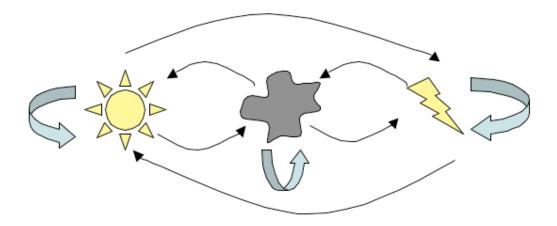
Baum-Welch and HMM applications

Analysis of Biological Sequences 140.638

Markov chains

- 3 states of weather: sunny, cloudy, rainy
 - Observed once a day at the same time



- All transitions are possible, with some probability
- Each state depends only on the previous state

Hidden Markov Models

Weather today

			Sunny	Clo	udy	Rainy		
	Weather	Sunny	0.50	0.20)	0.30		
	yesterday	Cloudy	0.10	0.60)	0.30		
		Rainy	0.20	0.40)	0.40		
							Dog	
	۸۱۱ س	shoon	a is the dear			in	out	porch
	All we c	bosei ve	e is the dog:		Sun	0.2	0.7	0.1
-	[OOOIPI	1000	OOPPIIIIP	ľ	Cloud	0.4	0.4	0.2
					Rain	0.7	0.1	0.2

Hidden Markov Models: the three questions

Evaluation

Given: a HMM, M, and a sequence x Find: P(x|M)

Forward, Backward and Forward-Backward algorithms

Decoding

Given: a HMM, M, and a sequence x Find: the sequence Q of states that maximizes P(x,Q|M) Viterbi algorithm

Learning

Given: an unknown HMM, M, and a sequence x Find: parameters θ that maximize P(x| θ , M) Baum-Welch expectation maximization (EM) algorithm

review

x are observations $\in A$, $q_1...q_n$ are hidden states $\in S$

$$\alpha(t,i) = p(x_1 x_2 \dots x_t, q_t = S_i)$$

$$\beta(t,i) = p(x_T x_{T-1} \dots x_t | q_t = S_i)$$

$$p(x, q_t = S_i | M) = \alpha(t,i)\beta(t,i)$$

$$p(x|M) = \sum_{i=1}^{N} \alpha(T,i) \quad p(x|M) = \sum_{i=1}^{N} \beta(1,i)$$

You have: observed data

You want: parameters of the HMM that generated that data

Problem: the calculation space is too big for exact calculation -> use heuristic method (even though it's a partial solution it's very useful!)

We are finding locally optimal parameters.

Assume: data come from some random process that we can fit to a HMM

Assumption #1: alphabet A and the number of states, N, are fixed. Transition, emission and initial distribution probabilities are all unknown.

Assumption #2: data are a set of observed sequences $\{x^{(d)}\}$ each of which has a hidden state sequence Q^d

Assumption #3: we can set all parameters/probabilities to some initial values

- Can choose from some uniform distribution
- Can choose to incorporate some prior knowledge
- Can just be random
- Cannot be flat

$$\alpha(t,i) = p(x_1 x_2 \dots x_t, q_t = S_i)$$

$$\beta(t,i) = p(x_T x_{T-1} \dots x_t | q_t = S_i)$$

$$p(x, q_t = S_i | M) = \alpha(t,i)\beta(t,i)$$

$$P(q_t = S_i, q_{t+1} = S_{\ell} \mid x, \theta) = [\alpha(t, i)p_{i\ell}b_{\ell}(x_{t+1})\beta(t+1, \ell)]/P(x)$$

$$p'_{i\ell} = \sum_{d} 1/P(x^d) \sum_{t} \alpha^d(t, i) p_{i\ell} b_\ell(x^d_{t+1}) \beta^d(t+1, \ell)$$

$$b'_{\ell}(c) = \sum_{d} 1/P(x^{d}) \sum_{t|x^{d}_{t}=c} \alpha^{d}(t,\ell) \beta^{d}(t,\ell)$$

$$P(q_t = S_i, q_{t+1} = S_{\ell} \mid x, \theta) = [\alpha(t, i)p_{i\ell}b_{\ell}(x_{t+1})\beta(t+1, \ell)]/P(x)$$

$$x_1x_2x_3 \cdot \cdot \cdot x_tx_{t+1} \cdot \cdot \cdot x_{T-1}x_T$$

$$q_1q_2q_3 \cdot \cdot \cdot q_tq_{t+1} \cdot \cdot \cdot q_{T-1}q_T$$

$$\cdot \cdot \cdot S_iS_1 \cdot \cdot \cdot$$

$$P(q_t = S_i, q_{t+1} = S_{\ell} \mid x, \theta) = [\alpha(t, i)p_{i\ell}b_{\ell}(x_{t+1})\beta(t+1, \ell)]/P(x)$$

$$p'_{i\ell} = \sum_{d} 1/P(x^d) \sum_{t} \alpha^d(t, i) p_{i\ell} b_\ell(x^d_{t+1}) \beta^d(t+1, \ell)$$

Figure out the probability of a hidden state i-> ℓ transition

- postulate that transition at every single spot in every single observed sequence (separately)
- see how those probabilities compare to the best probabilities for those observed sequences
- 3) use that ratio for the updated $p_{i\ell}$ transition probability

$$\begin{split} P(q_t = S_i, \ q_{t+1} = S_{\ell} \mid x, \theta) &= [\alpha(t, \ i)p_{i\ell}b_{\ell}(x_{t+1})\beta(t+1, \ell)]/P(x) \\ b'_{\ell}(c) &= \sum_{d} 1/P(x^d) \sum_{d} \alpha^d(t, \ell)\beta^d(t, \ell) \\ d & t|x^d_t = c \end{split}$$

Figure out the probability of an emission of symbol c from hidden state ℓ

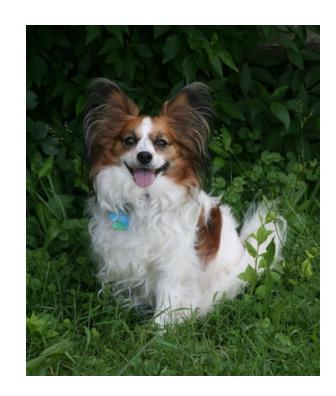
- 1) postulate that hidden state under every symbol c in every single observed sequence (separately)
- see how those probabilities compare to the best probabilities for those observed sequences
- 3) use that ratio for the updated $b'_{\ell}(c)$ transition probability

Then recalculate $P(x^d|M,\theta)$ for all observed data in the learning set (use Forward, Backward, or Forward/Backward to do this)

Rinse & repeat ...

Successive iterations increase P(data) and we stop when the probability stops increasing significantly (usually measured as log-likelihood ratios).

- I observe dog #2 at noon every day. Sometimes he's inside, sometimes he's outside.
- I guess that since he can't open the door by himself (yet) that there is another factor, hidden from me, that determines his behavior
- Since I am lazy I will guess that there are only two hidden states



• guessing two hidden states. I need to invent a transition matrix and an emission matrix.

today

yesterday

	SI	S2
SI	0.5	0.5
S2	0.4	0.6

	in	out
SI	0.2	0.8
S2	0.9	0.1

initial: p(S1) = 0.3, p(S2) = 0.7

```
one set of observations: II, II, II, II, IO, OO, OI, II, II
```

today

yesterday

	SI	S2
SI	0.5	0.5
S2	0.4	0.6

	in	out
SI	0.2	0.8
S2	0.9	0.1

initial: p(S1) = 0.3, p(S2) = 0.7

guess: if II came from \$1.52 the probability is

$$0.3 * 0.2 * 0.5 * 0.9 = 0.027$$

today

yesterday

	SI	S2
SI	0.5	0.5
S2	0.4	0.6

	in	out
SI	0.2	0.8
S2	0.9	0.1

initial: p(S1) = 0.3, p(S2) = 0.7

estimating the transition matrix:

Seq	P(Seq) if S1•S2	Best P(seq)
II	0.027	0.3403 S2•S2
IO	0.003	0.2016 S2•S1
00	0.012	0.096 S1•S1
OI	0.108	0.108 S1•S2
II	0.027	0.3403 S2•S2
II	0.027	0.3403 S2•S2
Total	0.285	2.4474

Our estimate for the \$1->\$2 transition probability is now 0.285/2.4474 = 0.116. Calculate the \$2->\$1,\$2->\$2,\$1->\$1 as well and normalize so they add up to 1 as needed, to update the transition matrix.

estimating the emission matrix:

Seq	Best P(Seq) if	Best P(seq)
	O came from S1	
IO	0.2016 (S2•S1)	0.2016 (S2•S1)
00	0.096 (S1•S1)	0.096 (S1•S1)
OI	0.108 (S1•S2)	0.108 (S1•S2)

estimating initial probabilities:

- assume all sequences start with hidden state \$1, calculate best probability
- 2. assume all sequences start with hidden state S2, calculate best probability
- 3. normalize to I

Now we have generated updated transition, emission, and initial probabilities. Repeat this method until those probabilities converge.

If you have guessed the wrong number of hidden states, it will be clear, though it's a very bad strategy to go through a huge range of possible hidden states to find the best model – you will over-optimize.

Applications of HMMs

- Exon finding through orthology (Haussler)
- ECG signal analysis (beat segmentation and classification)
- Analysis of microarray data especially tiling arrays
- Sequence feature prediction using homology information
- Sequence alignments, pairwise and multiple
- Analyzing ChIP-chip on tiling arrays

Finding genes

- The first gene finders were for prokaryotes
 - No introns
 - Distinct and known signals
- GLIMMER (1998, Salzberg et al.) was an early genefinding program and was very successful
 - Only for prokaryotes (first version)
 - Tested on relatively short sequences

GENSCAN (1997)

- GENSCAN (Burge and Karlin) was a huge breakthrough in eukaryotic gene-finding, and is still used by some groups
- How is it different?
 - Assumes that the input sequence can have no genes, one gene, multiple genes, or parts of genes
 - Models all known aspects of a eukaryotic gene
 - Uses general 3-periodic inhomogeneous fifthorder Markov model of coding regions
 - Does not use specific models of protein structure or database homology

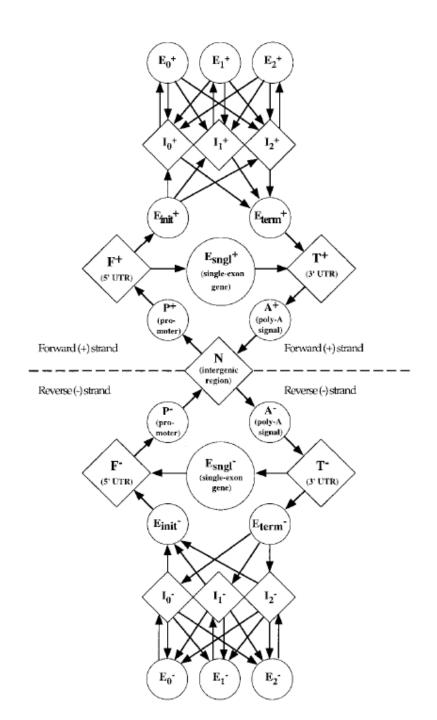
GENSCAN

- Uses double-stranded genomic sequence
- Partial genes, single gene, no genes all modeled
- Maximal Dependence Decomposition: models functional signals in DNA or protein to allow for statistical dependencies between signal positions
 - e.g. splice sites

```
exon...|GT..intron..AG|...exon
```

GENSCAN

- Explicit state duration HMM
 - Uses forward-backward algorithm
 - Choose initial state depending on the distribution of all possible states



GENSCAN — MDD

- Maximal Dependence Decomposition
 - Need aligned set of several hundred signal sequences
 - Use conditional probabilities to capture the most significant dependencies between positions
 - Calculate χ^2 for each pair of positions to detect dependencies

- Three types of de novo predictors
 - Single genome sequence (mostly HMMs)

Two aligned genomes
 Multiple aligned genomes
 jinfer local rates & patterns of mutation

 With good programs can expect 50-70% of the genes correctly predicted, in a compact genome

- Single-genome predictors
 - Easier to train, faster to run
 - First step in annotation
 - Use information from intrinsic sequence signals

- Dual-genome predictors
 - Rely on functional regions being more conserved
 - SLAM (HMM) uses joint probability for sequence alignment and gene structure to define types of alignments seen in coding vs noncoding sequence
 - More powerful approaches use HMM and dynamic programming
 - Problem: in closely related species most of the conserved sequences are noncoding

- Multi-genome predictors
 - More genomes -> stronger evidence
 - Hard to get enough species for a good alignment (translocations, deletions, inversions etc destroy alignments)
 - Some use phylogenetic trees (phylo-HMMs)

Common modern applications

- copy number variation
- areas of enrichment (ChIP-chip, ChIP-seq etc)
- finding CpG islands

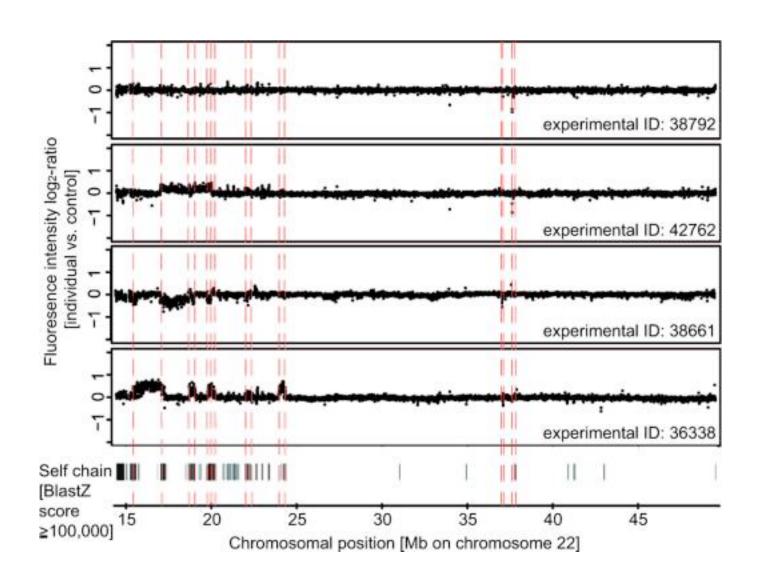
HMM for CNV

Systematic prediction and validation of breakpoints associated with copy-number variants in the human genome

Jan O. Korbel*^{†‡}, Alexander Eckehart Urban^{§¶}, Fabian Grubert[§], Jiang Du[|], Thomas E. Royce*, Peter Starr*, Guoneng Zhong*, Beverly S. Emanuel**, Sherman M. Weissman[§], Michael Snyder^{¶‡}, and Mark B. Gerstein*^{|‡}

Departments of *Molecular Biophysics and Biochemistry and §Genetics, Yale University School of Medicine, New Haven, CT 06520; †European Molecular Biology Laboratory, 69117 Heidelberg, Germany, Departments of ¶Molecular, Cellular, and Developmental Biology and Computer Science, Yale University, New Haven, CT 06520; and **Department of Pediatrics, University of Pennsylvania School of Medicine, Philadelphia, PA 19104

HMM for CNV



HMM for CNV

