



# Extrapolating Coverage Rate in Greybox Fuzzing

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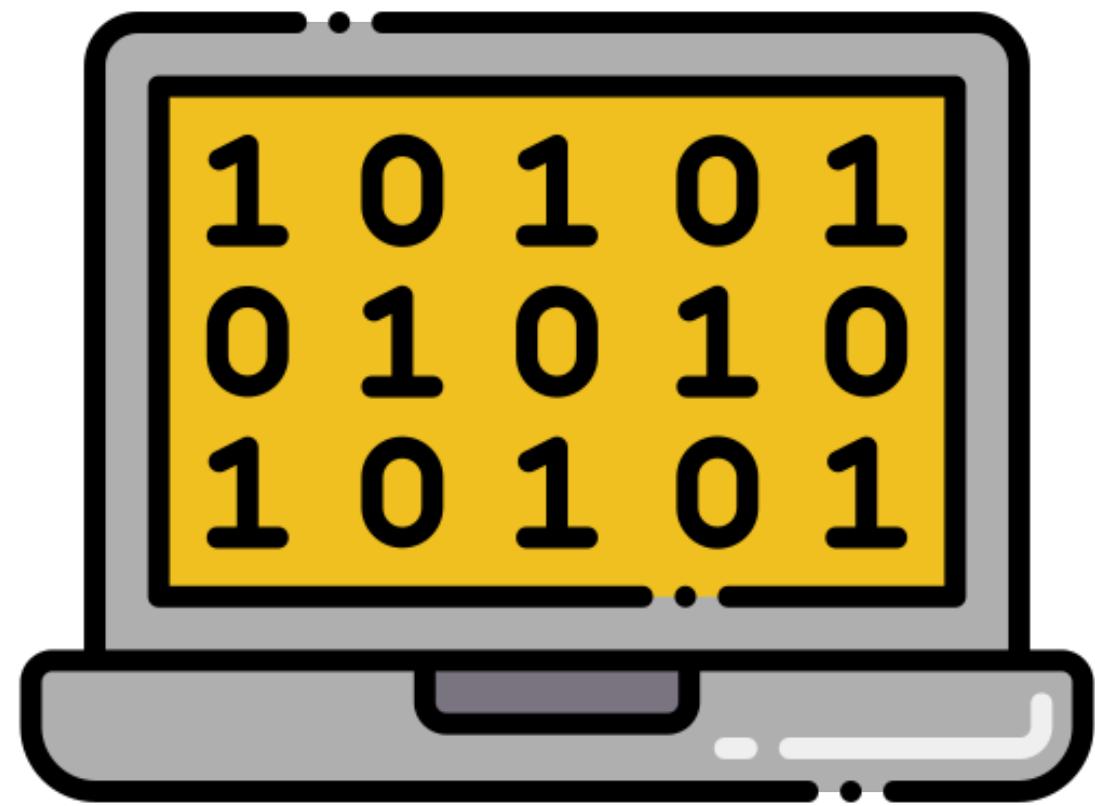
Monash University

Marcel Böhme

MPI-SP

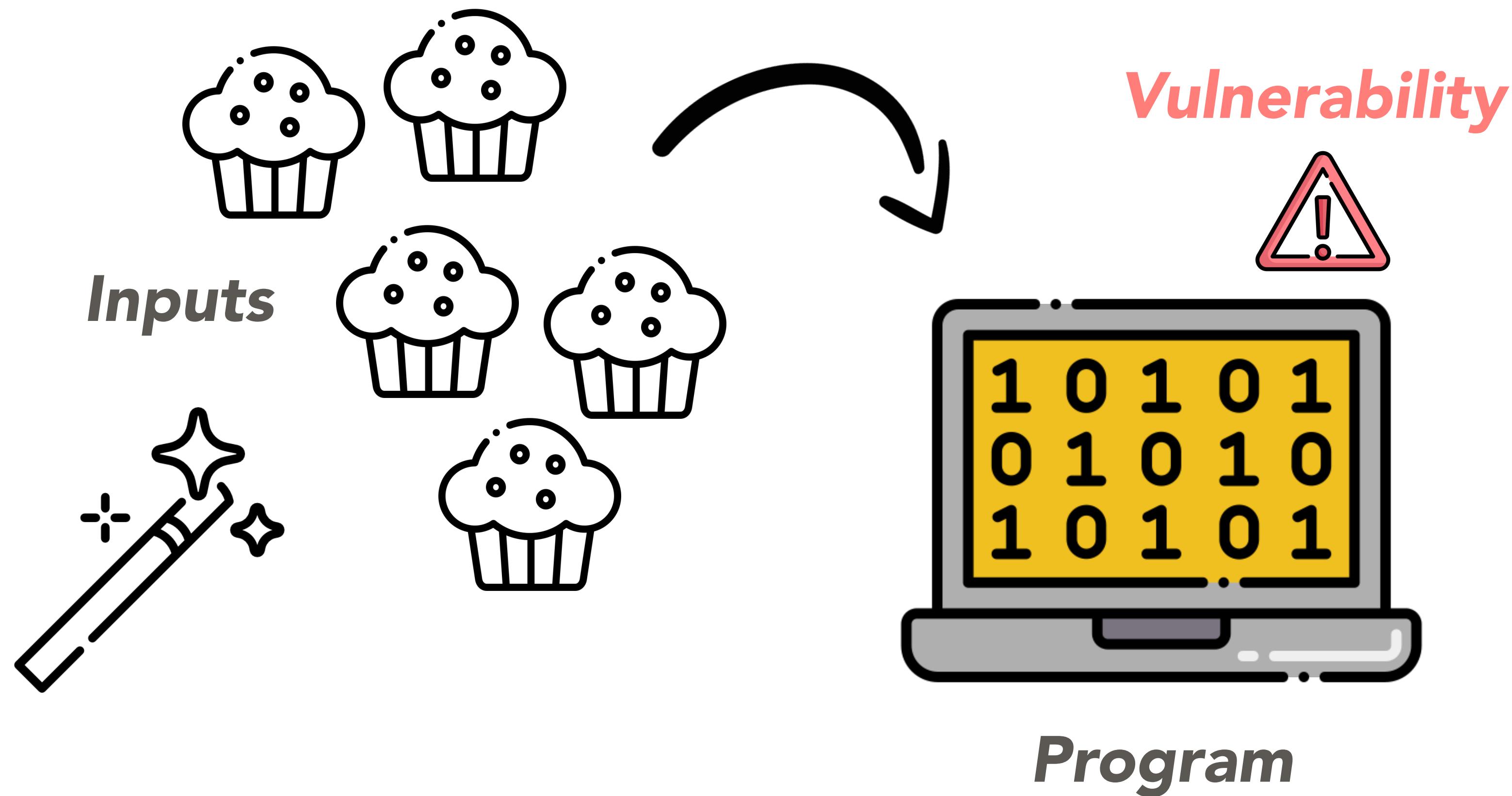
# Fuzzing

*Vulnerability*

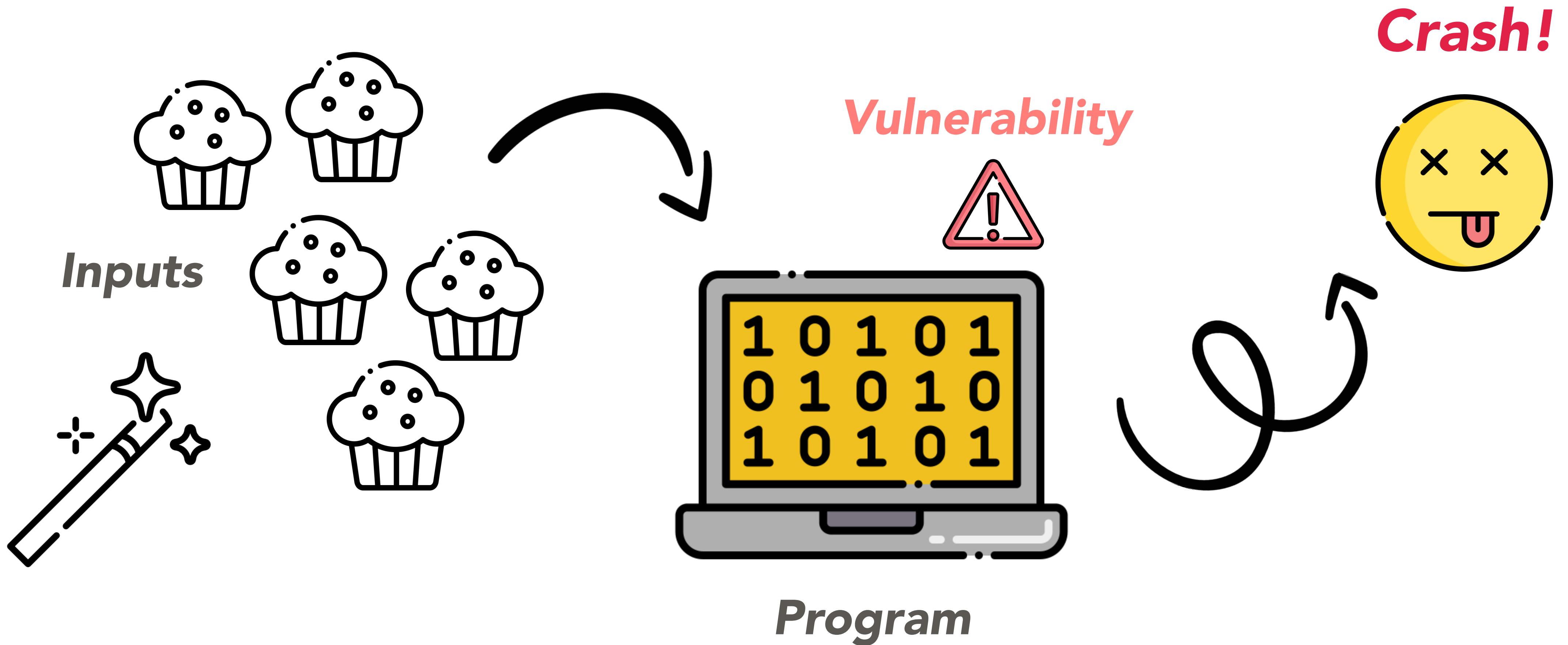


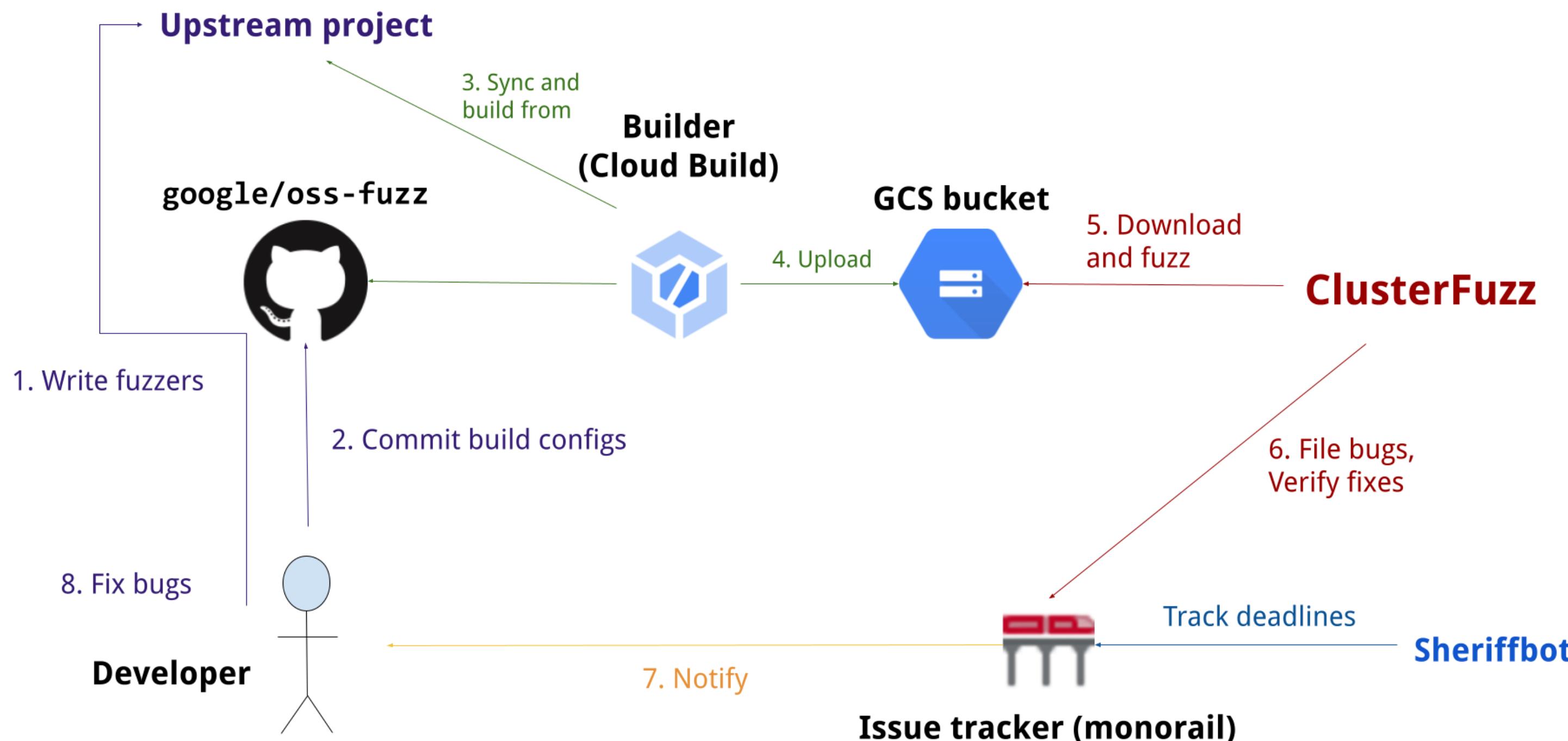
*Program*

# Fuzzing



# Fuzzing





## OSS-Fuzz

- 10,000 vulnerabilities and 36,000 bugs across 1,000 open-source projects. (~August 2023)

# OSS-FUZZ: Continuous Fuzzing for Open Source Software

★ FuzzSlice: Pruning False Positives in Static Analysis Warnings through Function-Level Fuzzing

Manual confirmation of static analysis reports is a time-consuming task due to the high number of false positives among them. Fuzzing techniques can help by automatically fuzzing the whole project to reach all static analysis warnings in a reasonable amount of time to increase code coverage linearly. Therefore, it is important to understand the nature of false positives among static analysis warnings. Unlike dynamic analysis tools, which typically require end-to-end fuzzing to find bugs, static analysis tools often provide detailed reports at the function level. The key insight that we have learned is that most false positives occur at the function level in a given time budget.

## ★ FuzzInMem: Fuzzing Programs via In-memory Structures

In recent years, coverage-based greybox fuzzing has proven to be an effective technique for discovering software vulnerabilities. The availability of American Fuzzy Loop (AFL) has facilitated numerous advances in overcoming challenges in fuzzing. However, the issue of mutating complex file formats, such as PDF, remains unresolved due to strict constraints. Existing fuzzers often produce mutants that fail to parse by applications, limited by bit/byte mutations performed on input files. Our observation is that most in-memory representations of file formats are simple, and well-designed applications have built-in printer functions to emit these structures as files. Thus, we propose a new technique that mutates the in-memory structures of inputs and utilizes printer functions to regenerate mutated

## ★ Are We There Yet? Unraveling the State-of-the-Art Smart Contract Fuzzers

Given the growing importance of smart contracts in various applications, ensuring their security and reliability is critical. Fuzzing, an effective vulnerability detection technique, has recently been widely applied to smart contracts. Despite numerous studies, a systematic investigation of smart contract fuzzing techniques remains lacking. In this experience paper, we fill this gap by: 1) providing a comprehensive review of current research in contract fuzzing, and 2) conducting an in-depth empirical study to evaluate state-of-the-art contract fuzzers' usability. To guarantee a fair evaluation, we employ a carefully-labeled benchmark and introduce a set of pragmatic performance metrics, evaluating fuzzers from five complementary perspectives. Based on our findings, we provide direction for the future research and development of contract fuzzers.

vulnerability of 2019. However, there are few automated tools—either in research or industry—to effectively find and remediate such issues. This is unsurprising as the problem lacks an explicit test oracle: the vulnerability does not manifest through explicit abnormal behaviours (e.g., program crashes or memory access violations).

## ★ Crossover in Parametric Fuzzing

Parametric fuzzing combines evolutionary and generator-based fuzzing to create structured test inputs that exercise unique execution behaviors. Parametric fuzzers internally represent inputs as bit strings referred to as “parameter sequences”. Interesting parameter sequences are saved by the fuzzer and perturbed to create new inputs without the need for type-specific operators. However, existing work on parametric fuzzing only uses mutation operators, which modify a single input; it does not incorporate crossover, an evolutionary operator that blends multiple inputs together. Crossover operators aim to combine advantageous traits from multiple inputs. However, the nature of parametric fuzzing limits the effectiveness of traditional crossover operators. In this paper, we propose linked crossover, an approach for using dynamic execution information to identify and exchange analogous portions of parameter sequences. We created an implementation of linked crossover for Java and evaluated linked crossover’s ability to preserve advantageous traits. We also evaluated linked crossover’s impact on fuzzer performance on seven real-world Java projects and found that linked crossover consistently performed as well as or better than three state-of-the-art parametric fuzzers and two other forms of crossover on both long and short fuzzing campaigns.

Fuzzing has achieved tremendous success in finding bugs in systems (SUTs) that take in programming or non-programming inputs. Systems with accessible APIs, are especially suitable for fuzzing. Fuzzers for such systems often target the same language as the SUT. Moreover, the fuzzer can hardly reveal bugs related to the language. This is because it makes sense that it can target many different languages. To leverage large language models (LLMs), we propose to generate realistic inputs for any practical system. Specifically, ECFuzz creates LLM prompts that are well-suited for the SUT. The generated prompts are then used to find configuration-induced bugs. However, they do not fully consider the complexity of large-scale systems, resulting in low testing effectiveness. In this paper, we propose ECFuzz, an effective configuration fuzzer for large-scale systems. Our core approach consists of (i) Multi-dimensional configuration generation strategy. ECFuzz first designs different mutation strategies according to different dependencies and selects multiple configuration parameters from the candidate configuration parameters to effectively generate configuration parameters; (ii) Unit-testing-oriented configuration validation strategy. ECFuzz introduces unit testing into configuration testing techniques to filter out configuration parameters that are unlikely to yield errors before executing system testing, and effectively validate generated configuration parameters. We have conducted extensive experiments in real-world large-scale systems including HCommon, HDFS, HBase, ZooKeeper and Alluxio. Our evaluation shows that ECFuzz is effective in finding configuration-induced crash bugs. Compared with the state-of-the-art configuration testing tools including ConfTest, ConfErr and ConfDiagDetector, ECFuzz finds 60.3–67 more unexpected failures when the same 1000 testcases are injected into the system with an increase of 1.87x–2.63x. Moreover, ECFuzz has exposed 14 previously unknown bugs, and 5 of them have been confirmed.

and Python) as inputs. The evaluation shows, across all six languages, that universal fuzzing achieves higher coverage than existing, language-specific fuzzers. Furthermore, Fuzz4All has identified 76 bugs in widely used systems, such as GCC, Clang, Z3, CVC5, OpenJDK, and the Qiskit quantum computing platform, with 47 bugs already confirmed by developers as previously unknown.



# Fuzzing workshop 2024



Co-located with ISSTA'24 @ Vienna, Austria

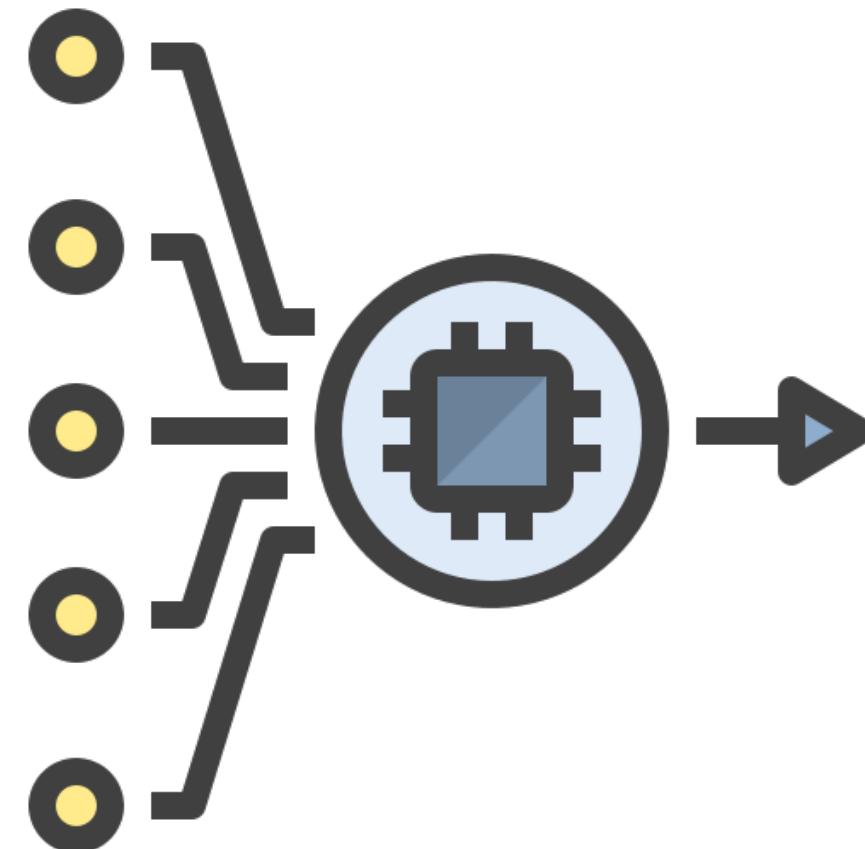


- How can we make the fuzzer smarter at generating useful inputs?

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- What/Where else can we apply the fuzzing?

# Q. When should we stop the fuzzing campaign?

*Every possible Input?*



*Well, it's simply infeasible...*

*100% Coverage?*



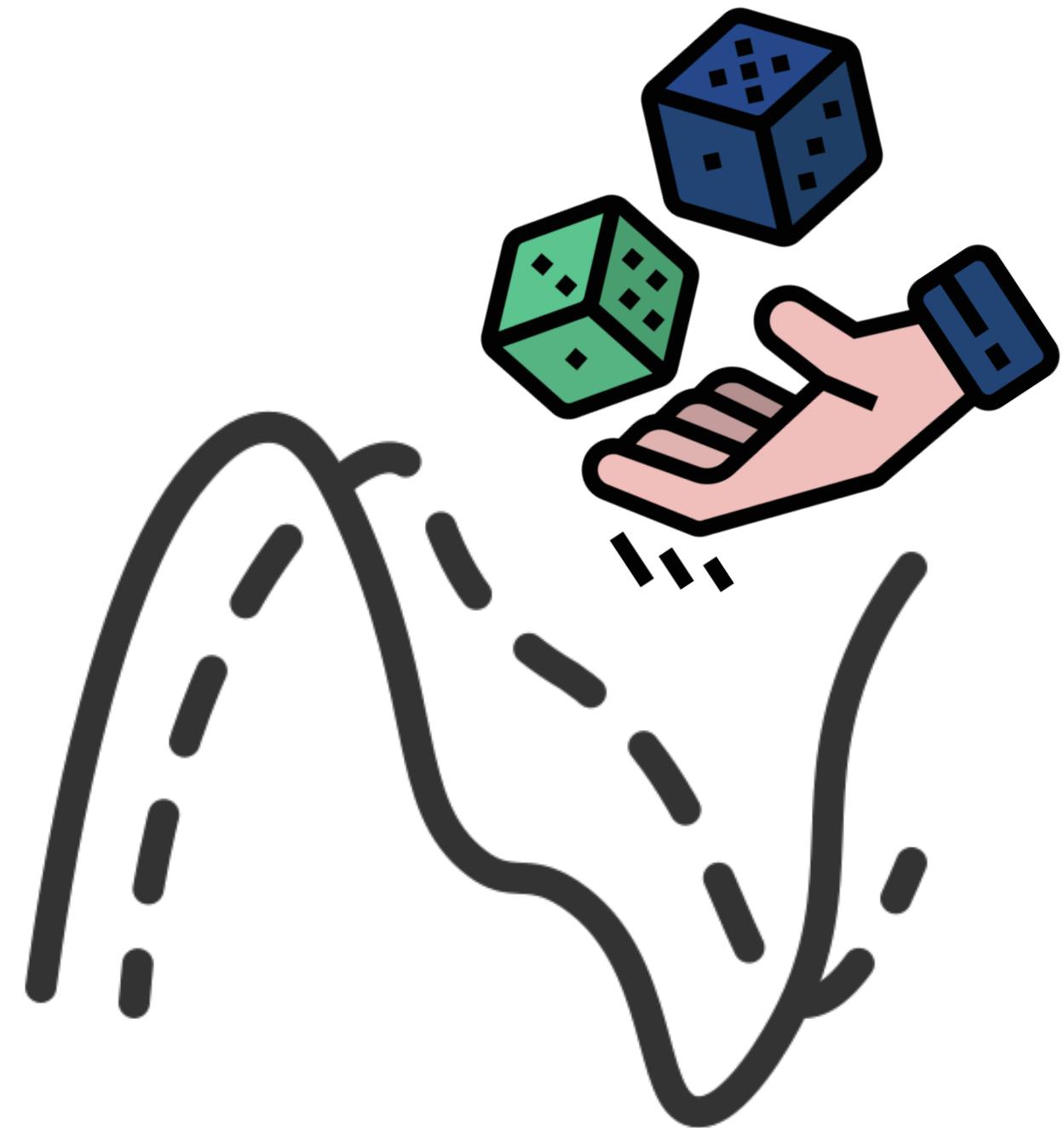
*Which level? Line? Method? Class?  
What about unreachable elements?*

*More importantly,*

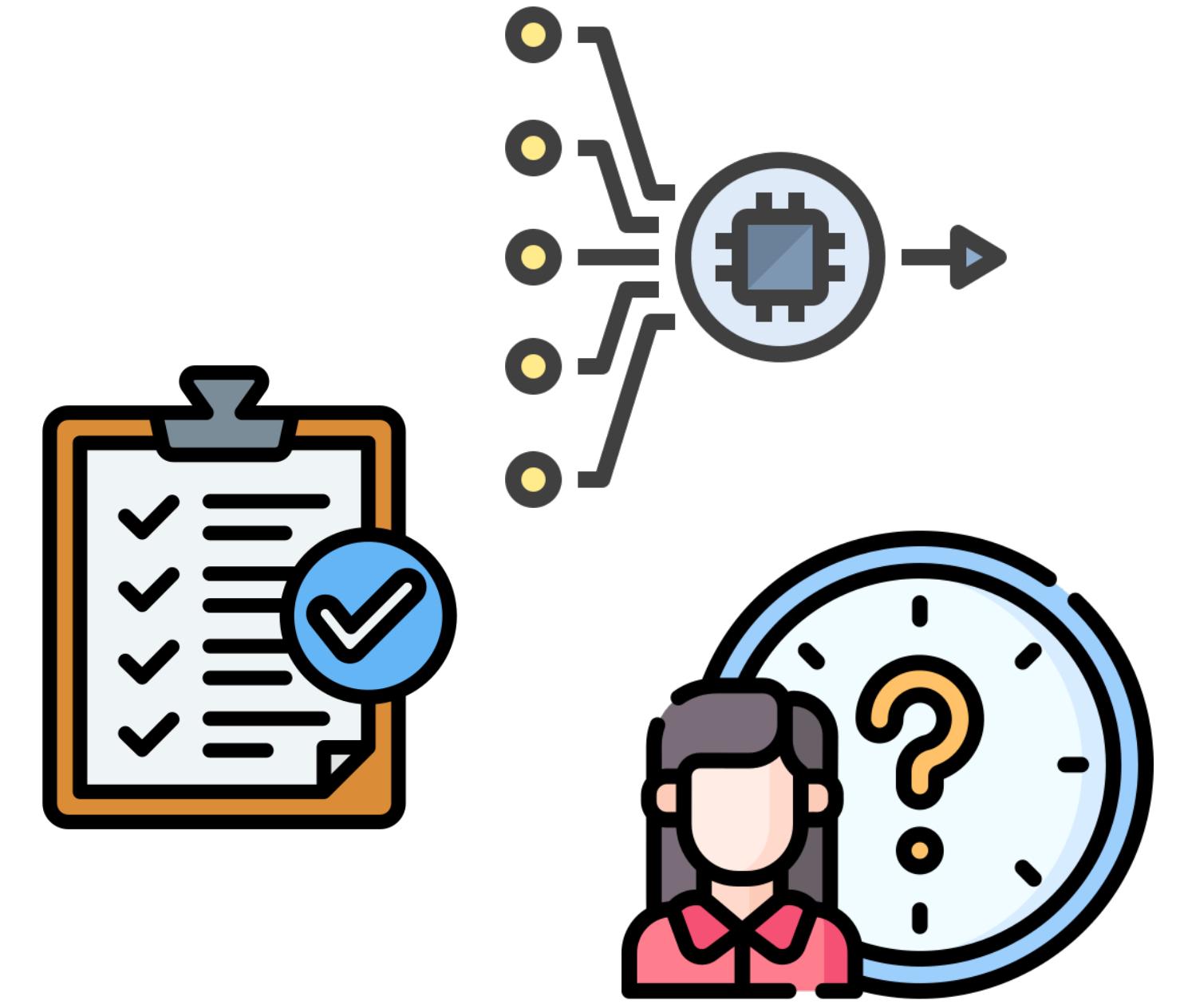


*Even if we have some criteria,  
how much of a resource do we  
need to use more?*

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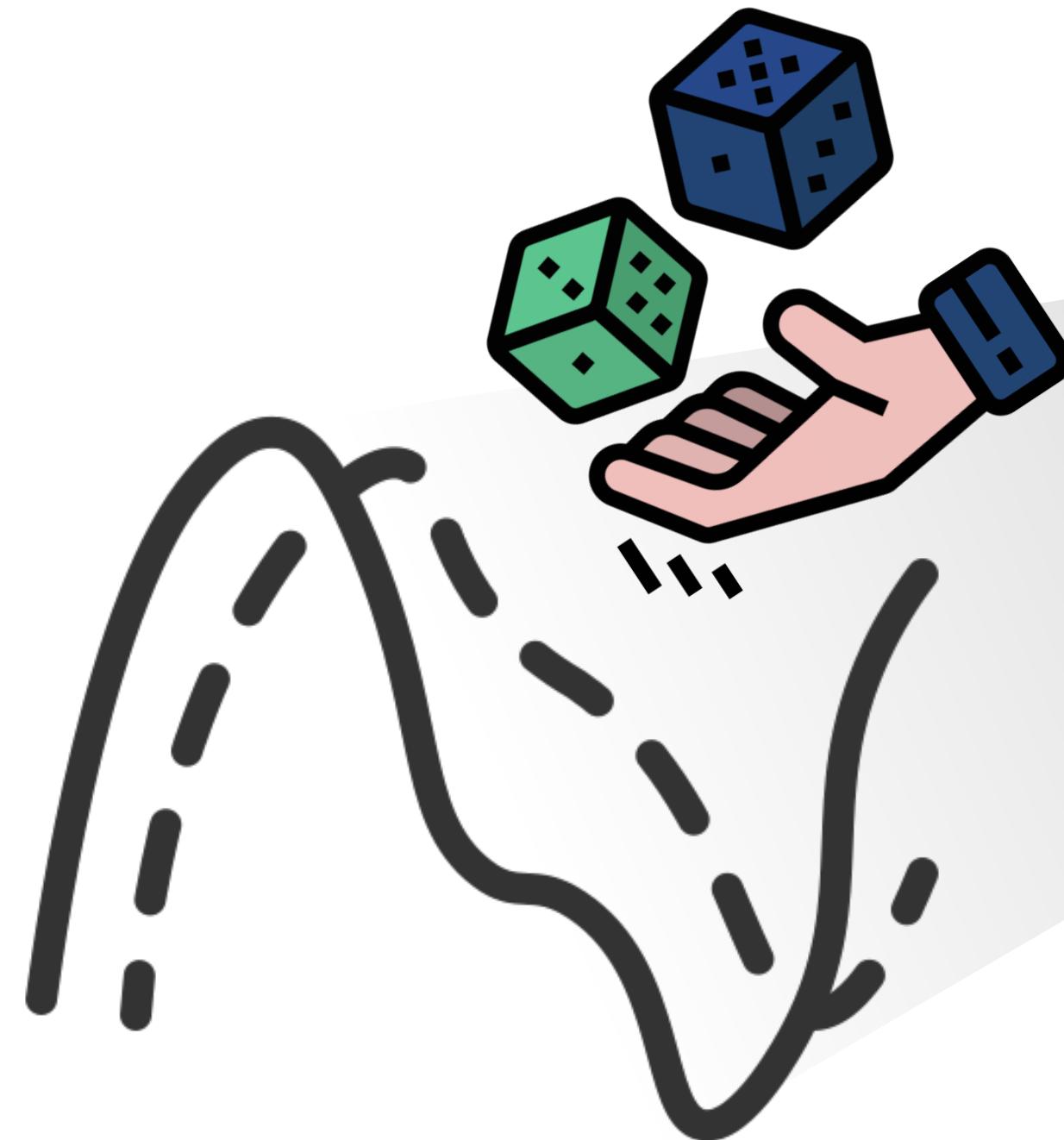


**Stochastic Process**

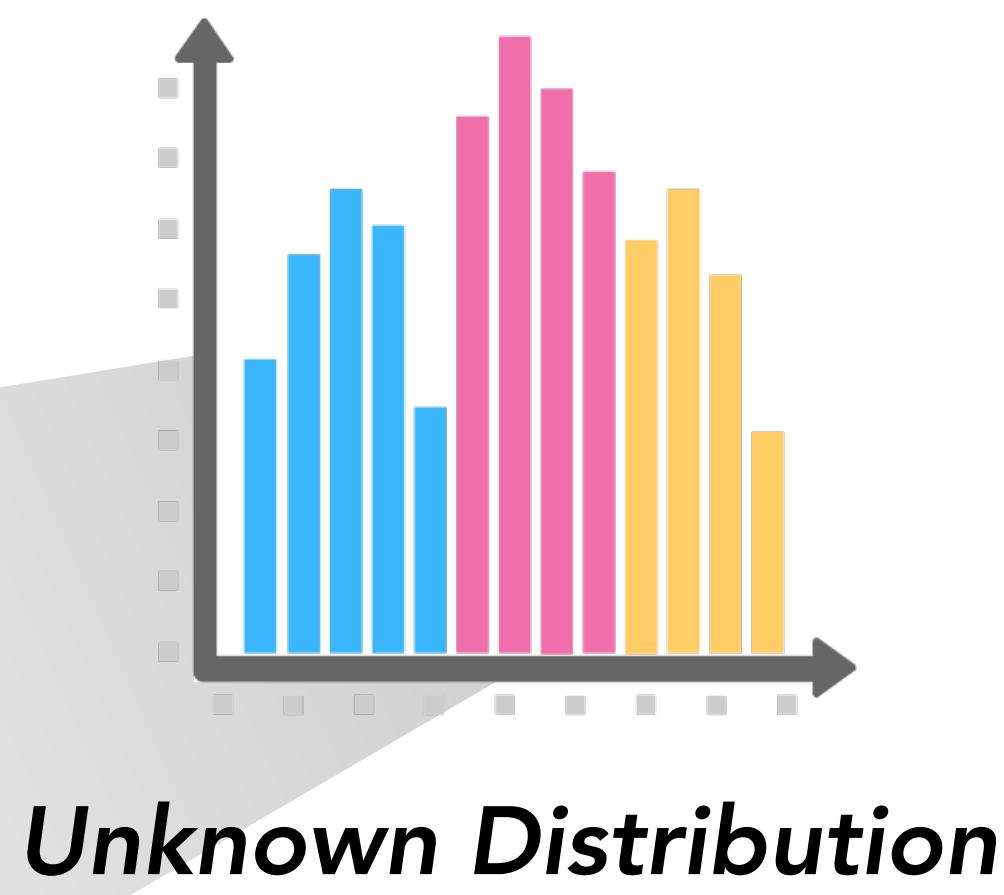


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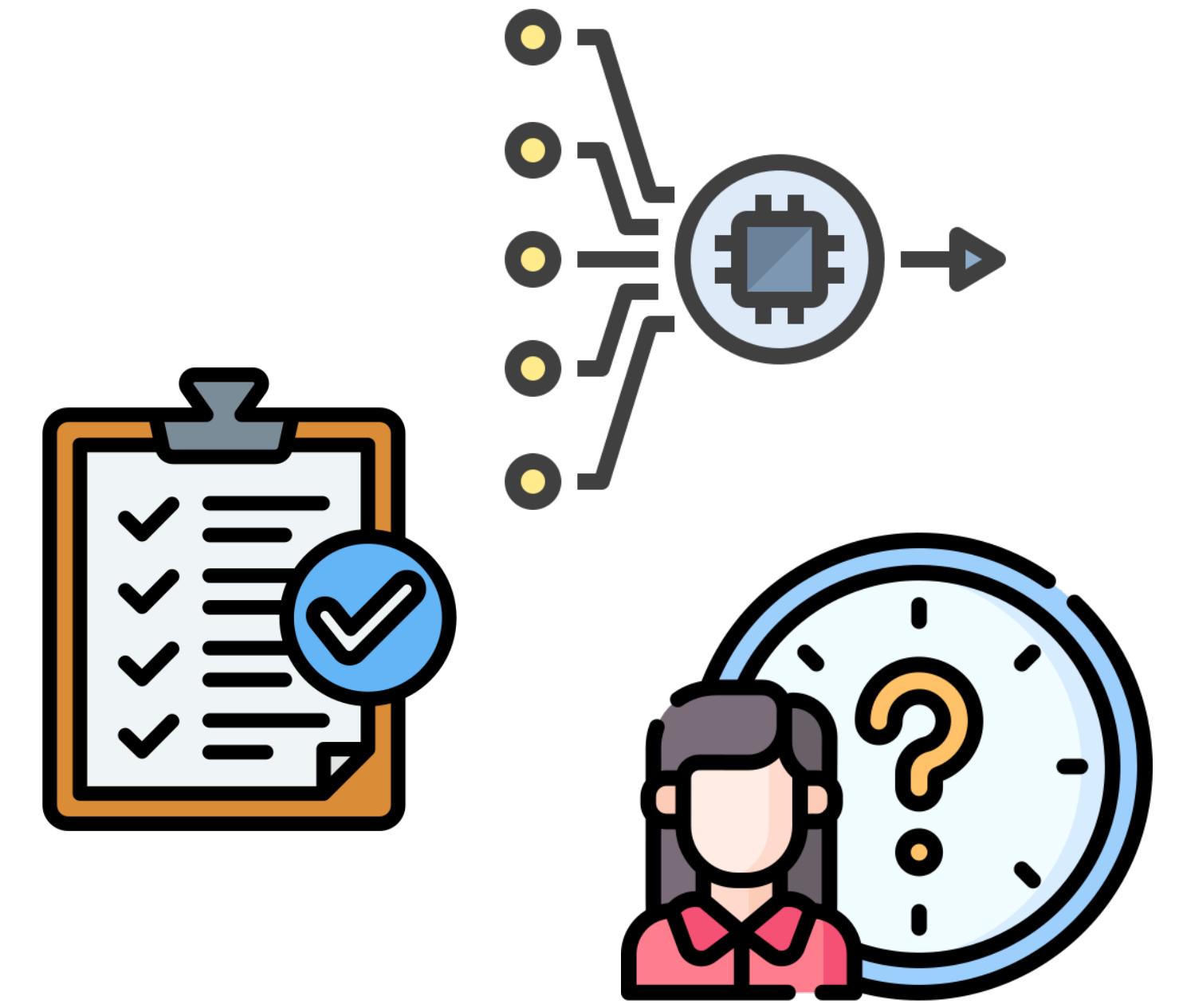
# Q. When should we stop the fuzzing campaign?



**Stochastic Process**

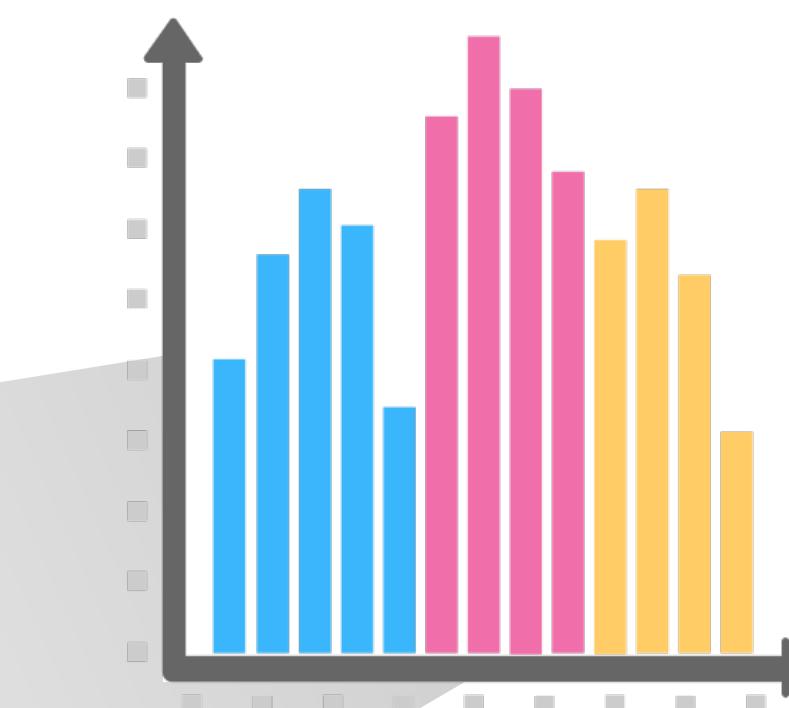
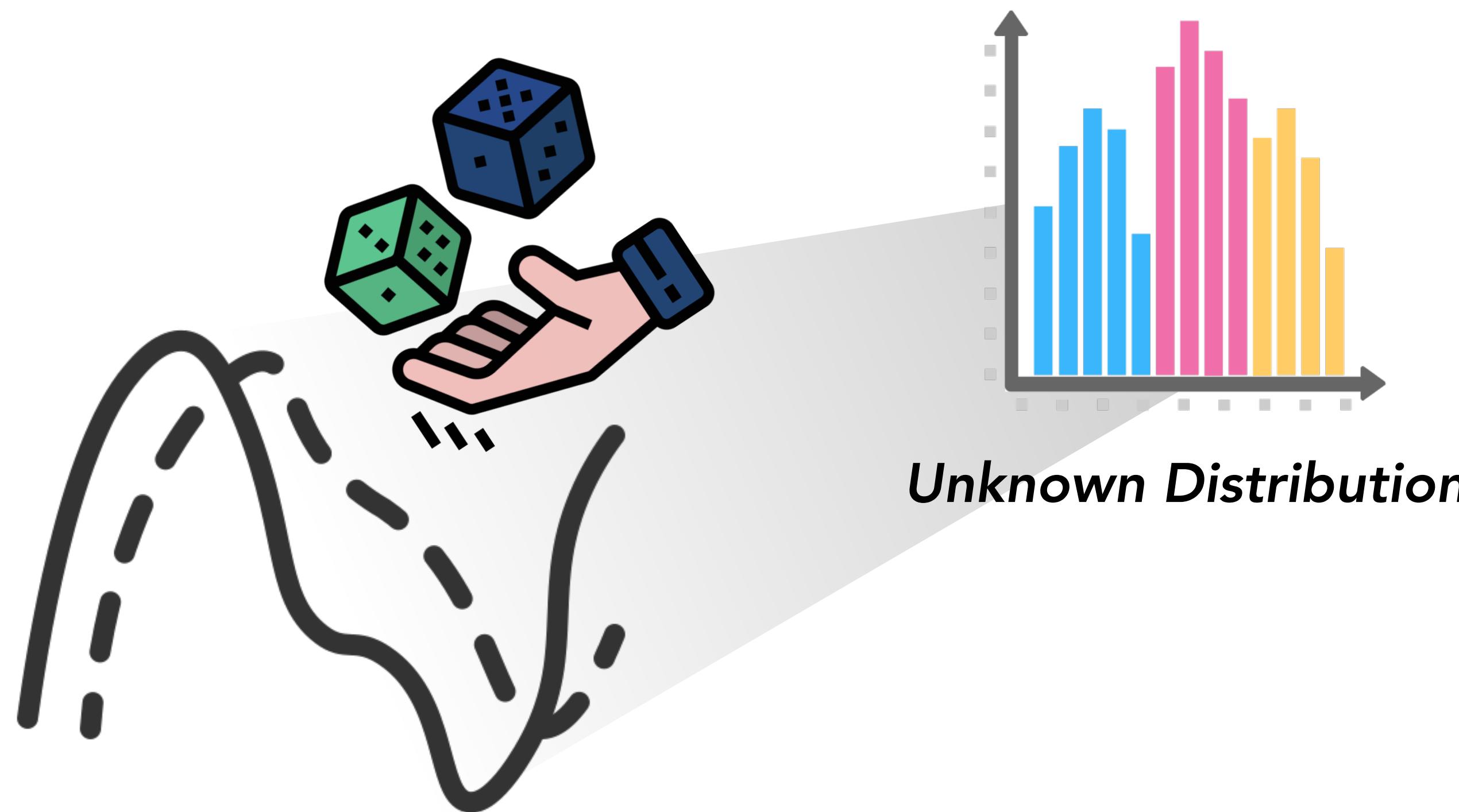


*Unknown Distribution*



*Even if we have some criteria,  
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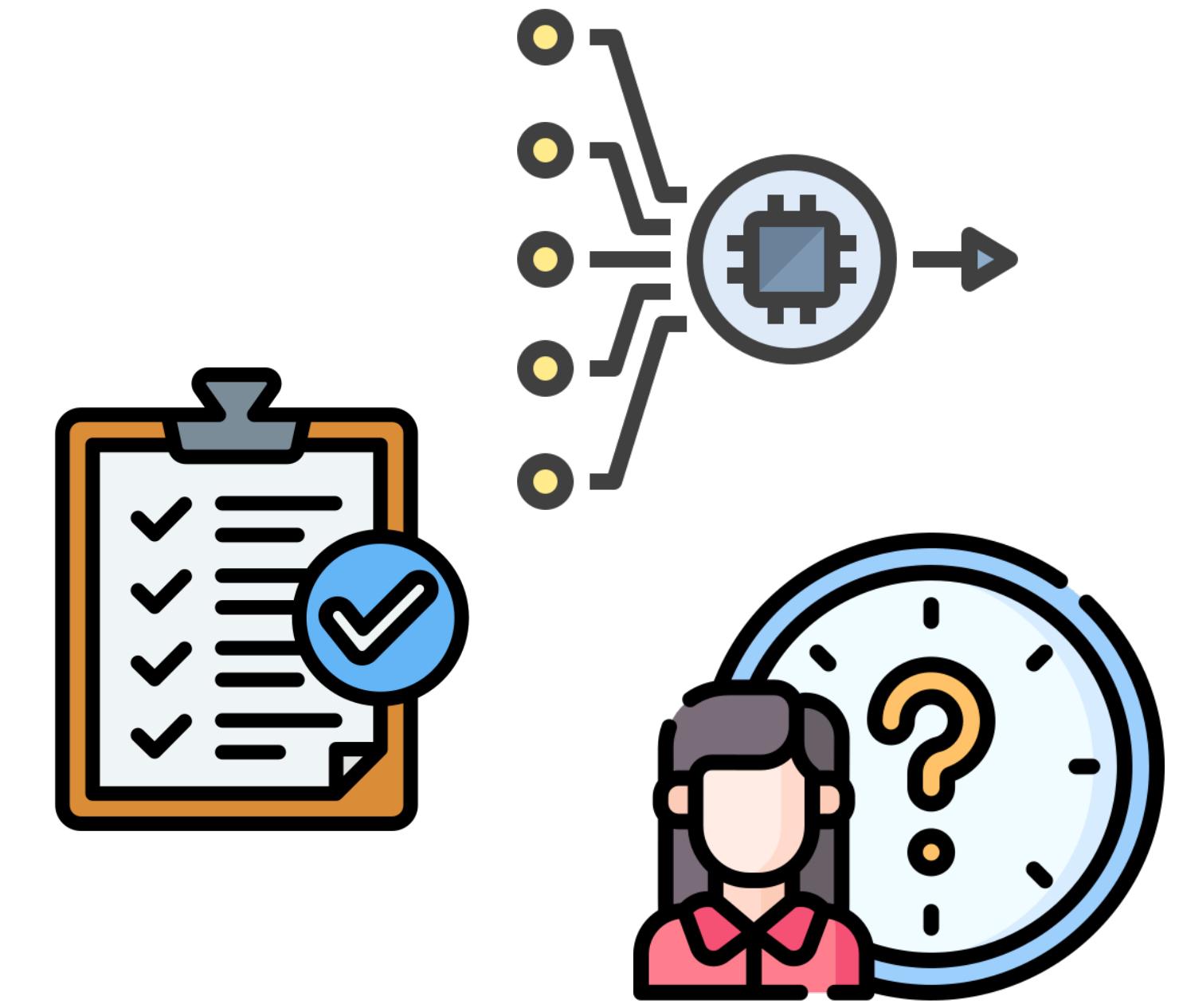
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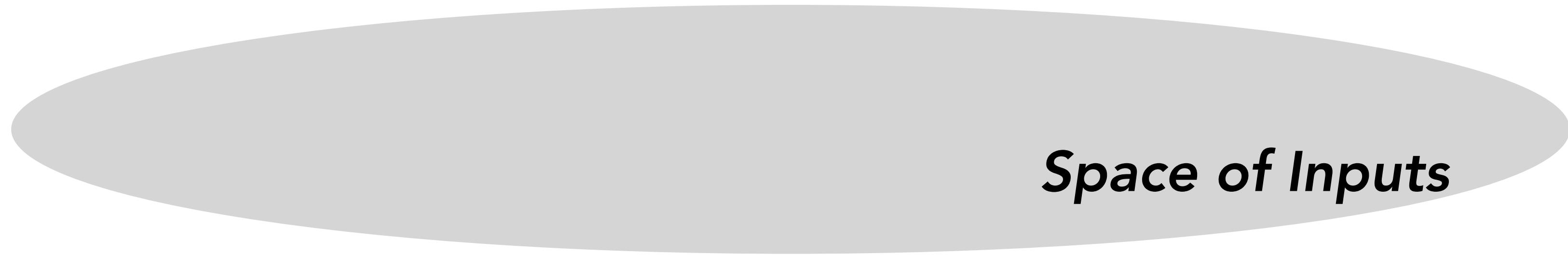
**Stochastic Process**

*Unsolvable with a formal/analytic method*



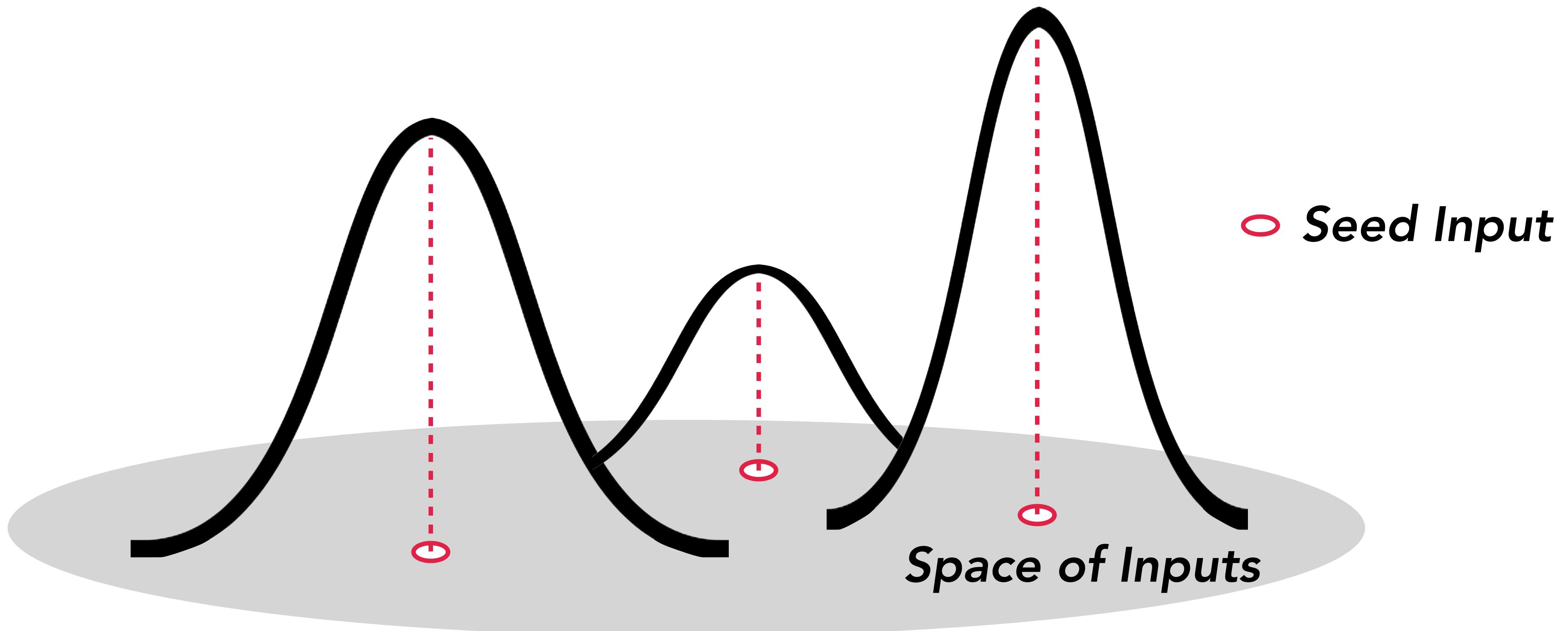
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# Fuzzing in terms of Statistics



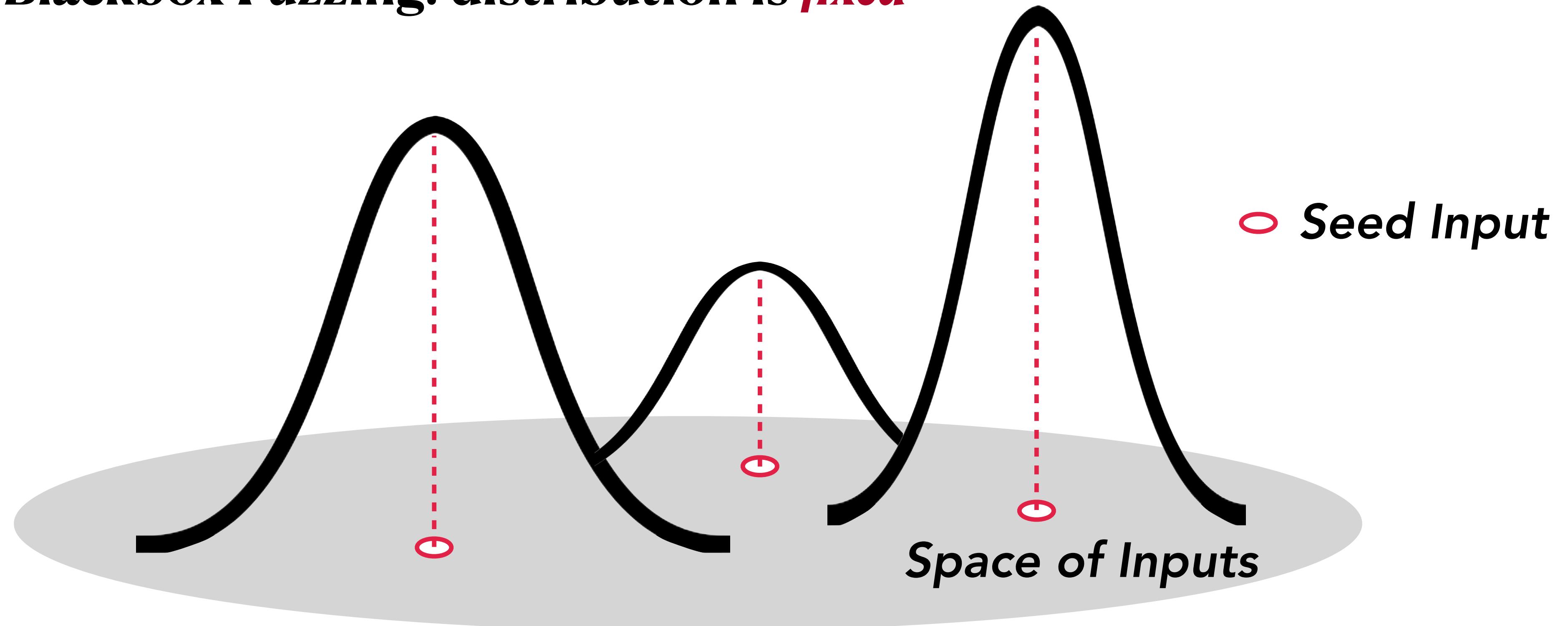
*Space of Inputs*

# Fuzzing in terms of Statistics



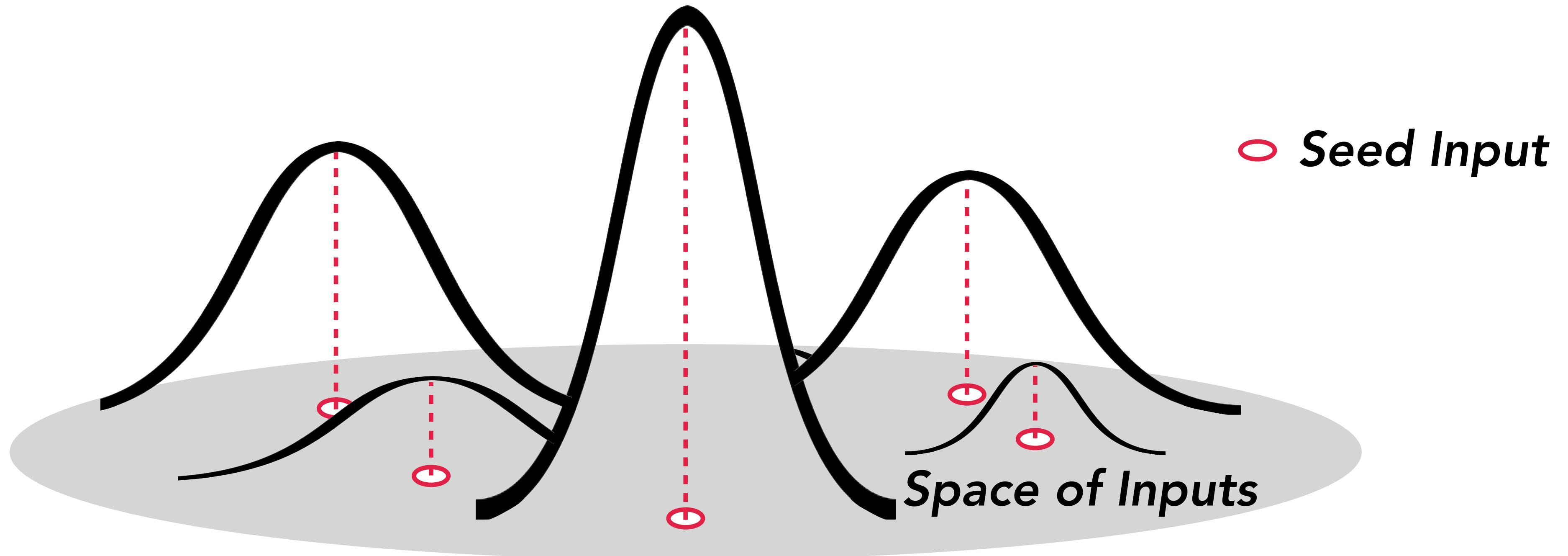
# Fuzzing in terms of Statistics

Blackbox Fuzzing: distribution is *fixed*



# Fuzzing in terms of Statistics

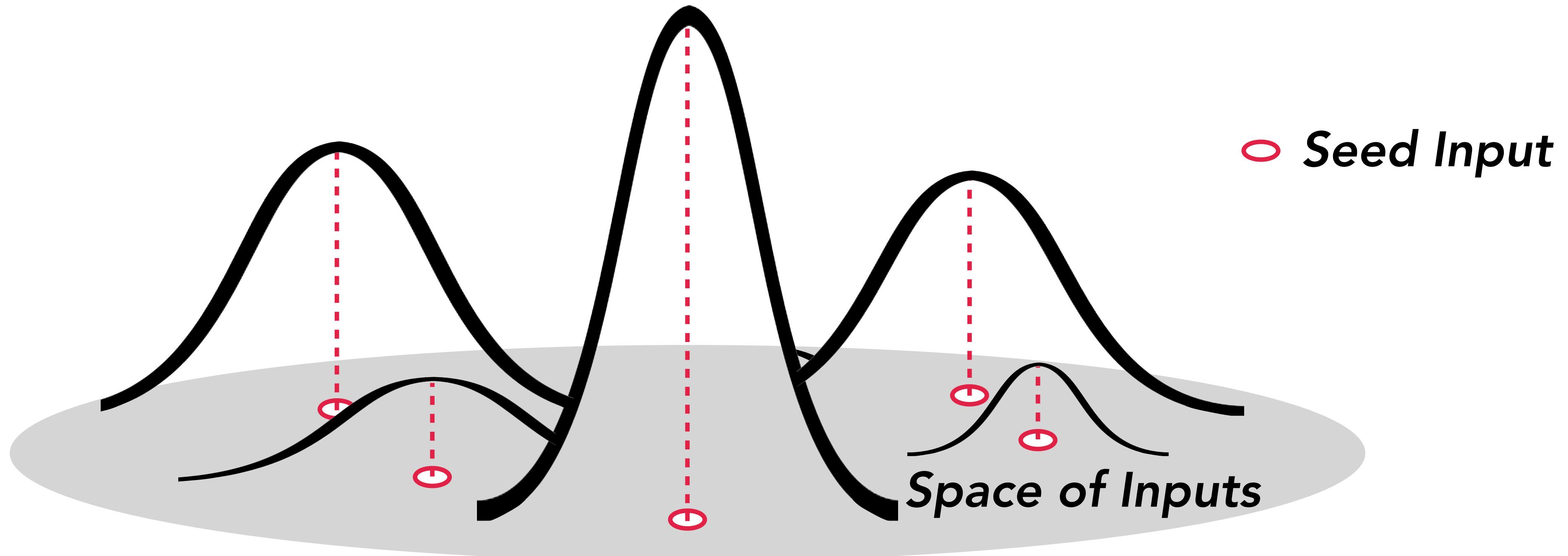
Greybox Fuzzing: distribution *changes as time goes on*



# Fuzzing in terms of Statistics

*Adaptive bias*

Greybox Fuzzing: distribution *changes as time goes on*



**Q. When should we stop the fuzzing campaign?**

# Statistically Extrapolating the Blackbox Fuzzing

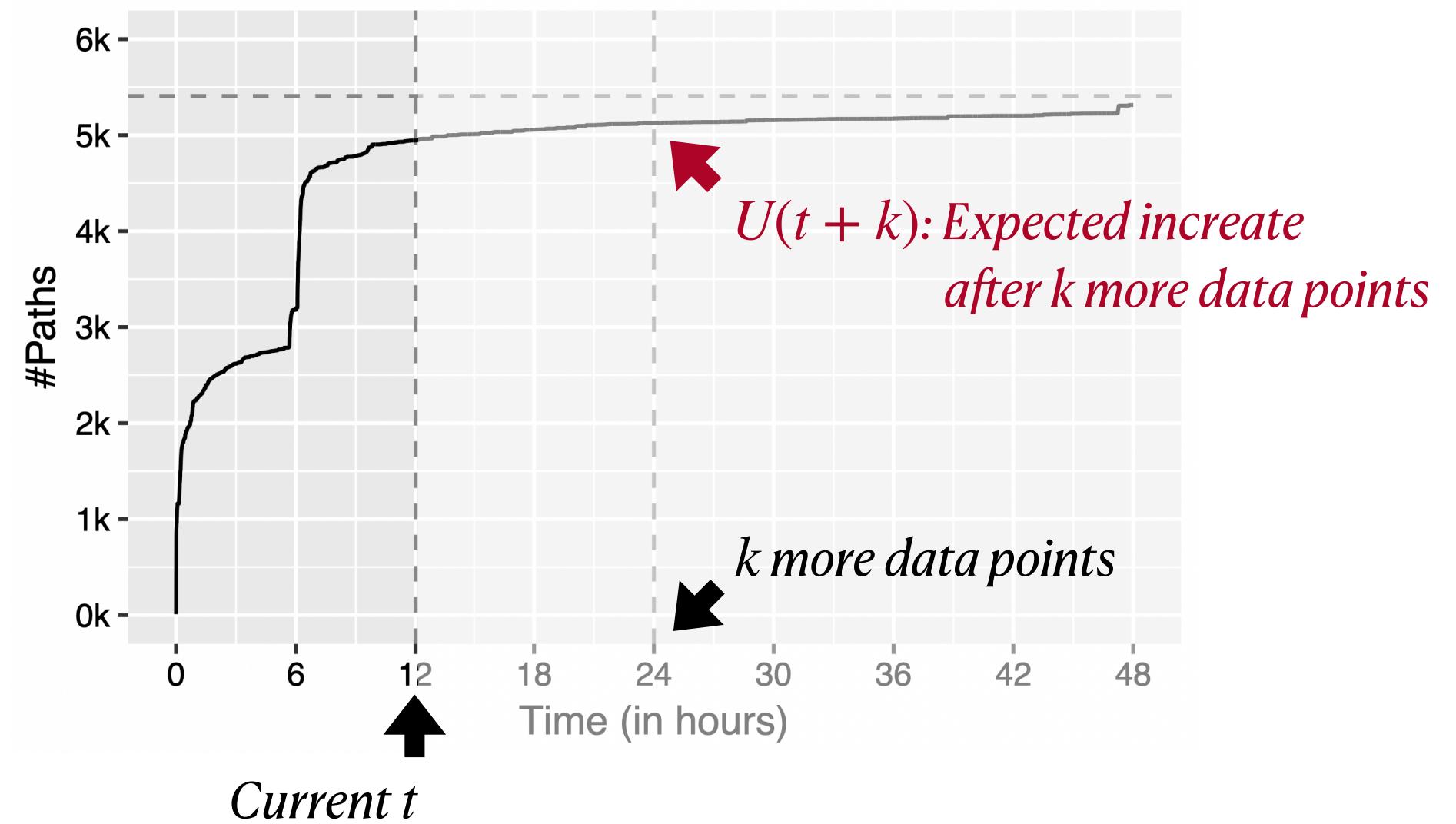
- Marcel Böhme, “STADS: Software testing as species discovery.” TOSEM, 2018.

*“A random sampling process of a **fixed distribution**, as a **Blackbox Fuzzing**, can be extrapolated statistically.”*

# Statistically Extrapolating the Blackbox Fuzzing

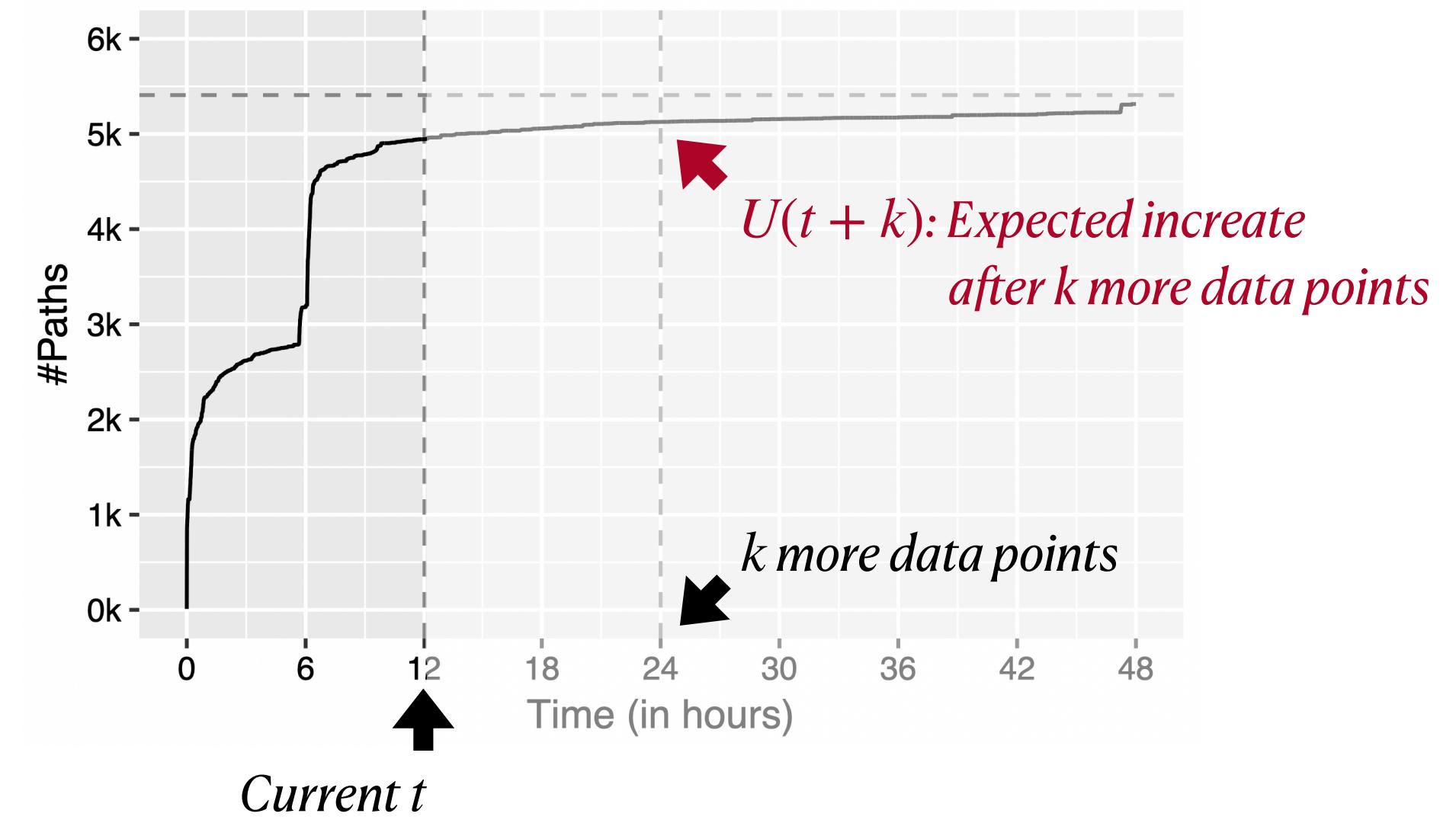
- Provides statistical estimators for a **coverage rate**
  - Coverage rate  $U(t)$ : the expected number of newly covered elements in the  $(t + 1)$ -th data point.
  - Extrapolation of **coverage rate**  $U(t + k)$

$$\hat{U}(t+k) = \hat{\Phi}_0 \left[ 1 - \left( 1 - \frac{\Phi_1}{t\hat{\Phi}_0 + \Phi_1} \right)^{k+1} \right] \quad , \text{ where } \hat{\Phi}_0 = \frac{t-1}{t} \frac{\Phi_1^2}{2\Phi_2}$$



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, where  $\hat{\Phi}_0 = \frac{t-1}{t} \frac{\Phi_1^2}{2\Phi_2}$
- $\Phi_k$ : number of program elements covered  $k$  times in  $t$  data points (*frequencies of frequency*)
  - $\Phi_1$  = number of singleton elements,  
 $\Phi_2$  = number of doubleton elements



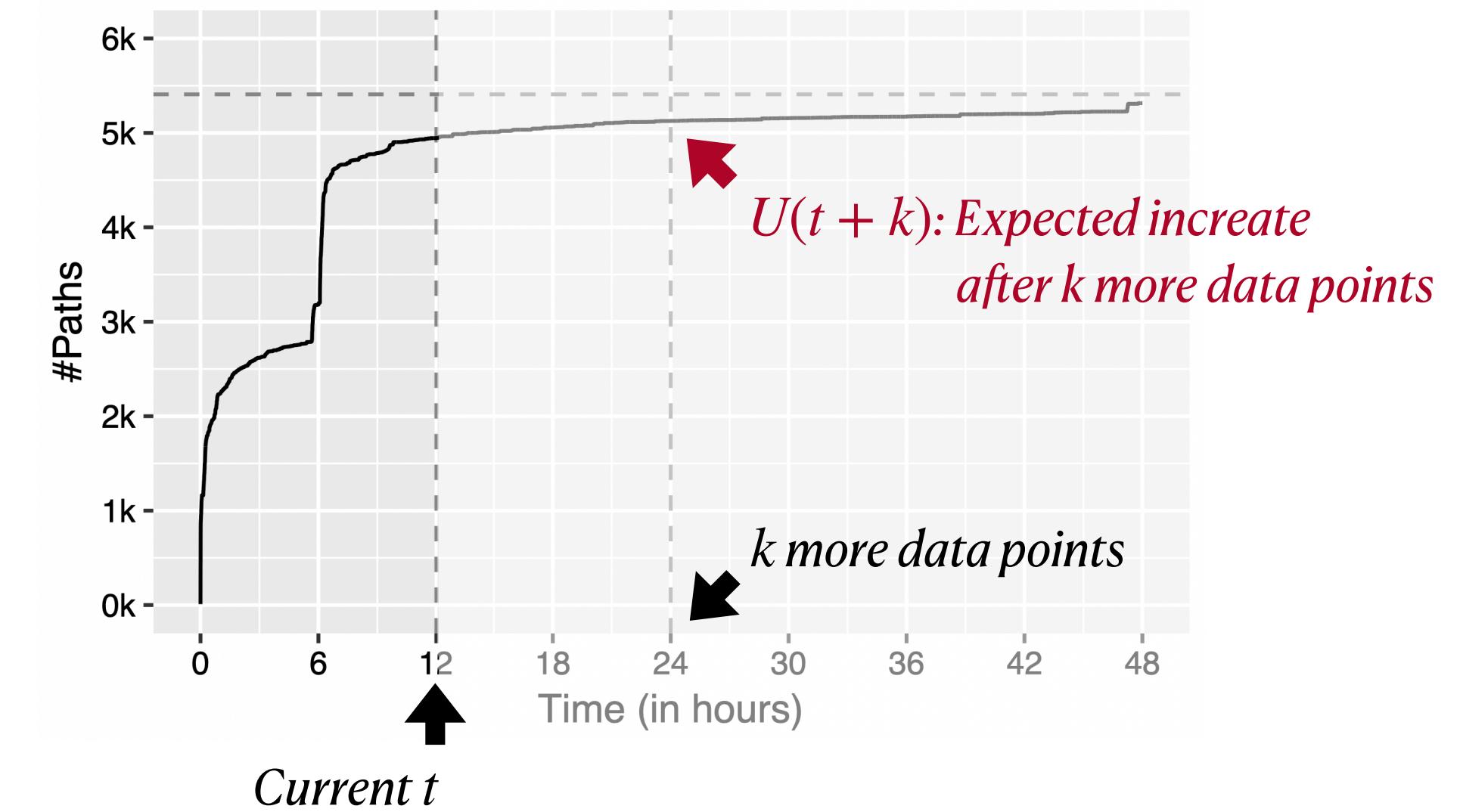
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# Statistically Extrapolating the Blackbox Fuzzing

## Without Extrapolation

```
american fuzzy lop 2.44b (djpeg)
-----
| run time : 0 days, 12 hrs, 0 min, 5 sec | cycles done : 53 |
| last new path : 0 days, 0 hrs, 17 min, 44 sec | current paths : 4944 |
| last uniq crash : none seen yet | uniq crashes : 0 |
| ... |
```

*12 hours of running, the last new path was 17 minutes ago.  
... should I stop this fuzzing?*

## With Extrapolation

```
extrapolation edition yeah! (djpeg)
-----
residual risk : 7·10^-06 | total inputs : 63.6M |
path coverage: 77.6% paths covered | singletons : 447 |
discover new path : 0 hrs, 1 min, 36 sec | doubletons : 70 |
142k new inputs needed |
```

*A new path will come in 2 minutes? Let's keep going!*

VS

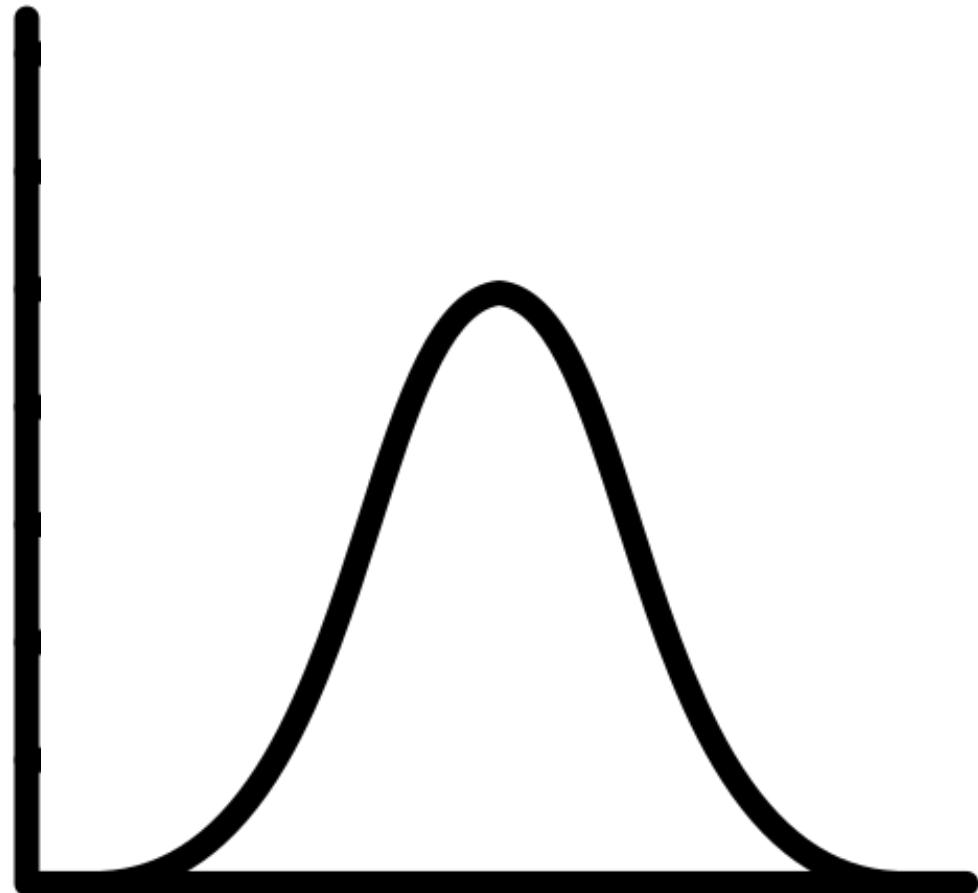
```
extrapolation edition yeah! (djpeg)
-----
residual risk : 8·10^-07 | total inputs : 124.8M |
path coverage: 97.9% paths covered | singletons : 95 |
discover new path : 0 hrs, 15 min, 9 sec | doubletons : 42 |
1.3M new inputs needed |
```

*1/4 hour is needed for the next path? Let's stop!*

*Extrapolation gives richer information for the **stopping criteria** for the fuzzing campaign*

# How about the Greybox fuzzing?

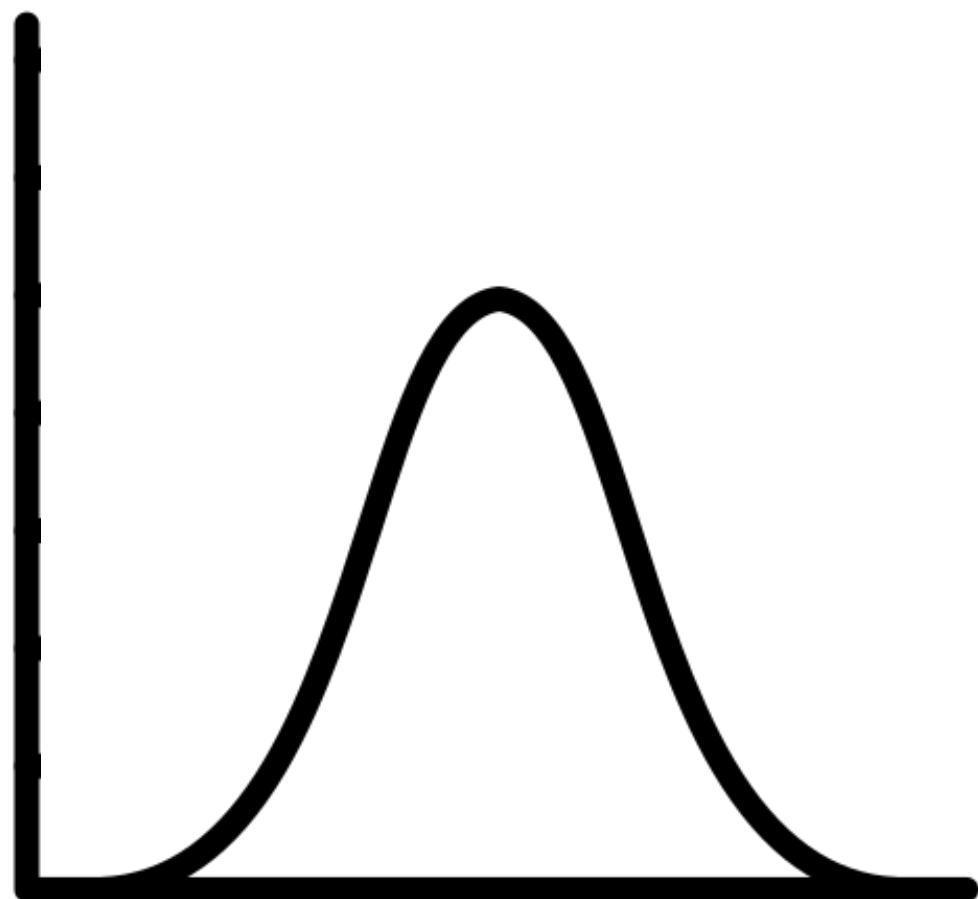
**Blackbox**



*Sampling distribution  
is consistent*

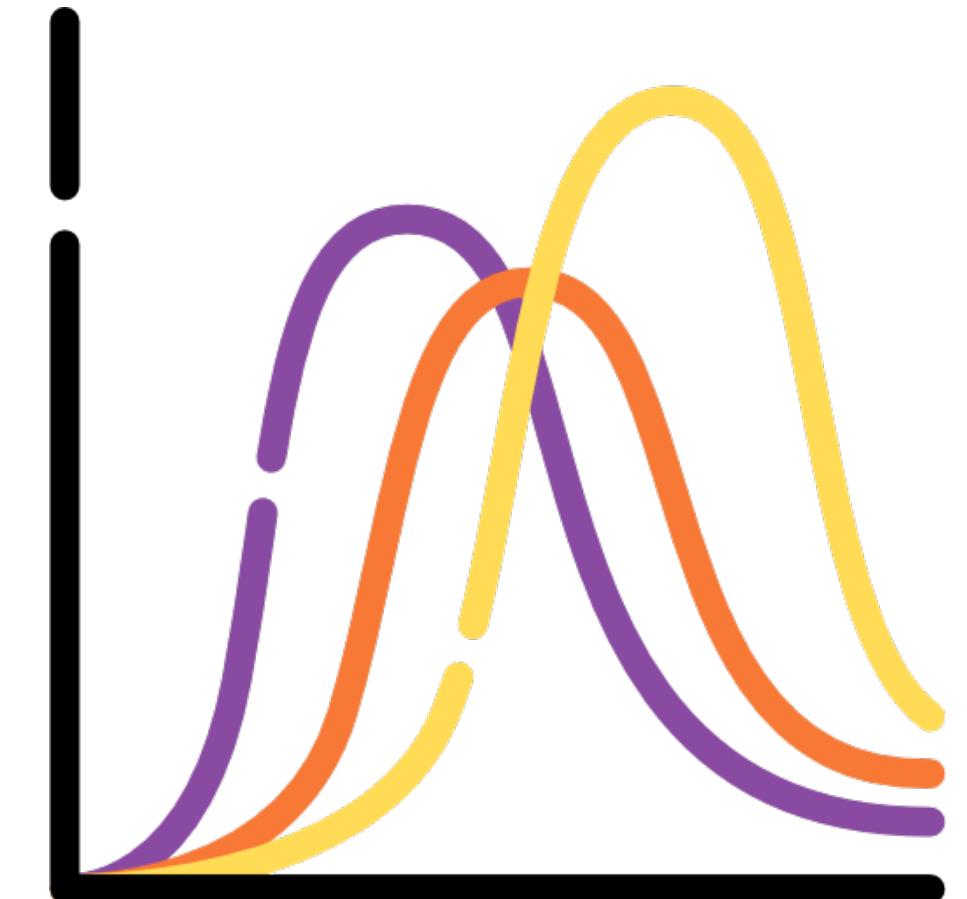
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**Greybox**

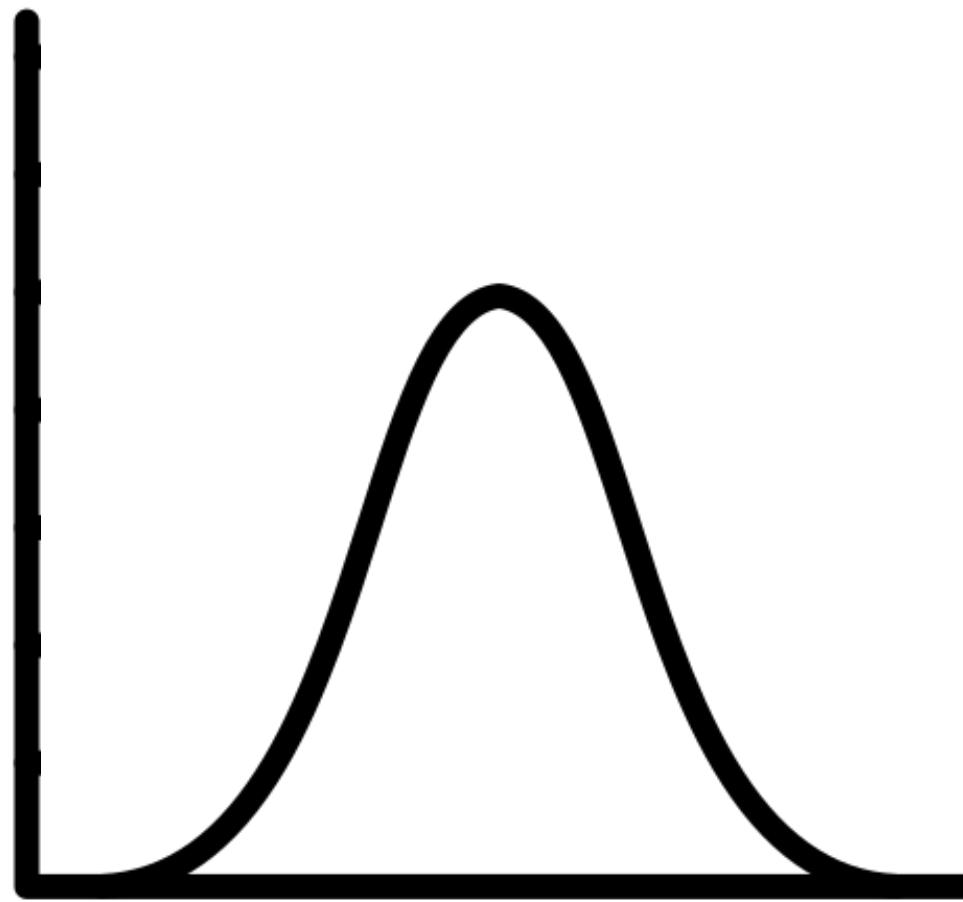


*Sampling distribution  
keeps change*

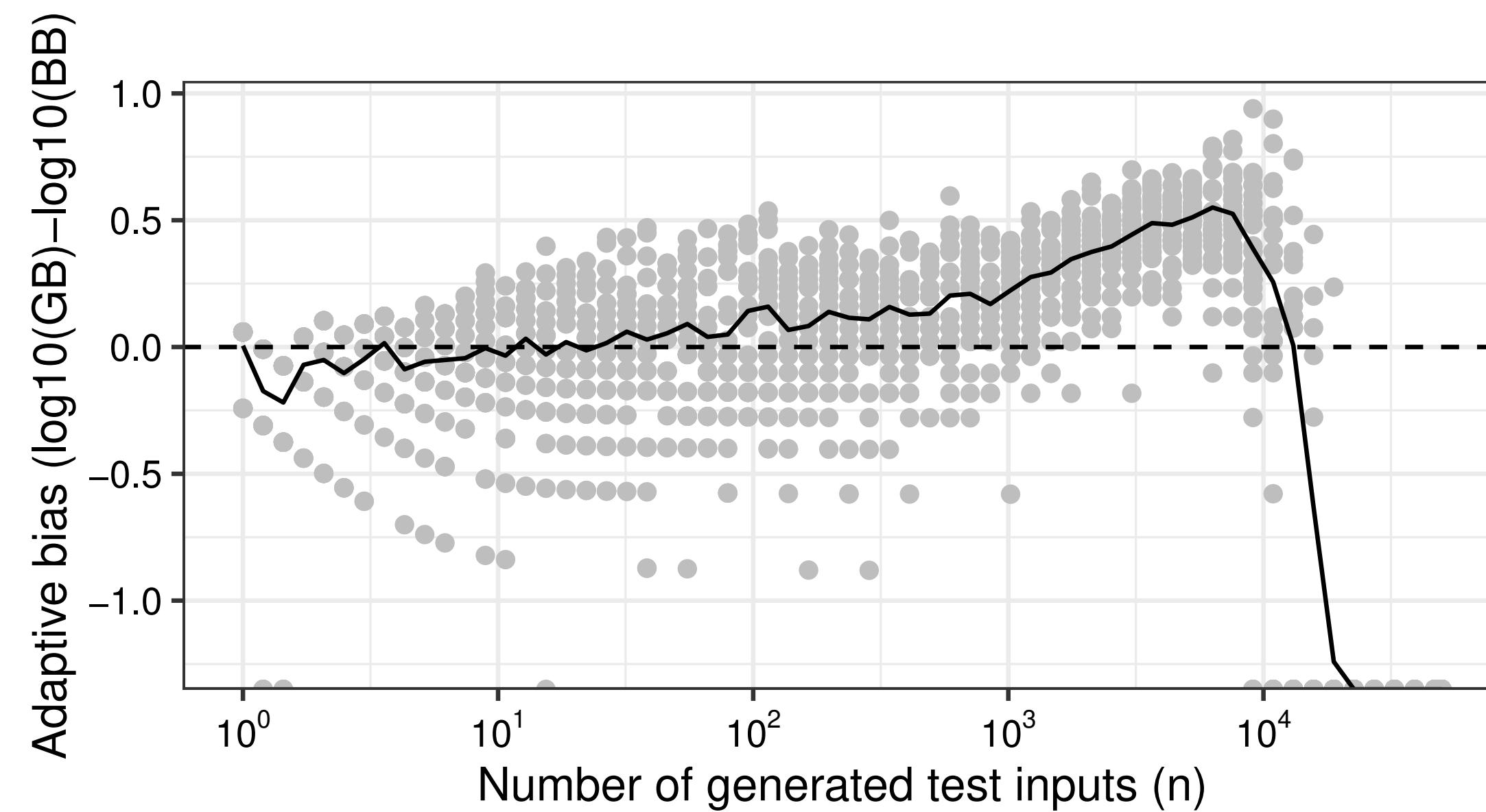
**Adaptive bias**

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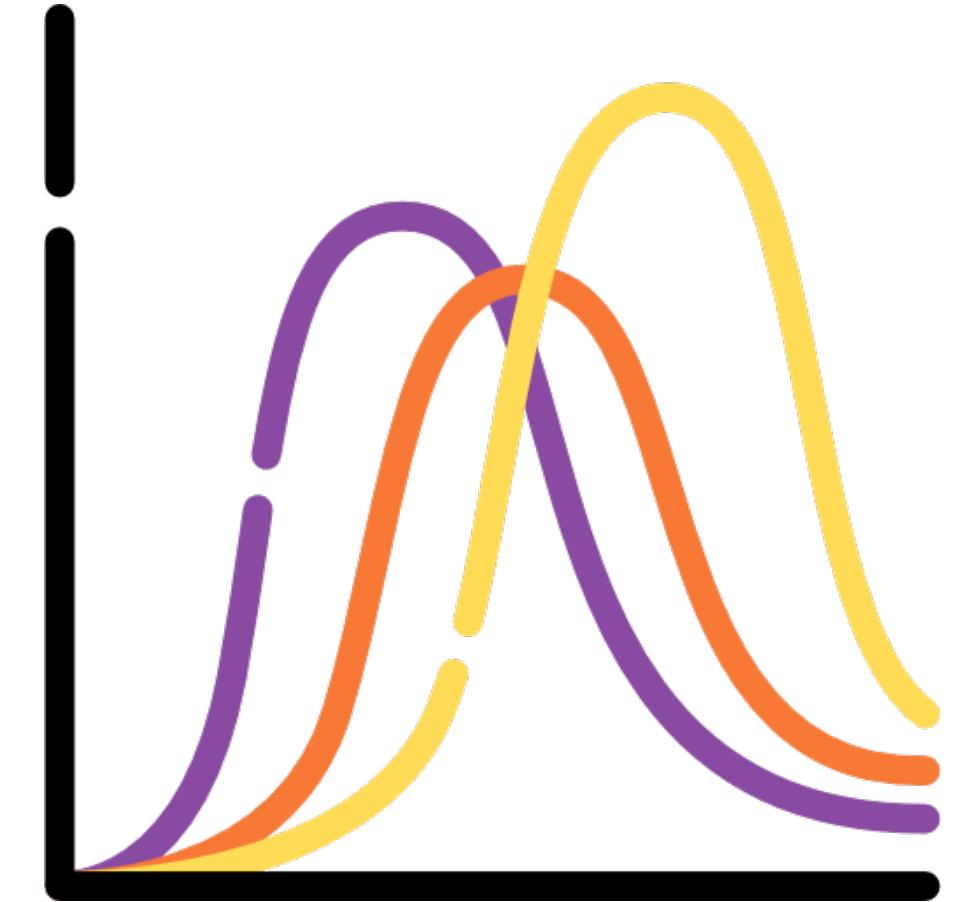
**Blackbox**



*Sampling distribution  
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**Greybox**



*Sampling distribution  
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**Adaptive bias***

*“Due to adaptive bias, the discovery probability is consistently higher in the greybox campaign than the blackbox campaign.”*

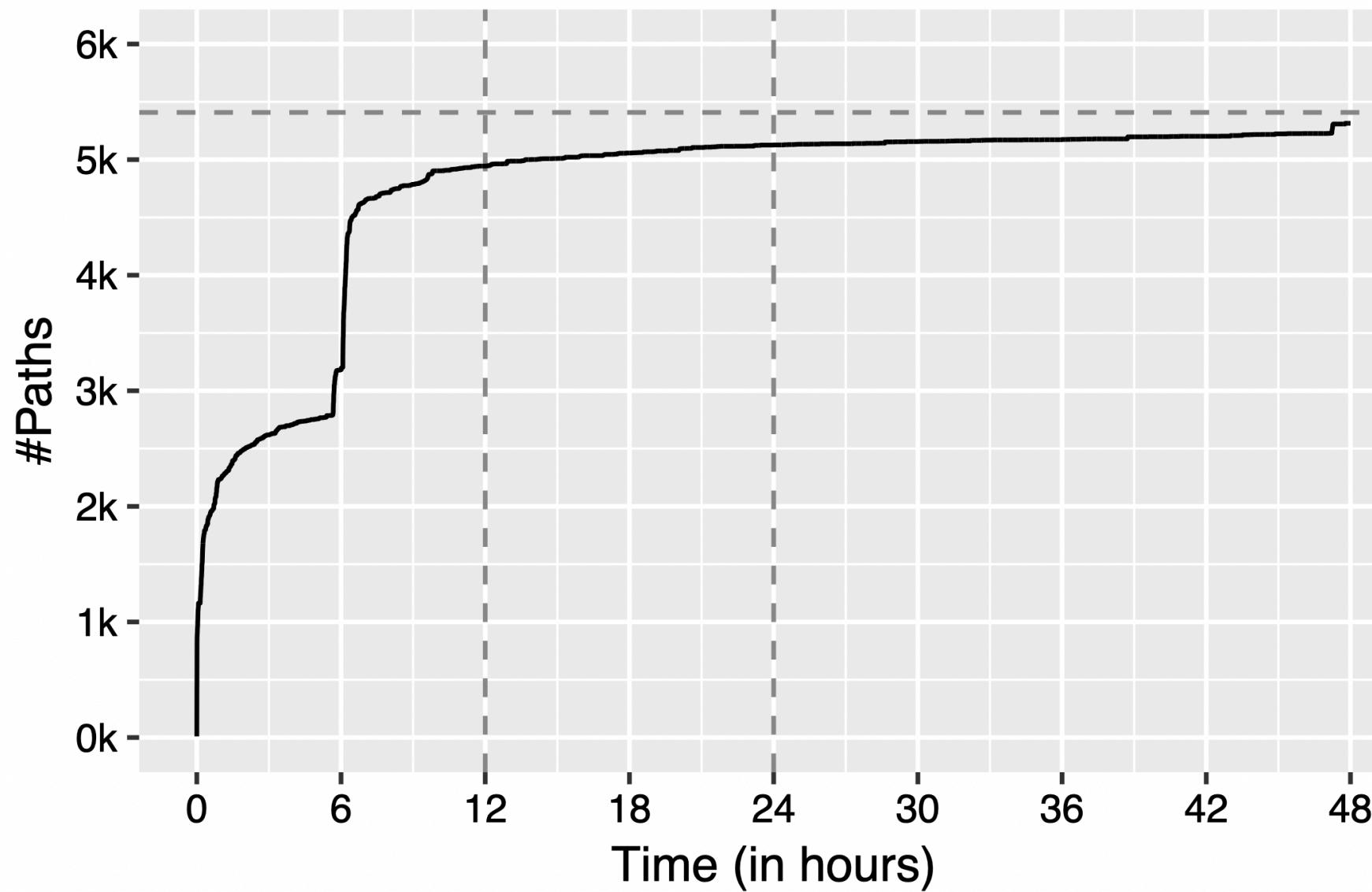


# Extrapolating the Greybox Fuzzing Campaign

- Aim: Predict the future coverage rate of the greybox fuzzing campaign

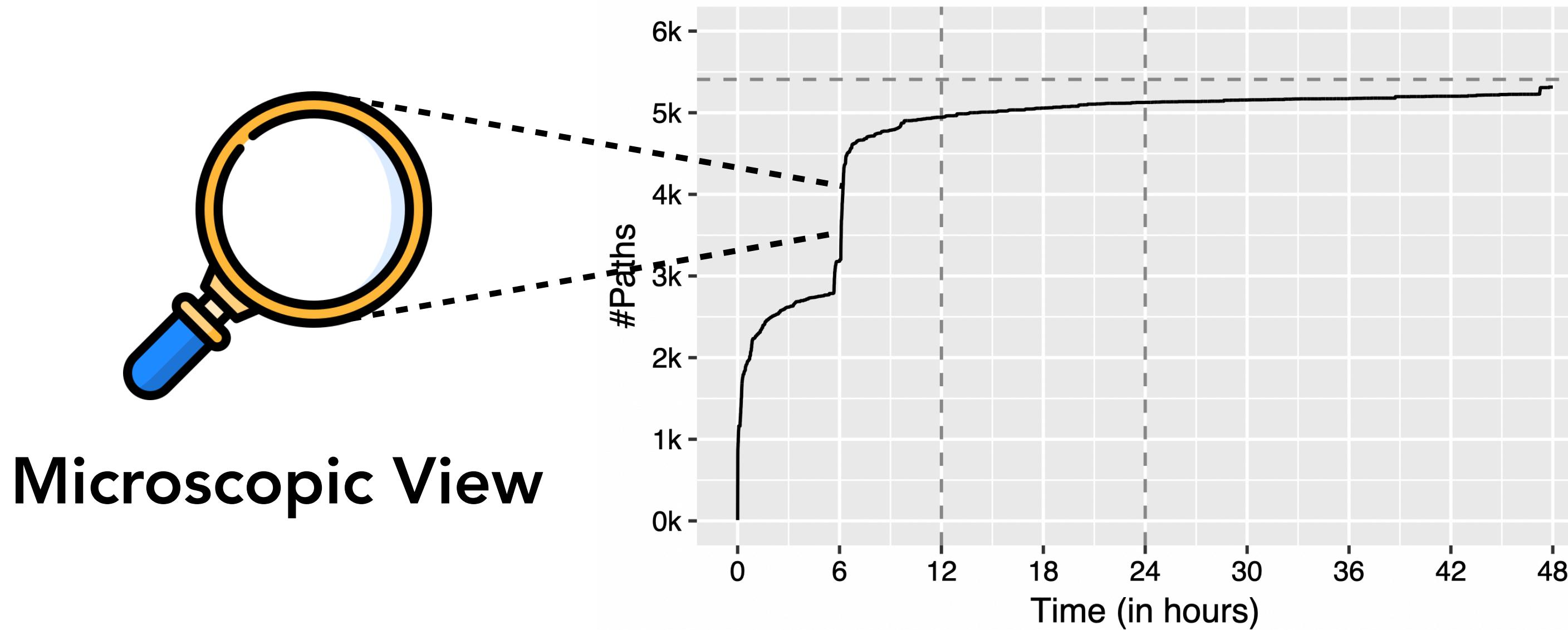
# Extrapolating the Greybox Fuzzing Campaign

- Aim: Predict the future coverage rate of the greybox fuzzing campaign
- In other words, how can we solve the *adaptive bias* problem?



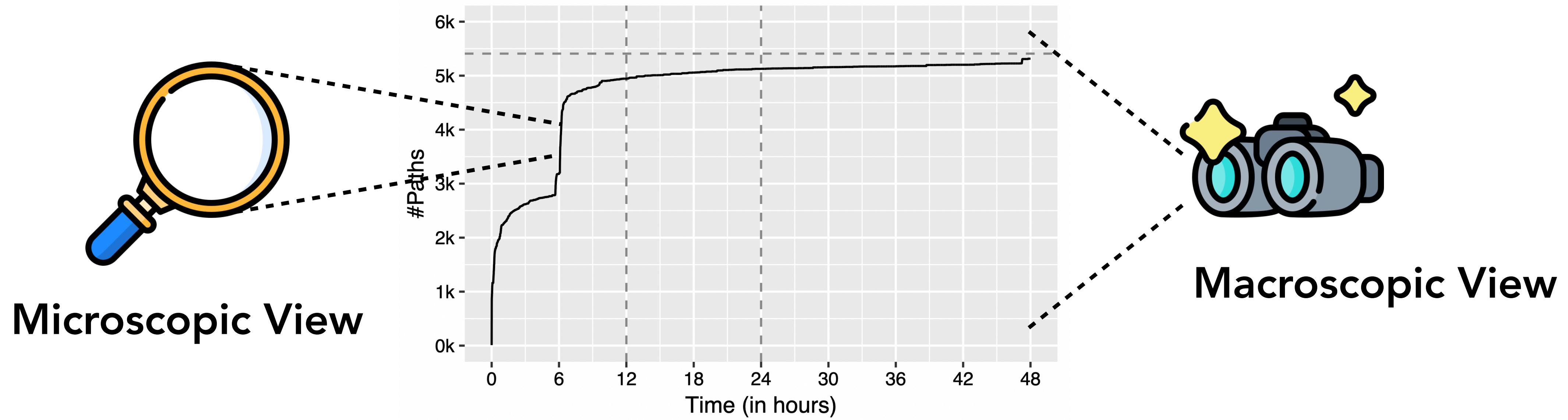
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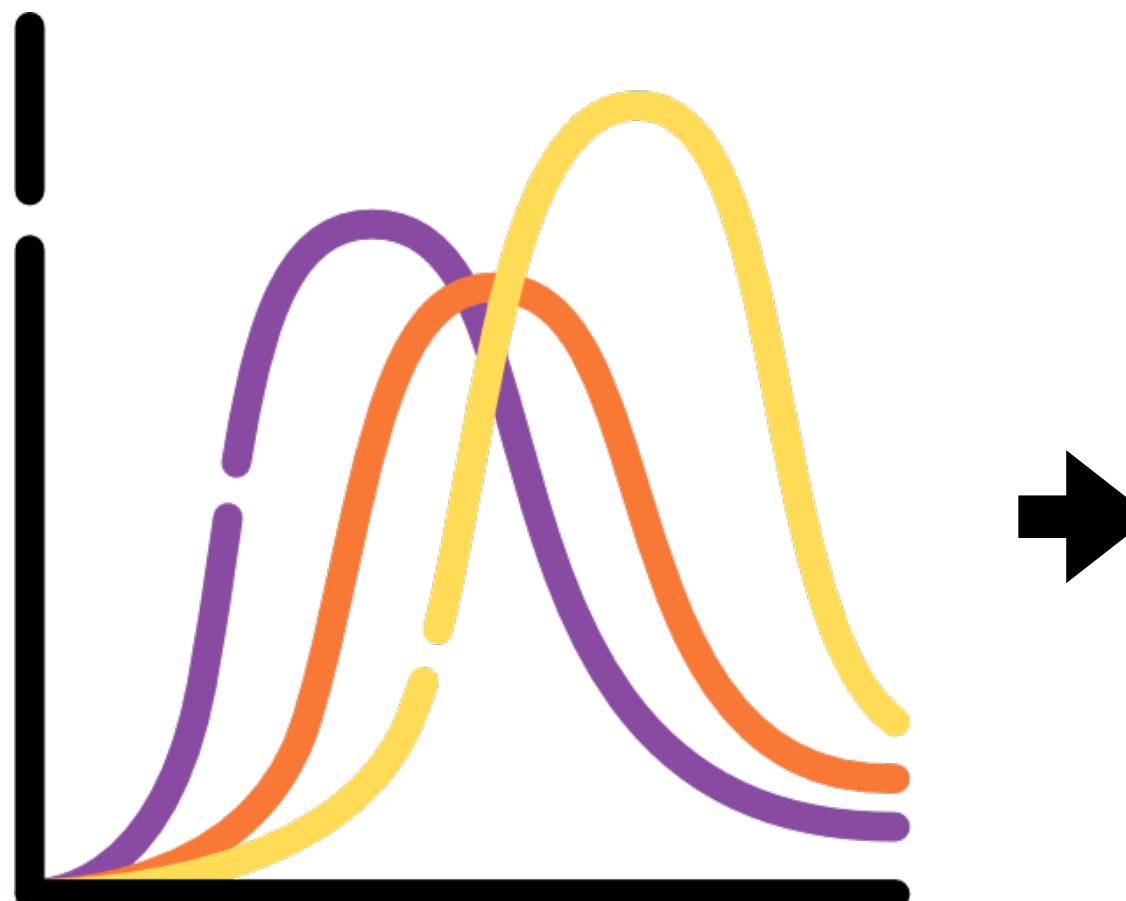


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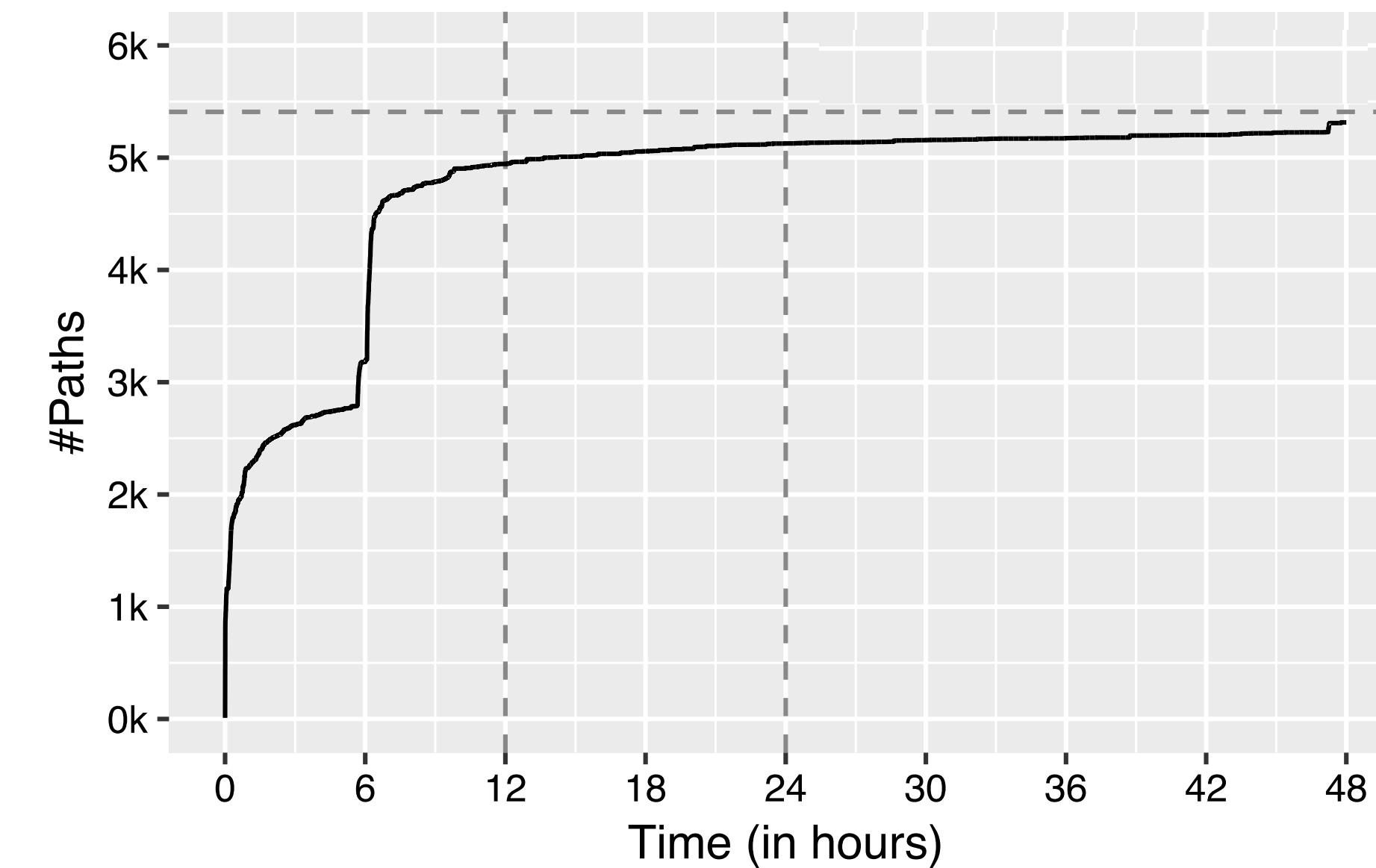
- First key insight – *Microscopic view*

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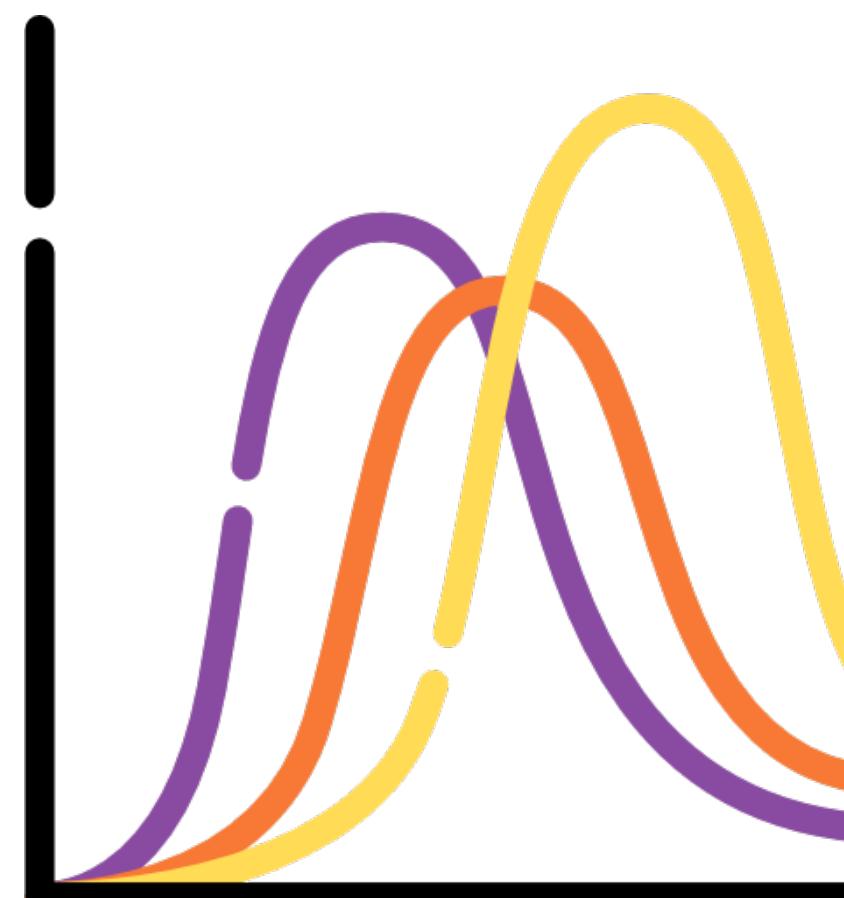


**Adaptive bias**

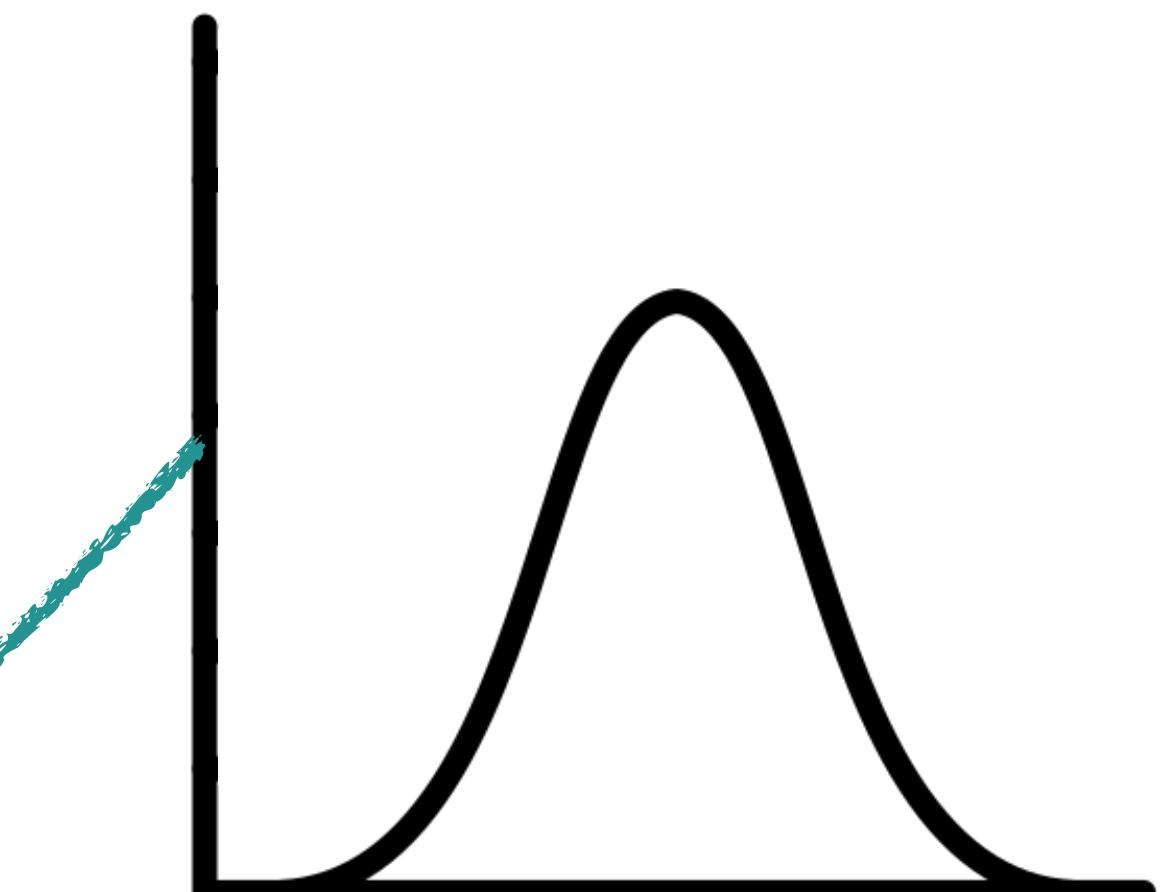
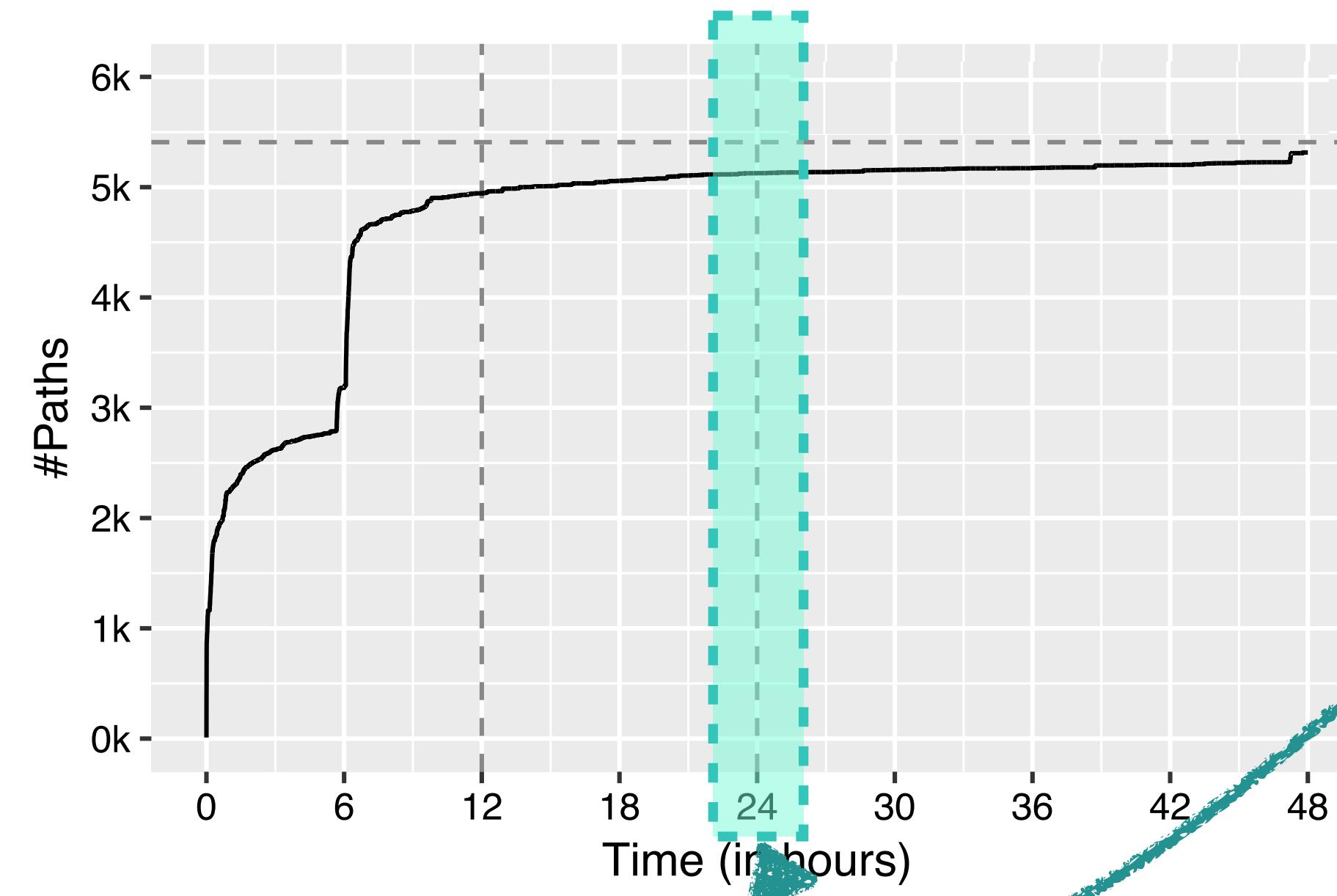
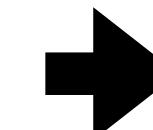


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- First key insight — *Microscopic view*



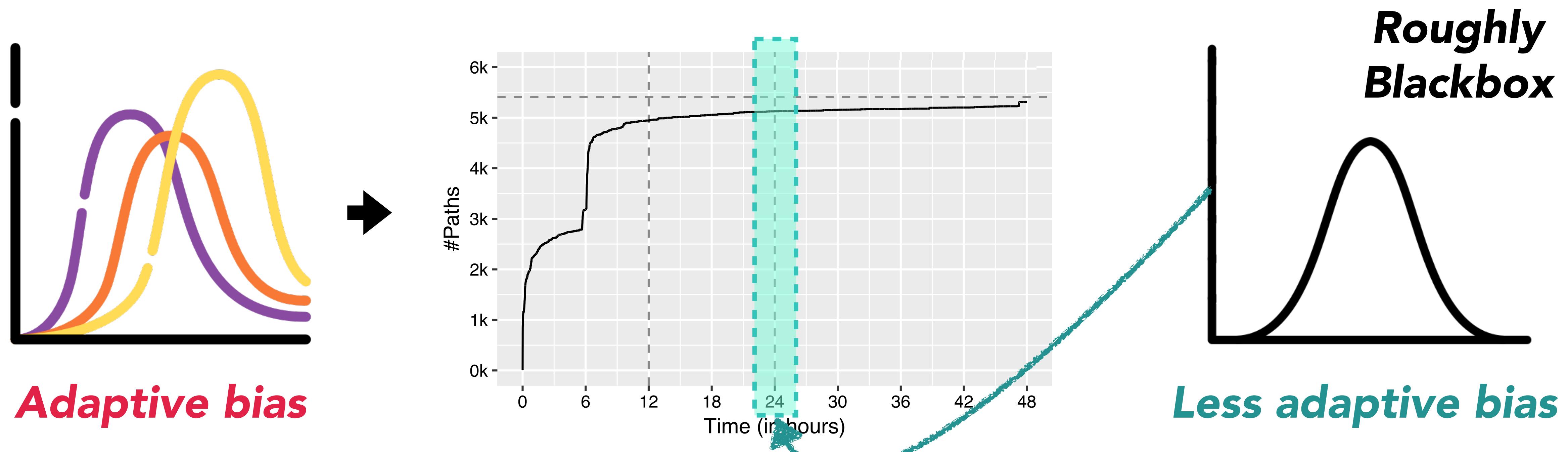
**Adaptive bias**



**Less adaptive bias**

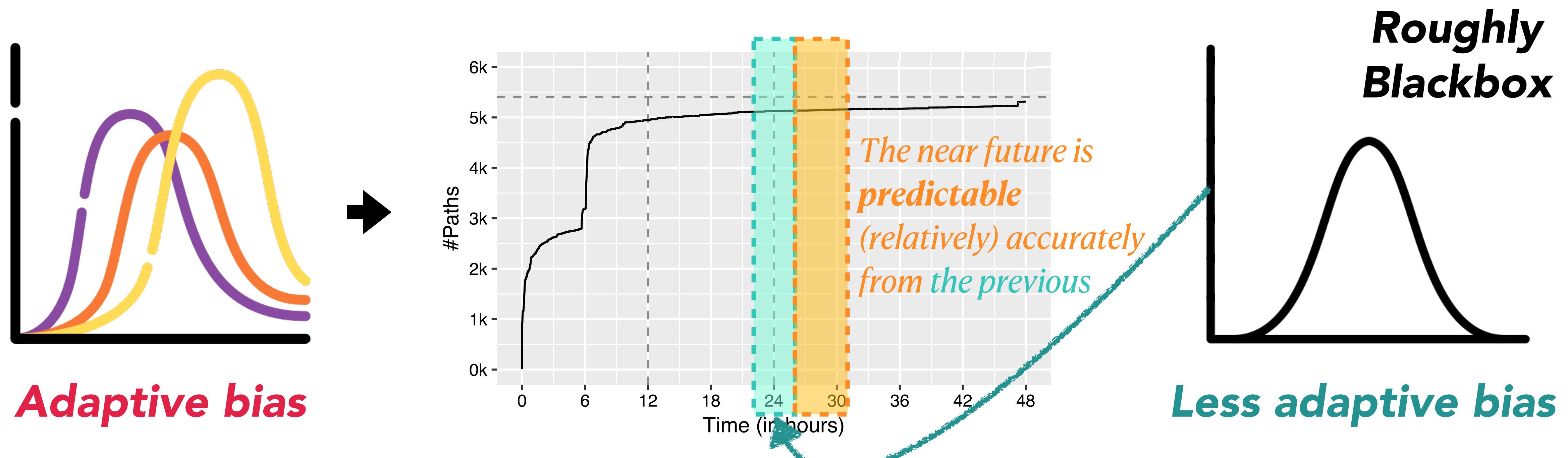
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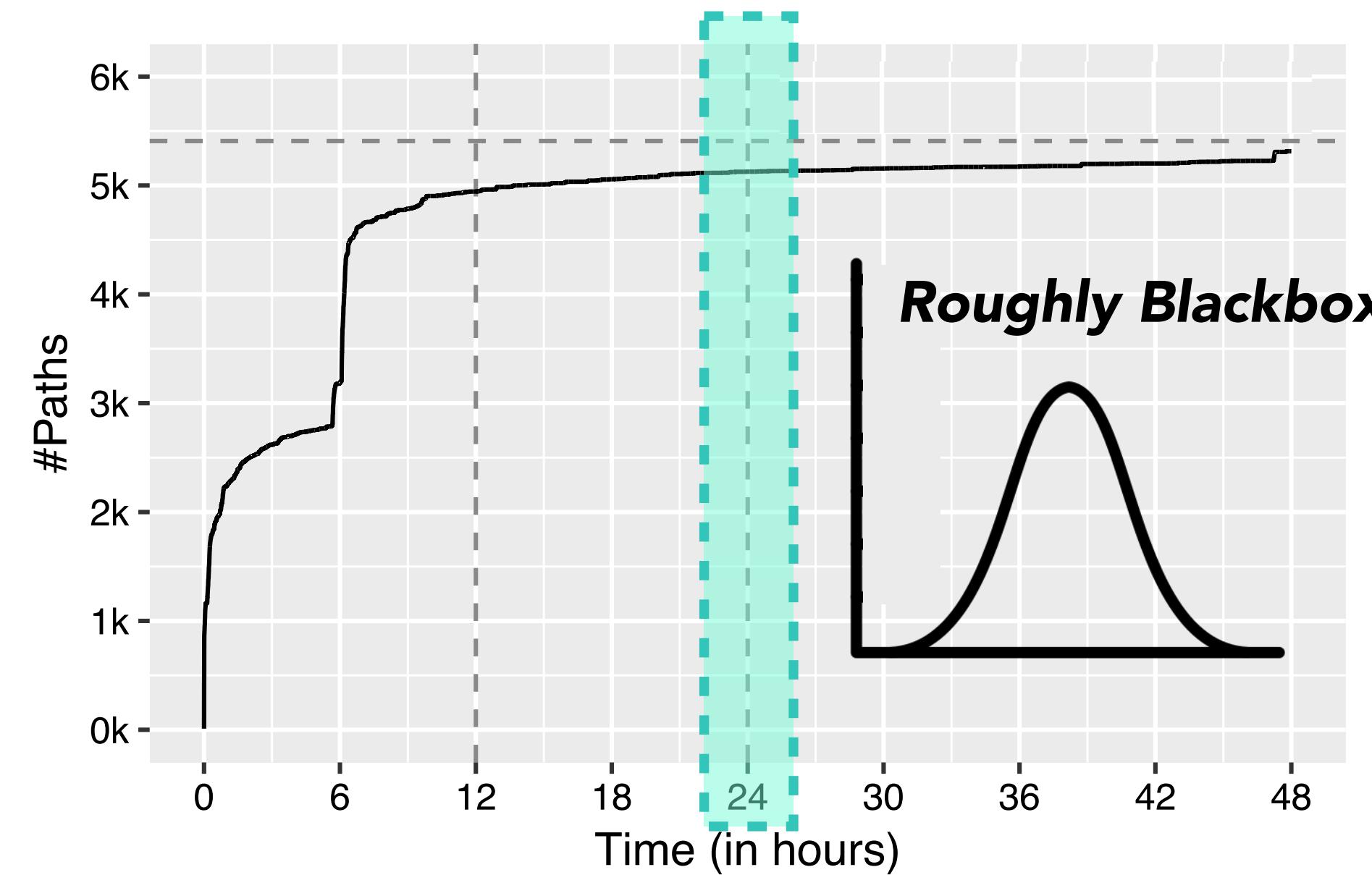
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# Extrapolating the Greybox Fuzzing Campaign

- First key insight — *Microscopic view*
- Potential drawback: ***Small region has small data to use***

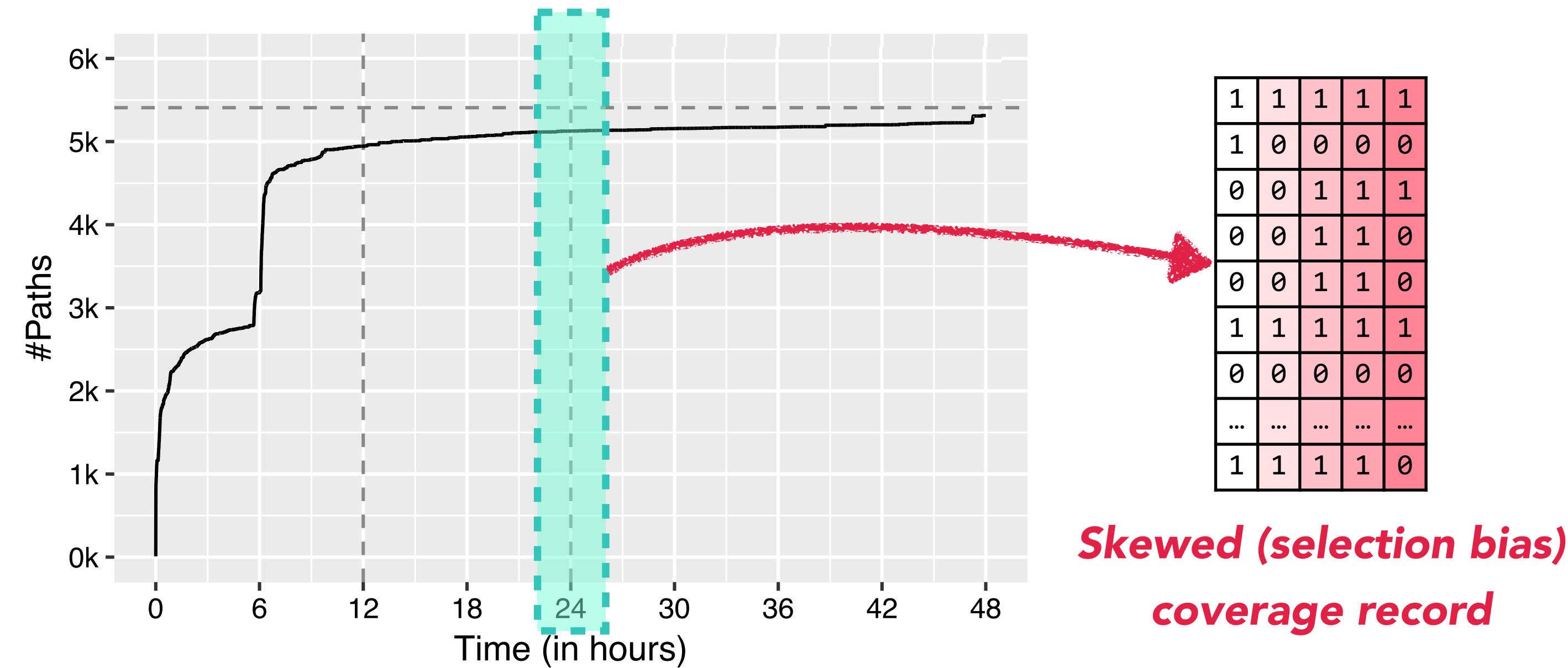


$$\hat{U}(t) = \frac{\Phi_1}{t} \left[ \frac{(t-1)\Phi_1}{(t-1)\Phi_1 + 2\Phi_2} \right]$$

**Coverage rate estimator  
for a blackbox fuzzing campaign**

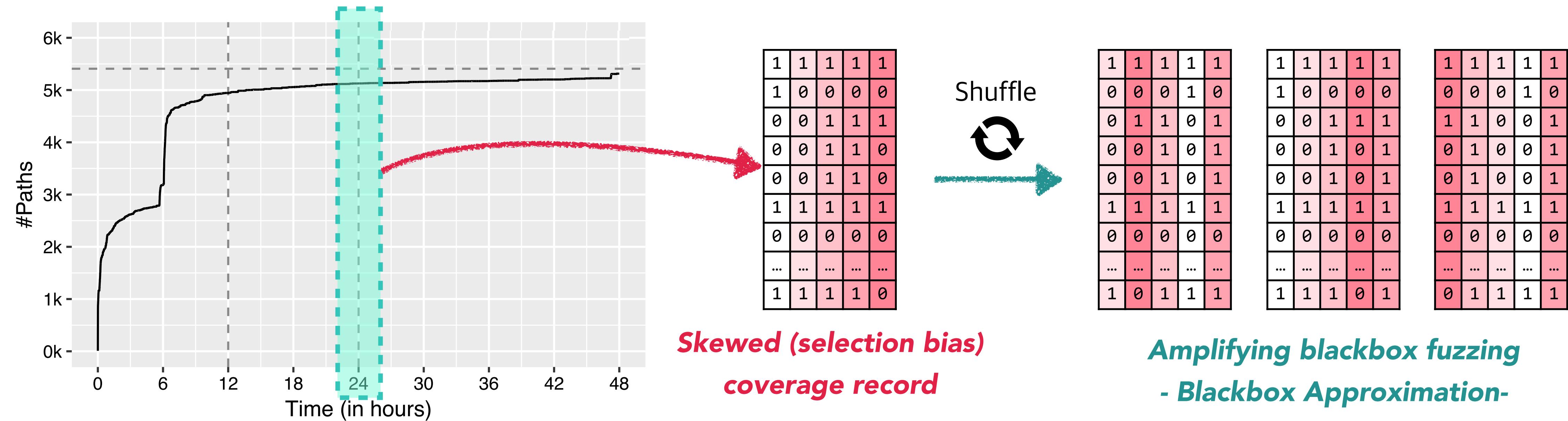
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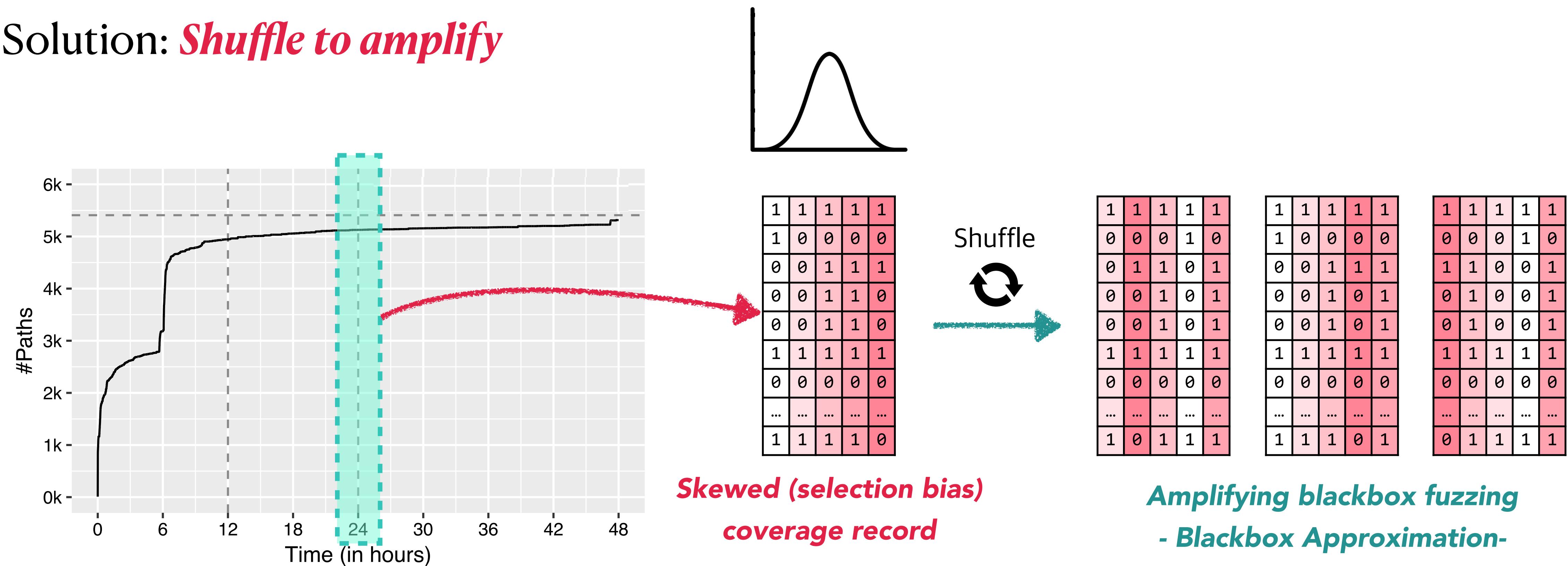
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- First key insight — *Microscopic view*
- Solution: **Shuffle to amplify**



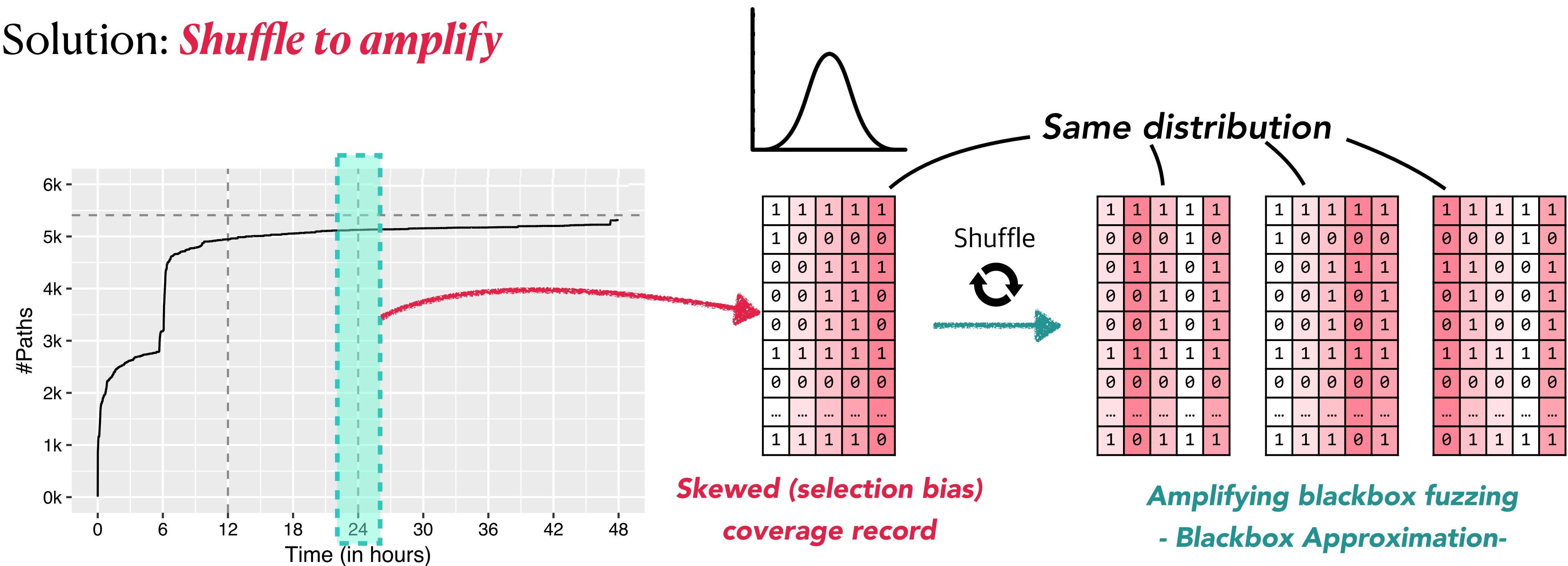
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# Extrapolating the Greybox Fuzzing Campaign

- Second key insight – *Macroscopic view*

“*Greybox fuzzing’s adaptive bias could be **predictable**.*”

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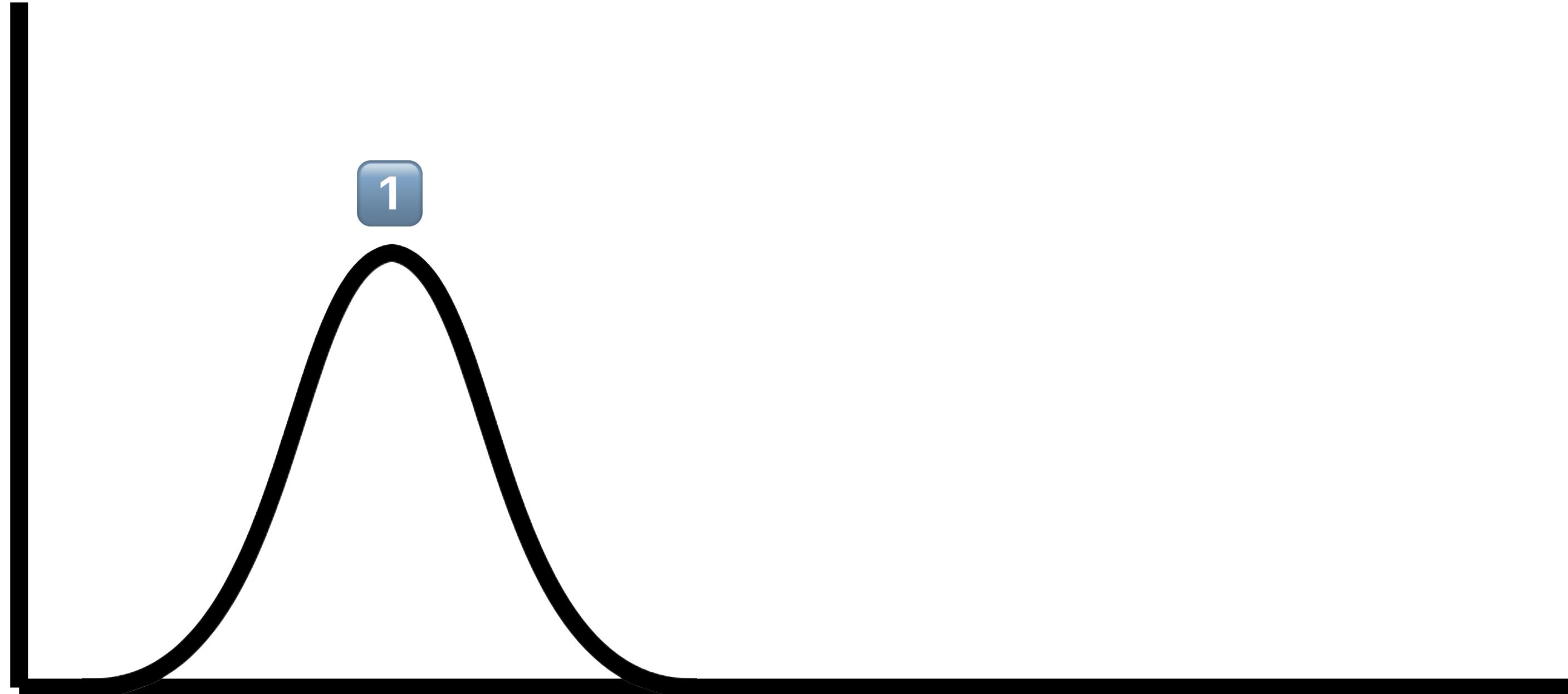
*“Greybox fuzzing’s adaptive bias could be **predictable**.”*



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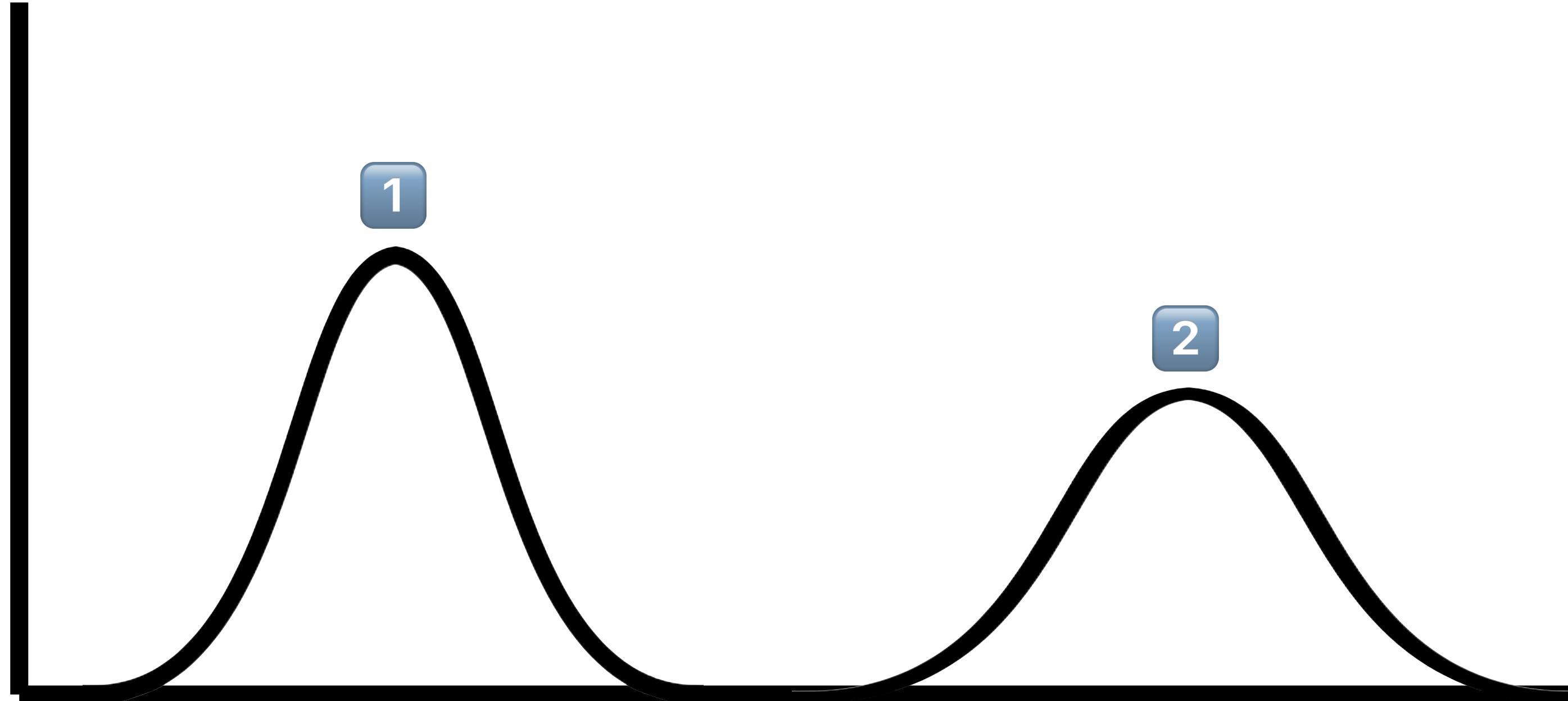
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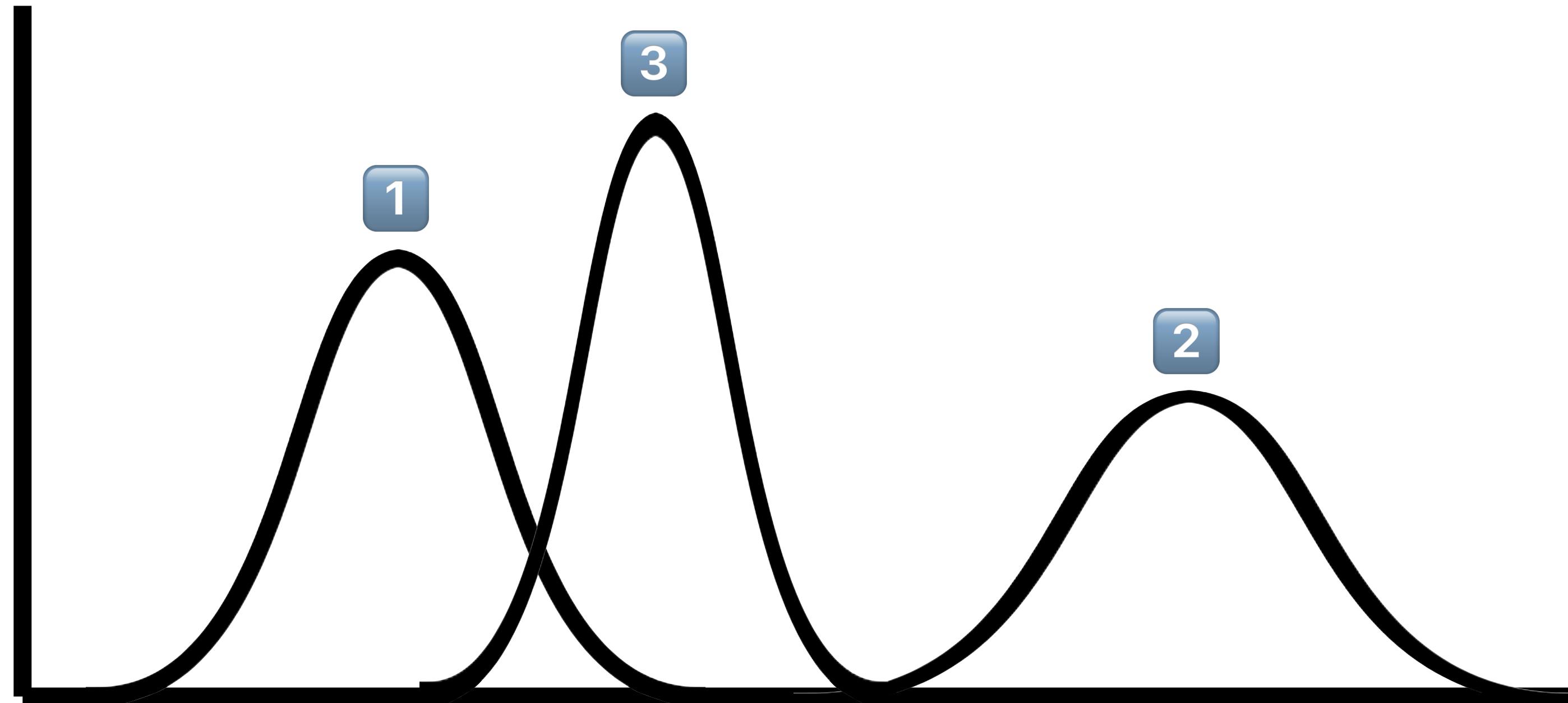
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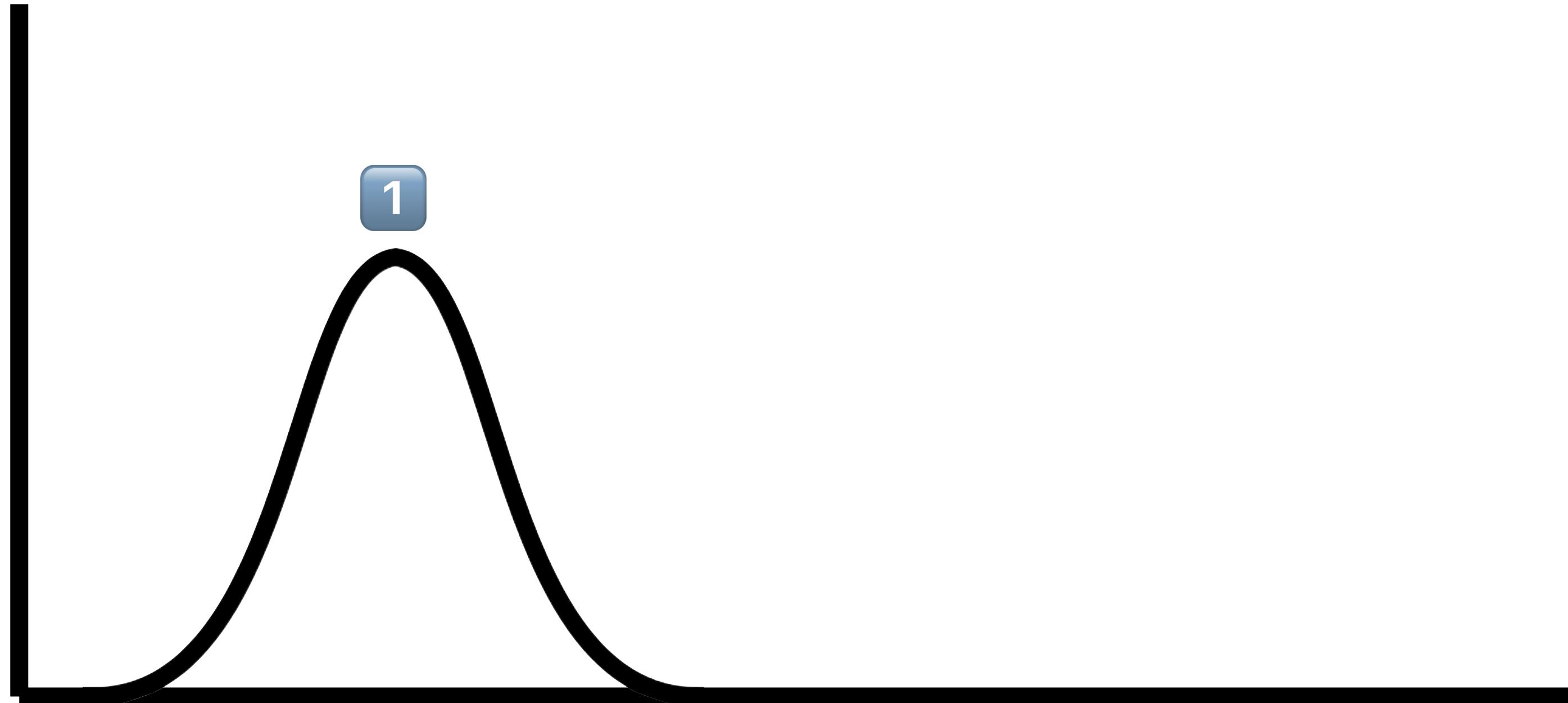
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# Extrapolating the Greybox Fuzzing Campaign

- Second key insight – *Macroscopic view*

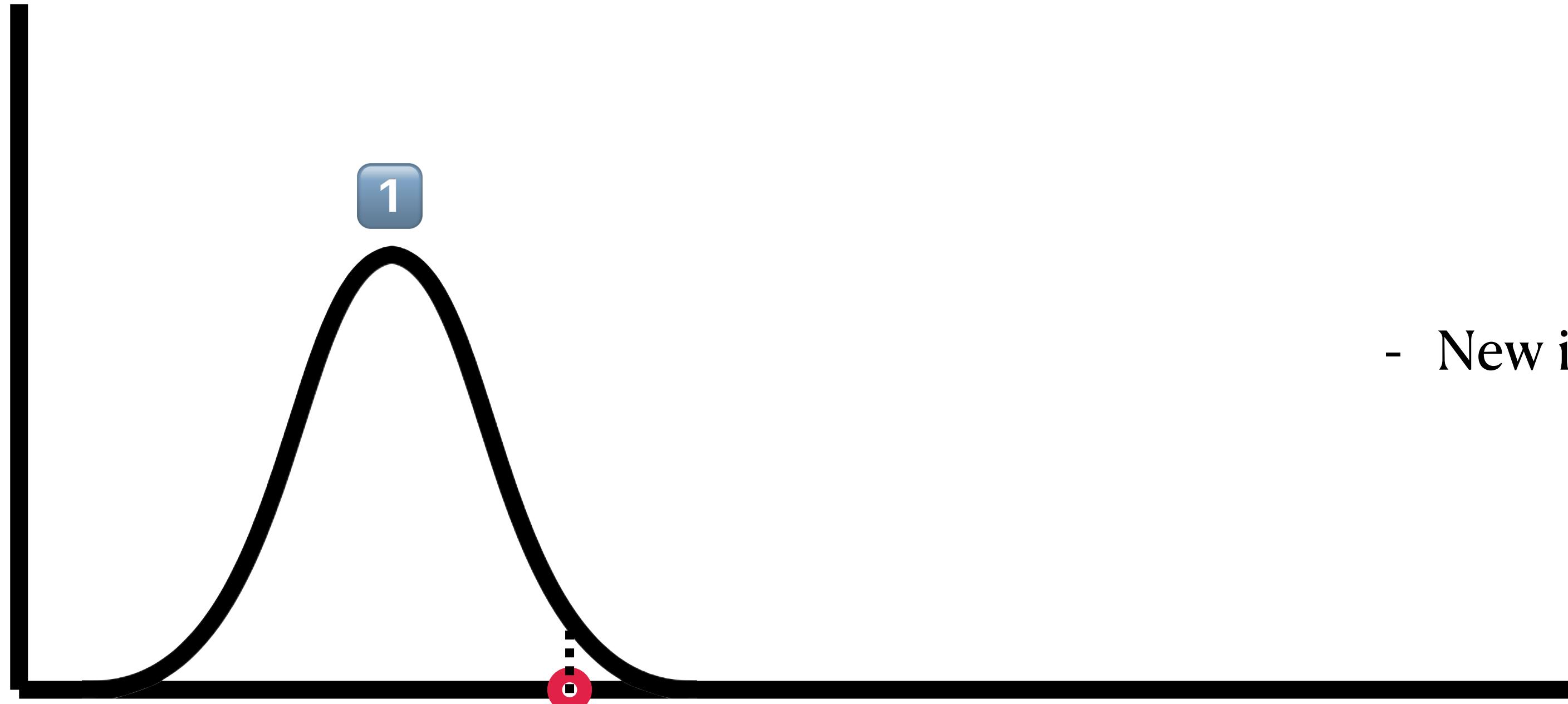
*“Greybox fuzzing’s adaptive bias could be **predictable**.”*



# Extrapolating the Greybox Fuzzing Campaign

- Second key insight – *Macroscopic view*

*“Greybox fuzzing’s adaptive bias could be **predictable**.”*

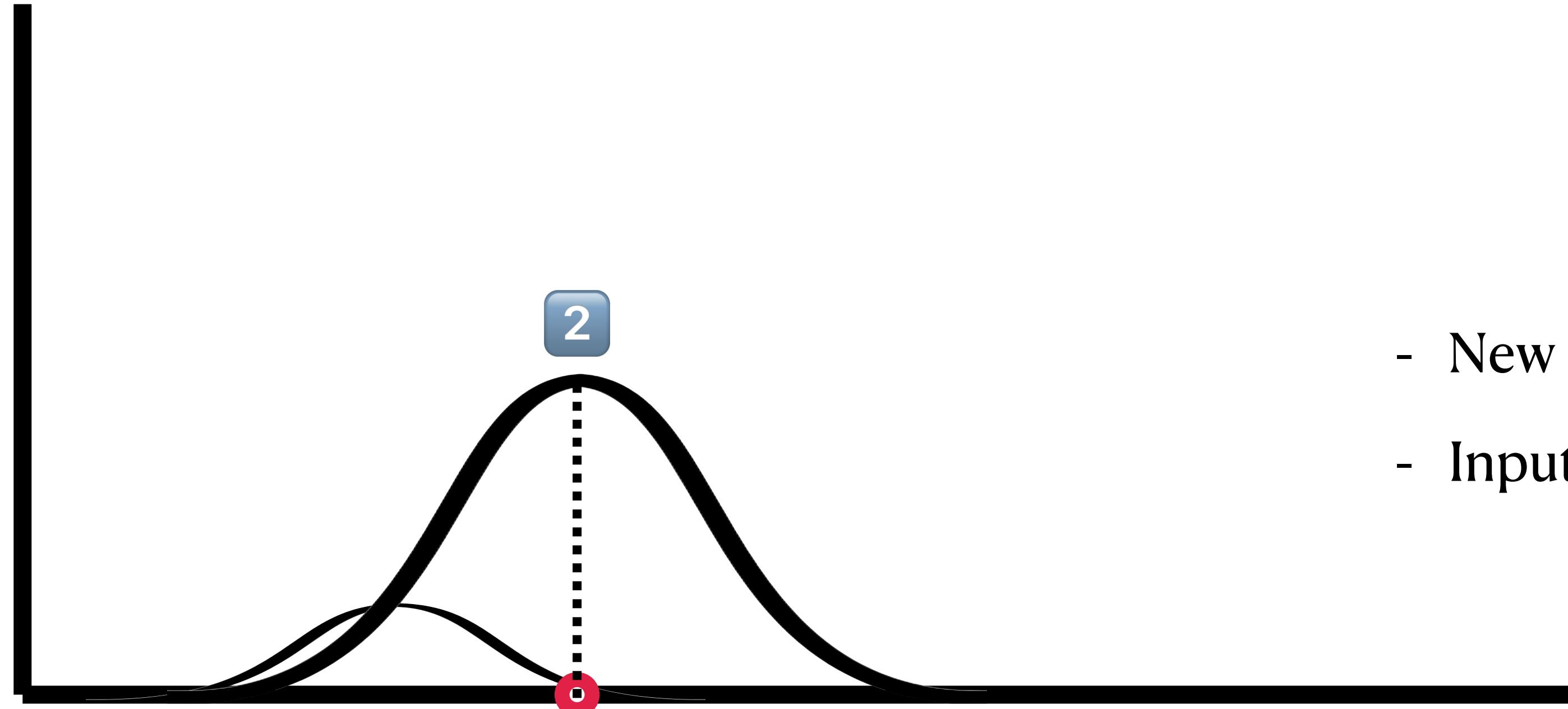


- New input that *increases coverage* is found

# Extrapolating the Greybox Fuzzing Campaign

- Second key insight – *Macroscopic view*

*“Greybox fuzzing’s adaptive bias could be **predictable**.”*

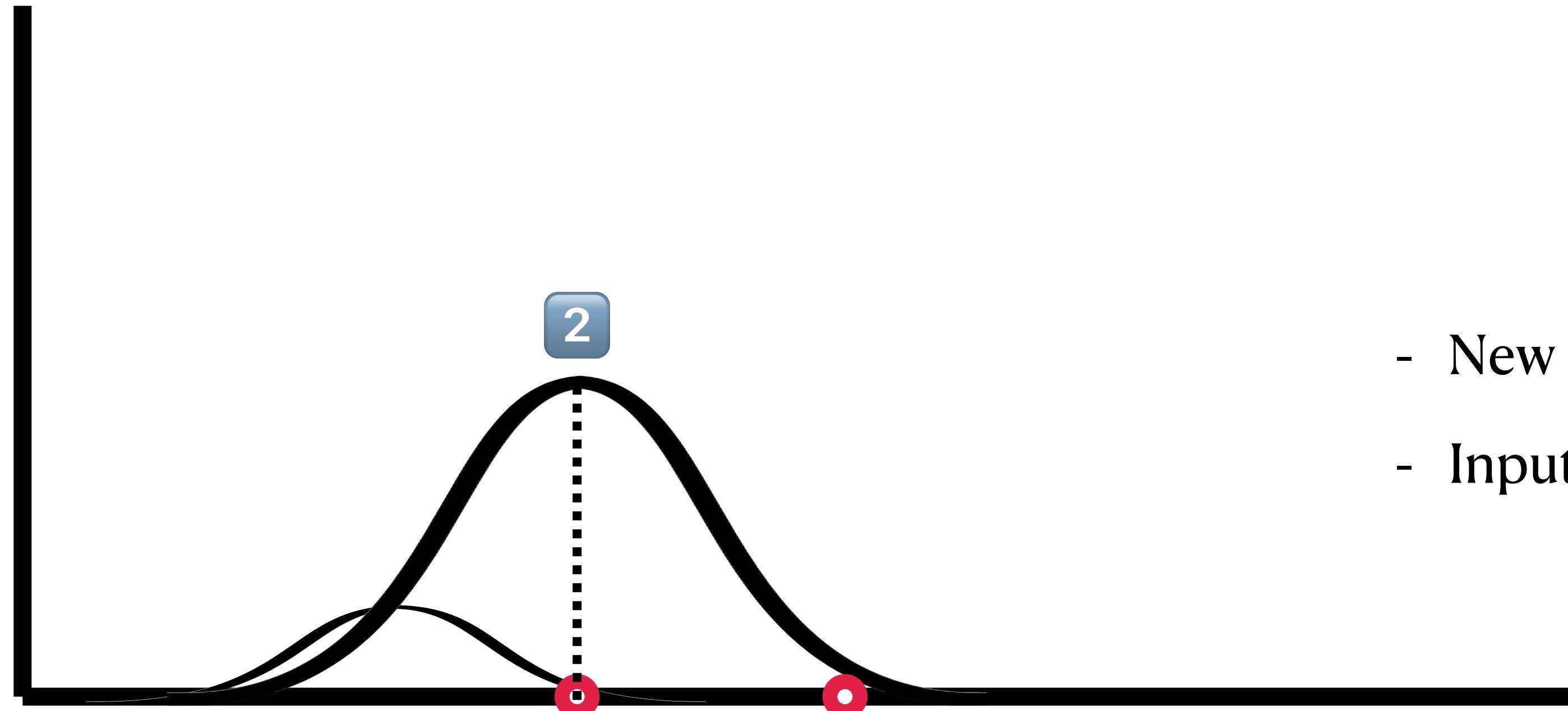


- New input that *increases coverage* is found
- Inputs around the new input are sampled

# Extrapolating the Greybox Fuzzing Campaign

- Second key insight – *Macroscopic view*

*“Greybox fuzzing’s adaptive bias could be **predictable**.”*

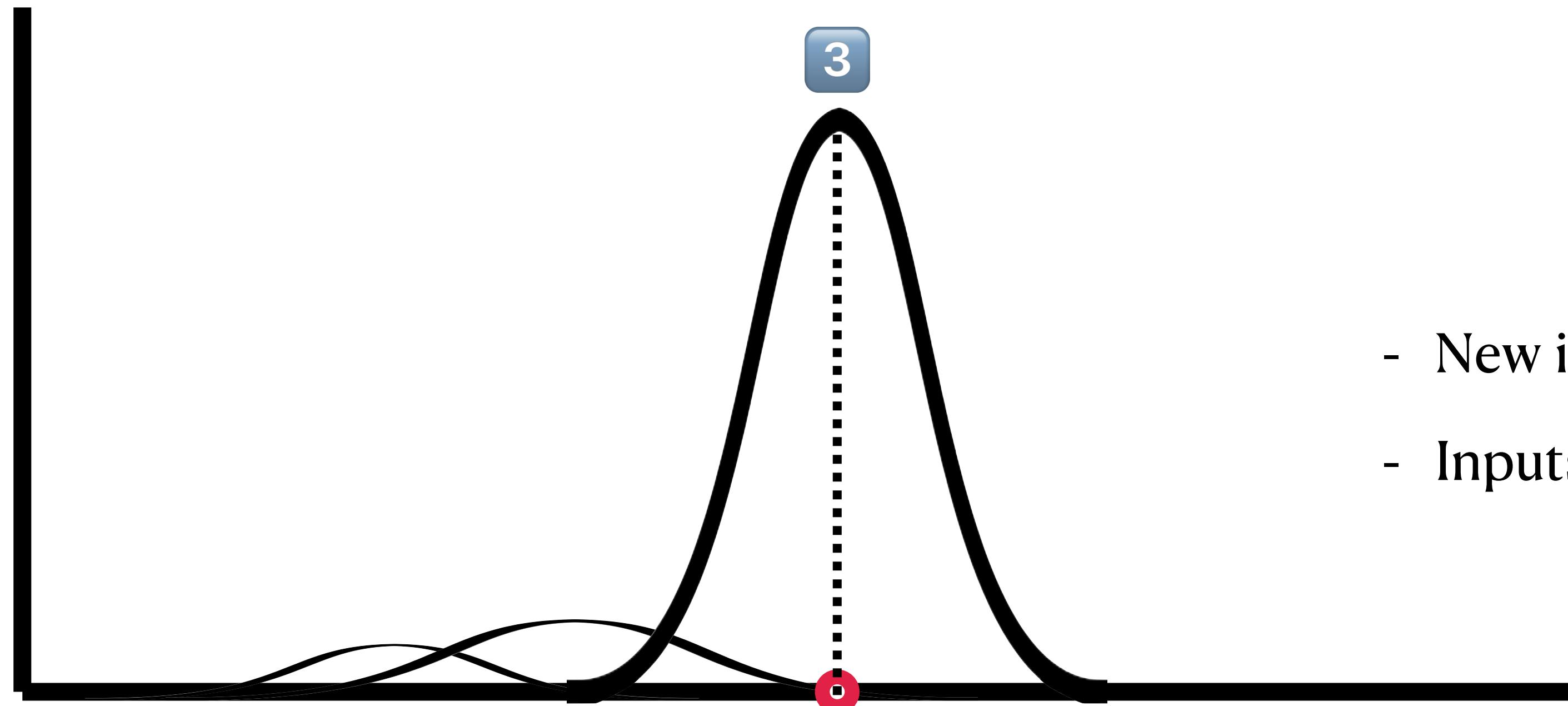


- New input that *increases coverage* is found
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# Extrapolating the Greybox Fuzzing Campaign

- Second key insight – *Macroscopic view*

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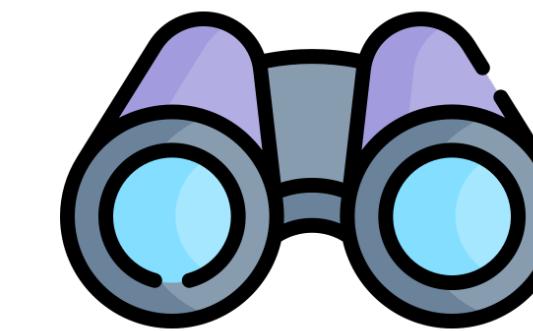
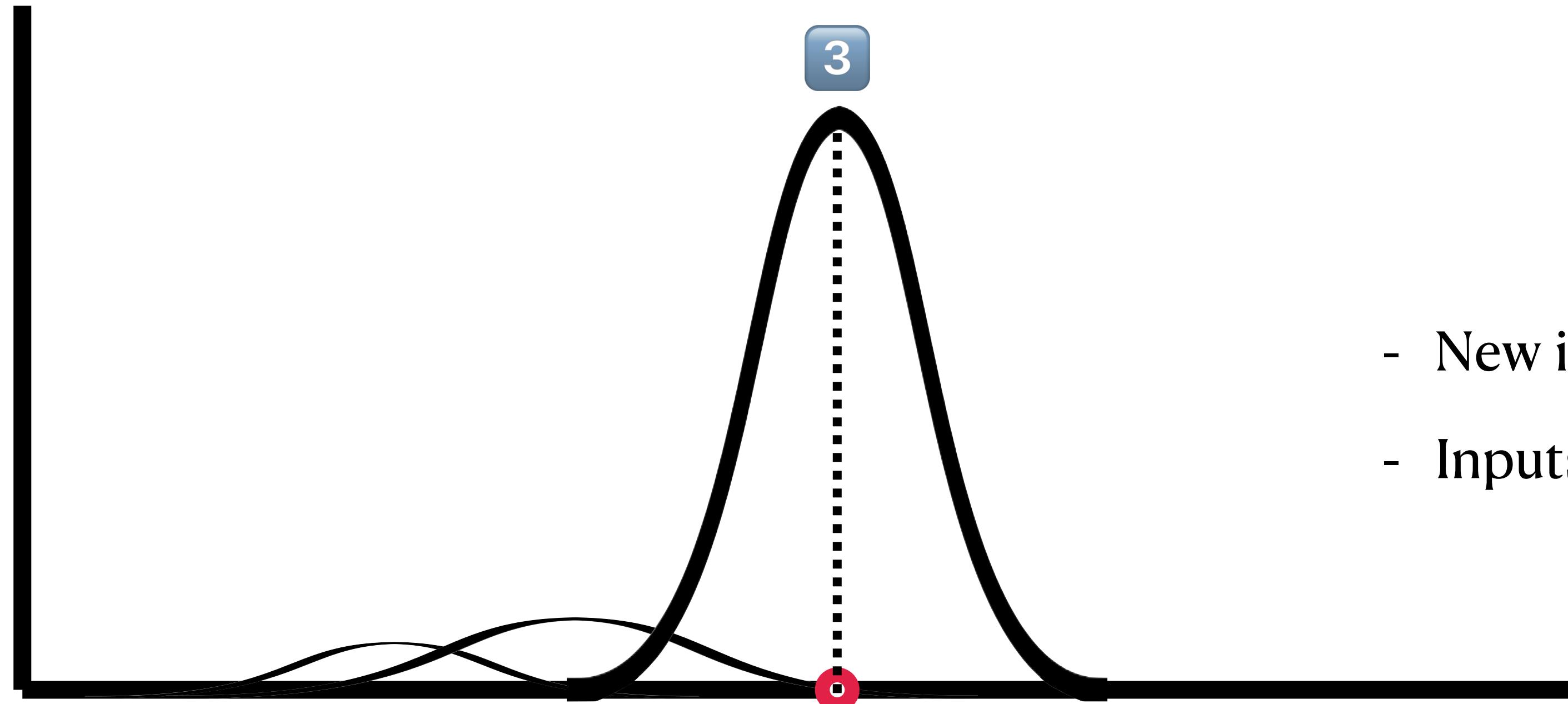


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# Extrapolating the Greybox Fuzzing Campaign

- Second key insight – *Macroscopic view*

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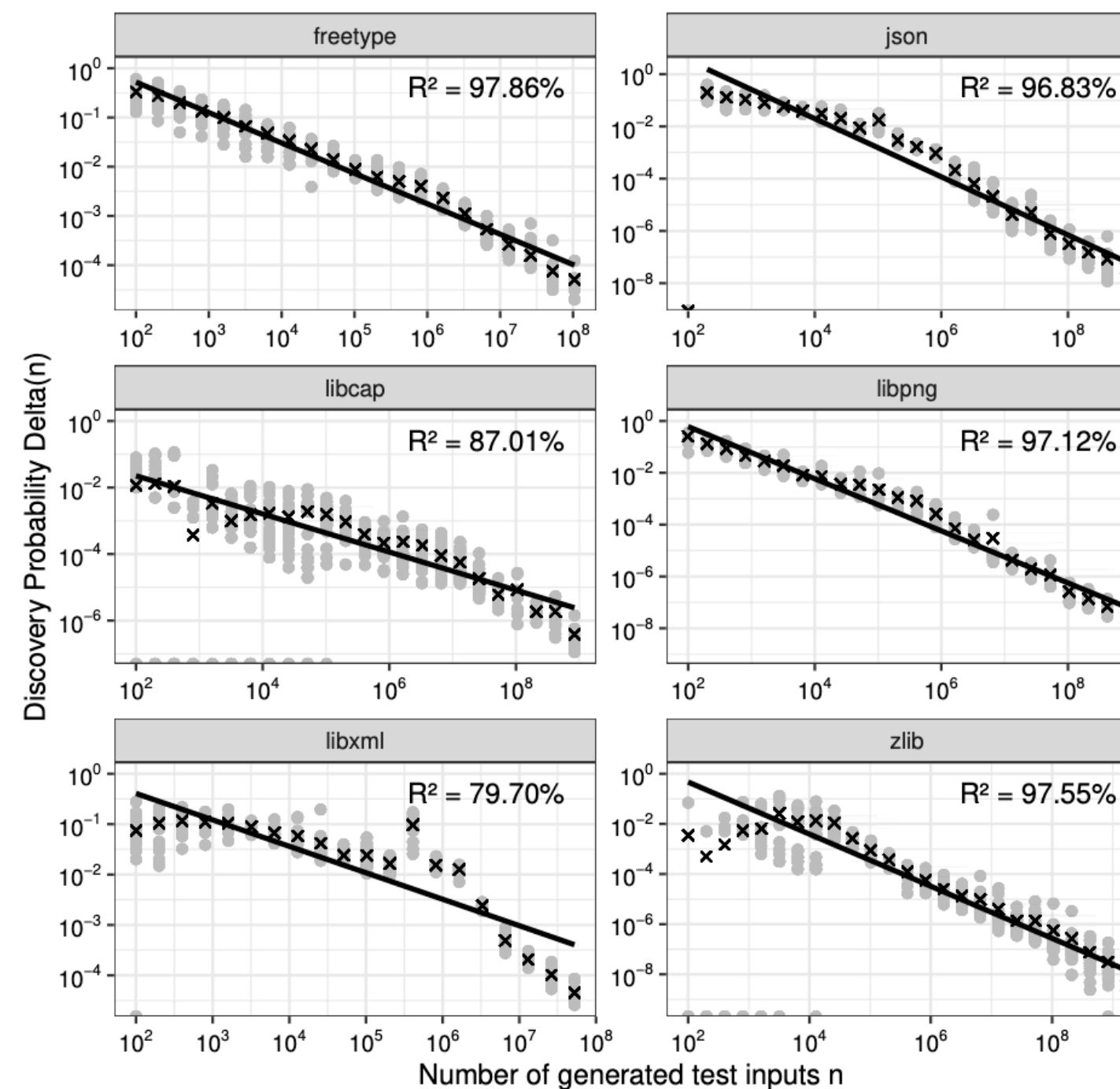


- New input that *increases coverage* is found
- Inputs around the new input are sampled

# Extrapolating the Greybox Fuzzing Campaign

- Second key insight – *Macroscopic view*

*“Greybox fuzzing’s adaptive bias could be **predictable**.”*



For example,

Böhme et al. “Estimating Residual Risk in Greybox Fuzzing.” ESEC/FSE’21

*log(# of data points) has linear relation with  
log(probability of discovering new program element)*

*(probability) discovery probability  $\neq$  coverage rate (# of new element)*

# Methodology

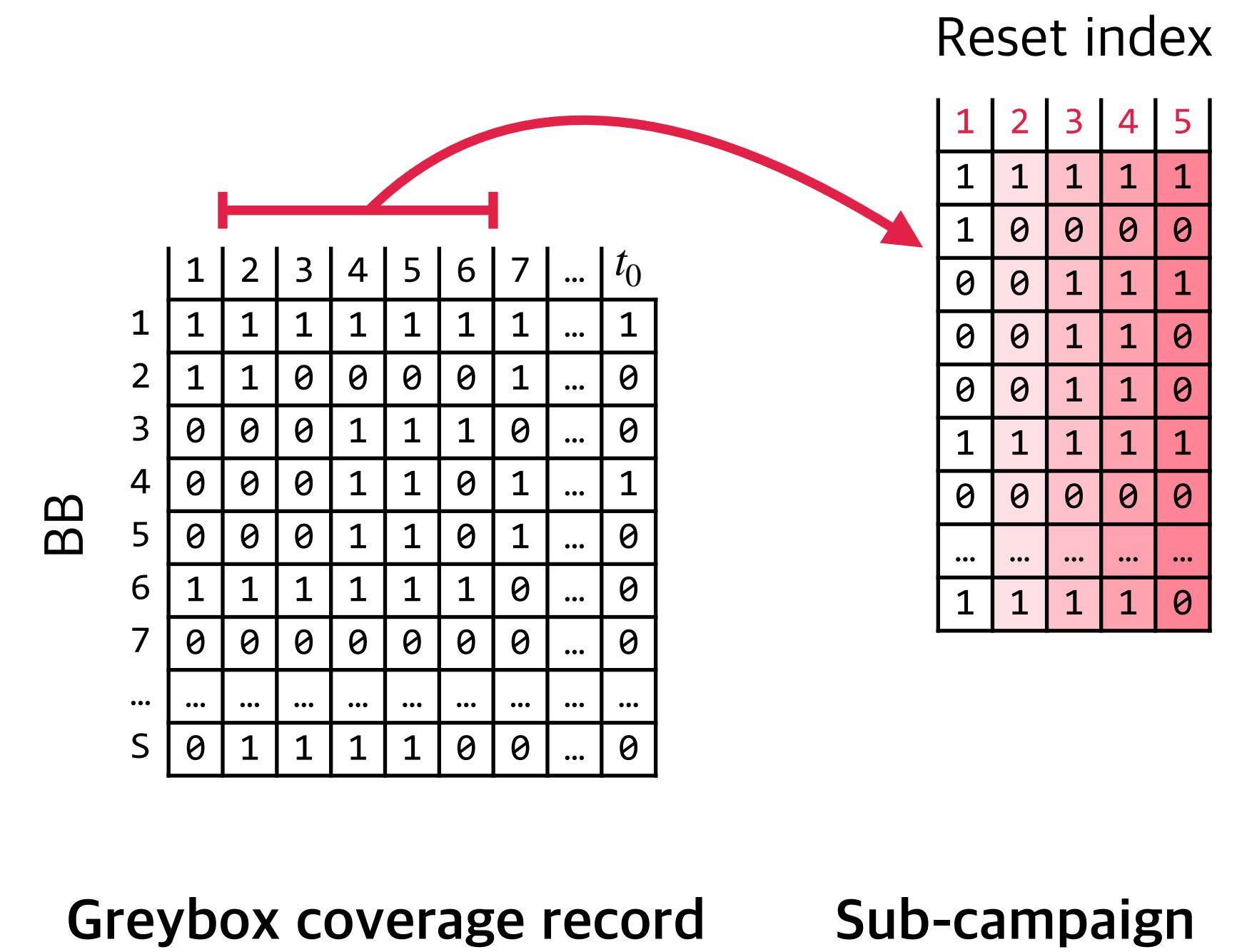
# Methodology

BB

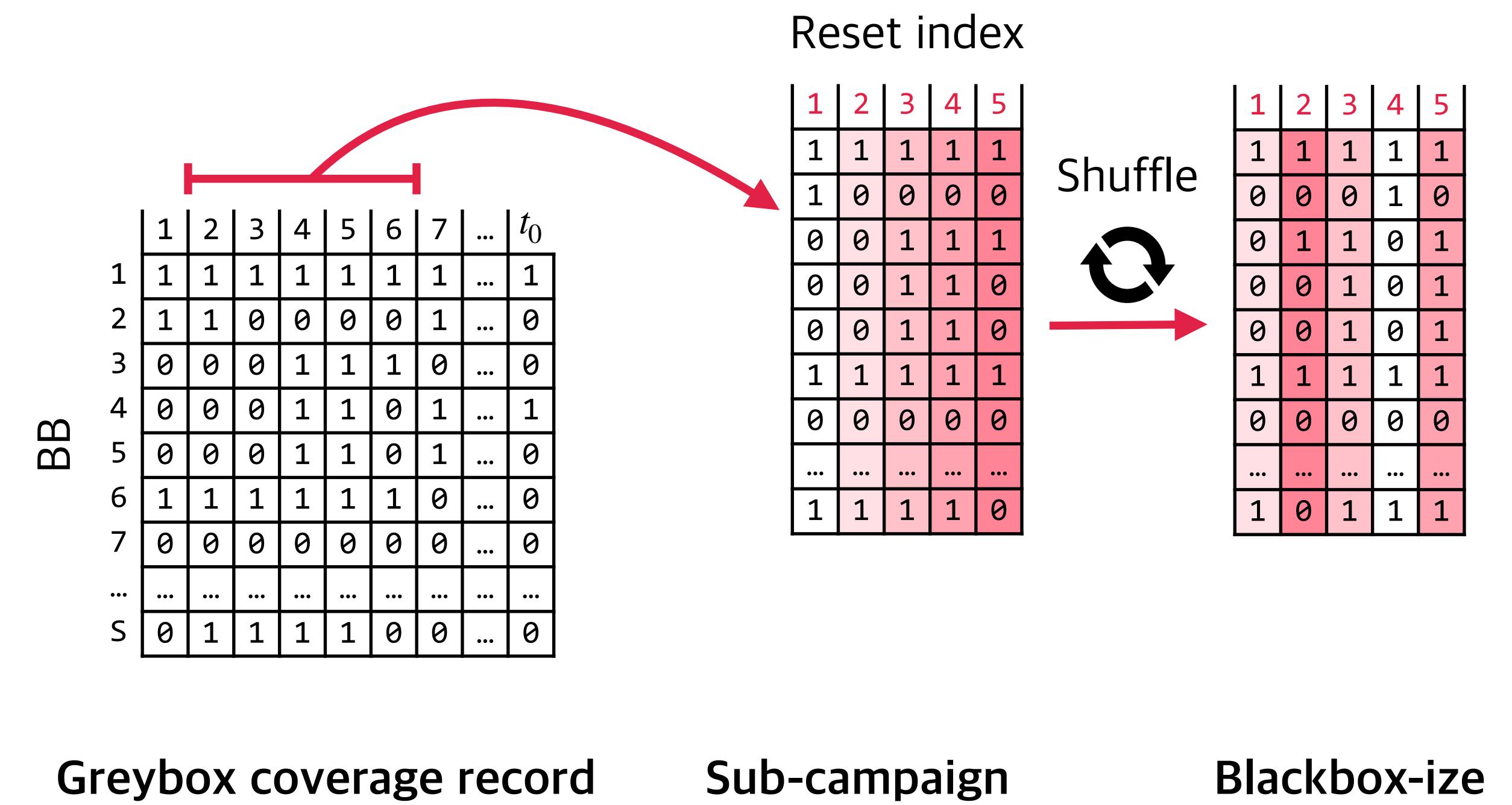
	1	2	3	4	5	6	7	...	$t_0$
1	1	1	1	1	1	1	1	...	1
2	1	1	0	0	0	0	1	...	0
3	0	0	0	1	1	1	0	...	0
4	0	0	0	1	1	0	1	...	1
5	0	0	0	1	1	0	1	...	0
6	1	1	1	1	1	1	0	...	0
7	0	0	0	0	0	0	0	...	0
...	...	...	...	...	...	...	...	...	...
S	0	1	1	1	1	0	0	...	0

Greybox coverage record

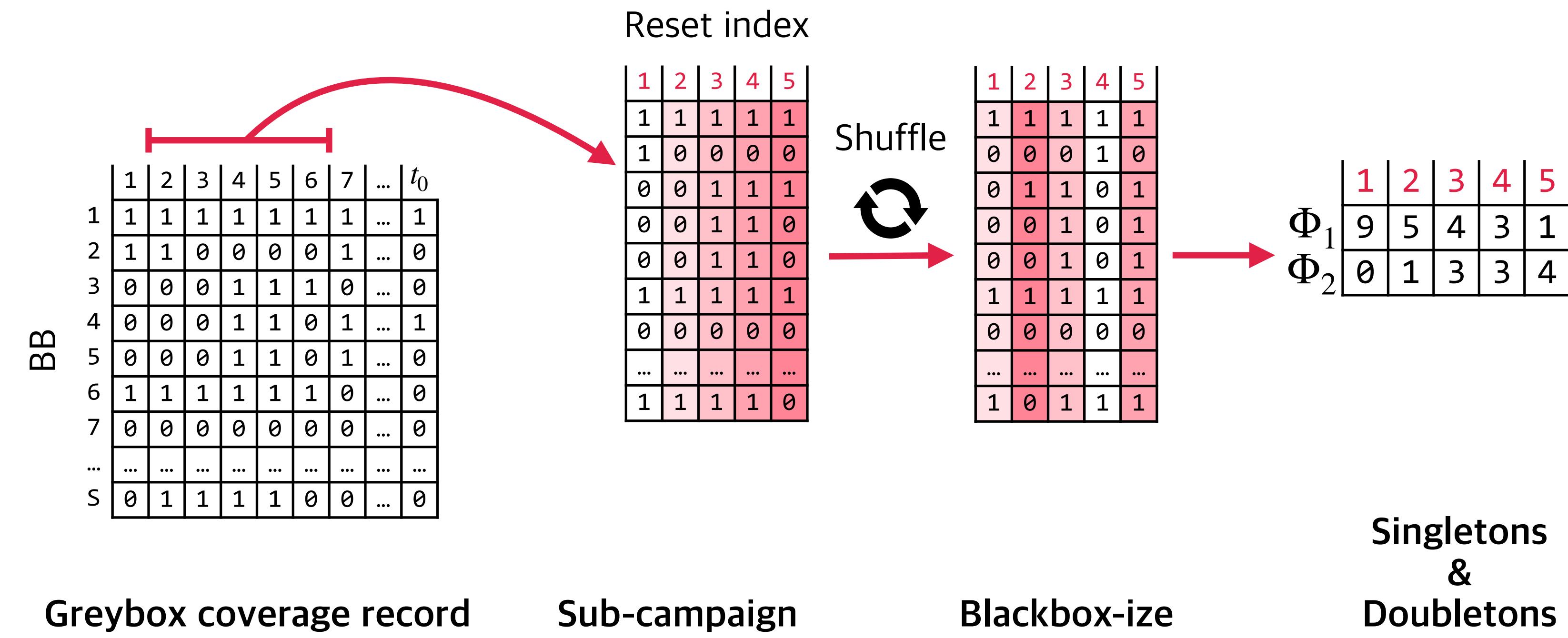
# Methodology



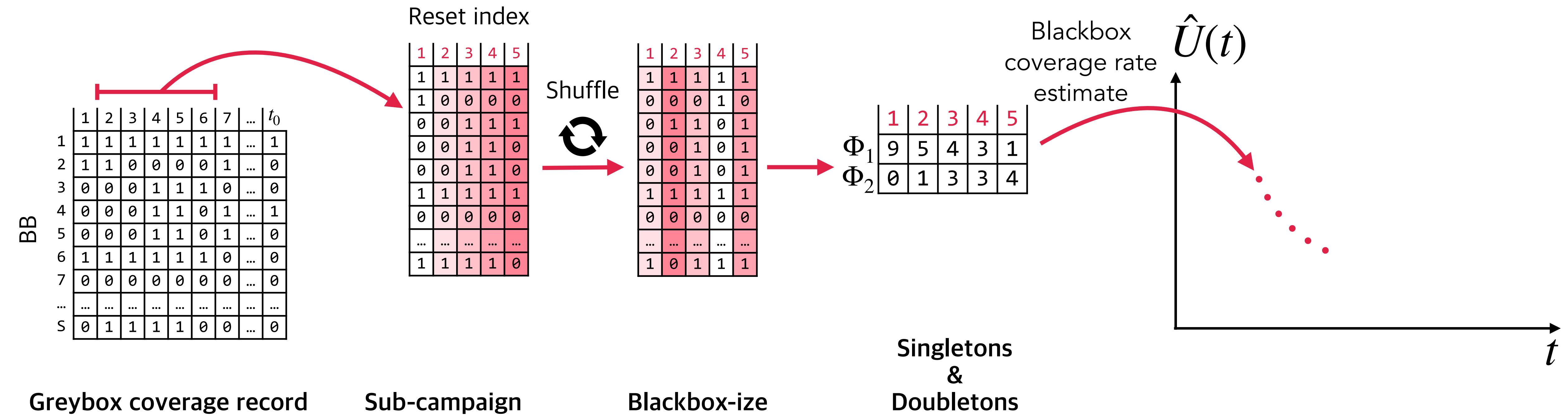
# Methodology



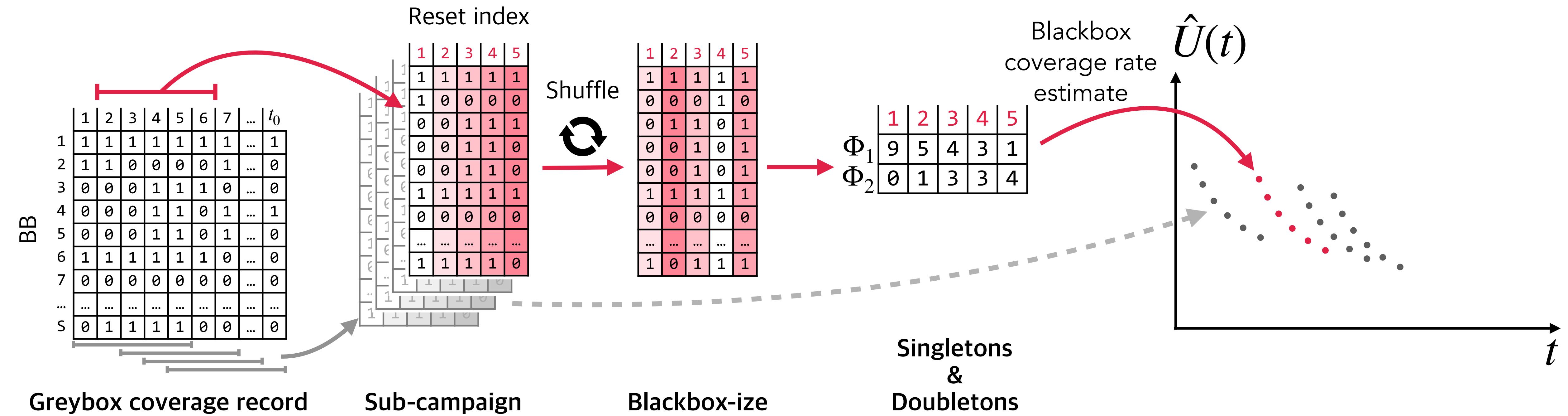
# Methodology



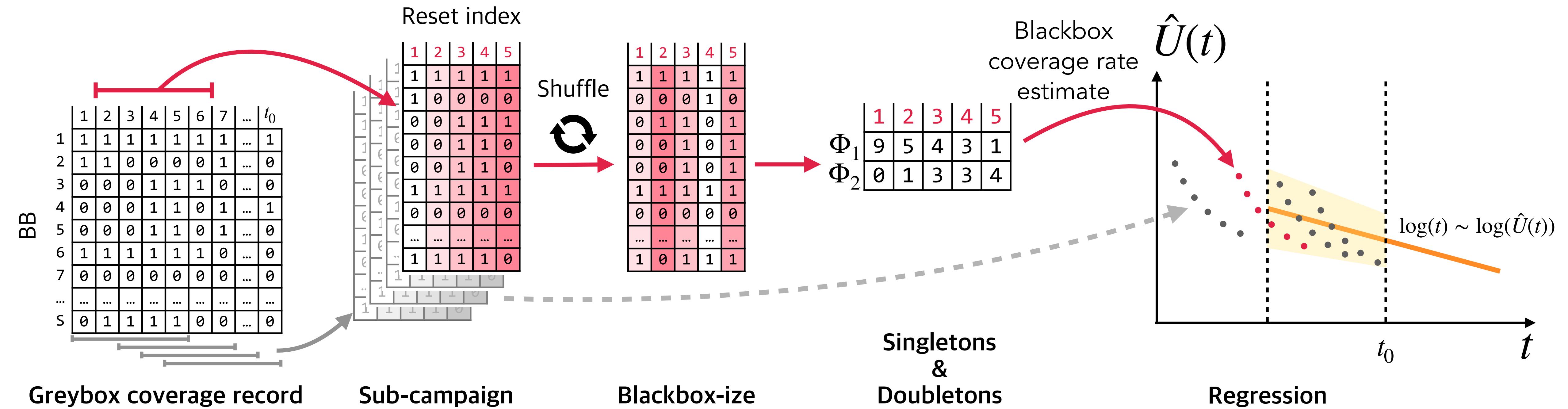
# Methodology



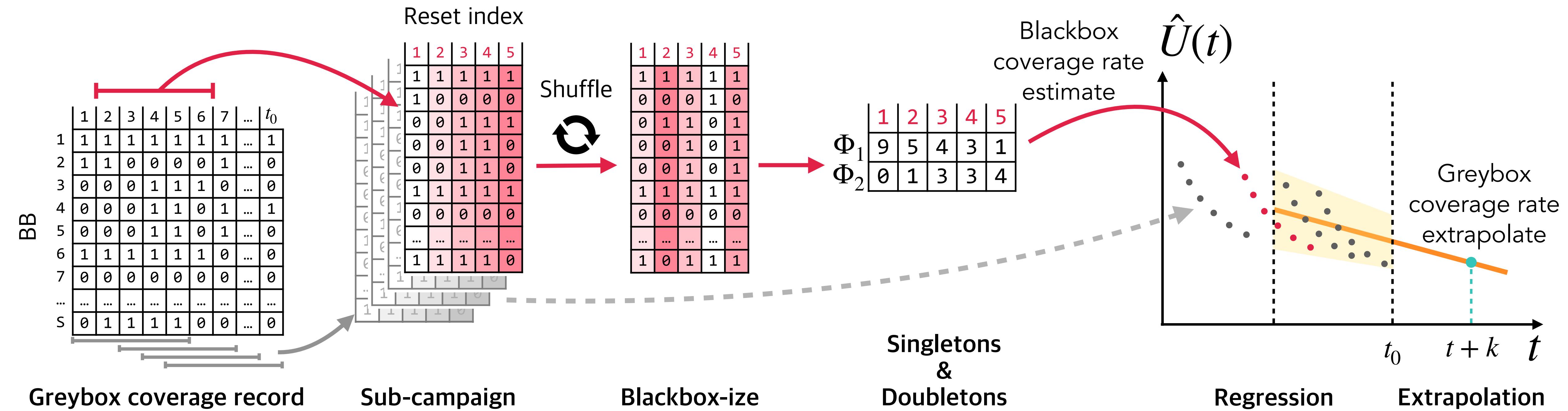
# Methodology



# Methodology



# Methodology



# RQ1. Coverage Rate Prediction

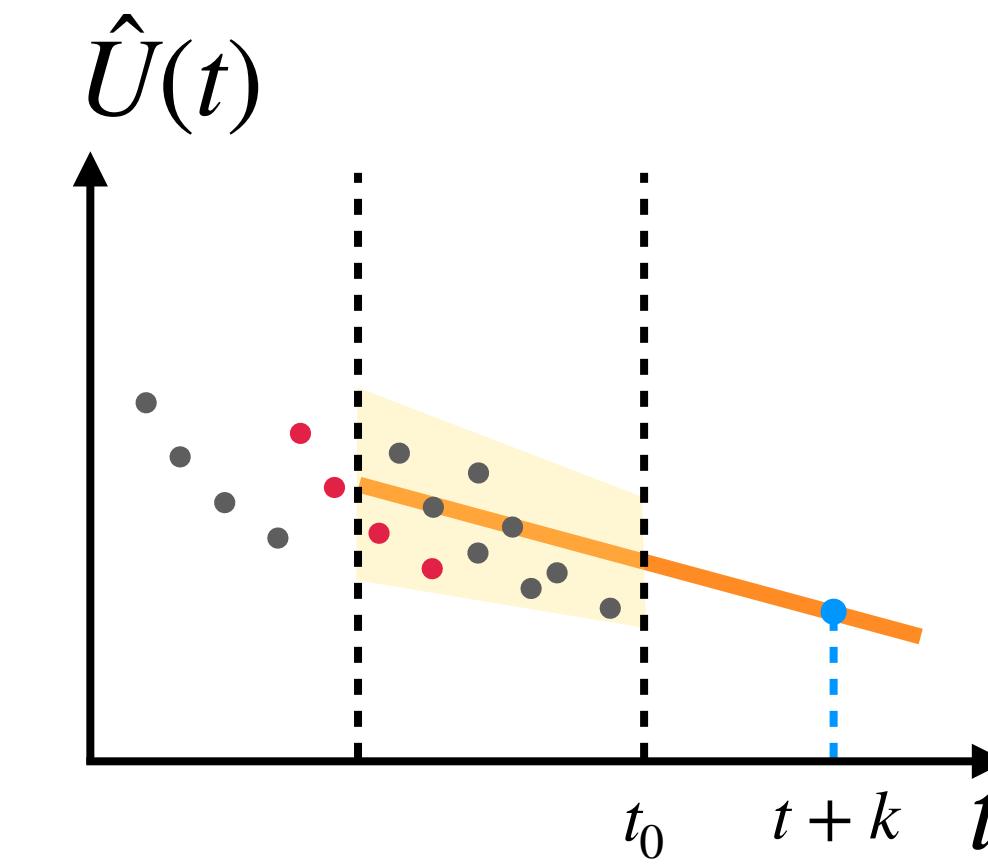
Q. How accurate is our *regression model considering the adaptive bias* compared to the *existing blackbox extrapolation model*?

**Existing  $\hat{U}(t + k)$   
Extrapolator**

$$\hat{\Phi}_0 \left[ 1 - \left( 1 - \frac{\Phi_1}{t\hat{\Phi}_0 + \Phi_1} \right)^k \right]$$

Ignores the adaptive bias

VS



**Our  $\hat{U}(t + k)$   
Extrapolator**

Consider the adaptive bias

# RQ1. Coverage Rate Prediction

Q. How accurate is our *regression model considering the adaptive bias* compared to the *existing blackbox extrapolation model*?

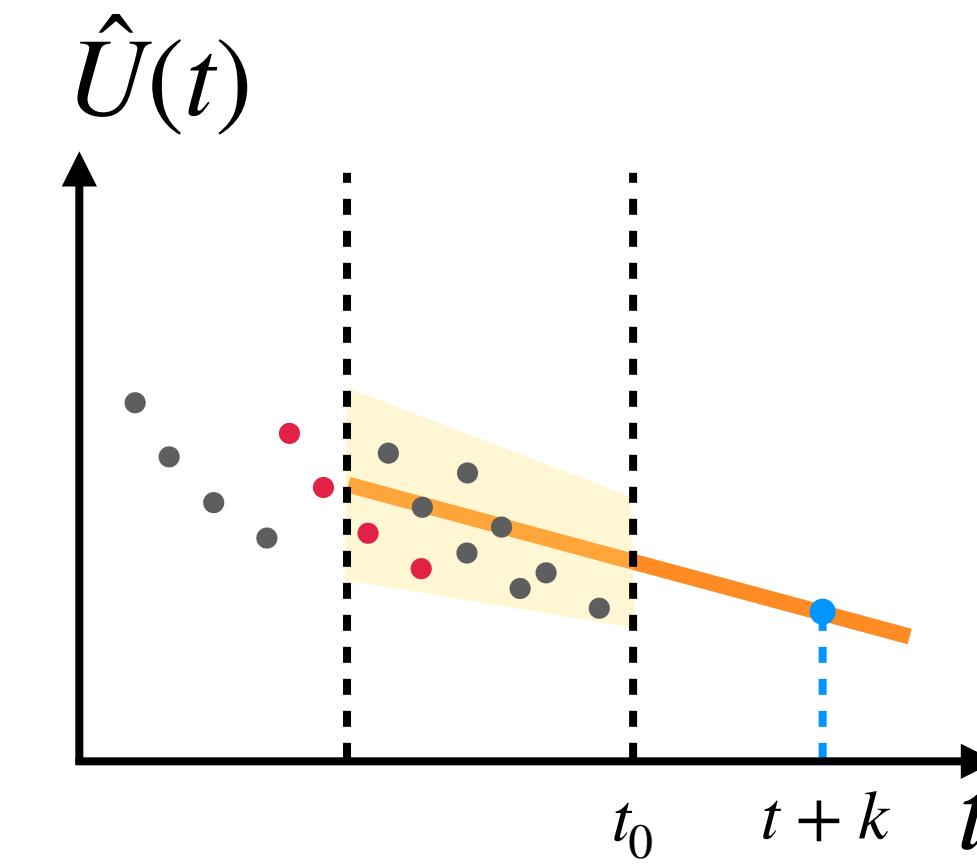
- Subject program: five open-source C libraries
- Evaluation Scenario:

**Existing  $\hat{U}(t + k)$**   
**Extrapolator**

$$\hat{\Phi}_0 \left[ 1 - \left( 1 - \frac{\Phi_1}{t\hat{\Phi}_0 + \Phi_1} \right)^k \right]$$

Ignores the adaptive bias

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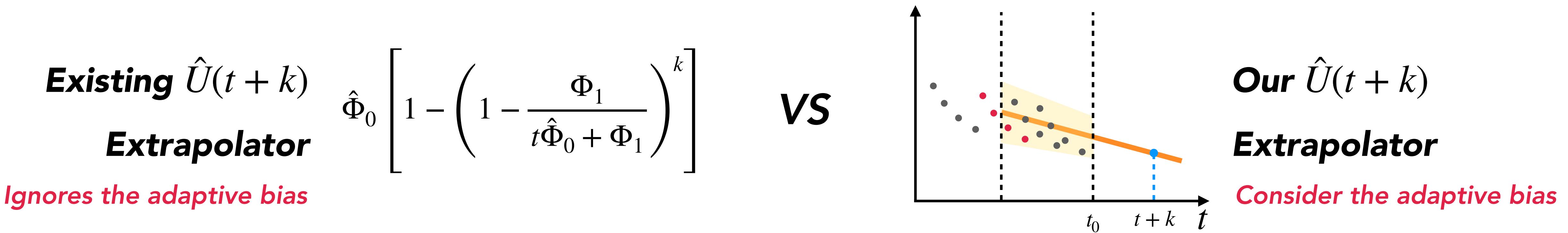


**Our  $\hat{U}(t + k)$**   
**Extrapolator**  
Consider the adaptive bias

# RQ1. Coverage Rate Prediction

Q. How accurate is our *regression model considering the adaptive bias* compared to the *existing blackbox extrapolation model*?

- Subject program: five open-source C libraries
- Evaluation Scenario: 1) run the greybox fuzzer until having  $t$  data points  
2) apply each extrapolator to extrapolate  $\hat{U}(t + k)$   
3) run the greybox fuzzer for  $k$  more data points to get  $U(t + k)$ .



# RQ1. Coverage Rate Prediction

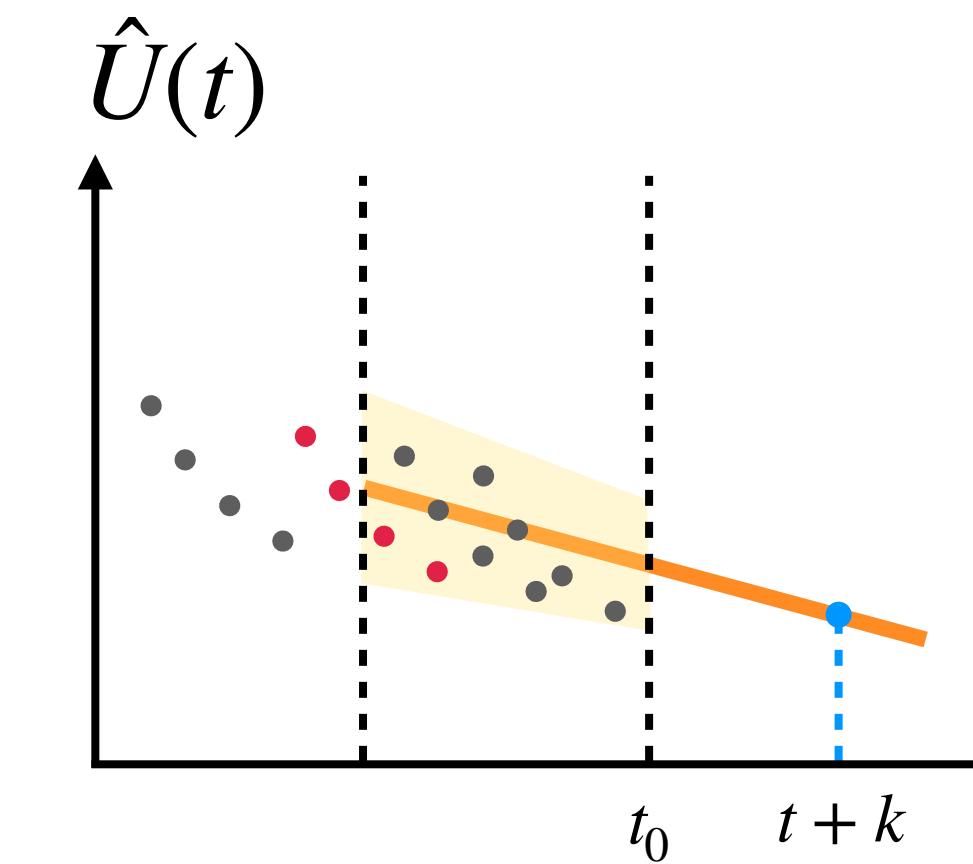
Q. How accurate is our *regression model considering the adaptive bias* compared to the *existing blackbox extrapolation model*?

- Subject program: five open-source C libraries
- Evaluation Scenario: 1) run the greybox fuzzer until having  $t$  data points  
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**Existing  $\hat{U}(t + k)$**   
**Extrapolator**  
*Ignores the adaptive bias*

$$\hat{\Phi}_0 \left[ 1 - \left( 1 - \frac{\Phi_1}{t\hat{\Phi}_0 + \Phi_1} \right)^k \right]$$

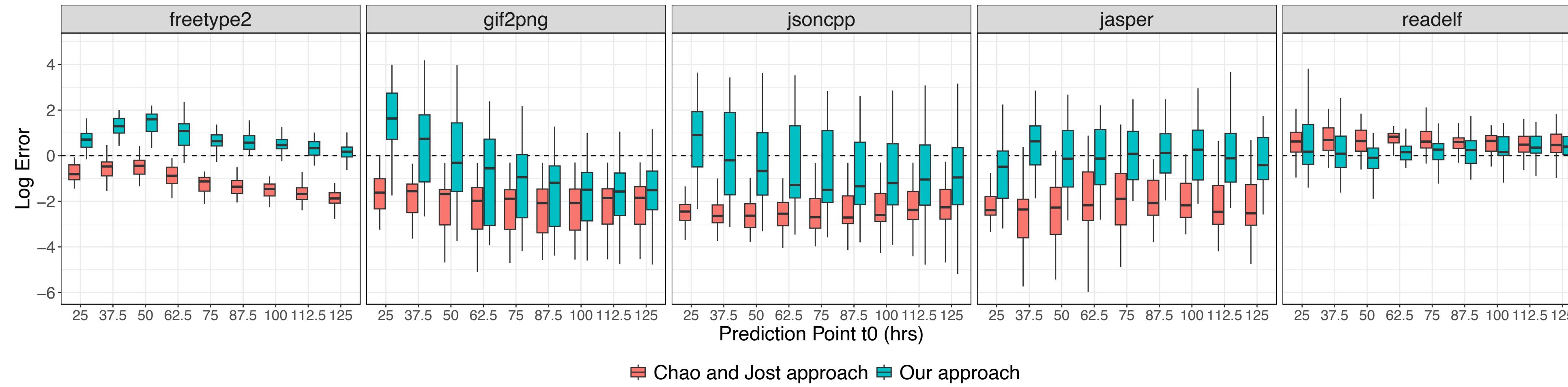
VS



**Our  $\hat{U}(t + k)$**   
**Extrapolator**  
*Consider the adaptive bias*

# Result 1: Coverage Rate Prediction

**Difference between  $\log(U(t + k))$  vs.  $\log(\hat{U}(t + k))$**

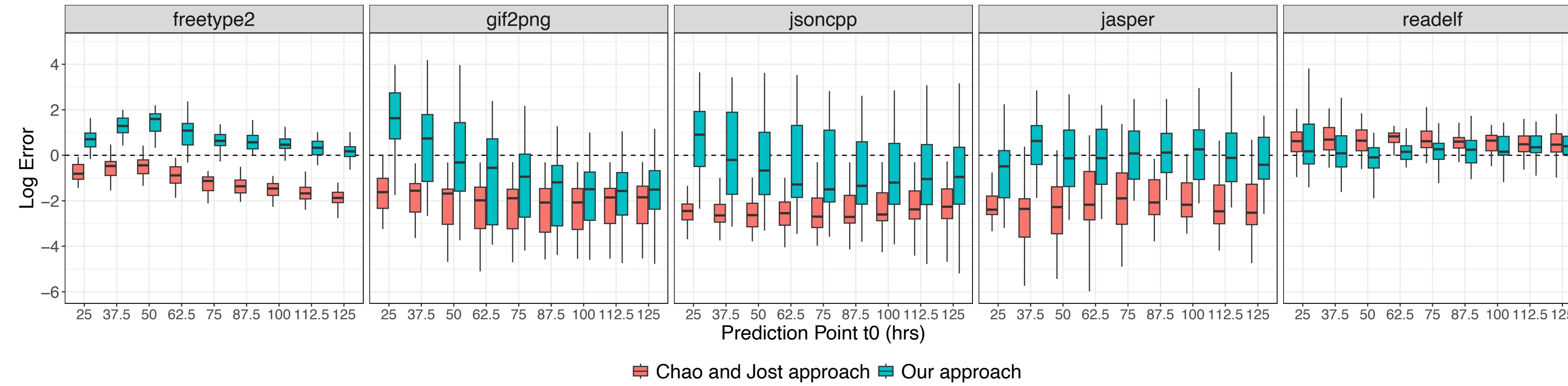


“Our extrapolator exhibits ***at least one order of magnitude lower absolute bias*** than the existing extrapolator for ***4 out of 5 subjects, especially for long-term prediction.***”

(close to 1 is better)  
The average ratio  $U(t + k)/\hat{U}(t + k)$ :  
[Existing] 1.6 - 800 [Ours] 1.17 - 7  
across all subjects.

# Result 1: Coverage Rate Prediction

**Difference between  $\log(U(t + k))$  vs.  $\log(\hat{U}(t + k))$**



“Our extrapolator exhibits  
***at least one order of magnitude lower absolute bias***  
than the existing extrapolator for *4 out of 5 subjects*,  
especially for long-term prediction.”

⇒ **Well-handled the adaptive bias**

(close to 1 is better)  
The average ratio  $U(t + k)/\hat{U}(t + k)$ :  
[Existing] 1.6 - 800 [Ours] 1.17 - 7  
across all subjects.

# RQ2. Stopping-Time Estimation

Q. Is our *extrapolator* useful for the stopping criteria?

**Greybox Coverage Record**

	1	2	3	4	5	6	7	...	$t_0$
1	1	1	1	1	1	1	1	...	1
2	1	1	0	0	0	0	1	...	0
3	0	0	0	1	1	1	0	...	0
4	0	0	0	1	1	0	1	...	1
5	0	0	0	1	1	0	1	...	0
6	1	1	1	1	1	1	0	...	0
7	0	0	0	0	0	0	0	...	0
...	...	...	...	...	...	...	...	...	...
S	0	1	1	1	1	0	0	...	0

&

*U: Target coverage rate*

# RQ2. Stopping-Time Estimation

Q. Is our *extrapolator* useful for the stopping criteria?

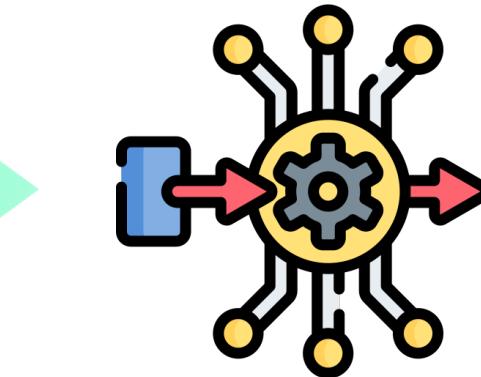
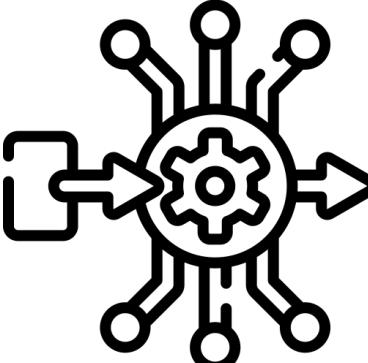
**Greybox Coverage Record**

	1	2	3	4	5	6	7	...	$t_0$
1	1	1	1	1	1	1	1	...	1
2	1	1	0	0	0	0	1	...	0
3	0	0	0	1	1	1	0	...	0
4	0	0	0	1	1	0	1	...	1
5	0	0	0	1	1	0	1	...	0
6	1	1	1	1	1	1	0	...	0
7	0	0	0	0	0	0	0	...	0
...	...	...	...	...	...	...	...	...	...
S	0	1	1	1	1	0	0	...	0

&

*U: Target coverage rate*

**Existing  
Extrapolator**



**Our  
Extrapolator**

# RQ2. Stopping-Time Estimation

Q. Is our *extrapolator* useful for the stopping criteria?

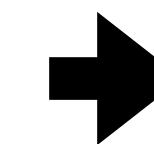
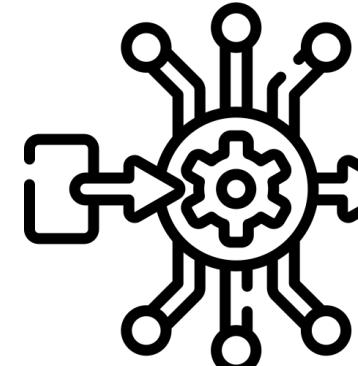
**Greybox Coverage Record**

	1	2	3	4	5	6	7	...	$t_0$
1	1	1	1	1	1	1	1	...	1
2	1	1	0	0	0	0	1	...	0
3	0	0	0	1	1	1	0	...	0
4	0	0	0	1	1	0	1	...	1
5	0	0	0	1	1	0	1	...	0
6	1	1	1	1	1	1	0	...	0
7	0	0	0	0	0	0	0	...	0
...	...	...	...	...	...	...	...	...	...
S	0	1	1	1	1	0	0	...	0

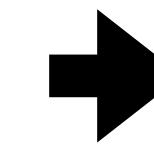
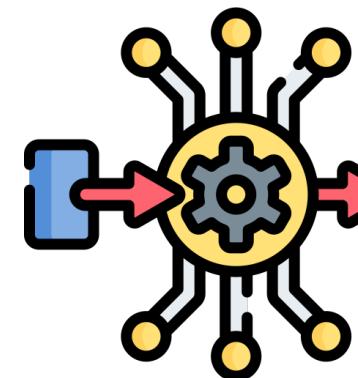
&

*U: Target coverage rate*

**Existing  
Extrapolator**



$t'$



$t''$

**Our  
Extrapolator**      **Estimated time**

# RQ2. Stopping-Time Estimation

Q. Is our *extrapolator* useful for the stopping criteria?

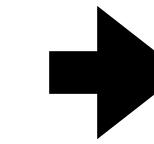
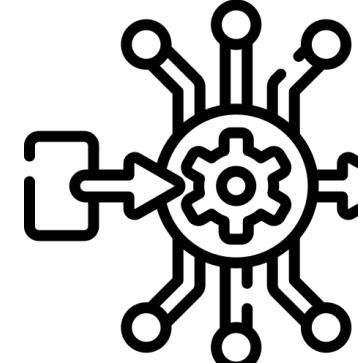
**Greybox Coverage Record**

	1	2	3	4	5	6	7	...	$t_0$
1	1	1	1	1	1	1	1	...	1
2	1	1	0	0	0	0	1	...	0
3	0	0	0	1	1	1	0	...	0
4	0	0	0	1	1	0	1	...	1
5	0	0	0	1	1	0	1	...	0
6	1	1	1	1	1	1	0	...	0
7	0	0	0	0	0	0	0	...	0
...	...	...	...	...	...	...	...	...	...
S	0	1	1	1	1	0	0	...	0

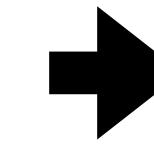
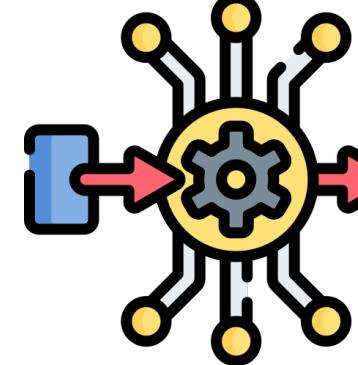
&

*U*: Target coverage rate

**Existing  
Extrapolator**



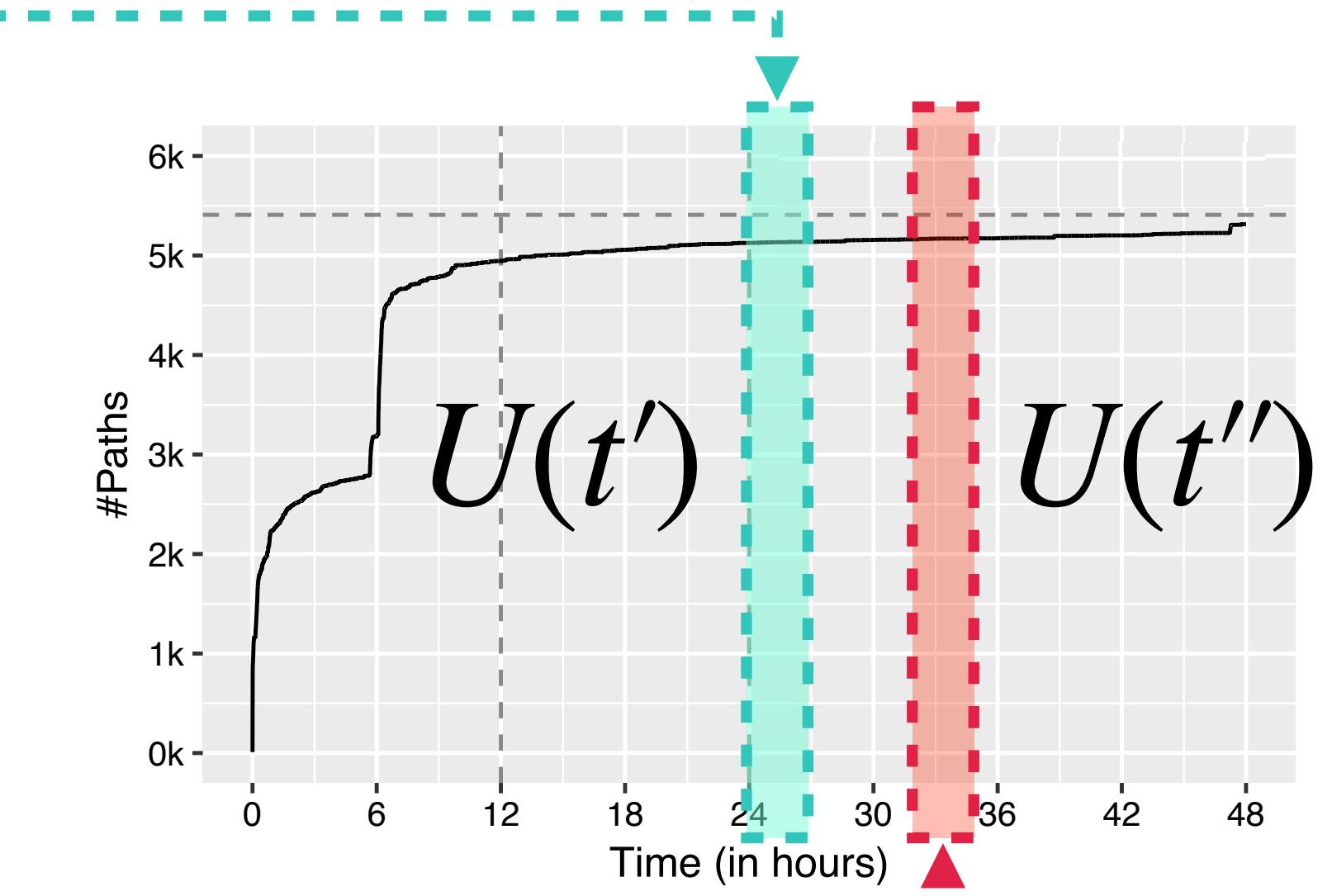
**Our  
Extrapolator**



**Estimated time**

$t'$

$t''$



**Actual  
coverage rate**

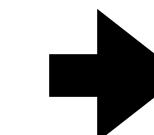
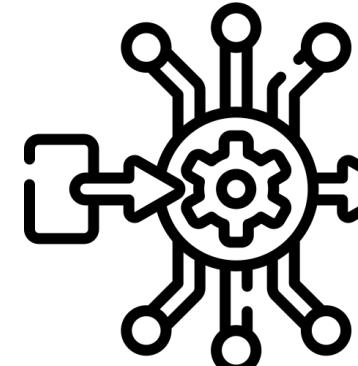
# RQ2. Stopping-Time Estimation

Q. Is our *extrapolator* useful for the stopping criteria?

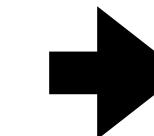
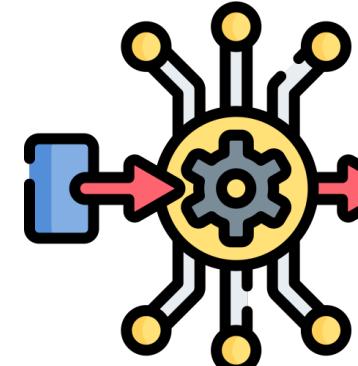
**Greybox Coverage Record**

	1	2	3	4	5	6	7	...	$t_0$
1	1	1	1	1	1	1	1	...	1
2	1	1	0	0	0	0	1	...	0
3	0	0	0	1	1	1	0	...	0
4	0	0	0	1	1	0	1	...	1
5	0	0	0	1	1	0	1	...	0
6	1	1	1	1	1	1	0	...	0
7	0	0	0	0	0	0	0	...	0
...	...	...	...	...	...	...	...	...	...
S	0	1	1	1	1	0	0	...	0

**Existing  
Extrapolator**



$t'$



$t''$

**Our  
Extrapolator**

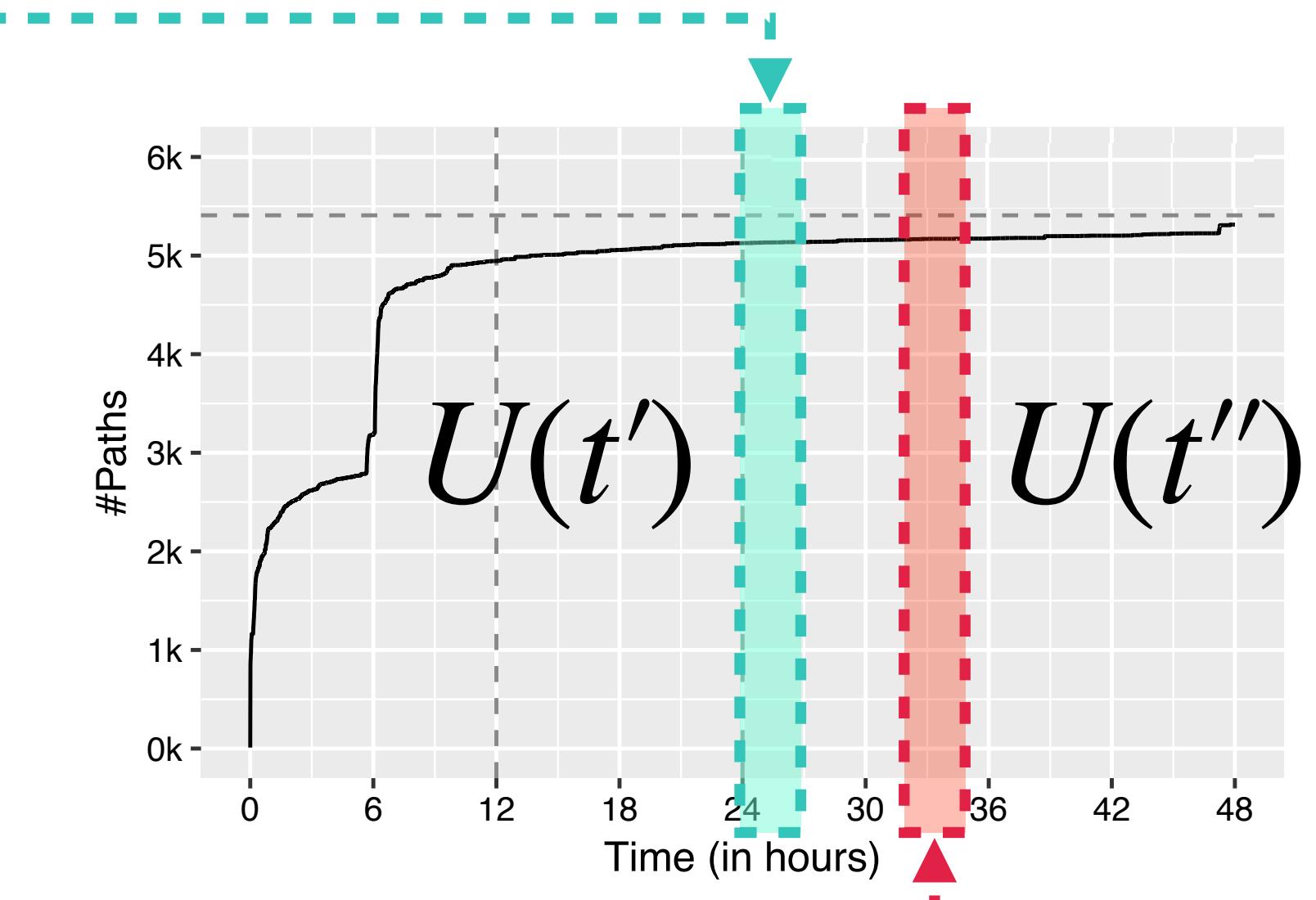
**Estimated time**

**Actual  
coverage rate**

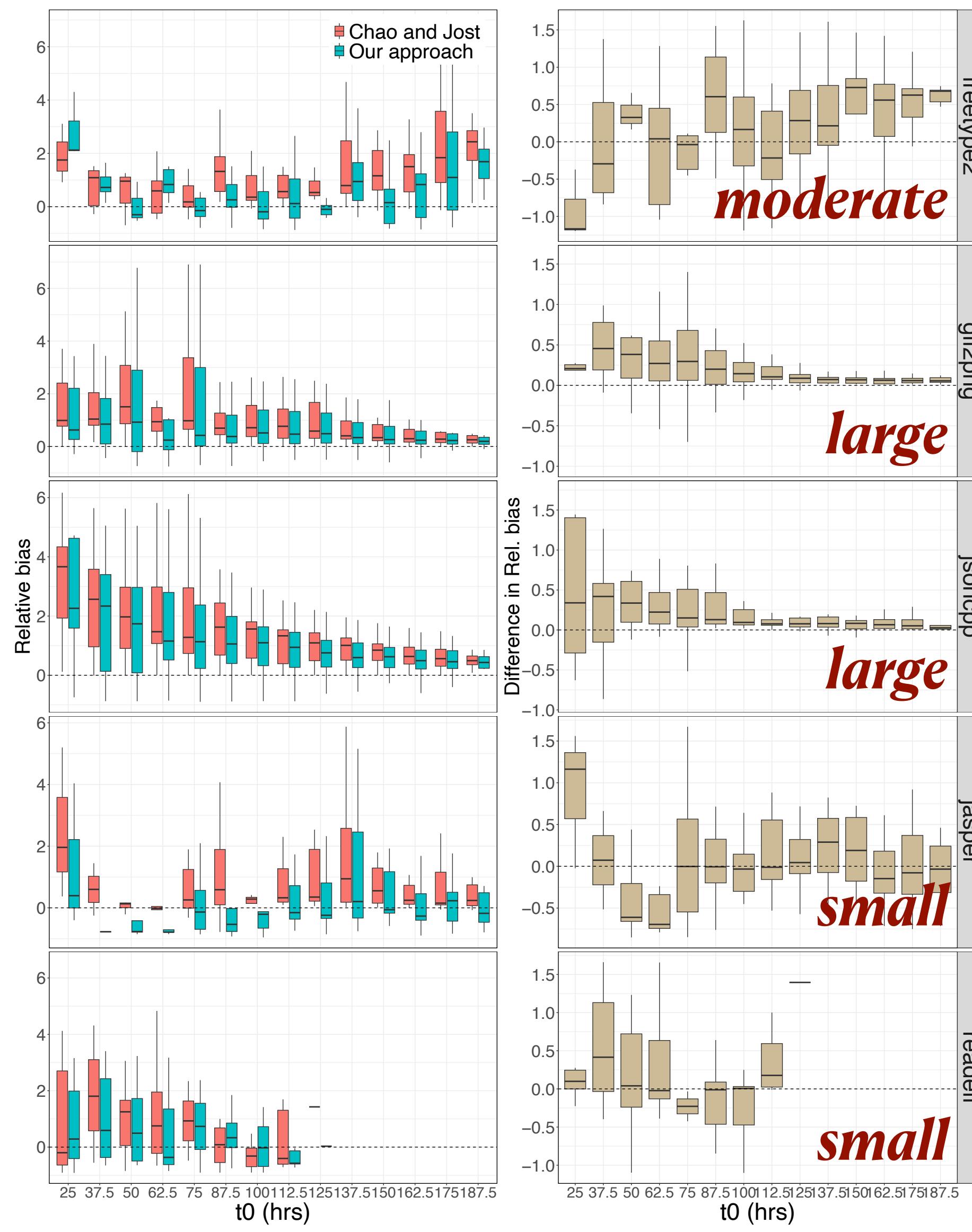
**U: Target coverage rate**



**v.s. U**



## Average difference between $U(\hat{t})$ and target $U$



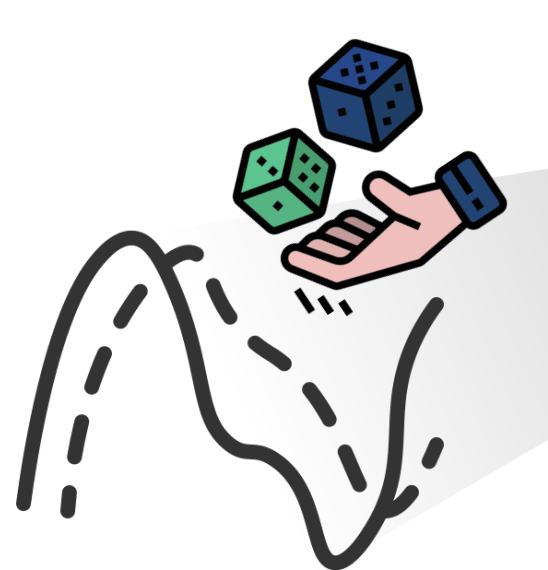
# Result 2. Stopping-Time Estimation

$$\leftarrow \text{Bias(Exist)} - \text{Bias(Our)} \quad (>0 \text{ is better})$$

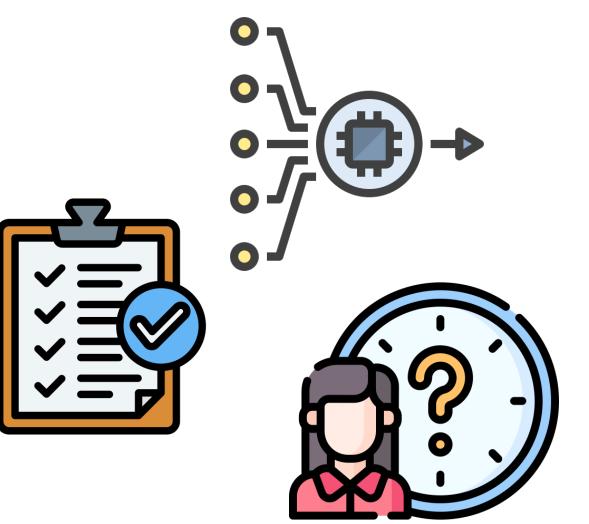
- Our extrapolator predicts the time significantly better (**large/moderate effect size**) than the existing extrapolator for **3 out of 5** subjects.
- For significant improvement, our extrapolator achieves **35-77% closer prediction** than the existing extrapolator.



## Q. When should we stop the fuzzing campaign?



**Stochastic Process**



*Even if we have some criteria,  
how much of a resource do we  
need to use more?*

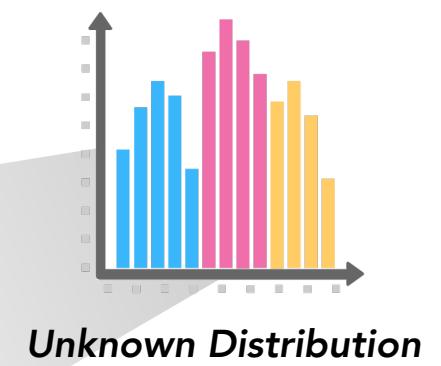
**Unsolvable with an analytical methodology**

## Q. When should we stop the fuzzing campaign?



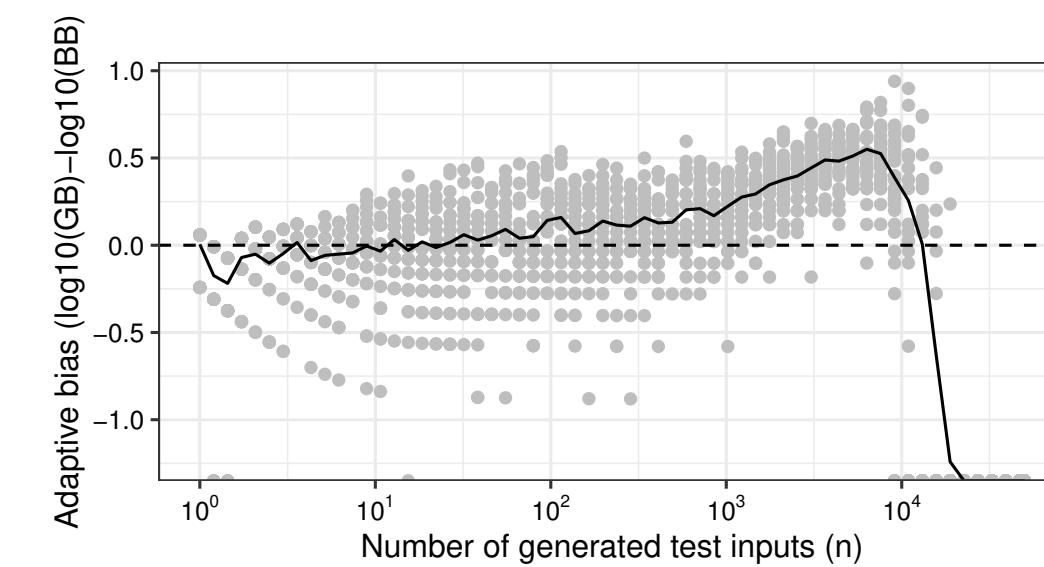
**Stochastic Process**

*Unsolvable with an analytical methodology*



*Even if we have some criteria,  
how much of a resource do we  
need to use more?*

**Adaptive bias**



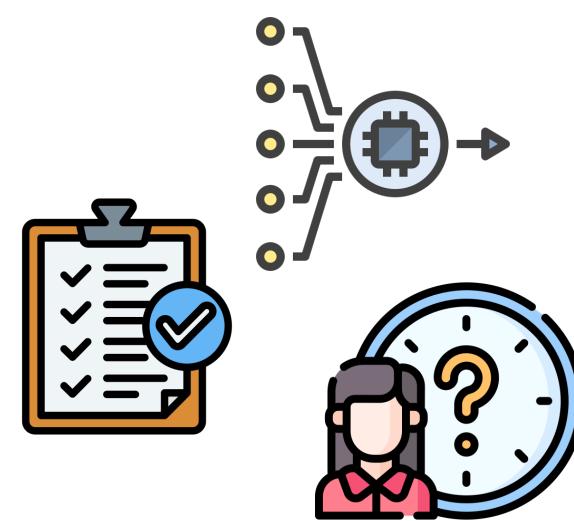
*"Due to adaptive bias, the discovery probability is consistently higher in the greybox campaign than the blackbox campaign."*

## Q. When should we stop the fuzzing campaign?



**Stochastic Process**

*Unsolvable with an analytical methodology*

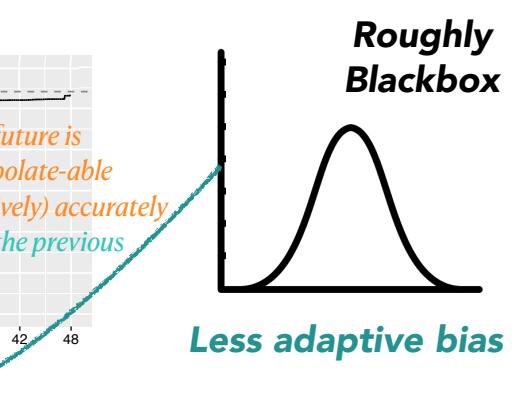
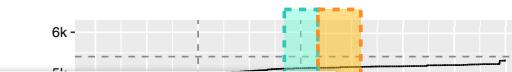
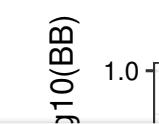


*Even if we have some criteria,  
how much of a resource do we  
need to use more?*

7

## Extrapolating the Greybox Fuzzing Campaign

- First key insight — *Microscopic view*

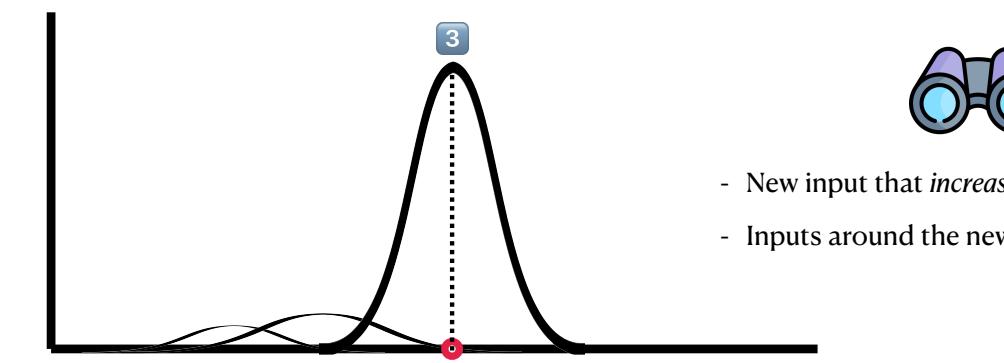


*tently align.*

## Extrapolating the Greybox Fuzzing Campaign

- Second key insight — *Macroscopic view*

"Greybox fuzzing's adaptive bias could be *predictable*."



- New input that *increases coverage* is found
- Inputs around the new input are sampled

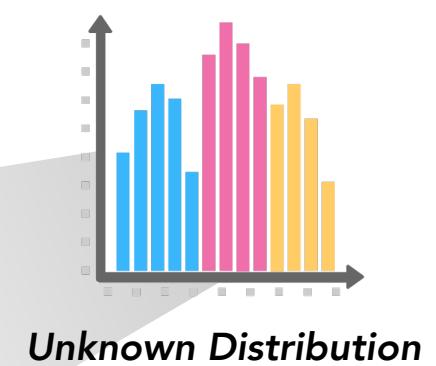
23

## Q. When should we stop the fuzzing campaign?



**Stochastic Process**

*Unsolvable with an analytical methodology*

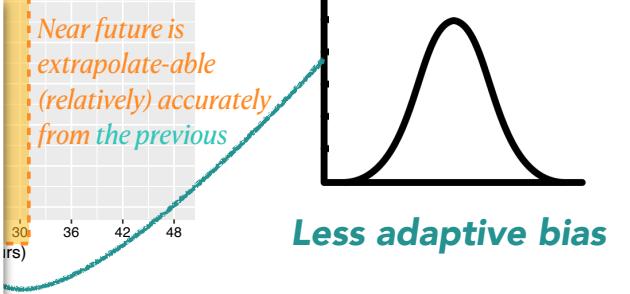
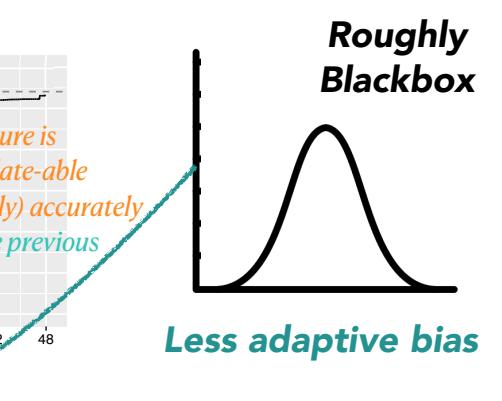
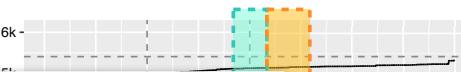


*Even if we have some criteria,  
how much of a resource do we  
need to use more?*

7

## Extrapolating the Greybox Fuzzing Campaign

- First key insight — *Microscopic view*



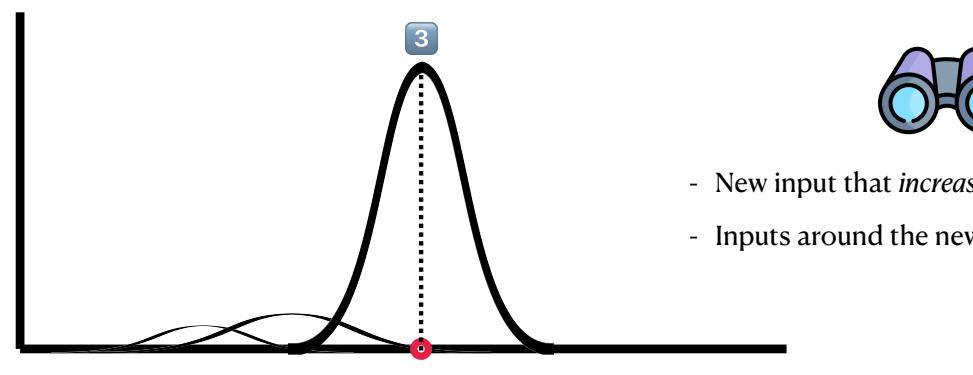
- New input that *increases coverage* is found
- Inputs around the new input are sampled

tently align."

## Extrapolating the Greybox Fuzzing Campaign

- Second key insight — *Macroscopic view*

"Greybox fuzzing's adaptive bias could be *predictable*."

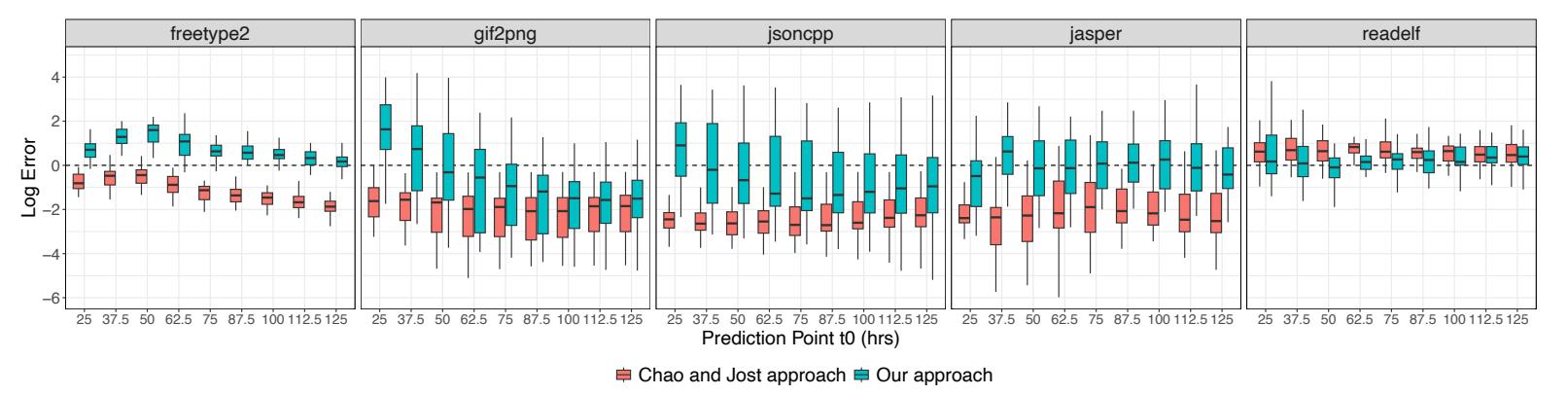


- New input that *increases coverage* is found
- Inputs around the new input are sampled

23

## Result 1: Coverage Rate Prediction

**Difference between  $\log(U(t + k))$  vs.  $\log(\hat{U}(t + k))$**



(close to 1 is better)

The average ratio  $U(t + k)/\hat{U}(t + k)$ :

[Existing] 1.6 - 800 [Ours] 1.17 - 7

across all subjects.

"Our extrapolator exhibits **at least one order of magnitude lower absolute bias** than the existing extrapolator for **4 out of 5 subjects**, especially for long-term prediction."

⇒ **Well-handled the adaptive bias**

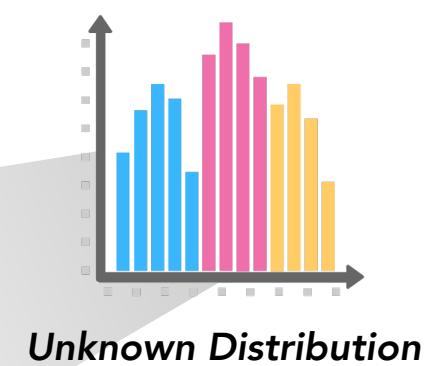
27

## Q. When should we stop the fuzzing campaign?



**Stochastic Process**

*Unsolvable with an analytical methodology*

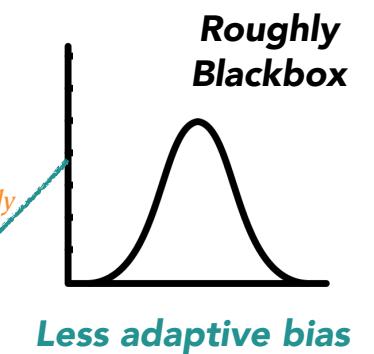
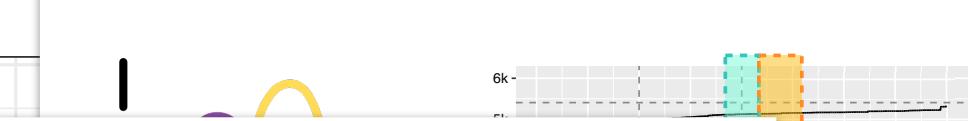


*Even if we have some criteria,  
how much of a resource do we  
need to use more?*

7

## Extrapolating the Greybox Fuzzing Campaign

- First key insight — *Microscopic view*



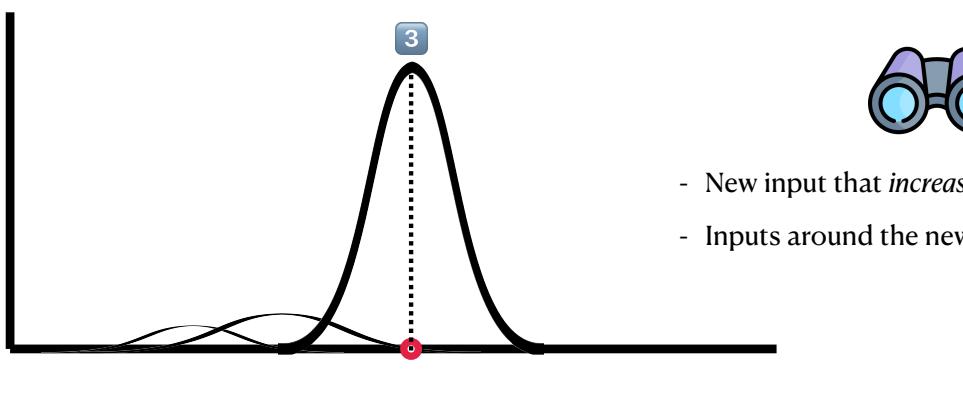
*Near future is extrapolateable (relatively) accurately from the previous*

*tently align.*

## Extrapolating the Greybox Fuzzing Campaign

- Second key insight — *Macroscopic view*

*"Greybox fuzzing's adaptive bias could be predictable."*

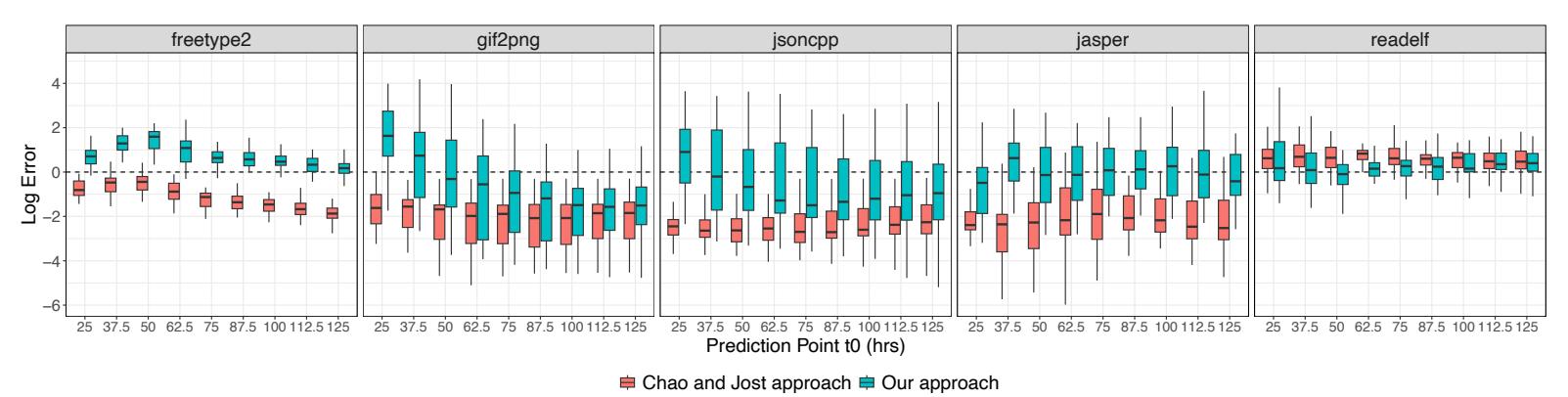


- New input that *increases coverage* is found
- Inputs around the new input are sampled

23

## Result 1: Coverage Rate Prediction

**Difference between  $\log(U(t + k))$  vs.  $\log(\hat{U}(t + k))$**



*(close to 0 is better)*

The average ratio  $U(t + k)/\hat{U}(t + k)$ :

[Existing] 1.6 - 800 [Ours] 1.17 - 7

across all subjects.

"Our extrapolator exhibits **at least one order of magnitude lower absolute bias** than the existing extrapolator for **4 out of 5 subjects**, especially for long-term prediction."

⇒ **Well-handled the adaptive bias**

27



## Dr. Seongmin Lee

🏠 <https://nimgnoeseel.github.io/>

