



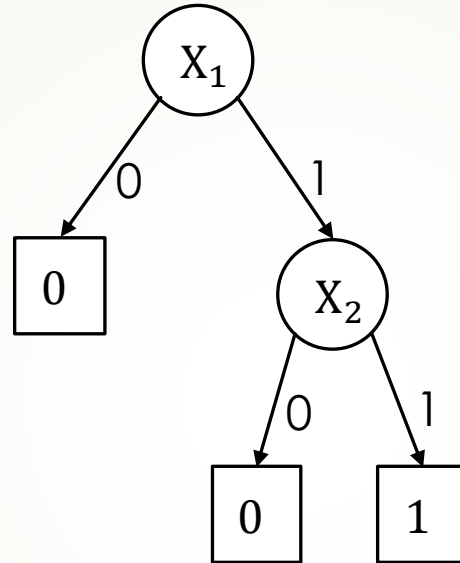
香港城市大學  
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# Classification: Rule-Based Classification

C5483 Data Warehousing and Data Mining

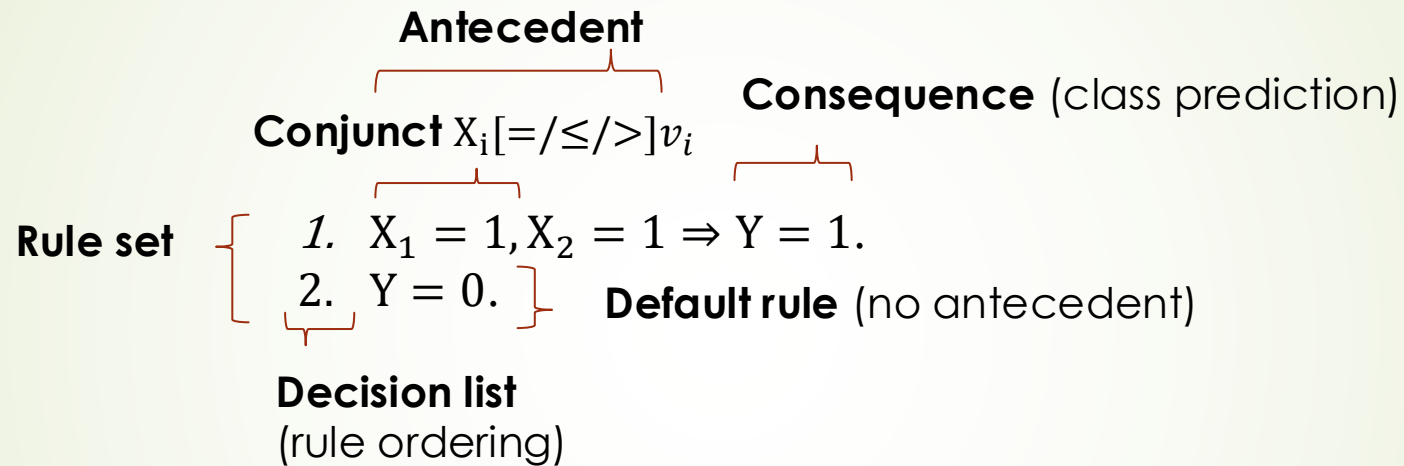
# Motivation



- When is the decision equal to 1?
  1. If \_\_\_\_\_, then  $Y = 1$ .
  2. Else  $Y = 0$ .

# Rule-based classification

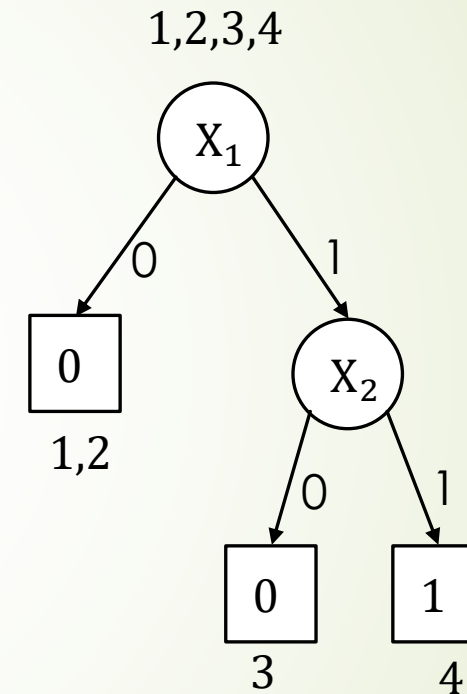
## Knowledge representation



- Benefits representing knowledge by rules: (c.f. decision tree or NN)
  - M \_\_\_\_\_
  - I \_\_\_\_\_
- How to generate rules?

# Generate rules from a decision tree

	$X_1$	$X_2$	$Y$
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1



► Each path from root to leaf corresponds to a rule:

1.  $X_1 = \_ \Rightarrow Y = 0$

2.  $X_1 = \_, X_2 = \_ \Rightarrow Y = 0$

3.  $X_1 = \_, X_2 = \_ \Rightarrow Y = 1$

► Does the ordering of these rules matter?

Yes/No because \_\_\_\_\_

# Sequential covering

- S\_\_\_\_\_ -and-c\_\_\_\_\_ (c.f. divide-and-conquer)
  1. Learn a good rule.
  2. Remove covered instances and repeat 1 until all instances covered.
- How to learn a good rule?
- PART (partial tree) decision list
  1. Build a new decision tree (by C4.5) and extract the rule that maximizes **coverage**: fraction of instances satisfying the antecedent.
  2. Remove covered instances and repeat 1 until all instances are covered.

# PART (partial tree) decision list

## Example

1. Rule 1: \_\_\_\_\_

*i.*  $X_1 = 0 \Rightarrow Y = 0$  (coverage: \_\_\_\_\_%)

*ii.*  $X_1 = 1, X_2 = 0 \Rightarrow Y = 0$  (coverage: \_\_\_\_\_%)

*iii.*  $X_1 = 1, X_2 = 1 \Rightarrow Y = 1$  (coverage: \_\_\_\_\_%)

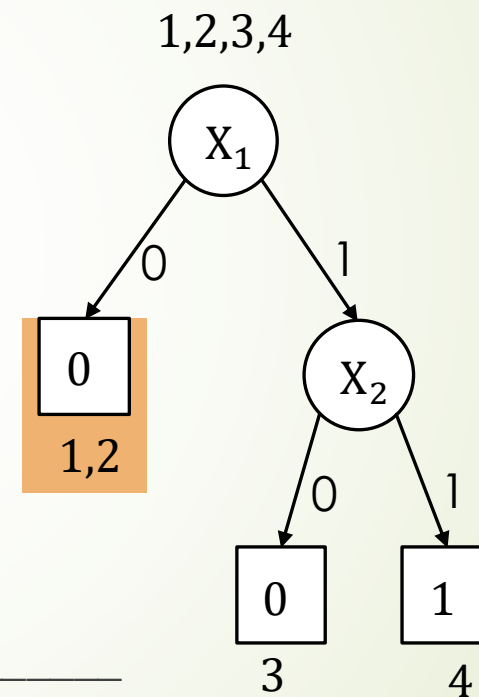
2. Rule 2: \_\_\_\_\_

*i.*  $X_2 = 0 \Rightarrow Y = 0$  (coverage: \_\_\_\_\_%)

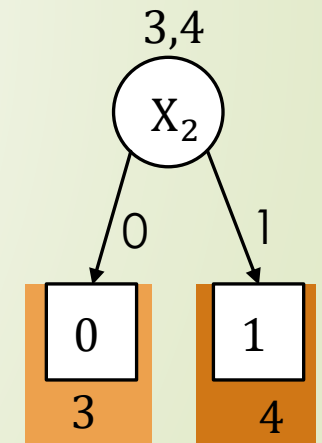
*ii.*  $X_2 = 1 \Rightarrow Y = 1$  (coverage: \_\_\_\_\_%)

3. Default rule:  $Y =$  \_\_\_\_\_

➡ Issue: [Time complexity] \_\_\_\_\_



	$X_1$	$X_2$	$Y$
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1



# Generating rule directly

1. Start with ZeroR, add conjuncts to improve **confidence**: fraction of correctly classified instances.

➤ Rule 1:  $Y = 0$

➤ Confidence: \_\_\_\_\_%

➤ Rule 1 (refined):  $X_1 = 0 \Rightarrow Y = 0$

➤ Confidence: \_\_\_\_\_%

2. Repeatedly add new rules to cover remaining tuples

➤ Rule 2:  $Y = 0$

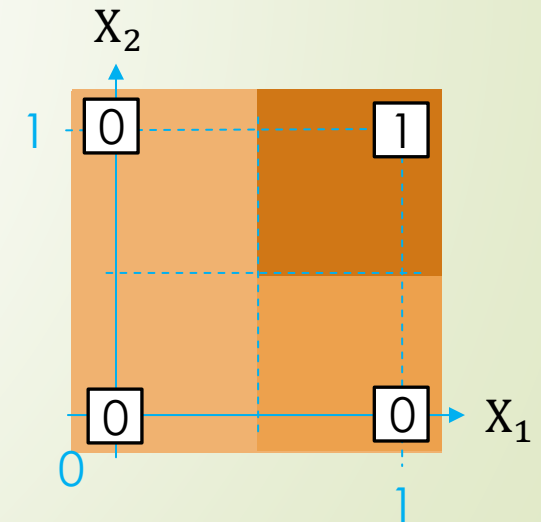
➤ Confidence: \_\_\_\_\_%

➤ Rule 2 (refined):  $X_2 = 0 \Rightarrow Y = 0$

➤ Confidence: \_\_\_\_\_%

➤ Default rule:  $Y = \underline{\hspace{1cm}}$ .

	$X_1$	$X_2$	$Y$
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1



# Generating rule directly

## ► Decision list

1. Rule 1:  $X_1 = 0 \Rightarrow Y = 0$
2. Rule 2:  $X_2 = 0 \Rightarrow Y = 0$
3. Default rule:  $Y = 1$ .

## ► Is the list best possible? Y/N

1. Time to detect positive class: \_\_\_\_\_
2. Length of the list: \_\_\_\_\_

	$X_1$	$X_2$	$Y$
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1



# Class-based ordering

► Learn rules for positive class first:

1. Rule 1:

i.  $Y = 1$  (confidence: \_\_\_\_%)

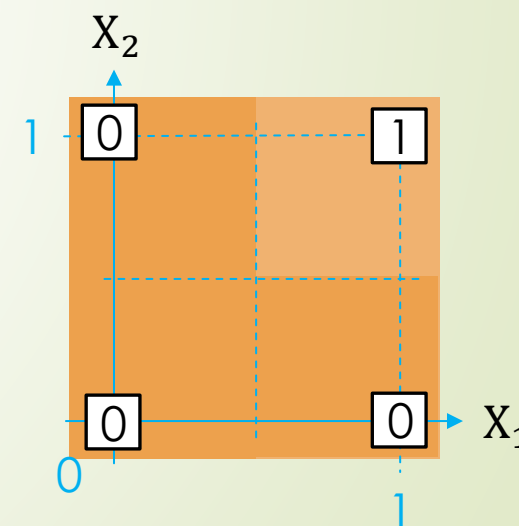
ii.  $X_1 = \_ \Rightarrow Y = 1$  (confidence: \_\_\_\_%)

iii.  $X_1 = \_, X_2 = \_ \Rightarrow Y = 1$  (confidence: \_\_\_\_%)

2. Default rule:  $Y = \_$

► Will the above guarantee a short decision list in general? Y/N  
because \_\_\_\_\_

	$X_1$	$X_2$	$Y$
1.	0	0	0
2.	0	1	0
3.	1	0	0
4.	1	1	1



# RIPPER

## First Order Inductive Learner Gain

- Add conjunct that maximizes

$$\text{FOIL\_Gain} = p' \left( \log \frac{p'}{p' + n'} - \log \frac{p}{p + n} \right)$$

- Change in # of positives:  $p \rightarrow p'$
- Change in # of negatives:  $n \rightarrow n'$

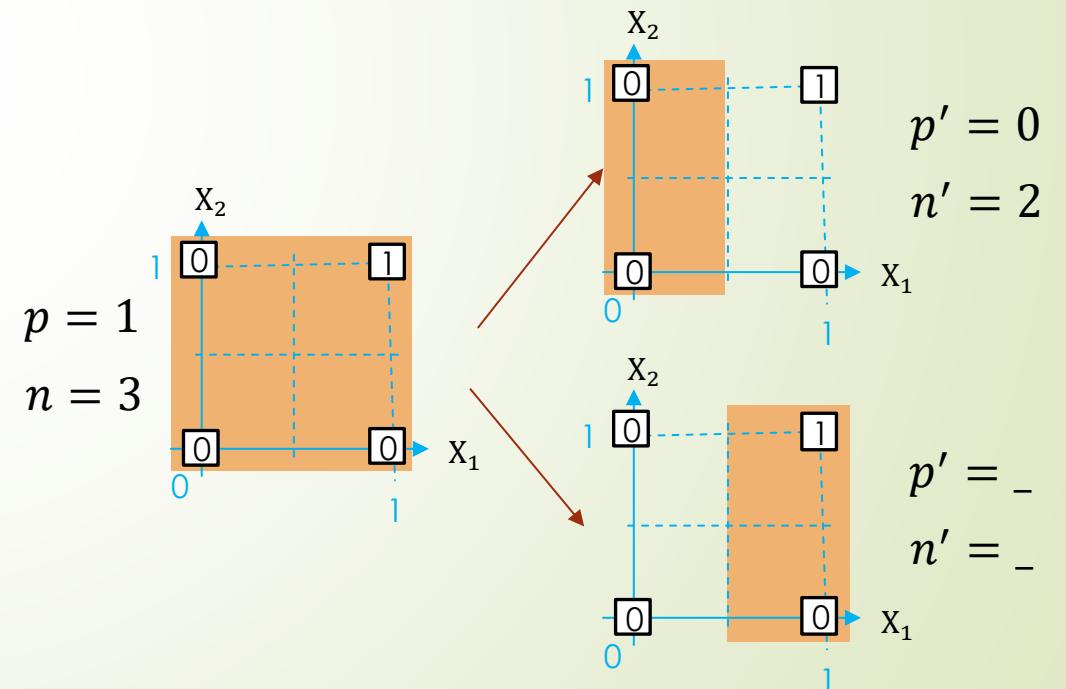
- $Y = 1 \rightarrow X_1 = 0 \Rightarrow Y = 1$ :

FOILGain=\_\_\_\_\_

- $Y = 1 \rightarrow X_1 = 1 \Rightarrow Y = 1$ :

FOILGain=\_\_\_\_\_

- First/Second is better.



# RIPPER

## First Order Inductive Learner Gain

- Improve a rule by maximizing

$$\text{FOIL\_Gain} = p' \left( \log \frac{p'}{p' + n'} - \log \frac{p}{p + n} \right)$$

- Change in # of positives:  $p \rightarrow p'$
- Change in # of negatives:  $n \rightarrow n'$

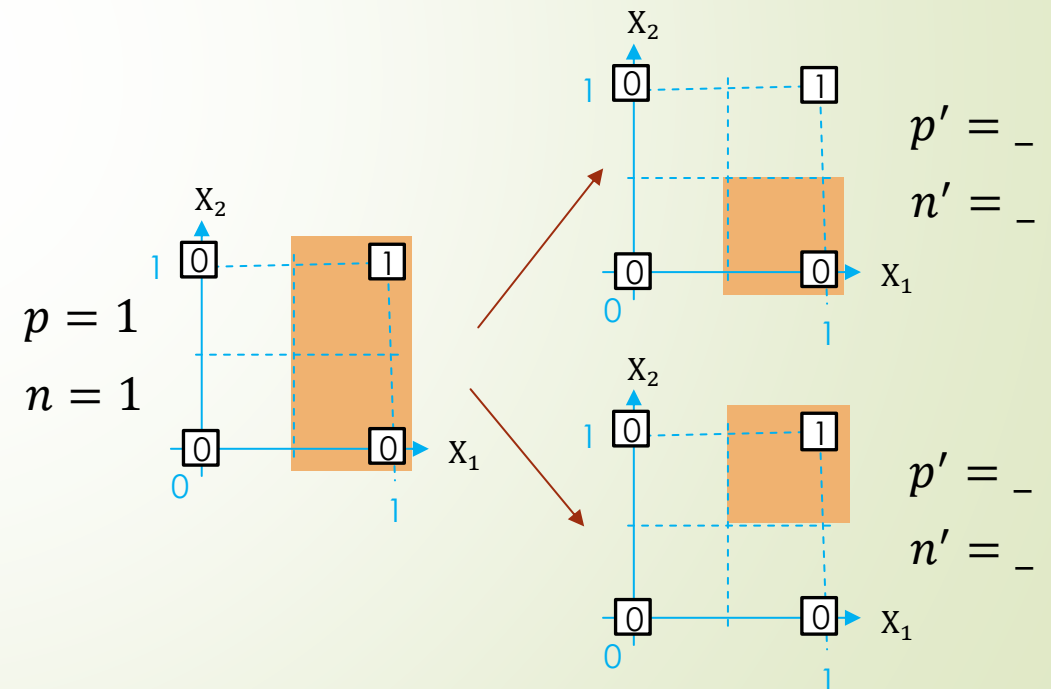
- $X_1 = 1 \Rightarrow Y = 1 \rightarrow X_1 = 1, X_2 = 0 \Rightarrow Y = 1$ :

FOILGain=\_\_\_\_\_

- $X_1 = 1 \Rightarrow Y = 1 \rightarrow X_1 = 1, X_2 = 1 \Rightarrow Y = 1$ :

FOILGain=\_\_\_\_\_

- First/Second is better.



# RIPPER

## First Order Inductive Learner Gain

$$\begin{aligned}
 \text{FOIL\_Gain} &= p' \left( \log \frac{p'}{p' + n'} - \log \frac{p}{p + n} \right) \\
 &= \underbrace{(p' + n')}_{(1)} \underbrace{\frac{p'}{p' + n'}}_{(2)} \underbrace{\left( \log \frac{p'}{p' + n'} - \log \frac{p}{p + n} \right)}_{(3)}
 \end{aligned}$$

- Heuristics:
  - (1) favors rules with large coverage/confidence.
  - (2)\*(3) favors rules with large coverage/confidence given the same coverage/confidence.
  - (3) ensures FOIL\_Gain is positive if coverage/confidence increases.
- [Challenge] Why not use information gain or gain ratio?

# RIPPER

## How to avoid overfitting?

- Repeated **Incremental Pruning to Produce Error Reduction**
- After each new rule, eliminate a conjunct (starting with the most recently added one) if it improves the following on a  $v$  set:

$$\text{FOIL\_Prune} = \frac{p - n}{p + n}$$

or equivalently reduces

$$\text{error} = \frac{n}{p + n}$$

# References

- 8.4 Rule-Based Classification
- (Optional) Eibe Frank, Ian H. Witten. "[Generating accurate rule sets without global optimization](#)." Fifteenth International Conference on Machine Learning, 1998, p.144-151.
  - A partial tree is built with nodes (subsets of data) split (expanded) in the order of their entropy.
  - A node is considered for pruning by subtree replacement if all its children are leaf nodes.
- (Optional) Cohen, William W. "[Fast effective rule induction](#)." *Machine Learning Proceedings*, 1995, p.115-123. (See also [WEKA JRIP](#) or its [source code](#).)
  - The algorithm stops adding rules to the rule-set if the description length of the new rule is 64 bits more than the minimum description length met.
  - After the algorithm stop adding rules, there is a rule optimization step that optimize each rule one-by-one.