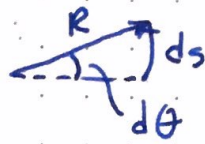


Problem 1

$$\oint_C f(\theta) ds$$



$$ds = R d\theta$$

$$\Rightarrow \oint_C f(\theta) R d\theta = R \oint_C f(\theta) d\theta$$

$$L' = R \int_0^{2\pi} -P(\theta) \sin \theta d\theta$$

$$C_p = \frac{P(\theta) - P_\infty}{q_\infty}$$

$$C_p = 1 - 4 \sin^2 \theta$$

$$\rightarrow 1 - 4 \sin^2 \theta = \frac{P - P_\infty}{q_\infty}$$

$$P(\theta) = q_\infty - 4 \sin^2 \theta q_\infty + P_\infty$$

$$P = C_p q_\infty + P_\infty$$

$$(\cancel{C_p(\theta) q_\infty} + P_\infty)$$

$$L' = -R \int_0^{2\pi} (q_\infty - 4 \sin^2 \theta q_\infty + P_\infty) \sin \theta d\theta$$

Composite Simpson's Rule:

$$\int_a^b f(\theta) d\theta \approx \frac{h}{3} \sum_{k=1}^{N/2} [f(\theta_{2k-1}) + 4f(\theta_{2k}) + f(\theta_{2k+1})]$$

$$\theta_k = a + (k-1)h \quad , \quad h = \frac{b-a}{N}$$

$$\rightarrow L' = -R \int_0^{2\pi} \overbrace{(q_\infty - 4 \sin^2 \theta q_\infty + P_\infty) \sin \theta}^{f(\theta)} d\theta$$

$$L' \approx -R \frac{h}{3} \sum_{k=1}^{N/2} [f(\theta_{2k-1}) + 4f(\theta_{2k}) + f(\theta_{2k+1})]$$

$$w/ f(\theta) = (q_\infty - 4 \sin^2 \theta q_\infty + P_\infty) \sin \theta$$

$$L' = f(\theta) (C_p(\theta) q_\infty + P_\infty) \sin \theta$$

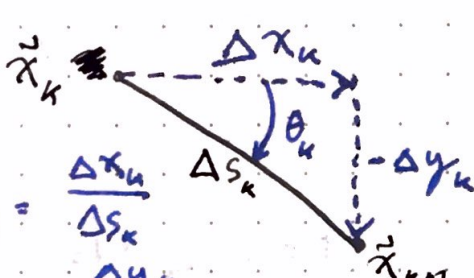
$$D' = f(\theta) = (C_p(\theta) q_\infty + P_\infty) \cos \theta$$

Lab 1 - Comp - Problem 2

$$N' = N_u' + N_l'$$

$$N_u' = - \int_{LE}^{TE} (P_u \cos \theta + \cancel{x_u s \theta}^{\vec{r}_0}) dS_u +$$

$$= - \sum_{k=1}^N |\vec{x}_{k+1} - \vec{x}_k| \left(\left[\frac{P_u(\vec{x}_{k+1}) + P_u(\vec{x}_k)}{2} \right] \cos \theta_k \right)$$



$$\cos \theta_k = \frac{\Delta x_k}{\Delta S_k}$$

$$\sin \theta_k = - \frac{\Delta y_k}{\Delta S_k}$$

$$\Delta S_k = |\vec{x}_{k+1} - \vec{x}_k|$$

$$\Delta x_k = x_{k+1} - x_k$$

$$\Delta y_k = y_{k+1} - y_k$$

$$N_u' \approx - \sum_{k=1}^N \Delta S_k \left(\frac{P_u(\vec{x}_{k+1}) + P_u(\vec{x}_k)}{2} \frac{\Delta x_k}{\Delta S_k} \right)$$

$$\approx - \sum_{k=1}^N \left(\frac{P_u(\vec{x}_{k+1}) + P_u(\vec{x}_k)}{2} \Delta x_k \right)$$

$$\therefore N_l' \approx \sum_{k=1}^N \left(\frac{P_l(\vec{x}_{k+1}) + P_l(\vec{x}_k)}{2} \Delta x_k \right)$$

$$A' = A_u' + A_l' \Rightarrow A_u' = - \sum_{k=1}^N \left(\frac{P_u(\vec{x}_{k+1}) + P_u(\vec{x}_k)}{2} \Delta y_k \right)$$

$$A_l' = \sum_{k=1}^N \left(\frac{P_l(\vec{x}_{k+1}) + P_l(\vec{x}_k)}{2} \Delta y_k \right)$$

$$C_p = \frac{p - p_\infty}{q_\infty}$$

$$\Rightarrow C_p q_\infty + p_\infty = p$$