Control-flow Analysis

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Agenda

- Control-flow graph
- Control-flow analysis

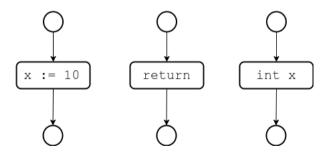
Reference: Chapter 3 of Principles of Program Analysis by Nielson, Nielson, Hankin

Control-flow Graphs

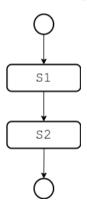
- A control-flow graph (CFG) is a direct graph where nodes corresponds to basic blocks (sequence of simple statements) and edges represent possible control flow
- The CFG provides a graphical representation of the possible runtime control-flow paths
- Typically, the statements inside basic blocks are represented with another IR
- CGF is used to perform Dataflow analysis and program transformation

- We assume that each CFG has single entry node
- For the time being, we consider a single procedure at the time and that basic blocks are made of single statements
- The construction is defined inductively on the structure of the statements

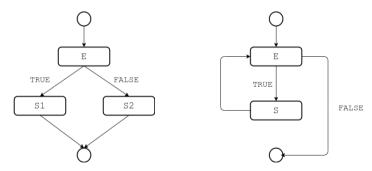
For simple statements, e.g., assignment, return statement, declaration, the CFG looks like



For sequential composition S_1 ; S_2 we build the CFG for S_1 and S_2 inductively, remove the exit node of S_1 and the entry node of S_2 and glue the statements together

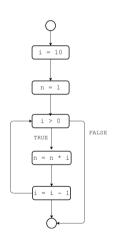


Similarly, for other control flow constructs (we label branches with true and false)



CFG Construction: Example

```
i = 10;
n = 1;
while(i > 0) {
   n = n * i;
   i = i - 1;
}
```



CFG Construction (intraprocedural)

$$x \in Id$$
 $e \in Exp$ $\ell \in Lab$

 $init(if [e]^{\ell} then S_1 else S_2) = \ell$

$$S ::= [x := e]^{\ell} \mid [skip]^{\ell} \mid S_1; S_2 \mid$$
 while $[e]^{\ell}$ do $S \mid$ if $[e]^{\ell}$ then S_1 else S_2

$$init([x := e]^{\ell}) = \ell$$
 $final([x := e]^{\ell}) = \ell$ $init([skip]^{\ell}) = \ell$ $final([skip]^{\ell}) = \ell$ $final([skip]^{\ell}) = \ell$ $final(S_1; S_2) = final(S_2)$ $final(Mile [e]^{\ell} \operatorname{do} S) = \ell$ $final(Mile [e]^{\ell} \operatorname{do} S) = \ell$

final(if $[e]^{\ell}$ then S_1 else S_2) = final(S_1) \cup final(S_2)

CFG Construction

$$s := [x := e]^{\ell} \mid [skip]^{\ell} \mid S_1; S_2 \mid \mathbf{while} \ [e]^{\ell} \mathbf{do} \ S \mid \mathbf{if} \ [e]^{\ell} \mathbf{then} \ S_1 \mathbf{else} \ S_2$$

$$flow([x := e]^{\ell}) = \emptyset$$

$$flow([skip]^{\ell}) = \emptyset$$

$$flow(S_1; S_2) = flow(S_1) \cup flow(S_2) \cup \{(\ell, init(S_2)), | \ell \in final(S_1)\}$$

$$flow(\mathbf{while} \ [e]^{\ell} \mathbf{do} \ S) = flow(S) \cup \{(\ell, init(S))\}$$

$$flow(\mathbf{if} \ [e]^{\ell} \mathbf{then} \ S_1 \mathbf{else} \ S_2) = flow(S_1) \cup flow(S_2) \cup \{(\ell, init(S_1)), (\ell, init(S_2))\}$$

CFG Construction

$$x \in Id \quad e \in Exp \quad \ell \in Lab$$

$$S ::= [x := e]^{\ell} \mid [skip]^{\ell} \mid S_1; S_2 \mid \mathbf{while} \ [e]^{\ell} \mathbf{do} \ S \mid \mathbf{if} \ [e]^{\ell} \mathbf{then} \ S_1 \mathbf{else} \ S_2$$

$$blocks([x := e]^{\ell}) = \{[x := e]^{\ell}\}$$

$$blocks([skip]^{\ell}) = \{[skip]^{\ell}\}$$

$$blocks(S_1; S_2) = blocks(S_1) \cup blocks(S_2)$$

$$blocks(\mathbf{while} \ [e]^{\ell} \mathbf{do} \ S) = blocks(S) \cup \{[e]^{\ell}\}$$

$$blocks(\mathbf{if} \ [e]^{\ell} \mathbf{then} \ S_1 \mathbf{else} \ S_2) = blocks(S_1) \cup blocks(S_2) \cup \{[e]^{\ell}\}$$

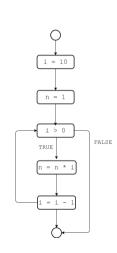
CFG Construction

$$x \in Id$$
 $e \in Exp$ $\ell \in Lab$
$$S ::= [x := e]^{\ell} \mid [skip]^{\ell} \mid S_1; S_2 \mid \mathbf{while} \ [e]^{\ell} \mathbf{do} \ S \mid \mathbf{if} \ [e]^{\ell} \mathbf{then} \ S_1 \mathbf{else} \ S_2$$

The control-flow graph of a statement S has the blocks(S) as nodes and flow(S) as arcs

CFG Construction: Example

```
S = [i = 10]^{1}:
       [n = 1]^2;
       while ([i > 0]^3) {
            [n = n * i]^4;
            [i = i - 1]^5;
init(S) = 1
final(S) = \{3\}
flow(S) = \{(1,2), (2,3), (3,4)(4,5)\}
```



CFG Construction (interprocedural)

When we consider procedures

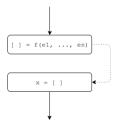
- Build the CFG for all functions bodies
- Glue them together to reflect the different function calls

CFG Construction: calling functions

In a CFG a function call is represented using two nodes:

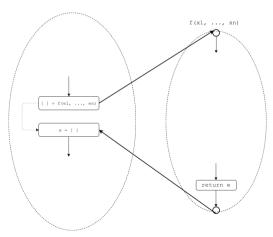
- ${f 1.}$ a call-node representing the connection from the caller to the entry point of the callee
- 2. a after-call node where the execution may resume after the termination of the callee

$$x = f(e_1, \ldots, e_n);$$



CFG Construction: interprocedural

Glue together the caller and the callee



Control-flow analysis (CFA)

Building the CFG of a program is not easy in real languages:

- First-order functions (functional languages)
- Function pointers/procedures as parameters (imperative languages)
- Dynamic dispatch (object-oriented languages)

The actual target of a call is resolved at run-time

Solution: a static analysis to over-approximate the interprocedural control flow of the program

Dynamic dispatch problem

Consider the following snippet of code

```
let f x = x 1
and g y = y + 2
and h z = z + 3;;
(f g) + (f h);;
```

the function $\tt f$ will transfer the code to its formal parameter $\tt x$: the inter-procedural control flow depends on the values $\tt x$ denotes

The fun language

$e \in Exp ::= t^\ell$	annotated expressions		
$t \in \mathit{Term} ::= c$	constant literal		
X	identifier		
\mid if e_1 then e_1 else e_2	conditionals		
$ e_1 \diamond e_2$	$\diamond \in \{+,-,*,\ldots\}$ primitive operators		
$ \mathbf{let} x = e_1 \mathbf{in} e_2$	declarations		
$ $ fun $x \rightarrow e$	lambda abstraction		
$ e_1 e_2 $	function application		

The analysis of fun

The goal

- Determine for each sub-expression e a set of function F, e may evaluates to at run-time
- Determine where the flow of control may be transferred when *e* is a function application

Example (Consider the OCaml expression)

```
(if e then (( * ) 2) else ((+) 1)) 10
```

depending on the value of e either ((*) 2) or ((+) 1) is applied

Example

Consider the expression

$$((\mathbf{fun} \, x \to x^1)^2 (\mathbf{fun} \, y \to y^3)^4)^5$$

We want to statically compute that

- x is bound to fun $y \to y^3$
- the sub-expression at label 1 evaluates to **fun** $y \rightarrow y^3$
- the overall expression evaluates to to **fun** $y \rightarrow y^3$
- y is never bound to a value

CFA via Flow Logic

Flow Logic is a declarative approach to program analysis that separates the specification from the actual computation.

specification we describe when the analysis results (estimates) are acceptable: the specification consists of a set of clauses defining an acceptability relation

computation from the specification we derive a constraint satisfaction problem: solving the constraints corresponds to compute the analysis.

Our plan for CFA

We define our CFA in three steps:

- 1. We define an acceptability relation over the syntax of FUN (syntax-directed specification)
- 2. We turn the syntax-directed specification into an algorithm for computing a finite set of constraints
- **3.** We compute the least solution of the constraints

Abstract domains

The result of a CFA analysis is a pair $(\hat{C}, \hat{\rho})$:

- ullet $\hat{\mathcal{C}}$ is the abstract cache associating abstract values with each labelled program point
- \bullet $\hat{\rho}$ is the abstract environment associating abstract values with each variable

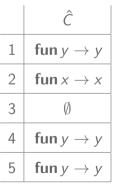
An abstract value is a set of functions, i.e., terms of the form $\operatorname{fun} x \to e$

We assume that all variables and labels are distinct (we can ensure that while building the AST of the program)

Example of a valid estimate

Consider the expression

$$((\mathbf{fun} \, x \to x^1)^2 (\mathbf{fun} \, y \to y^3)^4)^5$$



	$\hat{ ho}$			
X	$\mathbf{fun} y \to y$			
У	Ø			

Acceptability relation

The idea: assume to guess a pair $(\hat{C},\hat{\rho})$ and determine whether or not this guess is an

acceptable CFA for the program at hand

$$(\hat{C},\hat{\rho}) \vDash e$$

Note

Intuitively, the clauses of our syntax directed specification are a sort of an explicit formulation of Dataflow equations: our constraints have the form $lhs \subseteq rhs$ and we want to compute the least solution

CFA Clauses (1)

$$\begin{split} (\hat{C},\hat{\rho}) &\vDash c^{\ell} \iff true \\ (\hat{C},\hat{\rho}) &\vDash x^{\ell} \iff \hat{\rho}(x) \subseteq \hat{C}(\ell) \\ (\hat{C},\hat{\rho}) &\vDash (\mathbf{fun}\,x \to e)^{\ell} \iff \{\mathbf{fun}\,x \to e\} \subseteq \hat{C}(\ell) \land (\hat{C},\hat{\rho}) \vDash e \\ (\hat{C},\hat{\rho}) &\vDash (e_{1} \diamond e_{2})^{\ell} \iff (\hat{C},\hat{\rho}) \vDash e_{1} \land (\hat{C},\hat{\rho}) \vDash e_{2} \\ (\hat{C},\hat{\rho}) &\vDash (\mathbf{let}\,x = t_{1}^{\ell_{1}}\,\mathbf{in}\,t_{2}^{\ell_{2}})^{\ell} \iff (\hat{C},\hat{\rho}) \vDash t_{1}^{\ell_{1}} \land (\hat{C},\hat{\rho}) \vDash t_{2}^{\ell_{2}} \land \\ \hat{C}(\ell_{1}) \subseteq \hat{\rho}(x) \land \hat{C}(\ell_{2}) \subseteq \hat{C}(\ell) \end{split}$$

CFA Clauses (2)

$$(\hat{C},\hat{\rho})\vDash(\mathbf{if}\ t_0^{\ell_0}\ \mathbf{then}\ t_1^{\ell_1}\ \mathbf{else}\ t_2^{\ell_2})^{\ell}\iff(\hat{C},\hat{\rho})\vDash t_0^{\ell_0}\land(\hat{C},\hat{\rho})\vDash t_1^{\ell_1}\land(\hat{C},\hat{\rho})\vDash t_2^{\ell_2}\land\\ \hat{C}(\ell_1)\subseteq\hat{C}(\ell)\land\hat{C}(\ell_2)\subseteq\hat{C}(\ell)\\ (\hat{C},\hat{\rho})\vDash(t_1^{\ell_1}\ t_2^{\ell_2})^{\ell}\iff(\hat{C},\hat{\rho})\vDash t_1^{\ell_1}\land(\hat{C},\hat{\rho})\vDash t_2^{\ell_2}\land\\ (\forall (\mathbf{fun}\ x\to t_0^{\ell_0})\in\hat{C}(\ell_1):\hat{C}(\ell_2)\subseteq\hat{\rho}(x)\land\\ \hat{C}(\ell_0)\subseteq\hat{C}(\ell))$$

Example: the requirements of valid estimates (1)

Consider the expression ((fun $x \to x^1$)²(fun $y \to y^3$)⁴)⁵, the CFA clauses are

$$(\hat{C},\hat{\rho}) \vDash ((\operatorname{fun} x \to x^1)^2 (\operatorname{fun} y \to y^3)^4)^5$$
 iff
$$(\hat{C},\hat{\rho}) \vDash (\operatorname{fun} x \to x^1)^2 \wedge (\hat{C},\hat{\rho}) \vDash (\operatorname{fun} y \to y^3)^4 \wedge (\nabla (\operatorname{fun} z \to t_0^{\ell_0}) \in \hat{C}(2) : \hat{C}(4) \subseteq \rho(z) \wedge \hat{C}(\ell_0) \subseteq \hat{C}(5))$$
 if

Example: the requirements of valid estimates (2)

$$\{\operatorname{fun} x \to x\} \subseteq \hat{C}(2) \wedge (\hat{C}, \hat{\rho}) \vDash x^{1} \wedge \{\operatorname{fun} y \to y\} \subseteq \hat{C}(4) \wedge (\hat{C}, \hat{\rho}) \vDash y^{3} \wedge$$

$$\left(\forall (\operatorname{fun} z \to t_{0}^{\ell_{0}}) \in \hat{C}(\ell_{2}) : \hat{C}(\ell_{4}) \subseteq \rho(z) \wedge \hat{C}(\ell_{0}) \subseteq \hat{C}(5)\right) \quad \text{iff}$$

$$\{\operatorname{fun} x \to x\} \subseteq \hat{C}(2) \wedge \hat{\rho}(x) \subseteq \hat{C}(1) \wedge \{\operatorname{fun} y \to y\} \subseteq \hat{C}(4) \wedge \rho(y) \subseteq \hat{C}(3) \wedge$$

$$\left(\forall (\operatorname{fun} z \to t_{0}^{\ell_{0}}) \in \hat{C}(2) : \hat{C}(4) \subseteq \rho(z) \wedge \hat{C}(\ell_{0}) \subseteq \hat{C}(5)\right)$$

Example: the requirements of valid estimates (3)

The requirements a valid estimate must satisfy

$$\{\operatorname{fun} x \to x\} \subseteq \hat{C}(2) \land \hat{\rho}(x) \subseteq \hat{C}(1) \land \{\operatorname{fun} y \to y\} \subseteq \hat{C}(4) \land \rho(y) \subseteq \hat{C}(3) \land (\forall (\operatorname{fun} z \to t_0^{\ell_0}) \in \hat{C}(2) : \hat{C}(4) \subseteq \rho(z) \land \hat{C}(\ell_0) \subseteq \hat{C}(5)\}$$

Our previous guess

Ĉ	1	2	3	4	5
	$\mathbf{fun}y\to y$	$fun x \to x$	Ø	$\mathbf{fun} y \to y$	$\mathbf{fun}y\to y$

$\hat{ ho}$	X	У
	$\mathbf{fun} y \to y$	Ø

Constraints

- r(x) is a constraint variable denoting the entry of the abstract environment for x
- $C(\ell)$ is a constraint variable denoting the entry of the abstract label for ℓ
- t is a token denoting expression of the form $\operatorname{fun} x \to e$
- $\{t\} \subseteq \mathit{rhs'} \implies \mathit{lhs} \subseteq \mathit{rhs} \text{ should be read as } (\{t\} \subseteq \mathit{rhs'} \implies \mathit{lhs}) \subseteq \mathit{rhs}$

Constraint generation: C[e] (1)

The function $\mathcal{C}[\![_]\!]: \textit{Exp} \to \textit{Constr}$ given an expression returns a set of constraints

$$C[\![c^\ell]\!] = \emptyset \qquad \qquad C[\![x^\ell]\!] = \{r(x) \subseteq C(\ell)\}$$

$$\mathcal{C}[\![(\operatorname{fun} x \to e)^{\ell}]\!] = \{\{\operatorname{fun} x \to e\} \subseteq \mathcal{C}(\ell)\} \cup \mathcal{C}[\![e]\!]$$

$$\mathcal{C}[\![(\text{if }t_0^{\ell_0}\text{ then }t_1^{\ell_1}\text{ else }t_2^{\ell_2})^\ell]\!] = \mathcal{C}[\![t_0^{\ell_0}]\!] \cup \mathcal{C}[\![t_1^{\ell_1}]\!] \cup \mathcal{C}[\![t_2^{\ell_2}]\!] \cup \{\mathcal{C}(\ell_1) \subseteq \mathcal{C}(\ell), \ \mathcal{C}(\ell_2) \subseteq \mathcal{C}(\ell)\}$$

$$\mathcal{C}[\![(\mathbf{let} \, \mathbf{x} = t_1^{\ell_1} \, \mathbf{in} \, t_2^{\ell_2})^{\ell}]\!] = \mathcal{C}[\![t_1^{\ell_1}]\!] \cup \mathcal{C}[\![t_2^{\ell_2}]\!] \cup \{\mathcal{C}(\ell_1) \subseteq r(\mathbf{x}), \mathcal{C}(\ell_2) \subseteq \mathcal{C}(\ell)\}$$

Constraint generation: C[e] (2)

The function $\mathcal{C}[\![_]\!]: \mathit{Exp} \to \mathit{Constr}$ given an expression returns a set of constraints

$$\begin{split} \mathcal{C}\llbracket(e_1\diamond e_2)^\ell\rrbracket &= \mathcal{C}\llbracket e_1\rrbracket \cup \mathcal{C}\llbracket e_2\rrbracket \\ \mathcal{C}\llbracket(t_1^{\ell_1}\ t_2^{\ell_2})^\ell\rrbracket &= \mathcal{C}\llbracket t_1^{\ell_1}\rrbracket \cup \mathcal{C}\llbracket t_2^{\ell_2}\rrbracket \cup \\ &\{t\} \subseteq C(\ell_1) \implies C(\ell_2) \subseteq r(x), \\ &\{t\} \subseteq C(\ell_1) \implies C(\ell_0) \subseteq C(\ell) \mid \\ &t = (\operatorname{\mathbf{fun}} x \to t_0^{\ell_0}) \in \Lambda^* \} \end{split}$$

where Λ^* is the set of function abstractions occurring in the program to analyze

Example of constraints

Consider the expression

$$e_{\star} = ((\operatorname{fun} x \to x^{1})^{2} (\operatorname{fun} y \to y^{3})^{4})^{5}$$

```
\mathcal{C}\llbracket e_{\star} \rrbracket = \{
\{ \operatorname{fun} x \to x^{1} \} \subseteq C(2), \ r(x) \subseteq C(1), \ \{ \operatorname{fun} y \to y^{3} \} \subseteq C(4), r(y) \subseteq C(3),
\{ \operatorname{fun} x \to x^{1} \} \subseteq C(2) \Rightarrow C(4) \subseteq r(x), \{ \operatorname{fun} x \to x^{1} \} \subseteq C(2) \Rightarrow C(1) \subseteq C(5),
\{ \operatorname{fun} y \to y^{3} \} \subseteq C(2) \Rightarrow C(4) \subseteq r(y), \{ \operatorname{fun} y \to y^{3} \} \subseteq C(2) \Rightarrow C(3) \subseteq C(5) \}
\}
```

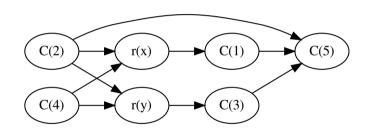
Solving the Constraints

Our constraint solver is based on a graph formulation of the constraints:

- There is a node for each variable $C(\ell)$ and r(x) occurring in the constraints
- Edges are built from the constraints and decorated with them:
 - a constraint $p_1 \subseteq p_2$ results in an edge from p_1 to p_2
 - a constraint $\{t\}\subseteq p\implies p_1\subseteq p_2$ results in an edge from p_1 to p_2 and from p to p_2
- For each node p we have a data field D[p] containing the tokens associated to that node, initially is given by $D[p] = \{t \mid \{t\} \subseteq p\}$

The idea of the algorithm is to propagate the information from data field to another according to the constraints

Example of Graph representation



Data field:

$$D[C(2)] = \{ \text{ fun } x \to x^1 \}, \ D[C(4)] = \{ \text{ fun } y \to y^3 \}, \ D[q] = \emptyset \text{ for other nodes }$$

The Constraint Solver

Input: a set of constraint $\mathcal{C}\llbracket e_\star \rrbracket$

Output: the least solution to the constrains (an assignment to variables $C(\ell)$ and r(x))

Data structures:

- a graph with one node for each variable $C(\ell)$ and r(x) and zero, one or two edges for each constraints of $C[e_*]$
- an worklist W containing the nodes whose data field should be propagated
- a data field D storing for each node the current abstract value
- an array E storing for each node a list of the constraint that the node may affect

The Solver Pseudocode (1)

```
(* Step 1: Initialization *)
W := [];
for q in Vars do
   D[q] := [];
   E[q] := [];
done
```

The Solver Pseudocode (2)

done

```
(* Step 2: Build the graph *)

for cc in C[e_*] do

match cc with

| {t} \subseteq p -> add p {t}

| p_1 \subseteq p_2 -> E[p_1] := cc :: E[p_1]

| {t} \subseteq p \Longrightarrow p_1 \subseteq p_2 -> E[p_1] := cc :: E[p_1];

E[p] := cc :: E[p];
```

Example: Initialization of data structures

Node q	D[q]	E[q]
C(1)	Ø	$id_{x}\subseteq C(2)\Rightarrow C(1)\subseteq C(5)$
C(2)	id_{\times}	$id_x \subseteq C(2) \Rightarrow C(4) \subseteq r(x), id_x \subseteq C(2) \Rightarrow C(1) \subseteq C(5)$
		$id_y \subseteq C(2) \Rightarrow C(4) \subseteq r(y), id_y \subseteq C(2) \Rightarrow C(3) \subseteq C(5)$
C(3)	Ø	$id_y \subseteq C(2) \Rightarrow C(3) \subseteq C(5)$
C(4)	id_y	$id_x \subseteq C(2) \Rightarrow C(4) \subseteq r(x), id_y \subseteq C(2) \Rightarrow C(4) \subseteq r(y)$
C(5)	Ø	
r(x)	Ø	$r(x) \subseteq C(1)$
r(y)	Ø	$r(y)\subseteq C(3)$

The Solver Pseudocode (3)

```
(* Step 3: Iteration *)
while W != [] do
   g = extract front W
   for cc in E[a] do
      match oc with
       | p_1 \subseteq p_2 -> \text{ add } p_2 \text{ D}[p_1]
       \{t\} \subseteq p \implies p_1 \subseteq p_2 \rightarrow \mathbf{if} \ t \ \mathbf{in} \ \mathbb{E}[p] \ \mathbf{then} \ \mathrm{add} \ p_2 \ \mathbb{D}[p_1]
   done
done
```

The Solver Pseudocode (4)

```
(* Step 4: Recording the solution *)
for \ell do C(\ell) = D[\ell]; done
for x do r(x) = D[x]; done
(* auxiliarv procedure *)
let add q d =
  if \neg (d \subseteq D[q]) then
      D[q] = d \cup D[q];
      push W q
```

Example of execution

W	[C(4), C(2)]	[r(x), C(2)]	[C(1), C(2)]	[C(5), C(2)]	[C(2)]	[]
q	D[q]	D[q]	D[q]	D[q]	D[q]	D[q]
C(1)	Ø	Ø	id_y	id_y	id_y	id_y
C(2)	id_{\times}	id_{\times}	id_{\times}	id_{\times}	id_{\times}	id_{\times}
C(3)	Ø	Ø	Ø	Ø	Ø	Ø
C(4)	id_y	id_y	id_y	id_y	id_y	id_y
C(5)	Ø	Ø	Ø	id_y	id_y	id_y
r(x)	Ø	id_y	id_y	id_y	id_y	id_y
r(y)	Ø	Ø	Ø	Ø	Ø	Ø

Analysis improvements

- Our analysis is a pure CFA it only computes how the control flow may be transferred
 - Actually, the data affect the control: it is possible to extend the analysis we described to take into account also Dataflow information
 - We perform data and control flow analyses together
- Our CFA is *context insensitive* (0-CFA) because it does not distinguish between different calls to the same functions (poor precision, infeasible paths, ...)
 - It is possible to distinguish between different calls by introducing a notion of context
 (K-CFA), e.g., a call string of finite length
 - The complexity of the analysis increases

Conclusion

- Control-flow graph
- Control-flow analysis

Reference: Chapter 3 of Principles of Program Analysis by Nielson, Nielson, Hankin