

# NICHOLAS GREIG

Phone: +61 447 680 619  
Email: nick.greig2@gmail.com

Sydney, NSW, Australia

## EDUCATION

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**2013 - 2020**

**BS** Bachelor of Mechatronics Engineering (Honours H2A)/Bachelor of Science  
(Extended major in computational science)  
- Faculty of Engineering Dean's Honours List Member 2020

## EMPLOYMENT HISTORY

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**2022 – Present** **Deakin University**

**September 2022 – Present** *Casual Research Assistant*

- Working with Richard Dazeley on a literature review of AI and AGI safety proposals

**2022 – Present** **Independent Machine Learning Researcher**

**June 2022 – Oct 2022** *Machine Learning Researcher*

- Received a short-term research grant from the Long Term Future Fund to up-skill in neural network interpretability for AGI safety

**2021 – 2022** **RMIT Integrated Photonics Applications Centre**

**Aug 2021 – June 2022** *Research Assistant*

- Completed internal photonics introductory course
- Used EME software and Python to simulate the performance of a silicon nitride material for various wavelengths and passive circuit components, including ring resonators, directional couplers and vertical inverse taper couplers
- Wrote custom technology stack and components as PCells in IPKISS framework, for exporting designed components to GDSII masks

**2019 – Present** **Additive Assurance**

**Jan 2021 – Aug 2021, June 2022 – Present** *Software Engineer (Data Analytics)*

**Nov 2019 – Feb 2020** *Machine Learning Research Intern*

- Created and trained a multi-output segmentation CNN to detect various types of defects in high resolution images of 3D printed metal parts during manufacturing
- Converted local back-end Python code to cloud appropriate code, by creating and testing Docker images and then deploying those Docker images to AWS instances.
- Created a 3D CNN and a 2D recurrent CNN to segment multiple defect types from images of 3D printed metal parts during manufacturing
- Performed literature review and quantitatively evaluated the relevance and efficacy of various superpixel segmentation techniques for printed part defect detection

- Developed a synthetic dataset and trained a lightweight, custom object detection system based upon a recent state of the art object detection architecture for detection of custom printed patterns

**2019 – 2020**

**Sentient Vision Systems**

**Jul 2019 -Mar 2020:**

***Machine Learning Software Developer***

**Jan 2019 – Jul 2019**

***Machine Learning Research Intern***

- Migrated existing object detection code-base from Keras into a new in-house deep-learning prototype/design and training framework
- Orchestrated continuous literature review, proposing and implementing new ideas based upon current state of the art methods in recent research
- Designed and created a prototype deep learning framework using Pytorch, which incorporated recent best practices and promising computer-vision based deep learning ideas, culminating in a MVP prototype for demonstration purposes. This work focussed on small object detection and classification from aerial imagery in high resolution nadir images.

## **NOTABLE PROJECTS**

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**Jan 2020 – Nov 2020**

**Capstone Engineering Project**

Over 2 semesters I performed an in-depth literature review of the current state of photonic neural networks and photonic co-processors for AI. After this, I proposed a novel design for a theoretical eletro-optic ReLU neuron for high throughput on-chip training of neural networks, and simulated the analog electronic circuits required for its functioning in MATLAB's Simulink.

**Jul 2019 – Jan 2020**

**Monash DeepNeuron Vision Team Leader**

As team leader of the Vision sub-team of the Monash student-run group DeepNeuron, I created a framework to train and deploy a multi-class, multi-object detection system, written in TensorFlow, for the purposes of real-time object detection on embedded devices. This object detection framework was based upon the recent trend of keypoint pixelwise classification. During this time I also coordinated the activities, education and work of the two other members of my team.

## **SKILLS**

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**Proficient in Python, growing competence in Rust**

**Experienced in using both Pytorch and Tensorflow for the creation of deep neural networks, primarily for semantic segmentation, object detection and image classification.**

**Strong mathematical and communicational skills**

**Able to work well under pressure in fast-paced team environments**