#### **CS319: Scientific Computing**

# Function Overloading and Memory Allocation

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Week 5: 12th and 14th of February, 2025

Slides and examples: https://www.niallmadden.ie/2425-CS319

# 0. Outline

- 1 Recall: Pass-by-value
- 2 Function overloading
- 3 Detailed example
- 4 Arrays
- 5 Pointers

- Pointer arithmetic
- Warning!
- 6 Dynamic Memory Allocation
  - new
  - delete
- 7 Example: Quadrature 1

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## 1. Recall: Pass-by-value

Last week we learned the following about C++:

- By default, an argument is passed by value. This means that the function gets a copy of the variable. So any changes to it are local to the function.
- ► If (say) v is a variable, then &v is (a reference to) the memory address of that variable.
- ► To pass the variable v's **reference** to a function, refer to it as &v in the function header/prototype and definition.
- ► If a variable is passed by reference to a function, f, and its value changed in f, then it is also changed in the calling function.

# 1. Recall: Pass-by-value

#### Example

#### OOPassByValueAndReference.cpp

```
void DoesNotChangeVar(int X);
6 void DoesChangeVar(int &X);
8 int main(void)
10
     int q=34;
     std::cout << "main: q=" << q << std::endl;
12
     std::cout << "main: Calling DoesNotChangeVar(q)...";</pre>
     DoesNotChangeVar(q);
14
     std::cout << "\t Now q=" << q << std::endl;
     std::cout << "main: Calling DoesChangeVar(q)...";
16
     DoesChangeVar(q);
     std::cout << "\t And now q=" << q << std::endl;
18
     return(0):
  void DoesNotChangeVar(int X){ X+=101; }
22 void DoesChangeVar(int &X){ X+=101; }
```

# 1. Recall: Pass-by-value

Output

C++ has certain features of **polymorphism**: where a single identifier can refer to two (or more) different things. A classic example is when two different functions can have the same name, but different argument lists.

This is called **function overloading**.

There are lots of reasons to do this. For example, in Week 4 we wrote a function called Swap() that swapped the value of two int variables.

However, we can write a function that is also called Swap() to swap two floats, or two strings.

(Note: this can also be done with something called templates: we'll look at that in a few weeks.)

As a simple example, we'll write two functions with the same name: one that swaps the values of a pair of ints, and that other that swaps a pair of floats. (Really this should be done with templates...)

#### 01Swaps.cpp (headers)

```
#include <iostream>

// We have two function prototypes with same name!

void Swap(int &a, int &b); // note use of references
void Swap(float &a, float &b);
```

## 01Swaps.cpp (main)

```
12 int main(void){
       int a, b;
14
       float c, d;
16
       std::cout << "Enter two integers: ";
       std::cin >> a >> b;
18
       std::cout << "Enter two floats: ":
       std::cin >> c >> d;
       std::cout << "a=" << a << ", b=" << b <<
         ", c=" << c << ", d=" << d << std::endl;
       std::cout << "Swapping ...." << std::endl;
       Swap(a,b);
26
       Swap(c,d);
28
       std::cout << "a=" << a << ", b=" << b <<
         ", c=" << c << ", d=" << d << std::endl;
30
       return(0);
```

## 01Swaps.cpp (functions)

```
34 // Swap(): swap two ints
   void Swap(int &a, int &b)
36
     int tmp;
     tmp=a;
40
     a=b:
     b=tmp;
   // Swap(): swap two floats
46 void Swap(float &a, float &b)
48
     float tmp;
50
     tmp=a;
     a=b;
     b=tmp;
```

What does the compiler take into account to distinguish between overloaded functions?

C++ distinguishes functions according to their **signature**. A signature is made up from:

- ► Type of arguments. So, e.g., void Sort(int, int) is different from void Sort(char, char).
- ► The number of arguments. So, e.g., int Add(int a, int b) is different from int Add(int a, int b, int c).

#### **Examples:**

However, the following to not impact signatures:

- Return values. For example, we cannot have two functions int Convert(int) and float Convert(int) since they have the same argument list.
- ▶ user-defined types (using typedef) that are in fact the same. See, for example, 020verloadedConvert.cpp.
- ▶ References: we cannot have two functions int MyFunction(int x) and int MyFunction(int &x)

In the following example, we combine two features of C++ functions:

- Pass-by-reference,
- Overloading,

We'll write two functions, both called Sort:

- ► Sort(int &a, int &b) sort two integers in ascending order.
- Sort(int list[], int n) sort the elements of a list of length n.

The program will make a list of length 8 of random numbers between 0 and 39, and then sort them using **bubble sort**.

#### 03Sort.cpp (headers)

```
#include <iostream>
6 #include <stdlib.h> // contains rand() header

8 const int N=8;

10 void Sort(int &a, int &b);
  void Sort(int list[], int length);
  void PrintList(int x[], int n);
```

#### O3Sort.cpp (main)

```
14 int main(void)
   {
16
       int i, x[N];
18
       for (i=0; i<N; i++)</pre>
         x[i]=rand()%40;
       std::cout << "The list is:\t\t";
22
       PrintList(x, N);
       std::cout << "Sorting..." << std::endl;
       Sort(x,N);
       std::cout << "The sorted list is:\t";</pre>
28
       PrintList(x, N);
       return(0);
30 }
```

## 03Sort.cpp (Sort two ints)

```
32  // Sort(a, b)
    // Arguments: two integers
34  // return value: void
    // Does: Sorts a and b so that a <= b.
36  void Sort(int &a, int &b)
    {
        if (a>b)
        {
            int tmp;
            tmp=a; a=b; b=tmp;
        }
    }
```

#### 03Sort.cpp (Sort list)

```
// Sort(int [], int)
// Arguments: an integer array and its length
// return value: void
48  // Does: Sorts the first n elements of x
void Sort(int x[], int n)
50  {
    int i, k;
    for (i=n-1; i>1; i--)
        for (k=0; k<i; k++)
        Sort(x[k], x[k+1]);
56 }</pre>
```

```
62 void PrintList(int x[], int n)
{

for (int i=0; i < n; i++)
    std::cout << x[i] << " ";

std::cout << std::endl;
}
```

Much of Scientific Computing involves working with data, and often collections of data are stored as **arrays**, which are list-like structures that stores a collection of values all of the same type.

**Example:** declare an array to store five floats:

```
float vals[5];

2 vals[0]=1.0;
vals[1]=2.1;

4 vals[2]=3.14;
vals[3]=-21.0;

6 vals[4]=-1.0;
```

Consider the following piece of code:

#### 04Array.cpp

```
float vals[3];
vals[0]=1.1; vals[1]=2.2; vals[2]=3.3;
for (int i=0; i<3; i++)
    std::cout << " vals["<<i<"]=" << vals[i];
std:: cout << std::endl;
std::cout << "vals=" << vals << '\n';</pre>
```

#### The output I get looks like

```
1 vals[0]=1.1 vals[1]=2.2 vals[2]=3.3 vals=0x7ffd9ab8ec9c
```

Can we explain the last line of output?

So now it know that, if vals is the name of an array, then in fact the value stored in vals is the memory address of vals [0].

We can check this with

```
std::cout << "vals=" << vals << '\n';
std::cout << "&vals[0]=" << &vals[0] << '\n';
std::cout << "&vals[1]=" << &vals[1] << '\n';
std::cout << "&vals[2]=" << &vals[2] << '\n';
```

For me, this gives

```
vals=0x7ffc932b960c

2 &vals[0]=0x7ffc932b960c

&vals[1]=0x7ffc932b9610

4 &vals[2]=0x7ffc932b9614
```

#### Can we explain?

```
And in the same piece of code, if I changed the first line from float vals[3]; to double vals[3];
```

we get something like

```
vals=0x7ffd361abdc0
&vals[0]=0x7ffd361abdc0
&vals[1]=0x7ffd361abdc8
&vals[2]=0x7ffd361abdd0
```

#### Can we explain?

So now we understand why C++ (and related languages) index their arrays from 0:

- vals[0] is stored at the address in vals;
- vals[1] is stored at the address after the one in vals;
- vals[k] is stored at the kth address after the one in vals;

But there are numerous complications, not least that different data types are stored using different numbers of bytes. So the off-set depends on the data type.

To understand the subtleties, we need to know about **pointers**.

#### 5. Pointers

To properly understand how to use arrays, we need to study **Pointers**.

- ► We already learned that if, say, x is a variable, then &x is its memory address.
- ▶ A pointer is a special type of variable that can store memory addresses. We use the \* symbol before the variable name in the declaration.
- For example, if we declare

```
int i;
int *p
then we can set p=&i.
```

#### 5. Pointers

#### O5Pointers.cpp

```
10
     int a=-3, b=12;
     int *where;
     std::cout << "The variable 'a' stores " << a << std::endl;</pre>
14
     std::cout << "The variable 'b' stores " << b << std::endl;
     std::cout << "'a' is stored at address " << &a << std::endl:
16
     std::cout << "'b' is stored at address " << &b << std::endl:
18
     where = &a:
     std::cout << "The variable 'where' stores "
20
               << (void *) where << std::endl;
     std::cout << "... and that in turn stores " <<
22
       *where << '\n':
```

One can actually do calculations on memory addresses. This is called **pointer arithmetic**. One can't (for example) add two addresses, or compute their product, but you can, for example, increment them.

#### O6PointerArithmetic.cpp

```
int vals[3];
vals[0]=10; vals[1]=8; vals[2]=-4;

int *p;
p = vals;

for (int i=0; i<3; i++)
{
    std::cout << "p=" << p << ", *p=" << *p << "\n";
    p++;
}</pre>
```

5. Pointers Warning!

Being able to manipulate memory addresses is one of the reasons C++ is considered a very **powerful** language. It is possible to preform (low-level) operations in C++ that are impossible in, say, Python.

But it is also possible to write programmes that will crash, or even crash your computer, since memory addresses are not well protected.

## 6. Dynamic Memory Allocation

In all examples we've had so far, we've specified the size of an array at the time it is defined.

In many practical cases, we don't have that information. For example, we might need to read data from a file, but not know the file size in advance.

It would be useful if, on the fly, we could set the size of an array.

Furthermore, for efficiency, we may want to free up memory allocated.

To add this functionality, we will use two new (to us) C++ operators for dynamic memory allocation and deallocation:

- new and
- ▶ delete.

(There are also functions malloc(), calloc() and free() inherited from C, but we won't use them).

The <u>new</u> operator is used in C++ to allocate memory. The basic form is

```
var = new type
```

where type is the specifier of the object for which you want to allocate memory and var is a pointer to that type.

If insufficient memory is available then new will return a NULL pointer or generate an exception.

To dynamically allocate an array:

First declare a pointer of the right type:

```
int *data;
```

► Then use new

```
data = new int[MAX_SIZE];
```

When it is no longer needed, the operator delete releases the memory allocated to an object.

```
To "delete" an array we use a slightly different syntax:

delete [] array;

where array is a pointer to an array allocated with new.
```

In Week 4, we introduced the idea of **numerical integration** or **quadrature**.

We computed estimates for  $\int_a^b f(x)dx$  by applying the Trapezium Rule:

- ▶ Choose the number of intervals N, and set h = (b a)/N.
- ▶ Define the quadrature points  $x_0 = a$ ,  $x_1 = a + h$ , ...  $x_N = b$ . In general,  $x_i = a + ih$ .
- ► Set  $y_i = f(x_i)$  for i = 0, 1, ..., N.
- ► Compute  $\int_{a}^{b} f(x)dx \approx Q_{1}(f) := h(\frac{1}{2}y_{0} + \sum_{i=1:(N-1)} y_{i} + \frac{1}{2}y_{N}).$

[Take notes for the next few slides]

```
# #include <iostream>
#include <cmath> // For exp()

#include <iomanip>

double f(double x) { return(exp(x)); } // definition
double ans_true = exp(1.0)-1.0; // true value of integral

double Quad1(double *x, double *y, unsigned int N);
```

Next we skip to the function code...

#### O7TrapeziumRule.cpp

```
double Quad1(double *x, double *y, unsigned int N)

{
     double h = (x[N]-x[0])/double(N);
     double Q = 0.5*(y[0] + y[N]);
     for (unsigned int i=1; i<N; i++)
        Q += y[i];
     Q *= h;
     return(Q);
}</pre>
```

Source of confusion: \* is used in two very different contexts here.

Back to the main function: declare the pointers, input N, and allocate memory.

```
int main(void )
{
    unsigned int N;
    double a=0.0, b=1.0; // limits of integration
    double *x; // quadrature points
    double *y; // quadrature values

20    std::cout << "Enter the number of intervals: ";
    std::cin >> N; // not doing input checking

    x = new double[N+1];
    y = new double[N+1];
```

Initialise the arrays, compute the estimates, and output the error.

```
double h = (b-a)/double(N);
26
     for (unsigned int i=0; i<=N; i++)</pre>
28
       x[i] = a+i*h;
       v[i] = f(x[i]);
30
     double Est1 = Quad1(x,y,N);
32
     double error = fabs(ans true - Est1):
     std::cout << "N=" << N << ", Trap Rule="
34
               << std::setprecision(6) << Est1
               << ", error=" << std::scientific
36
               << error << std::endl;
```

Finish by de-allocating memory (optional, in this instance).

```
38     delete [] x;
     delete [] y;
40     return(0);
}
```

Although this was presented as an application of using arrays in C++, some questions arise...

- 1. What value of N should we pick the ensure the error is less than, say,  $10^{-6}$ ?
- 2. How could we predict that value if we didn't know the true solution?
- 3. What is the smallest error that can be achieved in practice? Why?
- 4. How does the time required depend on *N*? What would happen if we tried computing in two or more dimensions?
- 5. Are there any better methods? (And what does "better" mean?)

Some answers to those questions.