# Lab 4: Graph in MATLAB (MA438)

[From Week 7, Feb 2023]

#### **Table of Contents**

Graphs in MATLAB	1
Adjacency Matrix	3
The graph of a matrix	
Computing with the Adjacency matrix	
Graphs as Objects	
Bipartite Graphs	
Directed Graphs	

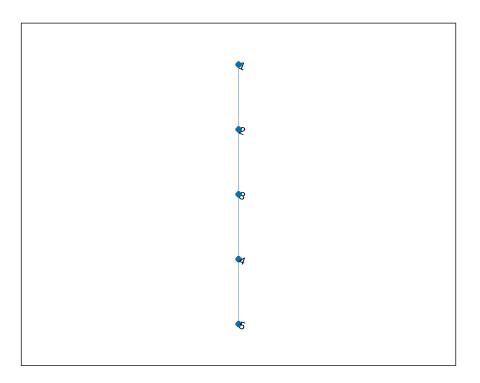
## **Graphs in MATLAB**

The simplest way to define a graph in MATLAB is by using the graph() function, with two integer arrays, a and b, as arguments: the resulting graph will have edges between a(i) and b(i), for i=1:length(a).

Let's start with  $P_n$ , the path graph on n vertices

```
n = 5;
G = graph(1:n-1, 2:n)

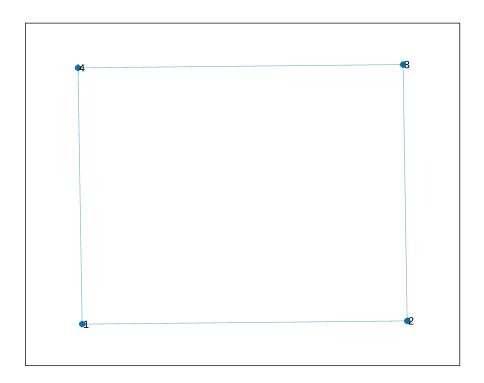
G =
    graph with properties:
    Edges: [4x1 table]
    Nodes: [5x0 table]
plot(G)
```



## For example, here is a cycle graph, $C_4$

```
a = [1,2,3,4];
b = [2,3,4,1];
C4 = graph(a,b)

C4 =
    graph with properties:
    Edges: [4×1 table]
    Nodes: [4×0 table]
plot(C4)
```



## **Adjacency Matrix**

Alternatively, we can define the graph using its adjacency matrix. If a graph has n vertices, then its adjacency matrix is the  $n \times n$  matrix, A, with  $a_{ij} = \begin{cases} 1 & \text{if there is an edge between vertices } i \text{ and } j \\ 0 & \text{otherwise} \end{cases}$ 

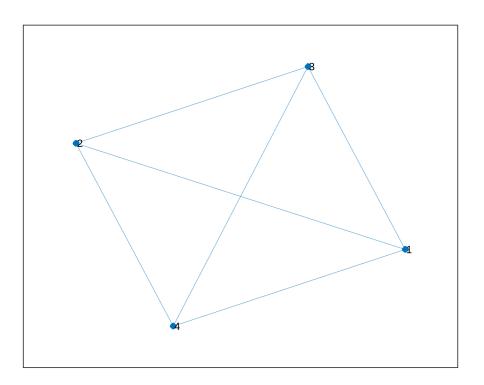
When G is not directed, A is symmetric.

For example,  $K_4$ , the complete graph on 4 vertices has the adjacency matrix:

### The graph of a matrix

You can pass *A* to the graph function to create the associated graph.

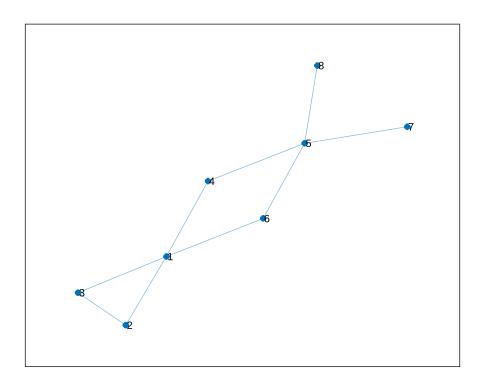
```
K4 = graph(A4);
plot(K4)
```



#### Another example:

plot(G8)

```
A = zeros(8);
A(1,2)=1; A(1,4)=1; A(1,6)=1;
A(1,3)=1; A(2,3)=1; A(4,5) = 1; A(5,6)=1;
A(5,7)=1; A(5,8)=1;
A=A+A' % make A symmetric, since this is non-directed
A = 8 \times 8
               1
                                      0
                                           0
    0
          1
                     1
                           0
                                1
    1
          0
               1
                                           0
                           0
    1
          1
    1
                          1
                                0
                     1
                          0
                                1
                                      1
    1
          0
               0
                     0
                                0
                                      0
                                           0
                          1
    0
          0
               0
                     0
                          1
                                0
                                      0
                                           0
    0
          0
                     0
                          1
                                0
                                      0
                                           0
G8 = graph(A);
```

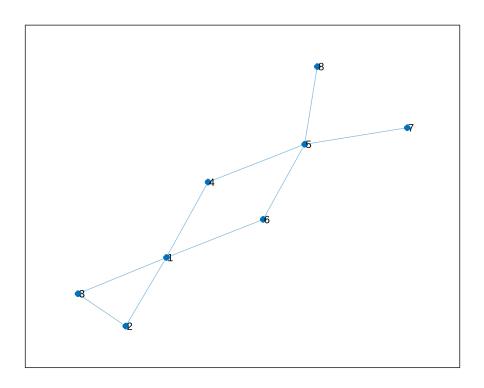


If we have a graph, we can also extract the Adjacency Matrix. By default, this is "sparse". so we will convert to full.

### **Computing with the Adjacency matrix**

The adjacency matrix has many applications. A simple one is the the row (or column) suns of A give you the degree of each vertex:

plot(G8)



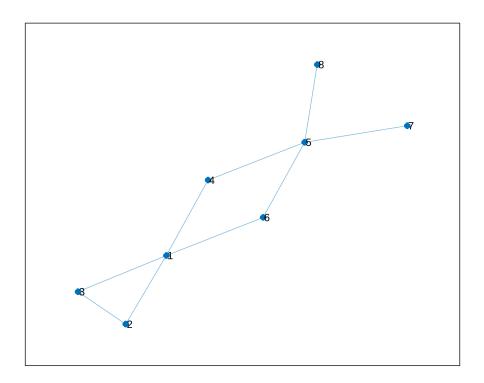
```
d=sum(A)
d = 1 \times 8
     4
           2
                                   2
                                         1
                                               1
for i=1:length(d)
   fprintf("Vertex %d has degree %d\n", i, d(i))
end
Vertex 1 has degree 4
Vertex 2 has degree 2
Vertex 3 has degree 2
Vertex 4 has degree 2
Vertex 5 has degree 4
Vertex 6 has degree 2
Vertex 7 has degree 1
Vertex 8 has degree 1
```

Similarly, we can count the number of edges in the graph: it is half the sum of all the entries in the graph.

Here is another useful property. Set  $e^{(i)}$  to be the vector where  $e_i^{(i)} = 1$ , and all other entries are zero; that is,  $e^{(i)}$  is the ith row of the identity matrix. Now compute  $v = Ae^{(i)}$ . Then  $v_j = 1$  if and only if i is a neighbour of j in G.

A consequence of this is that, if  $B = A^k$ , then  $b_{ij}$  is the number of paths of length k between vertex i and vertex j:

```
plot(G8)
```



B=A^3									
B = 8×8									
2	5	5	6	0	6	2	2		
5	2	3	1	2	1	0	0		
5	3	2	1	2	1	0	0		
6	1	1	0	6	0	0	0		
0	2	2	6	0	6	4	4		
6	1	1	0	6	0	0	0		
2	0	0	0	4	0	0	0		
2	0	0	0	4	0	0	0		

# **Graphs as Objects**

Graphs are examples of *objects* in MATLAB. The full ramifications of that is beyond this module. But, roughly, it means, that, unlike, say, a matrix, it as properties that we can check and change. Try these:

```
Number_of_edges = C4.numedges
Number_of_edges = 4
C4.numnodes
ans = 4
```

```
C4.Edges
```

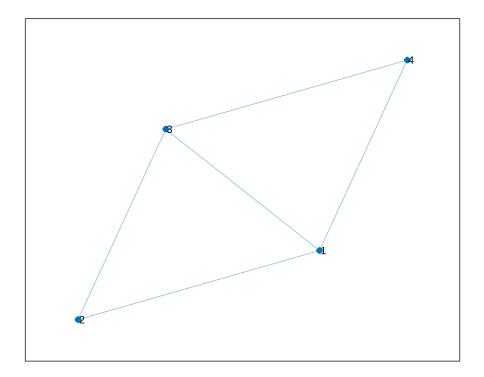
ans =  $4 \times 1$  table

	EndNodes							
	Liidi	140003						
1	1	2						
2	1	4						
3	2	3						
4	3	4						

#### And these:

h =

```
G=C4.addedge(1,3);
plot(G)
```



There are various built-in functions for graphs (though fewer than you might think). For example, the minspantree() function returns a minimum spanning tree for the graph. Here is an example of using it along with highlight().

```
M34 = K34.minspantree()

M34 = graph with properties:

Edges: [6x1 table]
Nodes: [7x0 table]

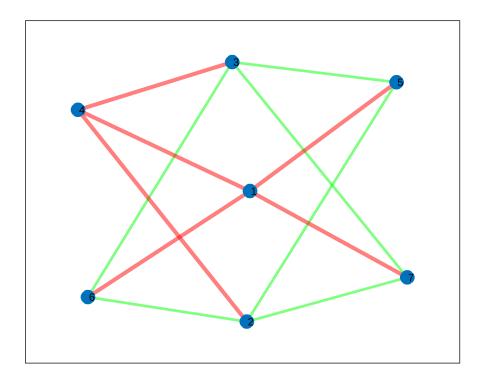
h = plot(K34, 'EdgeColor', 'green', 'LineWidth', 2, 'MarkerSize', 10)
```

```
GraphPlot with properties:

   NodeColor: [0 0.4470 0.7410]
   MarkerSize: 10
        Marker: 'o'
   EdgeColor: [0 1 0]
   LineWidth: 2
   LineStyle: '-'
   NodeLabel: {'1' '2' '3' '4' '5' '6' '7'}
   EdgeLabel: {}
        XData: [0.0782 0.0448 -0.1121 -1.7761 1.6592 -1.6689 1.7749]
        YData: [0.0050 -1.2084 1.2042 0.7596 1.0166 -0.9797 -0.7973]
        ZData: [0 0 0 0 0 0 0]

Show all properties
```

```
h.highlight(M34, 'EdgeColor', 'red', 'LineWidth',3)
```

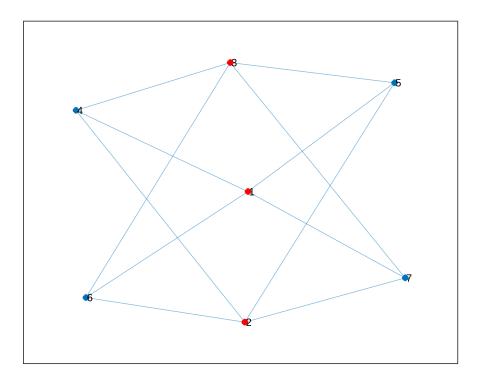


## **Bipartite Graphs**

From Rachel's lectures, you know what a bipartite graph is. Let's construct  $K_{3,4}$ . We'll let the parts be  $\{1,2,3\}$  and  $\{4,5,6,7\}$ . We'll make it with a for-loop (though there are other ways).

```
K34 = graph(); % empty graph
for i=1:3
    for j=4:7
        K34=K34.addedge(i,j);
    end
end
```

```
h=plot(K34);
highlight(h, [1:3], 'NodeColor','red')
```



Here the highlight() function is used to distinguish some vertices. We can also do this for edges, which will prove very useful.

The adjacency matrix of a bipartite graph can be revealing, at least of the vertices are ordered in a certain way,

```
full(K34.adjacency())
ans = 7 \times 7
          0
                     1
                          1
                                1
                                      1
    0
         0 0 1
    0
               0
                     1
                          1
                                1
                                      1
    0
               0
                     1
                          1
                                1
               1
                    0
               1
                    0
                          0
                                0
                                      0
          1
                    0
                          0
                                0
                                      0
               1
```

Determining if a graph is bipartite is not too hard: one can use a breadth-first search. We'll look at that another time.

# **Directed Graphs**

To make a directed grap, use the <code>digraph()</code> function. Example: let's make a random graph with 6 vertices, and 12 edges

```
D = digraph();
```

```
D = addnode(D, 6)

D =
    digraph with properties:

    Edges: [0x1 table]
    Nodes: [6x0 table]

while(D.numedges < 10)
    a = randi(6,1,1);
    b = randi(6,1,1);
    if ((a ~= b) && (findedge(D,a,b)==0))
        D = D.addedge(a,b);
    end
end
plot(D)</pre>
```

