

# Ultrasonic Anemometer

## Seminar Presentation

### Group 10

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# 1. Project Overview & Specifications

# Project Overview

## Project Background

- used to measure wind direction and speed using ultrasonic sound waves
- lack of moving parts makes them appropriate for long-term use in harsh marine environments

## Problem Statement

The Ultrasonic Anemometer team has been tasked with the design and testing of an ultrasonic anemometer for Dr. Peter Gregson of Visimetrix Inc. that will significantly decrease the cost for personal use.



# Project Requirements & Specifications

## Design Criteria

- **Wind Speed:** 0 to 30 m/s with an accuracy & precision of  $\pm 5\%$
- **Wind Direction:** Accuracy of  $\pm 3^\circ$  over designed operating range
- **Output Rate:** 2 Hz.

## Design Constraints

- **Serial Communication:** The device must interface using common marine protocols, including NMEA0183.
- **Device Cost:** The material cost of the device must be below \$100 per single unit.

## Performance Goals

- **Ingress Protection Rating:** IP67
- **Built in diagnostics**

## 2. Project Objectives & Deliverables

# Short Term Project Goals & Deliverables

## 1. Acceptance Test Plan

- Test Plan to ensure the proof-of-concept meets design requirements
- Documentation of the testing procedure, equipment, and results

## 2. Theory of Operation

- Short description of the theory behind the design decisions of the prototype

## 3. Data Processing Algorithm

- Development of a DSP algorithm for the required calculations and generation of system outputs

## 4. System Hardware Architecture

- Description of the hardware components required to perform analog amplification, filtering, and processing

# Long Term Project Goals & Deliverables

## 1. Proof-of-Concept Implementation

- A prototype that will measure wind speed along a single axis
- encompass a combination of concepts used to achieve the required functionality

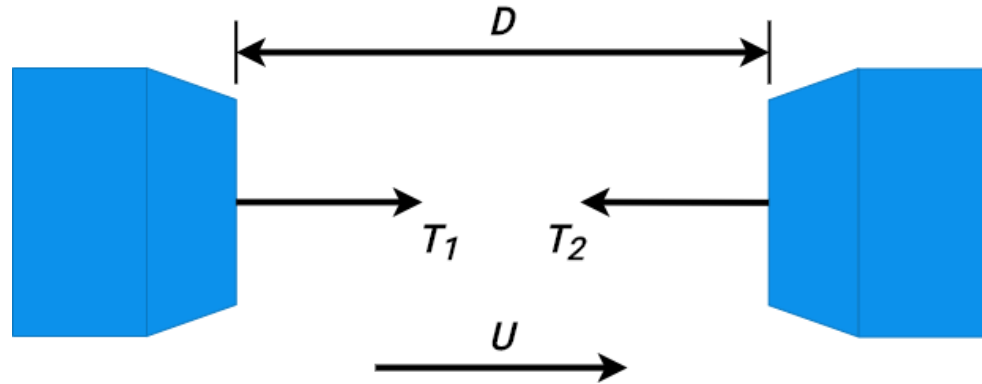
## 2. Project Report

- an outline of the theory of operation
- a description of the data processing algorithm and system hardware architecture
- summary of the proof-of-concept implementation and acceptance test plan
- provide an analysis of the performance of the device

### 3. System Design & Verification



# Theory of Operation



$$T_1 = \frac{D}{(v + U)}$$

$$T_2 = \frac{D}{(v - U)}$$

$$U = \frac{D}{2} \left( \frac{1}{T_1} - \frac{1}{T_2} \right)$$

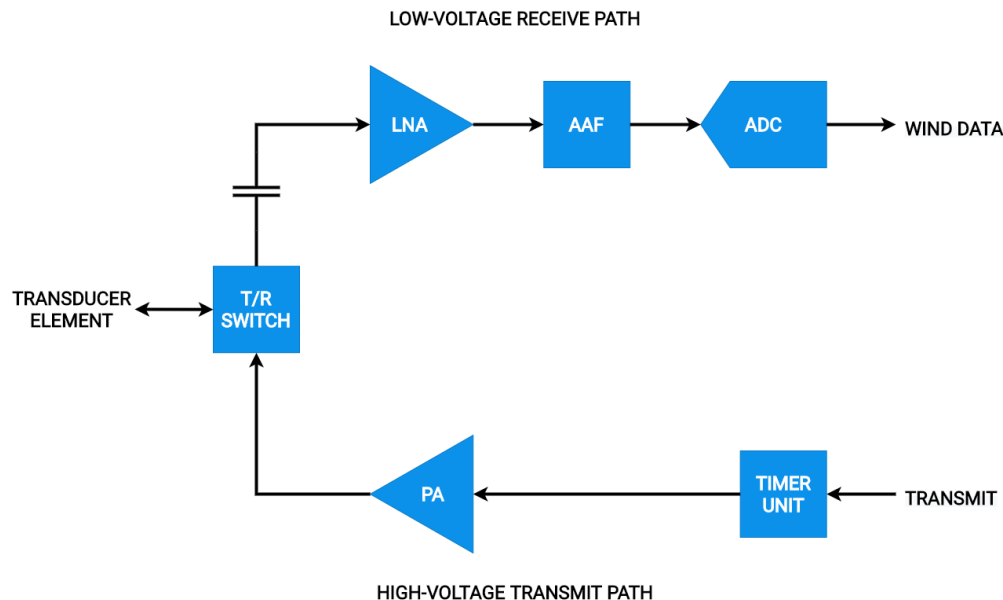
# Hardware Block Diagram

## High-Voltage Transmit Path

- Timer Unit on MCU generates low-voltage pulses
- High-voltage Power Amplifier (PA) excites the transducer element

## Low Voltage Receive Path

- Transmit Receive (T/R) Switch protects LNA input from high-voltage transmit signal
- Low-Noise Amplifier (LNA) provides fixed gain without significantly degrading SNR
- Anti-Aliasing Filter (AAF) restricts the bandwidth of the received signal to prevent aliasing
- Analog to Digital Converter (ADC) samples received signal



# High-Voltage Transmit Path Design

## Design Requirements

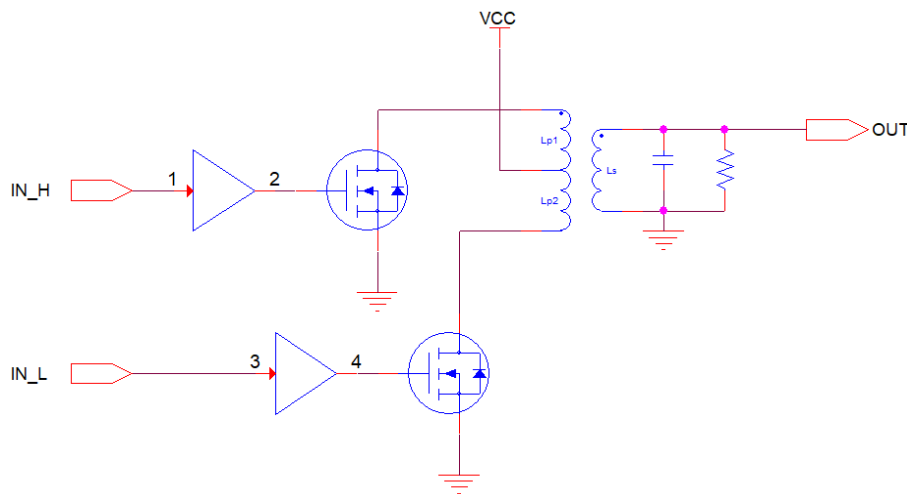
- Increase the voltage and power of the 40 kHz square wave driving signal generated by the microcontroller
- Obtain a sufficient SNR across the channel
- Minimize power dissipation

## Design Decisions

- **Topology:** Center-Tap Transformer driven in push-pull configuration using two complementary low-side power MOSFETS
- **Driving Voltage:** 100 Vpp, resulting in a received voltage level of 30 mVpp

## Design Verification

- Apply two 3.3 V square waves to input of power amplifier and probe output using oscilloscope



# Low-Voltage Receive Path Design

## Design Requirements

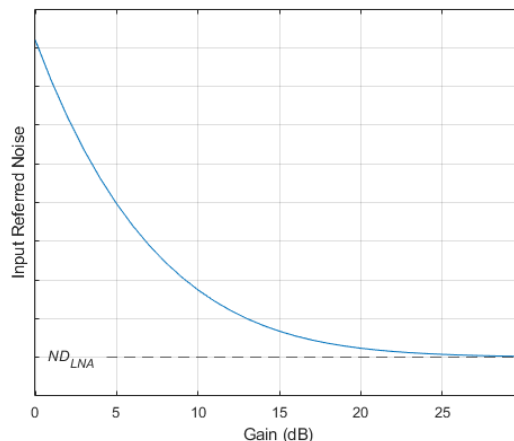
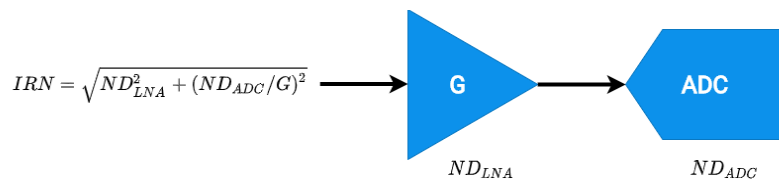
- Amplify the received signal without significantly degrading its SNR
- Reduce effect of quantization noise from ADC
- Restrict bandwidth of received signal to prevent aliasing within the band of interest

## Design Decisions

- **Topology:** Monolithic LNA based on LMP7731 low-noise operational amplifier with active low-pass anti-aliasing filter
- **Passband Gain:** Select such that input referred noise is dominated by noise density of LNA

## Design Verification

- Use oscilloscope or spectrum analyzer to measure frequency response and noise density



# Software Block Diagram

## Control Layer

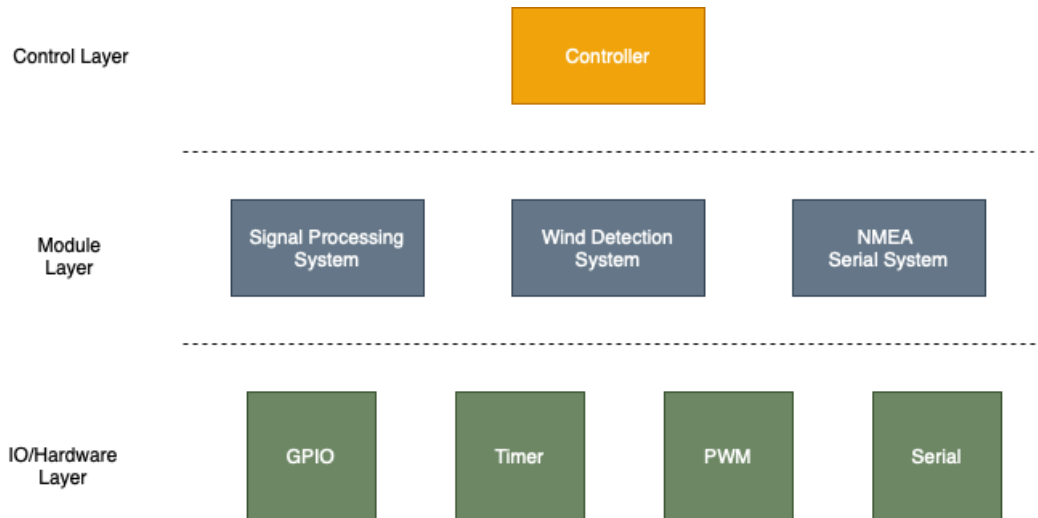
- Manages the state of the device and the tasks that are being performed

## Module Layer

- Contains modules that will control the ultrasonic transducers for the device

## IO/Hardware layer

- Low-level drivers that manage the hardware for the various sensors and amplifiers in use



# Digital Signal Processing Design

## Design Requirements

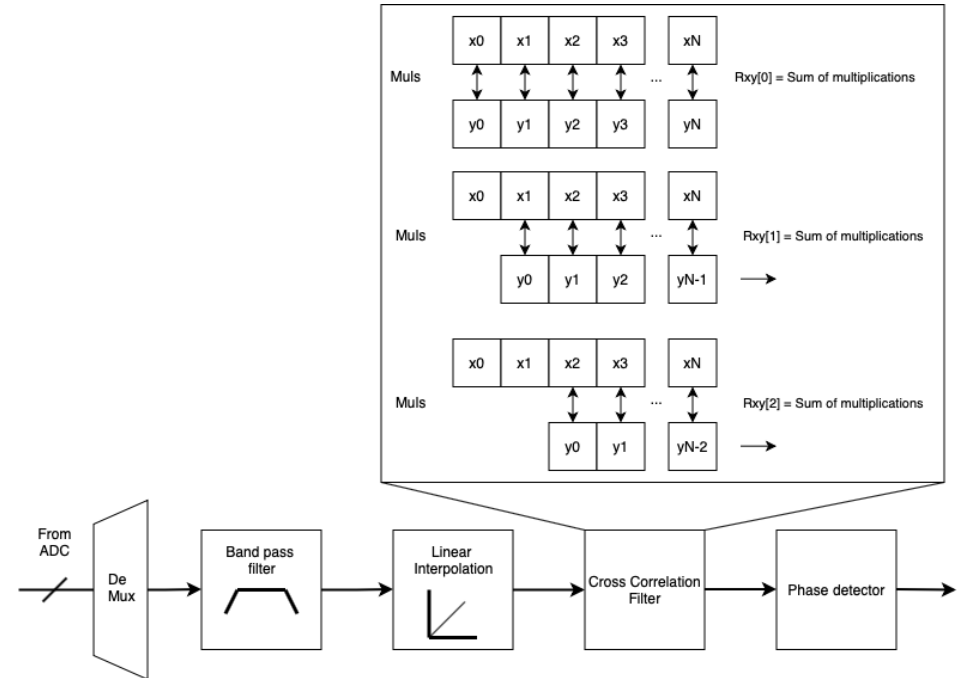
- Achieve a 2 Hz output rate
- Wind direction accuracy of  $\pm 3^\circ$  in various wind condition
- Margin of  $\pm 5\%$  of apparent wind speed

## Design Decisions

- **Wind Measurement Algorithm:** Cross correlation provides superior accuracy to ToF for measurement of time shifts.
- Signal must be sampled at high speed

## Design Verification

- Two 40 KHz 1 Vpp sinusoidal signals with different phases will be generated and will be input to the signal processing system.
- The output signal from the signal processing system will be compared to an oscilloscope.



## 4. Preliminary Results

# Power Amplifier

## Verification Criteria

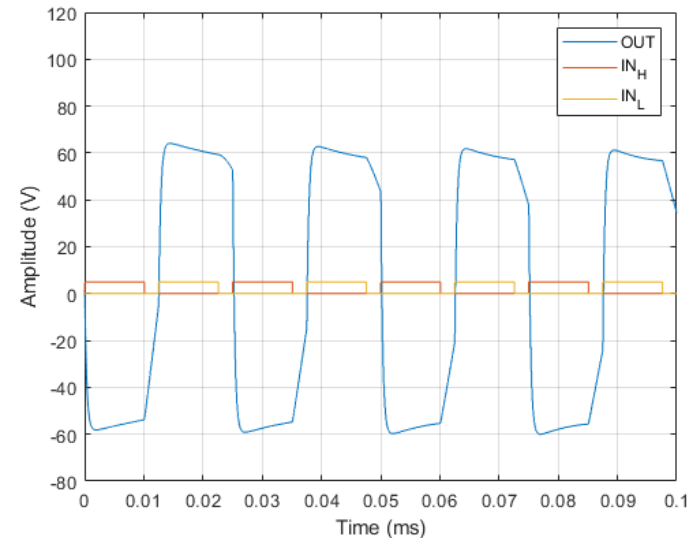
- Amplify two 3.3 Vpp 40.2 kHz square wave signals to achieve approximately 100 Vpp across transducer

## Verification Method

- Perform a transient analysis in PSpice using the simulation schematic of the power amplifier
- Connect the output of the power amplifier to the lumped element model of the ultrasonic transducer element

## Results

- The output signal from the power amplifier satisfies the design requirements





# Digital Signal Processing

## Verification Criteria

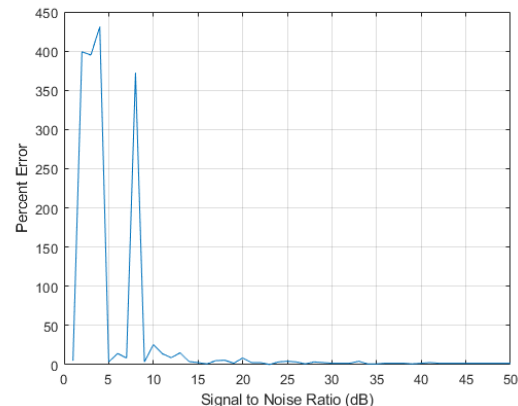
- Correctly recreated signal from simulated sampling and resampling of two signals at a specific SNR

## Verification Method

- Determine % error of calculated vs actual time shifts at various SNR values

## Results

- SNR value  $> 15$  will provide us the necessary resolution to accurately compute the shift in signals within the margin of error



# 5. Design Integration Testing

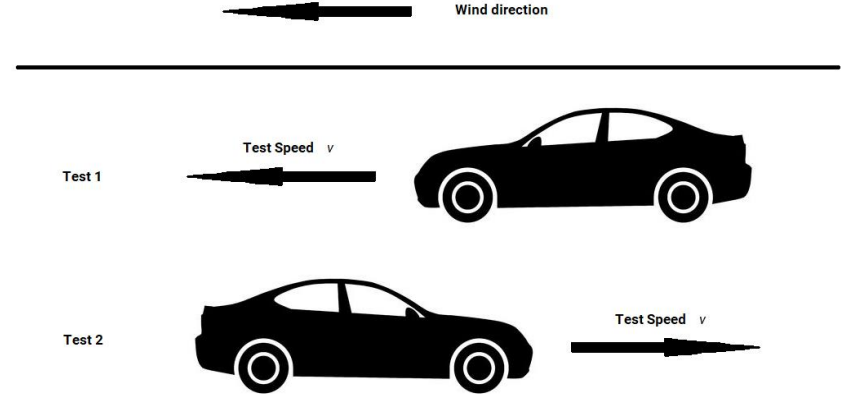
# Prototype Testing Plan

## High Speed Wind Test

- tested in a controlled environment while being exposed to a single axis of wind
- average of each trial of two tests will allow for the calibration of the signal response relative to actual wind speed
- wind angle can also be controlled

## Low Speed Wind Tunnel Test

- controlled low speed test to verify accuracy and repeatability of results

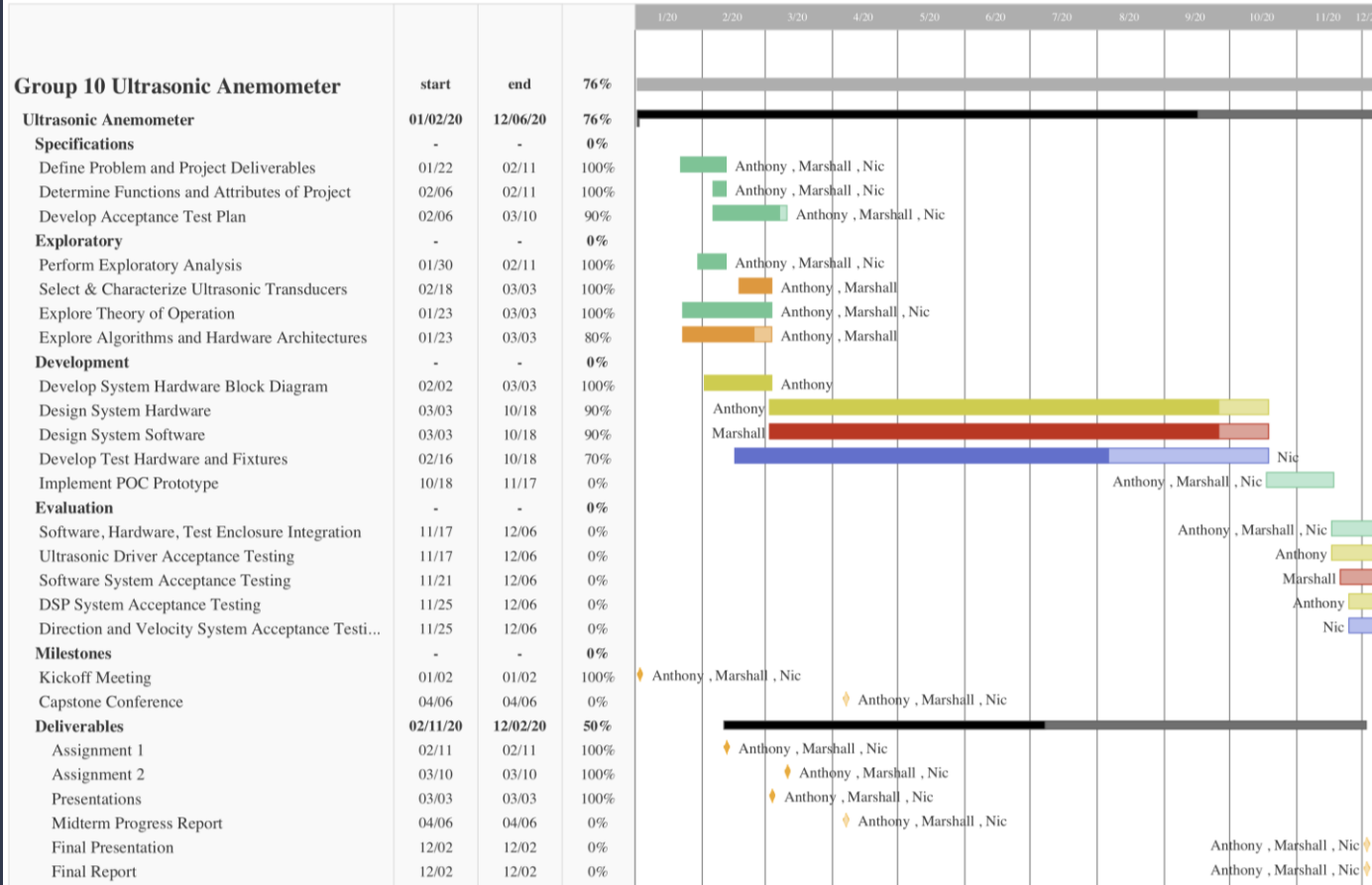


# 6. Project Management

# Budget

Expense	Cost
Ultrasonic Transducers	\$25
Low-Noise Amplifier & Anti-Aliasing Filter	\$50
Power Amplifier	\$100
Microcontroller	\$40
Test Fixtures & Enclosures	\$100
Total Cost	\$315
Initial Budget	\$500
Expected Remaining Budget	\$185

# Project Scheduling



# Questions?