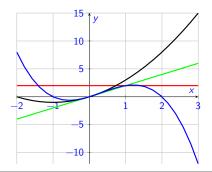
MA140: Engineering Calculus

Lecture 2: Functions

Dr Niall Madden

School of Mathematical and Statistical Sciences, University of Galway

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This version of the slides are by Niall Madden, but are adapted from original notes by Dr Kirsten Pfeiffer.

Outline

- 1 Functions
 - Notation and terminology
 - Domain, co-domain, range, etc
 - 4 Ways to Represent a Function

- 2 Graphical Representation
 - Domain of a function
- 3 A Catalog of Functions
 - Linear functions
- 4 Polynomials

For more, see Chapter 2 of Modern Engineering Mathematics: https://search.library.nuigalway.ie/permalink/f/3b1kce/TN_cdi_askewsholts_vlebooks_9780273742517

Functions

MA313 Lecture 2: Functions

Start of ...

Section 1: Functions

The single most important concept in MA140 is that of a **function**. For more, see Chapter 2 of "Modern Engineering Calculus (James).

We represent a function symbolically in two ways, either

$$f: x \to y$$

or

$$y = f(x)$$

Here x is in the set of X (or $x \in X$), and y is in the set of Y (or $y \in Y$).

If f is a function from X to Y...

- ► The set X is called the **domain** of the function.
- ► The set Y is called the codomain.
- When we write y = f(x), we say "x" is the **argument** of the function.
- ▶ When y = f(x) for some $x \in X$, y is said to be the image of x under f.
- ► The set of all images $y = f(x), x \in X$, is called the range (or image set) of f.

- While we could have functions between any pair of sets (e.g., a function from students in this class to their ID numbers), usually X and Y are sets of numbers.
- It is not necessary for all elements y of the codomain Y to be images under f.
- ▶ One element $y \in Y$ can serve as value f(x) for several $x \in X$.

A function can be represented in different ways:

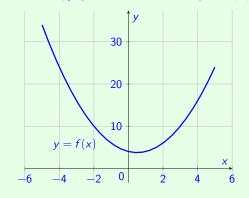
- 1. **verbally** (by a description in *words*);
- 2. numerically (as a table of values);
- visually (as a graph);
- 4. algebraically (by an explicit formula).

Often it is possible, and useful, to go from one way to another.

Graphical Representation

Graph \rightarrow **Table**

A common way to *visualize* a function $f: X \to \mathbb{R}$ is its *graph* in the x, y-plane. In this example, $f(x) = x^2 - x + 4$.



X	$\int f(x)$
-4	24
-2	10
0	4
2	6
4	16

Often, the domain of a function is not expilicitly stated. In such a case the following **Domain Convention** applies.

The **domain** of a function f is the set of all numbers x for which f(x) makes sense and gives a real-number output.

Example

1. Find the subset of \mathbb{R} that is the **domain** of $f(x) = \frac{1}{x^2 - x}$.

Find the subset of $\mathbb R$ that is the **domain** of the function $f(x) = \sqrt{x+2}$.

Given the function $f_1(x) = 3x^2 + 1$, find the largest subset of \mathbb{R} that is the domain of f_1 . What is the corresponding range?

Identify the domain (in \mathbb{R}) and range of $f_2(x) = \sqrt{(x+4)(3-x)}$

Identify the domain and range of $f_3(x) = \frac{1}{x}$.

A Catalog of Functions

There are many different types of functions that can be used to model relationships between objects in the real world.

The most common types of functions (in MA140) are:

- Linear Functions,
- Polynomial Functions,
- Power Functions,
- Rational Functions,
- Algebraic Functions,
- Trigonometric Functions,
- Exponential Functions,
- Logarithms.

Linear functions have formulae such as f(x) = mx + c, where m and c are some given numbers.

It is often represented graphically as a straight line of slope m through the point (0, c).

Polynomials

A **polynomial function** (or just **polynomial**) is a function of the form

$$y = f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x^1 + a_0, \quad x \in \mathbb{R},$$

where $a_0, a_1, ..., a_n$ are real numbers called the **coefficients** of the polynomial.

The number n is called the **degree** of the polynomial.

Exercises

Exercise 1.2.1

Identify the largest possible subset of \mathbb{R} that could be the domain of $f_2(x) = \sqrt{(x+4)(3-x)}$ if the co-domain is \mathbb{R} . What is the range?