

HW2: Contraction maps

Due in 10 days

Recap

Applications of Contraction mapping principle / Banach fixed point Theorem

→ Inverse function theorem

→ Conjugacies

$$F : M \rightarrow M$$

$G : M \rightarrow M$ is near F

$$\text{in } \|F - G\|_{\infty} < \varepsilon$$

F is "near" G if $\exists h : M \rightarrow M$ which is close to the identity and is invertible s.t.

$$\underline{F} = h^{-1} \circ \underline{G} \circ h$$

Why contraction?

$$h = \text{Id} + v$$

• Write $\phi : B_{\mathcal{V}}(0, \delta) \rightarrow B_{\mathcal{V}}(0, \delta)$

$\downarrow \quad \downarrow$
(δ -ball around C^0 vector fields on M)

and show that ϕ is a contraction

• $\{x_n\}$: orbit of F

$$x_0, x_1, x_2, \dots \quad x_n = F(x_{n-1})$$

$$y_0, y_1, \dots \quad y_n = G(y_{n-1})$$

$$\begin{aligned} \underline{h^{-1} \circ F \circ h}(x_n) &= F(x_n + v(x_n)) \\ &\quad - v(x_{n+1}) \\ &= G(x_n) \end{aligned}$$

• x_0, x_1, \dots, x_T (e.g. option prices you observe)

$$\|G(x_t) - x_{t+1}\| < \varepsilon$$

$$\forall t \in [1, T]$$

"finite-time orbit equivalence"

ϕ contraction defined on

$$\{T_{x_0}M, T_{x_1}M, \dots, T_{x_T}M\}$$

Linear systems

Map	Flow
$x_{t+1} = F x_t$	$\frac{dx}{dt} = A x$
$F: \mathbb{R}^d \rightarrow \mathbb{R}^d$	$A: \mathbb{R}^d \rightarrow \mathbb{R}^d$
	\downarrow
	$\frac{d F^t x}{dt} = A(F^t x)$
$F^t x = F \dots F x$	$F^t x = e^{tA} x$
	\downarrow
	$e^{tA} = \text{Id} + tA + \frac{t^2 A^2}{2!} + \dots$

$F = \text{time-1 map of the flow}$

$$e^{tA} x$$

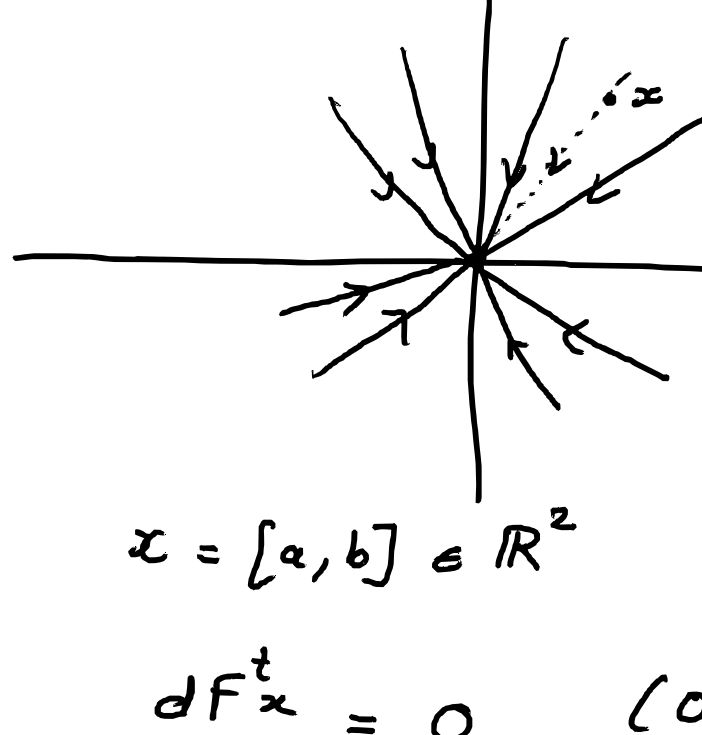
$$F = e^A$$

Map $F = \text{Id}$ \longleftrightarrow Flow Identity flow

ID: $x(t) = e^{tA} x(0)$ (nonautonomous)

Strogatz

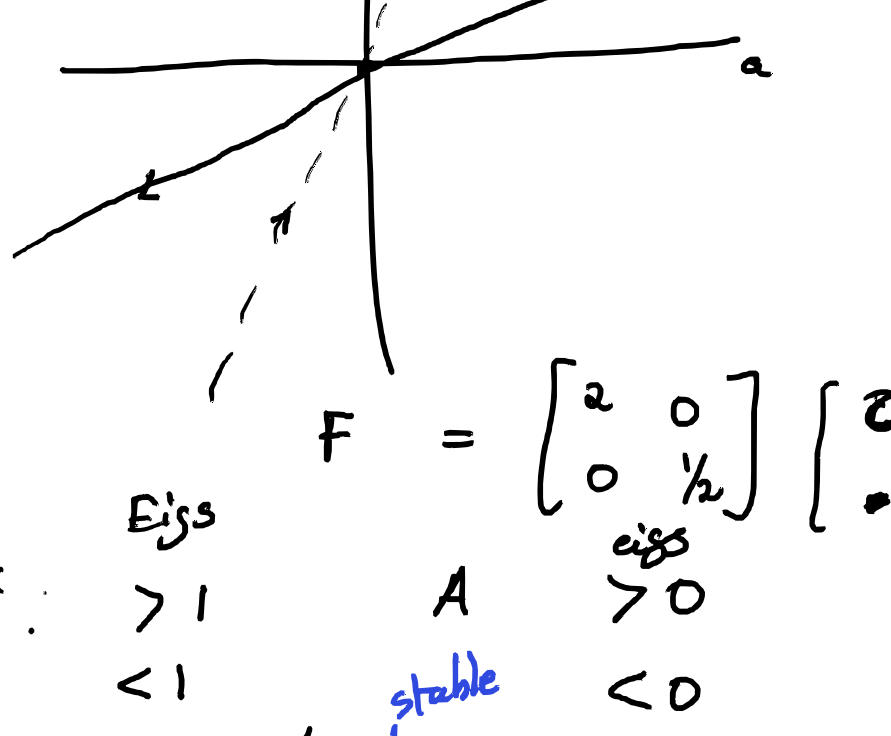
Phase portrait



$$x = [a, b] \in \mathbb{R}^2$$

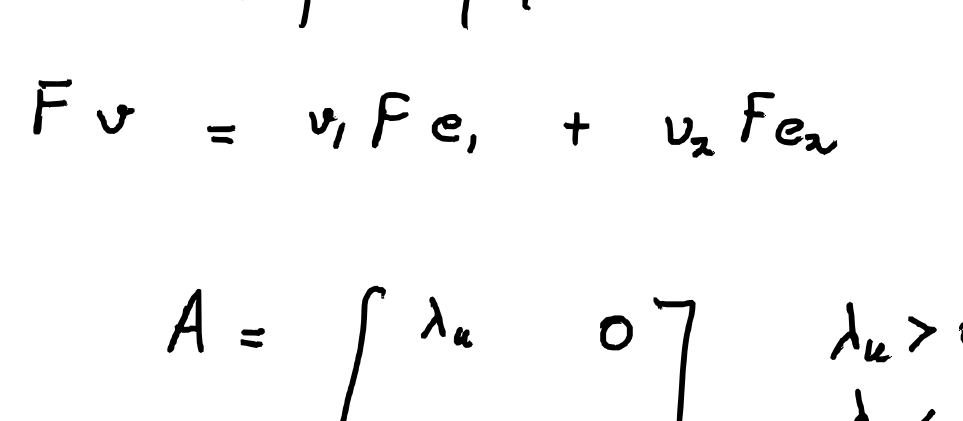
$$\frac{d F^t x}{dt} = 0 \quad (0 \text{ is a fixed point})$$

A has negative eigenvalues F has stable eigenvalues Abs value of eigenvalues of $F < 1$



$$F = \begin{bmatrix} 2 & 0 \\ 0 & 1/2 \end{bmatrix} \begin{bmatrix} 0 \\ c \end{bmatrix}$$

Eigs $F: >1 <1$ $A: >0 <0$



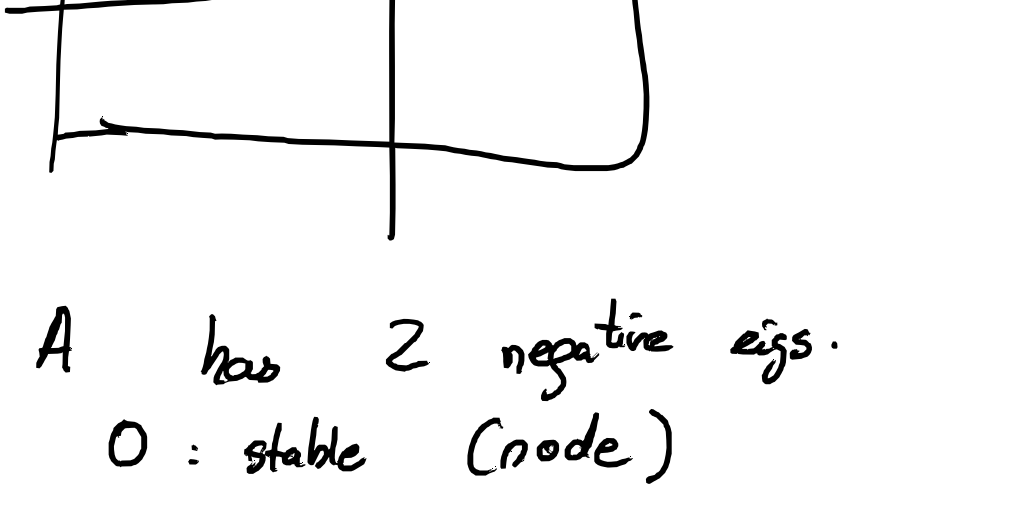
$$F v = v_1 F e_1 + v_2 F e_2$$

$$A = \begin{bmatrix} \lambda_u & 0 \\ 0 & \lambda_s \end{bmatrix} \quad \begin{matrix} \lambda_u > 0 \\ \lambda_s < 0 \end{matrix}$$

Invariant curves: $\frac{a^{\lambda_s}}{b^{\lambda_u}} = \text{const}$

$$\frac{d}{dt} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \lambda_u & 0 \\ 0 & \lambda_s \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$\frac{d}{dt} \left(\frac{a^{\lambda_s}}{b^{\lambda_u}} \right) = 0$$



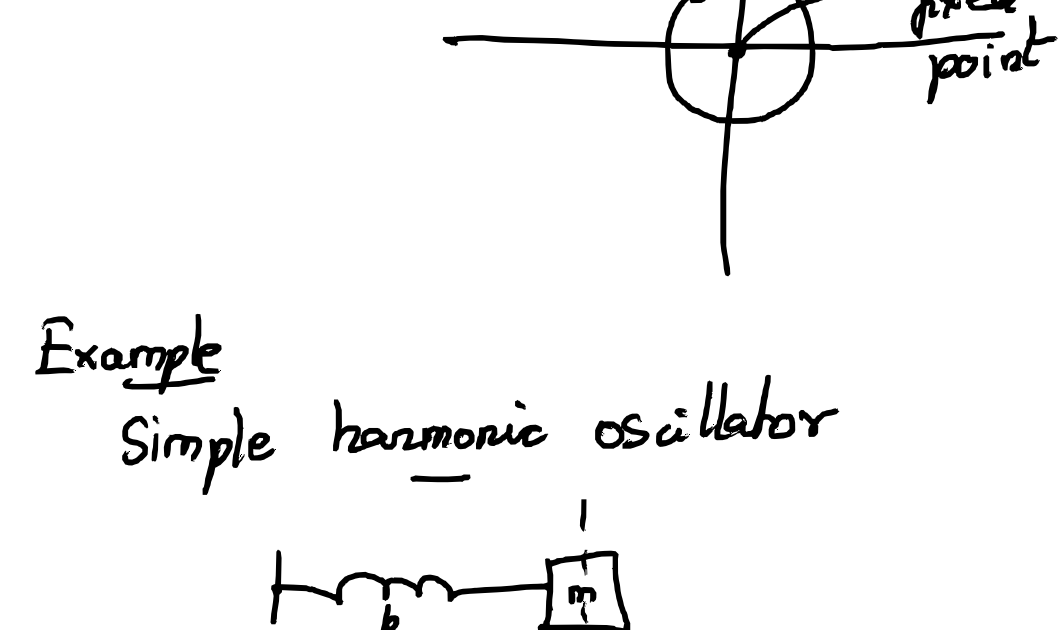
A has 2 negative eigs. O : stable (node)

A has 1 tr 1 -ve eig O : saddle point

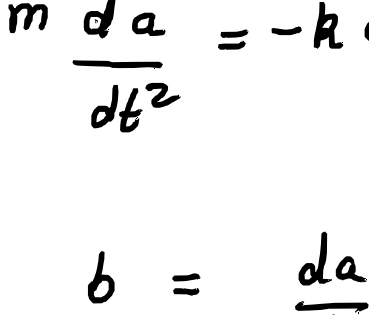
A has complex eigenvalues

$\gamma + i c_2$ \hookrightarrow spirals $c_1 \neq 0$

$c_1 = 0$



Example Simple harmonic oscillator



$$m \frac{d^2 a}{dt^2} = -k a$$

$$b = \frac{da}{dt}$$

$$m \frac{db}{dt} = -k a$$

$$\frac{d}{dt} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -k/m & 0 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$\frac{1}{2} k a^2 + \frac{1}{2} m b^2 = \text{const}$$

Linear dynamics in \mathbb{R}^d

$$x_{t+1} = F x_t \quad (F = e^A)$$

Define $\lambda \in (0, 1)$ $C > 0$

stable subspace

$$E^s = \left\{ v \in \mathbb{R}^d : \|F^t v\| \leq C \lambda^t \|v\| \quad \forall t \in \mathbb{Z}^+ \right\}$$

unstable subspace

$$E^u = \left\{ v \in \mathbb{R}^d : \|F^t v\| \leq C \lambda^{|t|} \|v\| \quad \forall t \in \mathbb{Z}^- \right\}$$

neutral / center subspace

$$E^c \oplus E^s = E^{cs} = \left\{ v \in \mathbb{R}^d : \text{sub-expon. growth/decay} \right\}$$

for any $v \in E^c$,

$$\lim_{t \rightarrow \infty} \frac{\|F^t v\|}{\|v\| \|t^k\|} = c \quad \text{for some } k$$

$$\mathbb{R}^d = E^s \oplus E^u \oplus E^c$$

Alternative characterization of (un)stable subspaces

$$E^s = \left\{ v \in \mathbb{R}^d : v \in \ker(F - \lambda I)^m \text{ for some } |\lambda| < 1, m \in \mathbb{N} \right\}$$

$$E^u = \left\{ v \in \mathbb{R}^d : v \in \ker(F - \lambda I)^m \text{ for some } |\lambda| > 1, m \in \mathbb{N} \right\}$$

$$E^c = \left\{ v \in \mathbb{R}^d : v \in \ker(F - \lambda I)^m \text{ for some } |\lambda| = 1, m \in \mathbb{N} \right\}$$

$$E^c = \{0 \in \mathbb{R}^d\} : F \text{ is linear hyperbolic}$$

$\rightarrow F$ is not diagonalizable

• eigenvectors are not linearly independent

• algebraic multiplicity $>$ geometric multiplicity for some eigenvalue

(Eigenvalues are continuous function on matrices)

Ex: how small are the set of defective matrices?

\rightarrow Jordan canonical form

$$\ker((F - \lambda I)^m) \quad \text{for some } m \in \mathbb{N}.$$

Generalized eigenvectors

$$J = P^{-1} F P$$

$$\begin{bmatrix} \lambda & & \\ & \mu & \\ & & \mu \end{bmatrix}$$

$$x(t) = t^k x(0)$$

$$x(t+1) = (t+1)^k x(0)$$

$$= \frac{(t+1)^k}{t^k} x(t)$$