

Assignment Four

Nicholas Fiore

Nicholas.Fiore@Marist.edu

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1 GRAPHS

1.1 GRAPHING

Graphs are a data structure with varying uses. Its topology is useful for representations of networks, maps, or similar diagrams. Additionally, they can be useful for various data sets which have elements with multiple dependencies.

Graphs are akin to linked list and other similar data structures in the way that they function with node-like objects that are then linked to other node-like objects. The largest difference that separates it from lists and trees is the way that these nodes, called vertices in graphs, can connect to each other. With lists, there is a single connection from the parent and a single connection to the child. Trees are similar, but can have multiple "child" vertices. In graphs, however, vertices are not limited to the child and parent relationship. A vertex from any part of the graph can connect to any other vertex within the graph, regardless of what vertices it might already be attached to. This can create the more 3D structure of a graph, including things like loops which aren't possible on a tree (otherwise I wouldn't be a tree, it would be a graph).

Graphing in this assignment was implemented in a simple way. A *Vertex* class was created, holding an integer id, a boolean to check if it was processed, and an ArrayList of Vertex objects to represent neighboring vertices. For simplicity, *Vertex* objects that hold each other in their *neighbors* table are considered to have an edge between them. A *Graph* class was also created to represent a physical graph, composed of many Vertex objects. The *Graph* object holds an ArrayList of all the *Vertex* objects within the graph and a name. There is also a String 2D array to be used for matrix printing, which will be touched on later. There are a few methods to this that allow it to function, including *addVertex()* and *addEdge()*, but also things such as *printMatrix()* and *printAdjacencyList()*, which print matrix and adjacency list representations of the graph, respectively.

1.2 BREADTH-FIRST AND DEPTH-FIRST SEARCHING/TRAVERSAL

Linked lists and trees can be pretty easily traversed linearly, as there is only a forward and sometimes backwards to move. Graphs, however, are more complicated, as they can contain loops that make linearly searching impossible due to infinite looping potential. Therefore, there needs to be a way to keep track of

which vertices in the graph have already been considered. Breadth-first and depth-first searching are the two ways that these are done.

The ideas of breadth-first (BFS) and depth-first searching (DFS) are sort of opposite ways to achieve the same concept, which is to search or traverse a graph (or a tree, which these methods can also be implemented for, because a tree is technically a graph). Both BFS and DFS utilize the *processed* boolean in the *Vertex* objects to keep track of which ones in the graph have already been processed.

1.2.1 BREADTH-FIRST

Breadth-first works based on the idea of finding and printing out all the adjacent vertices to the initial vertex, and then finding all the adjacent vertices of those vertices and printing the ones ***not yet processed***, repeating this process until all of the vertices in the graph have been processed. This is done by adding each vertex found as an adjacency to a Queue. As adjacencies are found, they are added to the Queue. Once no more adjacencies are found for the current node, the vertex at the front of the Queue is dequeued and printed, and its adjacencies are found, adding them to the Queue so long as they have not been processed already.

Breadth-first searching has an asymptomatic run-time that is a bit different from traditional Big-Oh classifications. Its runtime is considered to be $O(|V| + |E|)$, V being the total number of vertices in the graph and E being the total number of edges. This is due to the fact that every vertex and every edge will only ever be checked once, due to the nature of the processing. Simplifying this into more formal Big-Oh classes would make this a $O(n)$.

1.2.2 DEPTH-FIRST

Depth-first searching takes the idea of breadth-first but works in the opposite direction. Instead of looking for the close adjacencies, it moves towards finding the furthest it can go by taking a single path and never repeating vertices. This is handled through a recursive function. It takes in a vertex and then prints that vertex and sets its *processed* boolean to *true*. Then it enters a for loop that iterates through all the neighbors of the current vertex. If the neighbor vertex it currently is looking at is not currently processed (*processed* is set to false), it will call the *depthFirstSearch()* function with that neighbor vertex, repeating the process. This will happen recursively until every vertex that is connected in that loop or line is printed. As the recursive calls collapse again, any neighboring vertices that are not part of the branch or loop that had been printed already will be entered then, completely printing that branch/loop before collapsing again, until all connected vertices to the original starting vertex has been printed.

Like breadth-first searching, depth-first searching has a run-time of $O(|V| + |E|)$. This is for the same reason that it is in BFS: every edge and every vertex is checked only once. Simplified, this again gives the algorithm a run-time of $O(n)$.

1.3 BINARY TREES

Trees are a sort of data structure that are similar to linked lists, but instead of only having one next value, they can have multiple. The number of "children" that a Node in a tree can have depends on the type of tree. In the case of binary trees, any Node can have 0, 1, or 2 children. Any more and the tree is no longer binary. This type of tree is binary because traversing the tree will always present two options to go, if there is anything else in either direction (the lack of an option is technically not a lack of choice but rather a forced choice). When putting a list of items into a binary tree, the general distribution of the items in the list will create something close to a balanced tree, which is a tree in which the left and right subtree of any particular tree has a height difference of no more than one level. This includes all subtrees of said original tree.

Due to the nature of the binary tree, searching the tree becomes very similar to the binary search algorithm used with normal arrays or lists. The algorithm itself looks similar to a linear search, however, each time a

Node is compared to the key, the algorithm will choose a branch to take. With a properly balanced binary tree, taking a branch will cause roughly half of the other options in the tree to be eliminated. This happens every single time, halving continuously until the item is found or an end of the tree is reached. For this reason, with a balanced binary tree, the asymptomatic run-time for a binary search tree is the same as a binary search, standing at $O(\log(n))$. One of the benefits of a BST over normal binary search is that a BST does not need a sorted list to function (and actually prefers it not to be sorted), and therefore does not require the overhead of a sorting function.

As a caveat, however, poorly balanced binary tree can cause the run-time to degrade. The worst case scenario for this would be entering a sorted list into the binary tree. Since it is already sorted, the tree will always choose one option when placing the next element, causing a single, very long branch that always only has one child. In this worst case, the run-time of the algorithm degrades to $O(n)$ as the long branch is little more than a glorified linked list.

2 APPENDIX

2.1 VERTEX.JAVA

```
1 import java.util.ArrayList;
2
3 public class Vertex {
4     /* Data Fields */
5     private int id;
6     private boolean processed = false;
7     private ArrayList<Vertex> neighbors = new ArrayList<Vertex>();
8
9     /* Constructors */
10    public Vertex() {
11        //default empty constructor
12    }
13
14    //constructor with ID parameter
15    public Vertex(int idNum) {
16        this.id = idNum;
17        this.processed = false;
18    }
19
20    /* Accessors/Mutators */
21    public int getId() {
22        return this.id;
23    }
24
25    public Vertex getNeighbor(int index) {
26        return neighbors.get(index);
27    }
28
29    public int getNeighborSize() {
30        return neighbors.size();
31    }
32
33    public boolean wasProcessed() {
34        return this.processed;
35    }
36
37    public void setId(int newId) {
38        this.id = newId;
39    }
40
41    public void setProcessed(boolean bool) {
42        this.processed = bool;
43    }
44
45    /* Functions */
46    //adds an adjacent vertex as a neighbor to the neighbors ArrayList
47    public void addNeighbor(Vertex neighbor) {
48        this.neighbors.add(neighbor);
49    }
50 }
```

2.2 GRAPH.JAVA

```
1 import java.util.*;
2
3 public class Graph {
4     /* Data Fields */
5     private String name = "";
6     private ArrayList<Vertex> verticies = new ArrayList<Vertex>();
7 }
```

```

7   private String[][] matrix;
8
9   /* Constructors */
10  //Default, empty constructor
11  public Graph() {
12
13  }
14
15  //constructor with name parameter
16  public Graph(String newName) {
17      this.name = newName;
18  }
19
20  /* Accesors/Mutators */
21  public String getName() {
22      return this.name;
23  }
24
25  public ArrayList<Vertex> getVertices() {
26      return vertices;
27  }
28
29  public void setName(String newName) {
30      this.name = newName;
31  }
32
33  /* Functions */
34  //Adds a vertex to the vertices ArrayList
35  public void addVertex(Vertex vert) {
36      this.vertices.add(vert);
37  }
38  //Adds an edge between two vertices by adding each vertex to the other's list of neighbors
39  public void addEdge(Vertex vert1, Vertex vert2) {
40      vert1.addNeighbor(vert2);
41      vert2.addNeighbor(vert1);
42  }
43
44  //Performs a depth-first search of the graph
45  public void depthFirstSearch(Vertex vert) {
46      if (!vert.wasProcessed()) {
47          System.out.print(vert.getId() + "_");
48          vert.setProcessed(true);
49      }
50      for (int i = 0; i < vert.getNeighborSize(); i++) {
51          Vertex neighbor = vert.getNeighbor(i);
52          if (!neighbor.wasProcessed()) {
53              depthFirstSearch(neighbor);
54          }
55      }
56  }
57
58  //Performs a breadth-first search of the graph
59  public void breadthFirstSearch(Vertex vert) {
60      System.out.print("Breadth-First_Traversal:_");
61      VertQueue searchQueue = new VertQueue();
62      searchQueue.enqueue(new VertNode(vert));
63      vert.setProcessed(true);
64      while (!searchQueue.isEmpty()) {
65          Vertex currVert = searchQueue.dequeue().getMyVertex();
66          System.out.print(currVert.getId() + "_");
67          for (int i = 0; i < currVert.getNeighborSize(); i++) {
68              Vertex neighbor = currVert.getNeighbor(i);
69              if (!neighbor.wasProcessed()) {
70                  searchQueue.enqueue(new VertNode(neighbor));
71                  neighbor.setProcessed(true);

```

```

72     }
73 }
74 }
75 System.out.println();
76 }
77
78 //resets the "processed" status on all vertices in a graph.
79 public void resetProcessing() {
80     for (int i = 0; i < vertices.size(); i++) {
81         vertices.get(i).setProcessed(false);
82     }
83 }
84
85 //Prints the maxtrix representation of the graph
86 public void printMatrix() {
87     int size = vertices.size();
88     int i, j;
89     matrix = new String[size + 1][size + 1];
90     matrix[0][0] = "_";
91     //creates the "labels" of the matrix
92     for (i = 0; i < matrix.length - 1; i++) {
93         matrix[i + 1][0] = vertices.get(i).getId() + "";
94         matrix[0][i + 1] = vertices.get(i).getId() + "";
95     }
96
97     //initializes the matrix to have no adjacencies, marked with a period
98     for (i = 1; i < matrix.length; i++) {
99         for (j = 1; j < matrix[0].length; j++) {
100             matrix[i][j] = ".";
101         }
102     }
103
104     //adds all adjacencies to the matrix, marked by a 1
105     for (i = 0; i < vertices.size(); i++) {
106         Vertex vert = vertices.get(i);
107         for (j = 0; j < vert.getNeighborSize(); j++) {
108             Vertex neighbor = vert.getNeighbor(j);
109             int vertIndex = Search.linearSearchReturnIndex(vertices, vert.getId());
110             int neighborIndex = Search.linearSearchReturnIndex(vertices, neighbor.getId());
111
112             matrix[vertIndex + 1][neighborIndex + 1] = "1";
113             matrix[neighborIndex + 1][vertIndex + 1] = "1";
114         }
115     }
116
117     //prints the matrix
118     for (i = 0; i < matrix.length; i++) {
119         for (j = 0; j < matrix[0].length; j++) {
120             System.out.print(matrix[i][j] + "_");
121         }
122         System.out.println();
123     }
124
125     System.out.println();
126 }
127
128
129 public void printAdjacencyList() {
130     System.out.println("Adjacency_List");
131     for (int i = 0; i < vertices.size(); i++) {
132         Vertex vert = vertices.get(i);
133         System.out.print("[ " + vert.getId() + " ]_");
134         for (int j = 0; j < vert.getNeighborSize(); j++) {
135             System.out.print(vert.getNeighbor(j).getId() + "_");
136         }

```

```

137         System.out.println();
138     }
139     System.out.println();
140 }
141 }

```

Graph and Vertex also utilize slightly modified Queue and Node class (VertQueue and VertNode), however the modifications are only to the datatype so I didn't bother adding them here.

2.3 TREENODE.JAVA

```

1  /*
2  * The Node class is used to created linked lists of objects in order to more variably control the
3  size of said list without being locked into an array
4  * This is a modified version of the Node class to be used to construct binary trees.
5  */
6  public class TreeNode {
7      /* Data Fields */
8      private String myString = "";
9      private TreeNode myParent = null;
10     private TreeNode myLeft = null;
11     private TreeNode myRight = null;
12
13     /* Constructors */
14     //No-arg (default) constructor for creating a default Node object
15     public TreeNode() {}
16
17     //Partial constructor for initializing only the Item within the Node
18     public TreeNode(String str) {
19         myString = str;
20     }
21
22     //Full constructor for creating a Node object and assigning an character name and next Node
23     object pointer for left and right
24     public TreeNode(String str, TreeNode left, TreeNode right) {
25         myString = str;
26         myLeft = left;
27         myRight = right;
28     }
29
30     /* Accessors and Mutators */
31     //Returns the character String of the Node object
32     public String getMyString() {
33         return myString;
34     }
35
36     public TreeNode getMyParent() {
37         return myParent;
38     }
39
40     //Returns the pointer for the next Node object to the left
41     public TreeNode getMyLeft() {
42         return myLeft;
43     }
44
45     //Returns the pointer for the next Node object to the right
46     public TreeNode getMyRight() {
47         return myRight;
48     }
49
50     //Changes the value of the character String of a Node object to a new String
51     public void setMyString(String myString) {
52         this.myString = myString;

```

```

51     }
52
53     public void setMyParent(TreeNode myParent) {
54         this.myParent = myParent;
55     }
56
57     //Changes the pointer of the left pointer of a Node object to a new pointer to a node Object (
58     or NULL)
59     public void setMyLeft(TreeNode myLeft) {
60         this.myLeft = myLeft;
61     }
62
63     //Changes the pointer of the right pointer of a Node object to a new pointer to a node Object
64     (or NULL)
65     public void setMyRight(TreeNode myRight) {
66         this.myRight = myRight;
67     }
68
69     /* Functions */
70     //Checks to see if the Node object has a myLeft or myRight value != null. Returns boolean
71     depending on result.
72     public boolean hasLeft() {
73         if (this.getMyLeft() != null)
74             return true;
75         else
76             return false;
77     }
78
79     public boolean hasRight() {
80         if (this.getMyRight() != null)
81             return true;
82         else
83             return false;
84     }
85 }

```

2.4 TREE.JAVA

```

1 public class Tree {
2     /* Data Field */
3     private TreeNode myRoot;
4
5     /* Constructors */
6     //empty default constructor
7     public Tree() {
8
9     }
10    //constructor for starting with the root node
11    public Tree(TreeNode root) {
12        myRoot = root;
13    }
14
15    /* Accessor/Mutator */
16    public TreeNode getMyRoot() {
17        return this.myRoot;
18    }
19
20    public void setMyRoot(TreeNode myRoot) {
21        this.myRoot = myRoot;
22    }
23
24    /* Functions */

```



```

25 public void insert(TreeNode newNode) {
26     TreeNode trailing = null;
27     TreeNode current = this.myRoot;
28     System.out.print("Inserting_" + newNode.getMyString() + ":_");
29     while (current != null) {
30         trailing = current;
31         if ((newNode.getMyString().toUpperCase()).compareTo(current.getMyString().toUpperCase()) < 0) {
32             current = current.getMyLeft();
33             System.out.print("L");
34         }
35         else { //must be >=
36             current = current.getMyRight();
37             System.out.print("R");
38         }
39         System.out.print("_");
40     }
41     newNode.setMyParent(trailing);
42     if (trailing != null) {
43         if ((newNode.getMyString().toUpperCase()).compareTo(trailing.getMyString().toUpperCase()) < 0) {
44             trailing.setMyLeft(newNode);
45         }
46         else { // >=
47             trailing.setMyRight(newNode);
48         }
49     }
50     else {
51         this.setMyRoot(newNode);
52         System.out.print("Root.");
53     }
54     System.out.println();
55 }
56 }

```

2.5 SEARCH.JAVA

Mostly just the addition of *searchBinaryTree()*.

```

1 import java.util.ArrayList;
2 /*
3  * A class used to maintain static methods for searching algorithms (namely linear search and
4  * binary search). Linear search is iterative,
5  * while binary search is recursive.
6  */
7 public class Search {
8     //sequentially searches the list for the key, returning the index of where it was found. If it
9     //was not found, returns -1.
10    public static int linearSearch(String[] arr, String key, int[] counter) {
11        int i = 0;
12        while (i < arr.length && arr[i] != key) {
13            i++;
14            counter[0]++;
15        }
16        if (i >= arr.length)
17            i = -1;
18        return i;
19    }
20    //sequentially searches the list for the key, returning the vertex with that value. Version
21    //for ArrayLists.
22    public static Vertex linearSearchReturnVertex(ArrayList<Vertex> list, int key) {

```

```

22     int i = 0;
23     while (i < list.size() && list.get(i).getId() != key) {
24         i++;
25     }
26     if (i >= list.size())
27         i = -1;
28     return list.get(i);
29 }
30
31 //sequentially searches the list for the key, returning the index of where it was found. If it
    was not found, returns -1. version for ArrayLists
32 public static int linearSearchReturnIndex(ArrayList<Vertex> list, int key) {
33     int i = 0;
34     while (i < list.size() && list.get(i).getId() != key) {
35         i++;
36     }
37     if (i >= list.size())
38         i = -1;
39     return i;
40 }
41
42 //recursively searches the list by comparing the key to the item at the middle of the list,
    then choosing half of the array to
43 //then search depending on whether the key is lesser or greater than the element at the middle
44 . If the element is found, returns
45 //the index, otherwise returns -1.
46 public static int binarySearch(String[] arr, int startIndex, int endIndex, String key, int[]
    counter) {
47     int retVal;
48     int midIndex = (endIndex + startIndex) / 2;
49     if (startIndex > endIndex) {
50         retVal = -1;
51     } else if (key.toUpperCase().compareTo(arr[midIndex].toUpperCase()) == 0) {
52         counter[0]++;
53         retVal = midIndex;
54     } else if (key.toUpperCase().compareTo(arr[midIndex].toUpperCase()) < 0) {
55         counter[0]++;
56         retVal = binarySearch(arr, startIndex, midIndex - 1, key, counter);
57     } else {
58         counter[0]++;
59         retVal = binarySearch(arr, midIndex + 1, endIndex, key, counter);
60     }
61     return retVal;
62 }
63
64 public static int binarySearchIt(String[] arr, int startIndex, int endIndex, String key, int[]
    counter) {
65     int low = startIndex;
66     int high = (endIndex) - startIndex;
67     while (low < high) {
68         int mid = (low + high) / 2;
69         if (key.compareTo(arr[mid]) <= 0) {
70             high = mid;
71         } else {
72             low = mid + 1;
73         }
74         counter[0]++;
75     }
76     return high;
77 }
78
79 //searches a binary tree based on a list of keys to compare. Functions very similarly to
    binary search due to the nature of a binary tree.
80 public static boolean searchBinaryTree(Tree bst, String key, int[] comparisons) {
    boolean retVal = false;

```

```

81     TreeNode root = bst.getMyRoot();
82     TreeNode current = root;
83     comparisons[0] = 0;
84     System.out.print("Searching_for_" + key + ":");
85     while(current != null && (current.getMyString().toUpperCase()).compareTo(key.toUpperCase())
86         ) != 0) {
87         if ((current.getMyString().toUpperCase()).compareTo(key.toUpperCase()) > 0) {
88             current = current.getMyLeft();
89             System.out.print("_L");
90             comparisons[0]++;
91         } else {
92             current = current.getMyRight();
93             System.out.print("_R");
94             comparisons[0]++;
95         }
96         System.out.print(",");
97     }
98     if (current != null && (current.getMyString().toUpperCase()).compareTo(key.toUpperCase())
99         == 0) {
100         retVal = true;
101         System.out.print("_found._");
102     } else {
103         System.out.print("_not_found._");
104     }
105     System.out.print("Comparisons_made:_ " + comparisons[0] + "\n");
106     return retVal;
107 }

```

2.6 MAINFOUR.JAVA

```

1  //Utility imports
2  import java.io.*;
3  import java.nio.file.Files;
4  import java.nio.file.Path;
5  import java.nio.file.Paths;
6
7
8  /*
9   * The purpose of this program is to explore both graphs and the ways to traverse them, as well as
10   * create a binary tree to be used for
11   * the purpose of searching, similar to a binary search.
12   */
13  public class MainFour {
14      public static void main(String[] args) throws IOException {
15          //variable to store comparisons
16          int[] compCounter = new int[1];
17
18          createGraph("graphs1.txt");
19
20
21          //array to hold all the items in the magic items list
22          String[] itemList = null;
23
24          itemList = fileToArray("magicitems.txt", itemList);
25
26          // //array to hold the list of items that will be used to search the binary tree
27          String[] searchList = null;
28
29          searchList = fileToArray("magicitems-find-in-bst.txt", searchList);
30
31          Tree binarySearchTree = createBinaryTree(itemList);

```

```

32
33     System.out.print("In-Order_Traversal:_");
34     inOrderTraversal(binarySearchTree.getMyRoot());
35     System.out.println();
36     System.out.println();
37
38     int average = searchTreeFromList(searchList, binarySearchTree, compCounter);
39
40     System.out.println("Average_#_of_comparisons:_ " + average);
41
42 }
43
44 //takes a file name and a list and puts each line of the file into a String in an array
45 public static String[] fileToArray(String fileName, String[] list) throws IOException {
46     long totalLines = 0;
47     File file = new File(fileName);
48     BufferedReader input = null;
49     try {
50         //gets the path of the current file in order to get the # of lines
51         Path path = Paths.get(file.getName());
52
53         input = new BufferedReader(new FileReader(fileName));
54
55         totalLines = Files.lines(path).count();
56
57         list = new String[(int)totalLines];
58
59         for(int i = 0; i < totalLines; i++) {
60             list[i] = input.readLine();
61         }
62
63     } catch(FileNotFoundException ex) {
64         System.out.println("Failed_to_find_file:_ " + file.getAbsolutePath());
65     } catch(IOException ex) {
66         System.out.println(ex);
67     } catch(Exception ex) {
68         System.out.println("Something_went_wrong.");
69         System.out.println(ex.getMessage());
70         ex.printStackTrace();
71     } finally {
72         if (input != null) {
73             input.close();
74         }
75     }
76
77     return list;
78 }
79
80 //takes in an array of Strings and adds the entirety of the array to a Tree, before returning
that Tree object.
81 public static Tree createBinaryTree(String[] list) {
82     Tree tree = new Tree();
83     for (int i = 0; i < list.length; i++) {
84         tree.insert(new TreeNode(list[i]));
85     }
86     System.out.println();
87     return tree;
88 }
89
90 //calls the searchBinaryTree function for every String in the tree, then computes the average
and returns it.
91 public static int searchTreeFromList(String[] list, Tree bst, int[] comparisons) {
92     int total = 0;
93     int average;
94     for (int i = 0; i < list.length; i++) {

```

```

95         Search.searchBinaryTree(bst, list[i], comparisons);
96         total += comparisons[0];
97     }
98     average = total / list.length;
99     return average;
100 }
101
102 //searches a tree using in-order traversal
103 public static void inOrderTraversal(TreeNode node) {
104     if(node == null)
105         return;
106
107     inOrderTraversal(node.getMyLeft());
108
109     System.out.print "[" + node.getMyString() + " ]_";
110
111     inOrderTraversal(node.getMyRight());
112 }
113
114
115 //Creates graphs from instructions given in a file
116 public static int createGraph(String fileName) throws IOException {
117     long totalLines = 0;
118     File file = new File(fileName);
119     BufferedReader input = null;
120     String line;
121     String nextLine;
122     try {
123         //gets the path of the current file in order to get the # of lines
124         Path path = Paths.get(file.getName());
125
126         input = new BufferedReader(new FileReader(fileName));
127
128         totalLines = Files.lines(path).count();
129
130         //instantiate variables for graph and vertex objects. There are two Vertex objects in
131         the case of adding edges.
132         Graph graph = null;
133         Vertex vert1 = null;
134         Vertex vert2 = null;
135
136         nextLine = input.readLine();
137
138         //Command parsing. Goes through each line and determines what command is being used
139         based on strings.
140         for (int i = 0; i < totalLines; i++) {
141             line = nextLine;
142             nextLine = input.readLine();
143             if (line.split("_")[0].compareTo("--") == 0) {
144                 //do nothing, ignore this line as it is a comment
145             } else if (line.split("_")[0].compareTo("new") == 0) { //new graph
146                 //create a new graph object held by the graph variable
147                 graph = new Graph();
148
149             } else if (line.split("_")[0].compareTo("add") == 0) { //enters add vertex/add
150                 edge tree
151                 if (line.split("_")[1].compareTo("vertex") == 0) { //add vertex x
152                     //adds a new vertex to the graph, parsing the ID from the line given
153                     vert1 = new Vertex(Integer.parseInt(line.split("_")[2]));
154                     graph.addVertex(vert1);
155                 } else if (line.split("_")[1].compareTo("edge") == 0) { //add edge x - y
156                     //adds a new edge to the graph, based on the IDs parsed from the line
157                     //the vertices are found by searching the graph's vertices ArrayList
158                     for a Vertex that matches the ID given in the line at both
159                     positions

```

```

155         vert1 = Search.linearSearchReturnVertex(graph.getVertices(), Integer.
156             parseInt(line.split("_")[2]));
157         vert2 = Search.linearSearchReturnVertex(graph.getVertices(), Integer.
158             parseInt(line.split("_")[4]));
159         graph.addEdge(vert1, vert2); //the vertices are now added as neighbors,
160             forming an adjacency
161     }
162     //final check to see if the next line is either empty or does not exist
163     if (nextLine == null || nextLine.isEmpty()) { //empty space; commands for this
164         graph are done, begin processing
165         graph.printMatrix();
166         graph.printAdjacencyList();
167
168         System.out.print("Depth-First_Traversal:_");
169         graph.depthFirstSearch(graph.getVertices().get(0));
170         graph.resetProcessing();
171         System.out.println();
172
173         graph.breadthFirstSearch(graph.getVertices().get(0));
174         graph.resetProcessing();
175     }
176 } catch (FileNotFoundException ex) {
177     System.out.println("Failed_to_find_file:_ " + file.getAbsolutePath());
178 } catch (IOException ex) {
179     System.out.println(ex.getMessage());
180 } catch (NullPointerException ex) {
181     System.out.println(ex.getMessage());
182 } catch (Exception ex) {
183     System.out.println("Something_went_wrong.");
184     System.out.println(ex.getMessage());
185     ex.printStackTrace();
186 } finally {
187     if (input != null) {
188         input.close();
189     }
190 }
191
192 return (int)totalLines;
193 }
194 }

```