



(1)
$\Theta_D(s) - \Theta_L(s)$

(2)
$K_P(\Theta_D(s) - \Theta_L(s))$

(3)
$sK_D\Theta_L(s)$

(4)
$U(s) = K_P(\Theta_D(s) - \Theta_L(s)) - sK_D\Theta_L(s)$