

# Lecture 19: Introduction to RDS

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- ▶ Limit theorems review
- ▶ Goal: basic idea behind diffusion models
- ▶ Begin with Random walks
- ▶ Obtaining diffusion in the limit of random walks
- ▶ Ergodic theory basics
- ▶ Not much stochastic analysis
- ▶ References: [ [Arnold Random Dynamical Systems](#) ], [ [Song et al 2020](#) ], [ [Kidger 2022 PhD thesis](#) ]

# So far...

- ▶ Linear hyperbolic systems: where the matrix has no eigenvalues equal to 1 in magnitude.
- ▶ More general hyperbolic systems: no zero Lyapunov exponent
- ▶ Statistical properties of dynamical systems: ergodic theory
- ▶ Oseledets theorem: applies to Random Dynamical System (RDS), the cocycle considered is a linear RDS
- ▶  $x_{t+1} = \varphi(x_t)$ ,  $\varphi : M \rightarrow M$
- ▶ OMET deals with  $d\varphi(x_t)$  as a dynamics on tangent vectors
- ▶ Linear RDS:  $d\varphi(v_1 + v_2) = d\varphi v_1 + d\varphi v_2$ ;  $v_1, v_2 \in TM$

# Limit theorems review

- ▶  $X_1, X_2, \dots$ , where  $X_i$  is independent and identically distributed (iid) with mean  $\mu$  and std  $\sigma < \infty$ . Let  $S_n = \sum_{i=1}^n X_i$ .
- ▶ Weak Law of Large Numbers:  $\lim_{n \rightarrow \infty} \mathbb{P}(|S_n/n - \mu| > \epsilon) = 0$  for every  $\epsilon > 0$ . That is,  $S_n/n \xrightarrow{P} \mu$  as  $n \rightarrow \infty$ . Convergence in probability. (Proof: Chebyshev's inequality when  $\sigma < \infty$ , but LLNs do not require finite variance in general)
- ▶ Strong LLN:  $\mathbb{P}(\lim_{n \rightarrow \infty} S_n/n = \mu) = 1$ . Also written as  $S_n/n \xrightarrow{\text{a.s.}} \mu$ . Almost sure convergence. (requires boundedness of expected value)
- ▶ Central limit theorem:  
 $\lim_{n \rightarrow \infty} \text{CDF}((S_n - n\mu)/(\sqrt{n}\sigma))(t) = \text{CDF}(Z)(t)$ , where  $Z$  is a standard Gaussian. That is,  $((S_n - n\mu)/(\sqrt{n}\sigma)) \xrightarrow{d} \mathcal{N}(0, 1)$ . Convergence in distribution. (Requires finite variance)

- ▶ We will see limit theorems when  $X_i = f \circ \varphi^i(x_0)$ , where  $\varphi$  is a random or deterministic DS.  $x_0$  is a random variable sampled from any distribution.
- ▶ In deterministic dynamics, randomness comes from initial condition
- ▶  $\varphi(x) = Ax$ , linear hyperbolic
- ▶  $X_0 \sim \rho_0$ , then,  $X_t \sim \rho_t$ .
- ▶  $X_t \sim \rho$  and  $X_{t+1} \sim \rho$ , then,  $\rho$  is an invariant density.
- ▶ For Cat map,  $\rho$  is uniform on unit square
- ▶  $\rho_{t+1} = \varphi_{\#} \rho_t$
- ▶ Markov process:  $\mathbb{P}(X_t | X_1, \dots, X_{t-1}) = \mathbb{P}(X_t | X_{t-1})$
- ▶ Transition kernel of a Markov process:  
 $\mathcal{K}(x, A) = \mathbb{P}(X_{t+1} \in A | X_t = x)$
- ▶  $\rho_{t+1}(A) = \int_x \mathcal{K}(x, A) \rho_t(dx)$ .

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- ▶ Transition operator:  $\mathcal{T}\rho(A) = \int \mathcal{K}(x, A) \rho(dx)$  (Function on the space of measures)
- ▶  $\mathcal{T}(\rho_1 + \rho_2) = \mathcal{T}\rho_1 + \mathcal{T}\rho_2$  (linear operator)
- ▶ Alternatively:  $\rho$  is an invariant measure if it is an eigenfunction of  $\mathcal{T}$  with eigenvalue 1.
- ▶ Limit theorems also valid for some “weakly” dependent RVs
- ▶ If  $X_1, \dots, X_n, \dots$ , is generated by a hyperbolic dynamical system, CLT is valid.
- ▶  $|(1/T) \sum_{t \leq T} f(X_t) - E_{x \sim \rho} f(x)|$  behaves like a normal RV for an idealized class of chaotic systems

# Random walk

- ▶ Start on a 1D lattice at 0. With probability  $1/2$ , go left or right.
- ▶  $\mathbb{P}(X_t = k) = \binom{t}{(t+k)/2} \frac{1}{2^t}$ . Let  $a$  and  $b$  be the number of times you go right and left respectively. Clearly,  $a + b = t$ . Also,  $a - b = k$ .
- ▶ Stirling's approximations of these probabilities for large  $t$ .  
 $\log n! \approx n \log n - n$
- ▶  $\mathcal{K}(x, \{x + 1\}) = 1/2$
- ▶ Diffusion processes.