Features

You can use iMPACT to perform the following functions.

- Configure one or more devices
- Verify configuration data for single devices
- Create PROM, SVF, STAPL, System ACE CF, and System ACE MPM programming files.

For downloading, use any of the three configuration data file types (BIT, JEDEC, or PROM) and any download cable.

For single device verification use a BIT file. For Virtex and Spartan-II, generate a MSK file for verification. Include the READBACK symbol in your design and optionally, the STARTUP symbol.

PROM Formatter

The PROM Formatter tab enables you to format BIT files into a PROM file compatible with Xilinx and third-party PROM programmers. It is also used to concatenate multiple bitstreams into a single PROM file for daisy chain applications. This feature also enables you to take advantage of the Xilinx FPGA reconfiguration capability, as you can store several applications in the same PROM file.

PROM files are also compatible with the Xilinx iMPACT configuration tool software. You can use iMPACT to download a PROM file to an 18V00 series PROM, a single FPGA, or to a daisy chain of FPGA devices.

The PROM Formatter performs the same function as the PROMGen program, which can be executed from the UNIX™ or PC command line. Refer to the Development System Reference Guide for details about PROMGen.

Serial PROMs

Serial PROMs are PROMs that are read one bit at a time. In Serial PROM mode, you can create files that will:

- Configure a single device with one or more PROM devices.
- Configure a daisy-chained device with one or more PROM devices.

Parallel PROMs.

A Parallel PROM is a PROM that is read one byte at a time. In Parallel PROM mode, you can create files that will:

- Configure a single device with one or more applications
- Configure a daisy-chained device with one or more applications.

System ACE

System ACE is a Xilinx-developed configuration environment that allows for space-efficient, pre-engineered, high-density configuration solutions for systems with multiple FPGAs. There are two versions of System ACE; System ACE CF and System ACE MPM. See the [“Using iMPACT to Generate Files” chapter](#) for more information.

MultiPRO Desktop Programmer (MultiPRO)

Primarily an upgrade from the HW130, the MultiPRO cable is a multi-function tool capable of ISP configuration using JTAG, Slave-Serial, or SelectMAP interfaces. Ribbon cables can be simultaneously attached to an ISP target system.

- The MultiPRO connects to your PC using an IEEE-1284 standard parallel port.
- There is no overlap between devices supported by the two programmers.
- The MultiPRO supports the CoolRunner II CPLD family, the XC 18V00 Flash PROM family, and all System ACE-MPM modules.

iMPACT Platform Support

iMPACT supports the following platforms.

Table 1-1 Platform Support

Cable	Platforms	Ports
MultiLINX	Sol/HP/WinNT/ Win98/2000/ME	RS-232,USB
Parallel	WinNT/Win98/2000/ ME	Parallel

Starting iMPACT

This section explains how to start iMPACT. It describes the main screen and outlines the design and hardware requirements for using iMPACT.

From Project Navigator

To start iMPACT from Project Navigator, follow these steps:

- In the Processes for Current Source window, double click the “Configure Device (iMPACT)” selection under the “Generate Programming File” process.

From Design Manager

To start iMPACT from Design Manager, follow these steps:

- Click the iMPACT icon.



From the Command Line

To start iMPACT from the UNIX[®] or DOS[™] command prompt, enter the following command:

```
impact
```

If you want to start iMPACT with a `.bit`, `.cdf`, or `.jed` extension, or use iMPACT in batch mode, please see Appendix C for further instructions.

Exiting iMPACT

To exit iMPACT, select **File** → **Exit**. If you have an open window, you are prompted to save the data before quitting the application.

Using the Interface

This section describes the iMPACT interface.

Main Window

The main window is the background against which all other windows are displayed.

Title Bar





The title bar displays the program name followed by the name of the currently loaded design.







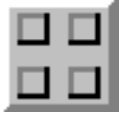
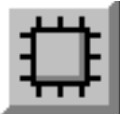
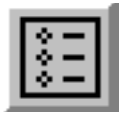
Menu Bar






The menu bar, located at the top of the window, includes the File, Edit, Mode, Operations, Output, View, and Help menus. You can also select menu commands by typing the letter underlined in the menu name while holding down the Alt key.

Toolbar

The toolbar, located below the menu bar, consists of buttons that you can use to execute commands. Place the mouse pointer over each button to display the command associated with the button. The command name appears as a “tool tip” and the status bar provides more descriptive information.

Button	Name	Function
	New	Removes all configuration descriptions from all tabs to let you start a new configuration description.
	Open	Open an existing CDF file.
	Save	Saves the active chain file. Clicking this button is the same as selecting Save in the file menu.
	Cut	Removes a selection from the iMPACT main window and temporarily stores it on the clipboard.

Button	Name	Function
	Copy	Copies a device and temporarily stores a copy of it on the clipboard.
	Paste	Inserts data stored on the clipboard into the iMPACT main window.
	Toggle Mode	Switches iMPACT tabs between Configuration and File Generation modes.
	Initialize Chain	Automatically detects the number and types of devices in a Boundary-Scan chain.
	Debug Chain	Initiates rudimentary Boundary-Scan TAP debug operations.
	Select All	Selects all the devices in the chain.
	Unselect All	Unselects all the devices in the chain.
	Add Xilinx Device	Adds a new Xilinx device to the chain.
	Assign New Configuration File	Changes the current device configuration file selection.

Button	Name	Function
	MultiPRO Program	Programs a configuration to a device.
	MultiPRO Verify	Verifies a configuration has been programmed to the device.
	MultiPRO Erase	Erases a programmed device.
	About	Displays the program information and copyright.
	Help	Invokes context-sensitive help. When you click this button, the cursor changes into a large question mark with an arrow. You can then select an object, such as a menu command or a toolbar button, and receive help for that object.

Status Window

The status window, located at the bottom of the iMPACT window, provides command and processing information. When you select a menu command, a brief description of the command's function appears in the status window. As the software processes, status messages are dynamically updated and displayed.

Commands and Dialog Boxes

You communicate with iMPACT by selecting commands from the menus and the toolbar.

Common Fields

The fields shown in the following table are common to most dialog boxes.

Table 1-2 Common Dialog Box Fields

Dialog Box Field	Function
OK	Closes the dialog box and implements the intended action according to the settings in the dialog box
Help	Displays information on that particular dialog box
Cancel	Closes the dialog box without affecting any action
Cancel All	Cancels the current configuration setup

The standard file open and file save dialog boxes enable you to load a project file or save a project file. This type of dialog box includes a file browser.

Selection Dialog Boxes

Use Selection dialog boxes to specify specific values and selections.

Selecting Commands and Dialog Box Options

To choose a menu item, a toolbar button, or a dialog box option, you can use the mouse or the keyboard.

Using the Mouse

1. Move the mouse cursor over the object you want to select, and click the left mouse button to select the object.

If you clicked on a toolbar button, a list box or a dialog box appears. If you clicked on a menu, menu options are displayed.

2. To exit a dialog box without making a selection, click **Cancel** or double-click the close box in the upper left corner of the dialog box.
3. To obtain help, click **Help** in the dialog box.

Using the Keyboard

You can use the keyboard to select objects on your screen, such as a dialog box button or a menu option.

1. To select a dialog box option, use the **Tab** key to position the cursor on that object and highlight it. Press the **Enter** key to process the selection.

To exit a dialog box without making a selection, press the **Esc** key.
2. To choose a menu and display its commands, press the **Alt** key and the appropriate underlined letter key corresponding to the menu you want. For example, press **Alt F** to select the File menu.
3. Use the arrow keys to scroll down the list of commands in a menu or the options in a list box. Press **Enter** when the selection you want to use is highlighted or, in the case of a menu item, press the underlined letter corresponding to the menu command. For example, press the **N** key to select the New command of the File menu.

Using Help

iMPACT includes both context-sensitive help and a Help menu. You can obtain help on commands and procedures through the Help menus or by selecting the Help toolbar button. In addition, the dialog boxes associated with many commands have a Help button that you can click to obtain context-sensitive help.

Help Menu

Use the following Help menu commands to get help.

- The Help Topics command opens the online help and lists the various topics available for iMPACT. From the Help Topics page, you can jump to command information or step-by-step instructions for using iMPACT. When you want to return to the help topic list, click the Help Topics button.
- The Online Documentation command provides access to the online documentation.

- The About iMPACT command displays a popup window that shows the version number of the iMPACT software and a copyright notice.
- The Supported Devices command displays a list of devices supported in iMPACT.

Toolbar Help Button

Click once with the left mouse button on the menu item or toolbar button for which you want help. iMPACT displays help for the selected command or option.

Note: You can also press **Shift F1** to obtain context-sensitive help.

F1 Key

Pressing the F1 key on a dialog box displays help on that dialog box. Pressing the F1 key is the same as selecting Help → Help Topics, if no dialog boxes are displayed.

Help Button in Dialog Boxes

Many of the dialog boxes in iMPACT have a Help button that you can click to get help on the dialog box options. You can also press **Alt H** or **F1** on your keyboard with the cursor positioned over the dialog box to access the online help.

Architecture Support

The software supports the following architecture families in this release.

- Virtex[™]/E/II/II PRO
- Spartan[™]/XL/II/III
- CoolRunner[™] XPLA3 /II
- XC9500[™] (Version 2 or Greater)
- XC9500XL/XV (All)
- XC18V00 PROMs

Cables

This chapter gives specific information about using cables to download from the iMPACT Configuration Tool to devices in-system.

This chapter contains the following sections.

- “Download Cables”
- “Cable Support”
- “Software and Cable Interface”
- “Target Board Requirements”
- “Parallel Cable IV”
- “Parallel Cable III”
- “MultiLINX Cable”
- “MultiLINX Connection and Power Sequence”

Download Cables

There are three cables available for use with the iMPACT Configuration Tool. The first is the Parallel Download Cable III which can be connected to a PC's parallel port. The second is the Parallel Cable IV which is also parallel port connected and backward compatible to the Parallel Cable III. The third is the MultiLINX cable which can be connected to a USB port or serial port. The USB port can be used on Win98/2000/Me. It cannot be used on Win95 or WinNT.

There are a few options to be considered in selecting a cable:

- The Multilinx Cable connects to the serial port of both PCs and workstations or the USB port on a PC.

- The Parallel Cable IV is over 10 times faster than Parallel Cable III and over 5 times faster than the MultiLINX cable.
- All three cables are ChipScope ILA compatible.
- The Parallel Cable IV replaces Parallel Cable III in March, 2002.

Cable Support

iMPACT supports the following cables.

Table 2-1 Cable Support

Name	Platforms	Voltages	Modes	Notes
MultiLINX Cable (Model: DLC6)	PC, Workstation	2.5, 3.3, 5 Volt	JTAG, Slave Serial, SelectMAP	The USB port can be used on Win98/2000/Me. It cannot be used on Win95 or WinNT.
Parallel Cable IV (Model: DLC7)	PC	1.5, 1.8, 2.5, 3.3, 5 Volt	JTAG, Slave Serial	
Parallel Cable III (Model: DLC5)	PC	2.5, 3.3, 5 Volt	JTAG, Slave Serial	Replaced by PC IV in March 2002.

Cable Baud Rates

The supported Baud Rates for the cables are shown in the following table.

Table 2-2 Cable Baud Rates

Cable	PC	WorkStation
MultiLINX Cable (USB)	1 M-12 M	USB is currently not supported on WorkStation.
MultiLINX Cable (RS-232)	9600, 19200, 38400, and 57600	9600, 19200, and 38400
Parallel Cable III	Not Selectable	Not Applicable
Parallel Cable IV	Not Selectable	Not Applicable

Software and Cable Interface

iMPACT allows for both automatic and manual cable connections.

Cable Auto Connect (Automatic)

Select **Output** → **Cable Auto Connect** if you want the software to scan for the presence of a cable and automatically establish communication. Cable information is presented in the status bar.

If you select any operation that requires a cable, such as **Program** or **Initialize Chain**, without first selecting a cable connection, iMPACT will attempt to auto connect.

Cable Setup (Manual)

After connecting the cable to download and verify, power your target board to enable the software to communicate with the cable and start iMPACT. You can then set the cable options manually with the following steps:

1. Select **Output** → **Cable Setup** to display the Cable Communication Setup dialog box, shown in the following figure.

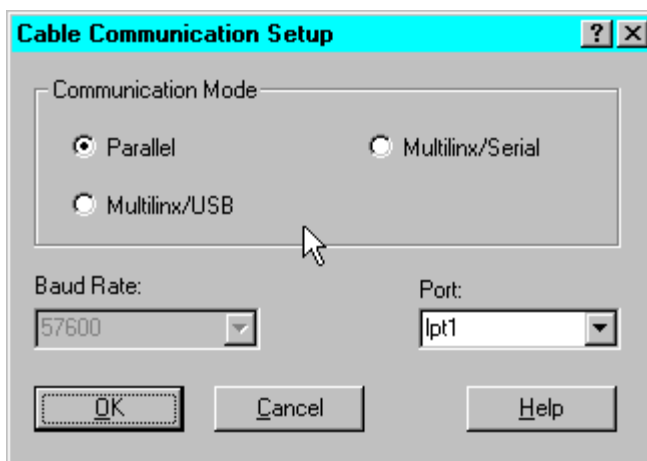


Figure 2-1 Cable Communication Setup Dialog Box

2. In the Communication Mode field, select the cable type that you installed for downloading. The Parallel Cable is supported for the PC only.

3. In the Port Name list box, select the port to use for downloading and readback. If the port name you want is not listed, select the blank name from the list box and type in the new port name. This list box saves up to two user-specified port names.

The Port Name list box contains a list of valid ports for the platform, as shown in the following table. If you selected the MultiLINX Cable, the USB port is displayed. If you selected a serial cable, the serial ports are displayed. If you selected a parallel cable, the parallel ports are displayed.

Table 2-3 USB, Serial, and Parallel Ports

Platform	USB Ports	Serial Ports	Parallel Ports
Sol	none	/dev/ttya, /dev/ttyb	not supported
HP 10.x	none	/dev/tty00, /dev/tty01 or /dev/ttya, /dev/ttyb	not supported
PC	USB	com1, com2, com3, com4	lpt1, lpt2, lpt3, lpt4

4. In the Baud Rate list box, select a communications baud rate between the cable and the host system. You cannot specify the baud rate for a parallel cable.

Communication speed between the host system and the Cable depends on host system capability. Refer to the “Valid Baud Rates” table for a list of valid baud rates.

5. Click **OK** to accept the selections.
iMPACT will attempt to connect to the cable.

Resetting the Cable

To reset internal logic of the cable after a power glitch, select **Output** → **Cable Reset** to reset the internal logic of the cable. The cable is reinitialized and the proper baud rate is set.

Reset your cable if you experience a power failure to the target device board.

Disconnecting the Cable

To disconnect the cable connection, select **Output → Cable Disconnect**.

Note You will need to disconnect the cable if you wish to use the same cable in a different configuration mode. For instance, if you start using the parallel cable in boundary-scan mode, then wish to use it for Slave Serial configuration, you will first have to disconnect it in boundary-scan and reconnect it in Slave Serial mode.

Target Board Requirements

The following are general target board requirements for all target boards regardless of the type of cable being used. Specific cables and configuration modes may have additional target board requirements.

High Performance Ribbon Cable

The Parallel Cable IV uses a high performance ribbon cable which incorporates multiple signal-ground pairs. The cable has a single 14-pin connector which requires a corresponding 14-pin board header with 0.5mm square posts on 2mm centers.

When you lay out the printed circuit board for use with iMPACT in-system programming and testing, a few adjustments will make the process of connecting and downloading easier. Place pins or header on the board so that flying leads or the high performance ribbon cable can reach them. The length of our flying leads is either six inches (Parallel Cable) or twelve inches (MultiLINX Cable). The ribbon cable is recommended for all new designs for the highest speed.

Flying Lead Connectors

Xilinx cables use flying lead connectors that have individual female connectors on one end that fit onto standard 0.025" square male pins on your target board. Each lead is labeled to identify the proper pin connection.

Flying Leads

- Provide pins on your printed circuit board for your desired configuration mode. For example, Boundary-Scan configuration would require VCC, GND, TCK, TDO, TDI and TMS header pins.

- These pins must be standard 0.025" square male pins that have dedicated traces to the target device control pins. You connect to these pins with the flying lead connector.
- While pins may be a couple of inches apart, do not have any two JTAG connector pins more than six inches apart. The high performance cable is 6" long.

Note Keep header pins on your board a minimum of 0.10" apart.

Mode Pin Connections for FPGAs Only

When using download cables to configure a device or chain of devices, you must set the appropriate device configuration mode. You must set M0, M1, and M2 to the value specified in the device's databook for the desired mode. Refer to the *Development System Guide* or *The Programmable Logic Data Book* for information on setting the mode pins.

If you are using a Parallel Download Cable proceed to the Parallel Cable section.

If you have a MultiLINX Cable proceed to the MultiLINX Cable section.

Parallel Cable IV

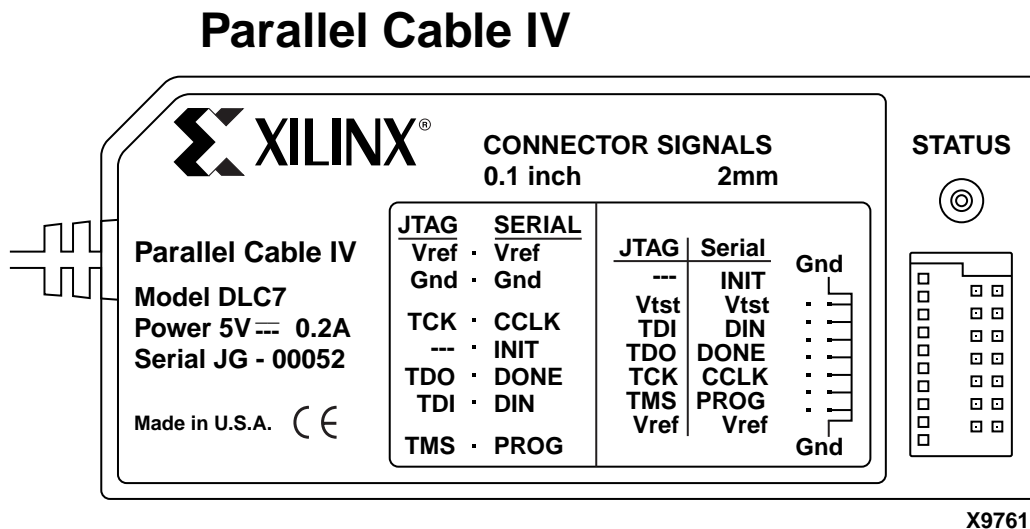


Figure 2-2 Top View of the Parallel Cable IV

The new Xilinx Parallel Cable IV (PC IV) is a high-speed download cable that configures or programs all Xilinx FPGA, CPLD, ISP PROM, and System ACE MPM devices. The cable takes advantage of the IEEE 1284 ECP protocol and Xilinx iMPACT software to achieve download speeds that are over 10 times faster than the PC III. The cable automatically senses and adapts to target I/O voltages and is able to accommodate a wide range of I/O standards from 1.5V to 5V.

PC IV supports the widely used industry standard IEEE 1149.1 Boundary Scan (JTAG) specification using a four-wire interface. It also supports the Xilinx Slave Serial mode for Xilinx FPGA devices. It interfaces to target systems using a ribbon cable that features integral alternating ground leads to reduce noise and increase signal integrity.

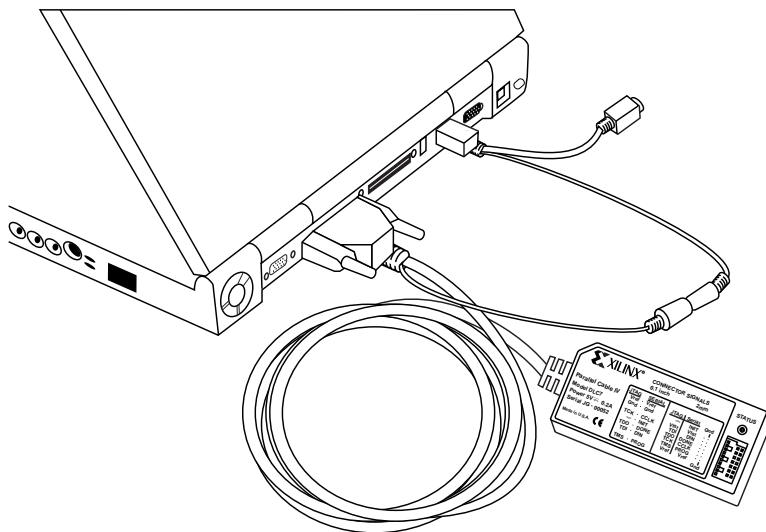
The cable is externally powered from either a power brick or by interfacing to a standard PC mouse or keyboard connection. A bi-color status LED indicates the presence of operating and target reference voltages.

Connecting to Host Computer

The PC IV connects to any PC using Win98, Win2000, or WinNT (4.0 or higher) through the standard IEEE 1284 DB25 parallel (printer) port connector. To fully utilize the higher speeds of this cable, the host PC must have a parallel port that is enabled to support extended capability port (ECP) mode. If ECP mode is not enabled, the PC IV will default to compatibility mode and will not run at the optimum speeds listed.

Cable Power

The host interface cable (Figure 2-3) includes a short power jack for connection to one of two possible +5V DC power sources: (1) an external AC adapter or (2) the keyboard or mouse port of the host PC (shown). The supplied power splitter cable is required when using the first option. The splitter cable is installed between the mouse cable and the standard 6-pin mini-DIN (PS2) connector on the host PC. PC IV operating current is less than 100 mA. It draws approximately 15 mA from the target board's reference voltage supply to power the JTAG/Slave Serial buffers.



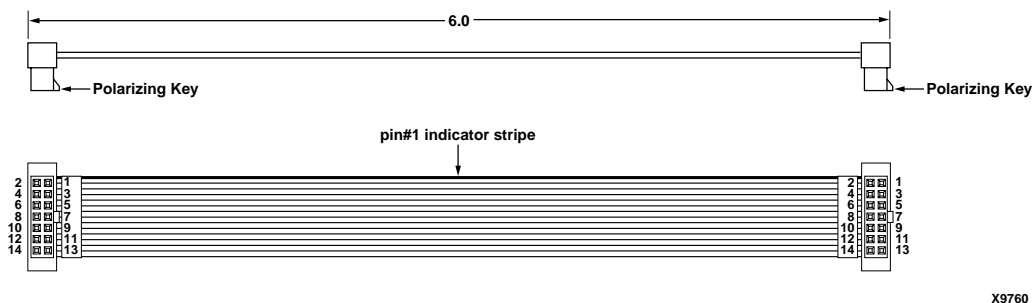
X9762

Figure 2-3 Parallel Cable IV Parallel and PS2 Connection

High Performance Ribbon Cable

An insulation displacement (IDC) ribbon cable is supplied and recommended for connection to target systems. This cable incorporates multiple signal-ground pairs and facilitates error-free connection. A very small footprint, keyed mating connector is all that is required on the target system. Refer to RD Redigure for the appropriate connector pin assignments and sample vendor part numbers.

The Parallel Cable IV can also interface to target systems using flying lead wires. However, these are not included with PC IV and can be purchased separately from the Xilinx E-Commerce web site.



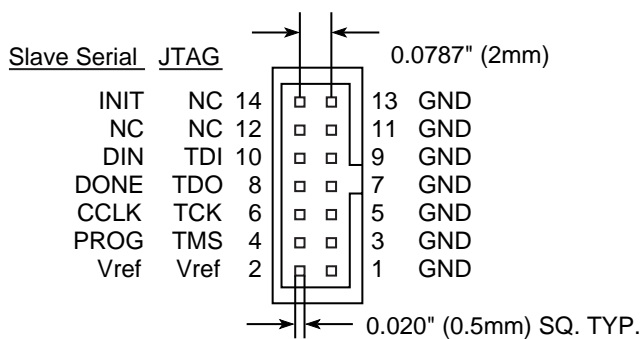
X9760

Figure 2-4 High Performance Ribbon Cable

Note Ribbon Cable - 14 conductor 1.0mm centers Round Conductor Flat Cable; 28 AWG (7x36) stranded copper conductors; gray PVC with pin 1 edge marked.

Note 2mm Ribbon Female Polarized Connectors - IDC connection to ribbon; contacts are beryllium copper plated; 30 micro inches gold plating over 50 micro inches nickel; connectors mate to 0.5mm square posts on 2mm centers.

Target Board Header



X9776

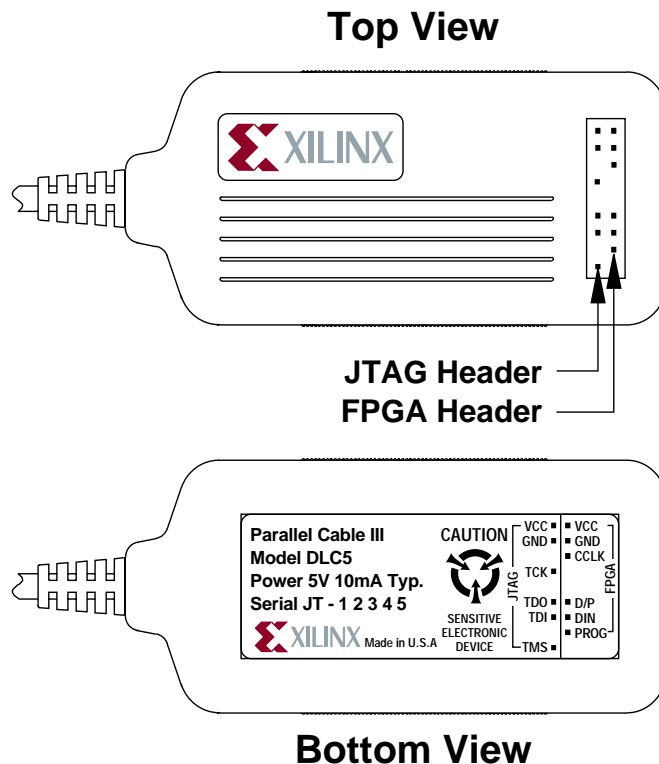
Figure 2-5 Target Interface Connector Signal Assignments

Table 2-4 Mating Connectors for 2mm pitch, 14 Conductor Ribbon Cable

Manufacturer	SMT. Vertical	SMT. Right Angle	Through-Hole Vertical	Through-Hole Right Angle
Molex	87333-1420	N/A	87331-1420	87333-1420
FCI	95615-114	N/A	90309-114	95609-114
Comm Con Connectors	2475-14G2	N/A	2422-14G2	N/A

Parallel Cable III

Parallel Cable III



X9759

Figure 2-6 Top and Bottom View of Parallel Download Cable III

The Parallel Download Cable III consists of a cable assembly containing logic to protect your PC's parallel port and a set of headers to connect to your target system. PC III is replaced by PC IV in March 2002 with legacy support from iMPACT.

Using the Parallel Download Cable requires a PC equipped with an AT compatible parallel port interface with a DB25 standard printer connector. Figure 2-1 shows the Parallel Download Cable.

Connecting for System Operation

Connect the parallel cable to the host system and your target system as shown in Figure 2-3.

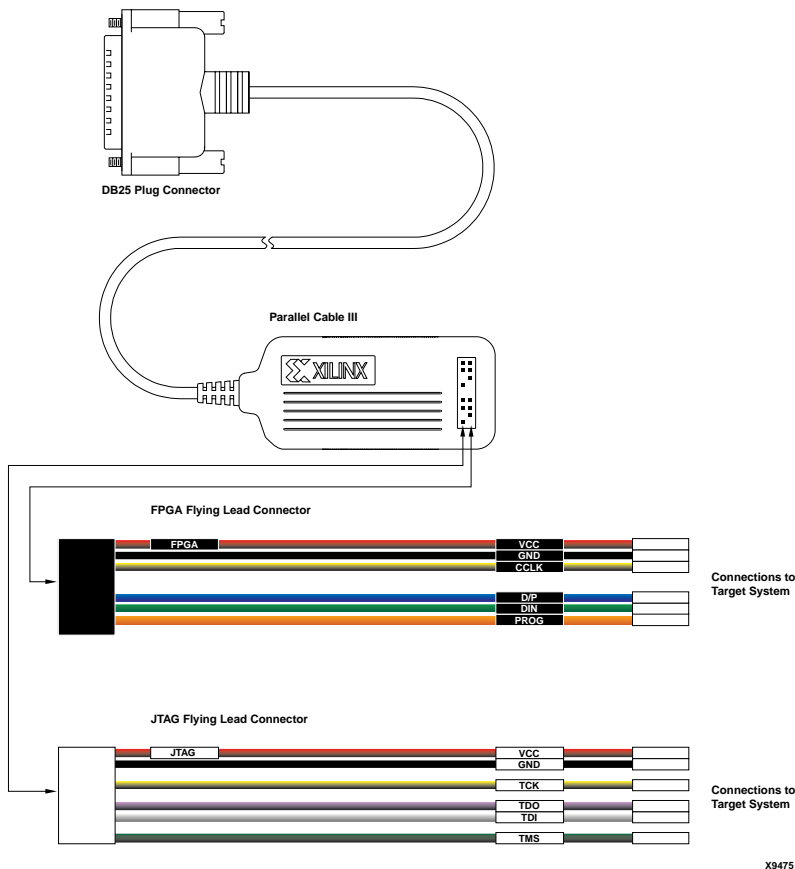
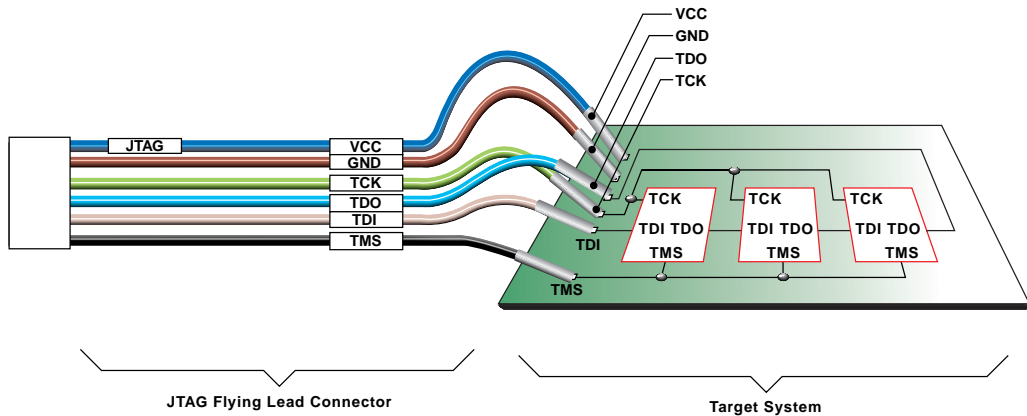


Figure 2-7 Parallel Download Cable III and Accessories

The parallel download cable can download to a single device or several devices connected in either a boundary-scan chain or a slave-serial daisy chain (FPGA only). The parallel cable can also be used to read back configuration and boundary-scan data.

The transmission speed of the Parallel Download Cable is determined solely by the speed at which the host PC can transmit data through its parallel port interface.



X8005

Figure 2-8 Parallel Download Cable Connection to JTAG Boundary-scan TAP

JTAG parallel cable schematic contains schematic diagrams of the Parallel Download Cable.

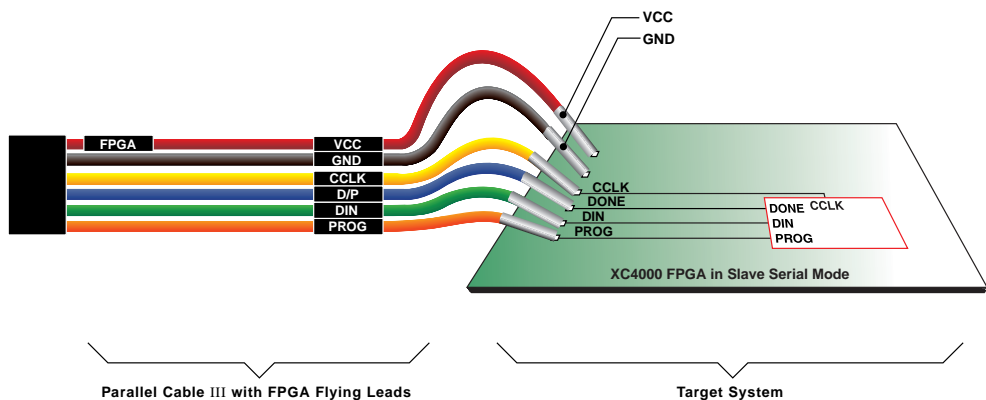
Table 2-5 Parallel Cable Connections and Definitions

Name	Function	Connections
VCC	Power – Supplies VCC (5 V, 3.3V, or 2.5V, 10 mA, typically) to the cable.	To target system VCC
GND	Ground – Supplies ground reference to the cable.	To target system ground
TCK	Test Clock – this clock drives the test logic for all devices on boundary-scan chain.	Connect to system TCK pin.

Table 2-5 Parallel Cable Connections and Definitions

Name	Function	Connections
TDO	Read Data – Read back data from the target system is read at this pin.	Connect to system TDO pin.
TDI	Test Data In – this signal is used to transmit serial test instructions and data.	Connect to system TDI pin.
TMS	Test Mode Select – this signal is decoded by the TAP controller to control test operations.	Connect to system TMS pin.

Serial Configuration Connection



X8326

Figure 2-9 Parallel Cable III Connections

Table 2-6 Parallel Cable Connections and Definitions

Name	Function	Connections
VCC	Power – Supplies VCC (5 V, 3.3V, or 2.5V, 10 mA, typically) to the cable.	To target system VCC
GND	Ground – Supplies ground reference to the cable.	To target system ground
CCLK	<i>Configuration Clock</i> --- is the configuration clock pin, and the default clock for readback operation.	Connect to system CCLK pin.
DONE (D/P)	<i>Done/Program</i> --- Indicates that configuration loading is complete, and that the start-up sequence is in progress.	Connect to system DONE pin.
DIN	<i>Data In</i> --- Provides configuration data to target system during configuration and is tristated at all other times.	Connect to system DIN pin.
PROG	<i>Program</i> --- A Low indicates the device is clearing its configuration memory. Active Low signal is used to initiate the configuration process.	Connect to system PROG pin.

MultiLINX Cable

Figure 2-10 shows the top and bottom view of the MultiLINX Cable.

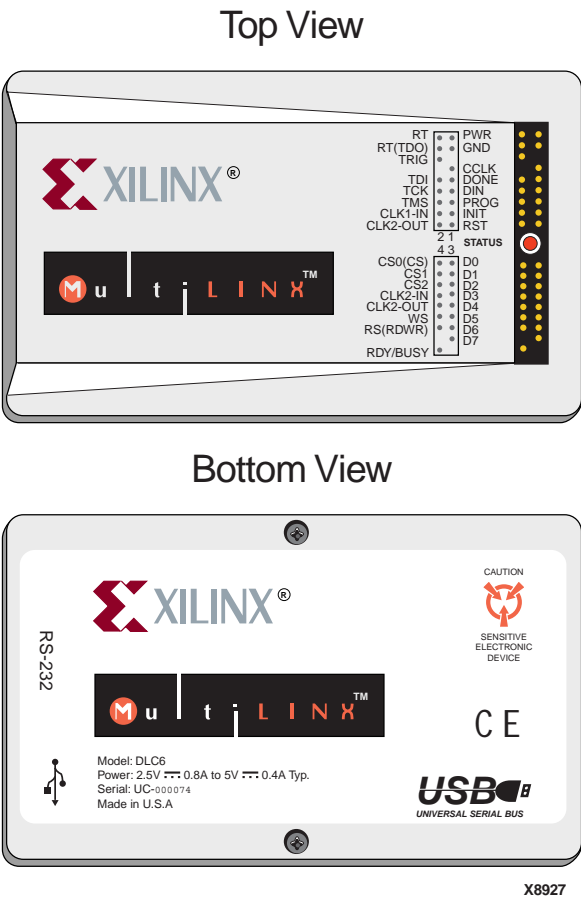


Figure 2-10 MultiLINX Cable

You can use the MultiLINX Cable to download and verify all Xilinx CPLDs and FPGAs. The MultiLINX Cable hardware communicates with the host over the Universal Serial Bus (USB) at up to 12M bits/sec, or at variable baud rates over an RS-232 interface at up to 57600 bits/sec.

You can access the following application notes with descriptions of device-specific design techniques and approaches from the support page at (<http://support.xilinx.com/support/searchtd.htm>).

“Getting Started with the MultiLINX Cable” application note is a quick reference to everything you need to know to use the MultiLINX

Cable, including using a USB device, Mixed Voltage environments, and connections for all the supported Modes.

“Integrating MultiLINX Cable with Target System Design” application note describes how to set up a Prototype application for use with the MultiLINX Cable.

“Xilinx Cable Overview and Roadmap” application note describes all the cables, their capabilities, and associated software tools.

MultiLINX Power Requirements

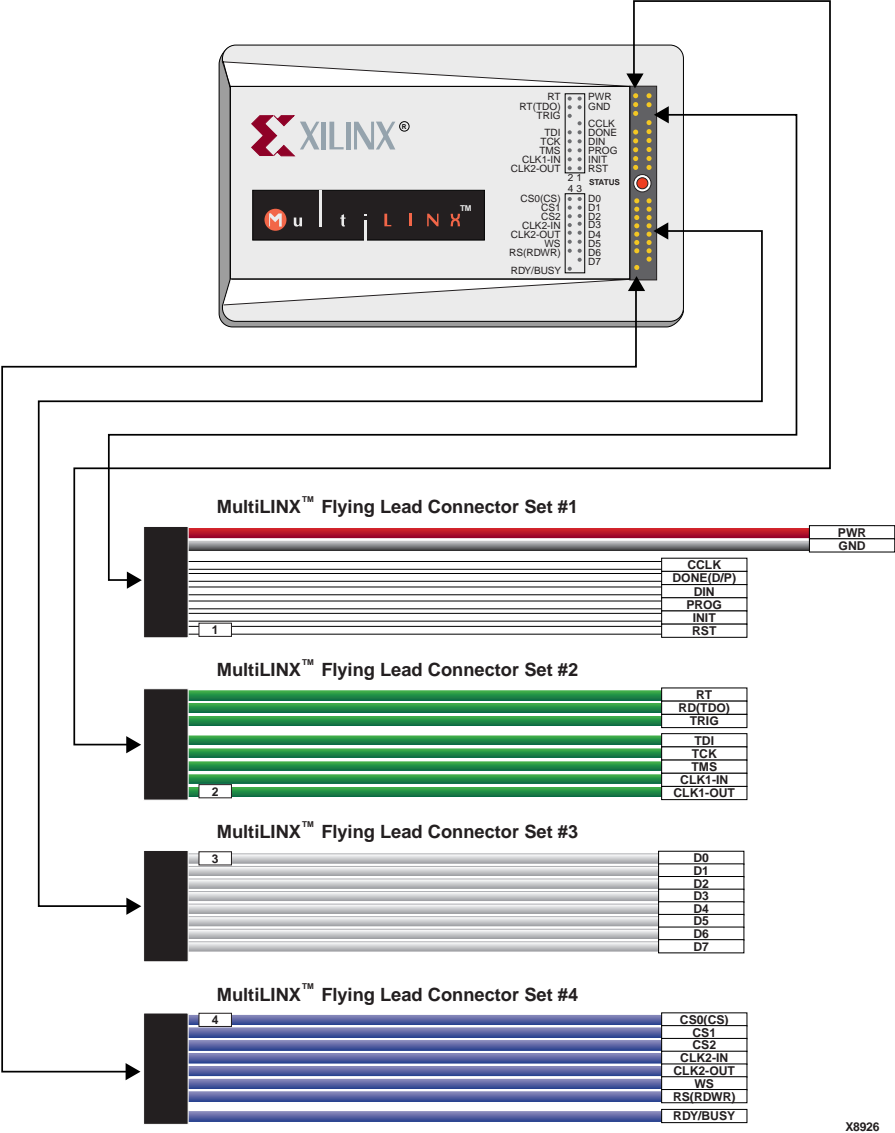
The MultiLINX Cable gets its power from the User’s circuit board. The cable power does not come from the USB port (nor the RS-232 port). The red (PWR) and black (GND) wires from Flying Wire Set #1 are connected to the VCC (red wire) and Ground (black wire) lines of the circuit board that is powering the Xilinx device.

The minimum input voltage to the cable is 2.5 V (.8 A). The maximum input voltage is 5 V (.4 A).

MultiLINX Cable and Flying Leads

The MultiLINX Cable is shipped with four sets of flying lead wires. A USB Cable and RS-232 Cable (with adapter) are also supplied.

Figure 2-11 shows the MultiLINX Cable hardware and flying lead connection wires.



X8926

Figure 2-11 MultiLINX Cable and Flying Lead Connectors

The MultiLINX Flying wires are described in the following tables.

Table 2-7 MultiLINX Pin Descriptions (Flying Lead Set #1)

Signal Name	Function
PWR	<i>Power</i> - Supplies VCC to cable (Works at multiple voltages 5V, 3.3V, and 2.5V).
GND	<i>Ground</i> - Supplies ground reference to cable.

Table 2-8 MultiLINX Slave Serial Pin Descriptions (Flying Lead Set #1)

Signal Name	Function
CCLK	<i>Configuration Clock</i> - is the configuration clock pin, and the default clock for readback operation.
DONE (D/P)	<i>Done/Program</i> - Indicates that configuration loading is complete, and that the start-up sequence is in progress.
DIN	<i>Data In</i> - Provides configuration data to target system during configuration and is tristated at all other times.
PROG	<i>Program</i> - A Low indicates the device is clearing its configuration memory. Use the Active Low signal to initiate the configuration process.

**Table 2-8 MultiLINX Slave Serial Pin Descriptions
(Flying Lead Set #1)**

Signal Name	Function
INIT	<i>Initialize</i> — Initialization sequencing pin during configuration (indicates start of configuration). A logical zero on this pin during configuration indicates a data error.
RST	<i>Reset</i> — Pin used to reset internal FPGA logic. Connection to this pin is optional during configuration.

**Table 2-9 MultiLINX Boundary-Scan Pin Descriptions
(Flying Lead Set #2)**

Signal Name	Function
RD (TDO)	<i>Read Data</i> — MultiLINX input. iMPACT receives the readback data through the RD pin after readback is initiated. Pin used to initiate a readback of target FPGA. TDO is for JTAG (Boundary-Scan).
TDI TCK TMS	These pins are used for JTAG (Boundary-Scan) device configuration. The JTAG/boundary scan pins function for FPGA and CPLD, ISP PROM, JTAG and SystemACE MPM operations.

**Table 2-10 MultiLINX Select Map Pin Descriptions
(Flying Lead Sets 3&4)**

Signal Name	Function
D0-D7	<i>Data Bus</i> — This pin is used for Virtex SelectMAP Mode. An 8 bit data bus supporting the SelectMAP and Express configuration modes.
CS0 (CS)	<i>Chip Select</i> — CS on the Virtex. The CS0/CS pin represents a chip select to the target FPGA during configuration.
CS1	<i>Chip Select</i> — The CS1 pin represents Chip Select to FPGAs during configuration.
CS2	<i>Chip Select</i> — The CS2 pin represents Chip Select to the FPGA while using the Peripheral configuration mode.
WS	<i>Write Select</i> — The WS pin represents Write Select control for the Asynchronous Peripheral configuration mode.
RS (RDWR)	<i>Read Select</i> — The RS pin represents Read Select control for the Asynchronous Peripheral configuration mode. <i>Read/Write</i> — The RDWR pin is used as an active high READ and an active low WRITE control signal to the Virtex FPGA.
RDY/BUSY	<i>Busy Pin</i> — Busy pin on the Virtex.

MultiLINX Connection and Power Sequence

The following considerations should be followed when powering up the MultiLINX cable.

Caution Connecting the MultiLINX leads to the wrong signal will cause permanent damage to the MultiLINX internal hardware. You must connect PWR to VCC and GND to ground. As with any CMOS device, the input/output pins of the internal FPGA should always be at a lower or equal potential than the rail voltage to avoid internal damage. The cable draws its power from the target system through VCC and GND. Therefore, power to the cable, as well as to the target FPGA, must be stable. Do not connect any signals before connecting VCC and GND.

Connecting Cable to Target System

This section covers cable connection to the target device. You need appropriate pins on the target system for connecting the target system board to the header connectors on the cable.

1. Connect your cable to your host computer. If you have a MultiLINX Cable, connect it to the USB or RS-232 port. A DB-9/DB-25 adapter may be required to connect the cable to your serial port. If you have a different serial port connection, you need to use the appropriate adapter.
2. Turn the power to your target system off, if possible.
3. The power for the drivers is derived from the target system. Connect the cable's GND wire to the corresponding signal on the target board. Next, connect VCC to the corresponding signal on the target board.
4. Download cables will not operate if the target system's power is turned off before or during iMPACT Configuration operations. Make certain that this power connection is on and stable. Your system's power should be on during iMPACT Configuration operations.
5. Next, connect the signal leads.

Note When using boundary-scan connections, please note that TRST is not supported by Xilinx Download Cables. If any of your JTAG parts have a TRST pin, it should be connected to VCC.

6. Turn on power to the target system.
7. Make sure VCC rises to a stable level within 10ms. After the cable VCC stabilizes, the level should be within 5% of the target systems VccIO.

Designing Boundary-Scan and ISP Systems

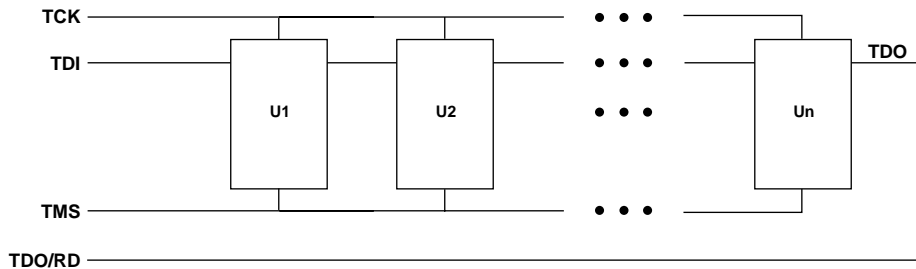
This chapter gives design considerations for boundary-scan and ISP systems.

This chapter contains the following sections.

- “Connecting Devices in a Boundary-Scan Chain”
- “FPGA Device Considerations”
- “Selecting a Configuration Mode”
- “Programming and Configuring Options”
- “Xilinx Common Configuring and Programming Setups”
- “Virtex Series or Spartan-II Master Serial and Boundary-Scan (JTAG) Combination Setup”
- “Spartan/XL Master Serial and JTAG Combination Setup”
- “Configuration Checklist”

Connecting Devices in a Boundary-Scan Chain

All devices in the chain share the TCK and TMS signals. The system TDI signal is connected to the TDI input of the first device in the boundary-scan chain. The TDO signal from that first device is connected to the TDI input of the second device in the chain and so on. The last device in the chain has its TDO output connected to the system TDO pin. This configuration is illustrated in Figure 3-1.



X8006

Figure 3-1 Single Port Serial Boundary-Scan Chain

The boundary-scan standard requires pull-up resistance to be supplied internally to the TDI and TMS pins by the chips, but no particular value is required. This allows vendors to supply whatever they choose and still remain in full compliance. Because of this, very long boundary-scan chains, or chains using parts from multiple vendors, may present significant loading to the ISP drive cable. In these cases:

- Use the latest Xilinx download cables (parallel cables with serial numbers greater than 5000, or MultiLINX cable).
- Consider including buffers on TMS or TCK signals interleaved at various points on your JTAG circuitry to account for unknown device impedance.
- Some users have noted that their designs appear to experience erase time or programming time extension as the design progresses, particularly for long chains. This is probably due to switching noise.
- Put the rest of the JTAG chain into HIGHZ mode by selecting the HIGHZ preference in the iMPACT Edit → Preferences dialog box when programming a troublesome part.
- If free running clocks are delivered into boundary-scan devices, it may be necessary to disconnect or disable their entry into these devices during ISP or boundary-scan operations.
- Charge pumps, the heart of the XC9500/XL/XV ISP circuitry, require a modest amount of care. The voltages to which the

pumps must rise are directly derived from the external voltage supplied to the VCCINT pins on the XC9500/XL/XV parts. Because these elevated voltages must be within their prescribed values to properly program the CPLD, it is vital that they be provided with very clean (noise free) voltage within the correct range. This suggests the first two key rules:

- Make sure VCC is within the rated value for the devices you are using.
- Provide both 0.1 and 0.01 uF capacitors at every VCC point of the chip, and attach directly to the nearest ground.

FPGA Device Considerations

iMPACT supports the configuration of Xilinx FPGA devices through the boundary-scan test access port (TAP). In order to enable boundary-scan-based configuration capabilities for FPGA devices, you must design your systems and prepare your configuration bitstreams in the following manner.

Bitstream Considerations

Express mode bitstreams cannot be used to configure devices via boundary-scan.

If you are using Spartan or SpartanXL, make certain that the boundary-scan (BSCAN) symbol has been included in your design. If it is not, then the bitstream will not be usable for boundary-scan based configuration.

Keep your device bitstream files separate for each device in the boundary-scan chain. iMPACT requires you to assign a single bit file to each device. It cannot manipulate composite bit files in Boundary Scan mode.

Virtex Considerations

When generating bitstreams for Virtex devices, always select the option to choose the JTAG clock as the startup clock. iMPACT will notify you if this is set incorrectly.

XC4KXLA, XV, Spartan XL Considerations

When generating bitstreams for these devices, always select the option to enable BSCAN status.

For Spartan and Spartan XL devices, Xilinx recommends that all the mode pins of the devices be tied low before starting the configuration.

In order to enable the boundary-scan circuitry in the device, you must install a pull-down resistor on the INIT pin. The value of the pull-down should be selected so as to draw the INIT pin to approximately 0.5V. Typically a pull-down of approximately 1KOhm should accomplish this.

Important Legacy FPGA Boundary-Scan Information

The XC4KE/L/XL/EX (not XC4KXLA/XV) and the Spartan (not XL or II) devices freeze if data errors occur during boundary-scan configuration. The only method for unlocking the frozen device is to reset the power to the device or pulse the PROGRAM pin low. (This latter method would have to be accomplished manually since the download cables (when being used for boundary-scan operations), do not have control over the PROGRAM pin. Although this situation is rare, it is possible to design your system so as to detect if that condition has occurred. The iMPACT software enables you to check for this in two ways:

1. Assume successful verification - since it is a low probability event, simply configure the device and run. The drawback is that the failure of the device is then only detected at run-time.
2. Readback verify the configuration memory - after configuring, readback the contents of the configuration memory and check against the source bitstream file. If the device has frozen, the returned bits will be incorrect. Since bit files can be large, this might be time consuming.

Device Behavior Notes

Any verify operation executed immediately after configuration without boundary-scan functionality enabled will fail because the test access port no longer exists. Always remember to instantiate the

BSCAN symbol for reliable operation of your Spartan and SpartanXL devices.

The implementation of boundary-scan based configuration of FPGAs precludes the use of concurrent ISP. For this reason, the concurrent mode preference is disabled (or ignored) when FPGAs are selected to be operated upon.

Selecting a Configuration Mode

Before deciding on the configuration environment, it is important to be aware of the available configuration modes. The following table shows the modes supported by each family with a description of each mode following the table.

Table 3-1 Modes Supported (by Family)

Family	JTAG	SelectMAP / Slave- Parallel	Master- Serial	Slave-Serial	Standalone Programmer
Virtex/E/II/II-PRO Families (FPGA)	X	X	X	X	
CoolRunner-II	X				X
Spartan/XL/II/II-E Families (FPGA)	X	Spartan-II/ II-E only	X	X	
XC9500/XL/XV Families (CPLD)	X				X
XPLA3 Family (CPLD)	X				X
XC18V00 Family (PROM)	X				X
XC17S00 Family (PROM)					X

FPGA Supported Modes

Note iMPACT does not support Express Mode download to Spartan-II devices.

JTAG or Boundary-Scan Mode

JTAG or Boundary Scan mode is an industry standard (IEEE 1149.1, or 1532) serial programming mode supported by iMPACT. External logic from a cable, microprocessor, or other device is used to drive the JTAG specific pins, Test Data In (TDI), Test Mode Select (TMS), and Test Clock (TCK). This mode has gained popularity due to its standardization and ability to program FPGAs, CPLDs, and PROMs through the same four JTAG pins. The data in this mode is loaded at one bit per TCK.

SelectMAP/Slave-Parallel Modes

SelectMAP mode is supported by the Virtex families, and Slave-Parallel mode is supported by the Spartan-II family, as well as by iMPACT. SelectMAP/Slave-Parallel modes allow parallel reading and writing through byte-wide ports. An external clock source, microprocessor, download cable or other FPGA is required. The data is loaded one byte per CCLK in this mode. This mode is typically used as a configuration mode on Virtex-E/Virtex-II or Spartan-II devices when configuration speed is an important factor.

Master-Serial Mode

Master-Serial mode is supported by all Xilinx FPGA families, but not Xilinx CPLDs, nor by iMPACT. It is the simplest configuration method for FPGAs. The FPGA loads configuration data from a serial PROM. Using the FPGA to provide the clock, it virtually loads itself and utilizes its internal oscillator, which drives the configuration clock. The FPGA provides all the control logic. In this mode, data is loaded at one bit per CCLK.

Slave-Serial Mode

Slave-Serial mode, like Master-Serial, is supported by all Xilinx FPGA families, but not Xilinx CPLDs. It uses an external clock and allows for daisy-chain configurations. In this mode, an external clock, such as a microprocessor, another FPGA, or download cable is required.

Data in this mode is loaded at one bit per CCLK. Slave Serial mode is supported by iMPACT.

CPLD/PROM Supported Modes

Standalone Programmer Mode

Standalone Programmer mode is supported by Third Party Programmers, and the MultiPRO Desktop Programming Cable.

JTAG or Boundary Scan Mode

JTAG or Boundary Scan mode is an industry standard (IEEE 1149.1, or 1532) serial programming mode. External logic from a cable, microprocessor, or other device is used to drive the JTAG specific pins, Test Data In (TDI), Test Mode Select (TMS), and Test Clock (TCK). This mode has gained popularity due to its standardization and ability to program FPGAs, CPLDs, and PROMs through the same four JTAG pins. The data in this mode is loaded at one bit per TCK.

Programming and Configuring Options

The next section gives an overview of all configuration or programming flows for each family.

CPLD Programming Options

The CPLD programming flow starts after the CPLD fitter software generates the **jedec** file. The following chart shows the options available for downloading the **jedec** file into the CPLD device.

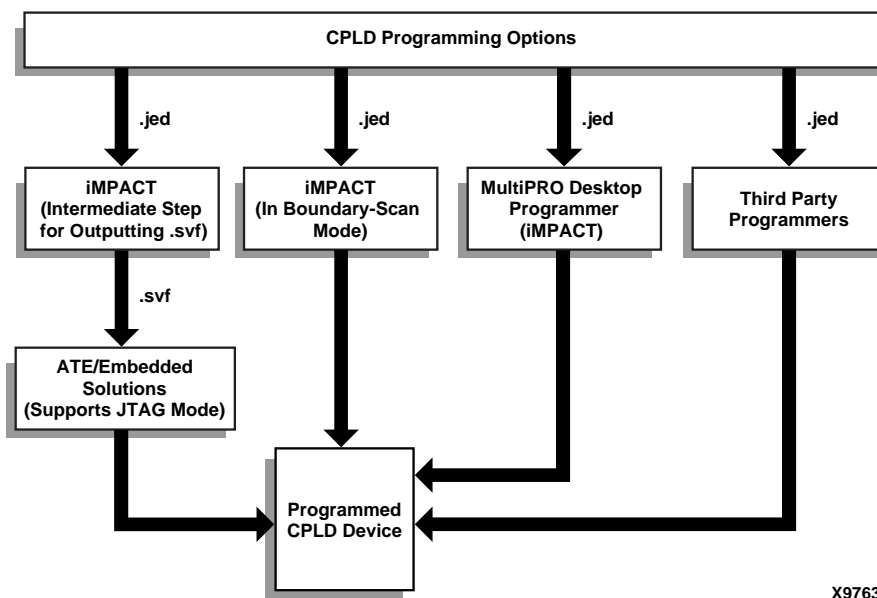


Figure 3-2 CPLD Programming Options

ATE/Embedded Solutions

Embedded solutions are becoming very popular as board densities increase and microprocessors become commonplace in many systems. For examples of how to use Xilinx CPLDs in ATE or embedded systems, see the websites at: <http://www.xilinx.com/isp/ate.htm> and <http://www.xilinx.com/isp/ess.htm>

MultiPRO Desktop Programmer

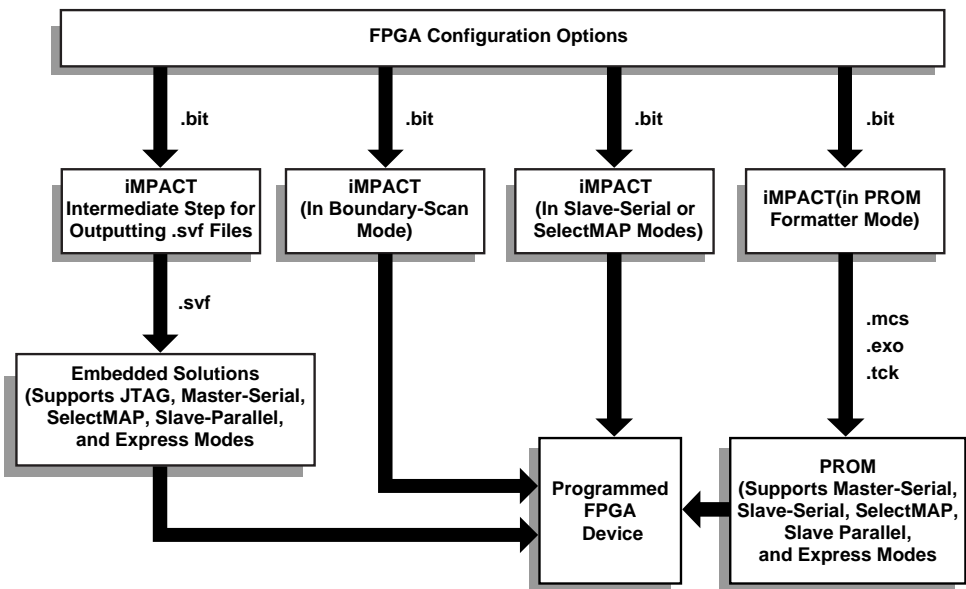
MultiPRO is the Xilinx desktop programmer. Primarily an upgrade from the HW130, the MultiPRO cable is a multi-function tool capable of ISP configuration using JTAG, Slave-Serial, or SelectMAP interfaces. Ribbon cables can be simultaneously attached to an ISP target system.

Third Party Programmers

Third Party Programmers, such as Data I/O and BP Microsystems, support many Xilinx CPLDS. For details on available third party support, see the website at: <http://www.xilinx.com/support/programr/ps.htm>

FPGA Configuration Flows

Refer to Table 1 for the software packages available to generate FPGA bitstreams. The following chart shows several options for downloading the bitstream into the FPGA device.



X9764

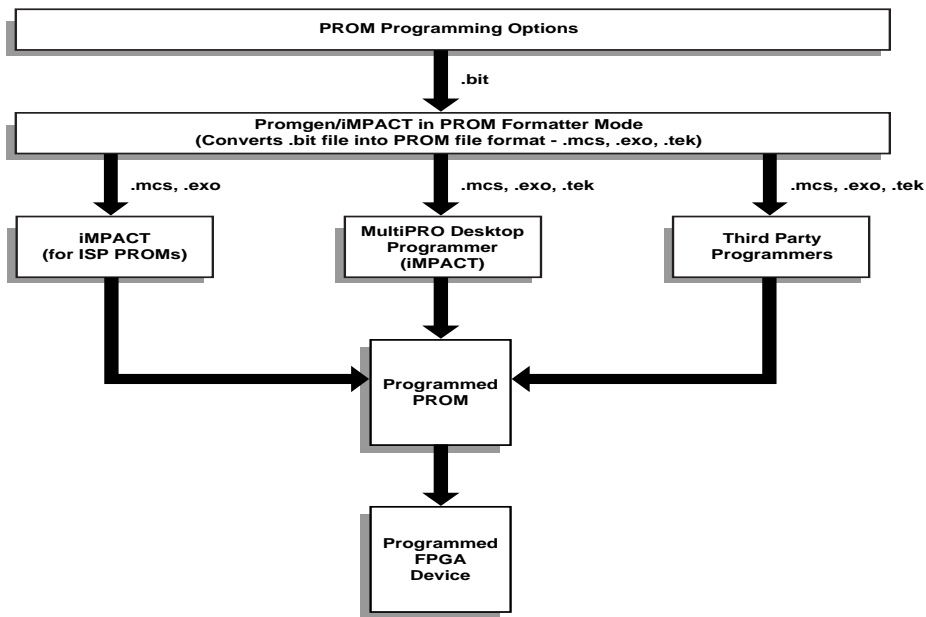
Figure 3-3 FPGA Configuration Options

Embedded Solutions

Embedded solutions are becoming very popular as board densities increase and microprocessors become commonplace in many systems. For examples of using Xilinx FPGA devices in embedded systems, see the website at: http://www.xilinx.com/xlnx/xil_prodcats/product.jsp?title=isp_ess_page

PROM

A PROM is a companion memory device to the FPGA. Configuring the FPGA from a PROM is one of the most widely used configuration methods. The PROM must be configured with the data intended for the FPGA. When the PROM is placed in the system, the FPGA configures itself from the memory device. This method supports Master-Serial, Slave-Serial, SelectMAP, Slave-Parallel, and Express modes.



X9765

Figure 3-4 PROM Programming Options

PROMgen/PROM Formatter

PROMgen/PROM Formatter mode of iMPACT are software tools that create PROM files for serial or byte-wide configuration PROMs. These tools convert .bit files into one of three popular standard PROM file formats: MCS, EXO, or TEK.

The PROM Formatter tab of iMPACT's File Generation mode provides a (GUI) version of the PROMgen command line software.

HW-140 is the Xilinx desktop programmer. The Xilinx desktop programmer is used in prototyping environments and can program both types of Xilinx PROMs.

Third Party Programmers

Third Party Programmers, such as Data I/O and BP Microsystems, support many Xilinx CPLDS. For details on available third party support, see the website at: <http://www.xilinx.com/support/programr/ps.htm>

Xilinx Common Configuring and Programming Setups

This section provides the Xilinx user a quick summary of some of the more common configuration and programming setups. There are many other methodologies for configuring Xilinx devices. The following setups are commonly used to allow for easy prototyping of robust production setups. A brief description of the setup advantages, required software and hardware, and hardware connections is provided for each setup.

CPLD JTAG Chain Setup

The CPLD JTAG Chain is the most common programming method for CPLDs, since it can be used for both prototyping and production environments.

Advantages:

In-System Programming support

Requires only the four JTAG pins to configure and test the chain

Hardware Used:

Combination of Xilinx CPLD devices (XC9500/XL/XV, XPLA3, CoolRunnerII).

For Prototyping: Xilinx Cable (Parallel III, IV or MultiLINX)

For Production: Microprocessor (Embedded Solution), Automatic Test Equipment (ATE), or Third Party Programmer

Software Used:

Xilinx CPLD programming **jedec** files (ISE Foundation/Alliance or WebPACK software packages create the **jedec** file)

For Prototyping: iMPACT Software in Boundary-Scan mode

For Production: Xilinx CPLD programming **jedec** files are converted to Xilinx Serial Vector Files (**.svf**) for use with a microprocessor, ATE, or Third Party Programmer. See XAPP058 at: <http://www.xilinx.com/xapp/xapp058.pdf>

See the Xilinx [ATE](#) and [Programmer](#) webpages for more information

Hardware Considerations

The connections to implement a CPLD JTAG chain are shown in the Figure below.

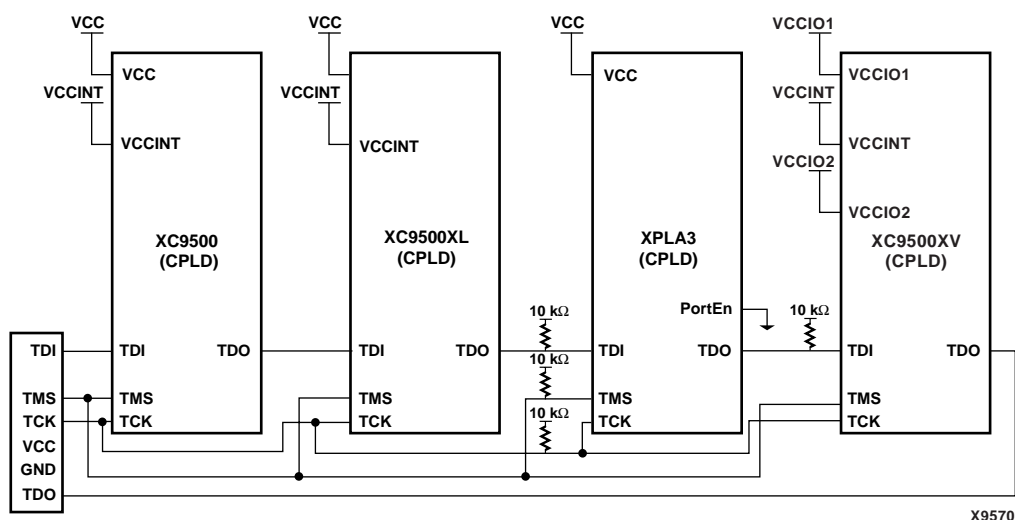


Figure 3-5 CPLD JTAG Chain Connections

When using a JTAG Chain with mixed voltage devices, extra care must be taken to ensure the integrity between the devices. Refer to the device's data sheet for the appropriate voltage operating ranges. In this example, using a 5 V, 3.3 V, and 2.5 V device in a single JTAG chain, although not as typical, allows consideration for a mixed voltage chain to be discussed.

To accommodate both the 9500 (5 V) and 9500XV (2.5 V) devices, the VCCIO signals should be tied to 3.3 V. This drives the TDO pin on all of the devices at 3.3 V, which meets the voltage requirements. For the 9500XV, only the VCCIO bank (1 or 2) where the TDO pin is located needs to be driven at 3.3 V.

When using a cable with this setup, it should be driven at 3.3 V. This ensures that the TMS and TCK TAP pin values are within the required voltage ranges for all of the specified devices. Since the 5 V part receives slightly lower but acceptable signal levels, good signal integrity is another practice that should be given appropriate consideration. Refer to the following sections for tips and techniques to ensure proper integrity strength and general practices on implementing a CPLD JTAG chain.

General JTAG Checklist

Include buffers on TMS and TCK signals interleaved at various points for larger JTAG chains of more than five devices to account for unknown device impedance.

Make sure the V_{CC} is within the rated value: 5 V $\pm 5\%$ for the XC9500 device, 3.3 V $\pm 10\%$ for XC9500XL/XPLA3 devices, and 2.5 V $\pm 10\%$ for the XC9500XV device.

Provide both 0.1 mF and 0.01 mF capacitors at every V_{CC} point of the chip and attach them directly to the nearest ground.

XC9500/XL/XV Specific Checklist

The TDI and TMS (JTAG) pins have internal pullups for the XC9500/XL/XV families and do not require any external pullups since the pins are dedicated for JTAG use.

It is vital that the XC9500/XL/XV devices be provided with very clean (noise free) voltage supplied to the V_{CCINT} pins within the correct range.

The JTAG Clock for the XC9500/XL devices, TCK, has a maximum frequency of 10 MHz.

When deciding the placement of devices in a mixed voltage chain, care should be taken to ensure compatibility. For instance, the XC9500XV parts are not 5 V tolerant, and care should be taken to ensure the device inputs are driven by the appropriate voltage levels.

XPLA3 Specific Checklist

The PortEn pin should be connected to ground when using dedicated JTAG pins as recommended in this programming setup example.

Note: If the JTAG pins need to be used as dual-purpose I/Os, the PortEn pin should be jumpered out. The PortEn pin is driven high to re-establish connection with the JTAG pins.

The XPLA3 JTAG pins should have an external 10 kW resistor placed on them to prevent them from floating.

The JTAG clock for the XPLA3 devices, TCK, has a maximum frequency of 10 MHz.

Software Implementation Considerations

The software **jedec** files need to be created to program the devices. In the implementation step, there are several options that can be modified. The only option whose default setting may need to be changed for 9500/XL/XV configuration purposes is “Create Programmable GND Pins on Unused I/O.” By default this option is not selected. Check this option to prevent unused I/O from floating and drawing additional power.

For CoolRunner XPLA3 devices, two of the most important options for programming you should be aware of are described below:

“Pull Up Unused I/O Pins” – By default, this option is selected. This is the recommended state to prevent additional power draw due to the CMOS I/O.

“Reserve JTAG Port Pins for ISP” – By default, this option is selected. Deselect this option only if you intend the JTAG pins to be used as dual-purpose I/Os.

Software Download Considerations

The last step needed to complete the implementation of a CPLD JTAG Chain is programming the bitstream to the device. With the JTAG Chain programming, this can be done for both prototyping and production environments.

Prototyping Environment

In a prototyping environment, it is very common to use a Xilinx programmer, which comprises a stand-alone downloadable software module that requires a Xilinx cable and access to the JTAG pins of the devices.

Production Environment

In a production environment, ATEs or Third Party Programmers are more common. In general, these tools supply faster programming times, and in many cases, supply a means to program more devices at a given time.

For this environment, a **jedec** file is normally converted into a standard vector format (**.svf**) file. This file format is a standard widely accepted by vendors and is a common way to distribute programming files. This format is an optional output of the Xilinx programmers described above in the Prototyping section. A description of how these files are created in the Xilinx programmers can be found in the ATE guides. Chapter 2, “Creating SVF files” of the ATE document describes in detail how the files are generated.

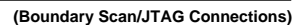
Virtex Series or Spartan-II Master Serial and Boundary-Scan (JTAG) Combination Setup

Master Serial mode and Boundary Scan (JTAG) mode are two of the most commonly used configuration modes for the Virtex Series and Spartan-II devices.

- **Advantages:**
 - ♦ The combination of the Master-Serial mode with the Boundary Scan (JTAG) mode gives you a versatile setup which allows for easy debug and multiple configuration methods.
 - ♦ Master Serial mode provides a simple and robust configuration mode for production, and the Boundary Scan (JTAG) mode provides in-system programming support for flexibility when configuring a chain in the prototyping stage.
- **Hardware Used:** Any combination of Xilinx Virtex/E or Spartan-II and companion 18Vxx companion devices.

- ## Hardware Considerations

The hardware connections to implement the Master Serial/Boundary Scan (JTAG) Mode Combination are shown in the figure below for the Virtex or Spartan-II families.



X9573

Figure 3-6 Virtex/Spartan-II Master Serial and Boundary-Scan (JTAG) Mode Connections

Virtex Spartan-II Master Serial and Boundary-Scan (JTAG) Mode Connections

Additional hardware considerations are listed below:

Refer to the appropriate family data sheets for voltage values required for each part.

For Spartan-II or Virtex mode pins, the following settings are required:

Master-Serial mode – M0=0, M1=0, M2=0

Boundary Scan (JTAG) mode – M0=1, M1=0, M2=1

Boundary Scan (JTAG) pins – For Virtex and Spartan-II, internal programmable 50-150 kW pullups are provided by default on the TMS, TCK, and TDI pins. TDO is floating.

Output buffer can source up to 24 mA and sink up to 48 mA.

The maximum Boundary Scan (JTAG) clock, TCK, for the Virtex devices is 33 MHz and for Spartan-II is 2 MHz-5 MHz.

Software Implementation Considerations

Once the hardware setup has been established, you must create bitstreamsto prepare for programming the devices. When using this configuration setup with the Virtex or Spartan-II devices, consider the following software implementation options when generating the bitstream.

Start-Up Clock – Generate the bitstream with the appropriate startup clock option to configure the part properly. The “Start-Up Clock” option by default is set to “CCLK” for Master Serial Mode. When generating a bitstream for Boundary Scan (JTAG) Mode the option must be set to “JTAGCLK” in the pull-down menu of the GUI or using bitgen’s command line.

For configuring using Boundary Scan (JTAG):

```
bitgen -g startupclk:jtagclk designName.ncd
```

For configuring via Master-Serial:

```
bitgen -g startupclk:cclk designName.ncd
```

If you use these two configuration modes in a setup, you must generate two bitstreams must be generated, one for the Boundary Scan (JTAG) download and the other for the Master Serial download.

The Virtex or Spartan-II configuration options are the same for all of the Xilinx software packages. The default configuration option settings are recommended for this example, and some of the important options are described below:

“Configuration Rate” is an implementation option which controls the speed of the CCLK in Master Serial Mode.

The configuration options include programmable pull-ups on the mode pins, PROGRAM, DONE, and CLK. Leave Boundary Scan (JTAG) pins as a default.

For more detailed information or information on command line options, refer to the *Development Systems Reference Guide*.

Software Download Considerations

After creating the bitstream follow the recommended programming options for this setup as discussed below.

Prototyping

For prototyping with this setup, use the Xilinx iMPACT Configuration tool with a Xilinx cable to download the bitstream from the PC to the device. To achieve this, you must have access to the four Boundary Scan (JTAG) pins of the Virtex, Spartan-II, or the XC18V00 device.

Production

In the production environment, systems must not be affected by power glitches or power down situations. Because the FPGA devices are volatile, a power outage erases the device contents. In order to ensure that the programmed data is not lost when the system is shut off, use a mode like Master Serial. The configuration data is permanently stored in the PROM in this example. If a power outage occurs, the data in the PROM reconfigures the FPGA when you regain power. Below are the steps needed to program a XC18V00 PROM.

- Use the PROM Formatter tab in the File Generation mode in iMPACT (GUI version) or PROMgen (command line version) to format the bitstream into a PROM file.
- Use iMPACT Boundary Scan mode to program the PROM.

Spartan/XL Master Serial and JTAG Combination Setup

Serial mode and JTAG mode are two of the most commonly used configuration modes for the Spartan/XL devices.

- **Advantages:**
 - ◆ Versatile and cost-effective solution
 - ◆ Master Serial Mode provides a simple and robust configuration mode for production, and the JTAG Mode provides In-System programming support for flexibility when configuring a chain in the Prototyping stage.
- **Hardware Used:**
 - ◆ Any combination of Xilinx Spartan/XL and companion 17Sxx devices
 - ◆ For Prototyping: Xilinx Cable (Parallel III or MultiLINX)
 - ◆ For Production: Xilinx PROM and supporting Programmer / Software
- **Software Used:**
 - ◆ Xilinx FPGA programming bitstream (.bit files)
 - ◆ For Prototyping: iMPACT Software
 - ◆ For Production: Xilinx iMPACT Software to create Xilinx PROM files (.mcs, .exo), and appropriate Third Party Programmer software

Hardware Considerations

The hardware connections used to implement the Master Serial/JTAG Mode combination are shown in figure 3-7. Hardware items you should be aware of are listed below:

1. When configuring with Boundary Scan/JTAG mode, you must hold the INIT pin low on power up to allow the device to enter the JTAG mode.

Note Connect INIT to GND for JTAG mode.

2. Set the mode pins for Master-Serial mode for the Spartan/XL: M0=0 and M1=1
3. For the JTAG pins, place a pullup of 4.7 kW on the TMS pin to avoid inadvertent JTAG operations.
4. Allow access to the INIT and DONE pins for initial board debugging. These two pins provide valuable status information.
5. The maximum for the JTAG clock, TCK, for the Spartan/XL is 2-5 MHz.
6. The speed of the CCLK in Master mode varies depending on the mode:
Slow (0.5 MHz - 1.25 MHz) (bitgen option "Configuration Rate.")

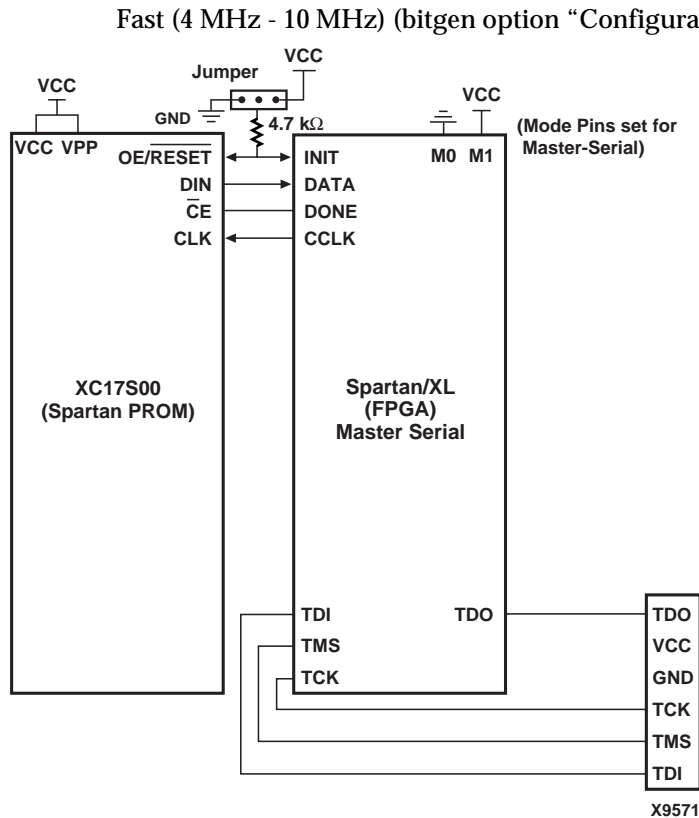


Figure 3-7 Spartan/XL Master-Serial/JTAG Mode Connections

Software Design Entry Considerations

In the Spartan/XL family you must add a library element to keep the JTAG pins from being converted to regular I/O after configuration.

- For the Spartan/XL family, the JTAG pins are dual purpose. If JTAG operations are needed after initial device configuration for reconfiguring the device or for other JTAG functions, you must place the BSCAN symbol in the design. This allows the JTAG pins to be dedicated and not converted to regular I/O after configuration, which is the default behavior.
- For a schematic example, the library element is shown in Figure 3-8. The four JTAG pins (TMS, TCK, TDI, and TDO) are the only pins that must be connected to maintain the JTAG pins. The

TDO1, TDO2, DRCK, SEL1, SEL2, and IDLE are special-purpose pins for custom logic and should be left unconnected.

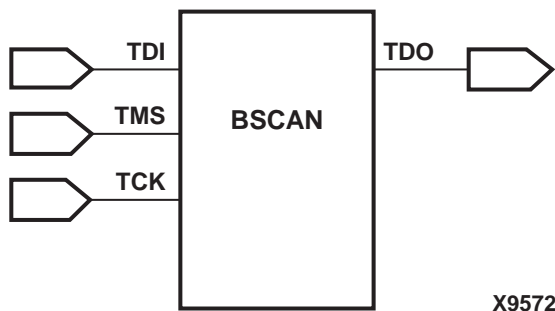


Figure 3-8 Boundary-Scan Spartan/XL Schematic Symbol

Software Implementation Considerations

After you have established the hardware setup, create the software bitstreams to prepare for programming the devices. When using this configuration setup with the Spartan/XL devices, consider the following software implementation options when generating the bitstream:

- “Configuration Rate” – is an implementation option that controls the speed of the CCLK in Master Serial mode. The speeds are described in the “Hardware Considerations” section above.
- “Enable BSCAN-Based Configuration” – is an implementation option that, when disabled, inhibits the BSCAN-based configuration after the device is successfully configured. This feature allows board testing without the risk of reconfiguring the Spartan/XL device by toggling the TCK/TMS/TDI/TDO lines.

For more detailed information or information on command line options, refer to the *Development Systems Reference Guide*.

Software Download Considerations

After the bitstream has been created, the download stage follows:

Prototyping

In this setup for prototyping, use the Xilinx iMPACT Configuration tool with a Xilinx cable to download the bitstream from the PC to the device. To achieve this, you need access to the four JTAG pins of the Spartan/XL device.

- Use the Xilinx Programming software, iMPACT, to download the bitstream to the part. Always be certain to use the latest version of the software.

Production

In the production environment, ensure that systems are not affected by power glitches or power down situations. The FPGA devices are volatile and a power outage erases the device contents. In order to ensure that the programmed data is not lost when the system is shut off, use a mode like Master Serial. The configuration data is permanently stored in the PROM in this example. Therefore, if a power outage occurs, the data in the PROM simply reconfigures the FPGA when power is regained. Below are the steps needed to program a XC17S00 PROM.

- Use the PROM Formatter tab in the File Generation mode in iMPACT (GUI version) or PROMgen (command line version) to format the bitstream into a PROM file.
- Use a third party programmer to program the PROM. See the website at: <http://www.xilinx.com/support/programr/ps.htm>

Configuration Checklist

Before designing a board with FPGAs/CPLDs, consider the following configuration issues.

Hardware:

- Boundary Scan (JTAG) Related:
 - ◆ If there are multiple FPGAs/CPLDs/(ISP)PROMs in a configuration chain, consider adding jumpers to isolate the devices to allow each to be loaded separately for debugging.
 - ◆ Be sure to treat configuration or Boundary Scan (JTAG) clocks like any other high-speed clock.

- ◆ Consider adding extra spare pins to the design to bring signals out for later debugging.
- ◆ Place buffers on TMS or TCK signals interleaved at various points on the Boundary Scan (JTAG) circuitry to account for unknown device impedance.
- ◆ Put the rest of the JTAG chain into HIGHZ mode by selecting the HIGHZ preference on iMPACT when having difficulty programming a particular part. This reduces any noise seen by the part.
- ◆ If free running clocks are delivered into a Boundary Scan (JTAG) device, you may have to disconnect or disable their entry into these devices during ISP or Boundary Scan (JTAG) operations.
- **Cable Related:**
 - ◆ Do not attach extension cables to the target system side of the cable, because this can compromise configuration data integrity and cause checksum errors.
 - ◆ Attach cable configuration leads firmly to the target system.
 - ◆ The Parallel Cable used with PCs draws less power from the target LCA board than the MultiLINX cable. This is because the MultiLINX cable utilizes an embedded microprocessor and has additional features like SelectMAP/USB support that the parallel cable does not have.
 - ◆ Design for the ability to configure using a cable, as well as your selected production configuration method. This allows for programming options and a method for debugging the part easily.
- **Board Related:**
 - ◆ Include the ability to set the mode pins to different values using jumpers.
 - ◆ Remember signal integrity issues, termination, edge rates, ground bounce, and trace layout.
 - ◆ For designs over 60 MHz, Xilinx recommends that you simulate board level switching to ensure there are no reflection or ground bounce issues.

- ◆ Keep in mind simultaneous switching output issues.
- ◆ Ensure that the ground pins are not overloaded to prevent ground bounce on the outputs.
- ◆ Unused I/Os can be set as outputs tied to ground to add extra grounding to a device.
- ◆ If there is space, add LEDs to the DONE pins so that you can determine whether or not the FPGAs were configured.
- ◆ Put test points on the key configuration pins (DOUT, INIT, DONE, and PROGRAM) for debug and status information.
- ◆ Do not overload configuration signals. Check the Fan-out/Fan-in loading of the configuration signals.
- ◆ Use the Output Enable on your clock source so you can stop the system clocks during configuration to check for cross-talk and other noise issues.
- ◆ Be aware of switching noise that might cause erase time or programming time extension as the design progresses, especially for long chains.
- ◆ Make sure the V_{CC} is within the rated value for devices being used.
- ◆ Provide both 0.1 μ F and 0.01 μ F capacitors at every V_{CC} point of the chip, and attach them directly to the nearest ground.
- **Software:**
 - ◆ Xilinx WEBPACK has the latest iMPACT software and can be used as a lab install. This allows you to use the download software without installing the entire software suite of tools located at: <http://www.xilinx.com/products/software/webpowered.htm#webpack>
 - ◆ Programmable pull-ups and pull-downs need I/O pins that are set in the software for configuration.
 - ◆ Check if release of DONE comes after or before the DLL has locked on the system clock.
 - ◆ Do not put regular design signals on configuration pins.
 - ◆ The STARTUP block is not recommended for Virtex/Spartan designs. If using this feature, be sure the internal signals do

not conflict and lock up the part after configuration. The STARTUP reset polarity and the regular system reset need to be of the same polarity.

- ◆ Check for system noise by running the IDCODE looping instruction in iMPACT (Operations → IDCODE Looping). This displays the edit window. Specify the number of loops desired. The operation should complete this correctly otherwise, there might be system noise.

Configuration Problem Solvers

The following software tools step you through configuration problems based on the inputs you provide the tool. Go to: <http://www.xilinx.com/support/troubleshoot/psolvers.htm>

Using iMPACT to Configure Devices

This chapter shows you how to use iMPACT to program and verify devices, as well as gives you some troubleshooting tips for common issues. It focuses on the most commonly used features and methodologies in iMPACT. For more detailed information on specific menu items and options that are not covered here, use the context sensitive help inside the iMPACT program.

This chapter contains the following sections.

- [“Configuration Mode General Information”](#)
- [“Connecting to a Cable”](#)
- [“Boundary-Scan Configuration Mode”](#)
- [“Available Boundary-Scan Operations”](#)
- [“Performing Boundary Scan Operations”](#)
- [“Slave Serial Configuration Mode”](#)
- [“Select MAP Configuration Mode”](#)
- [“Desktop Programmer Mode”](#)

Configuration Mode General Information

Configuration is the process of loading design-specific information into one or more FPGA, PROM, or CPLD devices to define the functional operations of the logical blocks, their interconnectors, and the chip I/O. If you are going to configure devices in this mode of iMPACT, you must have one of three cables; Parallel Cable III, Parallel Cable IV, or a MultiLINX cable.

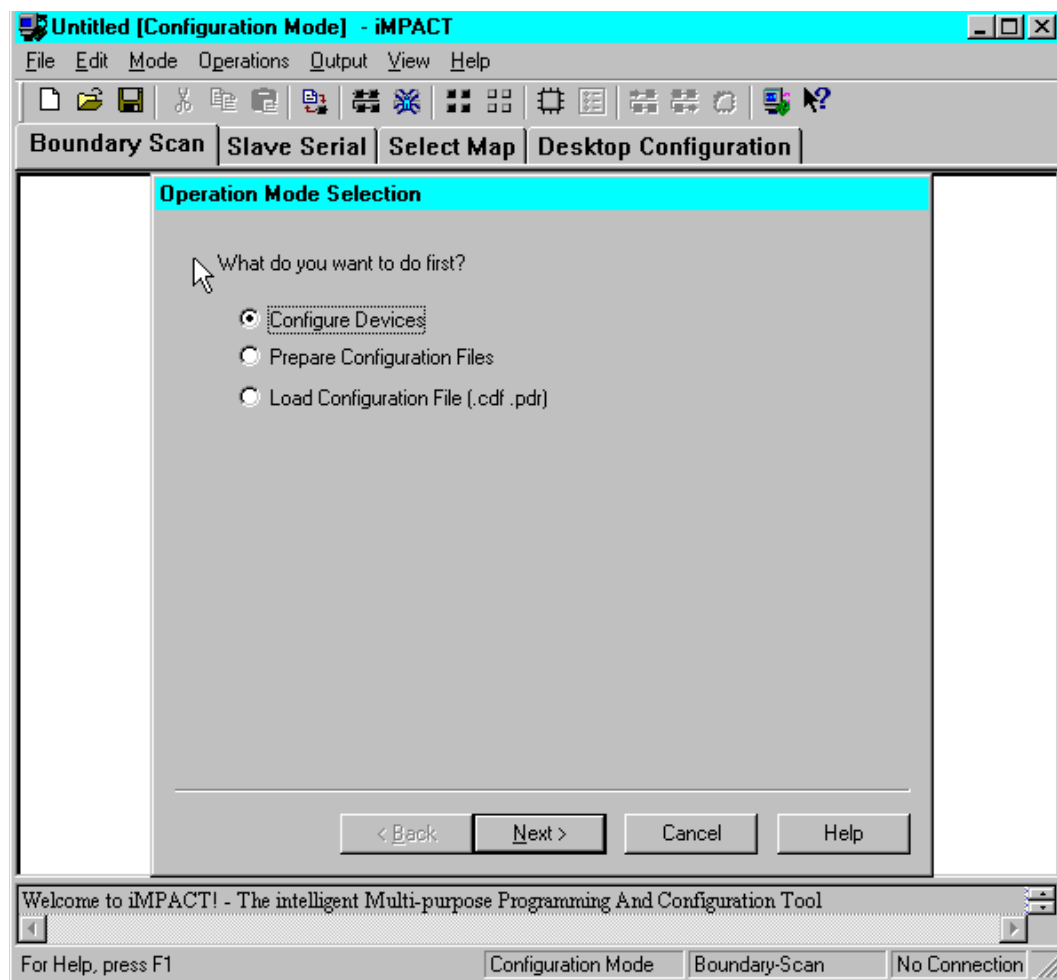


Figure 4-1 Initial Window When Opening iMPACT stand-alone

In the initial window of iMPACT, the wizard prompts you to select an operation mode. If you want to configure devices, select the Configure Devices radio button then select Next. The Configure Devices wizard appears.

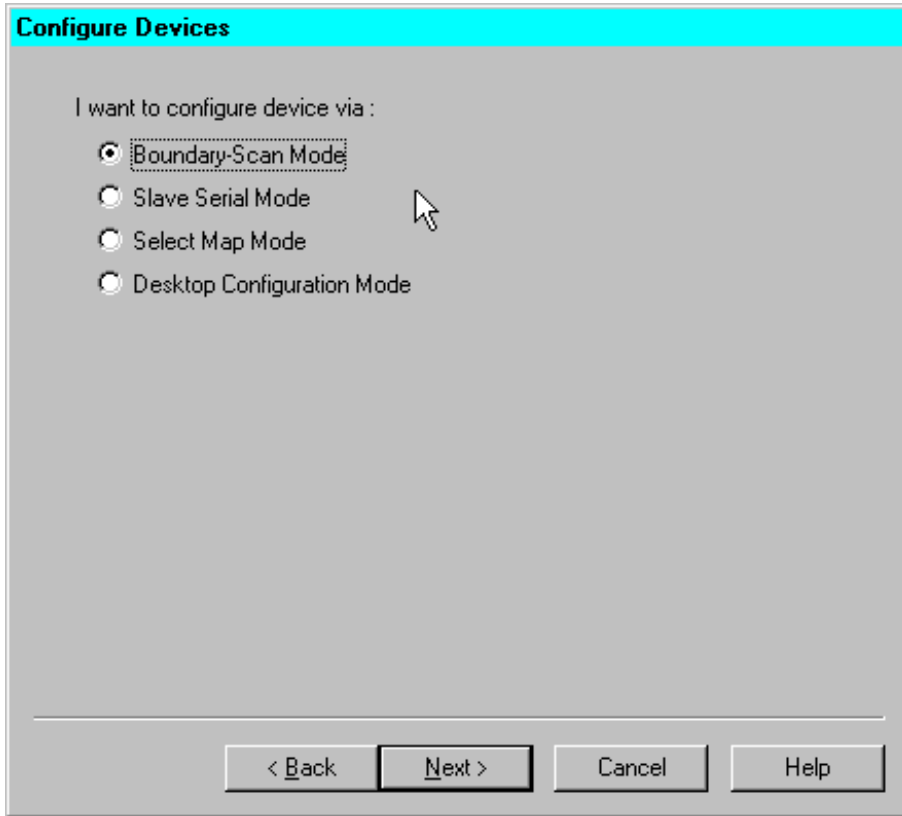


Figure 4-2 Configure Devices Wizard

Connecting to a Cable

A connection to a cable must be established before operations can be performed on a device. If a connection has not been established, attempting to perform any cable operation, such as Program, will cause iMPACT to attempt to auto detect the cable. An alternate method would be to right-click on a blank portion of the iMPACT window and select either **Cable Auto Connect** or **Cable Setup**.

Cable Auto Connect will force the software to search every port for a connection. Cable Setup allows the user to select the cable and the port to which the cable is connected.

```

Connecting to cable (COM1 Port).
Cable connection failed.
Overriding Xilinx file <q:/rtf/data/algo.alg> with local file<t:/epldsw5/E/rtf/data/algo.alg>
Overriding Xilinx file <q:/rtf/data/mlnxjtag.lcf> with local file<t:/epldsw5/E/rtf/data/mlnxjtag.lcf>
Connecting to cable (COM2 Port).
Cable connection failed.
Overriding Xilinx file <q:/rtf/data/algo.alg> with local file<t:/epldsw5/E/rtf/data/algo.alg>
Overriding Xilinx file <q:/rtf/data/mlnxjtag.lcf> with local file<t:/epldsw5/E/rtf/data/mlnxjtag.lcf>
Connecting to cable (COM3 Port).
Cable connection failed.
Overriding Xilinx file <q:/rtf/data/algo.alg> with local file<t:/epldsw5/E/rtf/data/algo.alg>
Overriding Xilinx file <q:/rtf/data/mlnxjtag.lcf> with local file<t:/epldsw5/E/rtf/data/mlnxjtag.lcf>
Connecting to cable (COM4 Port).
Cable connection failed.
CB_PROGRESS_END - End Operation.
Elapsed time = 23 sec.

```

Figure 4-3 Failed Attempt to Establish Cable Connection

If a cable is connected to the machine and the cable autodetection fails, use the following steps to debug:

1. Verify that the VCC and GND pins of the cable are connected to VCC and GND on the board and make sure that the power supply for the board is turned on.
2. If a connection was previously established with another cable or if the configuration mode has changed, terminate the previous connection by selecting **Output** → **Cable Disconnect** from the menu at the top of the iMPACT window.
3. Try performing a cable reset by selecting **Output** → **Cable Reset**.
4. Check the connection to the port on the computer and try another port if possible.
5. Shut down the software and reopen it.
6. Verify that the drivers for the cables were installed. Open the fileset.txt file that is located in the directory where the software was installed. The following lines should be in this file:

```
<Date of install> <Time> <Year>:: summary=MultiLINX Cable Driver
```

<Date of install> <Time> <Year>:: summary=Parallel Cable III Driver

If these lines are not present, the drivers were not installed. They can be installed by reinstalling the software or by installing the Webpack Programmer.

Boundary-Scan Configuration Mode

Boundary Scan Configuration mode allows you to perform Boundary Scan Operations on any chain of JTAG compliant devices. The chain can consist of both Xilinx and non-Xilinx devices, but only the BYPASS and HIGHZ operations will be available for a non-Xilinx device.

To perform operations, the cable must be connected and the JTAG pins, TDI, TCK, TMS, and TDO need to be connected from the cable to the board. The boundary scan chain that is created in the software must match the chain on the board. If the chain consists of eight devices, but only one of them is going to be configured, all eight devices must be added to the chain in the iMPACT window.

Automatically Creating the Chain

To automatically create the chain, right-click on an empty space in the iMPACT window and select Initialize Chain (see Figure 4-4). iMPACT will pass data through the devices and automatically identify the size and composition of the Boundary Scan chain.

Any supported Xilinx device will be recognized and labeled and any other device will be labeled as unknown. iMPACT will then highlight each device in the chain and prompt you for a configuration file.

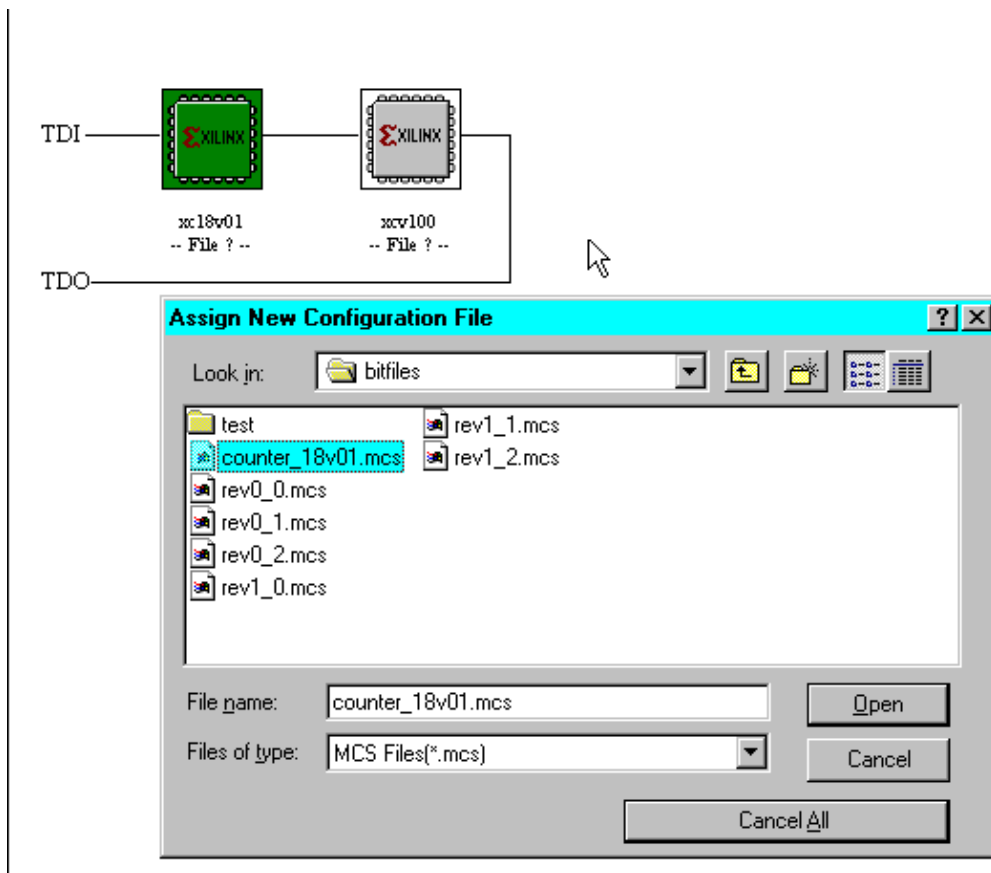


Figure 4-4 Performing Initialize Chain

Manually Creating the Chain

The chain can be manually created or modified as well. To perform this operation, right-click on an empty space in the iMPACT window and select **Add Xilinx Device** or **Add Non-Xilinx device** (see Figure 4-5). This allows you to add devices one at a time. The device will be added where the large cursor is positioned. To add a device between existing devices, click on the line between them and add the new device.

Manually adding devices is useful when creating a chain that will be used to generate an SVF or STAPL file. However, the Initialize Chain

command should be used whenever possible. Initializing the chain verifies that the chain is set up correctly and that iMPACT can correctly identify all of the devices.

Assigning Configuration Files

There are several types of configuration files. A Bitstream file (*.bit) is used to configure an FPGA. A JEDEC file (*.jed) is used to configure a CPLD. A PROM file (*.mcs, .exo, or .tek) is used to configure a PROM and to program FPGAs in Slave Serial mode. A Raw Bit File (*.rbt) is an ASCII version of the Bit file. The only difference is that the header information in a Bit File is removed from the Raw Bit File.

After initializing a chain or adding a device, iMPACT prompts you for a configuration file (see Figure 4-4). This is the file that will be used to program the device. If a configuration file is not available, a Boundary Scan Description File (BSDL or BSD) file can be applied instead. The BSDL file provides iMPACT with necessary Boundary Scan information that will allow a subset of the Boundary Scan operations to be available for that device.

To select a BSDL file, change the file type to *.BSD in the Assign New Configuration File window and browse to the BSDL file (see Figure 4-5). BSDL files for Xilinx devices are located in the \$Xilinx\<device>\data directories. For example, if the software is installed in c:\xilinx, the BSDL file for a Virtex device is in c:\xilinx\virtex\data.

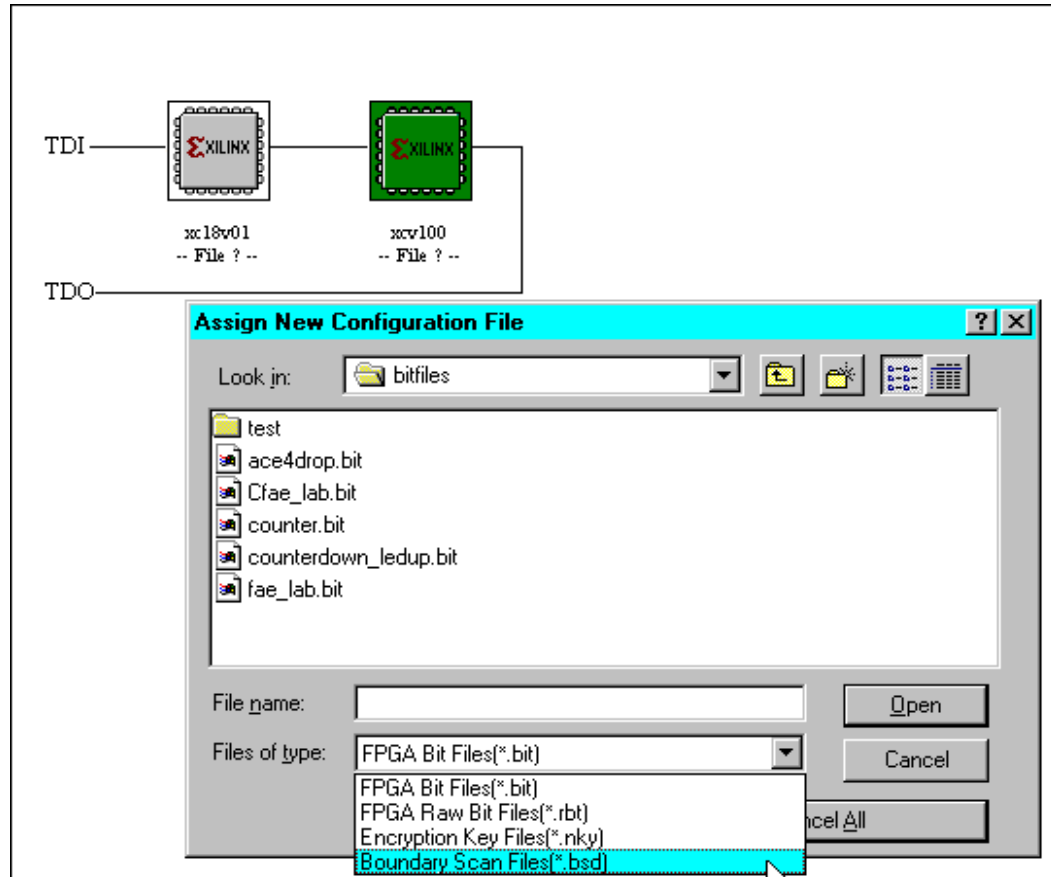


Figure 4-5 Selecting a BSDL File

For Xilinx devices, you do not have to associate a BSDL, JEDEC, or bit file with devices that you only wish to place in bypass mode. Press Cancel in the Assign New Configuration File dialog box. When any chain operation is attempted, iMPACT will automatically search the Xilinx directories for the correct BSDL file and place the device in bypass mode.

For non-Xilinx devices, a BSDL or BIT file must be applied. The BSDL file can typically be obtained from the vendor of the device. If a BSDL file cannot be obtained, iMPACT can create a generic BSDL file. When

a non-Xilinx device is added, iMPACT will ask you if a BSDL or BIT file exists for the device (see Figure 4-6).

If yes, you can browse to the file. If no, iMPACT will ask you for the device name and the Instruction Register Length (see Figure 4-7). This minimal amount of information enables iMPACT to create a generic BSDL file that will allow the device to be put in BYPASS or HIGHZ. Check with the vendor of the device to obtain the Instruction Register Length.

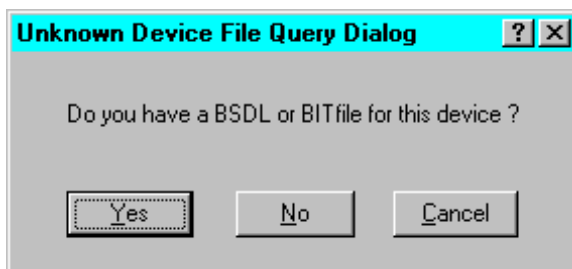


Figure 4-6 Unknown Device Query

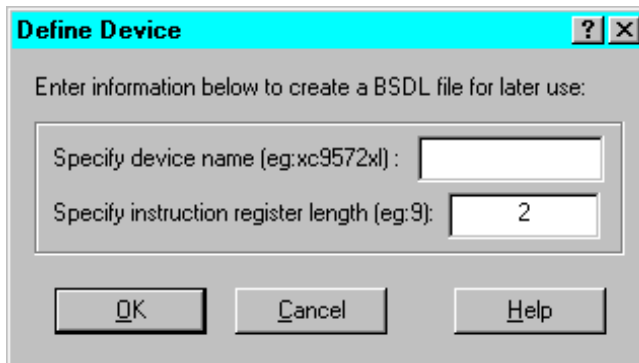


Figure 4-7 Defining an Unknown Device

Saving the Chain Description

Once the chain has been fully described, it can be saved for later use. This prevents you from having to redefine the chain each time the iMPACT software is started. To do this, select **File** → **Save** or **Save As**. This will create a Chain Description File (*.CDF).

To restore the chain when reopening iMPACT, select **File** → **Open** and browse to the CDF file. The CDF file can also be selected in the Process Properties window in ISE. This will restore the chain when opening iMPACT from the Project Navigator.

Edit Preferences

To edit the preferences for the Boundary Scan Configuration, select **Edit** → **Preferences**. This will open the window shown in Figure 4-8. Click on help for a description of the Preferences.

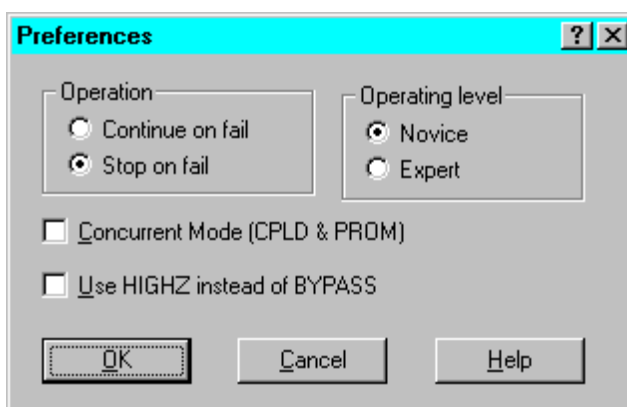


Figure 4-8 Edit Preferences

Available Boundary-Scan Operations

The available Boundary Scan Operations will vary based on the device and the configuration file that was applied to the device. To see a list of the available options, right-click on any device in the chain. This will bring up a window with all of the available options. Figure 4-9 shows the available options for a 9500XL device that has a JEDEC file applied to it.

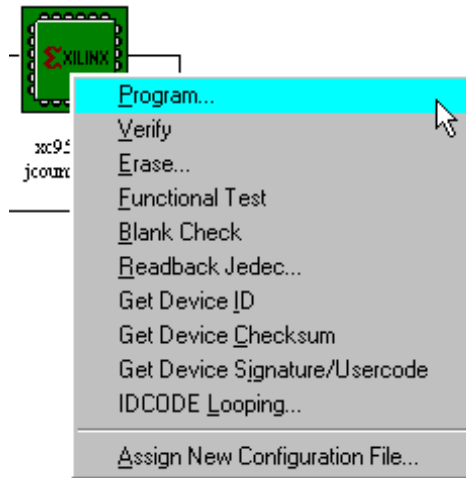


Figure 4-9 Available Boundary Scan Operations for an XC9572XL device

When a Virtex device is selected, a different set of options will be available (see Figure 4-10).

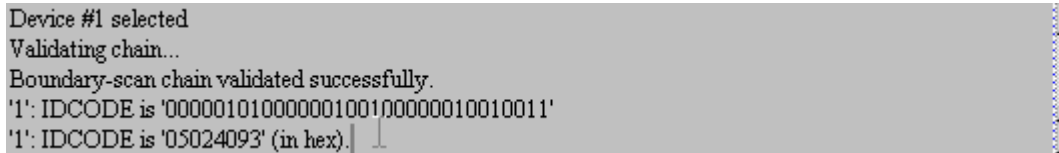


Figure 4-10 Available Boundary Scan Operations for a Virtex device

Performing Boundary Scan Operations

Boundary Scan operations are performed on one device at a time. When you select a device and perform an operation on that device, all other devices in the chain will automatically be placed in BYPASS (or HIGHZ - see Figure 4-8).

To perform an operation, right click on a device and then left click on one of the selections. For instance, when the Virtex Device is right-clicked, the window in Figure 4-10 appears. Then left click on **Get Device ID** and the software will get the IDCODE for this Virtex Device. The result will be displayed in the Log Window (see Figure 4-11).

A screenshot of a log window with a gray background and a blue border. The text inside the window is as follows:

```
Device #1 selected
Validating chain...
Boundary-scan chain validated successfully.
'1': IDCODE is '00000101000000100100000010010011'
'1': IDCODE is '05024093' (in hex).
```

Figure 4-11 Log Window showing result of Get Device ID

For another example, if the user right clicks on the XC9572XL and then left clicks on Program (see Figure 4-9), the Program Option Window will appear (see Figure 4-12). You then select the desired options and click OK to begin programming. The Program options will vary based on the device.

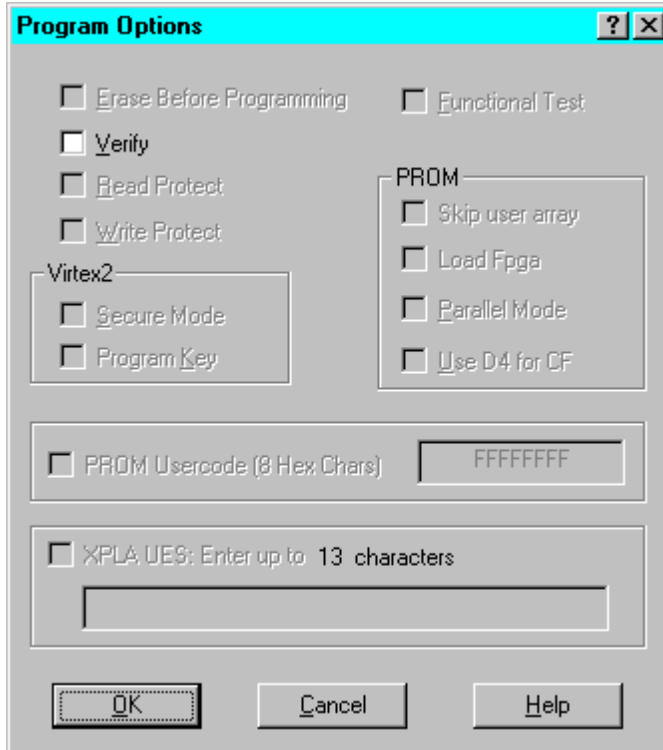


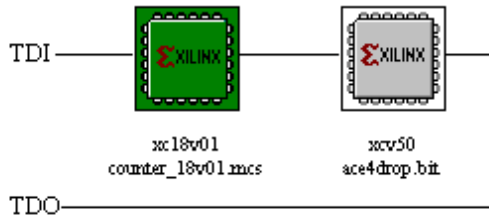
Figure 4-12 Program Options dialog box

After clicking on OK, the Program operation will begin and an operation status window will appear (see Figure 4-13). At the same time, the log window will report all of the operations being performed.



Figure 4-13 Operation Status

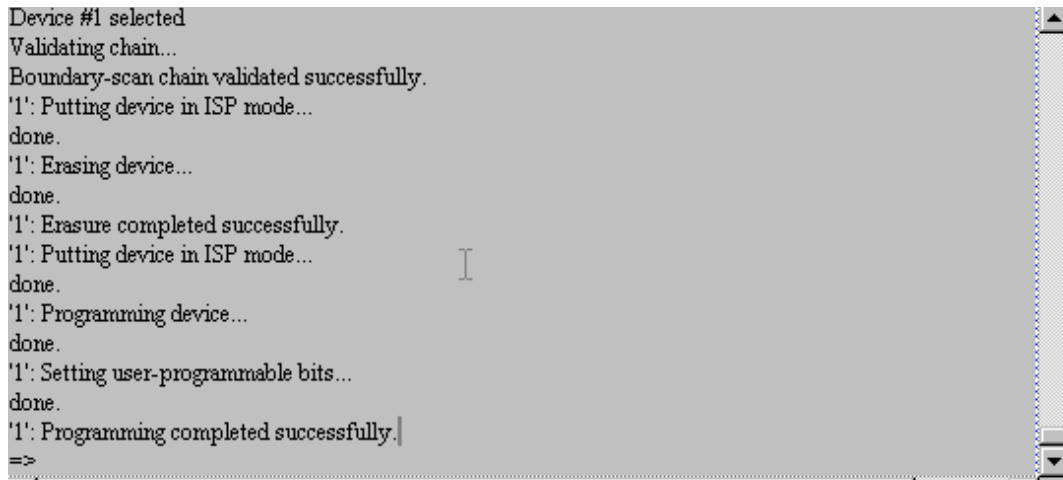
When the Program operation completes, a large blue message will appear showing that Programming Succeeded (See Figure 4-14). This only appears for several seconds and then disappears.



Programming Succeeded

Figure 4-14 Programming Succeeded

The log window will also show that the programming completed successfully and will show all of the operations that were performed (see Figure 4-15).

A screenshot of the iMPACT log window. The window has a gray background and a black border. The log text is as follows:

```
Device #1 selected
Validating chain...
Boundary-scan chain validated successfully.
'1': Putting device in ISP mode...
done.
'1': Erasing device...
done.
'1': Erasure completed successfully.
'1': Putting device in ISP mode...
done.
'1': Programming device...
done.
'1': Setting user-programmable bits...
done.
'1': Programming completed successfully.
=>
```

The text is left-aligned. There is a vertical scrollbar on the right side of the window, and a horizontal scrollbar at the bottom. The cursor is at the end of the last line of text.

Figure 4-15 Log window showing successful configuration of the CPLD

Operations can continue to be performed in this manner. Select a device and then select the operation. Wait for the previous operation to complete and then perform the next operation.

Slave Serial Configuration Mode

Slave Serial Configuration mode allows you to program a single Xilinx device or a serial chain of Xilinx devices.

To use the Slave Serial Configuration Mode, click on the Slave Serial Tab at the top of the iMPACT window and establish a cable connection.

Adding a Device

To add a device, right click on the iMPACT window and select Add Xilinx Device (see Figure 4-16).

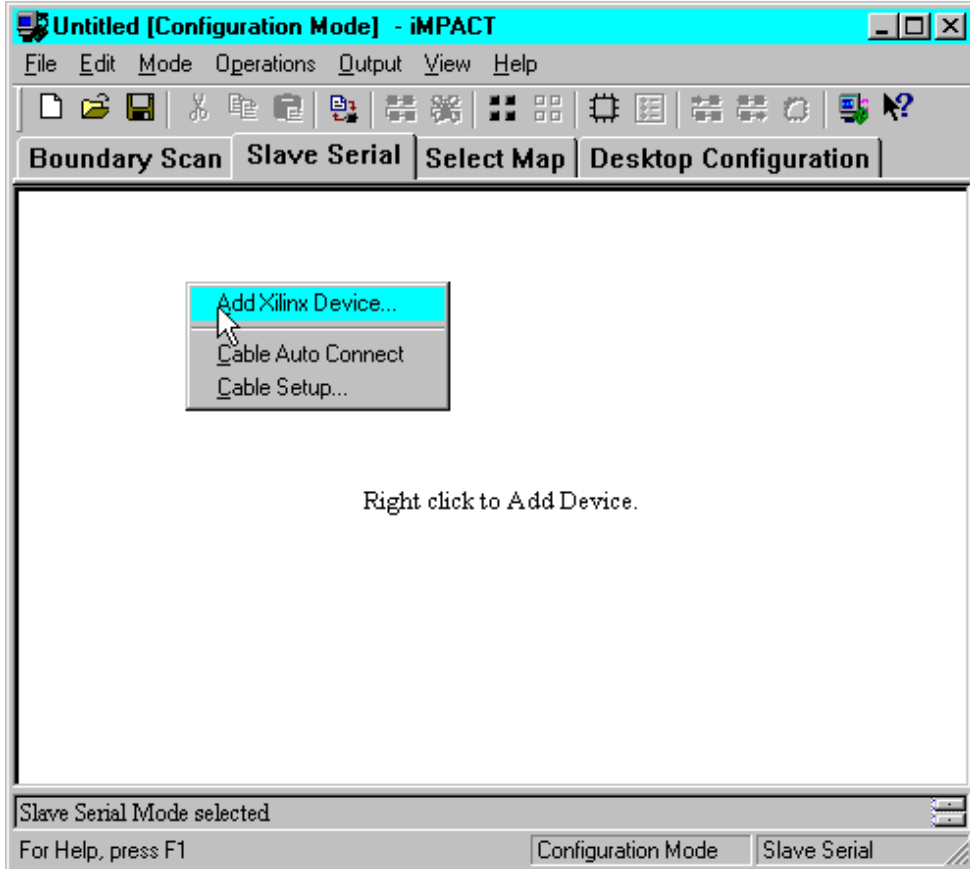


Figure 4-16 Adding a Xilinx Device in Slave Serial Mode

After clicking on **Add Xilinx Device**, a window will appear that allows you to browse to the desired file (see Figure 4-17).

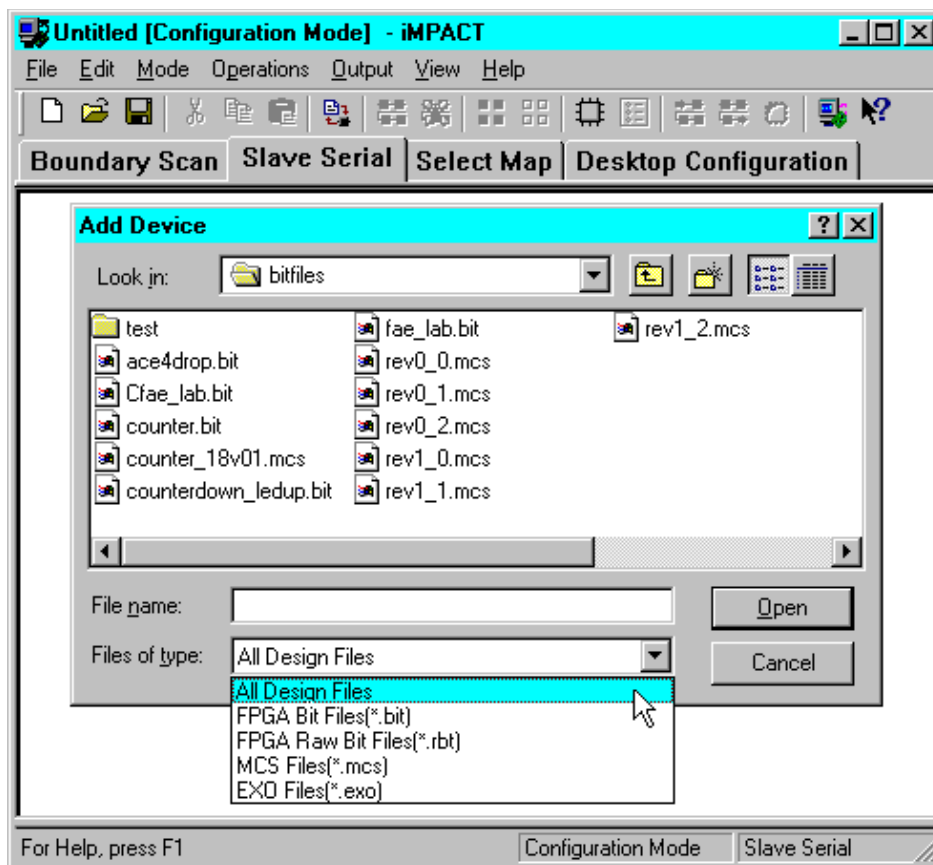


Figure 4-17 Add Device File Types for Slave Serial

Notice in Figure 4-17 that there are a number of different file types to select from. An explanation of each type is below:

FPGA Bit File (*.bit). Standard bit file created by Bitgen. A Bit file is used to program a single FPGA.

FPGA Raw Bit Files (*.rbt). A Raw Bit File is an ASCII version of the Bit file. The only difference is that the header information in a Bit File is removed from the Raw Bit File. This is also created by Bitgen and is used to program a single FPGA.

MCS and EXO Files (*.mcs, *.exo). These are PROM files. To program a serial chain of Xilinx devices, a PROM file is used to concatenate all

of the Bit files. This device represents a single device when a BIT or RBT file is used, and could represent a chain of devices when a PROM file is used. The PROM files are created in the PROM Formatter tab in the File Generation mode of iMPACT.

Only one file can be loaded for Slave Serial Configuration Mode so the PROM file must be used for programming a serial chain of devices. Once the desired file is selected, a window similar to Figure 4-18 will appear.

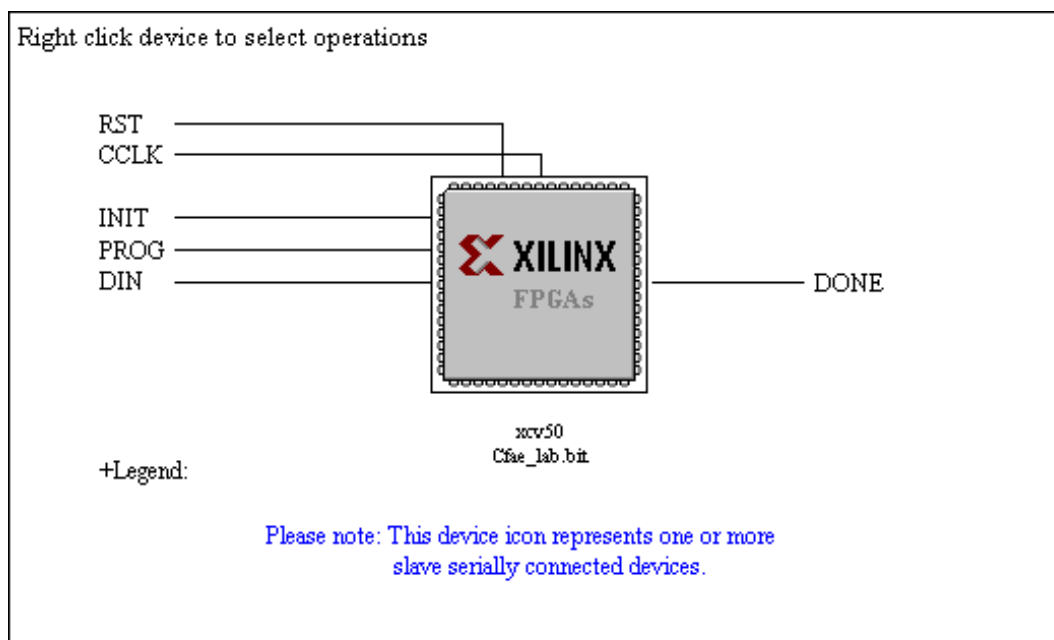
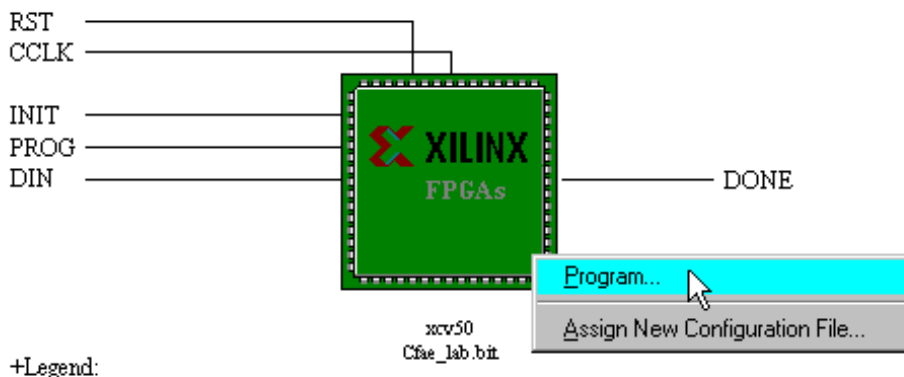


Figure 4-18 Device Loaded with a Single Bit File

Even if a chain of devices is being programmed, only the single device shown in Figure 4-18 will appear. This device represents a single device, when a BIT or RBT file is used and represents a chain of devices when a PROM file is used.

Programming the Device

To program a device, right click on the device and then select **Program** (see Figure 4-19).



Please note: This device icon represents one or more slave serially connected devices.

Figure 4-19 Selecting the Program Option

When Program is selected, iMPACT will begin programming the device or chain of devices. When it completes, a message will show that programming succeeded.

Troubleshooting Slave Serial Configuration

If configuration fails, the window in Figure 4-21 will appear. Notice that the error message appears in the Log Window.

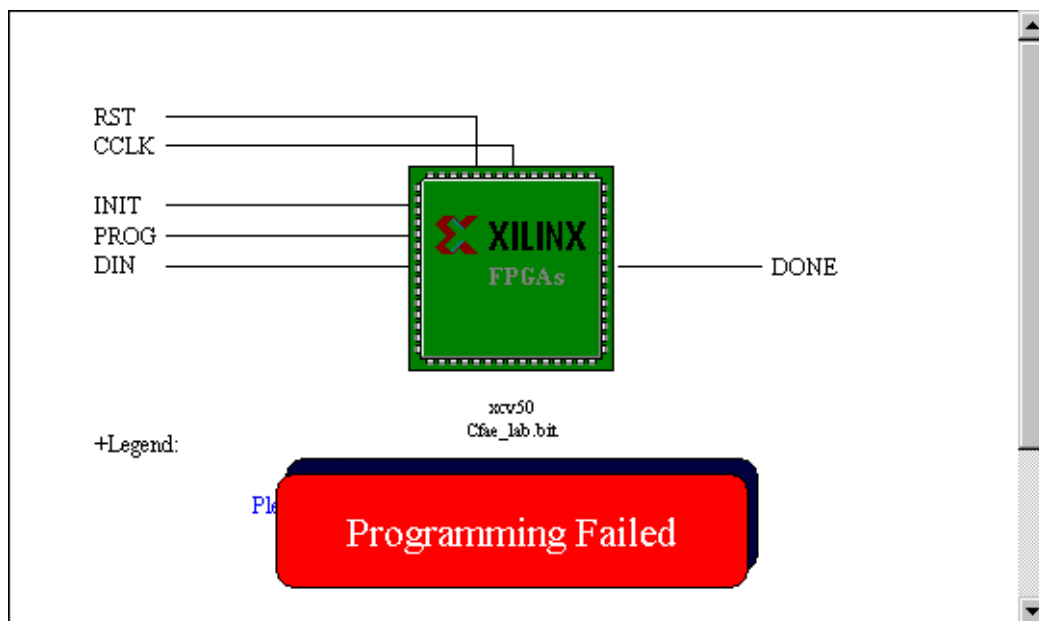


Figure 4-20 Programming Failed

There are two main error messages that a user may encounter. The first is:

1. DONE pin did not go low. Please check cable connection.
Programming terminated due to error.

The first step in programming through slave serial is that PROG is pulsed low, which erases the device and forces DONE to go low. If the above error message appears, it is likely that the PROG or DONE pin of the cable is not properly connected to the device.

2. The second common error message is:

Done pin did not go high. Programming terminated due to error.

The above error message can occur for many reasons. Below are some of the common causes:

- The Mode pins on the device are not set to Slave Serial
- DIN, INIT, or CCLK are not connected.
- Noise is corrupting CCLK or DIN signals.

- The hardware is not set up properly.
- The wrong configuration file was used or the PROM file does not have the BIT files concatenated in the correct order.

Select MAP Configuration Mode

With iMPACT, Select MAP Configuration mode allows you to program up to three Xilinx devices. The devices are programmed one at a time and are selected by the assertion of the correct CS pin. To use the Select MAP Configuration Mode, click on the Select MAP tab at the top of the iMPACT window and establish a cable connection. Only the Multilink cable can be used for Select MAP Configuration.

Adding a Device

To add a device, right click on the iMPACT window and select **Add Xilinx Device** (see Figure 4-22).

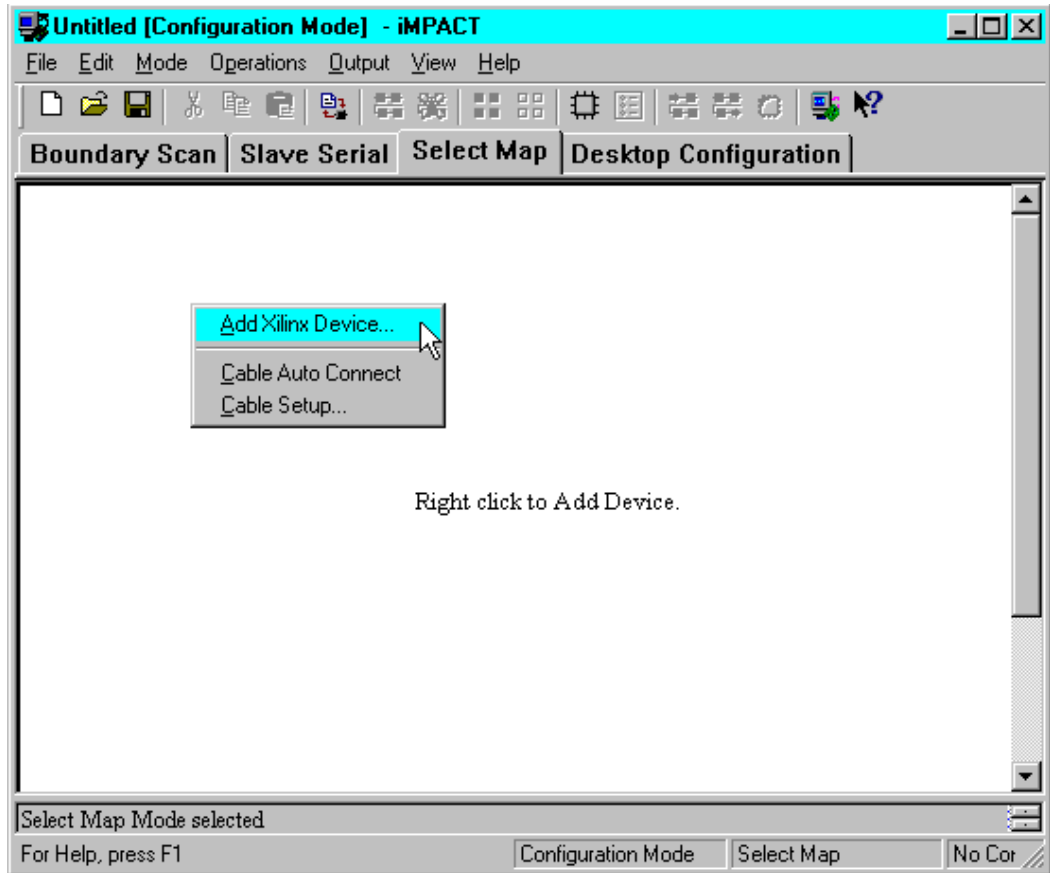


Figure 4-21 Adding a Device for Select MAP Configuration

After clicking on **Add Xilinx Device**, a window will appear that allows you to browse to the configuration (see Figure 4-23).

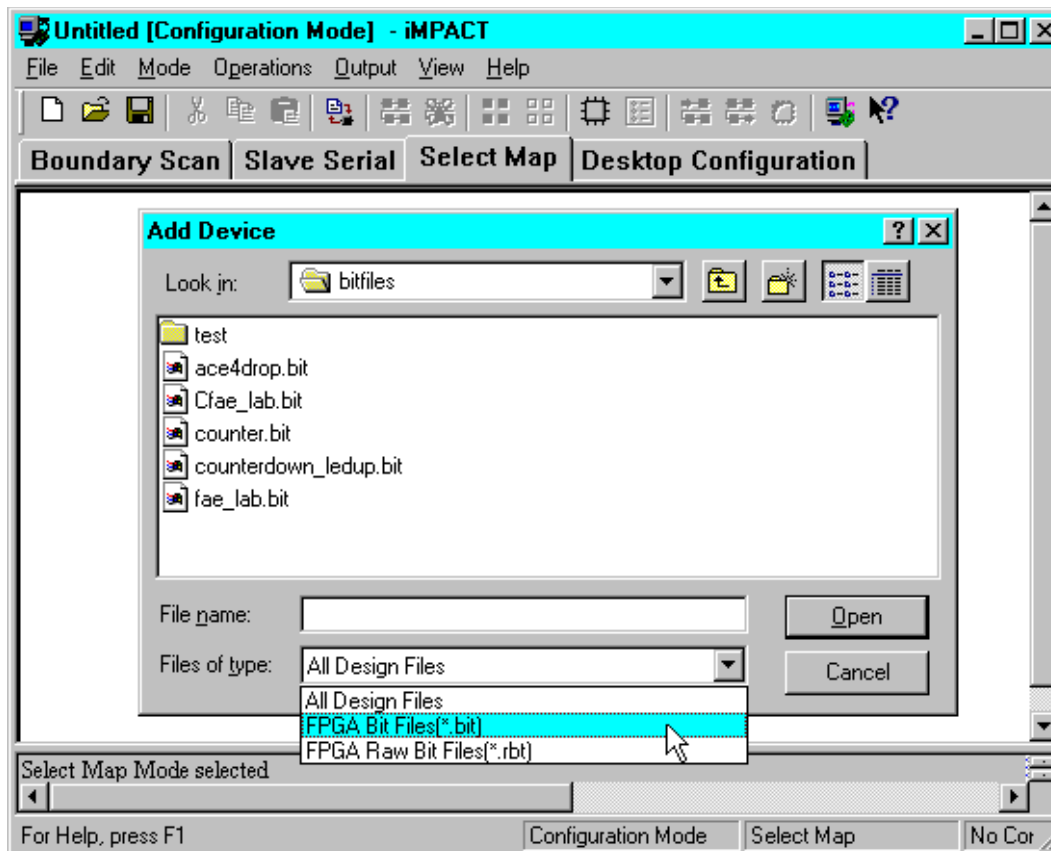


Figure 4-22 Configuration File Types for Select MAP Mode

Notice in Figure 4-23 that only two file types can be used, FPGA Bit Files and FPGA Raw Bit Files. For a description of these files, see the Add Device Section for Slave Serial Configuration.

Once a BIT or RBT file is selected the device will appear in the iMPACT window. Up to three devices can be added. Figure 4-24 shows an example where two devices have been added. Notice that each one has a different Chip Select (CS) pin. These correspond to the CS pin on the Multilink Cable. Make sure that the correct CS pin is connected to the correct device. The CS pins can be swapped by dragging and dropping the pins in the window.

Right click device to select operations

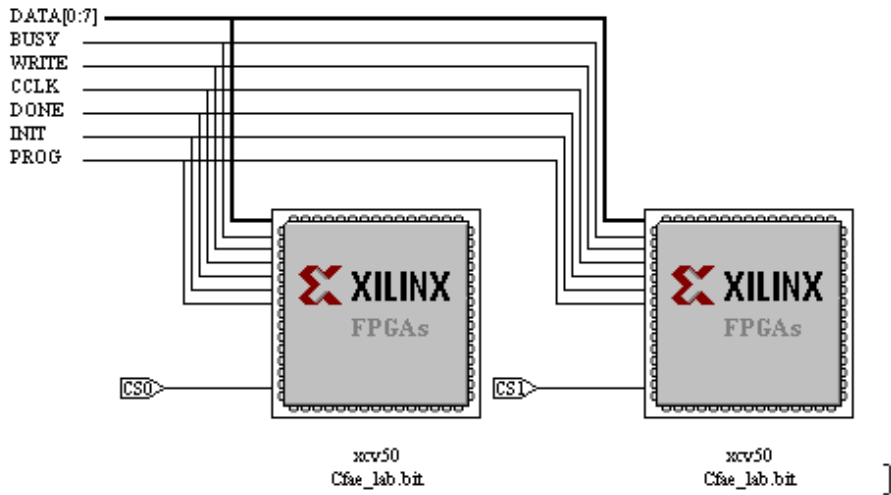


Figure 4-23 Two Devices Added for Select MAP Configuration

Programming and Verifying a Device

To program or verify a device, right click on the device and then select **Program** or **Verify** (see Figure 4-25). The Multilinx cable will assert the correct CS pin and then perform that operation on that device.

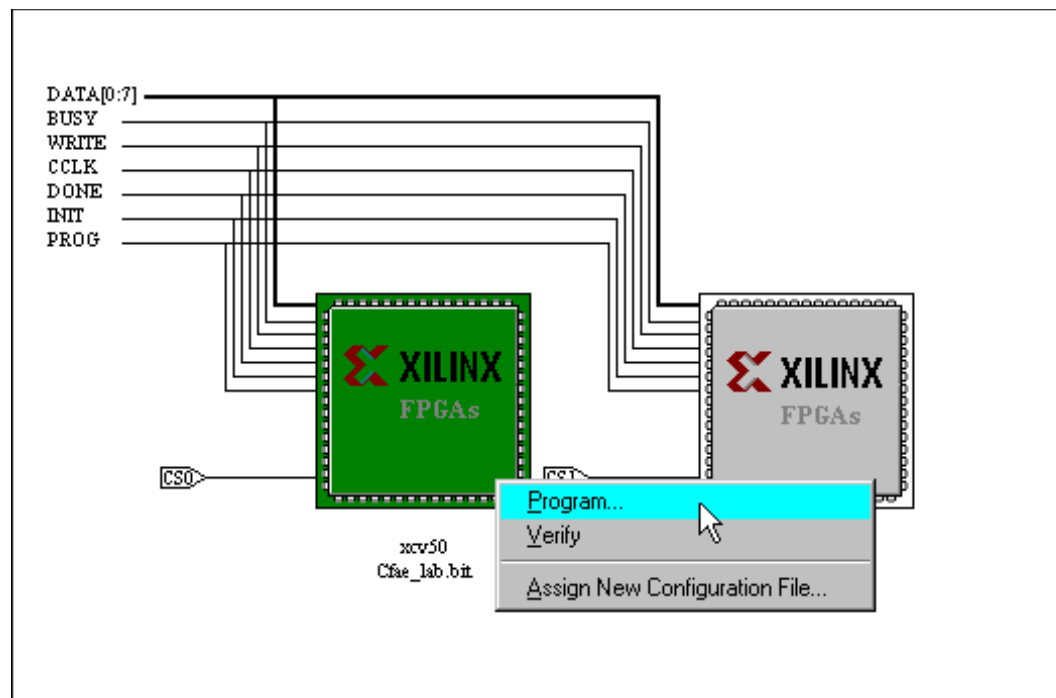


Figure 4-24 Selecting Program or Verify in Select MAP Mode

When **Program** or **Verify** is selected, iMPACT will perform the operation and a status message will indicate that the operation completed successfully.

Troubleshooting Select MAP Programming and Verify

If Programming or Verify fails, a red status message will indicate the operation failed. Figure 4-27 shows a failed Program Operation.

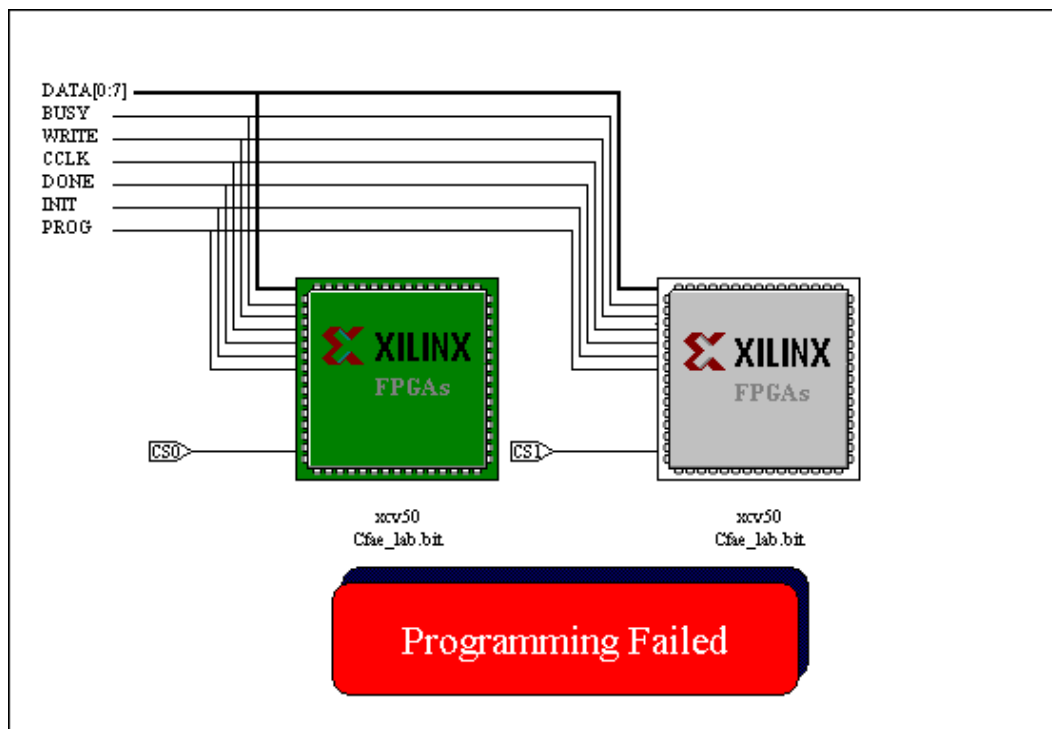


Figure 4-25 Select MAP Programming Failed

When Programming fails, the error message will likely read:

Done pin did not go high.

Programming terminated due to error.

Programming failed.

The above error message can occur for many reasons. Below are some of the common causes:

- The Mode pins on the device are not set to Select Map Mode.
- One or more of the Select Map signals are not connected properly.
- The wrong CS pin is connected to the device.
- Noise is corrupting CCLK or the DATA lines.
- The hardware is not set up properly.

- The wrong configuration file was applied to the device.

When Verify fails, the error message will likely read:

ERROR:Bitstream:98 - There are ## differences.

ERROR:iMPACT:395 - The number of difference is ##

Verification failed.

The above error message can be caused by any of the conditions listed above for a failed Program operation. In addition, the problem might be caused because the BIT File was generated incorrectly. If security is set to Level1 or Level2 or if Persist is set to No, verify will fail. Check the Bitgen options and make sure that Security is set to None and Persist is set to YES.

Desktop Programmer Mode

The MultiPRO Desktop Programmer mode is used to configure single, non-volatile, socket-based devices using the Xilinx MultiPRO Desktop Configuration Cable. The MultiPRO cable is a multi-function tool capable of ISP configuration using JTAG, Slave-Serial, or SelectMAP interfaces. The MultiPRO supports the CoolRunner II CPLD family, the XC 18V00 Flash PROM family, and all System ACE-MPM modules.

Automatically Identifying the Device

To automatically identify the device, select **File** → **Identify Device**. iMPACT will pass data through the device and automatically identify the type of device connected. Any supported Xilinx device will be recognized and labeled. iMPACT will then highlight the device and prompt you for a configuration file.

Manually Identifying the Device

The chain can be manually created or modified as well. To perform this operation, right-click on an empty space in the iMPACT window and select **Add Xilinx Device**. The device will be added where the large cursor is positioned.

Assigning a Configuration File

After identifying the device, iMPACT prompts you for a configuration file. This is the file that will be used to program the device.

If you want to assign a new file to the device, the device must first be selected. You can then select **Edit**, or right-click and select **Assign New Configuration File**.

Setting Options

Note In contrast to the other configuration modes in iMPACT, Desktop Programmer mode requires that you set options before performing device operations. This enables you to set options once, then operate on several devices using those settings. If you do not set options first, default settings will be applied.

To set the program options, select the device, then in the **Options** menu, select **Program Options**. The Program Options dialog box appears (Figure 4-26).

The same steps also apply for **Erase** and **Readback** operations.

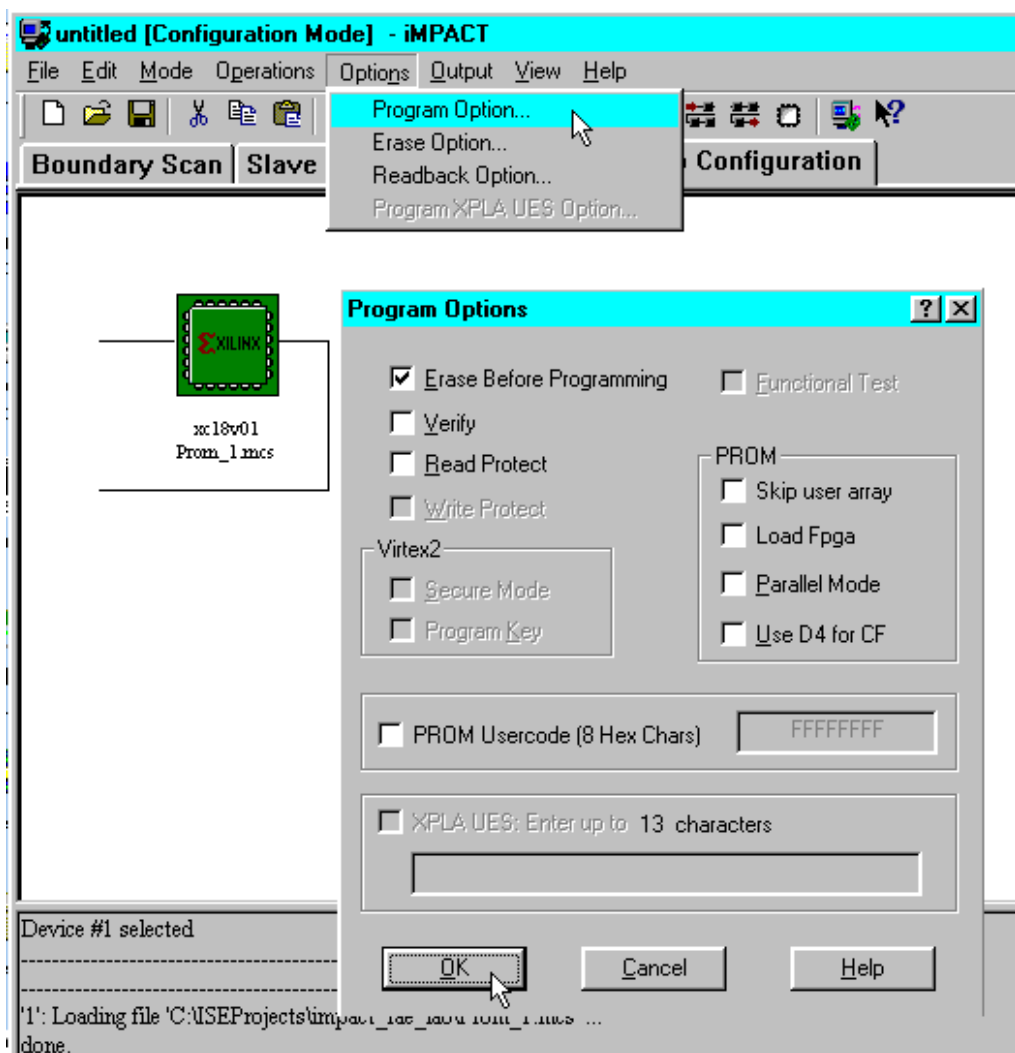


Figure 4-26 Program Options Dialog Box

Performing Device Operations

For the programming of devices in Desktop Programming mode, there are three commonly used buttons located on the iMPACT toolbar. From left to right, they are; Program, Verify, and Erase (See Figure 4-27).



Figure 4-27 Desktop Programmer Toolbar Buttons

To program a device, the device must first be selected. Once selected, you can then click the **Program** toolbar button. If you right-click, you will receive more operation choices.

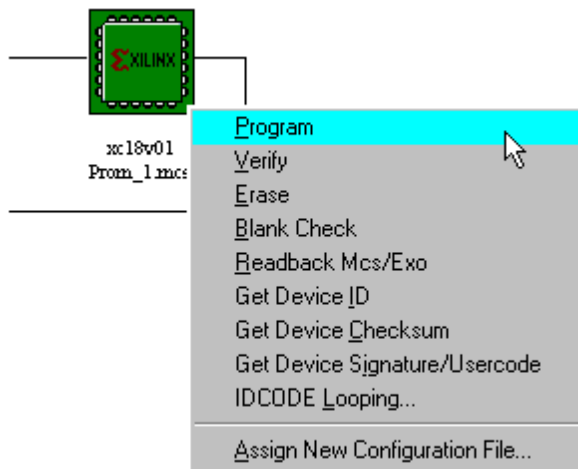


Figure 4-28 Right-Click Programming Options

Using iMPACT to Generate Files

IMPACT supports the generation of secondary configuration files based on bitstreams or JEDEC files in five formats: System ACE CF and MPM, PROM Files (TEK, EXO, and MCS), HEX files, SVF and STAPL files. System ACE and PROM files are output files which can be used to program one or more devices. SVF and STAPL files contain both programming instructions and configuration data. They are used by ATE machines and embedded controllers to perform Boundary Scan operations.

This chapter contains the following sections.

- [“General File Mode Instructions”](#)
- [“Creating System ACE Programming Files”](#)
- [“Creating PROM Formatter Programming Files”](#)
- [“Creating an SVF or STAPL File”](#)

General File Mode Instructions

When iMPACT is first launched, a wizard appears that enables you to start the file generation process, as shown in Figure 5-1.

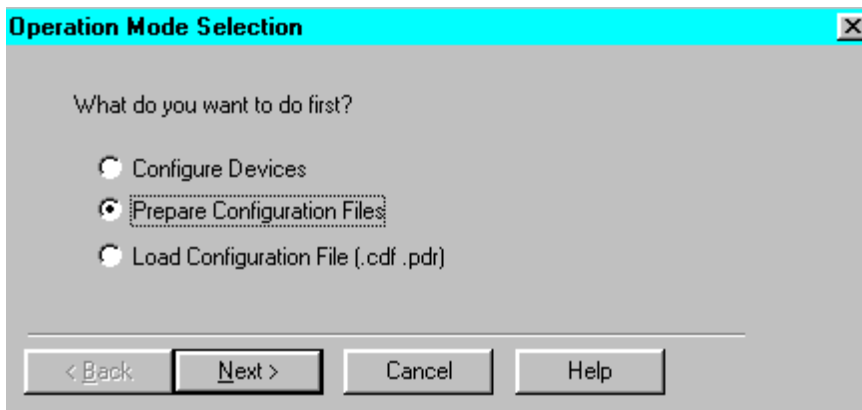


Figure 5-1 Operation Mode Selection Wizard

To generate a System ACE or PROM file, you must use the wizard to set required properties. To access the wizard from anywhere inside iMPACT, select **Edit** → **Launch Wizard** as shown in Figure 5-2.

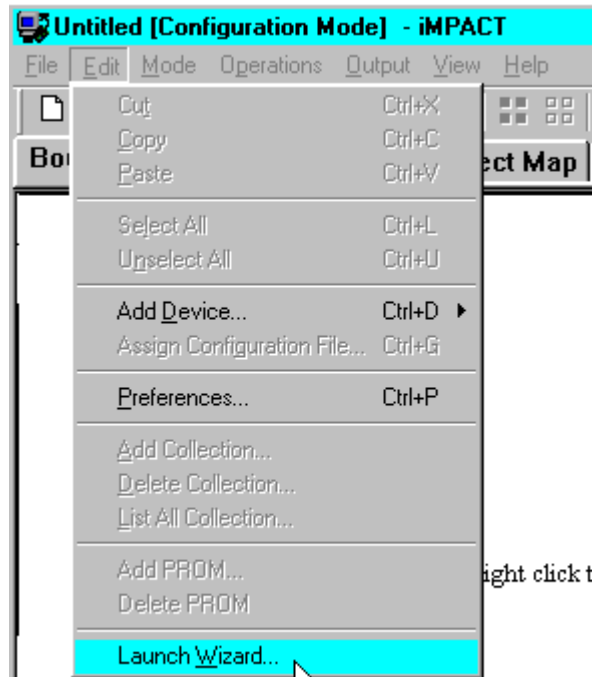


Figure 5-2 Launching the Wizard from the Edit Menu

A dialog will appear telling you that launching the wizard will "clean up" (erase) all current contents from all modes. If you wish to save your current work to a .cdf file, click No. If you wish to continue, click Yes.

Creating System ACE Programming Files

There are two types of System ACE products, System ACE CF and System ACE MPM. Although similar in some ways, each product type uses a different configuration methodology and therefore each requires a different type of file. System ACE CF uses Boundary-Scan technology to configure devices connected to the System ACE CF controller, while System ACE MPM uses either Slave Serial or Select MAP configuration modes.

The following sections will explain the settings on the wizard screens for the individual System ACE types. After setting the properties, you will be prompted to add devices to the configuration chain or

chains. As the final step in the wizard, you will be asked if you wish to generate the System ACE file. If you click "No", you can always generate the file later by using the Operations Menu.

System ACE CF Settings

The following are System ACE CF Wizard Selections.

Size (128, 256 Generic)

This enables you to specify the size of the compact flash you will be using in conjunction with the System ACE Controller. This will enable iMPACT to automatically confirm that the System ACE files will fit in your selected Compact Flash device. If your device is larger than 256 Megabits, or if you wish to disable this check, select Generic.

Reserve Space

This enables you to set aside space in the Compact Flash for other information, such as microprocessor code, general purpose ROM, etc. This value will be subtracted from the CF size, and the calculation for System ACE files will be based upon this reduced size.

System ACE CF Collection Name

All of the configuration files related to the different revisions in your System ACE design are referred to as a collection. This selection prompts you for the first collection name. You will be able to create other collections later in the flow. When creating the System ACE file, you will be prompted for which collection to make active. The active collection is actually used to configure the devices on your board.

Location

This is the directory path where you want your collection(s) to be saved on your local or network disk.

Configuration Address

These are also referred to as "revisions" and are accessed at run-time by using the physical address pins of the CF controller. You can have up to eight of these "revisions" per collection. Check the box next to the configuration address that you wish to use.

Design Name

This is the name of the "revision." Default is "rev<n>" where n corresponds to the configuration address number.

System ACE MPM Settings

Size (16,32,64,)

Enables you to specify the size of the MPM device you will use. This will enable iMPACT to automatically confirm that the System ACE files will fit in your selected MPM device.

System ACE MPM Name

This is the name of your System ACE MPM/SC formatted file.

Location

This is the directory path where you want your MPM file to be saved on your local or network disk.

Target in: Slave Serial Mode or SelectMAP Mode

Enables you to specify how devices are connected on your board. You have the choice of either connecting the FPGAs via SelectMAP parallel bus, or you can have up to 8 separate Slave Serial daisy chains. You can only select one mode per single MPM/SC device, as each configuration method is mutually exclusive of the other.

Slave Serial Mode > Number Of Chains

Clicking on a checkbox next to a data pin enables System ACE MPM/SC to download to a Slave Serial chain, connected to that data pin. You may have up to 8 independent daisy chains. You do not have to use sequential data pins. For example, you can have a chain hooked up to ConfigData0, and then another hooked up to ConfigData5, with none of the others used. Simply check the box next to the pin you are using.

Select MAP Mode > Specify CS Pin to be used in this design

Clicking on a checkbox next to a Chip Select pin enables that pin as a chip select to a device in Select MAP mode. You can have up to four FPGA devices connected to the System ACE MPM/SC device. You do not have to use sequential Chip Select pins. You can have one device hooked to CS0, and another connected to CS3. Simply check the box next to the pin you are using.

Configuration Address

This selection applies to both Slave Serial and Select MAP MPM/SC configurations. These addresses are also referred to as "revisions" and are accessed at run-time by using the physical address pins of the MPM/SC device. You can have up to eight of these "revisions" per collection. Check the box next to the configuration address that you wish to use.

File Generation > Compress File

MPM/SC devices offer compression/decompression of bitstreams which enables you to save space in the flash. The bitstreams are decompressed by the MPM/SC device before they are sent out over the data pins to the FPGA devices.

Adding Files to System ACE Devices

The last stage of the wizard enables you to add the individual configuration files you wish to be included in the System ACE file.

Note The same startup clock restrictions that apply for configuring devices with a cable also apply to adding bitstreams to the System Ace files. For System ACE CF, only bitstreams with startup clock settings of Boundary Scan (JTAG) Clock are allowed. For System ACE MPM, only bitstreams with startup clock settings of CCLK are allowed.

The Add Files wizard sequence will first take you through adding devices in a single Configuration Address space (revision). When you have added all of your files in the current revision, click No when you see the dialog that looks similar to the one in Figure 5-3.

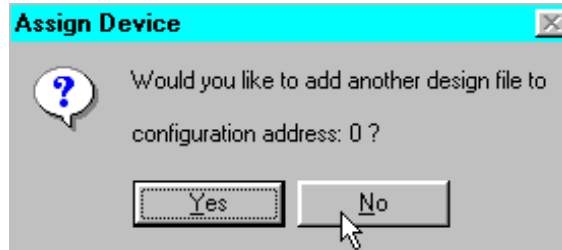


Figure 5-3 Assign Device Dialog Box

The wizard will then move to the next configuration address that you enabled earlier in the wizard sequence, and enable you to assign files to the devices shown in this address space. Follow the sequence until all desired files have been added.

System ACE CF

The following section provides specific information for System ACE CF operations.

System ACE CF Screen

Figure 5-4 shows the System ACE screen for a typical CF design. Moving your mouse over different areas of the screen will reveal details specific to that area. There are three basic areas of the screen:

1. The collection table at the top.
2. The chain description area in the center.
3. The System ACE area at the left.

In the Figure below, three different areas are shown. When moving the mouse over a configuration address, the configuration size for that address displays. Moving your mouse over the "Collection:" row of the table near the top of the screen will display a detailed summary for that collection. Moving your mouse over a device in the chain shows the size of that bitstream, and moving your mouse over the Compact Flash icon shows detailed size information for the total CF design, including all collections and any reserve space specified. Also, a tally of total utilization is always displayed under the System ACE CF icon.

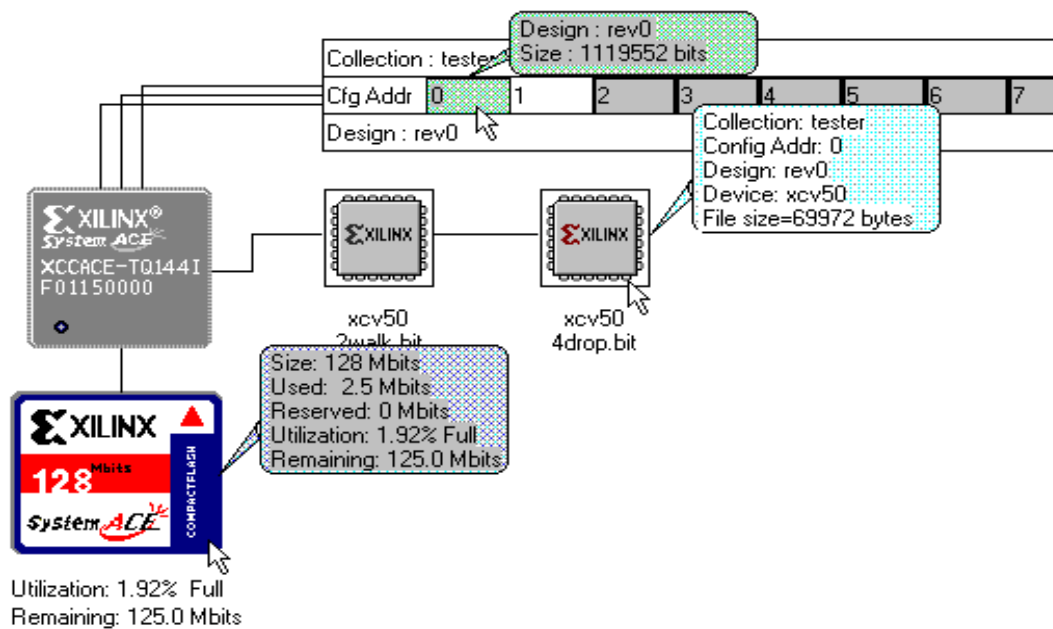


Figure 5-4 System ACE Screen for a CF Design

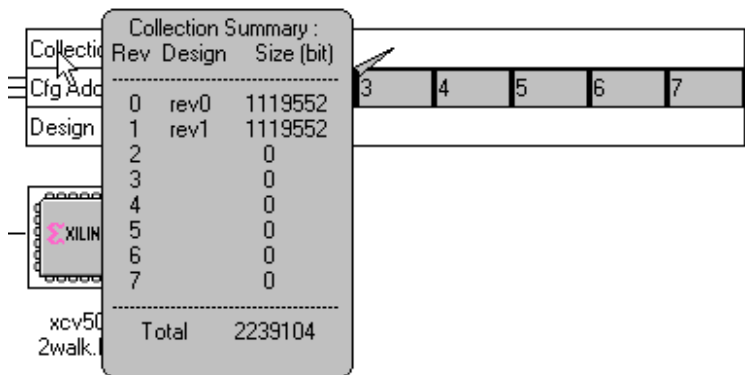


Figure 5-5 Collection Summary for a CF Design

Viewing Different Configuration Addresses

In the collection table, there is a row titled "Cfg Addr" which will also be referred to as revisions. Each revision that is not being used is grayed out and cannot be selected. Left-clicking your mouse on an active (lighter colored) revision name will select this revision and display the contents of the chain in the center of the window.

Adding More Devices After the Wizard Has Finished

In a blank portion of the chain description portion of the screen, right-click or use the **Edit** menu to select **Add Xilinx Device**. A dialog box will appear that will enable you to select a bitstream to add to the chain.

Note If you are in Novice Mode for System ACE CF devices (recommended), adding a device to one revision also adds a device to all revisions. In this case, a wizard appears and will assist in assigning files to the other revisions.

Assigning a Different File to a Device

If you wish to change the file that is assigned to a certain device, you can double-click the device and the Assign New Configuration File dialog will appear. This dialog can also be accessed by selecting the device and right-clicking or by using the **Edit** menu to select **Assign Configuration File**.

Managing Multiple Collections

System ACE CF devices enable you to store multiple collections on the Compact Flash device. However, only one collection, called the "active collection," is available to be loaded into FPGA devices by the System ACE CF controller. The decision on which collection is active is made when you actually generate the System ACE file. See "Generating the System ACE CF File" section for more information.

In a blank section of the chain description portion of the screen, right-click or use the **Edit** menu to select **Add Collection**, **Delete Collection**, **List All Collections**. **Add Collection** will open the Wizard at the collection name input screen, and the wizard will proceed from there to take you through the steps of adding files to your newly created collection.

To switch to a different collection, use **List All Collections**. This menu item will display the dialog box shown in Figure 5-6. The drop down list will enable you to select which collection you wish to work on and clicking OK will make that collection current.

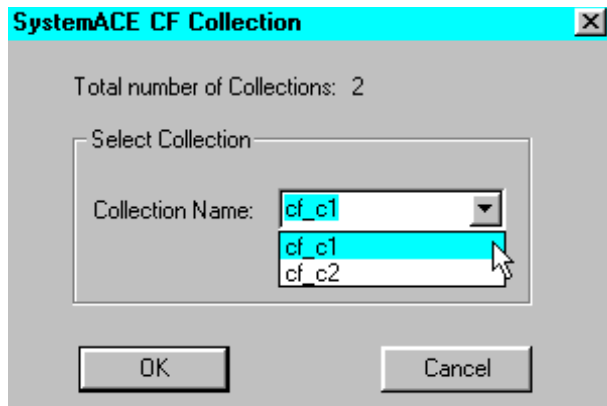


Figure 5-6 SystemACE CF Collection Dialog Box

To delete a collection, use the **Delete Collection** menu item. This will bring up the list dialog shown in Figure 5-6. Clicking OK on this dialog box will cause the selected collection to be deleted from iMPACT's current session. However, this command will not delete previously generated System ACE CF files from your disk.

Generating System ACE CF Files

To generate a System ACE CF fileset, right-click in a blank space in the Chain Description area, or from the **Operations** menu, select **Generate File**. This will open the dialog shown in Figure 5-7. Here you can select the active revision. Click OK to generate the file.

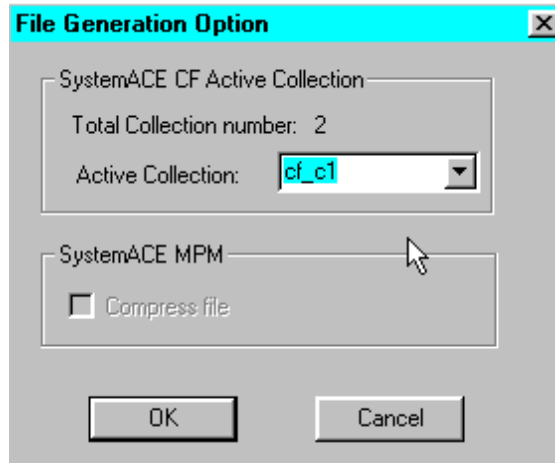


Figure 5-7 File Generation Dialog Box

System ACE MPM

The following section provides specific information for System ACE MPM operations.

System ACE MPM Screen

Figure 5-8 shows the System ACE screen for a typical MPM Slave Serial Mode design and Figure 5-9 shows the screen for a typical Select MAP design. Moving your mouse over different areas of the screen will reveal details specific to that area. There are four basic areas of the screen:

1. The Configuration Address (Revision) table at the top.
2. The chain description area in the center.
3. The Chip Select or Serial Data Stream selection area to the near left.
4. The System ACE MPM area at the far left.

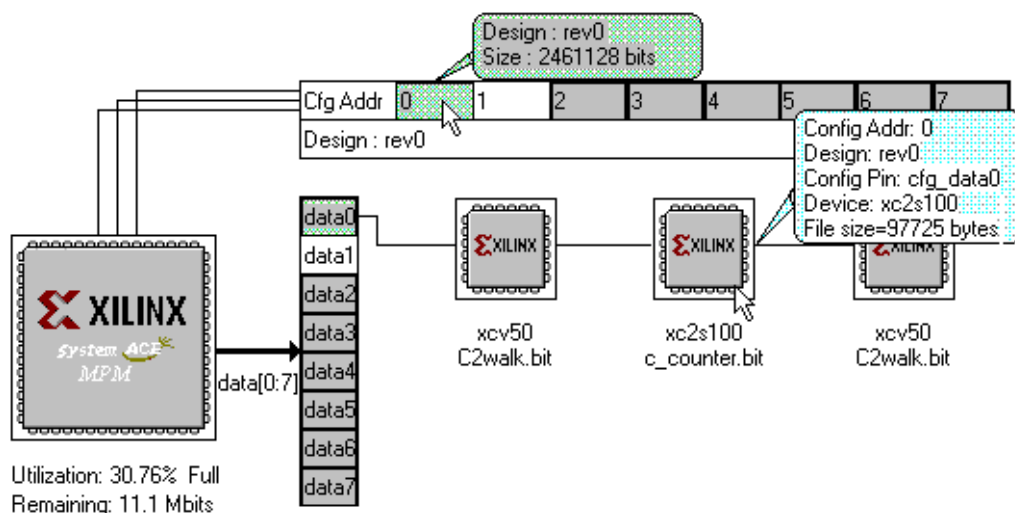


Figure 5-8 System ACE Screen for an MPM Slave Serial Design

In Figure 5-8, three different areas are shown. When moving the mouse over a configuration address, the configuration size for that address is shown. Moving your mouse over a device in the chain shows the size of that bitstream. In Slave Serial Mode, moving your mouse over a data pin shows the size of the chain connected to that pin.

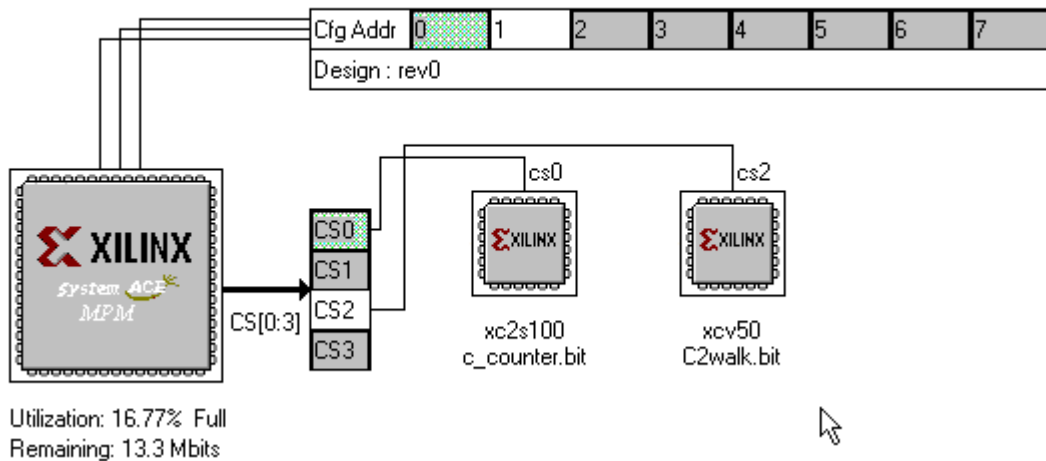


Figure 5-9 System ACE Screen for an MPM SelectMAP Design

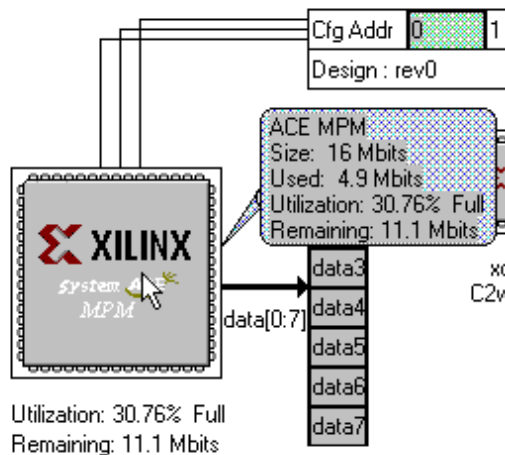


Figure 5-10 System ACE MPM Design Size Information

As shown in Figure 5-10, moving your mouse over the MPM icon shows detailed size information for the total MPM design, including any reserve space specified. Also, a tally of total utilization is always displayed under the MPM icon.

Viewing Different Configuration Addresses

In the collection table, there is a row titled "Cfg Addr" which will also be referred to as revisions. Each revision that is not being used is grayed out and cannot be selected. Left-clicking your mouse on an active (lighter colored) revision name will select this revision and display the contents of the chain in the center of the window.

Adding More Devices After the Wizard Has Finished

In a blank section of the chain description portion of the screen, right-click or use the **Edit** menu to select **Add Xilinx Device**. A dialog box will appear that will enable you to select a bitstream to add to the chain.

Assigning a Different File to a Device

If you wish to change the file that is assigned to a certain device, you can double-click the device and the Assign New Configuration File dialog box will appear. This dialog can also be accessed by selecting the device and right-clicking or by using the **Edit** menu to select **Assign Configuration File**.

Generating System ACE MPM Files

To generate a System ACE MPM file, right-click in a blank space in the Chain Description area, or from the **Operations** menu, select **Generate File**. This will open the dialog shown in Figure 5-11. Here you can turn on file compression by checking the Compress File box'. Click OK to generate the file.

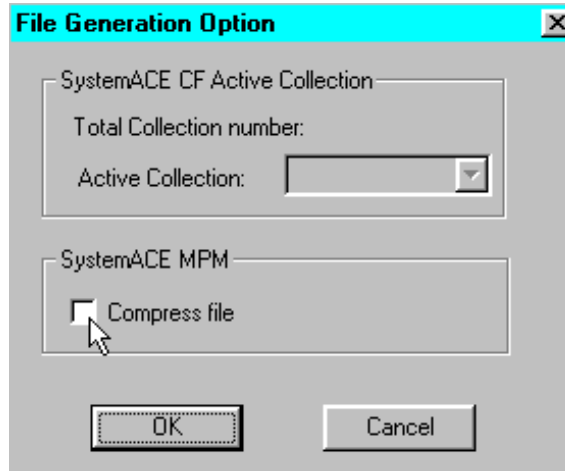


Figure 5-11 File Generation Option Dialog Box

Creating PROM Formatter Programming Files

The following section describes how to generate PROM files using the PROM Formatter in the File Generation mode of iMPACT.

General PROM File Information

This section provides general background information on PROMs and PROM files. For instructions on using PROM Formatter, go to [“PROM Formatter Operations”](#).

PROMs

There are two types of PROMs supported in iMPACT: Xilinx Serial PROMs and 3rd-party parallel PROMs. Xilinx Serial PROMs are designed to work with Xilinx FPGAs in a master-serial daisy-chain. Parallel PROMs are most commonly used in conjunction with CPLDs or microprocessors to program FPGAs in a daisy chain where the first device is in Slave Parallel Mode. Multiple data streams are only allowed in Parallel PROM mode.

PROM Formatter Files

Input Files

You can input one or more BIT files into the PROM Formatter. A BIT file contains configuration information for a single FPGA device.

Output Files

The PROM Formatter generates the following files as outputs:

- PROM files—The file or files containing the PROM configuration information. Depending on the PROM file format your PROM programmer uses, you can output a TEK, MCS, or EXO file. If you are using a microprocessor to configure your devices, you can output a HEX file.

If the data in the PROM Formatter is going to be split into multiple PROMs, there will be a PROM file corresponding to each PROM.

- PRM file—An ASCII file containing a memory map of the output PROM file. If the data in the PROM Formatter is split into

multiple PROM files, there will be a PRM file corresponding to each PROM file.

The following is a sample PRM file.

```
PROM /design/fpgal/fpgal00.prm map: Fri Feb 21
    11:00:50 1998

Format      Mcs86
Size        32K
PROM start  0000:0000
PROM end    0000:7fff

          Addr1          Addr2 File(s)
0000:0000    0000:7fff /design/fpgal/fpgal.bit
```

Bit Swapping in PROM Files

The PROM Formatter produces a PROM file in which the bits within a byte are swapped compared to the bits in the input BIT file. Bit swapping (also called “bit mirroring”) reverses the bits within each byte, as shown in the following figure.

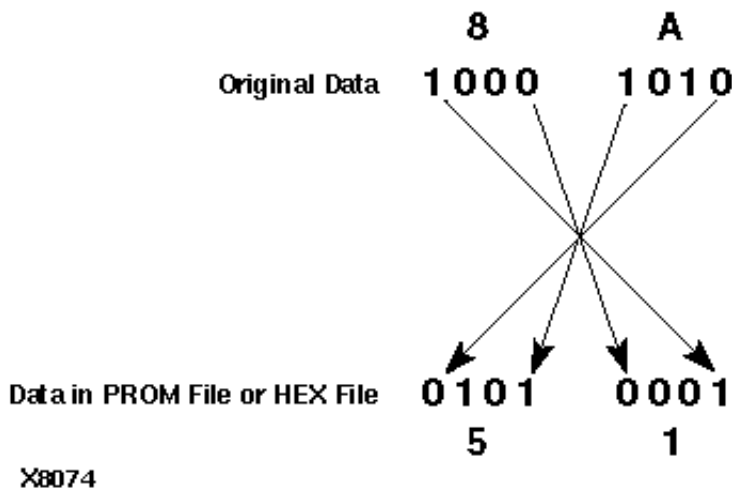


Figure 5-12 Bit Swapping

In a bitstream contained in a BIT file, the Least Significant Bit (LSB) is always on the left side of a byte. But when a PROM programmer or a microprocessor reads a data byte, it identifies the LSB on the right side of the byte. In order for the PROM programmer or microprocessor to read the bitstream correctly, the bits in each byte must first be swapped so they are read in the correct order.

The bits are automatically swapped for all of the PROM formats: MCS, EXO, and TEK. For a HEX file output, bit swapping is on by default, but it can be turned off by deselecting a Swap Bits option that is available only for HEX file format.

In the XACTstep 6.0 release, all formats were swapped except for the HEX format. If you turn off HEX file bit swapping, you can generate a HEX file that is compatible with a HEX file produced by the XACT 6.0 PROM Formatter.

Implementing Your Applications

You can use the PROM Formatter to generate a PROM file containing data to configure a single FPGA device, or a PROM file to configure one or more groups of FPGA devices. You can also store multiple data streams in the same PROM file and use these data streams to reconfigure a device or daisy chain for different applications.

The following table summarizes the various ways of structuring a PROM file.

Table 5-1 Configuration Data Stream Combinations

Number of Applications	Number of FPGA Devices to Configure	Number of Data Streams and BIT Files
Single Application	Single device	One data stream with a single BIT file
	Daisy chain of devices	One data stream with multiple BIT files
	Multiple daisy chains of devices ^a	Multiple data streams with multiple BIT files in each data stream. Each data stream includes configuration data for a different daisy chain of devices.

Table 5-1 Configuration Data Stream Combinations

Number of Applications	Number of FPGA Devices to Configure	Number of Data Streams and BIT Files
Multiple Applications (Reprogramming)	Single device	Multiple data streams with a single BIT file in each data stream
	Daisy chain of devices	Multiple data streams with multiple BIT files in each data stream. Each data stream programs the group of devices for a different application

- a. This type of application can be implemented with a byte-wide PROM only. Each data stream will use a different start-up address in the PROM file.

Single Application PROM Files

There are three different types of configuration data streams.

- **Single Device**
To implement an application for a single device, use a data stream containing a single BIT file.
- **One group of daisy-chained devices**
To implement an application for a group of FPGA devices connected together in a daisy chain, use a single data stream containing multiple BIT files; that is, one BIT file for each device in the daisy chain.
- **Several groups of daisy-chained devices**
To implement an application for several groups of daisy chained devices, you must build one data stream per daisy chain. This type of implementation is valid for byte-wide PROMs, which can be set for different start-up addresses, or for creating a bitstream for microprocessor download.

Multiple Application PROM Files

The Xilinx SRAM FPGA technology enables you to design multiple applications for a single device or a daisy chain of devices. Each data stream in the PROM description area represents a different configuration or application for the same device or daisy chain of devices.

To implement several applications for a single device, build a PROM file made of several data streams, with each data stream containing a single BIT file. To implement several applications for a group of daisy chained devices, use several data streams containing multiple BIT files. Each data stream programs the group of devices for a different application.

Note The number of BIT files within each data stream must be the same.

Configuration Setups

For information on setups for configuring FPGA devices and daisy chains for a single application, refer to The Programmable Logic Data Book.

XILINX PROM Part Names

The part name for a Xilinx serial configuration PROM indicates the PROM's size and type. The fields in the part name are described in the following figure.

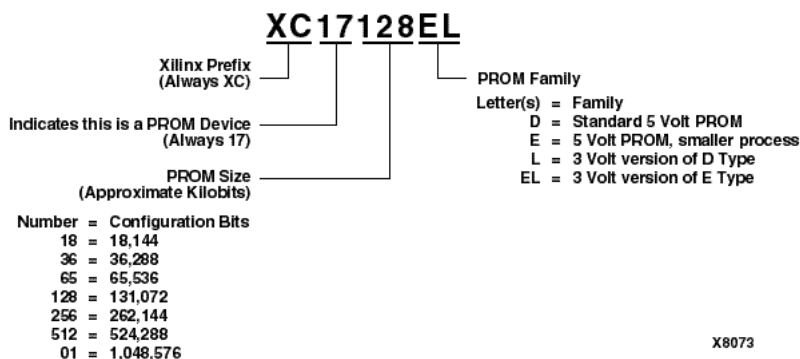


Figure 5-13 PROM Device Names

PROM Formatter Operations

The following section will explain the properties on the wizard screens for PROM files. After setting the properties, you will be prompted to add devices to the configuration chain or chains. As the

final step in the wizard, you will be asked if you wish to generate the System ACE file. If you click "No", you can always generate the file later by using the Operations Menu.

Serial PROM Settings

Select Serial PROM

There are two fields that make up this selection. The first, which defaults to the value of 17V, is the PROM family. PROMs in each of the Xilinx 1700 families are one-time programmable. The flash-based in-system re-programmable PROMs are called the 18V family. Once a family is selected, the drop-down list for the individual PROMs enable you to select the exact PROM you are using. The primary reason for selecting a PROM size is that you wish iMPACT to automatically perform a capacity check. If that is desired, select a size, and click the Add button.

Auto Select PROM

If you wish iMPACT to automatically choose the correct size PROM for you, turn on this checkbox (off by default).

Add button

This button will add the selected PROM to the list of PROMs in the box below the button. For multiple PROMs (also called a PROM daisy-chain), select the next PROM you wish to use and select the add button. This second PROM will start at position 1. iMPACT limits you to a maximum of 32 serial PROMs in a chain.

Parallel PROM Settings

Select Parallel PROM Density

In the drop-down list, there are common PROM densities listed, up to 32 Mbytes. If you wish iMPACT to automatically perform a capacity check, select a size, and click the Add button.

Auto Select PROM

If you wish iMPACT to automatically choose the correctly sized PROM for you, turn on this checkbox (off by default).

Add Button

This button will add the selected PROM to the list of PROMs in the box below the button. For multiple PROMs select the next PROM you wish to use and select the **Add** button. This second PROM will start at position 1. iMPACT limits you to a maximum of 32 PROMs.

Number of Data Streams (1-64)

For parallel PROMs, it is possible to utilize multiple configurations, or revisions, and store these in the parallel PROM. Typically, this is controlled with a microprocessor or other external logic, and each serial chain is referred to as a "data stream".

Loading Direction

This determines whether the PROM data is placed at sequentially higher addresses (UP), or if they are placed at sequentially lower addresses (DOWN).

Adding Files to PROM Devices

The last stage of the wizard enables you to add the individual FPGA configuration files you wish to be included in the PROM file.

Note The same startup clock restrictions that apply for configuring devices with a cable also apply to adding bitstreams to PROM files. For PROM files, only bitstreams with startup clock settings of CCLK are allowed.

The Add Files wizard sequence will first take you through adding devices in a single Data Stream. If you are using a parallel PROM, and you have more than one data stream, you will then be directed to enter the devices and the starting address for further data streams as shown in Figure 5-14. Follow the sequence until all desired files in all Data Streams have been added.

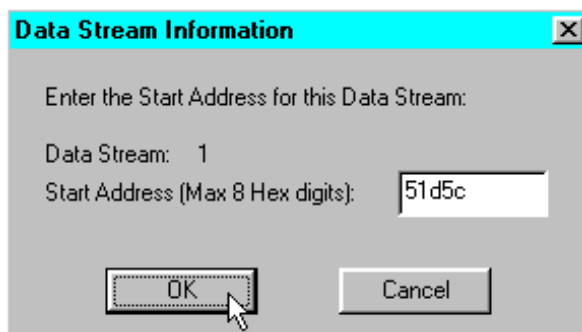


Figure 5-14 Data Stream Information Dialog Box

Generating PROM Files

To generate PROM files from the main PROM screens, right-click in a blank space in the Chain Description area, or from the Operations menu, select **Generate File**.

Serial PROM File Generation

The following section gives specific information on generating Serial PROM files.

Serial PROM Formatter Screen

Figure 5-15 shows the Serial PROM Formatter screen for a typical design. The PROM order is from top to bottom, with the PROM on top being the one that will be read from first. Moving your mouse over a device in the chain shows the size of that bitstream. A tally of total utilization is always displayed under each PROM icon.

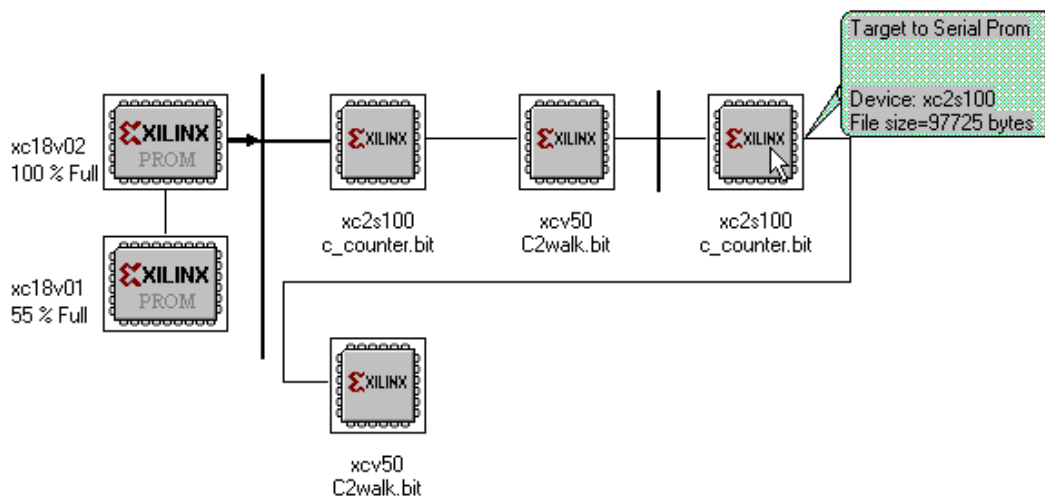


Figure 5-15 PROM Formatter Screen for a Serial PROM

Adding or Deleting FPGA Devices After The Wizard Has Finished

To add an FPGA device, right-click in a blank portion of the screen or use the **Edit** menu to select **Add Xilinx Device**. A dialog box will appear that will enable you to select a bitstream to add to the chain. To delete an FPGA, select the device by clicking on it, and then press the Delete key on the keyboard.

Adding or Deleting Serial PROM Devices After The Wizard Has Finished

To add a PROM, right-click in a blank portion of the screen or use the **Edit** menu to select **Add PROM**. A dialog box will appear that will enable you to select a new PROM to add to the serial PROM chain. To delete a PROM, select the device by clicking on it, and then press the Delete key on the keyboard, or use the **Edit** or right-click menus to select **Delete PROM**.

Assigning A Different File To A Device

If you wish to change the file that is assigned to a certain device, you can double-click the device and the Assign New Configuration File dialog will appear. This dialog can also be accessed by selecting the device and right-clicking or by using the **Edit** menu to select **Assign Configuration File**.

Modifying PROM Sizes

Double-click on the PROM you wish to change, or use the **Modify PROM** command under the **Edit** or right-click menus. A dialog will appear that will enable you to select a different PROM.

Parallel PROM File Generation

The following section gives specific information on generating Parallel PROM files.

Parallel PROM Formatter Screen

Figure 5-16 shows the Parallel PROM Formatter screen for a typical design. There are three basic areas of the screen:

- The Data Stream table at the top
- The chain description area in the center
- The PROM area at the left.

The PROM order is from top to bottom, with the PROM on top being the one that will be filled first. Moving your mouse over an active data stream will give size information and the starting address for that data stream. Moving your mouse over a device in the chain shows the size of that bitstream. A tally of total utilization is always displayed under the each PROM icon.

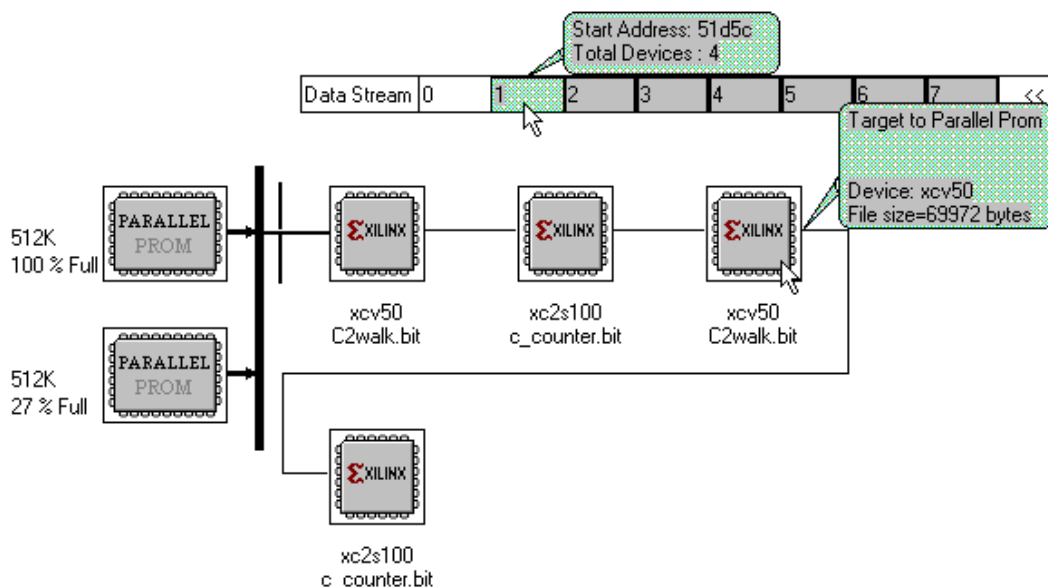


Figure 5-16 PROM Formatter Screen for a Parallel PROM

Viewing Different Data Streams

In the Data Stream table at the top of the screen, notice that each data stream that is not being used is grayed out and cannot be selected. Left-clicking your mouse on an active (lighter colored) data stream will select this stream and display the contents of the chain in the center of the window. You will then be able to modify this stream by the editing methods described below.

Adding or Deleting FPGA Devices After The Wizard Has Finished

To add an FPGA device, right-click in a blank portion of the screen or use the **Edit** menu to select **Add Xilinx Device**. A dialog box will appear that will enable you to select a bitstream to add to the chain. To delete an FPGA, select the device by clicking on it, and then press the Delete key on the keyboard.

Adding or Deleting Parallel PROM Devices After The Wizard Has Finished

To add a PROM, right-click in a blank portion of the screen or use the **Edit** menu to select **Add PROM**. A dialog box will appear that will enable you to select a new PROM to add to the parallel PROM area of the screen. To delete a PROM, select the device by clicking on it, and then press the Delete key on the keyboard, or use the **Edit** or right-click menus to select **Delete PROM**.

Assigning A Different File To A Device

If you wish to change the file that is assigned to a certain device, you can double-click the device and the Assign New Configuration File dialog box will appear. This dialog can also be accessed by selecting the device and right-clicking or by using the **Edit** menu to select **Assign Configuration File**.

Modifying PROM Sizes

Double-click the PROM you wish to change, or to select a PROM use the **Modify PROM** command under the **Edit** or right-click menus. A dialog will appear that will enable you to select a different PROM size.

Creating an SVF or STAPL File

To create an SVF or STAPL file, the File mode must be selected. A cable does not need to be connected because operations are not being performed on devices; all of the configuration information is written to the SVF or STAPL file.

Creating the chain

Before creating the SVF or STAPL file, the Boundary Scan chain must be created. Refer to the section on "Manually Creating the Chain" for the Boundary Scan Configuration Mode. The method of adding devices is the same as described in this section.

Selecting the Programming File

After the chain has been fully described, right-click on a blank area of the window and select **Create SVF File** or **Create STAPL File** (see Figure 5-17). This will bring up a window that enables you to select a

name for your programming file and specify the location for this file. After selecting the name and location, the SVF or STAPL file is ready to be written to.

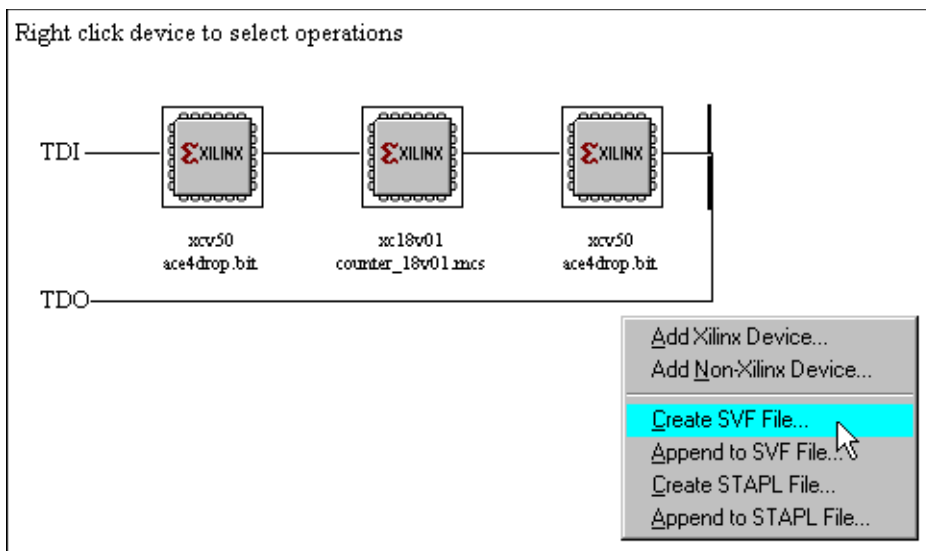


Figure 5-17 Selecting a SVF or STAPL File

Writing to an SVF or STAPL File

The process for writing to an SVF or STAPL file is identical to performing Boundary Scan operations with a cable. You can simply right-click on a device and select an operation. For instance, in Figure 5-18, the user right-clicked on the first device in the chain and will left-click on Get Device ID. The instructions that are necessary to perform a Get Device ID operation will then be written to the file. Figure 5-19 shows what the SVF file will look like after the Get Device ID operation is performed.

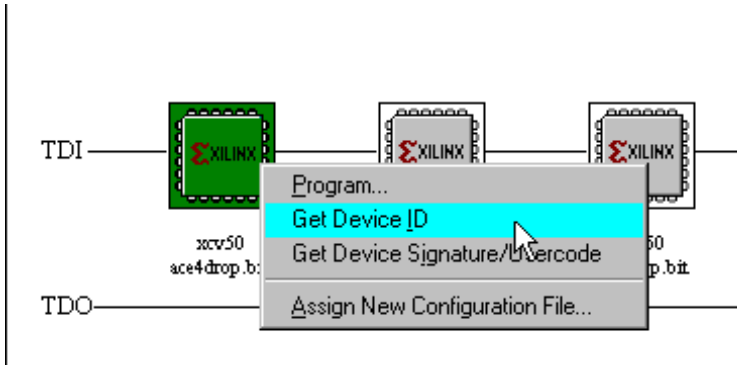


Figure 5-18 Selecting Boundary Scan Operation

```
Device #1 selected
Validating chain...
Boundary-scan chain validated successfully.
'1': IDCODE is '11110000011000010000000010010011'
'1': IDCODE is 'f0610093' (in hex).
```

Figure 5-19 SVF File That Gets a Device ID from the First Device in the Chain

Any number of operations can be written to an SVF or STAPL file. For instance, after selecting Get Device ID for the first device in the chain, you can select the second device in the chain and select the Program option. The instructions and configuration data needed to Program the second device will be added to the file.

After all the desired operations have been performed, right-click in a blank area of the window and select **Close SVF File** or **Close STAPL File** (See Figure 5-20). This will close the file so that no more information can be written to it.

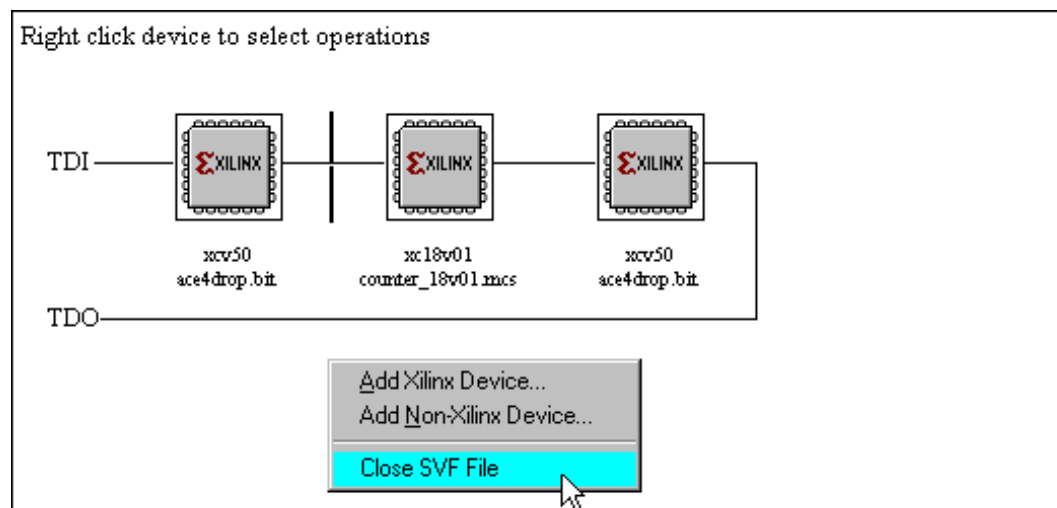
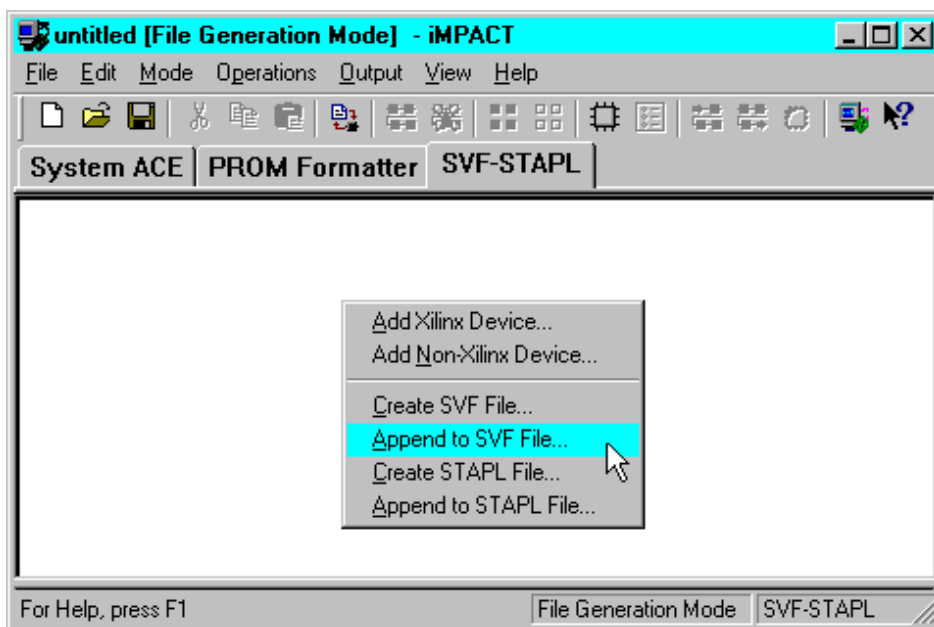


Figure 5-20 Closing the SVF File

To add additional operations in the future, right-click and select **Append to SVF File** or **Append to STAPL File**.



Troubleshooting for Boundary-Scan Chains

This chapter contains the following sections.

- “Communication”
- “Improper Connections”
- “Improper or Unstable VCC”
- “Boundary Scan Chain Debug”
- “System Noise”

Communication

Observing the following guidelines should minimize the communication difficulties that can occur between the cable hardware and the target system.

- Do not attach extension cables to the target system side of the cable; this can compromise configuration data integrity and cause checksum errors.
- Attach the cable configuration leads firmly to the target system.
- After connecting the target system, specify the boundary-scan chain configuration by adding a device (**Edit** → **Add Device** → **Xilinx Device**). Then use the "partinfo -id part_name" command to read the IDCODE from each part in the system. This will verify the integrity of the boundary-scan chain.
- Then read the IDCODE value of the device (**Operations** → **Get Device ID**). This will verify the integrity of the configuration data.
- After a device has been configured, use the verify operation (**Operations** → **Verify**) to assure integrity of the configura-

tion data. You can do this from the command line with the `-v` option or in the interactive mode by specifying the `verify` command.

Improper Connections

Check the following:

- Always make sure that cable leads are connected properly.
- Connecting the cable leads to the wrong signal will cause permanent damage to cable internal hardware. On a parallel cable, you must connect VCC to +5 V, +3.3V or +2.5V, and GND to ground.
- Make sure the Parallel Cable IV's modular power connector is connected to a PC or external power source.
- For workstations, you must have read and write permissions to the port to which you connect the cable. iMPACT might issue a message stating that the cable is not connected to port `ttyx`. When you see this message, follow the checklist below:

- ◆ The board must have the power on, since the cable uses power from the board.
- ◆ Check if the specific port is valid and if not, reconnect the cable to a valid port.
- ◆ Check the device driver using the following command string:

```
ls -l /dev/ttya /dev/ttyb
```

The result should be the following:

```
crw-rw-rw- 1 root12,0 month date time /dev/ttya
```

```
crw-rw-rw- 1 root12,1 month date time /dev/ttyb
```

- ◆ Read the `/etc/ttytab` file. There should be two lines, as follows:

```
ttya"/usr/etc/getty std.9600" unknown off local secure
```

```
ttyb"/usr/etc/getty std.9600" unknown off local secure
```

- If you use a port to connect a modem or a remote login, you cannot use that port. The port must be on. Consult your System Administrator if the information in the `/etc/ttytab` file is different than what is listed in the aforementioned list.

Improper or Unstable VCC

If you are having problems with unstable VCC, try the following:

Never connect the control signals to the cable before VCC and ground. Xilinx recommends the following sequence:

- Turn off power to the target system.
- Connect the Parallel Cable IV's modular power cable to a power source.
- Connect VCC ground, and then the signal leads.
- Turn on power to the target system.
- Make sure that VCC rises to a stable level within 10msec. The stable VCC level should be within 5% of the targets VccIO.
- In the event of power glitches, reset the cable by selecting:

Output → Cable Reset

Boundary Scan Chain Debug

If you experience a consistent error that identifies a break in your boundary-scan chain but are unable to identify such a discontinuity, execute the following steps:

1. Use the **Operations → IDCODE** Looping function to shift out a Device IDCODE repeatedly. Use the default loop count (10000) to begin this procedure.

iMPACT will then execute the IDCODE instruction and data shift 10000 times before quitting.

2. Use an oscilloscope or logic analyzer to probe the pins of the boundary-scan test access port (TAP) at each individual device.
3. Probe the TDO and watch for the following two data patterns:

The instruction capture value (once)

The IDCODE value (10000 times)

The IDCODE looping operations sequences the TAP through a TMS reset sequence (TMS set to 1, TCK pulsed 5 times) and then transitions the TAP to the RunTest/Idle state (TMS set to 0, TCK pulsed once).

Then the TAP is transitioned to the Shift-IR state and the IDCODE instruction is shifted into the device. As this value is shifted in, the instruction capture value is shifted out. For all XC9500/XL/XV devices this sequence is a "1" followed by seven zeroes (this value can be read from the device's BSDL file). You should therefore see a "1" on TDO after the falling edge of the 4th TCK pulse after transitioning out of the RunTest Idle state.

The CAPTURE -IR sequence consists of the following (starting from RunTest/Idle), as illustrated in Figure C-1.

TMS set to 1; TCK pulsed twice.

TMS set to 0; TCK pulsed twice.

TCK pulsed (number of bits in instruction register -1) times.

TMS set to 1; TCK pulsed twice.

TMS set to 0; TCK pulsed once.

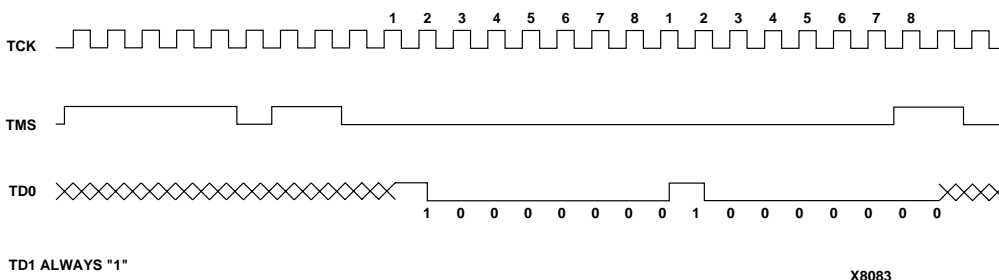


Figure 6-1 Sample Expected Waveform

Check for the following:

- The expected number of TCK pulses occur.
- The same TMS sequence occurs for each part.
- The TDO is not shorted or floating between parts, or floating at the system interconnect point.
- Make certain that all 4 TAP signals are getting into each part (Note that both TDI and TMS have internal pull-ups on them which could keep the device in TRST mode if TMS is not properly connected).

You can also use the Boundary Scan Chain Debug dialog and a logic probe or oscilloscope to transition the TAP state machine directly and observe results.

The IDCODE value (which can be determined from the device's BSDL file) will be visible each time the TAP is in the Shift-DR state.

System Noise

You can check for system noise by running the IDCODE looping instruction. The IDCODE should read correctly 100% of the time. If by test you find that the instruction is working less than 100% of the time, you may be experiencing system noise. To use IDCODE looping:

Operations → IDCODE Looping

This will display the Edit window. Enter the number of loops you desire and click OK.

To remedy a problem with system noise, select Use HIGHZ instead of BYPASS from the Preferences dialog box. This places devices into tri-state mode and reduces susceptibility to system noise. To find this box use:

Edit → Preferences

- The Preferences dialog box will appear. Place a check in the box adjacent to Use HIGHZ instead of BYPASS.

Glossary of Terms

This glossary contains definitions and explanations for terms commonly used in the iMPACT program.

ACE Flash

The Xilinx ACE Flash memory card is a CompactFlash solid-state storage device with an on-card intelligent controller that manages interface protocols, data storage and retrieval, ECC, defect handling and diagnostics, power management, and clock control.

BIT file

A synonym for a configuration bitstream file.

bitstream (BIT file)

A data stream, also called BIT file, that contains location information of logic on a device, that is, the placement of CLBs, IOBs, TBUFs, pins, and routing elements. The bitstream also includes empty placeholders that are filled with the logical states sent by the device during a readback. Only the memory elements, such as flip-flops, RAMs, and CLB outputs, are mapped to these placeholders, because their contents are likely to change from one state to another. When downloaded to a device, a bitstream programs the device.

A bitstream file has a .bit extension.

Boundary-Scan

Boundary-Scan mode is the method used for board-level testing of electronic assemblies. The primary objectives are the testing of chip I/O signals and the interconnections between ICs. It is the method for observing and controlling all new chip I/O signals through a standard interface called a Test Access Port (TAP). The boundary-

scan architecture includes four dedicated I/O pins for control and is described in IEEE spec 1149.1.

byte wide PROM

A PROM that is read one byte at a time. The other PROM type is a serial PROM, which is read one bit at a time.

CCLK pins

The pin of the configuration cable that connects the configuration clock to the device.

CFG_DONE pin

This pin has the same functionality as the ~DONE pin on the XC4000 and Spartan FPGAs. The CFG_DONE pin is a MultiLINX Target Interface Pin.

CFG_RDY pin

When asserted, this pin indicates that the FPGA is ready to receive configuration data. When de-asserted, the pin indicates that either the FPGA is in the power-up mode, or a configuration error has occurred. This pin has the same functionality as the INIT pin on the Spartan and XC4000 FPGAs. The CFG_RDY pin is a MultiLINX Target Interface Pin.

CFG_RESET pin

This pin has the same functionality as the ~PROGRAM pin on the XC4000 and Spartan FPGAs. The CFG_RESET pin is a MultiLINX Target Interface Pin.

console log

A record of the commands that you executed during an iMPACT session.

CS/CS0 pin

CS on the Virtex; and CS0 on the XC4000 FPGAs. The CS/CS0 pin represents a chip select to the target FPGA during configuration. The CS/CS0 pin is a MultiLINX Target Interface Pin.

CS1 pin

Chip Select to the XC4000 FPGAs during configuration. The CS1 pin is a MultiLINX Target Interface Pin.

CS2 pin

The CS2 pin is a MultiLINX Target Interface Pin.

daisy chain

In the context of iMPACT, a data stream used to configure a set of devices that are connected in series such that the Dout pin of a device in the daisy chain is connected to the DIN pin of the next device. You can generate a daisy chain data stream by concatenating two or more bitstreams (BIT files) together using the PROM Formatter tab in the File Generation mode of iMPACT.

data stream

In the context of the PROM Formatter, a data stream is a collection of one or more concatenated BIT files used to implement a single user application. To implement multiple applications, concatenate data streams — one data stream per application — to form a multiple data stream PROM file that enables you to reprogram a single FPGA or a daisy chain.

debugging

The process of reading back or probing the states of a configured device to ensure that the device is behaving normally while in circuit.

DIN pin

The Data In pin of the configuration cable connects to the DIN pin of your target device. In serial mode, the DIN pin loads the bitstream data to the target FPGA.

DONE pin (XC4000/Virtex/Spartan-II)

This pin connects to the DONE pin of your target FPGA. It indicates the completion of the configuration process. During configuration, this pin is Low. After configuration, this pin is High.

downloading

Configuring or programming a device by sending bitstream data to the device.

D0-D7 pins

An 8-bit data bus supporting the Express and SelectMAP configuration modes. The D0-D7 pins are MultiLINX Target Interface Pins.

DOUT pin

Provides configuration data to downstream devices in a daisy-chain. The pin becomes a user I/O after configuration.

EXORmacs (Motorola)

A PROM file format supported by the Xilinx tools. Its maximum address is 16,777,216. This format supports PROM files of up to $(8 \times 16,777,216) = 134,217,728$ bits.

Express Mode

FPGA configuration mode (XC5200 only) in which configuration data is loaded into the FPGA in parallel; one byte per clock cycle instead of one bit per clock cycle.

file selection area

The area located on the right side of the PROM Formatter window. The area presents a hierarchical view of the drives, directories, and BIT files in your system. The area is used to locate and select the BIT files that the PROM file will contain.

GND pin

Ground (0 volt) pin of the configuration cable. This pin connects to the Ground pin of a power supply.

hexidecimal format (HEX)

An ASCII hexadecimal version of the PROM data. It has unlimited data capacity.

INIT pin

Initialization pin on your configuration cable. This pin is connected to the INIT pin of your target device indicating when a device is ready to receive configuration data after power up. During configuration, INIT=0 indicates a configuration error.

loading direction

The direction in which data is stored on your PROM. In the Up direction, the data is stored in ascending order, starting at a low address. In the Down direction, the data is stored in descending order, starting at a high address.

MCS-86 (Intel)

An Intel PROM format supported by the Xilinx tools. Its maximum address is 1,048,576. This format supports PROM files of up to $(8 \times 1,048,576) = 8,388,608$ bits.

(.msk) file

The mask file, (.msk) file indicates which bits are configuration bits and which ones are not. This file is needed to do a verify operation on a Virtex family device using the MultiLINX Cable. This file is generated during the implementation process (BitGen) if readback is enabled in the “Configuration Template”.

main window

The background against which other windows are displayed in the iMPACT menu bar.

The area located at the top of the iMPACT window. It includes the File, Cable, Download, Debug, View, Window, and Help menus.

PROG pin

The Program pin of your configuration cable provides a reprogram pulse to devices when connected to the PROG pin of the device.

PROM file

A PROM file is the file output by the PROM Formatter tab in the File Generation mode of iMPACT, which can be used to program one or

more devices. iMPACT supports the following PROM file formats: MCS (Intel MCS-86), EXO (Motorola EXORMacs), TEKHEX (Tektronix hexadecimal).

PROM description area

The area located on the left side of the PROM Formatter window. The area shows the structure of your PROM file. It is a hierarchical view of the data streams and BIT files in the PROM file.

PROM description (PDR) file

An ASCII report file listing all the data streams and BIT files used to construct the PROM file, as well as the load direction and PROM file splitting information. The PROM Formatter uses this file to determine the structure and properties you have specified for the PROM file.

RBT file

A raw BIT format file, the ASCII version of the BIT file.

readback

The process of reading the logic downloaded to an FPGA device.

- A readback with a filter that extracts the configuration bits to verify that a design was downloaded correctly.

RD (TDO) pin

The readback data pin of the MultiLINX Cable. This pin connects to the RDATA pin of the device. When connected, the pin reads data from the programmed target device.

RDWR pin

The RDWR pin is used as an active high READ and an active low WRITE control signal to the Virtex FPGA. The RDWR pin is a MultiLINX Target Interface Pin.

RDY/BUSY pin

The RDY/BUSY pin is a MultiLINX Target Interface Pin.

RS pin

Read Select control for the Asynchronous Peripheral configuration mode on XC4000 FPGAs. The RS pin is a MultiLINX Target Interface Pin.

SelectMAP

SelectMAP mode is a configuration mode supported by the Spartan-II, Virtex, Virtex-II, and Virtex-II Pro device families.

Slave Serial

Slave Serial mode is a configuration mode supported by the Virtex and Spartan devices.

serial PROM

A PROM whose data is read serially, one bit at a time. The other PROM type is a byte wide PROM, which is read one byte at a time.

status bar

The field located at the bottom of the iMPACT window. It provides information about the commands that you are about to select or that are already being processed.

System ACE

System ACE is a Xilinx developed configuration environment that allows for space-efficient, pre-engineered, high-density configuration solutions for systems with multiple FPGAs. There are two versions of System ACE: System ACE CF and System ACE MPM.

TCK pin

In iMPACT, the Boundary-Scan clock pin.

TDI pin

In iMPACT, the Boundary-Scan data pin.

TEKHEX (Tektronix)

A Tektronix PROM format supported by Xilinx. Its maximum address is 65,536. This format supports PROM files of up to $(8 \times 65,536) = 524,288$ bits.

TMS pin

In iMPACT, the Boundary-Scan select pin.

toolbar

A field located under the menu bar at the top of the main window. It contains a series of buttons that execute some of the most frequently used commands. These buttons constitute an alternative to the menu commands.

TRIG pin

The external trigger pin of the MultiLINX Cable. This pin is connected to an external signal used as a trigger. A Low to High transition on this pin signals the cables to initiate a readback.

VCC pin

Power pin of the configuration cable. This pin connects to the power pin of a target board.

verification

The process of reading back the configuration data and comparing it to the original downloaded design to ensure that all of the design was received by the device.

WS pin

Write Select control for the Asynchronous Peripheral configuration mode on XC4000 FPGAs during configuration. The WS pin is a Multi-LINX Target Interface Pin.

Boundary Scan Basics

This appendix contains the following sections.

- [“Boundary Scan/IEEE Standard 1149.1”](#)
- [“Configuring the Parallel Download Cable”](#)

Boundary Scan/IEEE Standard 1149.1

Design complexity, difficulty of loaded board testing, and the limited pin access of surface mount technology led industry leaders to seek accord on a standard to support the solution of these problems.

JTAG Boundary Scan, formally known as IEEE Standard 1149.1, is primarily a testing standard created to alleviate the growing cost of designing and producing digital systems. The primary benefit of the standard is the ability to transform extremely difficult printed circuit board testing problems (that could only be attacked with ad-hoc testing methods) into well-structured problems that software can handle easily and swiftly.

The standard defines a hardware architecture and the mechanisms for its use to solve the aforementioned problems.

What can it be used for?

Although primarily a testing standard for on-chip circuitry, the proliferation of the standard has opened the door to a wide variety of applications. The standard itself defines instructions that can be used to perform functional and interconnect tests as well as built-in self test procedures.

Vendor-specific extensions to the standard have been developed to allow execution of maintenance and diagnostic applications as well

as programming algorithms for reconfigurable parts. It is the latter that have been implemented (in addition to all the mandatory operations of the standard and some optional ones) in the FastFLASH family.

How does it work?

The top level schematic of the test logic defined by IEEE Std 1149.1 includes three key blocks:

The TAP Controller

This responds to the control sequences supplied through the test access port (TAP) and generates the clock and control signals required for correct operation of the other circuit blocks.

The Instruction Register

This shift register-based circuit is serially loaded with the instruction that selects an operation to be performed.

The Data Registers

These are a bank of shift register based circuits. The stimuli required by an operation are serially loaded into the data registers selected by the current instruction. Following execution of the operation, results can be shifted out for examination.

Impact Test Access Port

The JTAG Test Access Port (TAP) contains four pins that drive the circuit blocks and control the operations specified. The TAP facilitates the serial loading and unloading of instructions and data. The four pins of the TAP are: TMS, TCK, TDI and TDO. The function of each TAP pin is as follows:

TCK - this pin is the JTAG test clock. It sequences the TAP controller as well as all of the JTAG registers provided in the XC95108.

TMS - this pin is the mode input signal to the TAP Controller. The TAP controller is a 16-state FSM that provides the control logic for JTAG. The state of TMS at the rising edge of TCK determines the sequence of states for the TAP controller. TMS has an internal pull-up resistor on it to provide a logic 1 to the system if the pin is not driven.

TDI -this pin is the serial data input to all JTAG instruction and data registers. The state of the TAP controller as well as the particular instruction held in the instruction register determines which register is fed by TDI for a specific operation. TDI has an internal pull-up resistor on it to provide a logic 1 to the system if the pin is not driven. TDI is sampled into the JTAG registers on the rising edge of TCK.

TDO - this pin is the serial data output for all JTAG instruction and data registers. The state of the TAP controller as well as the particular instruction held in the instruction register determines which register feeds TDO for a specific operation. Only one register (instruction or data) is allowed to be the active connection between TDI and TDO for any given operation. TDO changes state on the falling edge of TCK and is only active during the shifting of data through the device. This pin is three-stated at all other times.

JTAG TAP Controller

The JTAG TAP Controller is a 16-state finite state machine, that controls the scanning of data into the various registers of the JTAG architecture. The state of the TMS pin at the rising edge of TCK is responsible for determining the sequence of state transitions. There are two state transition paths for scanning the signal at TDI into the device, one for shifting in an instruction to the instruction register and one for shifting data into the active data register as determined by the current instruction.

JTAG TAP Controller States

Test-Logic-Reset. This state is entered on power-up of the device whenever at least five clocks of TCK occur with TMS held high. Entry into this state resets all JTAG logic to a state such that it will not interfere with the normal component logic, and causes the IDCODE instruction to be forced into the instruction register.

Run-Test-Idle. This state allows certain operations to occur depending on the current instruction. For the XC9500/XL/XV family, this state causes generation of the program, verify and erase pulses when the associated in-system programming (ISP) instruction is active.

Select-DR-Scan. This is a temporary state entered prior to performing a scan operation on a data register or in passing to the Select-IR-Scan state.

Select-IR-Scan. This is a temporary state entered prior to performing a scan operation on the instruction register or in returning to the Test-Logic-Reset state.

Capture-DR. This state allows data to be loaded from parallel inputs into the data register selected by the current instruction on the rising edge of TCK. If the selected data register does not have parallel inputs, the register retains its state.

Shift-DR. This state shifts the data, in the currently selected register, towards TDO by one stage on each rising edge of TCK after entering this state.

Exit1-DR. This is a temporary state that allows the option of passing on to the Pause-DR state or transitioning directly to the Update-DR state.

Pause-DR. This is a wait state that allows shifting of data to be temporarily halted.

Exit2-DR. This is a temporary state that allows the option of passing on to the Update-DR state or returning to the Shift-DR state to continue shifting in data.

Update-DR. This state causes the data contained in the currently selected data register to be loaded into a latched parallel output (for registers that have such a latch) on the falling edge of TCK after entering this state. The parallel latch prevents changes at the parallel output of these registers from occurring during the shifting process.

Capture-IR. This state allows data to be loaded from parallel inputs into the instruction register on the rising edge of TCK. The least two significant bits of the parallel inputs must have the value 01 as defined by IEEE Std. 1149.1, and the remaining 6 bits are either hard-coded or used for monitoring of the security and data protect bits.

Shift-IR. This state shifts the values in the instruction register towards TDO by one stage on each rising edge of TCK after entering this state.

Exit1-IR. This is a temporary state that allows the option of passing on to the Pause-IR state or transitioning directly to the Update-IR state.

Pause-IR. This is a wait state that allows shifting of the instruction to be temporarily halted.

Exit2-IR. This is a temporary state that allows the option of passing on to the Update-IR state or returning to the Shift-IR state to continue shifting in data.

Update-IR. This state causes the values contained in the instruction register to be loaded into a latched parallel output on the falling edge of TCK after entering this state. The parallel latch prevents changes at the parallel output of the instruction register from occurring during the shifting process.

Mandatory Boundary Scan Instructions

BYPASS. The BYPASS instruction allows rapid movement of data to and from other components on a board that are required to perform test operations.

SAMPLE/PRELOAD. The SAMPLE/PRELOAD instruction allows a snapshot of the normal operation of a component to be taken and examined. It also allows data values to be loaded onto the latched parallel outputs of the boundary scan shift register prior to the selection of other boundary-scan test instructions.

EXTEST. The EXTEST instruction allows testing of off-chip circuitry and board level interconnections.

Optional Boundary Scan Instructions

INTEST. The INTEST instruction allows testing of the on-chip system logic while the components are already on the board.

HIGHZ. The HIGHZ instruction forces all drivers into high impedance states.

IDCODE. The IDCODE instruction allows blind interrogation of the components assembled onto a printed circuit board to determine what components exist in a product.

USERCODE. The USERCODE instruction allows a user-programmable identification code to be shifted out for examination. This allows the programmed function of the component to be determined.

FastFLASH XC9500/XL/XV Reconfiguration Instructions

ISPEN. The ISPEN instruction activates the FastFLASH part for in-system programming.

FPGM. The FPGM instruction is used to program the fuse locations at a specified address.

FERASE. The FERASE instruction is used to perform an erase of a block of fuse locations.

FVIFY. The FVIFY instruction is used to read the programming of the fuse locations at a specified address.

ISPEX. The ISPEX instruction loads the programmed values into the device memory. It then activates the device to operate according to the programmed values.

FPGMI. The FPGMI instruction is used to program fuse locations sequentially from a preset starting address.

FVFI. The FVFI instruction is used to read the programming of fuse locations sequentially for a preset starting address.

FBULK. The FBULK instruction is used to perform an erase of either all function blocks or all Fastconnect blocks of a device.

Configuring the Parallel Download Cable

To configure your parallel download cable, follow these steps:

1. On PCs you can connect the parallel cable to your system's parallel printer port. The iMPACT Configuration software will automatically identify the cable when correctly connected to your PC. If you choose to, you may also select this connection manually. To set up a parallel port manually:

Output → Cable Setup

Select the Parallel box and match to the port you are using, then click on OK.

Appendix B

Parallel Cable III (DLC 5) Schematic

This appendix contains a schematic of the Parallel Download Cable III. It is included in case you want to build your own download cables. Schematic, Figure B-1, is our current version of the Parallel Download Cable III. If you want to build a parallel cable, this is the recommended schematic.

Note You must use recommended lengths for parallel cables. Xilinx cables are typically six feet (about two meters) in length.

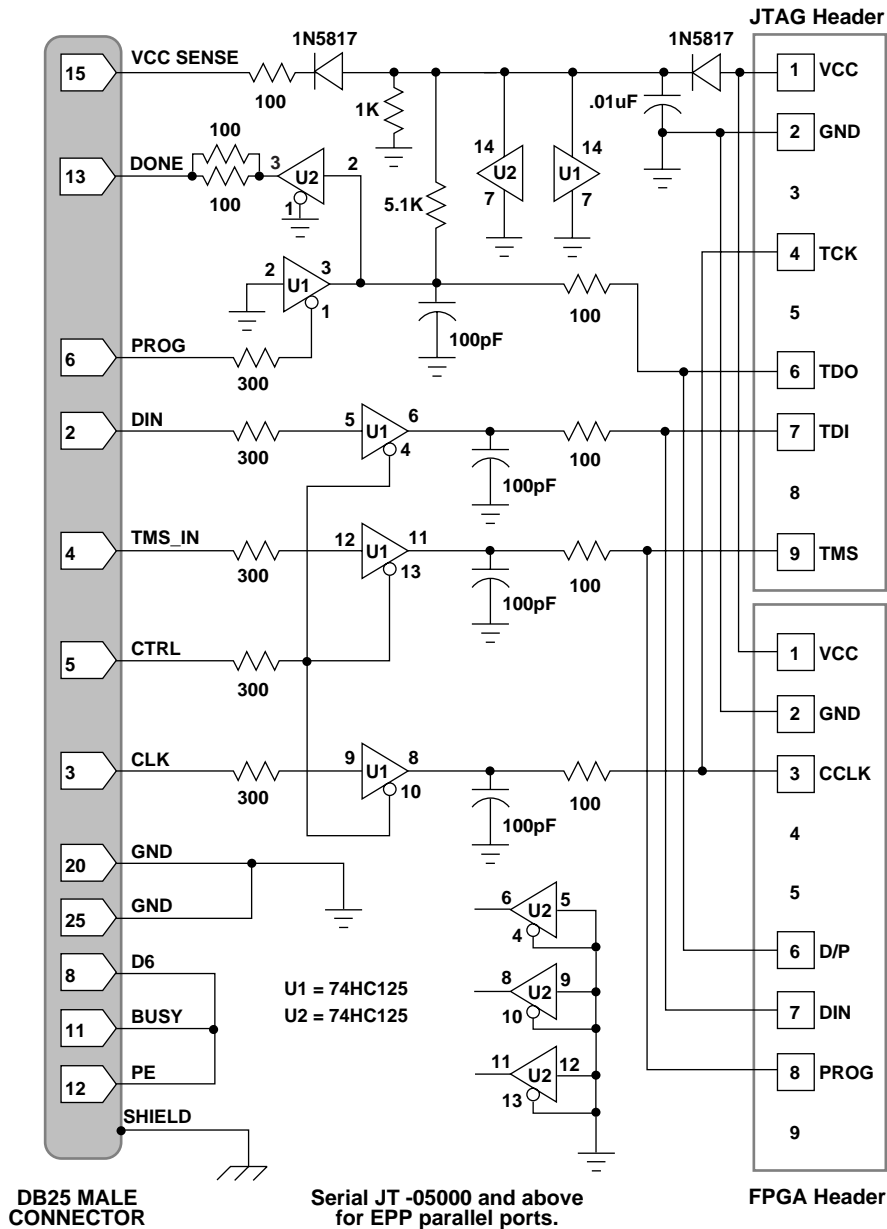


Figure B-1 Parallel Download Cable III

Appendix C

Command Line and Batch Mode Commands

This appendix contains the following sections.

- [“Difference Between Command Line and Batch Mode Operation”](#)
- [“Command Line Usage”](#)
- [“Command Line Options”](#)
- [“Batch Mode Commands”](#)
- [“Configuration Mode Commands”](#)
- [“File Generation Mode Commands”](#)
- [“Example Batch Mode Command Sequences”](#)
- [“JTAGPROG to iMPACT Script Migration”](#)

Difference Between Command Line and Batch Mode Operation

The iMPACT command line serves as a method to launch the iMPACT GUI in a specific place. However, operations such as Program, Erase, etc., cannot be specified on the command line. To perform operations, Batch mode must be used.

Batch mode is an interactive mode where you can type in commands at a command prompt. Batch mode can also receive command files (.cmd) and will perform the commands contained in the file as if they were coming from the command prompt.

Command Line Usage

```
impact[-Switch Parameter] [-Switch Parameter]
```

Command Line Options

When an option occurs without parentheses "(" next to the command name in the syntax, it is required. When it appears in square brackets "[]," it is optional.

When two or more options occur between braces "{ }," the options must be entered with the command. If the options are separated by a vertical bar "|," you must choose one of the possible parameters. If one term is divided into a subset of parameters that can be entered separately or together, each subparameter occurs between square brackets.

Table C-1 Command Line Options

Switch	Parameter(s)	Notes
-j or -jedec	jedec file name (.jed extension)	If a full path is not given, the specified file is assumed to reside in the current working directory.
-b or -bitstream	bitstream file name (.bit extension)	If a full path is not given, the specified file is assumed to reside in the current working directory.
-p or -prom	mcs, exo or hex file name (.exo, .mcs, .hex extensions respectively)	If a full path is not given, the specified file is assumed to reside in the current working directory.
-c or -cdf	cdf file name (.cdf extension)	If a full path is not given, the specified file is assumed to reside in the current working directory.

Table C-1 Command Line Options

Switch	Parameter(s)	Notes
-port	PC: auto,lpt1,lpt2,lpt3,com1, com2,com3,usb0,usb1, usb2 UNIX: auto,/dev/ttya,/dev/ttyb /dev/tty00 dev/tty01	"auto" means automatically detect cable available and connect to it. If the -port switch is not specified, the application does not attempt cable connection at start-up
-batch	none	initiates batch mode
-mode	bscan,sserial,smap,dtconfig, cf,mpm,bsfile,pff	Indicates the mode in which to start the application. The default mode is boundary-scan (bscan)
-baud	auto,9600,19200,38400,5760 0	When the "-port" switch is used to select a serial port connection (com1,com2,com3,/dev/ttya,/dev/ttyb) this switch indicates the connection speed (baud rate). "auto" indicates that the speed selection should automatically choose the fastest possible. The default "-baud" value is "auto".

Batch Mode Commands

Common flags and their meanings

-cs 0 | 1 | 2: Refers to chip selects in SelectMAP mode. There are three chip selects on the MultiLinX cable.

-p | -position: Refers to the position of the device in the chain.

-f | -file: Filename.

-size: Size of the storage device in bytes.

General Commands

savecdf -f|-file <file name>

(create cdf file from device database)

loadcdf -f|-file <file name>

(load cdf file and initialize device database from its contents)

deleteDevice [-p|-position <savecdf> -f|-file <file name>

(create cdf file from device database)

loadcdf -f|-file <file name>

(load cdf file and initialize device database from its contents)

deleteDevice [-p|-position <pos1>...<posN>] [-cs 0|1|2] [-all]

(**-all** takes no argument and removes all devices from iMPACT's memory.)

setMode [-ss|-sserial|-sm|-smap|-bs|-bscan|-mpm|-cf|-compactflash|-pff|-promfile|-bsfile|-dtconfig]

- ◆ **"-ss|-sserial"** switches to the Slave Serial Configuration mode. <pos1>...<posN>]
[-cs 0|1|2] [-all]

- ◆ **-all** takes no argument and removes all devices from iMPACT's memory.

setMode [-ss|-sserial|-sm|-smap|-bs|-bscan|-mpm|-cf|-compactflash|-pff|-promfile|-bsfile|-dtconfig]

- ◆ **"-ss|-sserial"** switches you to Slave Serial savecdf -f|-file <file name>

- ◆ create cdf file from device database

loadcdf -f|-file <file name>

(load cdf file and initialize device database from its contents)

deleteDevice [-p|-position <pos1>...<posN>] [-cs 0|1|2] [-all]

(**-all** takes no argument and removes all devices from iMPACT's memory.)

setMode [**-ss** | **-sserial** | **-sm** | **-smap** | **-bs** | **-bscan** | **-mpm** | **-cf** | **-compactflash** | **-pff** | **-promfile** | **-bsfile** | **-dtconfig**]

- ◆ **"-ss** | **-sserial"** switches you to the Slave Serial Configuration mode
- ◆ **"-sm** | **-smap"** switches you to the SelectMAP Configuration mode
- ◆ **"-bs** | **-bscan"** switches you to the Boundary Scan Configuration mode
- ◆ **"-ss** | **-sserial"** switches you to the Slave Serial Configuration mode
- ◆ **"-mpm"** switches you to the System ACE MPM File Generation mode
- ◆ **"-cf** | **-compactflash"** switches you to the System ACE CF File Generation mode
- ◆ **"-pff** | **-promfile"** switches you to the PROM File Generation mode
- ◆ **"-bsfile"** switches you to the Boundary Scan File Generation mode (SVF/STAPL, etc.)
- ◆ **"-dtconfig"** switches you to the Desktop Configuration mode, where you can access the Xilinx MultiPRO cable, and program non-volatile devices

assignFile **-p** | **position** <posN> **-file** | <filename>

(Assigns/changes file to previously defined device.)

[**exit** | **quit**]

(Exits the program.)

info

(displays table of device database (position:device type:file name))

Configuration Mode Commands

Because JTAG file formats like SVF and STAPL are essentially programming "batch" files, these configuration mode commands also are used when creating these types of files.

General Configuration Mode Commands

```
setCable [-p|-port  
lpt1|lpt2|lpt3|com1|com2|com3|com4|  
usb0|usb1|usb2|tty|ttyb|svf|stapl|auto] [-b|-baud  
9600|19200|38400|57600] [-f|-file <filename>]
```

- ◆ **-p** for this command means "port". It is equivalent to **-port**.
- ◆ "auto" means detect first available cable (order of detection: usb, parallel, serial).
- ◆ "svf" and "stapl" select file output.
- ◆ **-f** | **-file** refers to the svf or stapl file to use.
- ◆ **"-baud"** is applicable to serial port connections only.

```
setPreference concurrent|c|sequential|s  
expert|e|novice|n bypass|b|highz|h
```

(Sets preferences found in the Edit->Preferences dialog.)

- ◆ **concurrent** | **sequential** indicates which programming mode will be used for CPLD devices (default is concurrent).
- ◆ **bypass** | **highz** indicates which instruction to use on bypassed devices in JTAG (default is bypass).
- ◆ **Expert** | **e** | **novice** | **n** refers to the messaging mode.
- ◆ defaults: concurrent, novice, bypass.

```
addDevice [-p|-position <pos>] [-sprom xc18v256 |-mpm  
|xc18v512|xc18v01|xc18v02|xc18v04|xccacem16|  
xccacem32|xccacem64|xccacem128] [-cs 0|1|2]  
[file<filename>]
```

(Adds a device to the chain in the position specified.)

- ◆ If the device is a serial PROM or System ACE MPM device, the **-sprom** or **-mpm** flag must be used, and the particular device specified.

```
program [-e|-erase] [-v|-verify] [-w|-writeProtect]
[-r|-readProtect] [-u|-usercode|-ues <codeString>]
[-t|-functest] [-parallel] [-skipua] [-useD4] [-
loadfpga] [-s|-secureMode] [-keyonly] [-key
{<keyfile>}] [-p|-position <pos1> {<pos2>}]
```

- ◆ **-cs** (chip select) is used in SelectMap mode.
- ◆ **-f** (file) overwrites default file name specified in addDevice command and can only be used when only one device is specified.
- ◆ *pos1,,,posN* specifies a group of devices to operate on.
- ◆ **-ues** stands for User Electronic Signature.
- ◆ **-parallel** enables the parallel outputs on an 18Vxx PROM
- ◆ **-skipua** skips the user array for a PROM. This would be used in cases where the user does not wish to program the main PROM array, but instead wants to program just a user code, etc.
- ◆ **-useD4** causes the D4 pin of an 18Vxx PROM to be used as a Chip Select, when in parallel mode.
- ◆ **-loadfpga** issues the “load FPGA” instruction to the 18Vxx PROM, which causes it to automatically program the FPGA.

closeCable

(Closes the open cable and forces a detection the next time a cable operation is detected.)

```
verify [-p|-position <pos1...<posN>] [-cs 0|1|2] [-f|-
file <filename>]
```

(Boundary-Scan and SelectMAP modes only. Reads configuration information back from a programmed device, and compares it to the file specified.)

Boundary-Scan Mode Specific Commands

```
erase [-p|-position <pos1>...<posN>] [-cs 0|1|2]
```

(Erases the device(s) at the specified position(s).)

```
blankCheck [-p|-position <pos1>...<posN>] [-cs 0|1|2]
```

(Checks to see if the device(s) at the specified position(s) are not programmed.)

```
readIdcode [-p|-position <pos1>...<posN>] [-cs 0|1|2]
```

(Reads the ID Codes of the device(s) at the specified position(s).)

```
readUserCode [-p|-position <pos1>...<posN>] [-cs  
0|1|2]
```

(Reads the User Codes of the device(s) at the specified position(s).)

```
readUES [-p|-position <pos1>...<posN>] [-cs 0|1|2]
```

(Reads the User Electronic Signature of the device(s) at the specified position(s).)

```
readbackToFile [-p|-position <pos1>...<posN>] [-cs  
0|1|2] [-f |  
-file <filename>]
```

(Reads the programming information of the device(s) at the specified position(s) into a file.)

```
checksum [-p|-position <pos1>...<posN>] [-cs 0|1|2]
```

(Calculates the checksum of the device(s) at the specified position(s).)

```
bypass [-p|-position <pos1>...<posN>]
```

(Places the device(s) at the specified position(s) into bypass.)

```
bsdebug [-start] [-reset] [-stop] [-tms 0|1] [-tdi  
0|1] [-tck <number>] [-loop <number>]
```

(Executes the Boundary Scan Debug instruction which shifts in the instruction and data values specified by -tms and -tdi.)

```
identify
```

(display table of device types resulting from "initialize chain" operation.)

File Generation Mode Commands

```
setsubMode [-mpmss|-mpmsm|-pffserial|-pffparallel]
```

(Some of the modes of iMPACT have sub-modes.)

- ◆ **"-mpmss"** switches you to the Slave Serial sub-mode of MPM File Generation mode.
- ◆ **"-mpmsm"** switches you to the Select MAP sub-mode of MPM File Generation mode.
- ◆ **"-pffserial"** switches you to the Slave Serial sub-mode of PROM File Generation mode.
- ◆ **"-pffparallel"** switches you to the Parellel sub-mode of PROM File Generation mode.

```
generate [-active <collectionName>] [-path
<pathString>] [-output <outputFile>] [-compressed] [-
format mcs|exo|hex|tek] [-fillvalue <hexByte>] [-
disableswap] [-generic]
```

(Generates the file appropriate for the current mode.)

- ◆ **-active** sets the active collection name for System ACE CF.
- ◆ Using the **-compressed** option turns on bitstream compression for System ACE MPM mode.
- ◆ **-format** sets the file format for PROM Formatter.
- ◆ **-fillvalue** sets the value to fill the leftover portion of a PROM with. Specified as a hex byte, e.g. "FF" or "00".
- ◆ **-disableswap** turns off the automatic bitswapping.
- ◆ Using the **-generic** switch tells PROM Formatter that the target device is a generic (non-Xilinx) PROM. Size restrictions are not compared, in these cases.

PROM Formatter Specific Commands

```
addPromDevice [-p|-position <pos>] [-size <size>] [-
name <name>]
```

(Adds a PROM to PROM Formatter File Generation Mode.)

```
addConfigDevice [-size <size>] [-name <name>] [-path
<path>]
```

(Adds a PROM to PROM Formatter File Generation Mode.)

```
loadPdr [-file <fileName>]
```

(Load PROM Description file (file created from PROM File Formatter).)

```
setPromOptionBits [-p|-position <pos1> {<pos2>}] [-  
u|-usercode <usercode>] [-parallel] [-useD4] [-  
loadfpga]
```

- ◆ **-parallel** enables the parallel outputs on an 18Vxx PROM.
- ◆ **-skipua** skips the user array for a PROM. This would be used in cases where the user does not wish to program the main PROM array, but instead wants to program just a User Code, etc.
- ◆ **-useD4** causes the D4 pin of an 18Vxx PROM to be used as a Chip Select, when in parallel mode.
- ◆ **-loadfpga** sets a flag in the 18Vxx PROM which causes it to automatically load the FPGA once the PROM has been programmed.

System ACE Specific Commands

```
addCollection [-name <name>]
```

(Adds a System ACE CF collection to System ACE CF File Generation Mode.)

```
addDesign [-version <versionNumber>] [-name|-  
designName <designName>] [-collection|-c  
<collectionName>] [-d|-down]
```

(Adds a design to System ACE CF and MPM File Generation Modes.)

```
addDeviceChain [-index|-csPin ] [-d|-design <design>]  
[-c|-collection <collectionName>]
```

(Adds a Slave Serial device chain to System ACE MPM Slave Serial File Generation Mode.)

Example Batch Mode Command Sequences

iMPACT's batch mode can be used either interactively, by typing commands at a prompt (>), or in true batch mode by passing it a command (.cmd) file at the command line (impact -batch filename.cmd).

There is a certain order in which commands must be issued. For example, you cannot program a part unless you first set the mode,

issue the command to select the cable, and have defined a chain of at least one device.

You will probably only need to perform six operations in your command (.cmd) file:

1. Set the configuration mode
2. Set up the cable port
3. Define the JTAG chain and assign files
4. Program the device
5. Verify the device
6. Exit from the programming software

General Batch Command Sequence Format

Below is a list of the most commonly used commands and options.

```
setmode -bscan
setcable -p auto
identify (optional)
addDevice -p [device number] -file [filename.bit/
.jed]
addDevice -p [device number] -sprom [part name] -file
[filename.mcs/.exo]
program -p [device number]
saveCdf -file [filename]
loadCdf -file [filename]
quit (or exit)
```

Command Sequence Example 1: Creating a Chain Using addDevice

```
setMode -bs
setCable -p auto
addDevice -p 1 -file bitstream1.bit
addDevice -p 2 -file bitstream2.bit
program -p 2
```

quit

The preceding example creates a chain of two devices, then programs the second device in the chain and exits the program. The exit command ends batch mode and causes an exit to the command prompt.

**Command Sequence Example 2: Chain Consisting of:
XC18V04 (programmed), Third Party Device
(bypassed) XC18v04 (programmed), XC18V04
(bypassed with .bsd file)**

```
setmode -bscan  
setcable -p auto  
addDevice -p 1 -sprom xc18v04 -file design1.mcs  
addDevice -p 2 -file thirdparty.bsd  
addDevice -p 3 -sprom xc18v04 -file design2.mcs  
addDevice -p 4 -file xc18v04_vq44.bsd  
program -p 1  
program -p 3  
quit
```

Notice how the PROM devices require the use of the -sprom switch in the addDevice command. In this example, only the two PROMs are programmed and the other devices in the chain are placed in bypass.

**Command Sequence Example 3: Using JTAG to
Automatically Identify a Chain**

```
setMode -bs  
setCable -p auto  
identify  
assignFile -p 1 -file bitstream1.bit  
assignFile -p 2 -file bitstream2.bit  
saveCdf -file batch.cdf  
program -p 2  
quit
```

The "identify" command is equivalent to the "initialize chain" command, in the GUI. The "identify" command will display text that will list each device in the chain give a number for its order. Then, files can be assigned and the desired device programmed. Notice also that a Chain Description File (.cdf) is created for future use.

Command Sequence Example 4: Loading a .cdf File and Programming a Device

```
setMode -bs
setCable -p auto
loadCdf -file batch.cdf
program -p 2
quit
```

The loadCdf command loads an existing chain description into iMPACT. All file associations are contained in the .cdf file, so the device can immediately be programmed.

JTAGPROG to iMPACT Script Migration

This section is provided as a guide to help customers convert their 3.1i JTAGPROG .cmd script files for use with 4.1i iMPACT.

Getting Started

JTAGPROG and iMPACT are both case-insensitive. Uppercase syntax is used in this and other documents for the sake of clarity.

To invoke JTAGPROG in batch mode:

```
jtagprog -batch bat_file.cmd
```

To invoke iMPACT in batch mode:

```
impact -batch bat_file.cmd
```

The .cmd file is simply a text file which specifies the instructions to be performed in batch mode. All instructions that follow should be placed in this .cmd file.

Determining the Part Name

JTAGPROG and iMPACT both require the user to specify a part name for certain commands. This can cause confusion, as the required naming convention is not provided in the documentation for JTAGPROG or iMPACT.

When specifying the part name with the part command, the part name must exactly match the name of the BSDL file that is associated

with that part, minus the file extension (examples provided in table C-2). BSDL files for all parts can be found in the \$xilinx folder.

This applies to both JTAGPROG and iMPACT.

Note

Table C-2

Device	JTAGPROG/iMPACT Part Name	BSDL File Location
18v04 pc44	xc18v04_pc44	\$xilinx\xc1800\data\xc18v04_pc44.bsd
95144XL cs144	xc95144xl_cs144	\$xilinx\xc9500xl\data\xc95144xl_cs144
Virtex 100 pq240	xcv100_pq240	\$xilinx\virtex\data\xcv100_pq240.bsd

Programming and Verifying a Device

You will most likely only need to perform five operations in your command (.cmd) file:

1. Set up the cable port.
2. Define the JTAG chain and assign files.
3. Program the device.
4. Verify the device.
5. Exit from the programming software.

JTAGPROG

Autoconfigure

part part_type:*[arbitrary part name]*

program *[arbitrary part name]* **-f** *[filename.bit/.jed/.mcs]*

verify *[arbitrary part name]*

quit

iMPACT

setmode -bscan

setcable -p auto

```
identify (optional)
addDevice -p [devicenumber] -file [filename.bit/.jed]
program - verify -p [device number]
quit
```

iMPACT (18V00 Family)

The iMPACT syntax varies slightly for 18v00 PROMs.

```
setmode -bscan
setcable -p auto
identify (optional)
addDevice -p [device number] -sprom [part name]3 -file
[filename.mcs/.exo]
program -p [device number]
quit
```

iMPACT (when assigning a BSDL file)

Again, the syntax is slightly different when assigning a BSDL file to a device. This situation will arise whenever third-party devices are used or when BSDL files are used to bypass Xilinx devices.

```
setmode -bscan
setcable -p auto
identify (optional)
addDevice -p [device number] -file [filename.bsd]
assignFile3 -p [device number] -file [filename.bsd]
bypass -p [device number]4
quit
```

Note

[device number] = 1,2,3...

If the programming file does not reside in the working directory, the full path may be specified, e.g.: -file c:\test\filename.bit

[part name] = xc18v256, xc18v512, xc18v01, xc18v02, or xc18v04.

The assignFile instruction may not be required in future versions of iMPACT, although it will continue to be supported in future versions of iMPACT.

The bypass command is not needed in most cases, since devices with no action assigned are automatically placed in bypass. See the Examples, below.

Blank lines are not allowed in the iMPACT .cmd file.

Example: Programming a XC4062XLA Device

JTAGPROG

```
autoconfigure
part xc4062xla_hq208:device1
program device1 -f c:\test\design.bit
quit
```

iMPACT

```
setmode -bscan
setcable -p auto
identify
assignfile -p 1 -file design.bit
program -p 1
quit
```

iMPACT (SVF mode)

```
setmode -bscan
setcable -p svf -file output.svf
addDevice -p 1 -file design.bit
program -p 1
quit
```

Note The same procedure is used for any FPGA or CPLD device.

Example: Programming a 18v00 PROM

JTAGPROG

```
autoconfigure
part xc18v04_pc44:device1
program device1 -f c:\test\design.mcs
quit
```

iMPACT

```
setmode -bscan
setcable -p auto
identify
addDevice -p 1 -sprom xc18v04 -file design.mcs
program -p 1
quit
```

iMPACT (SVF mode)

```
setmode -bscan
setcable -p svf -file output.svf
addDevice -p 1 -sprom xc18v04 -file design.mcs
program -p 1
quit
```

Example: 2v1000 Device (bypassed with a .bit file) in a Chain with an 18v04 Device (programmed)

```
JTAGPROG
reset
autoconfigure
part xc2v1000_fg256:device1 xc18v04_pc44:device2
program device2 -f design.mcs
quit
```

iMPACT

```
setmode -bscan
setcable -p auto
identify
addDevice -p 1 -file design.bit
addDevice -p 2 -sprom xc18v04 -file design.mcs
program -p 2
quit
```

iMPACT (SVF mode)

```
setmode -bscan
setcable -p svf -file output.svf
addDevice -p 1 -file design.bit
addDevice -p 2 -sprom xc18v04 -file design.mcs
program -p 2
quit
```

Note No instruction is required to bypass the 2v1000. Devices that do not have instructions specified will be bypassed automatically. Bypassed Xilinx devices can be assigned either a BSDL (.bsd) file or a programming file (.bit/.jed/.mcs/.exo). Bypassed third-party devices must be assigned a BSDL file.

Example: 2v1000 (programmed) in a Chain with a 18v04 (bypassed with a BSDL file)

JTAGPROG

```
reset
autoconfigure
part xc2v1000_fg256:device1 xc18v04_pc44:device2
program device1 -f design.bit
quit
```

iMPACT

```
setmode -bscan
setcable -p auto
identify
addDevice -p 1 -file design.bit
addDevice -p 2 -file xc18v04_pc44.bsd
assignFile -p 2 -file xc18v04_pc44.bsd
program -p 1
quit
```

iMPACT (SVF mode)

```
setmode -bscan
setcable -p svf -file output.svf
assignfile -p 1 -file design.bit
assignfile -p 2 -sprom xc18v04 -file design.mcs
program -p 1
quit
```


Example: Chain Consisting of XC18v04 (programmed), Third Party Device (bypassed), XC18v04 (programmed), XC18v04 (bypassed with a .bsd file)

JTAGPROG

```
reset
autoconfigure
part xc18v04_vq44:device1 thirdparty:device2
xc18v04_vq44:device3 xc18v04_vq44:device4
program device1 -f design.mcs
program device3 -f design.mcs
quit
```

iMPACT

```
setmode -bscan
setcable -p auto
identify
addDevice -p 1 -sprom xc18v04 -file design1.mcs
addDevice -p 2 -file thirdparty.bsd
assignFile -p 2 -file thirdparty.bsd
addDevice -p 3 -sprom xc18v04 -file design2.mcs
addDevice -p 4 -file xc18v04_vq44.bsd
assignFile -p 4 -file xc18v04_vq44.bsd
program -p 1
program -p 3
quit
```

iMPACT (SVF mode)

```
setmode -bscan
setcable -p svf -file output.svf
addDevice -p 1 -sprom xc18v04 -file design1.mcs
addDevice -p 2 -file thirdparty.bsd
assignFile -p 2 -file thirdparty.bsd
addDevice -p 3 -sprom xc18v04 -file design2.mcs
addDevice -p 4 -file xc18v04_vq44.bsd
assignFile -p 4 -file xc18v04_vq44.bsd
program -p 1
program -p 3
quit
```