

Efficient Steady-state Simulation of High-dimensional Reflected Brownian Motions

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- Reflected Brownian Motion
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Reflected Brownian Motion (RBM)

- RBM is the solution of a Skorokhod problem with Brownian input.
- Skorokhod problem:

$$0 \leq \mathbf{Y}(t) = \mathbf{Y}(0) + \mathbf{X}(t) + R\mathbf{L}(t), \quad \mathbf{L}(0) = 0 \quad (1)$$

where the i -th entry of $\mathbf{L}(\cdot)$ is non-decreasing and $\int_0^t Y_i(s) dL_i(s) = 0$.

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- Multi-dimensional Brownian motion $\mathbf{X} \rightarrow$ RBM \mathbf{Y} .
- Goal: Find an efficient simulation algorithm to estimate the steady-state expectation of certain functions $f(\cdot)$ of a general multi-dimension RBM for arbitrary dimension d .

Assumptions

- **Uniform contraction:** let $R = I - Q^T$, where Q is substochastic and satisfies

$$\left\| \mathbf{1}^T Q^n \right\|_{\infty} \leq \kappa_0 (1 - \beta_0)^n, \quad n \geq 1.$$

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- **Lipschitz functions:** The function to be estimated $f(\cdot)$ is Lipschitz continuous in l_{∞} norm, i.e. $|f(\mathbf{y}) - f(\mathbf{y}')| \leq \mathcal{L} \|\mathbf{y} - \mathbf{y}'\|_{\infty}$ for $\mathcal{L} > 0$ independent of d .

Multilevel Monte Carlo Algorithm: Discretization

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$$B_i^m(t) = B_i(t_m^-) + (t - t_m^-) \frac{B_i(t_m^+) - B_i(t_m^-)}{t_m^+ - t_m^-}, \text{ for } i = 1, 2, \dots, d.$$

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- $\mathbf{X}^m(t) = \mu t + C\mathbf{B}^m(t)$.
- RBM driven by $\mathbf{X}_{s:t}(\mathbf{X}_{s:t}^m)$ for $\mathbf{X}_{s:t}(u) = \mathbf{X}(s+u) - \mathbf{X}(s)$:

$$\begin{aligned} \mathbf{Y}(t+s; \mathbf{y}, \mathbf{X}_{0:s+t}) &= \mathbf{Y}(t; \mathbf{Y}(s; \mathbf{y}, \mathbf{X}_{0:s}), \mathbf{X}_{s:s+t}), \\ \mathbf{Y}^m(t+s; \mathbf{y}, \mathbf{X}_{0:s+t}^m) &= \mathbf{Y}^m(t; \mathbf{Y}^m(s; \mathbf{y}, \mathbf{X}_{0:s}^m), \mathbf{X}_{s:s+t}^m). \end{aligned} \tag{2}$$

Multilevel Monte Carlo Algorithm: Estimator

Our estimator:

$$Z = \frac{1}{p(M)} \left(f \left(\mathbf{Y}^{M+1} \left(MT; \mathbf{Y}^{M+1} \left(T; \mathbf{y}_0, \mathbf{X}_{0:T}^{M+1} \right), \mathbf{X}_{T:(M+1)T}^{M+1} \right) \right) - f \left(\mathbf{Y}^M \left(MT; \mathbf{y}_0, \mathbf{X}_{T:(M+1)T}^M \right) \right) \right) + f(\mathbf{y}_0).$$

for a random variable M following probability distribution

$$P(M = m) = p(m) = \gamma^m (1 - \gamma) / (1 - \gamma^L) \triangleq K(\gamma) \gamma^m, \text{ for } 0 \leq m < L.$$

Multilevel Monte Carlo Algorithm: Estimator

$$\begin{aligned}
E[Z] &= E[E[Z|M]] \\
&= \sum_{m=0}^{L-1} \left(E \left[f \left(\mathbf{Y}^{m+1} \left(mT; \mathbf{Y}^{m+1}(T; \mathbf{y}_0, \mathbf{X}_{0:T}^{m+1}), \mathbf{X}_{T:(m+1)T}^{m+1} \right) \right) \right] \right. \\
&\quad \left. - E \left[f \left(\mathbf{Y}^m \left(mT; \mathbf{y}_0, \mathbf{X}_{T:(m+1)T}^m \right) \right) \right] \right) + f(\mathbf{y}_0) \\
&= \sum_{m=0}^{L-1} \left(E \left[f \left(\mathbf{Y}^{m+1} \left((m+1)T; \mathbf{y}_0, \mathbf{X}_{0:(m+1)T}^{m+1} \right) \right) \right] \right. \\
&\quad \left. - E[f(\mathbf{Y}^m(mT; \mathbf{y}_0, \mathbf{X}_{0:mT}^m))] \right) + f(\mathbf{y}_0) \\
&= E \left[f \left(\mathbf{Y}^L \left(TL; \mathbf{y}_0, \mathbf{X}_{0:LT}^L \right) \right) \right].
\end{aligned}$$

As $L \rightarrow \infty$,

$$E \left[f \left(\mathbf{Y}^L \left(TL; \mathbf{y}_0, \mathbf{X}_{0:LT}^L \right) \right) \right] \rightarrow E[f(\mathbf{Y}(\infty))].$$

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Error Analysis

$$\begin{aligned} & E \left[f \left(\mathbf{Y}^L \left(TL; \mathbf{y}_0, \mathbf{X}_{0:LT}^L \right) \right) \right] - E \left[f(\mathbf{Y}(\infty)) \right] \\ = & \left(E \left[f \left(\mathbf{Y}^L \left(TL; \mathbf{y}_0, \mathbf{X}_{0:LT}^L \right) \right) \right] - E \left[f \left(\mathbf{Y} \left(TL; \mathbf{y}_0, \mathbf{X}_{0:LT} \right) \right) \right] \right) \\ & + \left(E \left[f \left(\mathbf{Y} \left(TL; \mathbf{y}_0, \mathbf{X}_{0:LT} \right) \right) \right] - E \left[f(\mathbf{Y}(\infty)) \right] \right) \\ = & \text{Discretization Error} + \text{Non-stationarity Error.} \end{aligned}$$

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&= \left(E \left[f \left(\mathbf{Y}^L \left(TL; \mathbf{y}_0, \mathbf{X}_{0:LT}^L \right) \right) \right] - E [f(\mathbf{Y}(TL; \mathbf{y}_0, \mathbf{X}_{0:LT}))] \right) \\
&\quad + (E [f(\mathbf{Y}(TL; \mathbf{y}_0, \mathbf{X}_{0:LT}))] - E [f(\mathbf{Y}(\infty))]) \\
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& + (E [f(\mathbf{Y}(TL; \mathbf{y}_0, \mathbf{X}_{0:LT}))] - E [f(\mathbf{Y}(\infty))]) \\
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\end{aligned}$$

Error Bound

Parameter specification:

- Step size: we recommend γ around 0.05;
- Path length: $T = O(\log(d)^2)$;
- Number of levels: $L = \lceil (\log(\log(d)) + 2 \log(1/\varepsilon) + k_1) / \log(1/\gamma) \rceil$;
- Number of sample paths:

$$N = \lceil (1 - \gamma^L)(1 - \gamma)^{-1} \gamma^{-L} L \rceil = O(\varepsilon^2 \log(d) \log(\log(d))).$$

Theorem

Suppose \mathbf{Y} (indexed by the number of dimensions d) is a sequence of RBMs satisfying Assumptions 1-4. Then, the total expected cost, in terms of **the number of scalar Gaussian random variables**, for the Multilevel Monte Carlo Algorithm to produce an estimator of $E[f(\mathbf{Y}(\infty))]$ with mean square error (MSE) ε^2 is

$$O(\varepsilon^{-2} d \log(d)^3 (\log(\log(d)) + \log(1/\varepsilon))^3).$$

Numerical Experiments: Setup

- Symmetric RBMs: $\boldsymbol{\mu} = -[1, 1, \dots, 1]^T$

$$\Sigma = \begin{bmatrix} 1 & \rho_\sigma & \dots & \rho_\sigma \\ \rho_\sigma & 1 & \dots & \rho_\sigma \\ \vdots & & 1 & \vdots \\ \rho_\sigma & \dots & \rho_\sigma & 1 \end{bmatrix}, \quad R = \begin{bmatrix} 1 & -r & \dots & -r \\ -r & 1 & \dots & -r \\ \vdots & & 1 & \vdots \\ -r & \dots & -r & 1 \end{bmatrix}.$$

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- Closed form solution:

$$E[Y_1(\infty)] = \frac{1 - (d-2)r + (d-1)r\rho_\sigma}{2(1+r)} = \frac{\beta}{2}.$$

Numerical Experiments: Setup

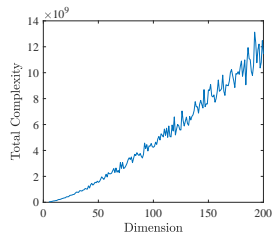
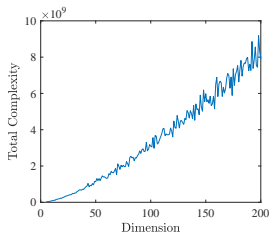
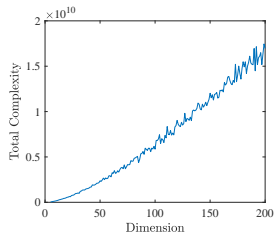
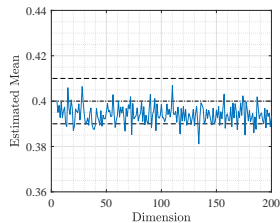
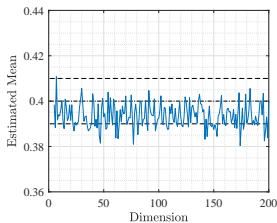
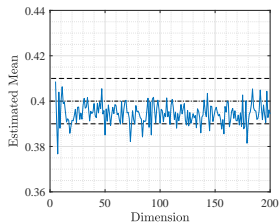
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- Pick $\beta = 0.8$ and $E[Y_1(\infty)] = 0.4$.

(a) $\gamma = 0.01$ (b) $\gamma = 0.05$ (c) $\gamma = 0.1$ Figure 1: Simulation results for symmetric RBMs at target error level $\epsilon = 0.01$.

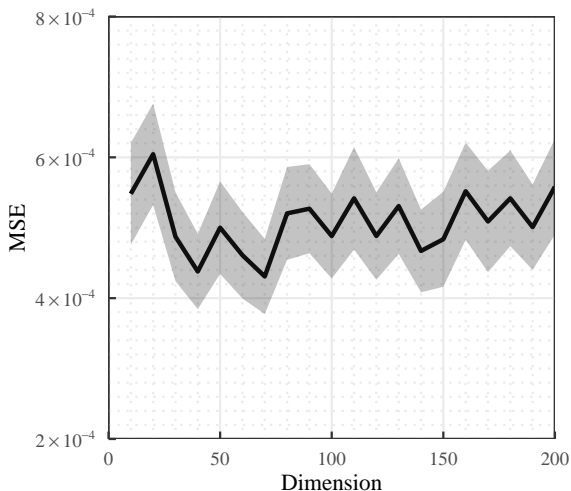


Figure 2: Mean square error of the estimators at target error level $\epsilon = 0.05$ for $\gamma = 0.05$. The shaded area represents 95% confidence band for the MSE.

Blanchent, Jose, Xinyun Chen, Peter Glynn, and **Nian Si**. "Efficient Steady-state Simulation of High-dimensional Stochastic Networks." arXiv preprint arXiv:2001.08384 (2020).

Thanks!