Perceptron under linear Binary classification separability +++++ _=== Margin: min distance of training points from Separating hyperplane w.x+b=0 1W.P +61 $d(\rho, H) =$ $\|\omega\|$ margin = $\min_{i} \frac{y_i(\omega \cdot x_i + b)}{\|\omega\|}$ + + + + + _____ $x_i \in \mathbb{R}^d$ $y_i = \pm 1$ $[n] = \{1, ..., n\}$ Assumption on data for theorem on Perception convergence: · linearly separability: I P>0 s.t. $\beta := \min_{i \in [n]} \frac{y_i \omega \cdot x_i}{\|\omega\|}$ for some we Rd bounded data: R > 0 ¥ i. $||z_i|| < R$ (ω_i) if $x_i \notin I$ makes at most $\frac{R^2}{\rho^2}$ updates. Proof: Mohin et al 2018 Interlude: Classifier returned by the Perception algorithm: $h(x) = \xi g_n(\omega_T \cdot x)$ $= sgn\left(\left(\sum_{i \in \underline{T}} \gamma g_i x_i\right) \cdot x\right)$ WLOh: Wo=O∈ Rd linear comb. of incorrectly classified points sgn (\Set ? \diamondiamond dot product Dot product algorithms can be lifted to as a higher-dimensional or infinite-dimensional spaces (kernel methods) $x \to \bar{\phi}(x) \in \mathbb{R}^{\nu}$ D>>d P(x) ∈ H function (Hilbert space) Jeatenes if $\langle \underline{\Phi}(x), \underline{\Phi}(x') \rangle = \chi(x,x')$ (bernet /similarity
measure) $h(x) = \operatorname{Sgn}\left(\sum_{i \in T} \eta y_i \langle \Phi(x_i), \overline{\Phi}(x_i) \rangle\right)$ = 300 (& 2 yi x(2i,2)) Example (XOR) | | 2") <u>—②</u> (1,-1) $x^{(2)}(x_i) = 1$ $x_{(i)}(x_i) = 1$ $x^{(2)}(x_3) = -1$ $\begin{bmatrix} x^{(1)}^{2} \\ x^{(2)}^{2} \\ x^{(2)}^{2} \end{bmatrix} \cdot \begin{bmatrix} x^{(1)}(x^{1}) \\ x^{(2)}^{2}(x^{1}) \end{bmatrix} = \begin{bmatrix} x^{(1)}(x^{1}) \\ x^{(2)}(x^{1}) \end{bmatrix}$ $\underline{\Phi}(\mathbf{z}) \cdot \underline{\Phi}(\mathbf{z}')$ = <<u>\$</u>[*), **\$**(*')} $x^{(1)^{2}}(x) x^{(1)^{2}(2^{1})} + x^{(2)^{2}(2)} x^{(2)^{2}(2^{1})}$ + 2 $x^{(1)}(x) x^{(2)}(x)$ x(1)(x1) x(2)(x1)) (x. z)2 z, z e iRd $\chi(z,z')=(z\cdot z'+b)^m$ Can be written as a dot product of features D = 6, m = 2 (dim of parture space) $b \neq 0$, d = a, $\left(x \cdot x^{1} + b\right)^{2} = \left(\sum_{i=1}^{d} x^{(i)}(x) x^{(i)}(x^{1}) + b\right)^{2}$ $\begin{array}{c} \left(\begin{array}{c} x^{(1)^{2}} \\ x^{(2)^{2}} \end{array} \right) & D=6 \text{ dim} \\ \sqrt{2} x^{(1)} x^{(2)} \\ \sqrt{6} x^{(1)} \times \sqrt{2} \\ \sqrt{6} \end{array}$ $\begin{array}{c} \left(\begin{array}{c} x^{(1)^{2}} \\ \sqrt{6} \end{array} \right) \times \sqrt{2} \\ \sqrt{6} \end{array}$ $\left(x^{(1)}(x)x^{(2)}(x^{(2)}) + x^{(2)}(x)x^{(2)}(x^{(1)}) + b^{2}$ $= \frac{2}{2} x^{(i)}(x) x^{(i)}(x^{(i)}) + b^2 + \frac{2}{2} abx^{(i)}(x) x^{(i)}(x^{(i)})$ $= \frac{2}{2} x^{(i)}(x) x^{(i)}(x^{(i)}) + b^2 + \frac{2}{2} abx^{(i)}(x) x^{(i)}(x^{(i)})$ $= \underline{\mathcal{F}}(x) \cdot \underline{\mathcal{F}}(x^{1}).$ To evaluate $\Phi(x)$. $\Phi(x')$ (ahich consisto of nontinear functions), he only x(x, x') $\mathcal{H}(z,z') = \mathcal{I}(z) \cdot \mathcal{I}(z')$ $= \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ \sqrt{b} \end{bmatrix} \cdot \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ \sqrt{b} \end{bmatrix}$ $= \left(\frac{\mathbf{z} \cdot \mathbf{x}' + \mathbf{b}}{\mathbf{x}'}\right)^m$ Perception: $h(x) = sgn(\sum y_i x(x_i, x))$ Kernel evaluation (=) inner product on feature space · does not regime Es computationly expensive explicit 3 peatures · have to know $\omega^{(1)}\chi^{(1)}(x) + \omega^{(2)}\chi^{(2)}(x) + b$ $\underline{x^{(2)}(x)} = -\underline{\omega^{(1)}}_{\omega^{(2)}} \underline{x^{(1)}(x)}_{\omega} - b$