# dog\_app

June 5, 2020

# 1 Convolutional Neural Networks

# 1.1 Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

**Note**: Once you have completed all of the code implementations, you need to finalize your work by exporting the Jupyter Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to **File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

**Note:** Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this Jupyter notebook.

## Step 0: Import Datasets

Make sure that you've downloaded the required human and dog datasets:

Note: if you are using the Udacity workspace, you *DO NOT* need to re-download these - they can be found in the /data folder as noted in the cell below.

- Download the dog dataset. Unzip the folder and place it in this project's home directory, at the location /dog\_images.
- Download the human dataset. Unzip the folder and place it in the home directory, at location /lfw.

Note: If you are using a Windows machine, you are encouraged to use 7zip to extract the folder. In the code cell below, we save the file paths for both the human (LFW) dataset and dog dataset in the numpy arrays human\_files and dog\_files.

# ## Step 1: Detect Humans

In this section, we use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

OpenCV provides many pre-trained face detectors, stored as XML files on github. We have downloaded one of these detectors and stored it in the haarcascades directory. In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

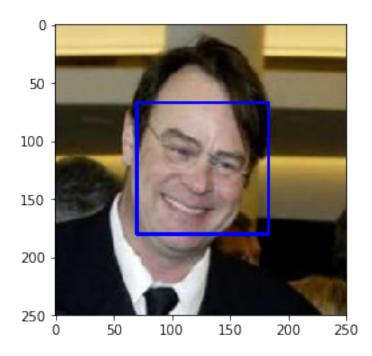
```
In [2]: import cv2
    import matplotlib.pyplot as plt
    %matplotlib inline

# extract pre-trained face detector
    face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')

# load color (BGR) image
    img = cv2.imread(human_files[0])
    # convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
    faces = face_cascade.detectMultiScale(gray)
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face\_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

#### 1.1.1 Write a Human Face Detector

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face\_detector, takes a string-valued file path to an image as input and appears in the code block below.

```
In [3]: # returns "True" if face is detected in image stored at img_path
    def face_detector(img_path):
        img = cv2.imread(img_path)
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        faces = face_cascade.detectMultiScale(gray)
        return len(faces) > 0
```

# 1.1.2 (IMPLEMENTATION) Assess the Human Face Detector

**Question 1:** Use the code cell below to test the performance of the face\_detector function.

- What percentage of the first 100 images in human\_files have a detected human face?
- What percentage of the first 100 images in dog\_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human\_files\_short and dog\_files\_short.

Answer: (You can print out your results and/or write your percentages in this cell)

```
In [4]: from tqdm import tqdm
        human_files_short = human_files[:100]
        dog_files_short = dog_files[:100]
        #-#-# Do NOT modify the code above this line. #-#-#
        ## TODO: Test the performance of the face_detector algorithm
        ## on the images in human_files_short and dog_files_short.
        sum_human=0
        for i in human_files_short:
            if(face_detector(i)==True):
                sum_human=sum_human+1
        percent_human_face=float(sum_human/len(human_files_short))*100
        print("%.2f%% percent of the first 100 images in human_files have a detected human face"
        ## Dog file and detected human face
        sum_dog=0
        for i in dog_files_short:
            if(face_detector(i)==True):
                sum_dog=sum_dog+1
        percent_human_face_dog=float(sum_dog/len(dog_files_short))*100
        print("%.2f%% percent of the first 100 images in dog_files have a detected human face "%
98.00% percent of the first 100 images in human_files have a detected human face
```

17.00% percent of the first 100 images in dog\_files have a detected human face

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

## Step 2: Detect Dogs

In this section, we use a pre-trained model to detect dogs in images.

### 1.1.3 Obtain Pre-trained VGG-16 Model

The code cell below downloads the VGG-16 model, along with weights that have been trained on ImageNet, a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories.

```
In [5]: import torch
    import torchvision.models as models

# define VGG16 model
    VGG16 = models.vgg16(pretrained=True)

# check if CUDA is available
    use_cuda = torch.cuda.is_available()

# move model to GPU if CUDA is available
    if use_cuda:
        VGG16 = VGG16.cuda()
```

Downloading: "https://download.pytorch.org/models/vgg16-397923af.pth" to /root/.torch/models/vgg100%|| 553433881/553433881 [00:05<00:00, 99997037.95it/s]

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

### 1.1.4 (IMPLEMENTATION) Making Predictions with a Pre-trained Model

In the next code cell, you will write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher\_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model. The output should always be an integer between 0 and 999, inclusive.

Before writing the function, make sure that you take the time to learn how to appropriately pre-process tensors for pre-trained models in the PyTorch documentation.

```
In [6]: from PIL import Image
        import torchvision.transforms as transforms
        from PIL import ImageFile
        ImageFile.LOAD_TRUNCATED_IMAGES = True
        def VGG16_predict(img_path, max_size=400, shape = None):
            Use pre-trained VGG-16 model to obtain index corresponding to
            predicted ImageNet class for image at specified path
            Args:
                img_path: path to an image
            Returns:
                Index corresponding to VGG-16 model's prediction
            ## TODO: Complete the function.
            ## Load and pre-process an image from the given img_path
            if "http" in img_path:
                response = requests.get(img_path)
                image = Image.open(BytesIO(response.content)).convert('RGB')
            else:
                image = Image.open(img_path).convert('RGB')
            # large images will slow down processing
            if max(image.size) > max_size:
                size = max size
            else:
                size = max(image.size)
            if shape is not None:
                size = shape
            in_transform = transforms.Compose([transforms.Resize(size),
                                                  transforms.CenterCrop((224,224)),
                                                  transforms.ToTensor(),
                                                  transforms.Normalize(mean=[0.485, 0.456, 0.406]
                                                                       std=[0.229, 0.224, 0.225])
            # discard the transparent, alpha channel (that's the :3) and add the batch dimension
            image = in_transform(image).unsqueeze(0)
            if torch.cuda.is_available():
                image = image.cuda()
            # get sample outputs
```

```
pred = VGG16(image)
    _, preds_tensor = torch.max(pred, 1)
    pred = np.squeeze(preds_tensor.numpy()) if not use_cuda else np.squeeze(preds_tensor
    return int(pred)

In [7]: VGG16_predict(dog_files[0])

Out[7]: 243

In [8]: VGG16_predict(human_files_short[0])
```

# 1.1.5 (IMPLEMENTATION) Write a Dog Detector

While looking at the dictionary, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained VGG-16 model, we need only check if the pre-trained model predicts an index between 151 and 268 (inclusive).

Use these ideas to complete the dog\_detector function below, which returns True if a dog is detected in an image (and False if not).

# 1.1.6 (IMPLEMENTATION) Assess the Dog Detector

**Question 2:** Use the code cell below to test the performance of your dog\_detector function.

- What percentage of the images in human\_files\_short have a detected dog?
- What percentage of the images in dog\_files\_short have a detected dog?

### Answer:

Out[8]: 906

```
number_human_detected += 1

for image in dog_files_short:
    if (dog_detector(image)):
        number_dog_detected += 1

    print("Percentage of the images in human_files_short with detected dog :", number_human_print("Percentage of the images in dog_files_short with detected dog :", number_dog_det

Percentage of the images in human_files_short with detected dog : 0.01

Percentage of the images in dog_files_short with detected dog : 0.99
```

## In []:

We suggest VGG-16 as a potential network to detect dog images in your algorithm, but you are free to explore other pre-trained networks (such as Inception-v3, ResNet-50, etc). Please use the code cell below to test other pre-trained PyTorch models. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

## Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

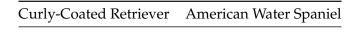
for image in human\_files\_short:
 if (dog\_detector(image)):

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain a test accuracy of at least 10%. In Step 4 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have trouble distinguishing between a Brittany and a Welsh Springer Spaniel.

Brittany	Welsh Springer Spaniel

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).



Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.

Yellow Labrador Chocolate Labrador

We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

## 1.1.7 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dog\_images/train, dog\_images/valid, and dog\_images/test, respectively). You may find this documentation on custom datasets to be a useful resource. If you are interested in augmenting your training and/or validation data, check out the wide variety of transforms!

```
In [32]: import os
         from torchvision import datasets
         ## defining training, validation and test data directories
         data_dir = '/data/dog_images/'
         train_dir = os.path.join(data_dir, 'train/')
         valid_dir = os.path.join(data_dir, 'valid/')
         test_dir = os.path.join(data_dir, 'test/')
         size=224
         # VGG-16 Takes 224x224 images as input, so we resize all of them
         train_transforms = transforms.Compose([transforms.Resize(size),
                                                   transforms.CenterCrop((size, size)),
                                                   transforms.RandomHorizontalFlip(),
                                                   transforms.ToTensor(),
                                                   transforms.Normalize(mean=[0.485, 0.456, 0.406
                                                                        std=[0.229, 0.224, 0.225]
         valid_transforms = transforms.Compose([transforms.Resize(size),
                                                   transforms.CenterCrop((size, size)),
                                                   transforms.ToTensor(),
                                                   transforms.Normalize(mean=[0.485, 0.456, 0.406
                                                                        std=[0.229, 0.224, 0.225]
         test_transforms = transforms.Compose([transforms.Resize(size),
                                                transforms.CenterCrop((size, size)),
                                                transforms.ToTensor(),
```

transforms.Normalize(mean=[0.485, 0.456, 0.406],

**Question 3:** Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

### Answer:

When we perform transfer learning, we have to shape our input data into the shape that the pre-trained model expects. VGG16 expects 224-dim square images as input and so, we resize each image to fit this mold. We use randomResizedCrop. This code give the crop of random size of the original size and a random aspect ratio of the original aspect ratio is made. This crop is finally resized to given size 224.

### 1.1.8 (IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. Use the template in the code cell below.

# In []: In [33]: # define the CNN architecture class Net(nn.Module): def \_\_init\_\_(self): super(Net, self).\_\_init\_\_() # convolutional layer (sees 32x32x3 image tensor) self.conv1 = nn.Conv2d(3, 16, 3, padding=1) # convolutional layer (sees 16x16x16 tensor) self.conv2 = nn.Conv2d(16, 32, 3, padding=1) # convolutional layer (sees 8x8x32 tensor) self.conv3 = nn.Conv2d(32, 64, 3, padding=1)# max pooling layer self.pool = nn.MaxPool2d(2, 2) # linear layer (64 \* 4 \* 4 -> 500) self.fc1 = nn.Linear(64 \* 28 \* 28, 500)# linear layer (500 -> 133) self.fc2 = nn.Linear(500, 133)# dropout layer (p=0.20) self.dropout = nn.Dropout(0.20)

```
self.batch_norm = nn.BatchNorm1d(num_features=500)
             def forward(self, x):
                 # add sequence of convolutional and max pooling layers
                 x = self.pool(F.relu(self.conv1(x)))
                 x = self.pool(F.relu(self.conv2(x)))
                 x = self.pool(F.relu(self.conv3(x)))
                 # flatten image input
                 x = x.view(x.size(0), -1)
                 # add dropout layer
                 x = self.dropout(x)
                 # add 1st hidden layer, with relu activation function
                 x = F.relu(self.fc1(x))
                 # add dropout layer
                 x = self.dropout(x)
                 # add 2nd hidden layer, with relu activation function
                 x = self.fc2(x)
                 return x
         #-#-# You so NOT have to modify the code below this line. #-#-#
         # instantiate the CNN
         model_scratch = Net()
         print(model_scratch)
Net(
  (conv1): Conv2d(3, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (conv2): Conv2d(16, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (conv3): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (fc1): Linear(in_features=50176, out_features=500, bias=True)
  (fc2): Linear(in_features=500, out_features=133, bias=True)
  (dropout): Dropout(p=0.2)
  (batch_norm): BatchNorm1d(500, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
)
In [34]: # move tensors to GPU if CUDA is available
         if use_cuda:
             model_scratch.cuda()
```

**Question 4:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

### **Answer:**

I started by checking result for simple network, didn't get good result. Then 2, 3 convolutional layers, then add 3 layers to get better result. I also add dropout to avoid overfitting problem.

## 1.1.9 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_scratch, and the optimizer as optimizer\_scratch below.

```
In [35]: import torch.optim as optim
    ### TODO: select loss function
    criterion_scratch = nn.CrossEntropyLoss()

### TODO: select optimizer
    optimizer_scratch = optim.SGD(model_scratch.parameters(), lr=0.05)
```

### 1.1.10 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_scratch.pt'.

In [36]: def train(n\_epochs, loaders, model, optimizer, criterion, use\_cuda, save\_path):

```
"""returns trained model"""
# initialize tracker for minimum validation loss
valid_loss_min = np.Inf
for epoch in range(1, n_epochs+1):
    # initialize variables to monitor training and validation loss
    train_loss = 0.0
    valid_loss = 0.0
    ##################
    # train the model #
    ###################
    model.train()
    for batch_idx, (data, target) in enumerate(loaders['train']):
        # move to GPU
        if use_cuda:
            data, target = data.cuda(), target.cuda()
        ## find the loss and update the model parameters accordingly
        ## record the average training loss, using something like
        \#\# train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
        # clear the gradients of all optimized variables
        optimizer.zero_grad()
        # forward pass: compute predicted outputs by passing inputs to the model
        output = model(data)
        # calculate the batch loss
        loss = criterion(output, target)
        # backward pass: compute gradient of the loss with respect to model paramet
        loss.backward()
```

# perform a single optimization step (parameter update)

```
train_loss += loss.item()*data.size(0)
                 #####################
                 # validate the model #
                 #######################
                 model.eval()
                 for batch_idx, (data, target) in enumerate(loaders['valid']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.cuda(), target.cuda()
                     ## update the average validation loss
                     # forward pass: compute predicted outputs by passing inputs to the model
                     output = model(data)
                     # calculate the batch loss
                     loss = criterion(output, target)
                     # update average validation loss
                     valid_loss += loss.item()*data.size(0)
                 # calculate average losses
                 train_loss = train_loss/len(loaders['train'].dataset)
                 valid_loss = valid_loss/len(loaders['valid'].dataset)
                 # print training/validation statistics
                 print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
                     epoch,
                     train_loss,
                     valid loss
                     ))
                 ## TODO: save the model if validation loss has decreased
                 if valid_loss <= valid_loss_min:</pre>
                     print('Validation loss decreased ({:.6f} --> {:.6f}). Saving model ...'.fc
                     valid_loss_min,
                     valid_loss))
                     torch.save(model.state_dict(), save_path)
                     valid_loss_min = valid_loss
             # return trained model
             return model
In []: # train the model
        model_scratch = train(10, loaders_scratch, model_scratch, optimizer_scratch, criterion_s
                                                 Validation Loss: 4.672931
Epoch: 1
                 Training Loss: 4.823888
```

optimizer.step()

# update training loss

```
Validation loss decreased (inf --> 4.672931). Saving model ...
Epoch: 2
                 Training Loss: 4.573184
                                                 Validation Loss: 4.423127
Validation loss decreased (4.672931 --> 4.423127).
                                                    Saving model ...
                 Training Loss: 4.339071
                                                 Validation Loss: 4.316312
Epoch: 3
Validation loss decreased (4.423127 --> 4.316312). Saving model ...
Epoch: 4
                 Training Loss: 4.174902
                                                 Validation Loss: 4.315998
Validation loss decreased (4.316312 --> 4.315998). Saving model ...
Epoch: 5
                 Training Loss: 4.039317
                                                 Validation Loss: 4.214721
Validation loss decreased (4.315998 --> 4.214721). Saving model ...
Epoch: 6
                 Training Loss: 3.867229
                                                 Validation Loss: 4.083994
Validation loss decreased (4.214721 --> 4.083994). Saving model ...
                 Training Loss: 3.650617
                                                 Validation Loss: 4.096654
Epoch: 7
                                                 Validation Loss: 4.280151
Epoch: 8
                 Training Loss: 3.337385
Epoch: 9
                                                 Validation Loss: 4.467838
                 Training Loss: 2.914119
```

### 1.1.11 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 10%.

```
In [24]: def test(loaders, model, criterion, use_cuda):
             # monitor test loss and accuracy
             test_loss = 0.
             correct = 0.
             total = 0.
             model.eval()
             for batch_idx, (data, target) in enumerate(loaders['test']):
                 # move to GPU
                 if use_cuda:
                     data, target = data.cuda(), target.cuda()
                 # forward pass: compute predicted outputs by passing inputs to the model
                 output = model(data)
                 # calculate the loss
                 loss = criterion(output, target)
                 # update average test loss
                 test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                 # convert output probabilities to predicted class
                 pred = output.data.max(1, keepdim=True)[1]
                 # compare predictions to true label
                 correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
                 total += data.size(0)
```

## Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

# 1.1.12 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dogImages/train, dogImages/valid, and dogImages/test, respectively).

If you like, **you are welcome to use the same data loaders from the previous step**, when you created a CNN from scratch.

### 1.1.13 (IMPLEMENTATION) Model Architecture

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model\_transfer.

```
In [38]: import torchvision.models as models
    import torch.nn as nn

## TODO: Specify model architecture
    model_transfer = models.vgg16(pretrained=True)

# Freeze training for all "features" layers
    for param in model_transfer.parameters():
        param.requires_grad = False

n_inputs = model_transfer.classifier[6].in_features
```

```
# add last linear layer (n_inputs -> 5 flower classes)
# new layers automatically have requires_grad = True
last_layer = nn.Linear(n_inputs, 133)

model_transfer.classifier[6] = last_layer

if use_cuda:
    model_transfer = model_transfer.cuda()
```

**Question 5:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

#### **Answer:**

We used vgg16 tot train our model. We decided to change the last layer, to fit our problem. The only thing we changed in our CNN network. And take output to 133, in order to fit our problem which contains 133 dog labels.

### 1.1.14 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_transfer, and the optimizer as optimizer\_transfer below.

### 1.1.15 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_transfer.pt'.

```
In [40]: # train the model
        model_transfer = train(10, loaders_transfer, model_transfer, optimizer_transfer, crite
         # load the model that got the best validation accuracy (uncomment the line below)
        model_transfer.load_state_dict(torch.load('model_transfer.pt'))
                Training Loss: 1.327893
                                                Validation Loss: 0.551729
Epoch: 1
Validation loss decreased (inf --> 0.551729). Saving model ...
                Training Loss: 0.651695
Epoch: 2
                                                Validation Loss: 0.522373
Validation loss decreased (0.551729 --> 0.522373). Saving model ...
                Training Loss: 0.554557
Epoch: 3
                                               Validation Loss: 0.506304
Validation loss decreased (0.522373 --> 0.506304). Saving model ...
Epoch: 4
                Training Loss: 0.503766
                                               Validation Loss: 0.504608
Validation loss decreased (0.506304 --> 0.504608). Saving model ...
                Training Loss: 0.452263
Epoch: 5
                                          Validation Loss: 0.426363
Validation loss decreased (0.504608 --> 0.426363). Saving model ...
Epoch: 6
                Training Loss: 0.410407
                                             Validation Loss: 0.470198
Epoch: 7
                Training Loss: 0.396995
                                              Validation Loss: 0.560766
```

```
Epoch: 8 Training Loss: 0.401364 Validation Loss: 0.452321

Epoch: 9 Training Loss: 0.361444 Validation Loss: 0.492270

Epoch: 10 Training Loss: 0.348414 Validation Loss: 0.468799
```

### 1.1.16 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 60%.

```
In [41]: test(loaders_transfer, model_transfer, criterion_transfer, use_cuda)
Test Loss: 0.518747
Test Accuracy: 86% (723/836)
```

# 1.1.17 (IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

```
In [49]: ### TODO: Write a function that takes a path to an image as input
         ### and returns the dog breed that is predicted by the model.
         # list of class names by index, i.e. a name can be accessed like class_names[0]
         class_names = [item[4:].replace("_", " ") for item in image_datasets['train'].classes]
         def predict_breed_transfer(img_path, max_size=400, shape = None):
             # load the image and return the predicted breed
             if "http" in img_path:
                 response = requests.get(img_path)
                 image = Image.open(BytesIO(response.content)).convert('RGB')
             else:
                 image = Image.open(img_path).convert('RGB')
             # large images will slow down processing
             if max(image.size) > max_size:
                 size = max_size
             else:
                 size = max(image.size)
             if shape is not None:
                 size = shape
             in_transform = transforms.Compose([transforms.Resize(size),
                                                  transforms.CenterCrop((224,224)),
                                                   transforms.ToTensor(),
```



Sample Human Output

```
transforms.Normalize(mean=[0.485, 0.456, 0.406
std=[0.229, 0.224, 0.225]
```

```
# discard the transparent, alpha channel (that's the :3) and add the batch dimension
image = in_transform(image).unsqueeze(0)

if torch.cuda.is_available():
    image = image.cuda()

# get sample outputs
pred = model_transfer(image)

_, preds_tensor = torch.max(pred, 1)
pred = np.squeeze(preds_tensor.numpy()) if not use_cuda else np.squeeze(preds_tensor.numpy())
return class_names[pred]
```

## Step 5: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then, - if a **dog** is detected in the image, return the predicted breed. - if a **human** is detected in the image, return the resembling dog breed. - if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face\_detector and human\_detector functions developed above. You are required to use your CNN from Step 4 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!

# 1.1.18 (IMPLEMENTATION) Write your Algorithm

```
image = Image.open(img_path)
## handle cases for a human face, dog, and neither
if dog_detector(img_path):
    dog_pred = predict_breed_transfer(img_path)
    plt.imshow(image)
    print(f"Look like there dog : {dog_pred}\n")

elif (face_detector(img_path)):
    face_pred = predict_breed_transfer(img_path)
    plt.imshow(image)
    print(f"Look like there is human face : {face_pred}\n")
else:
    print("No human or dog found")

plt.show()
```

## Step 6: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that *you* look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

# 1.1.19 (IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

**Question 6:** Is the output better than you expected:)? Or worse:(? Provide at least three possible points of improvement for your algorithm.

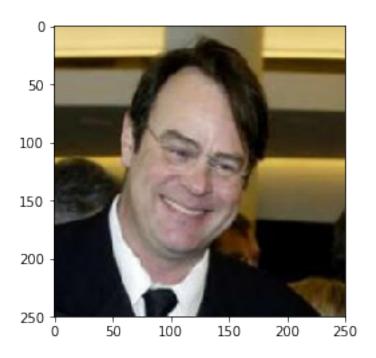
I'm very impressed for the result. I was wondering if could get better result.

Some suggestions to improve my algorithm.

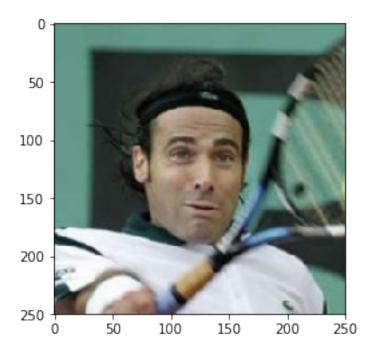
We can try a set of learning rate and selected automatically the learning rate with optimal accuracy

We only use the parameters on the last layers to train our model, we could change and train on overall parameters and try to compare the result

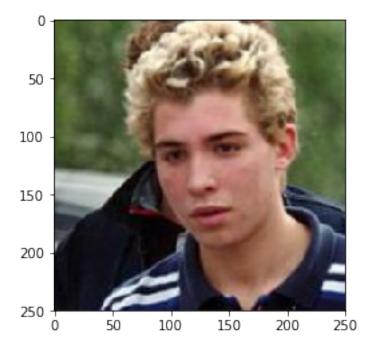
We can also try to augment the data.



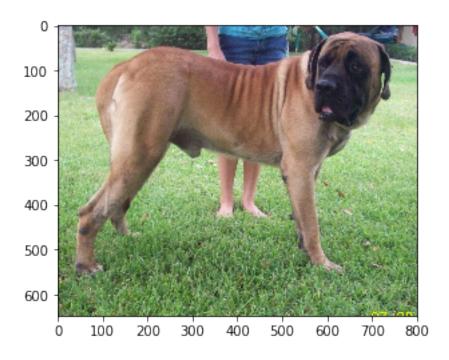
Look like there is human face : Dachshund



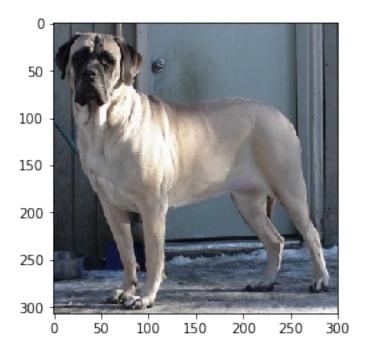
Look like there is human face : Otterhound



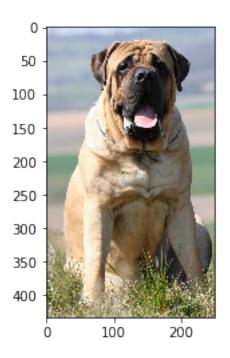
Look like there dog : Mastiff



Look like there dog : Mastiff



Look like there dog : Mastiff



In [ ]: