Chapter 2 (Initial Value Problems) and Chapter 3 (Numerical Linear Algebra)

Outline solutions to homework assignment: Exercises 2.7, 2.14, 3.12 and 3.15.

Exercise 2.7 (\star). In his seminal paper of 1901, Carl Runge gave an example of what we now call a Runge-Kutta 2 method, where

$$\Phi(t_{i}, y_{i}; h) = \frac{1}{4}f(t_{i}, y_{i}) + \frac{3}{4}f(t_{i} + \frac{2}{3}h, y_{i} + \frac{2}{3}hf(t_{i}, y_{i})).$$

- (i) Show that it is consistent.
- (ii) Show how this method fits into the general framework of RK2 methods. That is,
 - (a) What are α , b, α , and β ?
 - (b) Do they satisfy the conditions

$$\beta = \alpha$$
, $b = \frac{1}{2\alpha}$, $a = 1 - b$?

(iii) Use it to estimate the solution at the point t=2 to y(1)=1, y'=1+t+y/t taking n=2 time steps.

SOLUTION:

(i) The method is consistent if $\Phi(t_i, y_i; 0) = f(t_i, y_i)$ (that is, if we formally set h = 0 in the method, we recover the right-hand side of the differential equation). In this case,

$$\Phi(t_i,y_i;0) = \frac{1}{4}f(t_i,y_i) + \frac{3}{4}f\big(t_i+0\frac{2}{3},y_i+0\frac{2}{3}f(t_i,y_i)\big) = \frac{1}{4}f(t_i,y_i) + \frac{3}{4}f\big(t_i,y_i) = f(t_i,y_i),$$

as required.

(ii) All RK-2 methods fall into the following framework:

$$k_1 = f(t_i, y_i),$$
 $k_2 = f(t_i + \alpha h, y_i + \beta h k_1),$ $\Phi(t_i, y_i; h) = a k_1 + b k_2$

So we can see that $\alpha=1/4$ and b=3/4. Furthermore, we see that $k_2=f\big(t_i+\frac{2}{3}h,y_i+\frac{2}{3}hk_1\big)$. That is, $\alpha=\beta=2/3$. So, to answer the question,

- (a) a = 1/4 and b = 3/4, $\alpha = \beta = 2/3$.
- (b) Yes, since $\alpha + b = (1+3)/4 = 1$ and $\alpha = \beta$ and $1/(2\alpha) = 3/4 = b$ as required.
- (iii) For this problem, f(x,t) = 1 + t + y/t, $t_0 = 1$ and $y_0 = 1$. Proceed as follows.

Step 1: To solve for $y_1 \approx y(3/2)$, we compute

$$k_1 = \mathsf{f}(t_0, y_0) = \mathsf{f}(1, 1) = 3, \qquad \text{ and } \qquad k_2 = \mathsf{f}(1 + \frac{1}{3}, 1 + \frac{1}{3}\mathsf{f}(1, 1)) = \mathsf{f}(\frac{4}{3}, 2) = \frac{23}{6}.$$

Then

$$y_1 = y_0 + h(ak_1 + bk_2) = 1 + \frac{1}{2}(\frac{1}{4} \cdot 3 + \frac{3}{4} \cdot \frac{23}{6}) = \frac{45}{16}$$

Step 2: To Solve for $y_2 \approx y(2)$, we compute

$$k_1 = \mathsf{f}(\frac{3}{2}, \frac{45}{16}) = \frac{35}{8}, \qquad \text{and} \qquad k_2 = \mathsf{f}(\frac{3}{2} + \frac{1}{3}, \frac{45}{16} + \frac{1}{3} \cdot \frac{35}{8}) = \mathsf{f}(\frac{11}{6}, \frac{205}{48}) = \frac{1363}{264}.$$

Then

$$y_2 = \frac{45}{16} + \frac{1}{2}(\frac{1}{4} \cdot \frac{35}{8} + \frac{3}{4} \cdot \frac{1363}{264}) = \frac{233}{44} \approx 5.2955.$$

Here are some entries for 3-stage Runge-Kutta method tableaux for Exercise 2.14.

Method 0: $\alpha_2 = 2/3$, $\alpha_3 = 0$, $b_1 = 1/12$, $b_2 = 3/4$, $\beta_{32} = 3/2$

Method 1: $\alpha_2 = 1/4$, $\alpha_3 = 1$, $b_1 = -1/6$, $b_2 = 8/9$, $\beta_{32} = 12/5$

Method 2: $\alpha_2 = 1/4$, $\alpha_3 = 1/2$, $b_1 = 2/3$, $b_2 = -4/3$, $\beta_{32} = 2/5$

Method 3: $\alpha_2 = 1/4$, $\alpha_3 = 1/3$, $b_1 = 3/2$, $b_2 = -8$, $\beta_{32} = 4/45$

Method 4: $\alpha_2 = 1$, $\alpha_3 = 1/4$, $b_1 = -1/6$, $b_2 = 5/18$, $\beta_{32} = 3/16$

Method 5: $\alpha_2 = 1$, $\alpha_3 = 1/5$, $b_1 = -1/3$, $b_2 = 7/24$, $\beta_{32} = 4/25$

Method 6: $\alpha_2 = 1$, $\alpha_3 = 1/6$, $b_1 = -1/2$, $b_2 = 3/10$, $\beta_{32} = 5/36$

Method 7: $\alpha_2 = 1/2$, $\alpha_3 = 1/7$, $b_1 = 7/6$, $b_2 = 22/15$, $\beta_{32} = -10/49$

Method 8: $\alpha_2 = 1/2$, $\alpha_3 = 1/8$, $b_1 = 4/3$, $b_2 = 13/9$, $\beta_{32} = -3/16$

Method 9: $\alpha_2 = 1/3$, $\alpha_3 = 1/9$, $b_1 = 4$, $b_2 = 15/4$, $\beta_{32} = -2/27$

Exercise 2.14 (Your own RK3 method \star). Answer the following questions for Method K from the list above, where K is the last digit of your ID number. For example, if your ID number is 01234567, use Method 7.

- (a) Assuming that the method is consistent, determine the value of b_3 .
- (b) Consider the initial value problem:

$$y(0) = 1, y'(t) = \lambda y(t).$$

Using that the solution is $y(t)=e^{\lambda t}$, write out a Taylor series for $y(t_{i+1})$ about $y(t_i)$ up to terms of order h^4 (use that $h=t_{i+1}-t_i$).

Using that your method should agree with the Taylor Series expansion up to terms of order h^3 , determine β_{21} and β_{31} .

SOLUTION:

(a) A method is consistent if

$$\Phi(\mathsf{t}_{\mathsf{i}},\mathsf{y}_{\mathsf{i}};0)=\mathsf{f}(\mathsf{t}_{\mathsf{i}},\mathsf{y}_{\mathsf{i}}),$$

For all these methods, RK3 if h = 0, then $k_1 = k_2 = k_3$. Since

$$\Phi(t_i, y_i; h) = b_1 k_1 + b_2 k_2 + b_3 k_3,$$

it follows that the method is consistent if $b_1 + b_2 + b_3 = 1$. You can use this to find your b_3

(b) The Taylor series expansion up to order h⁴ is

$$y(t_{i+1}) = y(t_i) + (t_{i+1} - t_i)y'(t_i) + \frac{(t_{i+1} - t_i)^2}{2!}y''(t_i) + \frac{(t_{i+1} - t_i)^3}{3!}y'''(t_i) + \frac{(t_{i+1} - t_i)^4}{4!}y''''(t_i).$$

Letting y_i approximate $y(t_i)$, and using that $y^{(k)}(t) = \lambda^t y(t)$, and $t_{i+1} - t_i = h$, we get

$$y(t_{i+1}) = y(t_i) \left(1 + h\lambda + \frac{h^2\lambda^2}{2} + \frac{h^3\lambda^3}{6} \right) + O(h^4).$$

Next, we write out the Runge-Kutta 3 method:

$$\begin{split} k_1 &= f(t_i + \alpha_1 h, y_i) = \lambda y_i, \\ k_2 &= f(t_i + \alpha_2 h, y_i + \beta_{21} h k_1) = \lambda (y_i + \beta_{21} h \lambda y_i), \\ k_3 &= f(t_i + \alpha_3 h, y_i + \beta_{31} h k_1 + \beta_{32} h k_2) = \lambda \left((y_i + \beta_{31} h \lambda y_i) + \beta_{32} h \lambda (y_i + \beta_{21} h \lambda y_i) \right). \end{split}$$

The method is

$$y_{i+1} = y_i + h(b_1k_1 + b_2k_2 + b_3k_3)$$

So

$$\begin{split} y_{i+1} &= y_i + h \bigg(b_1 \lambda y_i + b_2 \lambda (y_i + \beta_{21} h \lambda y_i) + b_3 \lambda \big((y_i + \beta_{31} h \lambda y_i) + \beta_{32} h \lambda (y_i + \beta_{21} h \lambda y_i) \big) \bigg) \\ &= y_i \big(1 + h \lambda \left(b_1 + b_2 + b_3 \right) + h^2 \lambda^2 \left(b_2 \beta_{21} + b_3 (\beta_{31} + \beta_{32}) \right) + h^3 \lambda^3 \left(b_3 \beta_{32} \beta_{21} \right) \big) \end{split}$$

For this to agree with the Taylor series expansion, we would need

- (i) $(b_1 + b_2 + b_3) = 1$, which we have already.
- (ii) $b_2\beta_{21} + b_3(\beta_{31} + \beta_{32}) = \frac{1}{2}$, and
- (iii) $b_3\beta_{32}\beta_{21} = \frac{1}{6}$.

Since we already have b_3 and β_{32} we can use (iii) to calculate β_{21} , and then substitute this into (ii) to find β_{31} .

Table of coefficients

Method	\mathfrak{b}_3	β_{21}	β_{31}
0	1/6	2/3	-3/2
1	5/18	1/4	-7/5
2	5/3	1/4	1/10
3	15/2	1/4	11/45
4	8/9	1	1/16
5	25/24	1	1/25
6	6/5	1	1/36
7	-49/30	1/2	17/49
8	-16/9	1/2	5/16
9	-27/4	1/3	5/27

Exercise 3.12 (*). Show that, for any vector $\mathbf{x} \in \mathbb{R}^n$, $\|\mathbf{x}\|_{\infty} \leqslant \|\mathbf{x}\|_2$ and $\|\mathbf{x}\|_2^2 \leqslant \|\mathbf{x}\|_1 \|\mathbf{x}\|_{\infty}$. For each of these inequalities, give an example for which the equality holds. Deduce that $\|\mathbf{x}\|_{\infty} \leqslant \|\mathbf{x}\|_2 \leqslant \|\mathbf{x}\|_1$.

Solution: First recall the definitions of these norms:

$$\|\mathbf{x}\|_{\infty} = \max_{i=1,\dots,n} |x_i|, \quad \|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|, \quad \text{and} \quad \|\mathbf{x}\|_2 = \left(\sum_{i=1}^n x_i^2\right)^{\frac{1}{2}}.$$

To show that $\|\mathbf{x}\|_{\infty} \leq \|\mathbf{x}\|_{2}$, let $\mathbf{x} \in \mathbb{R}^{n}$ be the vector $\mathbf{x} = (x_{1}, x_{2}, \dots, x_{n})^{T}$, where x_{j} is such that $|x_{j}| \geqslant |x_{i}|$ for all i. Then,

$$\|\mathbf{x}\|_{\infty}^2 = x_i^2 \leqslant x_i^2 + (x_1^2 + x_2^2 + \dots + \dots + x_{i-1}^2 + \dots + x_{i+1}^2 + \dots + x_n^2) = \|\mathbf{x}\|_{2}$$

where here we have used that each $x_i^2 \geqslant 0$.

Next, to show that $\|\mathbf{x}\|_2^2 \leq \|\mathbf{x}\|_1 \|\mathbf{x}\|_{\infty}$ we will use that

$$\|\mathbf{x}\|_{2}^{2} = x_{1}x_{1} + x_{2}x_{2} + \dots + x_{j}x_{j} + \dots + x_{n}x_{n} \leqslant (|x_{1}| + |x_{2}| + \dots + |x_{j}| + \dots + |x_{n}|)|x_{j}| = \|\mathbf{x}\|_{1}\|\mathbf{x}\|_{\infty}$$

where again we use that $||\mathbf{x}||_{\infty} = |\mathbf{x}_{\mathbf{j}}|$.

There are examples where equality holds. E.g., if $\mathbf{x}=(1,0,\dots,0)^T$, then $\|\mathbf{x}\|_{\infty}=\|\mathbf{x}\|_2=\|\mathbf{x}\|_1=1$. So, for this \mathbf{x} , $\|\mathbf{x}\|_{\infty}=\|\mathbf{x}\|_2$ and $\|\mathbf{x}\|_2^2=\|\mathbf{x}\|_1\|\mathbf{x}\|_{\infty}$.

To finish, we need to show that $\|\mathbf{x}\|_2 \leqslant \|\mathbf{x}\|_1$. Clearly this is true for $\|\mathbf{x}\| = 0$. Otherwise, Combine $\|\mathbf{x}\|_{\infty} \leqslant \|\mathbf{x}\|_2$, and $\|\mathbf{x}\|_2^2 \leqslant \|\mathbf{x}\|_1 \|\mathbf{x}\|_{\infty}$, to get that

$$\|\mathbf{x}\|_{2}^{2} \leq \|\mathbf{x}\|_{1} \|\mathbf{x}\|_{2},$$

and so $\|\mathbf{x}\|_{2} \leqslant \|\mathbf{x}\|_{1}$.

Exercise 3.15 (*). Prove that $\|A\|_1 = \max_{j=1,\dots,n} \sum_{i=1}^n |a_{i,j}|$. Hint: Suppose that $\sum_{i=1}^n |a_{ij}| \leqslant C$, for $j=1,2,\dots n$, and show that for any vector $\mathbf{x} \in \mathbb{R}^n \sum_{i=1}^n |(A\mathbf{x})_i| \leqslant C \|\mathbf{x}\|_1$. Now find a vector \mathbf{x} such that $\sum_{i=1}^n |(A\mathbf{x})_i| = C \|\mathbf{x}\|_1$. Now deduce the result.

SOLUTION: For a given $A \in \mathbb{R}^{n \times n}$ let

$$C_j = \sum_{i=1}^n |\alpha_{i,j}|, \quad \text{ and let } C = \max_{j=1,\dots,n} C_j.$$

That is, C is the sum of the largest column. Let x be the vector $\mathbf{x} = (x_1, x_2, \dots, x_n)^T$. Then

$$\|A\mathbf{x}\|_1 = \sum_{i=1}^n |(A\mathbf{x})_i| = \sum_{i=1}^n \bigg|\sum_{j=1}^n \alpha_{i,j} x_j\bigg| \leqslant \sum_{i=1}^n \sum_{j=1}^n |\alpha_{i,j}| |x_j| = \sum_{j=1}^n |x_j| \sum_{i=1}^n |\alpha_{i,j}| \leqslant \sum_{j=1}^n |x_j| C = C \|\mathbf{x}\|_1.$$

That is, for any x whatsoever, $||Ax||_1/||x||_1 \le C$. It follows, since x is arbitrary that

$$||A||_1 := \max_{\mathbf{x} \in \mathbb{R}/\{\mathbf{0}\}} \frac{||A\mathbf{x}||_1}{||\mathbf{x}||_1} \leqslant C.$$

To get equality, we need to choose a x for which $\|Ax\|_1/\|x\|_1=C$. Let q be such that column q of A has the largest sum. That is, $C_q=C$. Now let $\mathbf{x}=e^{(q)}$ (i.e., the vector whose only non-zero entry is $\mathbf{x}_q=1$; equivalently, it is column q of the identity matrix). For this vector $\|\mathbf{x}\|_1=1$. Moreover, $A\mathbf{x}=(\alpha_{1,q},\alpha_{2,q},\ldots,\alpha_{n,q})^T$; that is, it is the vector which is column q of A. So, $\|A\mathbf{x}\|_1=C$. This gives, for this \mathbf{x} ,

$$\frac{\|A\mathbf{x}\|_1}{\|\mathbf{x}\|_1} = \frac{C\|\mathbf{x}\|_1}{\|\mathbf{x}\|_1} = C = \max_{j=1,\dots,n} \sum_{i=1}^n |a_{i,j}|.$$