

## Interpretation of likelihood

The likelihood function  $L(\boldsymbol{\theta}; \mathbf{x})$  of a vector of parameters  $\boldsymbol{\theta}$ , based on a random sample  $\mathbf{x} = (x_1, x_2, \dots, x_n)^T$ , is a function of  $\boldsymbol{\theta}$ .

The meaning of  $L(\boldsymbol{\theta}; \mathbf{x})$  is that its value gives a measure of “how likely” it is that  $\boldsymbol{\theta}$  gives the true values of the parameter of interest, given the random sample  $\mathbf{x}$ .

## Which $\theta$ ?

If we take two different values of  $\theta$ , say  $\theta_1$  and  $\theta_2$ , then a question arises on which of the two we should choose, given the sample  $\mathbf{x}$ .

The previous ideas might suggest that if

$$L(\theta_1; \mathbf{x}) \geq L(\theta_2; \mathbf{x}),$$

then  $\theta_1$  should be preferred, because  $\theta_1$  is “more likely” to describe the process underlying our experiment.

# Maximum likelihood estimation

This idea leads to the principle of **maximum likelihood estimation**:

We estimate  $\theta$  by the value  $\hat{\theta}$  which maximises the likelihood function, i.e.

$$\hat{\theta} \text{ is such that } L(\hat{\theta}; \mathbf{x}) \geq L(\theta; \mathbf{x}), \quad \text{for all } \theta \in \Theta,$$

where  $\Theta$  is set of possible parameters  $\theta$ .

# The maximum likelihood estimate

We call  $\hat{\theta}$  the **maximum likelihood estimate** of  $\theta$ , given the data  $\mathbf{x}$ .

Note that if we had different data  $\mathbf{x}$ , we would typically get a different  $\hat{\theta}$ . We hope that if we take enough samples,  $\hat{\theta}$  becomes close to its true value  $\theta$ .

## Numbers of parameters

In some cases  $\theta$  will consist of just one parameter, in which case we say we have a **one-parameter problem**.

In some cases  $\theta$  will consist of two or more parameters, in which case we say we have a **multi-parameter problem**.

In the former case we can write  $\theta = \theta$  (a scalar parameter) and we will want to maximise  $L(\theta; \mathbf{x})$  over  $\theta$ .

In the latter case we will want to maximise  $L(\theta; \mathbf{x})$  over  $\theta$ , a multi-dimensional maximisation problem.

# Examples

**Example 30:** Discrete maximisation of likelihood

**Example 31:** Exponential maximum likelihood

**Example 32:** Binomial maximum likelihood

# Maximising the likelihood

Maximum likelihood estimation comes down to a maximisation problem.

Whether this is easy or difficult depends on (a) the statistical model we use in the form  $f(\mathbf{x}; \boldsymbol{\theta})$  and (b) the parameter vector  $\boldsymbol{\theta}$ .

One-parameter problems are clearly easier to handle and in many cases multi-parameter problems require the use of numerical maximisation techniques.

## Log likelihood

In maximising  $L(\boldsymbol{\theta}; \mathbf{x})$  it is usually easier to work with the logarithm of the likelihood instead of the likelihood itself.

We call the logarithm of the likelihood the **log-likelihood function** and we write

$$\ell(\boldsymbol{\theta}; \mathbf{x}) = \log L(\boldsymbol{\theta}; \mathbf{x}).$$

Maximising  $\ell(\boldsymbol{\theta}; \mathbf{x})$  over  $\boldsymbol{\theta}$  produces the same estimator  $\hat{\boldsymbol{\theta}}$  as maximising the likelihood, because the logarithm is increasing, i.e.

$$\hat{\boldsymbol{\theta}} \text{ is such that } \ell(\hat{\boldsymbol{\theta}}; \mathbf{x}) \geq \ell(\boldsymbol{\theta}; \mathbf{x}), \text{ for all } \boldsymbol{\theta} \in \Theta.$$

In this course we work with natural logarithms, which are useful because many p.d.f.s include an exponential term.



# The parameter set and maximisation techniques

When we maximise  $\ell(\boldsymbol{\theta}; \mathbf{x})$ , we need to be careful with the parameter set  $\Theta$ .

In most of the examples we will meet in this module  $\boldsymbol{\theta}$  will be continuous (NB this is not the same thing as saying that the distribution of  $\mathbf{X}$  is continuous) and so we can use differentiation to obtain the maximum.

However, in some cases (e.g. Example 30) the possible values of  $\boldsymbol{\theta}$  may be discrete (i.e.  $\Theta$  is a discrete set) and in such cases we cannot use differentiation.

## One parameter problems

One-parameter problems can be easily handled using the maximisation and minimisation techniques from single variable calculus theory.

For example to obtain the maximum of  $\ell(\theta; \mathbf{x})$ , we first find the solution of

$$\frac{d\ell(\theta; \mathbf{x})}{d\theta} = 0 \Rightarrow \theta = \hat{\theta} \quad (1)$$

and then we check that

$$\left. \frac{d^2\ell(\theta; \mathbf{x})}{d\theta^2} \right|_{\theta=\hat{\theta}} < 0. \quad (2)$$

## Checking for maxima

Note that (1) only does not guarantee that  $\hat{\theta}$  is a maximum; it is necessary to check with (2).

(In some cases, the maximum likelihood estimate of  $\theta$  does not exist!)

# Examples

**Example 33:** Chemical reaction again

**Example 34:** Poisson maximum likelihood estimation

**Example 35:** Uniform maximum likelihood estimation

## Multi-parameter problems

For multi-parameter problems, where  $\theta$  is a vector, a similar procedure can be followed.

Here for simplicity we consider only the case where there are 2 parameters (so that  $\theta$  is a  $2 \times 1$  vector) and write  $\theta = (\theta_1, \theta_2)^T$ .

## Stationary points

Now we find a stationary point  $\hat{\boldsymbol{\theta}} = (\hat{\theta}_1, \hat{\theta}_2)^T$  of the log-likelihood by solving

$$\frac{\partial \ell(\boldsymbol{\theta}, \mathbf{x})}{\partial \theta_1} = 0, \quad \frac{\partial \ell(\boldsymbol{\theta}, \mathbf{x})}{\partial \theta_2} = 0. \quad (3)$$

Equation (3) is the analogue in the two parameter case of equation (1) in the one parameter case.

## The Hessian

The candidate  $\hat{\theta}$  may be a maximum or not, and we have to check this by using an analogue of equation (2) in order to check if  $\hat{\theta}$  is indeed a (local) maximum of the log likelihood function.

First we calculate the so called **Hessian matrix**:

$$H = \begin{pmatrix} \partial^2 \ell(\theta; \mathbf{x}) / \partial \theta_1^2 & \partial^2 \ell(\theta; \mathbf{x}) / \partial \theta_1 \partial \theta_2 \\ \partial^2 \ell(\theta; \mathbf{x}) / \partial \theta_1 \partial \theta_2 & \partial^2 \ell(\theta; \mathbf{x}) / \partial \theta_2^2 \end{pmatrix}$$

and then we evaluate  $H$  at  $\theta = \hat{\theta}$ , where  $\hat{\theta}$  is the stationary point we found using (3).

## Identifying maxima

If  $H$  is a negative definite matrix (the analogue of the second derivative being negative in the one parameter case), then  $\hat{\theta}$  maximises  $\ell(\theta; \mathbf{x})$ .

If  $H$  is not a negative definite matrix, then we cannot conclude that  $\hat{\theta}$  is a (local) maximum.



## Negative definite matrices

To check that  $H$  is a negative definite matrix we can use the following (in the 2 variable case): if

$$\partial^2 \ell(\boldsymbol{\theta}; \mathbf{x}) / \partial \theta_1^2 < 0$$

and the determinant  $\det(H)$  is positive, then  $H$  is negative definite.

(More detail on maximising and minimising functions of more than one variable can be found in the module MAS211 Advanced Calculus and Linear Algebra.)

## Example

**Example 36:** Maximum likelihood estimation for normal distribution with unknown mean and variance