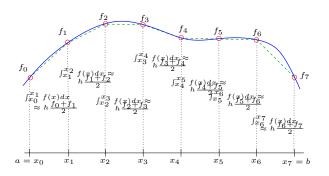
MA378 Chapter 3: Numerical Integration

§3.3 Precision and Composition

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3.1 Simpson's, again

In the final example of Section 3.2 ("Simpson's Rule") we noticed that Simpson's Rule yields exactly the right answer (i.e., the error is zero) when applied to approximating $\int_0^1 x^3 dx$.

In fact, Simpson's Rule is exact for **any** polynomial of degree 3 or less. We'll now explain why, restricting our focus to the interval [-1,1]. (See below for the general case).

- 1. Suppose that $Q_2(f)$ approximates $\int_{-1}^1 f(x)dx$.
- 2. We know that, if p_2 is any quadratic polynomial, then $Q_2(p_2)=\int_{-1}^1 p_2(x)dx.$
- 3. Write p_3 as

$$p_3(x) = c_3 x^3 + c_2 x^2 + c_1 x + c_0 = c_3 x^3 + p_2(x),$$

for some quadratic $p_2(x)$.

3.1 Simpson's, again

- 4. Note that $\int_{-1}^{1} p_3(x)dx = c_3 \int_{-1}^{1} x^3 dx + \int_{-1}^{1} p_2(x)dx.$
- 5. However, $\int_{-1}^{1} x^3 dx = 0$.
- 6. Therefore, $\int_{-1}^{1} p_3(x) dx = \int_{-1}^{1} p_2(x) dx$.
- 7. Similarly, $Q_2(p_3)dx = c_3Q_2(x^3) + Q_2(p_2)$. (iii) **2** (iv)
- 8. However, $Q_2(x^3) = \frac{2}{6}((-1)^3 + 4(0^3) + 1^3) = 0.$
- 9. Therefore $Q_2(p_3)dx = Q_2(p_2) = \int_{-1}^{1} p_2(x)dx$.
- 10. So, we have that

$$\int_{-1}^{1} p_3(x)dx = \int_{-1}^{1} p_2(x)dx = Q_2(p_3).$$

Conclude: $Q_2(\cdot)$ gives exactly the right answer when applied to estimating $\int_{-1}^{1} p_3(x) dx$ for any cubic polynomial, p_3 .

Here are the details for the general case. We won't go though this in class, but please read it carefully.

We now claim that Simpson's Rule is exact for *any* polynomial of degree 3 or less, and on *any* interval.

Denote by $Q_2(f)$ the approximation of $\int_a^b f(x)dx$ with Simpson's Rule:

$$Q_2(f) = \frac{b-a}{6} \left(f(a) + 4f(\frac{a+b}{2}) + f(b) \right).$$

Since the method can be derived by integrating the quadratic that interpolates f(x) at the three points a, (a+b)/2, and b, it is clearly exact for all quadratics.

Let $f(x) = c_0 + c_1 x + c_2 x^2 + c_3 x^3$. Then

$$\int_{a}^{b} f(x)dx = \int_{a}^{b} \left(c_{0} + c_{1}x + c_{2}x^{2}\right)dx + c_{3} \int_{a}^{b} x^{3}dx =$$

$$\int_{a}^{b} \left(c_{0} + c_{1}x + c_{2}x^{2}\right)dx + c_{3} \frac{b^{4} - a^{4}}{4}.$$

Also,

$$Q_2(f) = Q_2(c_0 + c_1 x + c_2 x^2) + Q_2(c_3 x^3) =$$

$$\int_a^b \left(c_0 + c_1 x + c_2 x^2\right) dx + c_3 \left(\frac{b-a}{6}\right) \left(a^3 + 4\left(\frac{a+b}{2}\right)^3 + b^3\right). \quad (1)$$

With a bit of symbolic manipulation we get that

$$\frac{b^4 - a^4}{4} = \left(\frac{b - a}{6}\right) \left(a^3 + 4\left(\frac{a + b}{2}\right)^3 + b^3\right),$$

as required.

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In Section 3.2, we discussed a nieve attempt to derive an upper bound for the error in Simpson's rule leading to

$$\mathcal{E}_2 \le \frac{(b-a)^4}{196} M_3.$$

This is not wrong – just not sharp. For example it does not give that Simpson's Rule is exact for all cubic. The sharp result is

Theorem 3.1

$$\mathcal{E}_2 := |\int_a^b f(x)dx - Q_2(f)| \le \frac{(b-a)^5}{2880} M_4.$$

For the proof see the text book (Theorem 7.2 of Suli and Mayers). Instead of working through it in class we'll prove a more general version of a consequence it.

3.2 Precision

Definition 3.2 (Precision of a Quadrature Rule)

A quadrature rule has **precision** n if it is exact for all polynomials of degree n or less. That is, the rule Q(f) has precision n if

$$Q(p_n) = \int_a^b p_n(x) dx$$
 for all $p_n \in \mathcal{P}_n$.

Example 3.3

By construction, the (N+1)-point Newton-Cotes rule has precision

This is because
$$Q_N(f)$$
 is defined to be $Q_N(f) = \int_a^b f_N(x) dx$ where p_N is the Lagrange interpolant to f .

3.2 Precision

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$$Q(p_n) = \int_a^b p_n(x) dx \quad \text{ for all } p_n \in \mathcal{P}_n.$$

Example 3.3

By construction, the (n+1)-point Newton-Cotes rule has precision n.

Eg, Q₁(f) (ie Trapezium Rule) has precision 1. Q₂(f) (Simpson's Rule) is designed to have precision 2, but in fact, has precision 3.

3.2 Precision That is QN(·) for Even N.

Theorem 3.4

If $Q_{2k}(\cdot)$ is a Newton-Cotes quadrature rule on 2k+1 points, then $Q_{2k}(\cdot)$ has in fact precision 2k+1.

Important: n=2K

Proof: Let p_{n+1} be a polynomial of degree n+1. We wish to show that $Q_n(p_{n+1})=\int_a^b p_{n+1}(x)dx$. We can take a=-1, b=1 because a simple linear transformation can be used to map to an arbitrary interval.

Also, since the quadrature points are equally spaced on [-1,1] we have that $x_i=-x_{n-i}$.

Furthermore (see Exercise 3.1) the quadrature weights are symmetric: $q_i = q_{n-i}$.

Lint: $q_i = \int_{-\infty}^{\infty} L_i(x) dx$ a Lagrange Poly.

3.2 Precision

Note that
$$\int_{-1}^{1} P_{n+1}(x) dx = \int_{-1}^{1} P_{n}(x) + a_{n+1} x^{n+1} dx$$

$$= \int_{-1}^{1} P_{n}(x) dx + a_{n+1} \int_{-1}^{1} x^{n+1} dx$$

$$= Q_{n}(P_{n}) + O \quad \text{since } n+1 \text{ is odd}$$
Similarly
$$Q_{n}(P_{n}+1) = Q_{n}(P_{n}) + Q_{n+1} Q_{n}(x^{n+1})$$

$$= Q_{n}(P_{n}) + O \quad \text{See}$$

$$Why ? board!$$

3.3 Composite Rules

Suppose that we want to estimate $\int_a^b f(x) dx$ and the Trapezium rule is not sufficiently accurate. We could try Simpson's Rule, which should be better. Failing that, we could try a 4-point rule, based on integrating the p_4 interpolant, or a five-point rule, based on integrating p_5 .

However, quite apart from the fact that it might be tedious to derive these rules, we know (Runge's example again!) that high-order polynomial interpolation can be very inaccurate.

3.3 Composite Rules

It is better to use a **Composite Rule**. This is analogous to the idea behind piecewise linear interpolation.

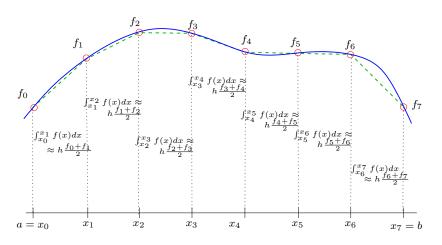
For the **Composite Trapezium Rule** we divide [a,b] into N intervals of size h=(b-a)/N. Applying the Trapezium Rule on each interval $[x_{i-1},x_i]$ we get

$$\int_{x_{i-1}}^{x_i} f(x)dx \approx h \frac{f_{i-1} + f_i}{2}.$$

Summing for the n intervals we get

$$\int_{a}^{b} f(x)dx \approx \underbrace{\frac{b-a}{N}}_{h} \left(\frac{f_{0}}{2} + f_{1} + f_{2} + \dots + f_{N-1} + \frac{f_{N}}{2}\right). \tag{2}$$

3.3 Composite Rules



Similarly, one con define a composite Simpson's Rule, etc

3.4 Exercises

Exercise 3.1

Explain clearly, with an example, why in general it is not true that

$$Q_n(f) \to \int_a^b f(x)dx \text{ as } n \to \infty.$$

Exercise 3.2

- (i) Deduce an error estimate for the Composite Trapezium Rule (2).
- (ii) Taking N=10, give an upper bound for the error in the Composite Trapezium Rule when approximating $\int_1^2 \ln(x) dx$.
- (iii) What value of n would you have to take to ensure that the error was less that 10^{-5} ?

3.4 Exercises

Exercise 3.3

- (i) Deduce the formula for the composite Simpson's Rule.
- (ii) Derive an error estimate for the composite Simpson's Rule.
- (iii) What value of N would you have to take to ensure that the error in the estimate of $\int_1^2 \ln(x) dx$ is less that 10^{-6} ?
- (iv) Denote the (N+1)-point Composite Simpson's Rule by $S_N(f) \approx \int_a^b f(x) dx$. Show that, for sufficiently smooth f(x),

$$\lim_{n \to \infty} S_N(f) = \int_a^b f(x) dx.$$

3.4 Exercises

Exercise 3.4

Determine the precision of the following schemes for estimating $\int_0^1 f(x)dx$.

- (i) $Q(f) = f(\frac{1}{2}).$
- (ii) $Q(f) = \frac{1}{4}f(0) + \frac{3}{4}f(\frac{2}{3}).$
- (iii) $Q(f) = \frac{3}{2}f(\frac{1}{3}) 2f(\frac{1}{2}) + \frac{3}{2}f(\frac{2}{3}).$

Exercise 3.5 (*)

Consider the rule:

$$R(f) = q_0 f(1/3) - f(\frac{1}{2}) + q_2 f(\frac{3}{4})$$

for approximating $\int_0^1 f(x)dx$.

- 1. Determine values of q_0 and q_2 that ensure this rule has precision 2.
- 2. What is the maximum precision of $R(\cdot)$ with the values of q_1 and q_2 that you have determined?
- 3. Why is this not, strictly speaking, a Newton-Cotes rule?