

CyUSB Suite for Linux

Version 1.0.5

Programmer's Guide



Document Version History

Version	Date	Author	Notes
1.0.0	08/07/12	V.Radhakrishnan	Detailed function description documentation added (format of libusb documentation)
1.0.2	10/01/12	Cypress Semiconductor	Update documentation formatting
1.0.3	01/23/13	Cypress Semiconductor	Updated version information. No API changes involved in this version.
1.0.4	07/11/13	Cypress Semiconductor	No API changes involved in this version. A new download_fx3 example is provided for FX3 firmware programming. download_fx2 example has been enhanced to support I2C programming. cyusb_linux GUI has been enhanced to support single step download of FX2/FX3 firmware to EEPROM.
1.0.5	05/08/15	Cypress Semiconductor	No API changes involved in this version. A new console application (09_cyusb_performance) has been provided for USB data rate measurement. cyusb_linux GUI has also been updated with STREAMER functionality under the data transfers tab.

Chapter – 1: Introduction to CyUSB Suite for Linux

This guide helps you get started quickly with CyUSB Suite for Linux.

The software is a clone of the CyUSB Suite for Windows and helps you work with the EZ-USB FX2LP and FX3 USB Peripheral Controllers from Cypress, using a Linux host computer.

The FX2LP Peripheral Controller combines USB (High Speed) with an integrated, enhanced industry standard 8051 micro-controller, whereas the FX3 Peripheral Controller combines Super Speed USB 3.0 with an integrated ARM-9 based micro-controller. More details can be obtained by looking at the device data sheets available on the Cypress website.

The CyUSB Suite for Linux does not help you develop firmware either for the FX2 or FX3. However, firmware already developed using either the Keil Tools for FX2 or the Eclipse IDE and the GNU tool-chain for FX3, may be downloaded using the CyUSB Suite for Linux and drivers for the peripherals (host side) can be developed using the user space library provided by this software

The CyUSB Suite for Linux is a wrapper around an existing Open Source user-space USB Library called **libush**

The CyUSB Suite gets you started quickly with a simplified wrapper around libusb, as well as by providing an infrastructure for testing your peripheral after the firmware is downloaded.

In other words, the libusb software is a **<u>pure 'C' library on linux</u>**, whereas the CyUSB Suite for Linux is **<u>a full-fledged Application</u>** built on top of libusb in two flavors :

- 1. As a Command Line Interface [CLI]
- 2. With a GUI built as a Qt based application

The CyUSB Suite also provides a header file 'cyusb.h' and a shared object library 'libcyusb.so' which can be used to build your own user space USB applications. The applications in the CyUSB suite have been developed using the same library and header file.

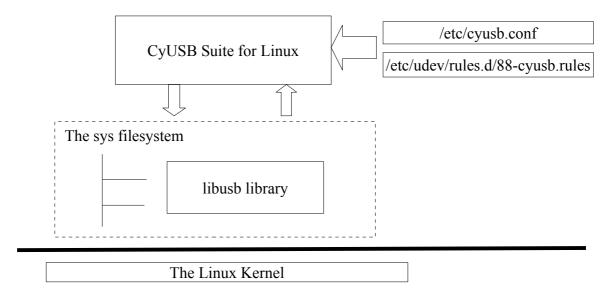


Figure-1: Block Diagram of CyUSB Suite for Linux

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Chapter - 2: Folder structure

Once the building process is complete the following folder are created.

The *doc* subdirectory contains the user guide and programmers guide (this manual).

The *configs* subdirectory contains three files -

- cyusb.conf
- 88-cyusb.rules
- cy_renumerate.sh

The **cyusb.conf** can be modified to include additional 'devices of interest', which means those devices (typically Cypress devices, but not necessarily so) which you wish to communicate with CyUSB Suite for Linux.

NOTE:

If a Cypress device is attached and you are not getting a notification on GUI, then add the VID and PID of the new device to /etc/cyusb.conf manually. This step requires root (superuser) privileges.

The **88-cyusb.rules** is a simple UDEV rules file that can also be modified to indicate devices of interest (again, typically Cypress devices, but not necessarily so).

The **cy_renumerate.sh** script is responsible for sending a notification of plug/unplug of a device of interest to the cyusb driver library.

More information about these files would be provided later on in this guide.

The *fx2_images and fx3_images* sub-directories contains a set of firmware binaries that can be downloaded into the EZ-USB devices to demonstrate sample applications. These binaries are for the FX2LP and FX3 devices respectively.

The *include* sub-directory contains the main cyusb.h header file that has been used by the CLI as well as the GUI applications that constitute CyUSB Suite For Linux.

The *lib* subdirectory contains the source code as well as the shared object (equivalent to 'DLL' on Microsoft Windows) for libcyusb, the main library used to build CyUSBSuite for Linux. The source file is called libcyusb.c, whereas the shared object file is called libcyusb.so.1 and a soft link target called libcyusb.so which is the soname for the library.

The *src* subdirectory contains all the CLI Application sources used. A makefile is also provided to build the various sample applications.

The *gui src* subdirectory contains the source for the GUI, which is developed using QT.



Chapter - 3: Getting started

It is assumed that the installation procedure documented in the user guide document has been followed before starting with the following steps.

Building the library:

Run make in the root folder to build the libcyusb.so library.

```
karthik@karthik-u3test (cyusb_linux_1.0.5) $ make
g++ -fPIC -o lib/libcyusb.o -c lib/libcyusb.cpp
g++ -shared -Wl,-soname,libcyusb.so -o lib/libcyusb.so.1 lib/libcyusb.o -l usb-1.0 -l rt
cd lib; ln -sf libcyusb.so.1 libcyusb.so
rm -f lib/libcyusb.o
karthik@karthik-u3test (cyusb_linux_1.0.5) $
```

Building the binaries:

Go to the **src** directory and do make to build all the example source files.

```
karthik@karthik-u3test (src) $ ls -l
total 116
-r--r--r-- 1 karthik karthik 3916 May
                                           8 14:22 00_fwload.cpp
-r--r--r-- 1 karthik karthik 5145 May
                                           8 14:23 01 getdesc.cpp
-r--r-- 1 karthik karthik 3554 May
                                           8 21:23 03_getconfig.cpp
-r--r--- 1 karthik karthik 3621 May
                                           8 14:24 04_kerneldriver.cpp
  --r--r-- 1 karthik karthik  3570 May  8 14:24 05_claiminterface.cpp
-r--r--r-- 1 karthik karthik 3894 May 8 14:24 06_setalternate.cpp
-r--r--r-- 1 karthik karthik 4418 May 8 14:26 08_cybulk.cpp
-rw-r--r-- 1 karthik karthik 14329 May 8 14:16 09 cyusb performance.cpp
-r--r--r-- 1 karthik karthik 2977 Sep 22 2014 config_parser.c
-r--r--r-- 1 karthik karthik 4610 May 8 14:26 cyusbd.cpp
-r--r-- 1 karthik karthik 25549 Sep 22 2014 download_fx2.cpp
-r--r-- 1 karthik karthik 17021 Sep 22 2014 download_fx3.cpp
-r--r-- 1 karthik karthik 1248 May 8 14:33 Makefile
karthik@karthik-u3test (src) $ make
g++ -o 00_fwload
                              00_fwload.cpp
                                                          -L ../lib -l cyusb
g++ -o 01_getdesc
                                                          -L ../lib -l cyusb
                             01_getdesc.cpp
                                                          -L ../lib -l cyusb
g++ -o 03_getconfig
                             03_getconfig.cpp
                                                         -L ../lib -l cyusb
g++ -o 04 kerneldriver
                            04_kerneldriver.cpp
g++ -o 05_claiminterface
                              05_claiminterface.cpp
                                                         -L ../lib -l cyusb
                                                         -L ../lib -l cyusb
g++ -o 06_setalternate
                              06_setalternate.cpp
                                                         -L ../lib -l cyusb -l pthread
g++ -o 08_cybulk
                              08_cybulk.cpp
g++ -o 09_cyusb_performance 09_cyusb_performance.cpp -L ../lib -l cyusb -l usb-1.0
g++ -o download_fx2
                              download_fx2.cpp -L ../lib -l cyusb
g++ -o download_fx3
                              download_fx3.cpp
                                                        -L ../lib -l cyusb
g++ -o cyusbd
                                                         -L ../lib -l cyusb
                              cyusbd.cpp
gcc -o config_parser
                              config_parser.c
                                                         -L ../lib -l cyusb
karthik@karthik-u3test (src) $
```



Test to see if everything is installed fine, by first plugging in the FX2LP DVK and then running the 01 getdesc program.

Example - Get Device Descriptor : 01_getdesc.c

\$./01 getdesc

```
carthik@karthik-u3test (src) $ ./01_getdesc
                      = 18
bLength
bDescriptorType
bcdUSB
                      = 0x0200
bDeviceClass
                      = 0xff
bDeviceSubClass
                      = 0xff
bDeviceProtocol
                      = 0xff
bMaxPacketSize
                      = 64
idVendor
                      = 0x04b4
                      = 0x8613
idProduct
bcdDevice
                      = 0xa001
iManufacturer
                      = 0
i.Product
                      = 0
                      = 0
iSerialNumber
bNumConfigurations = 1
karthik@karthik-u3test (src) $
```

The various programs demonstrated in the src directory can be run on the FX2 and/or FX3 devices. Some programs require a firmware binary to be downloaded and this is also illustrated in this guide, where appropriate.

Example - Get Device Configuration : 03_getconfig.c

\$./03 getconfig

```
karthik@karthik-u3test (src) $ ./03_getconfig
Device configured. Current configuration = 1
bLength
                   = 9
bDescriptorType
                   = 2
TotalLength
                   = 171
Num. of interfaces
                   = 1
bConfigurationValue = 1
iConfiguration
                   = 0
bmAttributes
                   = 128
                   = 0050
Max Power
karthik@karthik-u3test (src) $
```

Example - Attach / Detach Kernel Mode Driver for an USB device

\$./04 kerneldriver

```
karthik@karthik-u3test (src) $ ./04_kerneldriver
This device has no kernel driver attached to this interface
Do you wish to attach/reattach a kernel driver ? (1=yes,0=no) : 1
Successfully attached kernel driver for this interface
Do you wish to detach the kernel driver ? (1=yes,0=no) : 1
Successfully detached kernel driver for this interface
karthik@karthik-u3test (src) $
```



This example shows how to detach a kernel mode driver (if one exists) before you attach a user mode driver through CyUSB.

For a USB device, there is a driver per interface and each interface has to be free (not claimed) before it can be used for data traffic.

Therefore, if a device-interface already has a driver interface claimed by a kernel driver module, this has to be first released ('freed') before you can use it with CyUSB.

Example - Claim an interface for a USB device

\$./05 claiminterface

```
karthik@karthik-u3test (src) $ ./05_claiminterface
Enter interface number you wish to claim : 0
Interface 0 claimed successfully
^CSignal to quit received
karthik@karthik-u3test (src) $
```

Example - Set an alternate interface (after claiming an interface)

The FX2LP device has 1 interface, and four alternate interfaces numbered as 0, 1, 2 and 3. The alternate interface selected by default is 0.

We will demonstrate how to select an alternate interface of 1 for the interface 1

\$./06 setalternate

```
karthik@karthik-u3test (src) $ ./06_setalternate
Enter interface number you wish to claim : 0
Interface 0 claimed successfully
Enter alternate interface you wish to set : 1
Successfully set alternate interface setting
^CSignal to quit received
karthik@karthik-u3test (src) $
```

The download_fx2 example supports downloading FX2LP firmware into the RAM (internal or external), small I2C EEPROM or large I2C EEPROM.

Example - Downloading the dev io.hex file to the FX2LP RAM

\$./download fx2 -i../fx2 images/dev io.hex -t ram

Download the dev_io.hex firmware example that demonstrates GPIO based switches and 7-segment LED display on the FX2LP DVK.

```
karthik@karthik-u3test (src) $ ./download_fx2 -i ../fx2_images/dev_io.hex -t ram
Found Hex format file
Info: Releasing FX2 CPU from reset
FX2LP firmware programming to ram completed
karthik@karthik-u3test (src) $
```



Example - Downloading the bulkloop.iic file to large I2C EEPROM

The bulkloop firmware loops back EP2OUT to EP6IN and EP4OUT to EP8IN. The iic version of the firmware binary (generated through hex2bix) is downloaded to the large I2C EEPROM in this example. The FX2LP needs to be reset before running this step.

Please note that only iic files should be downloaded to the I2C EEPROMs. The download program does not do any verification of the file format or content.

\$./download fx2../fx2 images/bulkloop.iic -t li2c

```
karthik@karthik-u3test (src) $ ./download_fx2 -i ../fx2_images/bulkloop.iic -t li2c
Info: Forcing FX2 CPU into reset
Info: Downloading Vend_ax hex into FX2 RAM
Info: Releasing FX2 CPU from reset
FX2LP firmware programming to li2c completed
karthik@karthik-u3test (src) $
```

Test with the program 08_cybulk, the program echoes what you type in...

\$./08 cybulk

```
karthik@karthik-u3test (src) $ ./08_cybulk
Successfully claimed interface
Test
Test
Hello
Hello
Loopback
Loopback
^C
karthik@karthik-u3test (src) $ []
```

The download_fx3 program supports FX3 firmware download to device RAM, I2C EEPROM or SPI Flash devices.

Example - Downloading the cyfxbulksrcsink.img file to FX3 RAM

The cyfxbulksrcsink firmware implements a pair of IN and OUT endpoints that serve as perfect data sink and source. EP1OUT continuously accepts all data sent to it, and EP1IN continuously sends full data packets upto the USB host.

\$./download fx3 -i../fx3 images/cyfxbulksrcsink.img -i ram

```
karthik@karthik-u3test (src) $ ./download_fx3 -i ../fx3_images/cyfxbulksrcsink.img -t RAM FX3 firmware programming to RAM completed karthik@karthik-u3test (src) $
```



Example – Downloading FX3 firmware to SPI Flash

\$./download fx3 -i ../fx3 images/cyfxbulksrcsink.img -i spi

Download the cyfxbulksrcsink firmware onto I2C EEPROM devices. The download_fx3 program automatically downloads the cyfxflashprog firmware to FX3 RAM, and then uses it to do the flash programming. The flash programming can take about 20 to 30 seconds.

```
karthik@karthik-u3test (src) $ ./download_fx3 -i ../fx3_images/cyfxbulksrcsink.img -t spi
Info: Current device is not the FX3 flash programmer
Info: Trying to download flash programmer to RAM
Info: Found FX3 flash programmer
Info: Got handle to FX3 flash programmer
Info: Erased sector 0 of SPI flash
Info: Erased sector 1 of SPI flash
Info: SPI flash programming completed
FX3 firmware programming to spi completed
karthik@karthik-u3test (src) $
```

Example – Measuring USB Transfer Performance

\$./09 cyusb performance -e 129 -s 32 -q 8 -d 100

This application uses the asynchronous libusb API to repeatedly perform data transfers on the selected endpoint. The size of each individual request, the number of requests to be queued and the duration of the test are also specified through command line parameters.

Chapter - 4 : Programmers Guide to the CyUSB Library

This chapter gives details on how to develop code using the CyUSB Suite for Linux, as well as steps to compile and link the code, using the libcyusb.so library

Developing code:

The **cyusb.h** header file present in \$CyHome/include subdirectory, needs to be included in your program.

For example, if you are in the \$CyHome/src subdirectory, you would say

#include "../include/cyusb.h"

This header file describes one major data type called **struct cydev**, which is declared as follows:

```
struct cydev {
    cyusb device
                         *dev:
                         *handle;
    cyusb handle
    unsigned short
                         vid:
    unsigned short
                         pid;
    unsigned char
                         is open;
    unsigned char
                         busnum;
    unsigned char
                         devaddr;
    unsigned char
                         filler;
};
```

The **cyusb_device** data-type maps to the opaque libusb data-type called **struct libusb_device**, and the **cyusb_handle** data-type maps to the opaque libusb data-type called **struct libusb_device handle**.

1. **Opening a device (** and populating the cydev array)

```
int cyusb open(void);
```

This function populates the cydev [] array and returns the number of **interesting devices** found. An **'interesting device'** or alternatively, **'a device of interest'** is a device whose vendor ID/device ID is present in the **/etc/cyusb.conf** file described earlier.

This function is overloaded and a simpler alternative is

int cyusb open(unsigned short vid, unsigned short pid);

which populates the cydev array with just one entry and returns 1 if a single device is found that matches the vendor ID and device ID mentioned in the parameters. Usually, you would typically get a return value of 1, since you would be dealing with a single device of interest,

but the library has been built (and tested) to support multiple instances of the same vendor id/device id combinations, in which case, you would need to traverse the cydev[] array and extract the handle for the appropriate device by matching with bus number and device address.

2. Obtaining a cyusb handle

```
cyusb handle * cyusb gethandle(int index);
```

This function usually takes as input parameter the number 0 since you would usually be dealing with a single device of interest, as discussed earlier. The function then returns a non-null cyusb handle which is then used subsequently for data transfers.

3. Getting Device Information

Given a handle, it is possible to extract the vendor ID and device ID as follows:

```
unsigned short cyusb_getvendor(cyusb_handle *); and
unsigned short cyusb getproduct(cyusb handle *);
```

4. Closing all cyusb devices of interest

```
void cyusb close(void);
```

This function closes ALL cyusb devices of interest discovered.

5. Getting Bus Number and Device Address, given the handle

```
int cyusb_get_busnumber(cyusb_handle *);
int cyusb get devaddr(cyusb handle *);
```

These two functions return th bus number and the device address, given the handle. Since the handle itself is returned, given the index of the cydev[] array, it is useful in those circumstances where you have multiple instances of the same device.

6. Determining whether a usb device interface already is claimed by a kernel driver

The CyUSB Suite for Linux software is essentially a user mode driver library for a device. This means it is possible to communicate with a USB device provided it is not already claimed by another driver (user mode or kernel mode). The function described below returns true if a kernel mode driver is active for a given usb device handle :

int cyusb kernel driver active(cyusb handle *, int interface);

7. Detach / Attach a kernel mode driver for a usb device of interest:

In case a device already has a kernel mode driver active, as returned by true in the earlier API described just above, then this API allows one to detach a kernel mode driver, which is

then normally followed by claiming the interface by a user mode application like CyUSB Suite

```
int cyusb_detach_kernel_driver(cyusb_handle *, int interface); int cyusb_attach_kernel_driver(cyusb_handle *, int interface);
```

8. Claiming and releasing an interface:

User mode applications such as CyUSB Suite for Linux, can only work after claiming an interface. Use the following API.

```
int cyusb claim interface(cyusb handle *h, int interface);
```

and the API for releasing the interface is:

int cyusb_release_interface(cyusb_handle *h, int interface);

9. Getting USB Descriptors through a standard request:

```
int cyusb_get_descriptor(cyusb_handle *h, unsigned char desc_type, unsigned char desc_index,unsigned char *data, int len);
```

This function translates into the standard USB Request using a control type of transfer.

However, there are easier and more direct API to obtain Device, Configuration, String etc.

```
int cyusb_get_config_descriptor_by_value(cyusb_handle *h, unsigned char bConfigurationValue, struct libusb_config_descriptor **config);
```

10. Doing Data Transfers, after obtaining the handle:

```
int cyusb_control_transfer (cyusb_handle *h, unsigned char bmRequestType, unsigned char bRequest, unsigned short wValue, unsigned short wIndex, unsigned char *data, unsigned short wLength, unsigned int timeout);
```

```
int cyusb_bulk_transfer(cyusb_handle *h, unsigned char endpoint, unsigned char *data, int length, int *transferred, int timeout);
```

int cyusb interrupt transfer(cyusb handle *h, unsigned char endpoint,



-

unsigned char *data, int length, int *transferred, unsigned int timeout);

These translate directly into libusb commands and hence you are requested to look into the libusb library for more details.

Note: The Library does not provide an interface for Isochronous data transfer. The libusb APIs can be directly used to perform data transfers on isochronous endpoints. Please refer to the sample code in 09_cyusb_performance.cpp for an example of how to do this.

Using the library - Detailed Function Documentation

Structure Documentation /* Opaque object from libusb */ typedef struct libusb device cyusb device; typedef struct libusb device handle cyusb handle; /* Opaque object from libusb */ struct cydev { *dev: /* as above ... */ cyusb device cyusb handle /* as above ... */ *handle; unsigned short /* Vendor ID */ vid; unsigned short /* Product ID */ pid; unsigned char /* When device is opened, val = 1 */ is open; /* The bus number of this device */ unsigned char busnum; unsigned char devaddr; /* The device address /* Padding to make struct = 16 bytes */ unsigned char filler; **}**;

The above structure gets populated (as an array) when the library is opened using the cyusb_open() call or the overloaded function cyusb_open(unsigned short vid, unsigned short pid); The array would contain only 'devices of interest' i.e if the device is mentioned in the configuration file /etc/cyusb.conf.

Function Documentation

Prototype : int cyusb open(void);

Description : This initializes the underlying libusb library, populates the cydev[] array, and

returns the number of devices of interest detected. A 'device of interest' is a

device which appears in the /etc/cyusb.conf file.

Parameters : None

Return Value: Returns an integer, equal to number of devices of interest detected.

Prototype : int cyusb open(unsigned short vid, unsigned short pid);

Description : This is an overloaded function that populates the cydev[] array with just one

device that matches the provided vendor ID and Product ID.

Parameters : unsigned short vid : Vendor ID

unsigned short pid: Product ID

Return Value: Returns 1 if a device of interest exists, else returns 0. This function is only

useful if you know in advance that there is only 1 device with the given VID

and PID attached to the host system.



Prototype : cyusb_handle * cyusb_gethandle(int index);

Description : This function returns a libusb device handle given an index from the

cydev[] array.

Parameters : int index : Equal to the index in the cydev[] array that gets populated during

the cyusb open() call described above.

Return Value: Returns the pointer to a struct of type cyusb handle, also called as

libusb device handle.

Prototype : unsigned short cyusb getvendor(cyusb handle *);

Description : This function returns a 16-bit value corresponding to the vendor ID given a

device's handle.

Parameters : cyusb_handle *handle : Pointer to a struct of type cyusb_handle.

Return Value: Returns the 16-bit unique vendor ID of the given device.

Prototype : unsigned short cyusb getproduct(cyusb handle *);

Description : This function returns a 16-bit value corresponding to the device ID given a

device's handle.

Parameters : cyusb_handle *handle : Pointer to a struct of type cyusb_handle.

Return Value : Returns the 16-bit product ID of the given device.

Prototype : **void cyusb_close(void)**;

Description : This function closes the libusb library and releases memory allocated to

cydev[].

Parameters : none. Return Value : none.

Prototype : int cyusb get busnumber(cyusb handle * handle);

Description : This function returns the Bus Number pertaining to a given device handle

Parameters : cyusb handle *handle : The libusb device handle

Return Value : An integer value corresponding to the Bus Number on which the device

resides. This is also the same value present in the cydev[] array.

Prototype : int cyusb get devaddr(cyusb handle * handle);

Description : This function returns the device address pertaining to a given device handle

Parameters : cyusb handle *handle : The libusb device handle

Return Value: An integer value corresponding to the device address (between 1 to 127).

This is also the same value present in the cydev[] array.

Prototype : int cyusb_get_max_packet_size(cyusb_handle * handle,

unsigned char endpoint);

Description : This function returns the max packet size that an endpoint can handle,

without taking into account high-bandwidth capability. It is therefore only

useful for Bulk, not Isochronous endpoints.

Parameters : cyusb_handle *handle : The libusb device handle

unsigned char endpoint : The endpoint number



Return Value: An integer value corresponding to the max packet size capable of being

handled by that endpoint.

Prototype : int cyusb get max iso packet size(cyusb handle * handle,

unsigned char endpoint);

Description : This function returns the max packet size that an isochronous endpoint can

handle, after considering multiple transactions per microframe if present.

Parameters : cyusb handle *handle : The libusb device handle

unsigned char endpoint : The endpoint number

Return Value: An integer value corresponding to the max packet size capable of being

handled by that isochronous endpoint.

Prototype : int cyusb_get_configuration(cyusb_handle * handle,

int *config);

Description : This function determines the bConfiguration value of the active

configuration.

Parameters : cyusb handle *handle: The libusb device handle

int * config : Address of an integer variable that will store the

currently active configuration number.

Return Value : 0 on success, or an appropriate LIBUSB_ERROR

Prototype : int cyusb_set_configuration(cyusb_handle * handle,

int config);

Description : This function sets the device's active configuration (standard request).

Parameters : cyusb handle *handle : The libusb device handle

int config : Configuration number required to be made active.

Return Value: 0 on success, or an appropriate LIBUSB ERROR

Prototype : int cyusb claim interface(cyusb handle * handle,

int interface);

Description : This function claims an interface for a given device handle.

You must claim an interface before performing I/O operations on the device.

Parameters : cyusb handle *handle : The libusb device handle

int interface : The bInterfaceNumber of the interface you wish to

claim.

Return Value: 0 on success, or an appropriate LIBUSB_ERROR

Prototype : int cyusb claim interface(cyusb handle * handle,

int interface);

Description : This function claims an interface for a given device handle.

You must claim an interface before performing I/O operations on the device.

Parameters : cyusb handle *handle : The libusb device handle

int interface : The bInterfaceNumber of the interface you wish to

claim.

Return Value : 0 on success, or an appropriate LIBUSB_ERROR



Prototype : int cyusb release interface(cyusb handle * handle,

int interface);

Description : This function releases an interface previously claimed for a given device

handle.

You must release all claimed interfaces before closing a device handle. This is a blocking function, where a standard SET_INTERFACE control request is sent to the device, resetting interface state to the first alternate

setting.

Parameters : cyusb handle *handle: The libusb device handle

int interface : The bInterfaceNumber of the interface you wish to

release

Return Value: 0 on success, or an appropriate LIBUSB ERROR

Prototype : int cyusb_set_interface_alt_setting(cyusb_handle * handle,

int interface,
int altsetting);

Description : This function activates an alternate setting for an interface.

The interface itself must have been previously claimed using

cyusb claim interface. This is a blocking funcion, where a standard control

request is sent to the device.

Parameters : cyusb handle *handle: The libusb device handle

int interface : The bInterfaceNumber of the interface you wish to

set.

int altsetting : The bAlternateSetting number to activate

Return Value: 0 on success, or an appropriate LIBUSB ERROR

Prototype : int cyusb_clear_halt(cyusb_handle * handle,

unsigned char endpoint);

Description : This function clears a halt condition on an endpoint.

Endpoints with a halt condition are unable to send/receive data unless the

condition is specifically cleared by the Host.

This is a blocking function.

Parameters : cyusb handle *handle : The libusb device handle

unsigned char endpoint : The endpoint for which the clear request is

sent.

Return Value: 0 on success, or an appropriate LIBUSB ERROR



Prototype : int cyusb_reset_device(cyusb_handle * handle);
Description : This function performs a USB port reset to the device.

This is a blocking funcion.

Parameters : cyusb_handle *handle : The libusb device handle Return Value : 0 on success, or an appropriate LIBUSB ERROR

Prototype : int cyusb kernel driver active(cyusb handle * handle,

int interface);

Description

This function returns whether a kernel driver has already claimed an

interface.

If a kernel driver is active and has claimed an interface, cyusb cannot

perform I/O operations on that interface unless the interface is first released.

Parameters : cyusb_handle *handle: The libusb device handle

int interface : The interface which you are testing.

Return Value : 0 if no kernel driver is active, 1 if a kernel driver IS active or an appropriate

error.

Prototype : int cyusb_detach_kernel_driver(cyusb_handle * handle,

int interface);

Description : This function detaches a kernel mode driver (in order for cyusb to claim the

interface)

If a kernel driver is active and has claimed an interface, cyusb cannot

perform I/O operations on that interface unless the interface is first released.

Parameters : cyusb handle *handle: The libusb device handle

int interface : The interface which you want to be detached.

Return Value: 0 on success, or an appropriate LIBUSB ERROR.

Prototype : int cyusb attach kernel driver(cyusb handle * handle,

int interface);

Description : This function reattaches a kernel mode driver which was previously detached

Parameters : cyusb handle *handle : The libusb device handle

int interface : The interface which you want to be reattached.

Return Value: 0 on success, or an appropriate LIBUSB ERROR.

Prototype : int cyusb get device descriptot(cyusb handle * handle,

struct libusb device descriptor *);

Description : This function returns the usb device descriptor for the given device.

Parameters : cyusb handle *handle : The libusb device handle

struct libusb device descriptor *desc: Address of a device desc structure

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Return Value: 0 on success, or an appropriate LIBUSB ERROR. The

libusb device descriptor structure will contain detailed information if

success.

Prototype : int cyusb get active config descriptor(cyusb handle * handle,

struct libusb_config_descriptor **);

Description : This function returns the usb configuration descriptor for the given device.

Only valid if return value was 0.

Must be freed with cyusb free config descriptor() explained below.

Parameters : cyusb handle *handle : The libusb device handle

struct libusb_configuration_descriptor **desc: Address of a

config_descriptor

Return Value: 0 on success, or an appropriate LIBUSB ERROR.

The libusb config descriptor structure will contain detailed information if

success.

Prototype : int cyusb get config descriptor(cyusb handle * handle,

unsigned char index,

struct libusb config descriptor **);

Description : This function returns the usb configuration descriptor for the given device.

Only valid if return value was 0.

Must be freed with cyusb free config descriptor() explained below.

Parameters : cyusb handle *handle : The libusb device handle

unsigned char index : Index of configuration you wish to retrieve.

struct libusb configuration descriptor **desc : Address of a

config descriptor

Return Value: 0 on success, or an appropriate LIBUSB_ERROR.

The libusb_config_descriptor structure will contain detailed information if

success.

Prototype : void cyusb free config descriptor(

struct libusb_config_descriptor *);

Description : Frees the configuration descriptor obtained earlier.

Parameters : struct libusb config descriptor * : The config descriptor you wish to free.

Return Value: NIL.

Prototype : void cyusb_control_transfer(cyusb_handle *h,

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unsigned char bmRequestType,

unsigned char bRequest,

unsigned short wValue,

unsigned short wIndex,

unsigned char *data,

unsigned short wLength,

unsigned int timeout);

Description : Performs a USB Control Transfer.

Parameters : cyusb_handle *h : Device handle

unsigned char bmRequestType: The request type field for the setup packet

unsigned char bRequest : The request field of the setup packet

unsigned short wValue : The value field of the setup packet

unsigned short wIndex : The index field of the setup packet

unsigned char *data : Data Buffer (for input or output)

unsigned short wLength : The length field of the setup packet

The data buffer must be at least this size.

unsigned int timeout : Timeout in milliseconds.

For unlimited timeout, use 0.

Return Value: Number of bytes transferred on success, or an appropriate LIBUSB ERROR.

Prototype : void cyusb bulk transfer(cyusb handle *h,

unsigned char endpoint,

unsigned char *data,

int length,

int *transferred,

int timeout);

Description : Performs a USB Bulk Transfer.

Parameters : cyusb handle *h : Device handle

unsigned char endpoint : Address of endpoint to communicate with

unsigned char *data : Data Buffer (for input or output)

unsigned short wLength : The length field of the data buffer for read or

write

int * transferred : Output location of bytes actually transferred



unsigned int timeout : Timeout in milliseconds.

For unlimited timeout, use 0.

Return Value: 0 on success, or an appropriate LIBUSB_ERROR.

Prototype : void cyusb download fx2 (cyusb handle *handle, char *filepath,

char vendor command);

Description : Downloads firmware on to Fx2 device.

Parameters : cyusb handle *handle: Device handle

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filepath : Path for the FX2 firmware file.

vendor command : Vendor command specifying where to load the

firmware. This normally needs to be 0xA0 as

firmware is loaded to RAM.

Return Value: 0 on success or an appropriate LIBUSB_ERROR

Prototype : void cyusb download fx3(cyusb handle *handle, char *filepath);

Description : Downloads the firmware on to fx3 device

Parameters : cyusb_handle *handle: Device handle

filepath : Path for the FX3 firmware file.

Return Value: 0 on success or an appropriate LIBUSB_ERROR