

$$\lambda(x) = \lambda_i \quad x \in V_i \setminus V_{i+1}$$

$$|g(t, x)| \leq C |x|^{1+\alpha}$$

$$\alpha > 0$$

$$\sum_{i=1}^p \lambda_i k_i = \lim_{t \rightarrow \infty} \frac{1}{t} \log |\det A(t)|$$

$$(A_{t-1} \cdots A_0)^T \quad \frac{1}{t} \log |\det \Phi(t)|$$

$$\log |\det e^{tA}|$$

$$e^{k_1 \lambda_1} \cdot e^{\frac{k_2}{2} \lambda_2} \cdots e^{\lambda_p k_p}$$

$$\log(e^{k_1(a+ib)})$$

A : periodic

$$\log(e^{k_1 a} \cdot e^{k_1 i b})$$

$$A(t) = A(t+c)$$

$$e^{k_1 a} \cdot e^{k_1 i b}$$

$$\frac{1}{t} \log \|A_t\| \rightarrow 0$$

$$\|A(t)\| \leq e^{ct}$$

$$\sum_{i=1}^p k_i \lambda_i = \lim_{t \rightarrow \infty} \frac{1}{t} \log |\det A(t)|$$

$$\Phi(t) = P(t) e^{tR}$$

$$\dot{x}(t) = A(t)x(t)$$

$$x(t) = P(t)y(t)$$

$$\frac{d}{dt} x(t) = \frac{dP(t)}{dt} y(t) + P(t) \dot{y}(t)$$

$$= A(t) P(t) y(t)$$

$$P(t) \dot{y}(t) = \left(-\frac{dP(t)}{dt} + A(t)P(t) \right) y(t)$$

$$= P(t) R y(t)$$

$$A(t)P(t) - \frac{dP(t)}{dt} = P(t)R$$

$$\frac{dP(t)}{dt} = A(t)P(t) - P(t)R$$

$$\Phi(t) = P(t) e^{tR}$$

$$A(t) = \frac{dP(t)}{dt} e^{tR} + P(t) e^{tR}$$

Sign-up sheet: 2 days for presentation
11th

- 10 mins Participatory presentation
- broad introduction
 - computational algorithm/analysis
 - interpretation

Note: doesn't have to be new research

5 pages: last day of class
report

Check Rubric on canvas.

HW4 Due Sunday

HW5

HW2, HW3 grades

Recap

Introduction to ergodic theory

$F: M \rightarrow M$ $(M, \Sigma, \mathbb{P}, F)$

Corollary of Birkhoff's ergodic theorem:

For any $g \in L^1$, and measure-preserving dynamical system F ,

$$\frac{1}{T} \sum_{t \leq T} g \circ F^t(x) \xrightarrow{T \rightarrow \infty} \mathbb{E}_{x \sim \mu} g(x) = \langle g, \mu \rangle$$

for x μ -a.e.

• (F, μ) is ergodic

• Ergodic decomposition theorem:
any invariant measure can be
decomposed into ergodic components

M (viewed as a Lebesgue space)

$\int g d\mu \underset{\text{invariant}}{=} \int \int g d\mu_x d\alpha$

→ partitioned into $\{M_k\}_k$ ergodic
measures
supported on
 M_k .

• Ergodic measures are extremal points
on (convex) sets of invariant measures.

• ℓ^2 sequences shifts
translations

• For any continuous map $F: M \rightarrow M$
on compact M , \exists at least one
invariant ergodic measure.

dissipative
• Chaotic systems: μ an ergodic measure
may not be "observable".

C may have $\text{leb}(\text{supp}(\mu)) = 0$
↓
Volume measure

Kingman's subadditive ergodic theorem

(M, Σ, P, F) (F, μ) is ergodic

g_1, g_2, g_3, \dots are a sequence of random variables ($g_i: M \rightarrow \mathbb{R}$) and

- $g_i \in L^1 \quad \forall i.$

- $\{g_i\}$ is a subadditive sequence

$$g_{m+n}(x) \leq g_n(x) + g_m(F^n x) \quad x \text{ } \mu\text{-a.e.}$$

Then,

- $\frac{g_n}{n} \xrightarrow{L^1} \bar{g} \in L^1$

$$\left(\lim_{n \rightarrow \infty} \frac{g_n(x)}{n} = \bar{g}(x) \quad \forall x \text{ } \mu\text{-a.e.} \right)$$

- $\mathbb{E} \frac{g_n}{n} \xrightarrow{L^1} c$

$$g_n = \sum_{i \leq n} g \circ F^i$$

- HW4 : $\text{Unif} \{x_0, \dots, x_n\} \xrightarrow{n \rightarrow \infty} \mu,$
 $x_i = F(x_{i-1})$

$$\text{Unif} \{y_0, \dots, y_n\} \xrightarrow{n \rightarrow \infty} \mu_2$$

Oseledets multiplicative ergodic theorem (OMET)

$(M, \Sigma, \mathbb{P}, F)$ RDS

$$A_i(x) \in \mathbb{R}^{d \times d}$$

$$A_{m+n}(x)$$

$$\log^+ \|A_n\|(x) := \max \{0, \log \|A_n(x)\|\}$$

$$\log^+ \|A_n\| \in L^1$$

The sequence $\{A_n\}$ is regular for μ -a.e.

$$\sum_{i=1}^{p(x)} \lambda_i(x) k_i(x) = \lim_{t \rightarrow \infty} \frac{1}{t} \log \det \|\Phi(x, t)\|$$

$$\Phi(x, t) = A_{t-1}(x) \dots A_0(x)$$

if (F, μ) is ergodic,

$$\lambda_i(x) = \lambda_i \quad \mu\text{-a.e.}$$

$$p(x) = p \quad \mu\text{-a.e.}$$

$$k_i(x) = k_i \quad \mu\text{-a.e.}$$

Lyapunov exponent, subspaces, Oseledets subspaces

OMET says

$$\lim_{t \rightarrow \infty} \frac{1}{t} \log \|\Phi(x, t)v\|$$

$$:= \lambda(x, v) = \lambda(v)$$

(F, μ) ergodic

Filtration

$$V_{p+1}^{(x)} \subset V_p^{(x)} \subset \dots \subset V_2^{(x)} \subset V_1^{(x)} = \mathbb{R}^d$$

"{0}"

$$V_i := \{v \in \mathbb{R}^d : \lambda(x, v) \leq \lambda_i\}$$

$\lambda_1 > \lambda_2 > \dots > \lambda_p$ are distinct LEs.

"Backward" regular

$$\Phi(x, t) \quad t \in \mathbb{Z}^-$$

$$A_{-1}(x) \quad A_{-1}^{-1} = A(F^{-1}x)$$

$$\lambda_1^- > \lambda_2^- > \dots > \lambda_p^-$$

$$\text{OMET: } \lambda_i^- = -\lambda_{p+1-i}$$

$$\{0\} \subset V_p^-(x) \subset \dots \subset V_2^-(x) \subset V_1^-(x) = \mathbb{R}^d$$

$$\hookrightarrow V_{p+1}^-(x)$$

$$E_i(x) = V_i^{(x)} \cap V_{p+1-i}^-(x) \quad \text{Oseledets subspaces}$$

$$E_i(F^n x) = \Phi(x, n) E_i(x) \quad n \in \mathbb{Z}$$

$$E_i(x) = \{e \in \mathbb{R}^d : \lambda(x, e) = \pm \lambda_i\}$$

Proof idea

$$\lim_{t \rightarrow \infty} \frac{1}{t} \log \det |\Phi(x, t)| \text{ exist}$$

$$\frac{1}{t} \log \|\Phi(x, t)\|$$

$$\Phi(x, t+u) = \Phi(F^u(x), t) \Phi(x, u)$$

$\mathbb{R}^{d \times d}$ ($\Phi(x, t)$ is a cocycle)

$$\log \|\Phi(x, t+u)\| \leq \log \|\Phi(F^u(x), t)\| + \log \|\Phi(x, u)\|$$

Apply Kingman's subadditive ergodic theorem