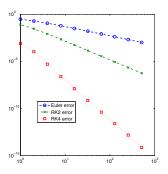
Initial Value Problems

§2.5 Runge-Kutta 4

 ${\sf MA385/530-Numerical\ Analysis\ 1}$

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It is possible to construct methods that have higher orders of accuracy than RK2 methods. Of these, the most used are probably those that belong to the Runge-Kutta 4 (RK4) family, and have the property that

$$|y(t_n)-y_n|\leq Ch^4.$$

However, even writing down the general form of the RK4 method, and then deriving conditions on the parameters is rather complicated. Therefore, we'll focus on just one RK4 method, and use examples, rather than theory, to demonstrate that it is 4th-order.

(53/65)

"The RK4 Method"

$$k_1 = f(t_i, y_i),$$

$$k_2 = f(t_i + \frac{h}{2}, y_i + \frac{h}{2}k_1),$$

$$k_3 = f(t_i + \frac{h}{2}, y_i + \frac{h}{2}k_2),$$

$$k_4 = f(t_i + h, y_i + hk_3),$$

$$y_{i+1} = y_i + \frac{h}{6}(k_1 + 2k_2 + 2k_3 + k_4).$$

§2.5.1 A higher order method

The RK4 method can be interpreted as follows :

(54/65)

§2.5.1 A higher order method

(55/65)

As the following example shows, RK4 can be much more accurate than the Euler or RK2 methods for small h (i.e., large n). For the RK4, doubling n reduces the error by a factor of 8 (compared with 2 and 4 for the Euler and RK2 methods, respectively).

Example 2.12 (2.11 (again))

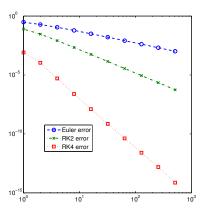
Compare Euler, Modified Euler, and RK4 for approximating y(1) where: y(0) = 1, $y'(t) = y \log(1 + t^2)$.

Error: $|y(t_n) - y_n|$

n	Euler	Modified	RK4
1	3.02e-01	7.89e-02	8.14e-04
2	1.90e-01	2.90e-02	1.08e-04
4	1.11e-01	8.20e-03	5.07e-06
8	6.02e-02	2.16e-03	2.44e-07
16	3.14e-02	5.55e-04	1.27e-08
32	1.61e-02	1.40e-04	7.11e-10
64	8.13e-03	3.53e-05	4.18e-11
128	4.09e-03	8.84e-06	2.53e-12
256	2.05e-03	2.21e-06	1.54e-13
512	1.03e-03	5.54e-07	7.33e-15

Example 2.12 (2.11 (again))

Compare Euler, Modified Euler, and RK4 for approximating y(1) where: y(0) = 1, $y'(t) = y \log(1 + t^2)$.



§2.5.2 Consistency and convergence of RK4 (57/65)

Although we won't do a detailed analysis of RK4, we can do a little. In particular, we would like to show it is

- (i) consistent,
- (ii) convergent and fourth-order, at least for some examples.

Example 2.13

It is easy to see that RK4 is consistent:

§2.5.2 Consistency and convergence of RK4 (58/65)

Example 2.14

In general, showing the rate of convergence is tricky. Instead, we'll demonstrate how the method relates to a Taylor Series expansion for the problem $y'=\lambda y$ where λ is a constant.

§2.5.2 Consistency and convergence of RK4 (59/65)

Many (seemingly different) RK have been proposed and studied. A unified approach of representing them was developed by John Butcher: write an *s*-stage method as

$$\Phi(t_{i}, y_{i}; h) = \sum_{j=1}^{s} b_{j}k_{j}, \text{ where}$$

$$k_{1} = f(t_{i} + \alpha_{1}h, y_{i}),$$

$$k_{2} = f(t_{i} + \alpha_{2}h, y_{i} + \beta_{21}hk_{1}),$$

$$k_{3} = f(t_{i} + \alpha_{3}h, y_{i} + \beta_{31}hk_{1} + \beta_{32}hk_{2}),$$

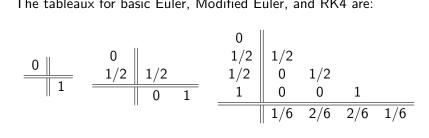
$$\vdots$$

$$k_{s} = f(t_{i} + \alpha_{s}h, y_{i} + \beta_{s1}hk_{1} + \dots \beta_{s,s-1}hk_{s-1}),$$

(61/65)

The most convenient way to represent the coefficients is in a tableau:

The tableaux for basic Euler, Modified Euler, and RK4 are:



A Runge Kutta method has s stages if it involves s evaluations of the function f. (That it, its formula features k_1, k_2, \ldots, k_s).

We've seen a 1-stage method that is 1st-order.

We studied 2-stage methods that are $2^{\rm nd}$ -order.

In an exercise, you'll construct a 3-stage method that is 3rd order.

And, of course, we have just considered a four-stage method that is $4^{\rm th}$ -order.

It is tempting to think that for any s we can get a method of order s using s stages. However, it can be shown that, for example, to get a $5^{\rm th}$ -order method, you need at least 6 stages; for a $7^{\rm th}$ -order method, you need at least 9 stages. The theory involved is both intricate and intriguing, and involves aspects of group theory, graph theory, and differential equations. Students in third year might consider this as a topic for their final year project.

Exercise 2.8

We claim that, for RK4:

$$|\mathcal{E}_N| = |y(t_N) - y_N| \le Kh^4.$$

for some constant K. How could you verify that the statement is true using the data of Table 2.3, at least for test problem in Example 2.4.2? Give an estimate for K.

Exercise 2.9

Recall the problem in Example 2.2.2: Estimate y(2) given that

$$y(1) = 1,$$
 $y' = f(t, y) := 1 + t + \frac{y}{t},$

- (i) Show that f(t, y) satisfies a Lipschitz condition and give an upper bound for L.
- (ii) Use Euler's method with h=1/4 to estimate y(2). Using the true solution, calculate the error.
- (iii) Repeat this for the RK2 method of your choice (with $a \neq 0$) taking h = 1/2.
- (iv) Use RK4 with h = 1 to estimate y(2).

Exercise 2.10 (*)

Here is the tableau for a three stage Runge-Kutta method:

$$\begin{array}{c|cccc}
0 & 1/2 & \\
1 & \beta_{31} & 2 & \\
\hline
& 1/6 & b_2 & 1/6 & \\
\end{array}$$

- (i) Use that the method is consistent to determine b_2 .
- (ii) The method is exact when used to compute the solution to

$$y(0) = 0, \quad y'(t) = 2t, \ t > 0.$$

Use this to determine α_2 .

(iii) The method should agree with an appropriate Taylor series for the solution to $y'(t) = \lambda y(t)$, up to terms that are $\mathcal{O}(h^3)$. Use this to determine β_{31} .