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MCSNet: Multi-scale Channel Sharing based network for Single Image Super-resolution

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Abstract:. The performance and processing speed of single-image super-resolution (SISR) increased every day due to the rapid advancement in convolutional neural network (CNN) architectures. However, CNN-based architectures have a high computational cost, more processing time, and reconstructed results are still necessarisfactory. Furthermore, CNN architectures depend on the single-channel type network architecture to reconstruct the high-resolution (HR) image, which also creates problems furing the training, and extracted features are not received at the later end layer. To report these problems, we proposed a Multi-scal fundamental sharing based network for SISR known as MCSNet. In addition, the multi-channel sharing technique is used to extract and share the features information through different routes, which is very important to resolve the SISR problem. Extensive quantitative and qualitative results show that our MCSNet method achieves a better trade-off against other existing methods in terms of peak signal-to-noise ratio (PSNR), Structural Similarity Index (SSIM), and perceptual quality. Especially on difficult scale factor 8×, our proposed method improves the overall average PSNR on all test datasets including Set5, Set14, Urban100, and Manga109 by 2.04dB with the baseline southood.

Index terms: Single image super-resolution, Dense channel sharing block, LeakyReLU, Convolutional Neural Network.

INTRODUCTION

The main target of single image super-resolution (SISR) is to reconstruct the high quality / highresolution (HR) output image from its degraded lowquality / low-resolution (LR) input image [1]. The SISR is still a challenging task to solve due to its illposed problem. To report such problem 27 various image super-resolution (SR) methods have been including bicubic interpolations, construction, and learning-based approaches.

CNN learning-based image SR methods have achieved tremendous performance due to the rapid improvement in the convolutional neural network (CNN) design. Recently, available approaches to deep learning-based CNN methods. Among them, Dong et al. [2] initially proposed the shallow-based architecture using three CNN layers to deve18) the direct relationships between an original LR input image and a high-resolution reconstructed output image known as a super-resolution convolutional neural network (SRCNN). Tiese three layers perform three basic operations, such as feature extraction, non-linear mapping, and restoration, respectively. The main flaws 2 f this approach are to use the bicubic interpolation as a pre-processing step to upscale the LR image as an input and reconstruct the interpolated version of the HR output image. The author of SRCNN [2] modified the architecture and replaced the pre-upsampling bicubic interpolation

technique with a post-upsampling learnable layer (transpose convolution) named Fast SR Convolutional Neural Network (FSRCNN) [3]. This modification leads to a decrease in the number of parameters as well as memory consumption.

To improve the shortcomings observed during the SRCNN [2] and FSRCNN [3] models, Kim et al. used the concept of the Visual Geometry Group (VGG) model which is used in the ImageNet clanding track, and proposed the 20-layer network known as Very Deep Super Resolution (VDSR) [4]. The performance of VDSR [4] is better than earlier approaches such as SRCNN [2] and FSRCNN [3] with the large margin gap. Furthermore, VDSR [1] employed the residual learning technique to avoid the vanishing gradient problem as well as increase the speed of convergence.

The relationship between SRCNN [2] and the sparse-SCN methods confirms its acceptable performance. Wang et al. [5] replaced layers of mapping with the set of sparse-based coding type networks and commonly known as SCN (sparse coding 25 twork). Deeper is the better to follow this concept Kim et al., [6] proposed the image SR method using a deeply recursive CN (DRCN). This architecture used very deep recursive type layers (16 times of recursions). DRCNN [6] method same convolutional layers applies repeatedly as several times as desired, but the computational cost

does not increase although more times recursions are applied.

Likewise, Tai et al. suggest 24 he concept of a twoway novel network, one for a deep recursive residual network (DRRN) [7] [24], and the next is used for a persistent memory network (MemNet) [8]. The earlier 19 ign is employed for the recursive type of learning to reduce the number of parameters. The final part of a model resolves the long-term dependency problem. However, these two methods used more processing time and extra huge memory consumption in the testing as well as the training process. 27-CNN layers with robust Charbonnier 10 ss function network architecture proposed by Lai et al. presented the Laplacian pyramid SR network (LapSRN) [9] to gradually reconstruct the HR images.

Recently, deep CNN-based single image SR is to attain the improved performance as compared to conventional methods, but still faces some challenging issues [10]. Generally, the deep CNN model used a convolutional layer side-by-side to design a deeper framework, which introduces the vanishing gradient problem and later end layers work as a dead layer. Similarly, some well-known deep NN methods [2, 4] used the interpolation technique as a pre-nocessing stage to upscale the LR image and then extract the CNN features from the upscaled version of the HR image. These approaches are not successful, because it introduces the new noise in the models and used more burden on the model during the training. Additionally, deep CNN relies on two-way multi-scale channel sharing type network architecture, which does not extract the complete feature information through the previous layers.

To address these problems, we have suggested the Multi-scale Channel Sharing based network for Single Image Super-resolution architecture, named as MCSNet, which uses the Dense channel sharing ResNet blocks (DCSRB) with local as well as global skip connections. In summary, we stablish a novel Multi-scale Channel Sharing based network for Single Image Super-resolution, which performs a better improvement in terms of PSNR/SSIM, and perceptual quality point of view.

The overall main contribution of our MCSNet method can be summarized as follow:

• Inspired by N2 liti-scale Channel Sharing with ResNet architecture, we proposed a Multi-scale Channel Sharing the network for Single Image Superresolution network for the image SR method with post-upsampling technique to reconstruct the high-quality HR output image.

- We proposed a new multi-channel path scheme to excellently boost the representations of features of the HR image. Multi-channel path scheme consists of dense channel sharing ResNet block (DCSRB) which facilitates the feature extraction through each earlier and subsequent CNN layer.
- Conventional deep CNN methods used Rectified Linear Unit (ReLU) activation function, which introduces the vanishing-gradient problems in a training, in case of deeper network rehitecture. In this regard, we changed the ReLU with a leaky ReLU activation function to avoid the vanishing-gradient problems and perform the training of the model more efficient. The remaining parts of the paper are divided as follows: The proposed method is presented in Section III. The experimental calculations are discussed in Section III. Finally, the conclusion is reported in the last section.

II. PROPOSED METHOD

In this paper, we propose the concept of multi-scale channel sharing type network architecture with the support of dense channel sharing Resnet block (DCSRB). First, we discuss the proposed network architecture of MCSNet in detail, and then we discuss the DCSR 26 lock with different CNN layers used in the main architecture as shown in Figure 1. The proposed ne propos CNN layers followed by Leaky Rectified Linear Unit (LeakyReLU) activation function. These CNN layers extracted the initial features and then fed the four DCSRB blocks side by side as well as timely updated features information received through local as well as global skip connections. Finally, the cumulative LR features pass through the deconvolution layer to upscale and reconstructed the HR output image. The design of LReLU depends on the ReLU and it provides two outputs one for (0, x) and the other for (x,0). Additionally, the earlier approach depends on a maximum one or two-channel sharing residual block to extract the image features of different scales [11]. The reconstructed features information is satisfactory, but in the case of deeper and denser network architecture information is lost and cannot extract the detailed features, as well as sometimes information, is stuck. In our proposed DCSRB block design in such a way to split the original features information with five different kernel size multiscale channels in the order of 1×1 , 3×3 , 5×5 , 7×7 , and 9×9 . The first branch used 1×1, convolutional neural netwark layers to reduce the dimension of the input data as well as reduce the computational cost of the model [12] and other branches of different kernel sizes are used to extract the multi-channel information as shown in Figure 2. Finally, in the reconstruction phase, the upsamples operation is used by 3×3 deconvolution to generate the high-17 lity or high-resolution (HR) output image. The 1×1 convolution operation is used before the deconvolution layer to reduce the size of the dimension.

41. EXPERIMENTS

In the experimental section, we explain the training and testing datasets strategy for reconstructing the HR image, procedures. Our MCSNet used the 3 different training datasets, such as Yang et al., [13], BSDS100 [14], and DIV2K [15] (including 50 impgs) for training purposes. The complete training dataset is split into two sections, like 80% for training and 20% 🌇 validation. Our proposed method is tested on four standard publicly available datasets, including Set5 [16], Set14 [13], Urban100 [17], and Manga109 [18]. Set5 [16], and Set14 [13] used the images in the order of 5 and 14. In Urban100 and Manga109 [18] available images are in the order of 100 and 109. We evaluated our model with frequently used quality metrics the PSNR/SSIM because these metrics are directly related. Our model performs training as well as testing under the environment of the Windows 10 operating system with NVIDIA GeForce RTX20270 GPU model having 16 GB RAM. Training performs an enlargement factor 8x in Keras 2.15 and MAT 16 B2018 a framework. The quantitative experimental results are present in Table 1, which shows that the proposed method attains higher average quantitative values.

8 CONCLUSION

In this paper, we proposed a Multi-scale Channel Sharing based network for Single Image Super-resolution (MCSNet) based on the convolution, LeakyReLU, and dense chan 5 l sharing Resnet block (DCSRB) for reconstructing the visually pleasing HR output image. To increase the quantitative as well as a qualitative evaluation of the LR image, we employed the four DCSRB bocks followed by the LeakyReLU activation function. Furthermore, to increase the training convergence process and fixed the dying ReLU problem in the dense CNN model, we replaced the ReLU activation function with LeakyReLU nonlinear activation function. Moreover, the whole network architecture adopts local as well global skip connections to cantare the more high-frequency feature information for single image super-resolution reconstruction. Quantitati8, as well as qualitative performance evaluated on four benchmark test datasets, demonstrates that the proposed MCSNet can superior performance in terms of reconstructed results. 20

Additionally, we evaluate the performance of our proposed method in terms of perceptual quality with different publicly available methods as shown in Figure 3. The proposed and other methods in Figure 3 used 3 images of butterfly, zebra, and PrayerHaNemurenai obtained from Set5, Set14, and Manga109 with scale factor 8×. In the case of the bicubic interpolation technique texture generated is blurry output. Other methods such as SRCNN, VDSR, and DRCN produce improved results than the baseline method. In our proposed method reconstructed output is a visually pleasing texture detail with a high value of PSNR/SSIM.

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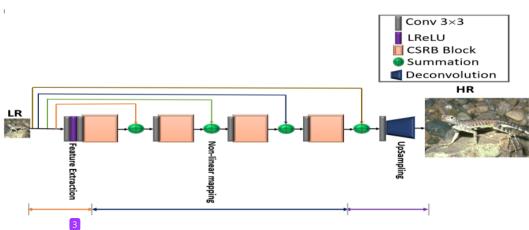


Figure 1: Proposed Multi-scale Channel Sharing based network for Single Image Super-resolution (MCSNet)

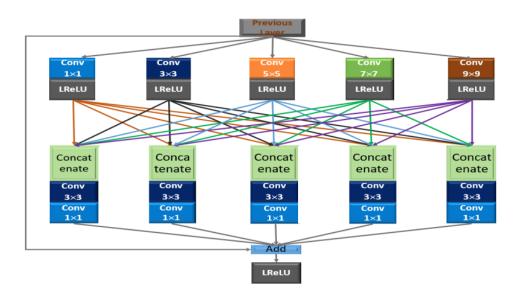


Figure 2: Dense channel sharing ResNet Block (DCSRB)

Table 1

The quantitative comparison of average PSNR/SSIM with existing image super-resolution algorithms on four test datasets (Set5, Set14, Urban100, and Manga109) on challenging enlargement factor ×8.

Datasets	Scale	15 bic PSNR SSIM	SRCNN [2] PSNR SSIM	FSRCNN [3] PSNR SSIM	SCN [5] PSNR SSIM	VDSR [4] PSNR SSIM	DRCN [6] PSNR SSIM	MCSNet PSNR SSIM
SET5 [16]	×8	24.40	25.33	20.13	25.59	25.93	25.93	25.95
SET14 [13]	×8	0.6580 23.10	0.6900 23.76	0.5520 19.75	0.7071 24.02	0.7240 24.26	0.7230 24.25	0.7231 25.12
		0.5660	0.5910	0.4820	0.6028	0.6140	0.6141	0.6152
URBAN100 [17]	×8	20.74 0.5160	21.29 0.5440	21.32 0.5380	21.52 0.5571	21.70 0.5710	21.71 0.5710	23.38 0.5821
MANGA109 [18]	×8	21.47	22.46	22.39	22.68	23.16	23.20	23.43
		0.6500	0.6950	0.6730	0.6963	0.7250	0.7240	0.7331
Average	×8	22.43	23.21	20.90	23.45	23.76	23.77	24.47
		0.5975	0.6300	0.5613	0.6408	0.6585	0.6580	0.6634

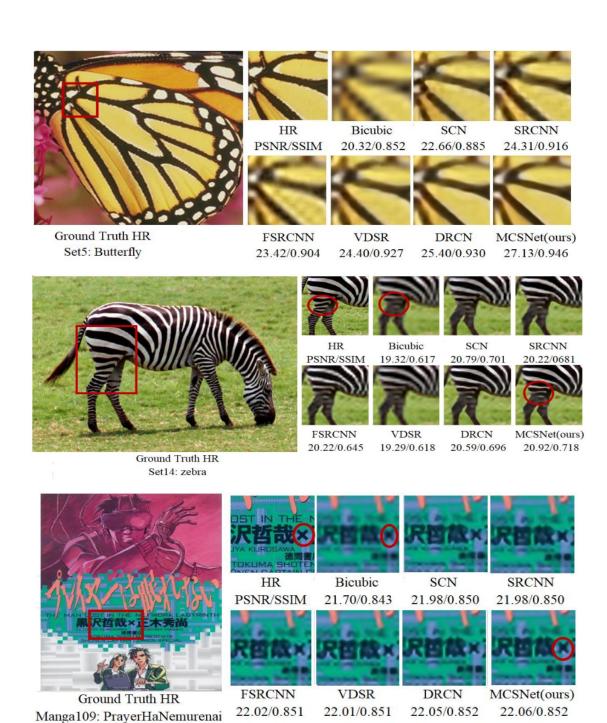


Figure 3: Presents the perceptual quality comparison on enlargement factor 8x of different image super-resolution methods using test datasets of Set5, Set14, and Manga109.

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