



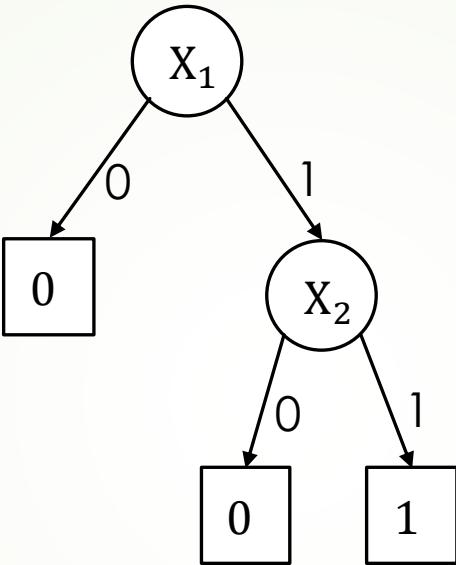
香港城市大學
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Classification: Rule-Based Classification

C5483 Data Warehousing and Data Mining

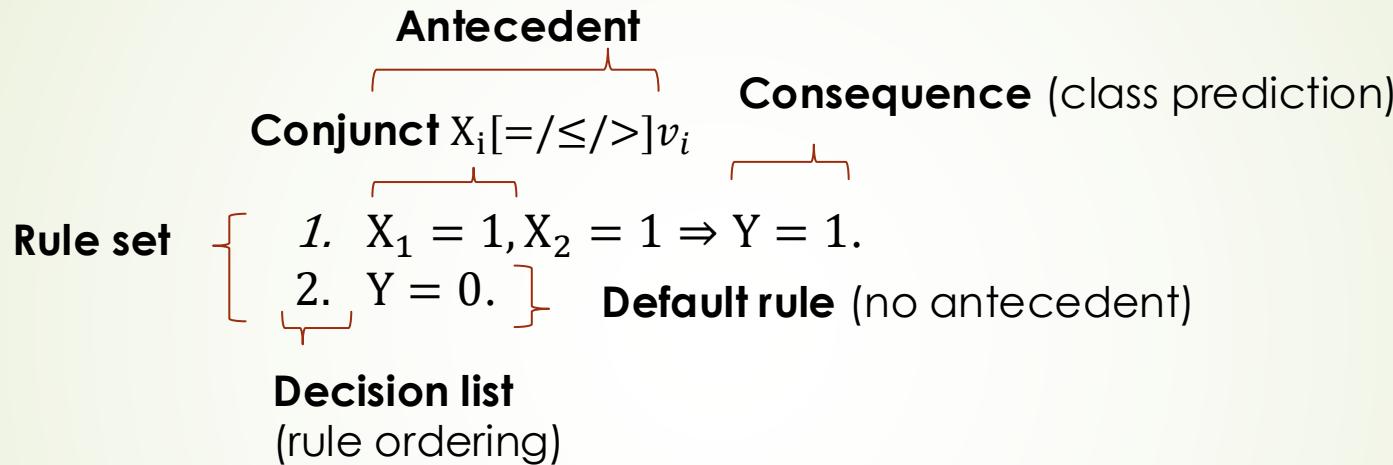
Motivation



- ▶ When is the decision equal to 1?
 1. If _____, then $Y = 1$.
 2. Else $Y = 0$.

Rule-based classification

Knowledge representation

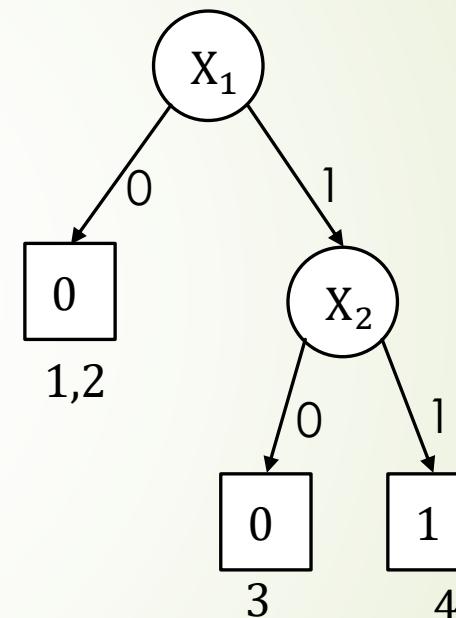


- ▶ Benefits representing knowledge by rules: (c.f. decision tree or NN)
 - ▶ M _____
 - ▶ I _____
- ▶ How to generate rules?

Generate rules from a decision tree

	X_1	X_2	Y
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1

1,2,3,4



- ▶ Each path from root to leaf corresponds to a rule:

1. $X_1 = \underline{\quad} \Rightarrow Y = 0$
2. $X_1 = \underline{\quad}, X_2 = \underline{\quad} \Rightarrow Y = 0$
3. $X_1 = \underline{\quad}, X_2 = \underline{\quad} \Rightarrow Y = 1$

- ▶ Does the ordering of these rules matter?
Yes/No because _____

Sequential covering

- ▶ **S**_____ -and- **c**_____ (c.f. divide-and-conquer)
 1. Learn a good rule.
 2. Remove covered instances and repeat 1 until all instances covered.
- ▶ How to learn a good rule?
- ▶ PART (partial tree) decision list
 1. Build a new decision tree (by C4.5) and extract the rule that maximizes **coverage**: fraction of instances satisfying the antecedent.
 2. Remove covered instances and repeat 1 until all instances are covered.

PART (partial tree) decision list

Example

1. Rule 1: _____

i. $X_1 = 0 \Rightarrow Y = 0$

(coverage: ____ %)

ii. $X_1 = 1, X_2 = 0 \Rightarrow Y = 0$

(coverage: ____ %)

iii. $X_1 = 1, X_2 = 1 \Rightarrow Y = 1$

(coverage: ____ %)

2. Rule 2: _____

i. $X_2 = 0 \Rightarrow Y = 0$

(coverage: ____ %)

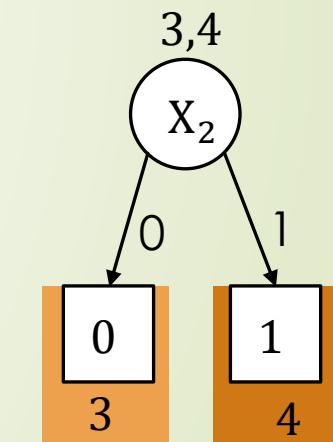
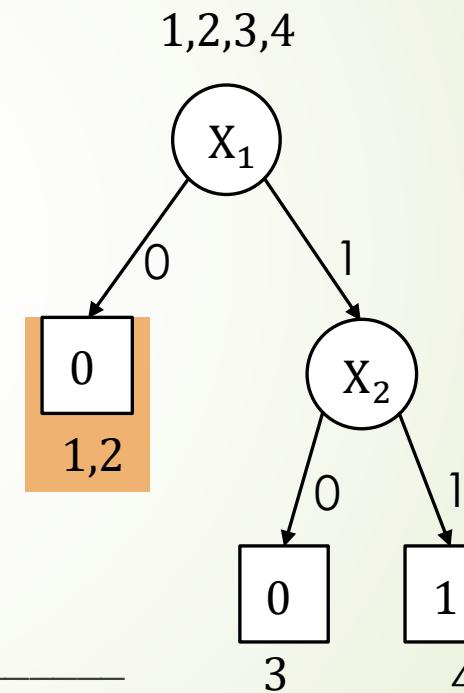
ii. $X_2 = 1 \Rightarrow Y = 1$

(coverage: ____ %)

3. Default rule: $Y = \underline{\hspace{2cm}}$

► Issue: [Time complexity] _____

	X_1	X_2	Y
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1



Generating rule directly

- Start with ZeroR, add conjuncts to improve **confidence**: fraction of correctly classified instances.

► Rule 1: $Y = 0$

► Confidence: _____ %

► Rule 1 (refined): $X_1 = 0 \Rightarrow Y = 0$

► Confidence: _____ %

- Repeatedly add new rules to cover remaining tuples

► Rule 2: $Y = 0$

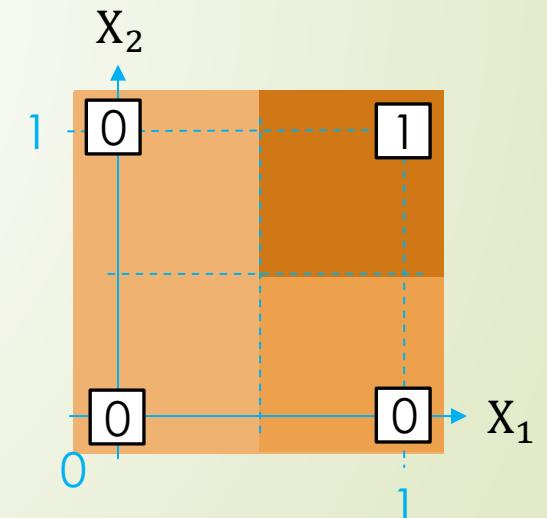
► Confidence: _____ %

► Rule 2 (refined): $X_2 = 0 \Rightarrow Y = 0$

► Confidence: _____ %

► Default rule: $Y = \text{_____}$.

	X_1	X_2	Y
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1



Generating rule directly

► Decision list

1. Rule 1: $X_1 = 0 \Rightarrow Y = 0$
2. Rule 2: $X_2 = 0 \Rightarrow Y = 0$
3. Default rule: $Y = 1$.

► Is the list best possible? Y/N

1. Time to detect positive class: _____
2. Length of the list: _____

	X_1	X_2	Y
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1

Class-based ordering

► Learn rules for positive class first:

1. Rule 1:

i. $Y = 1$ (confidence: _____ %)

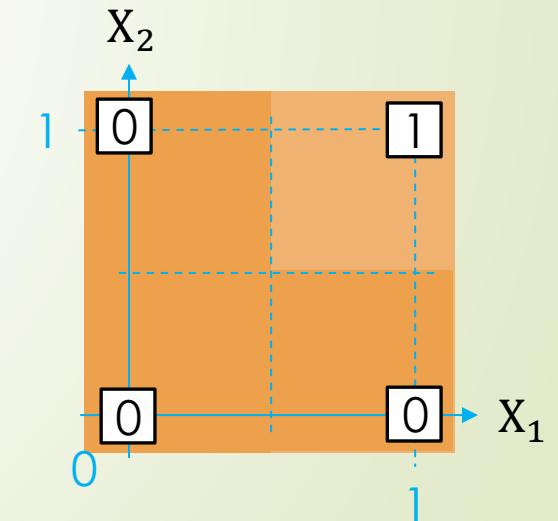
ii. $X_1 = \underline{\hspace{2cm}} \Rightarrow Y = 1$ (confidence: _____ %)

iii. $X_1 = \underline{\hspace{2cm}}, X_2 = \underline{\hspace{2cm}} \Rightarrow Y = 1$ (confidence: _____ %)

2. Default rule: $Y = \underline{\hspace{2cm}}$

► Will the above guarantee a short decision list in general? Y/N
because _____

	X_1	X_2	Y
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1



RIPPER

First Order Inductive Learner Gain

- Add conjunct that maximizes

$$\text{FOIL_Gain} = p' \left(\log \frac{p'}{p' + n'} - \log \frac{p}{p + n} \right)$$

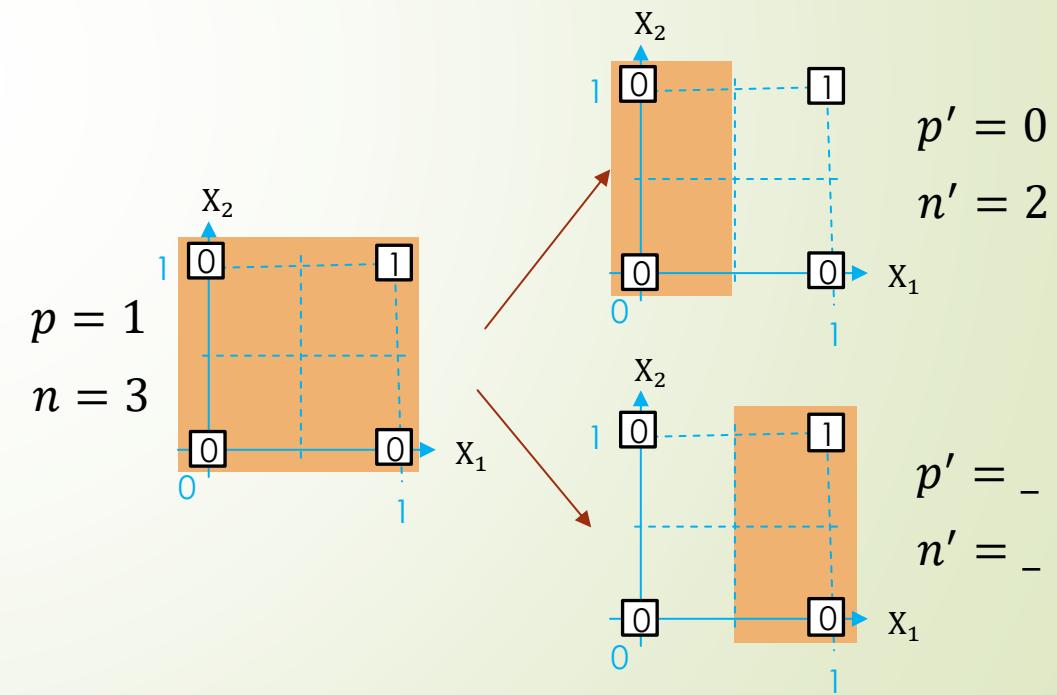
- Change in # of positives: $p \rightarrow p'$
- Change in # of negatives: $n \rightarrow n'$
- $Y = 1 \rightarrow X_1 = 0 \Rightarrow Y = 1:$

FOILGain= _____

- $Y = 1 \rightarrow X_1 = 1 \Rightarrow Y = 1:$

FOILGain= _____

- First/Second is better.



RIPPER

First Order Inductive Learner Gain

- ▶ Improve a rule by maximizing

$$\text{FOIL_Gain} = p' \left(\log \frac{p'}{p' + n'} - \log \frac{p}{p + n} \right)$$

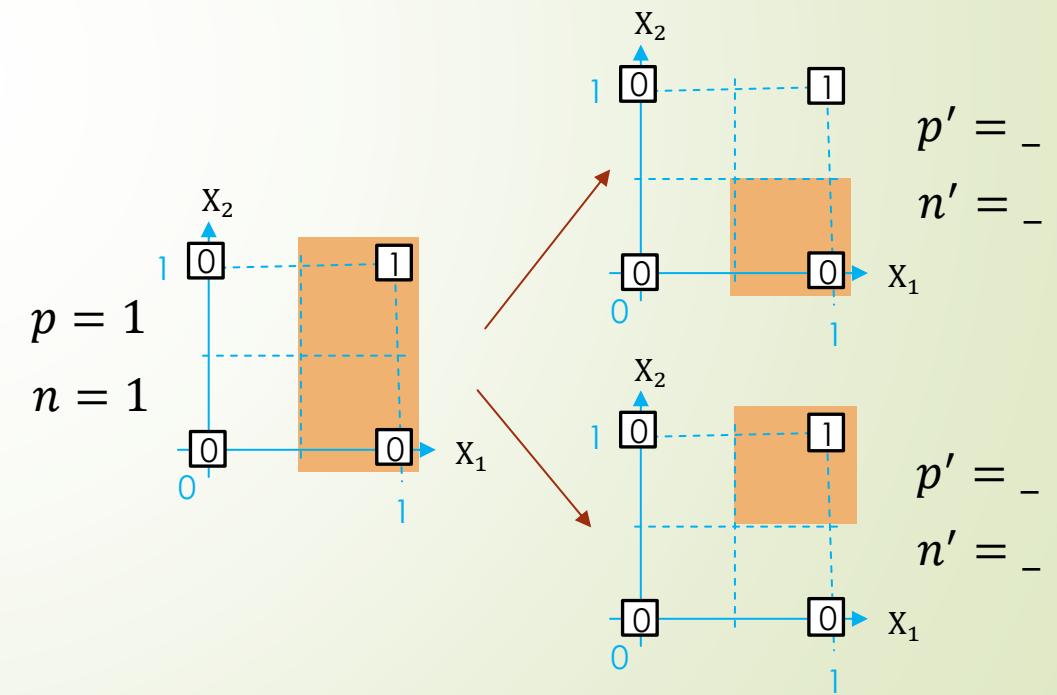
- ▶ Change in # of positives: $p \rightarrow p'$
- ▶ Change in # of negatives: $n \rightarrow n'$
- ▶ $X_1 = 1 \Rightarrow Y = 1 \rightarrow X_1 = 1, X_2 = 0 \Rightarrow Y = 1$:

FOILGain= _____

- ▶ $X_1 = 1 \Rightarrow Y = 1 \rightarrow X_1 = 1, X_2 = 1 \Rightarrow Y = 1$:

FOILGain= _____

- ▶ First/Second is better.



RIPPER

First Order Inductive Learner Gain

$$\begin{aligned}
 \text{FOIL_Gain} &= p' \left(\log \frac{p'}{p' + n'} - \log \frac{p}{p + n} \right) \\
 &= (p' + n') \underbrace{\frac{p'}{p' + n'}}_{(1)} \left(\underbrace{\log \frac{p'}{p' + n'}}_{(2)} - \underbrace{\log \frac{p}{p + n}}_{(3)} \right)
 \end{aligned}$$

- ▶ Heuristics:
 - ▶ (1) favors rules with large coverage/confidence.
 - ▶ (2)*(3) favors rules with large coverage/confidence given the same coverage/confidence.
 - ▶ (3) ensures FOIL_Gain is positive if coverage/confidence increases.
- ▶ [Challenge] Why not use information gain or gain ratio?

RIPPER

How to avoid overfitting?

- ▶ Repeated Incremental Pruning to Produce Error Reduction
- ▶ After each new rule, eliminate a conjunct (starting with the most recently added one) if it improves the following on a v_____ set:

$$\text{FOIL_Prune} = \frac{p - n}{p + n}$$

or equivalently reduces

$$\text{error} = \frac{n}{p + n}$$

References

- ▶ 8.4 Rule-Based Classification
- ▶ (Optional) Eibe Frank, Ian H. Witten. "[Generating accurate rule sets without global optimization](#)." Fifteenth International Conference on Machine Learning, 1998, p.144-151.
 - ▶ A partial tree is built with nodes (subsets of data) split (expanded) in the order of their entropy.
 - ▶ A node is considered for pruning by subtree replacement if all its children are leaf nodes.
- ▶ (Optional) Cohen, William W. "[Fast effective rule induction](#)." Machine Learning Proceedings, 1995, p.115-123. (See also [WEKA JRIP](#) or its [source code](#).)
 - ▶ The algorithm stops adding rules to the rule-set if the description length of the new rule is 64 bits more than the minimum description length met.
 - ▶ After the algorithm stop adding rules, there is a rule optimization step that optimize each rule one-by-one.