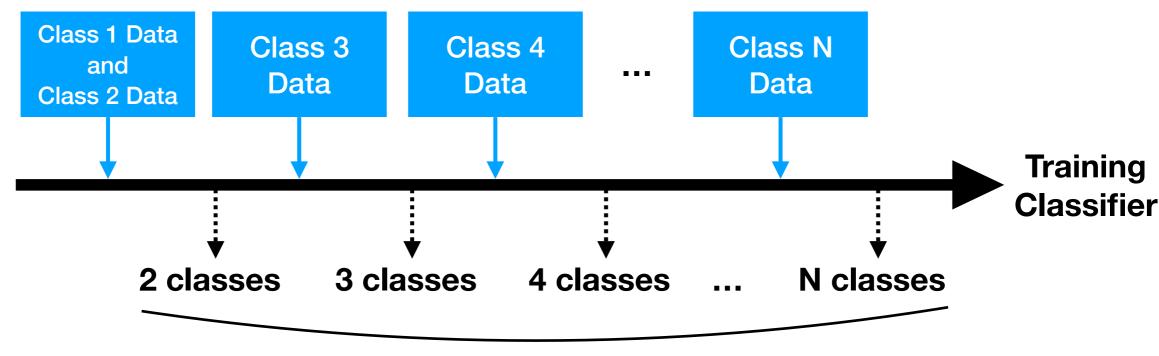
CRIL: Compact Representation for Incremental Learning

Presented by Youngki Hong, Seongmin Lee, Minsuk Choi

Contents

- Introduction
 - Incremental Learning
 - iCaRL
 - CRIL
- Methods
 - Class-Increamental Classifier Learning
 - Nearest-Mean-of-Exemplars Classification
 - Exemplar Management
 - Representation Learning
 - With Naive Linear Classifier
 - With Variational Auto Encoder
- Experiments
 - Environments
 - Results
- Conclusion

Incremental Learning



The number of classes available to classify

 Class-incremental learning is the scheme of learning that is able to learn about new classes, when the training data for new classes is available.

Incremental Learning

- There are 3 properties of an algorithm to qualify as classincremental.
 - i) Trainability for a class-incremental data stream.
 - ii) Competitive performance as a multi-class classifier for the classes observed so far, at any time during the training.
 - iii) Bounded computational requirements and memory footprint.

Incremental Learning

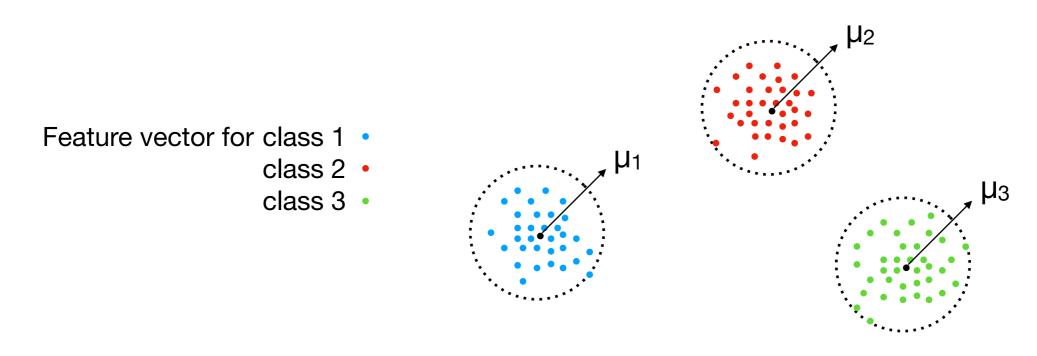
- The most of the artificial object recognition systems can only be trained in a batch setting where all object classes are known.
- Training the classifiers with class-incremental data streams incurs quick deterioration of accuracy, which is known as catastrophic forgetting.
- Existing solutions are limited to the case with the fixed data representation. They cannot learn classifiers and feature representations simultaneously.

iCaRL

- iCaRL, incremental classifier and representation learning, provides a practical strategy for simultaneous learning of classifiers and a feature representation in the classincremental setting.
- There are 3 main components.
 - Classification by a nearest-mean-of-exemplars rule.
 - Prioritized exemplar selection based on examples from observed classes.
 - Representation learning using knowledge distillation and prototype rehearsal.
- iCaRL uses naive linear classifier for representation learning.

CRIL

- We presents compact representation for incremental learning,
 CRIL, using variational auto encoder, VAE, for representation learning.
- With VAE, the network is trained to have the output features that follow the gaussian distribution with given mean μ_i and variance σ_i^2 for class i.
- The network is expected to generate the output feature vectors which are more compact within each class and distinctive between classes.



Class-Incremental Classifier Learning

Classification

- Classifying by nearest-mean-of-exemplars algorithm.
- Using the sets of exemplar images for each class observed so far: if there are 5 observed classes so far, there are 5 exemplar sets.

Training

- Using batches of classes observed so far.
- Updating on representation, exemplar set occurs when the data with new classes becomes available.

Class-Incremental Classifier Learning

Architecture

- In case with linear classifier, using CNN for feature extractor and single classification layer to classify in classes observed so far for training.
- In case with **VAE**, using encoder layer to generate the output features following certain gaussian distributions for each classes observed so far for training.
- Using network only for representation learning.

Resource Usage

- Considering finite number of classes.
- Using limited number of exemplar to limit the resource.

Nearest-Mean-of-Exemplars Classification

 Predict a label y* of the input image x by compare the distances between the feature vector of the image x and the average feature vector of all exemplars for a class y.

$$y^* = \underset{y=1,...,t}{\operatorname{argmin}} \|\varphi(x) - \mu_y\|$$

- x: an input image
- µ_y: the average feature vector for all exemplars for a class y
- y*: a label for a image x
- $\varphi(x)$: a feature vector of x

Exemplar Management

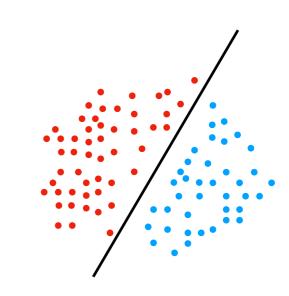
- Update exemplar set when new classes become available.
- For K exemplars, divide them into number of classes.
 - If there are t observed classes so far, $\frac{K}{t}$ exemplars for each class.
- Select exemplars for new classes: add examples which causes best approximation of the average feature vector over all training examples.
- Reduce exemplars from old classes: discard exemplars from the end of the set of each class.

Representation Learning

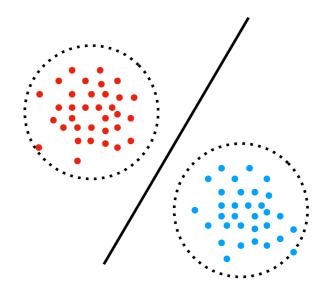
- When new classes are available, the feature extractor is updated in following three steps.
 - Construct an augmented training set with the current training examples and the stored exemplars.
 - Evaluate current network for each example for old classes.
 - Update the network parameters by minimizing a loss function with a classification loss for new classes and a distillation loss for previous classes.

Representation Learning

 With naive linear classifier, the network is trained to generate the output feature vectors to be linearly separable.



 With variational auto encoder, the network is trained to generate the output feature vectors following the distinctive gaussian distribution for each of the observed class.



Experiments

- Using MNIST and CIFAR-100 as data sets.
- iCaRL is constructed with ResNet; CRIL is constructed with MLP.
- Experiment 1
 - Train iCaRL network with K=100, 200, 500, 1000 exemplars.
 - To evaluate the performance changing as the number of exemplar changing.

Experiments

- Experiment 2
 - Train CRIL with K=100, 200, 500, 1000 exemplars.
 - Give μ_i and variance σ_i^2 for class i as following.

$$\mu_i = [v_j], \ \mu_i \in \mathbb{R}^n, \ v_j = \begin{cases} a & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$
 for $i = 1, 2, ..., n$,

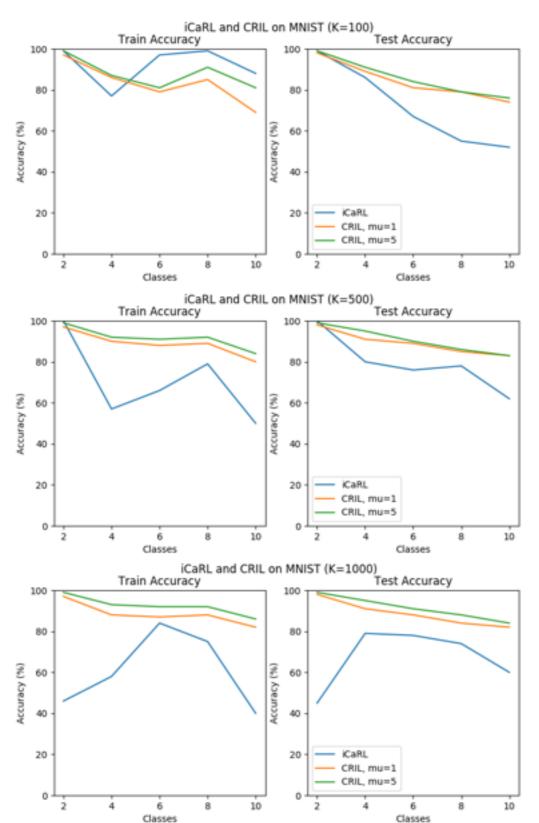
$$\sigma_i = I, \ \sigma_i \in \mathbb{R}^n, \ i = 1, 2, ..., n,$$

where a = 1, 5, n = the number of the observed classes

Experiments

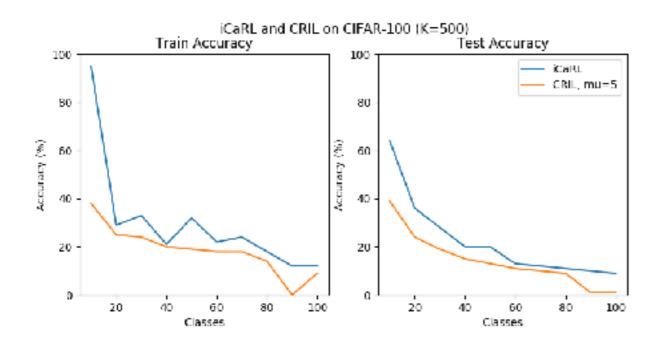
- Experiment 3 (will be on report)
 - Compare the distribution of the output feature vectors from previous experiments by t-sne visualization.
 - To compare the compactness of the output feature vectors for iCaRL and CRIL.

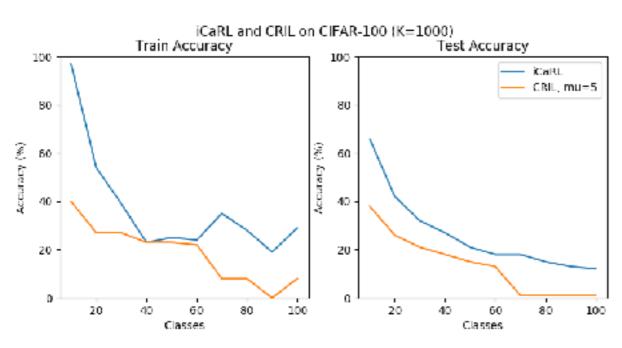
Results: MNIST



- CRIL outperformed over 20% in average accuracy to iCaRL for all sizes of exemplar.
- The performance tended to decrease for the smaller number of exemplars both in iCaRL and CRIL.

Results: CIFAR-100





- Both iCaRL and CRIL had poor performances, where the average accuracies were lower then 21%.
- iCaRL outperformed about 10% in average accuracy to CRIL for both K=500 and 1000.
- CRIL has pure MLP architecture, so the performance can be improved with CNN architecture.

Summary

- CRIL outperformed about 21% in average accuracy to iCaRL on MNIST dataset for all sizes of exemplars.
- CRIL had competitive performance with small size of exemplar, which was 23% higher than iCaRL.
 - CRIL: 75% test accuracy for 10 classes with K=100
 - iCaRL: 52% test accuracy for 10 classes with K=100
- iCaRL outperformed about 10% in average accuracy to CRIL on CIFAR dataset for all sizes of exemplars.
 - The performance of CRIL can be improved by adding the convolutional layers.

Conclusion

- CRIL showed competitive performance in classincremental learning, which outperformed iCaRL on MNIST dataset.
- For CIFAR-100, CNN architecture can be added for CRIL for further comparison.
- The compactness of the output feature vectors will be analyzed with t-sne on the final report.