

Ecological forecasting with dynamic GAMs

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November, 2023

“Because all decision making is based on what will happen in the future, either under the status quo or different decision alternatives, decision making ultimately depends on forecasts”

Dietze et al. 2018



Properties of ecological series

Temporal autocorrelation

Lagged effects

Non-Gaussian data and missing observations

Measurement error

Time-varying effects

Nonlinearities

Multi-series clustering

Properties of ecological series

Temporal autocorrelation

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Non-Gaussian data and missing observations

Measurement error

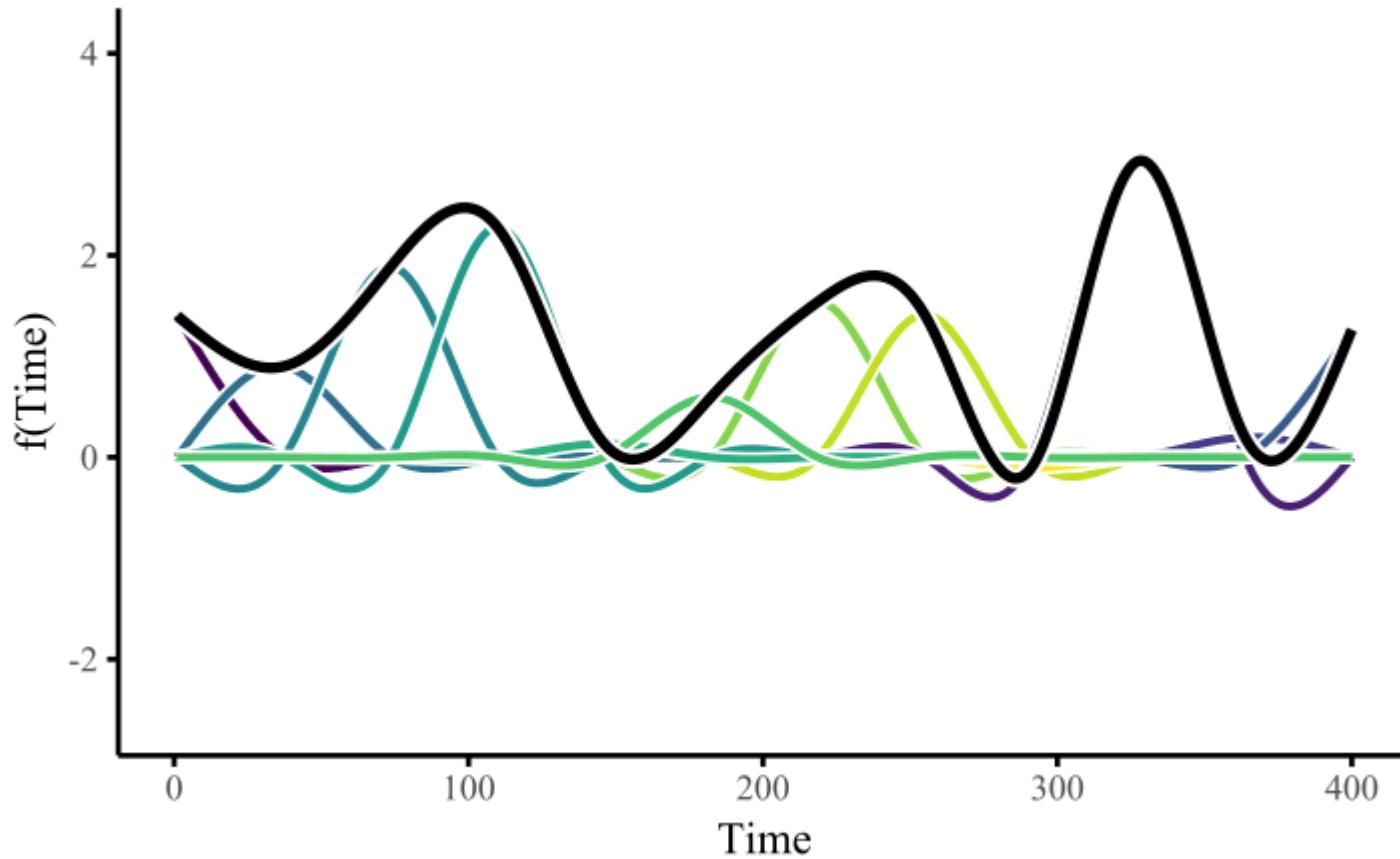
Time-varying effects

Nonlinearities

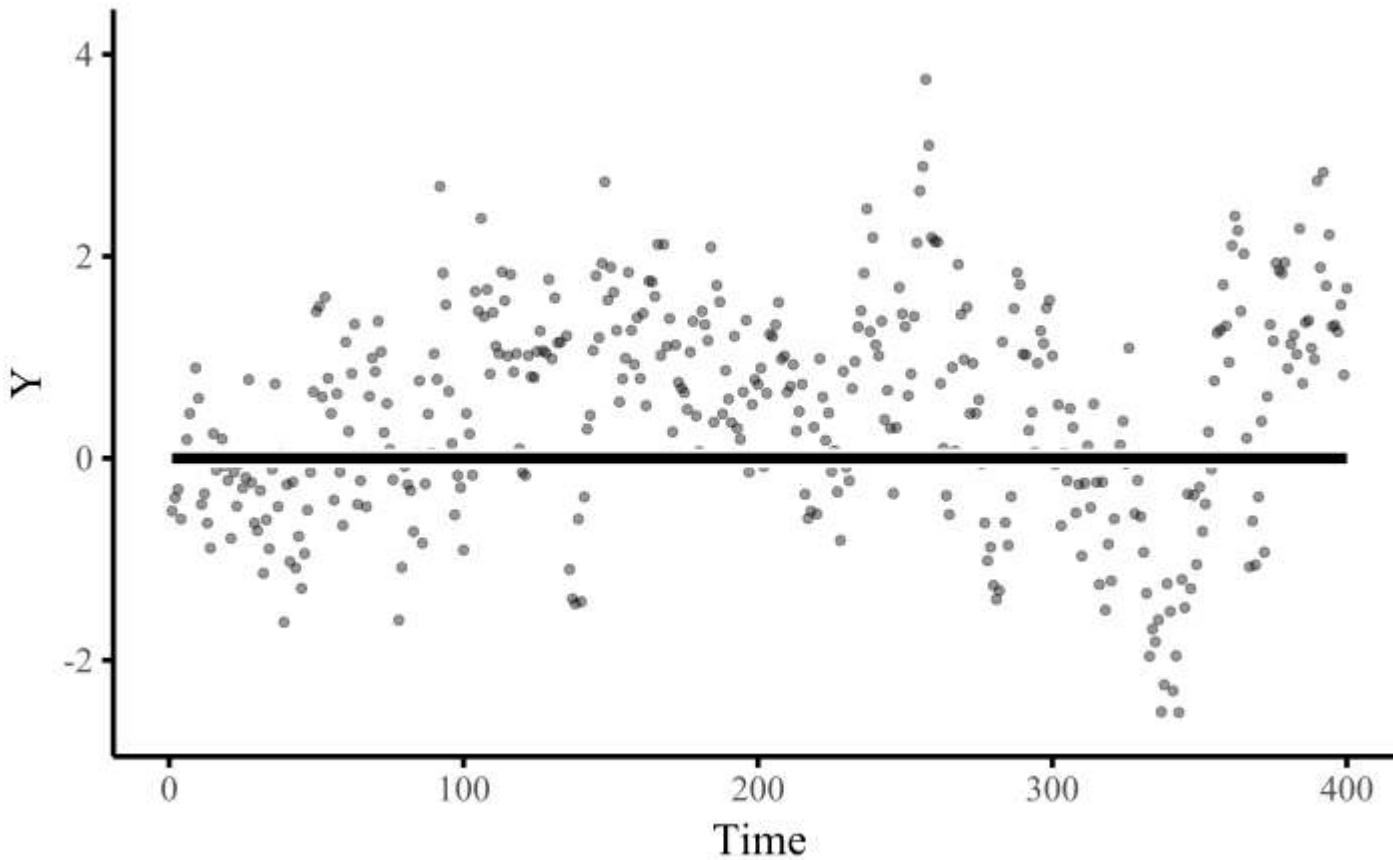
Multi-series clustering



GAMs use splines...



...penalized to fit data



Easy to fit in

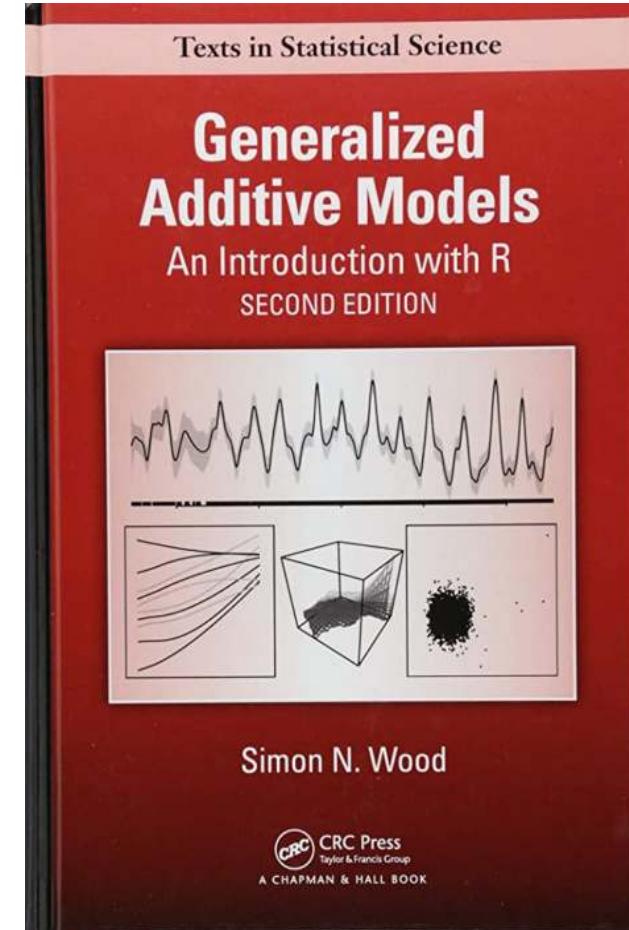
$$\mathbb{E}(Y_t | X_t) = g^{-1}(\alpha + \sum_{j=1}^J f(x_{jt}))$$

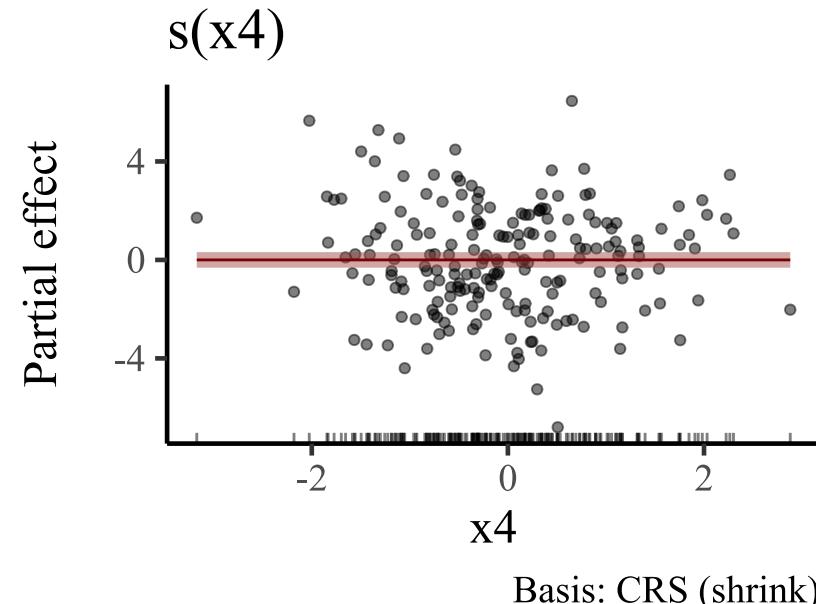
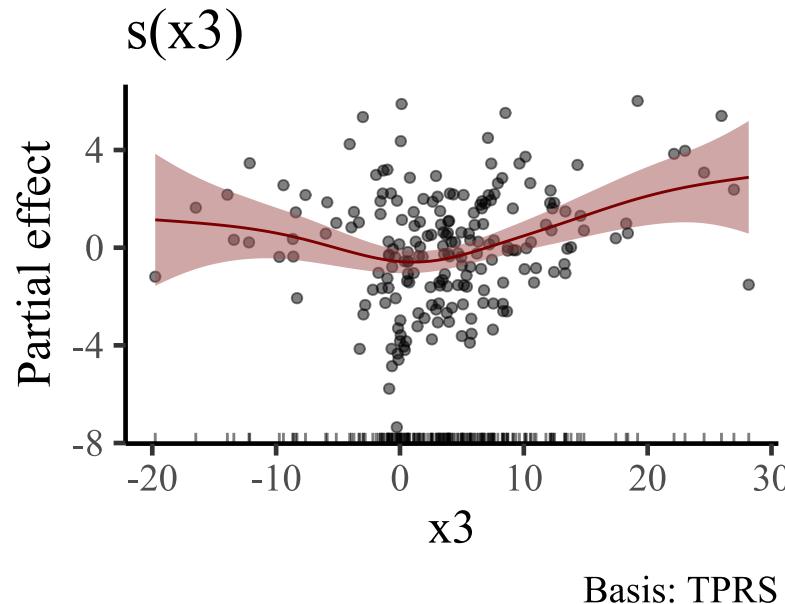
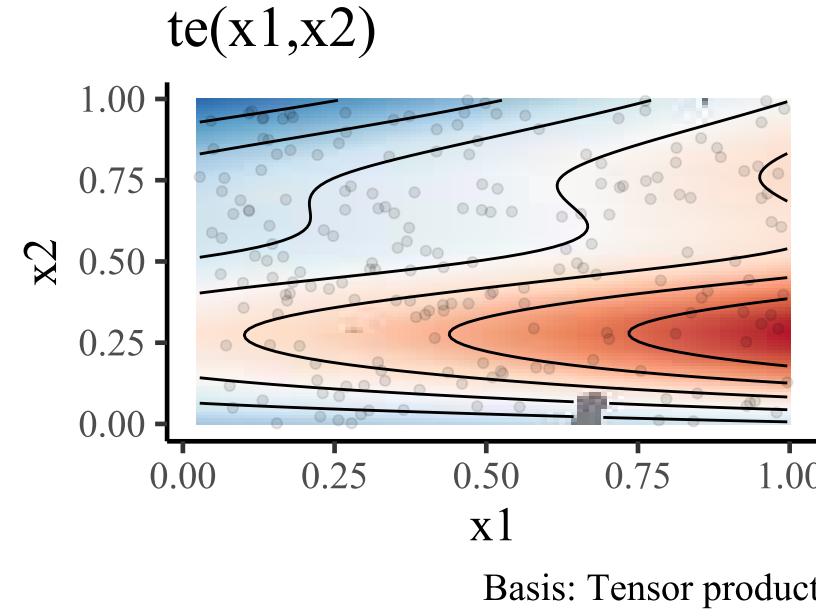
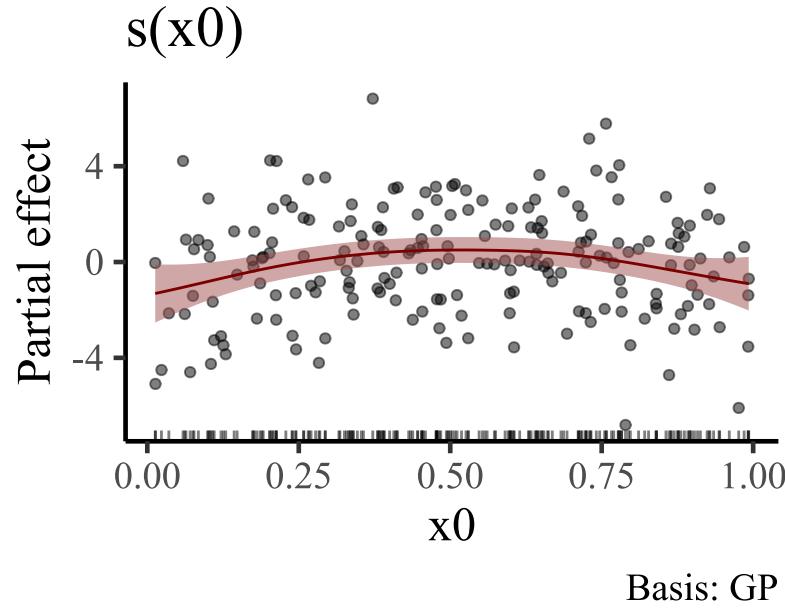
Where:

g^{-1} is the inverse of the link function

α is the intercept

$f(x)$ are potentially nonlinear functions of the J predictors





Need more on GAMs?

Gavin has you covered ☺

Generalized Additive Models with R and mgcv

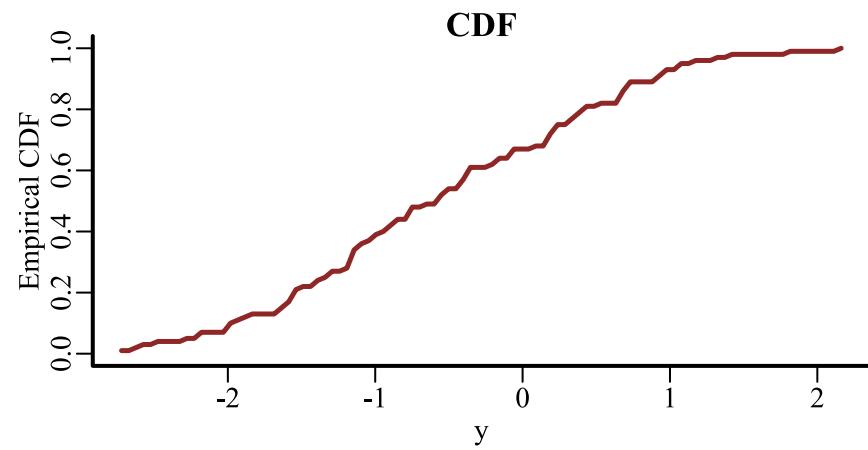
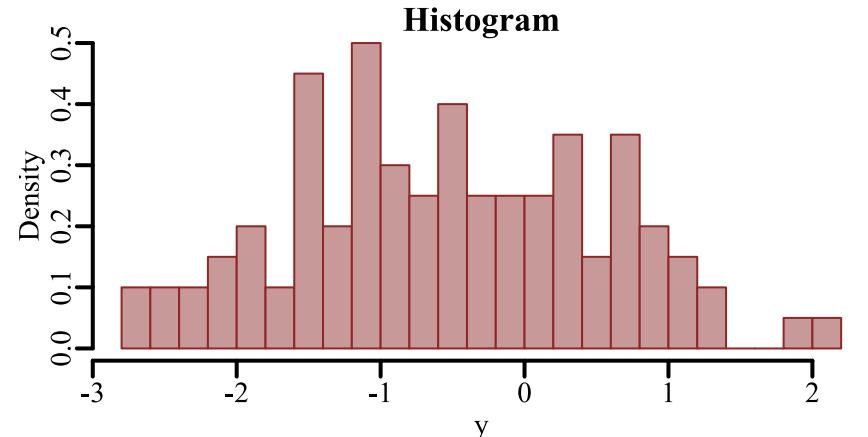
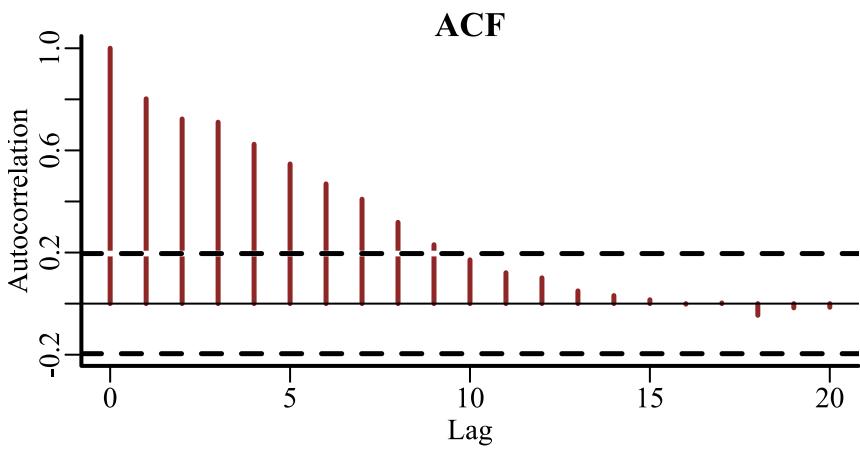
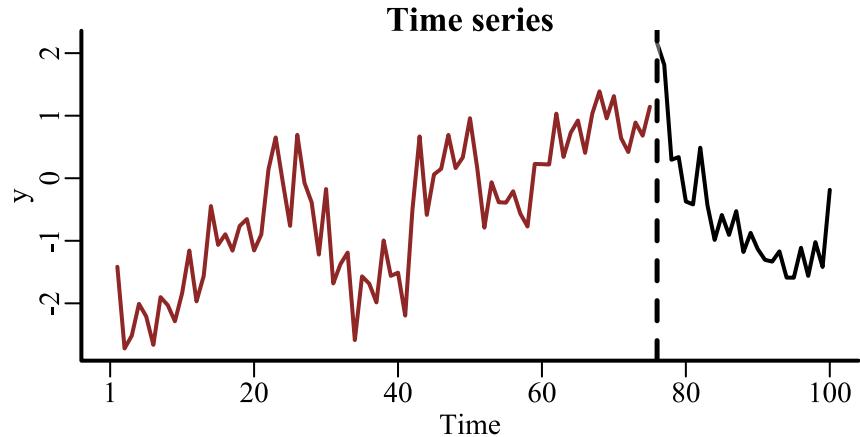
Gavin Simpson
January 3, 2022



GAMs are just fancy GLMs, where some (or all) of the predictor effects are estimated as (possibly nonlinear) smooth functions

**But the complexity these smooth functions can handle is
*enormous***

What's the catch?

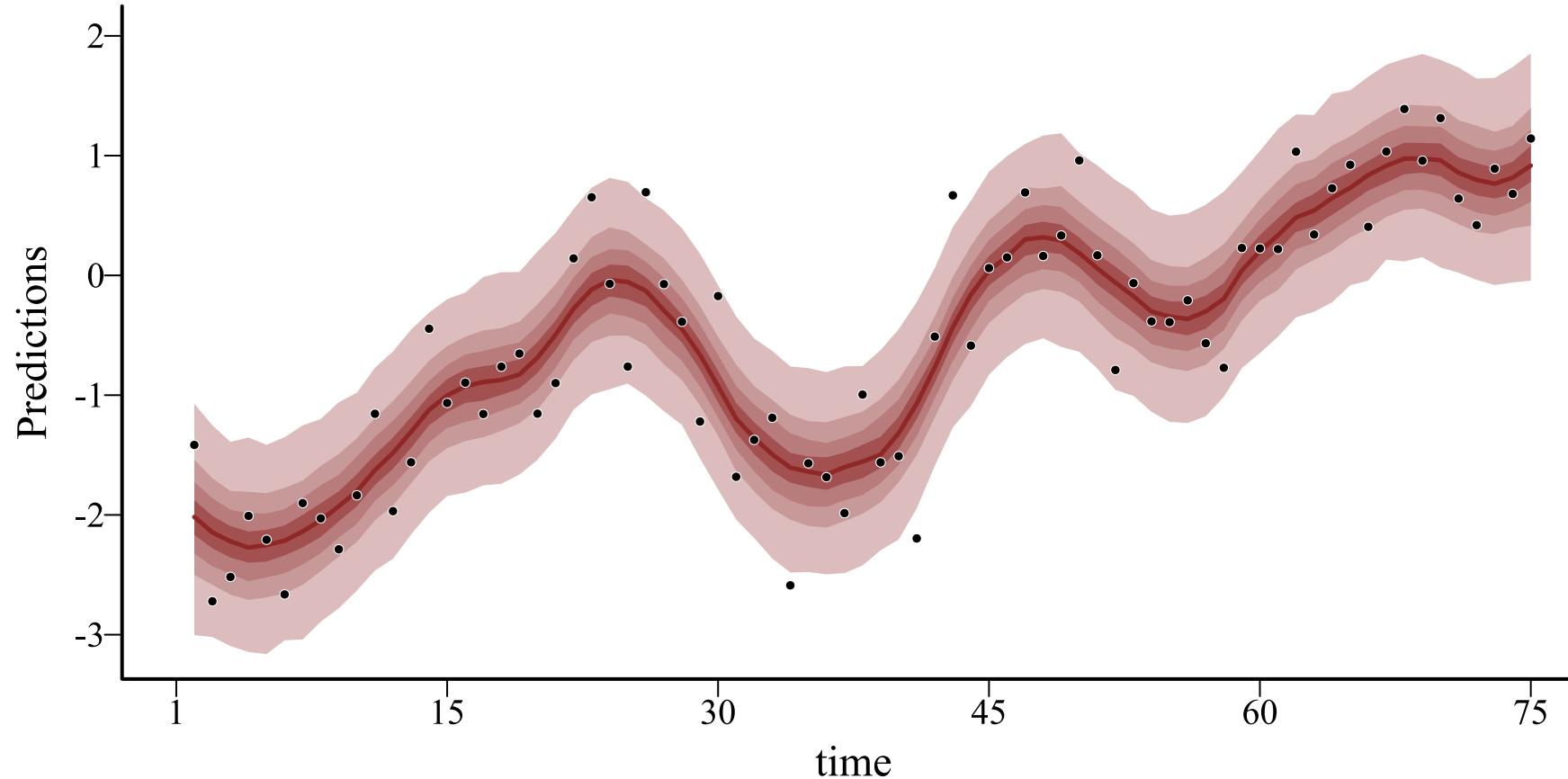


A spline of time

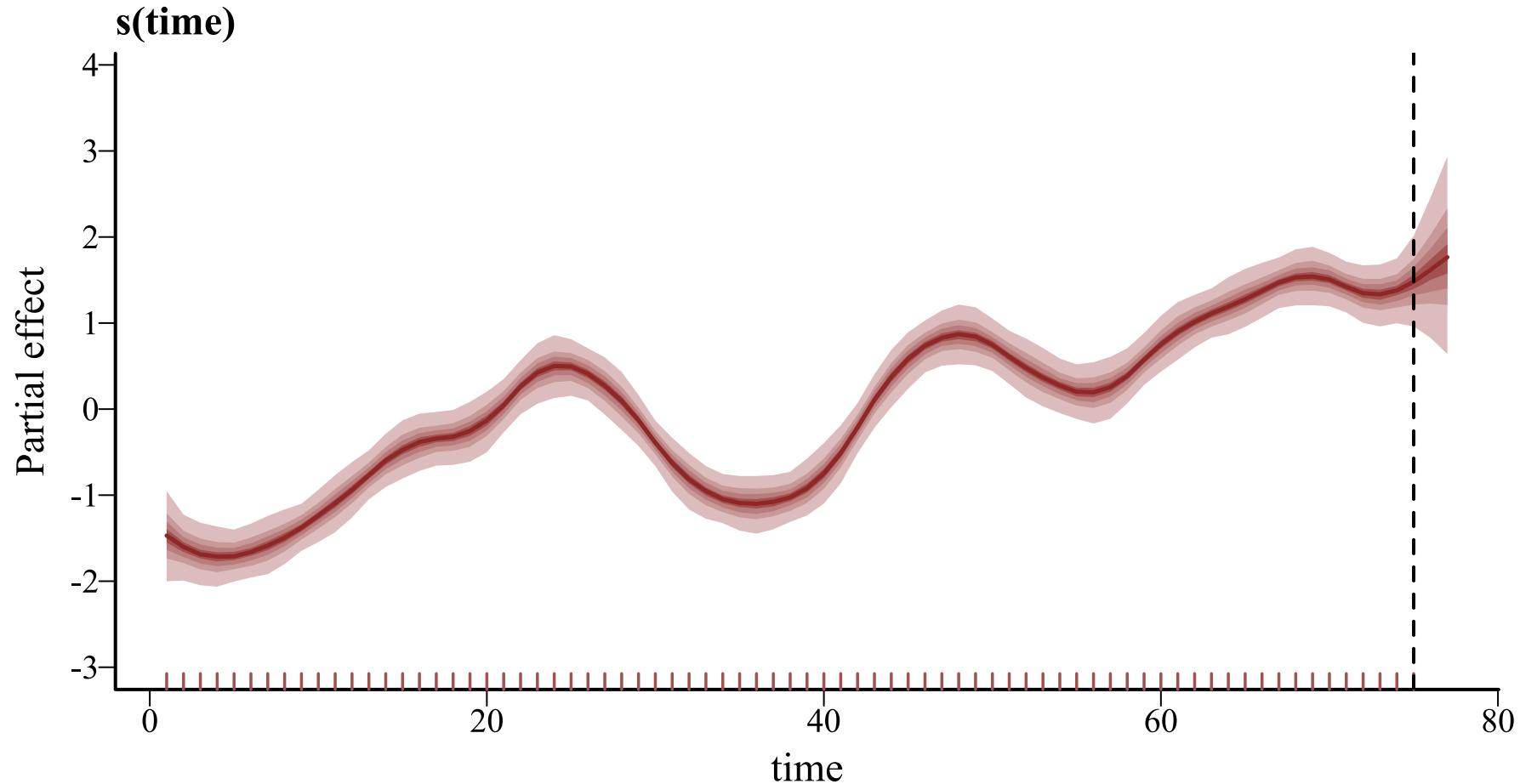
```
library(mgcv)
model <- gam(y ~ s(time, k = 20, bs = 'bs', m = 2),
              data = data,
              family = gaussian())
```

A B-spline (`bs = 'bs'`) with `m = 2` sets the penalty on the second derivative

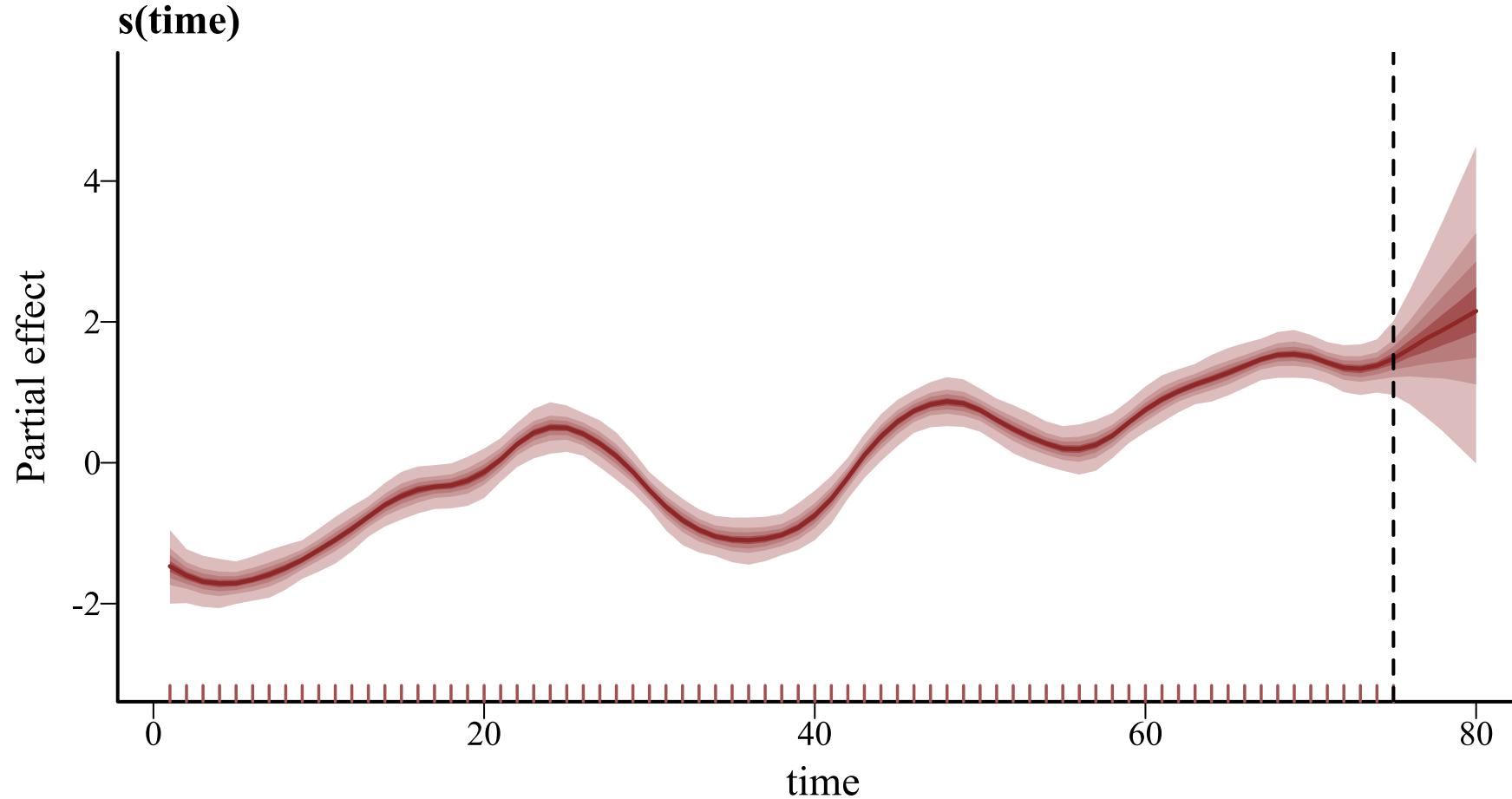
Hindcasts 😊



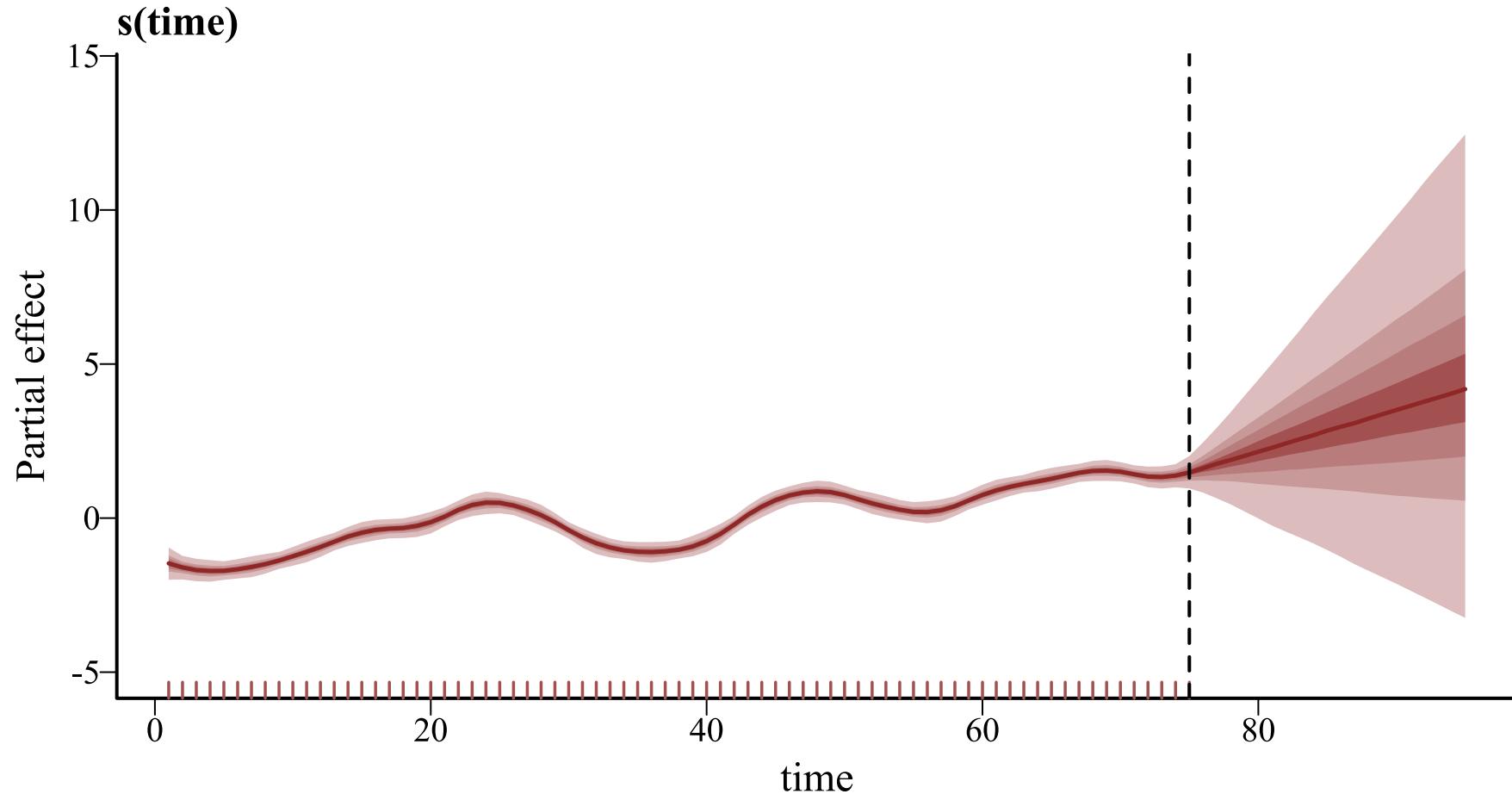
Extrapolate 2-steps ahead 😊



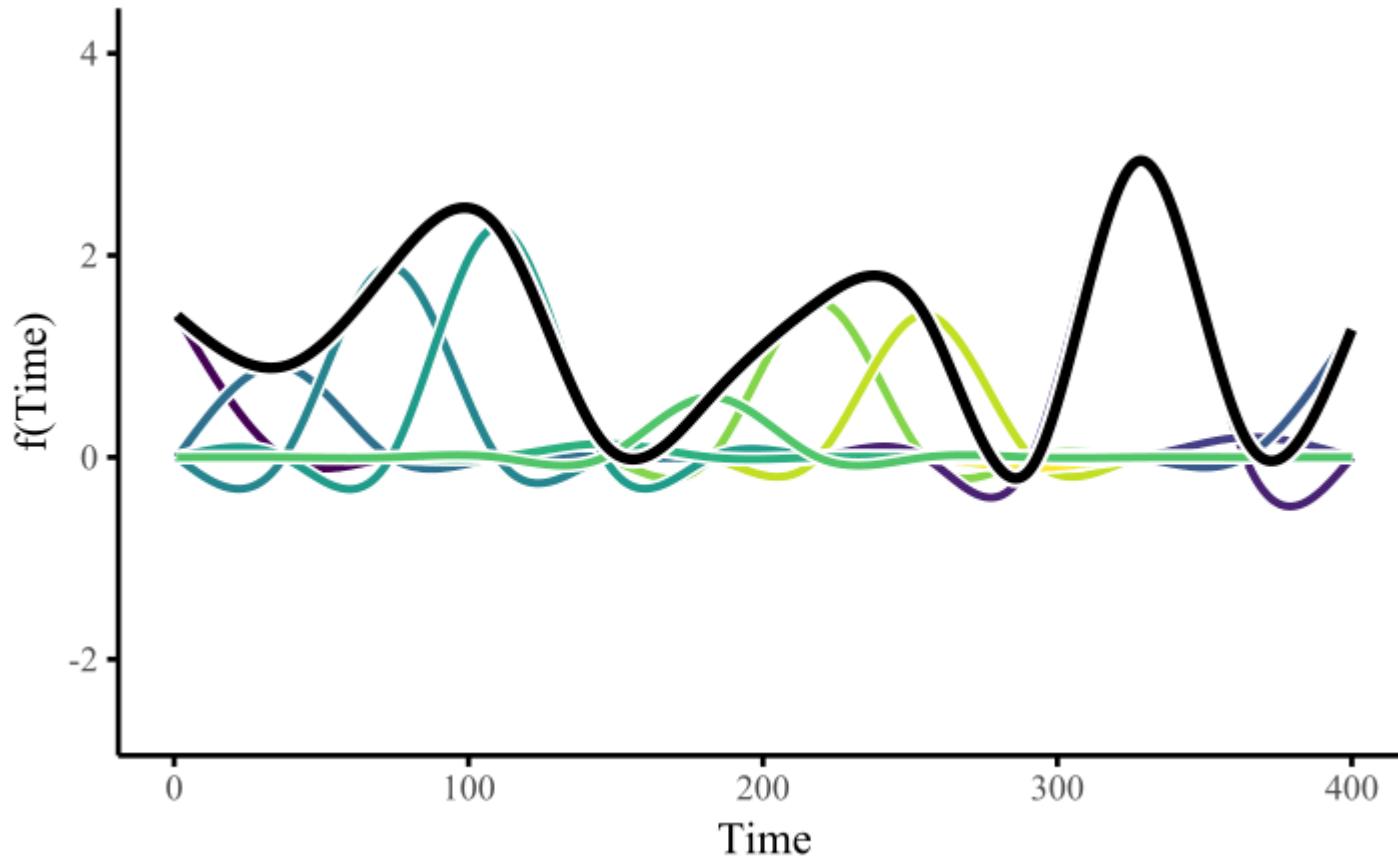
5-steps ahead ☹



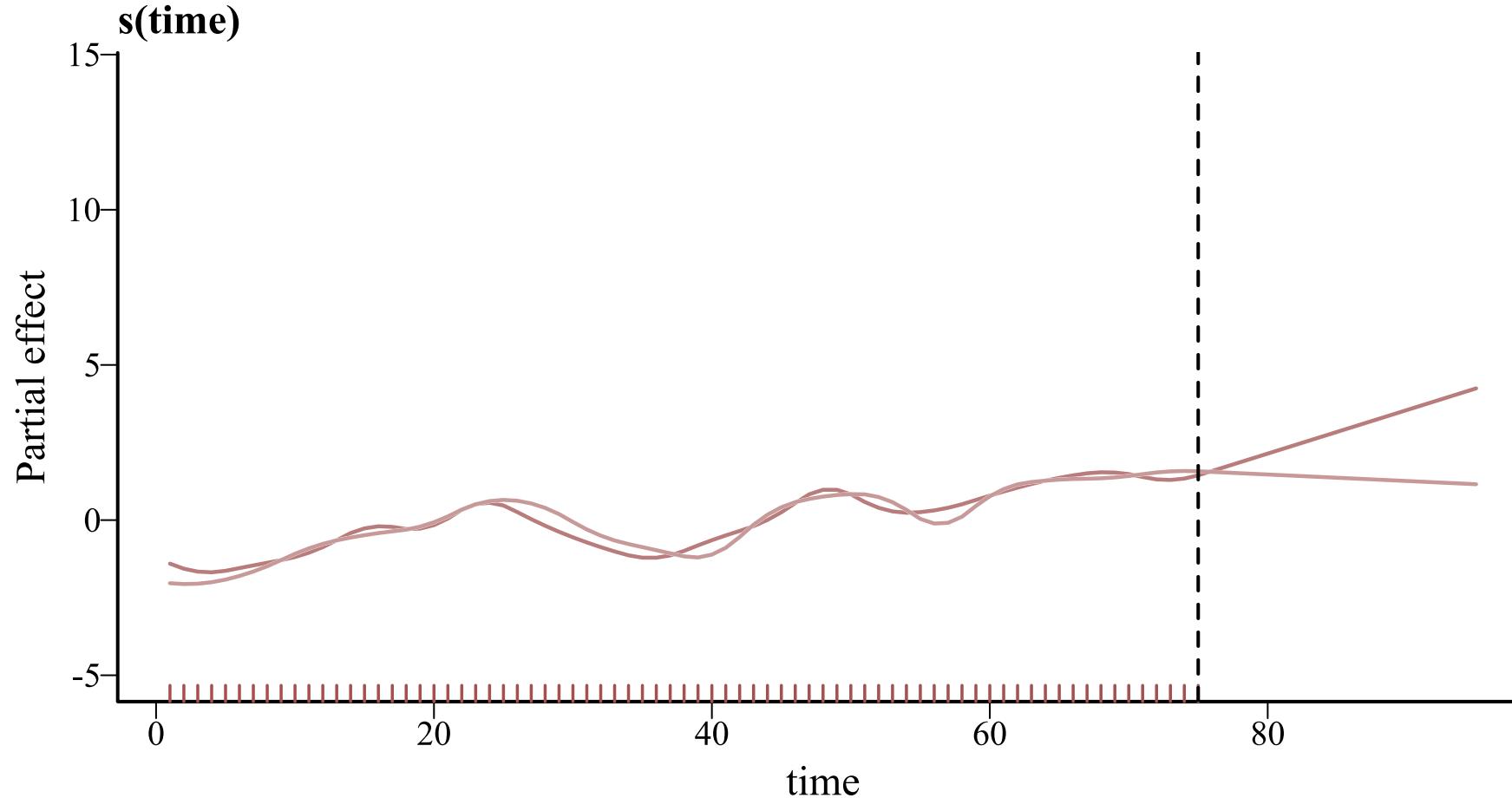
20-steps ahead 😰



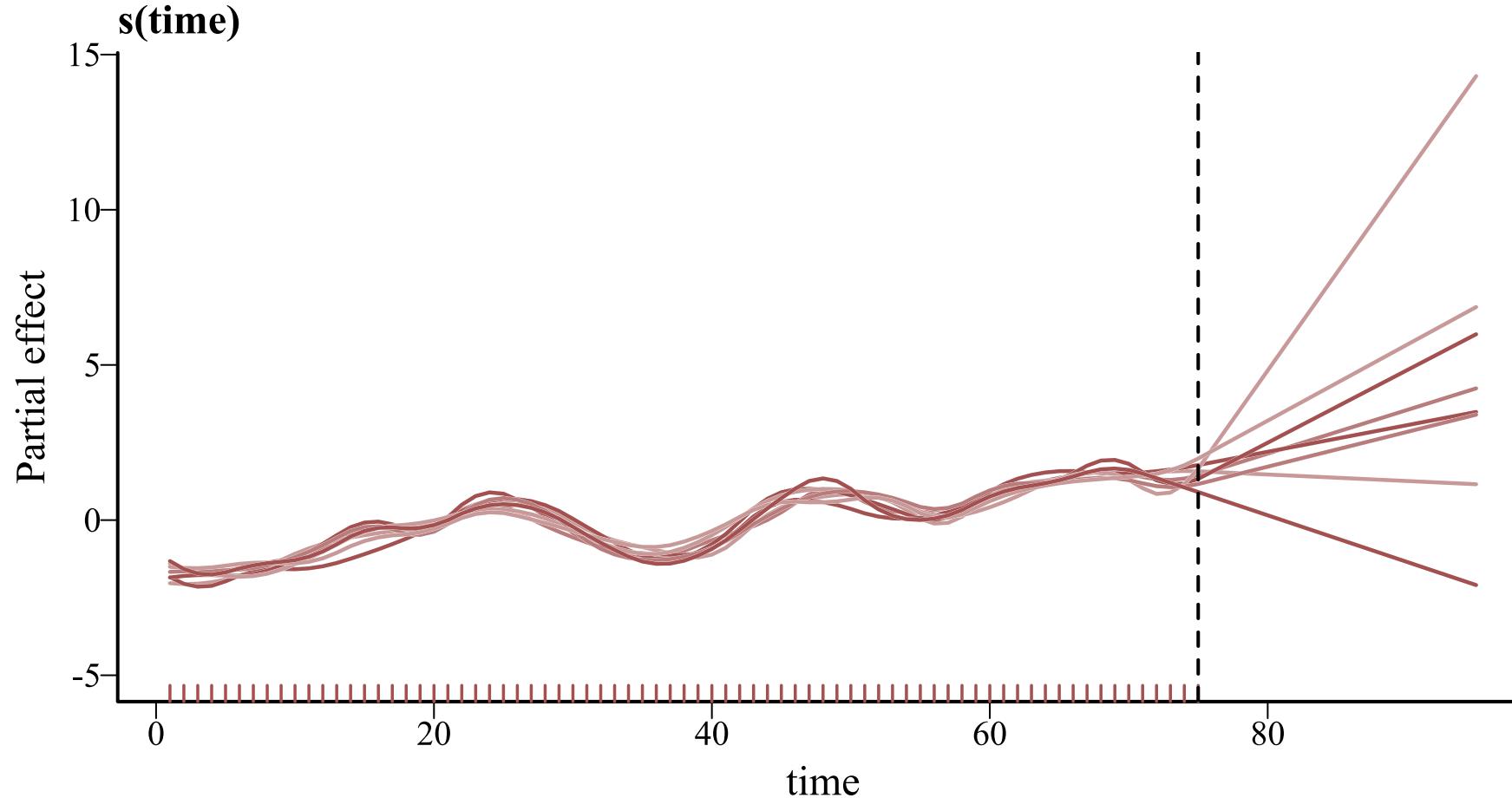
Basis functions \Rightarrow local knowledge



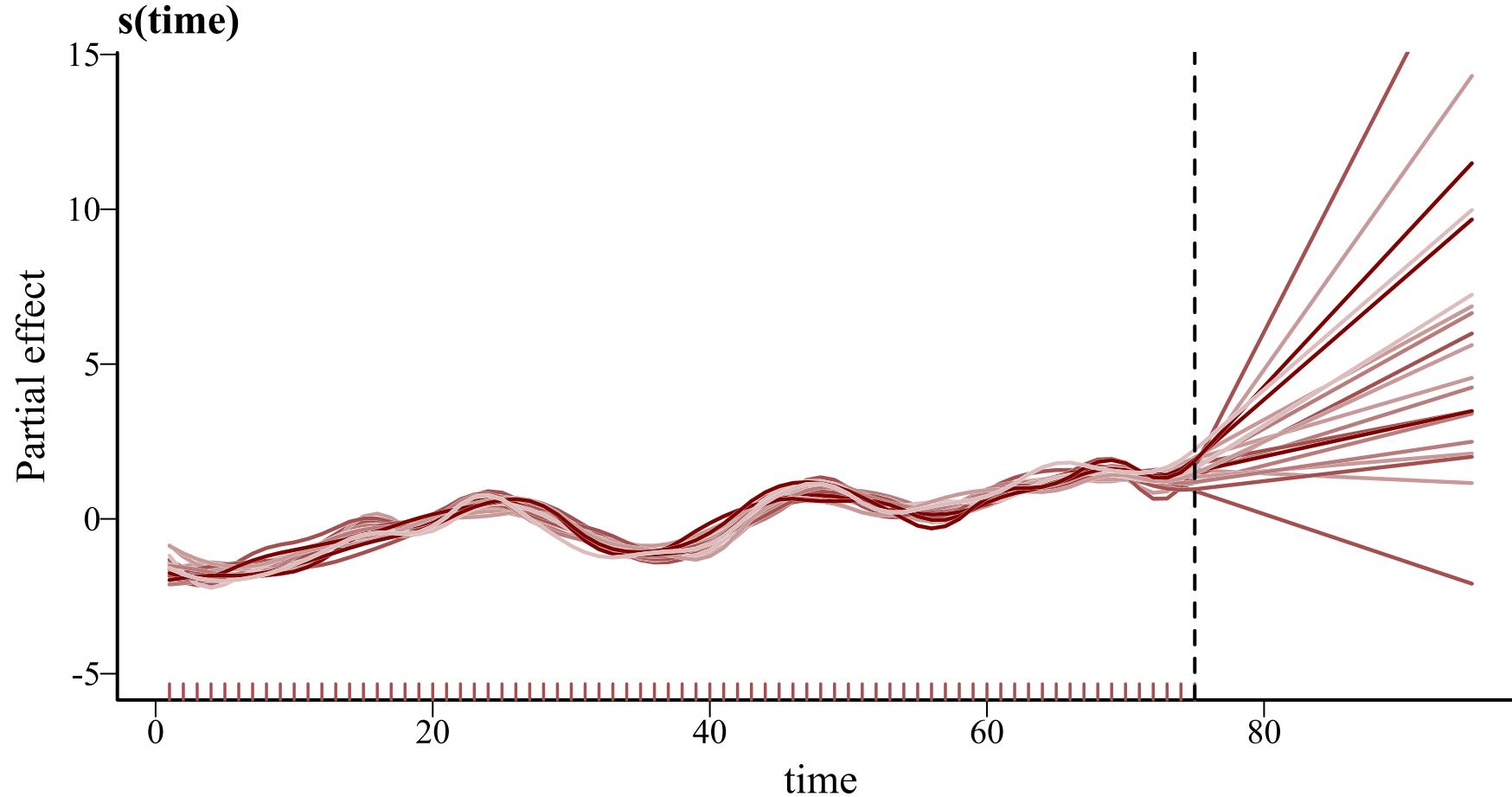
Basis functions \Rightarrow local knowledge



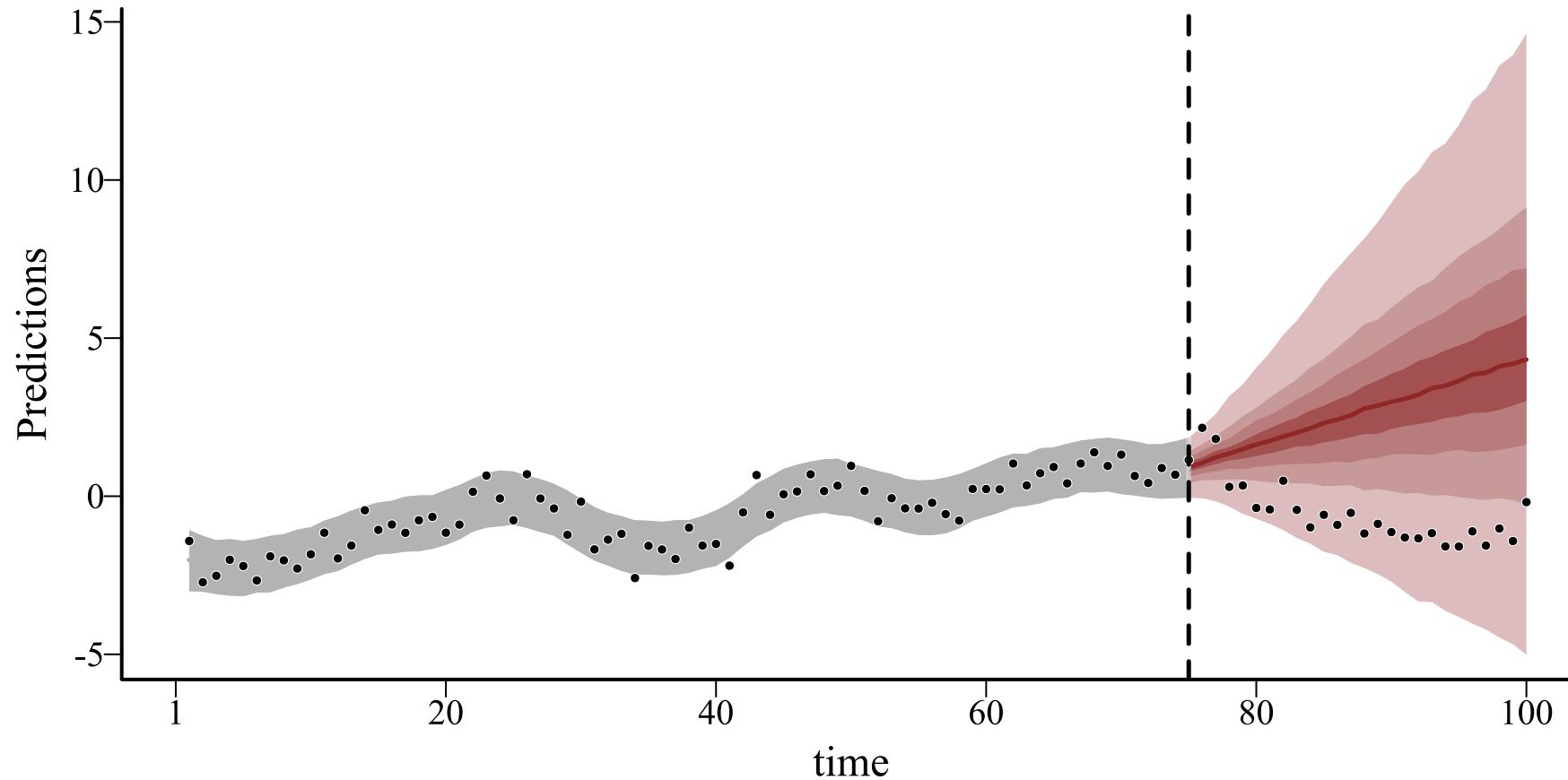
Basis functions \Rightarrow local knowledge



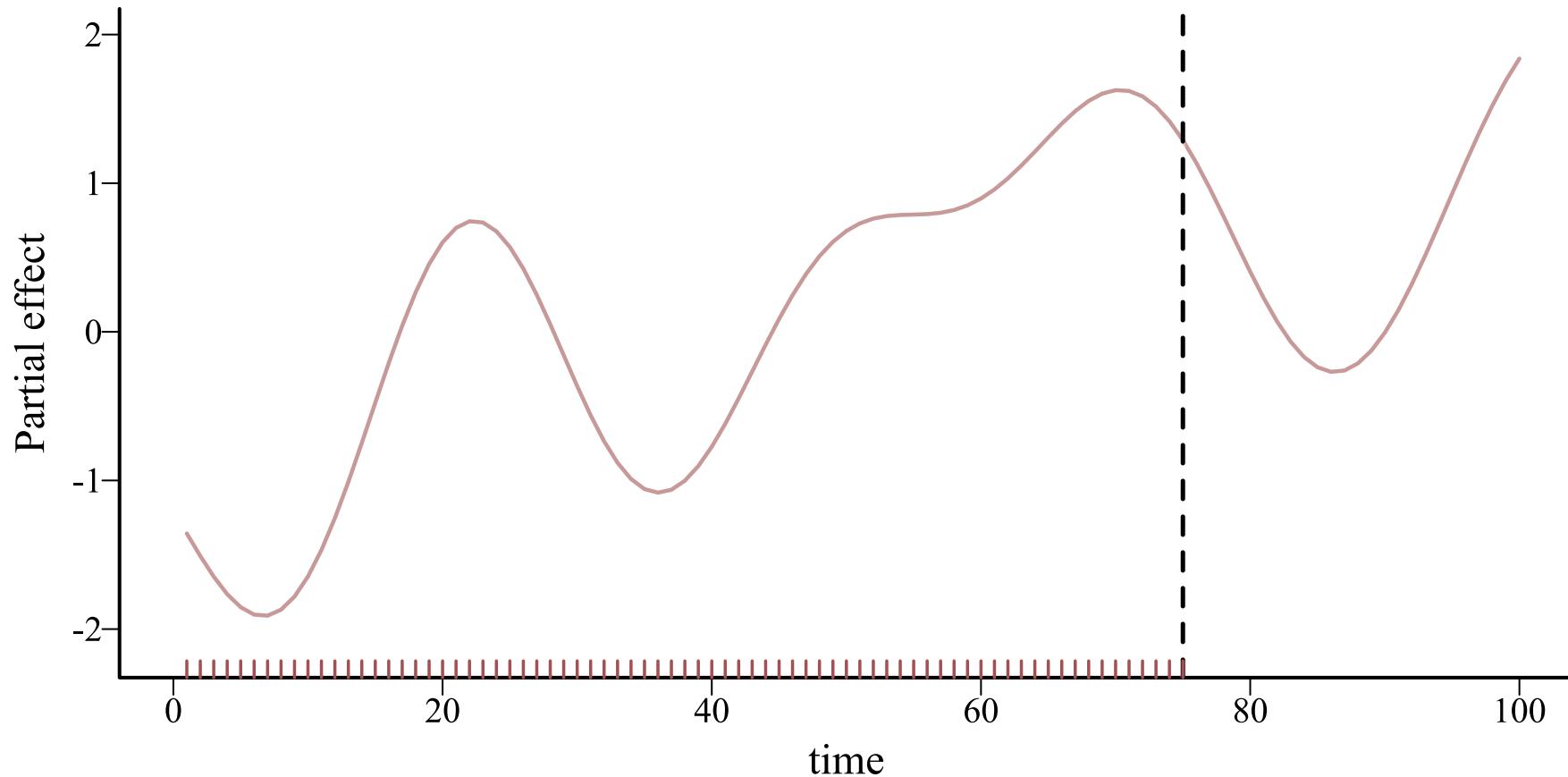
Basis functions \Rightarrow local knowledge



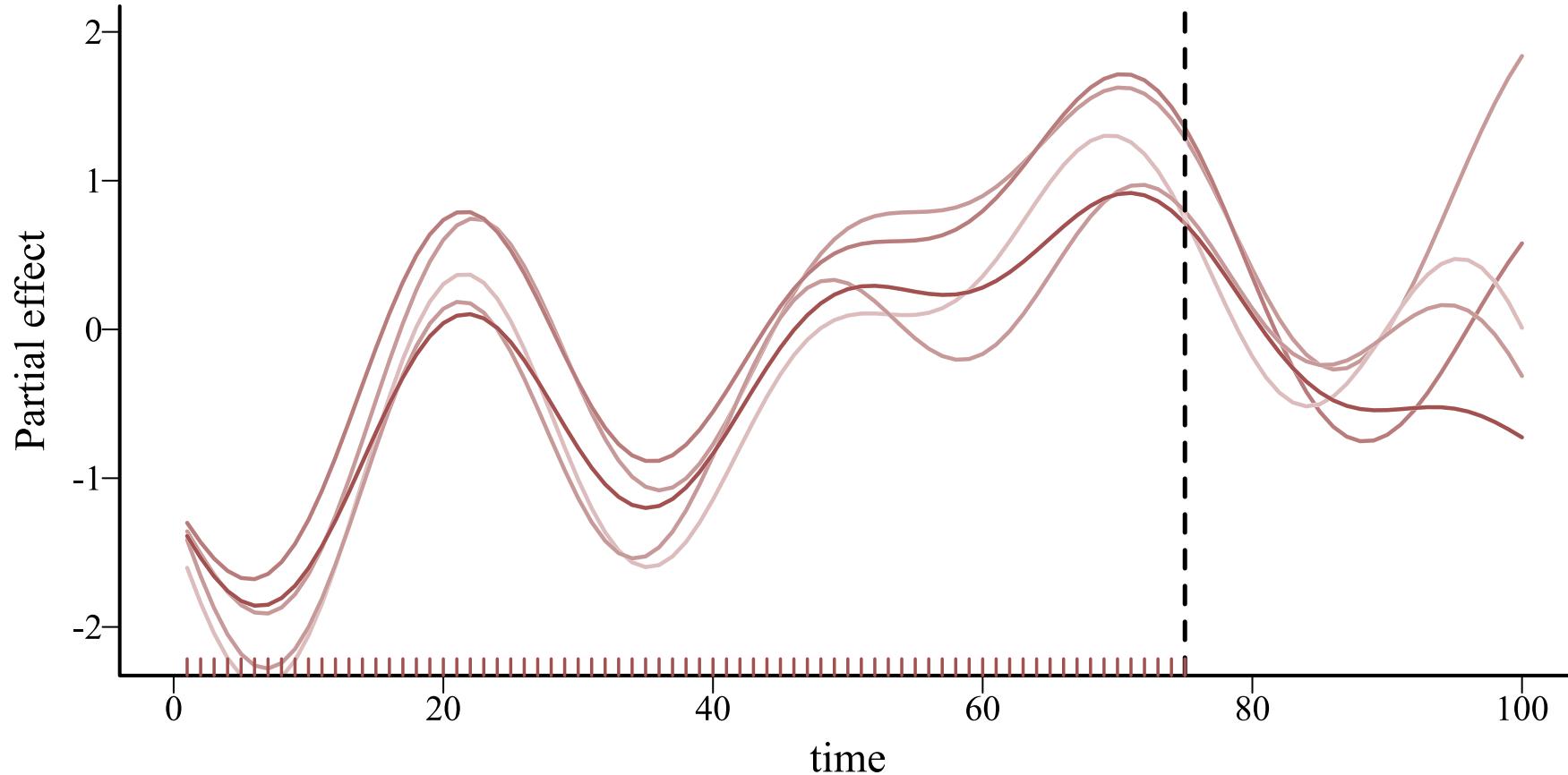
Forecasts



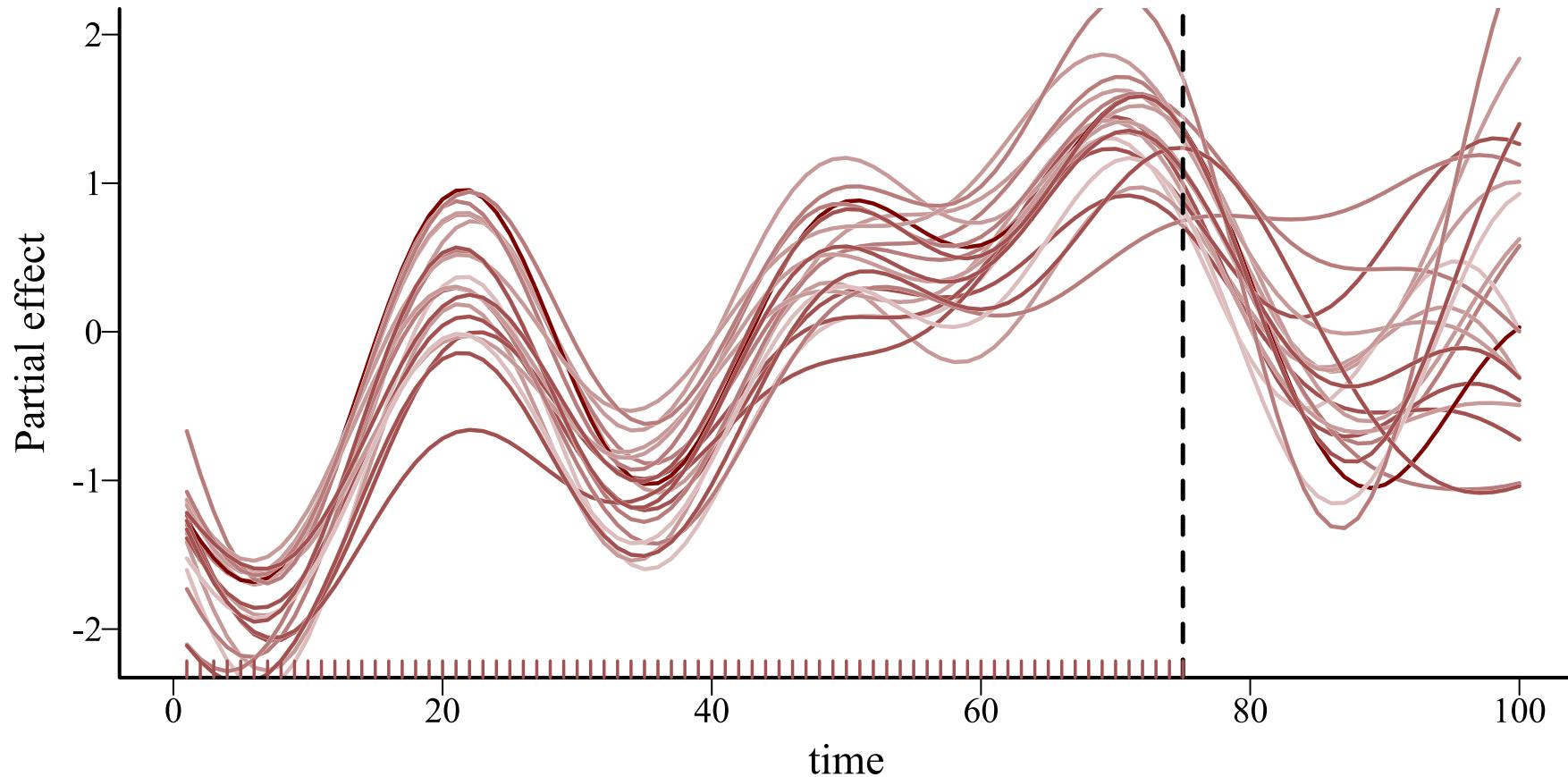
We need *global knowledge*



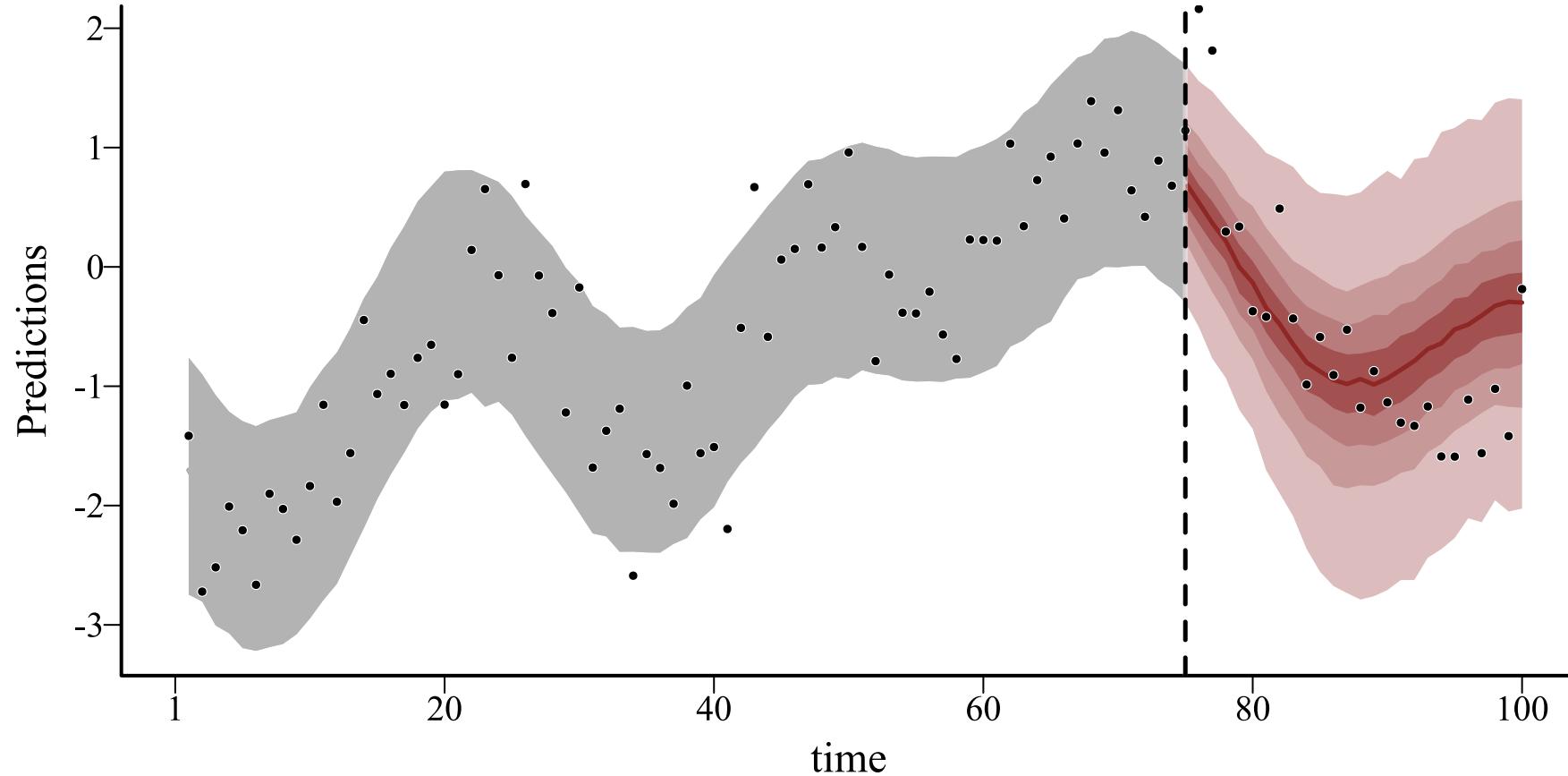
We need *global knowledge*



We need *global knowledge*



We need *global knowledge*



Dynamic GAMs

$$\mathbb{E}(\mathbf{Y}_t | \mathbf{X}_t) = g^{-1}(\alpha + \sum_{j=1}^J f(x_{jt}) + z_t)$$

Where:

g^{-1} is the inverse of the link function

α is the intercept

$f(x)$ are potentially nonlinear functions of the J predictors

z_t is a ***latent dynamic process***

Modelling with the [mvgam](#)

Bayesian framework to fit Dynamic GLMs and Dynamic GAMs

Hierarchical intercepts, slopes and smooths

Latent dynamic processes

State-Space models with measurement error

Built off the [mgcv](#)  to construct penalized smoothing splines

Convenient and familiar  formula interface

Uni- or multivariate series from a range of response distributions

Uses [Stan](#) for efficient Hamiltonian Monte Carlo sampling

Observation families

`gaussian()`, `student-t()` \Rightarrow real values in $(-\infty, \infty)$

`lognormal()`, `Gamma()` \Rightarrow positive real values in $[0, \infty)$

`betar()` \Rightarrow real values (proportional) in $[0, 1]$

`poisson()`, `nb()` \Rightarrow non-negative integers in $(0, 1, 2, \dots)$

Extended predictor effects

`s()` ⇒ Smoothing spline of one or more covariates

`s(bs = 're')` ⇒ Hierarchical slopes or intercepts

`te()`, `ti()`, `t2()` ⇒ Tensor product smoothing spline of two or more covariates

`gp()` ⇒ Gaussian Process function (with squared exponential kernel) of one covariate

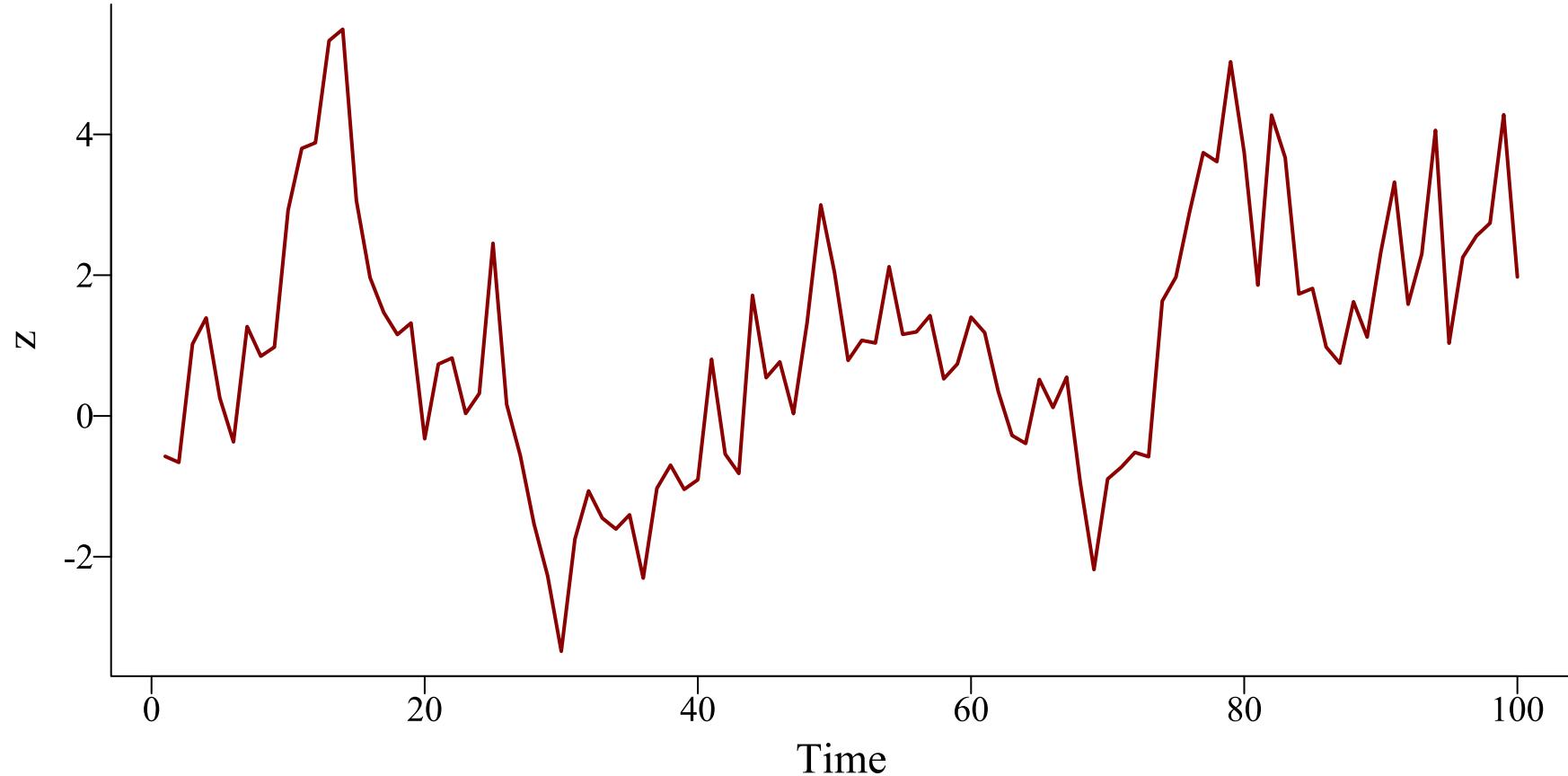
`dynamic()` ⇒ Time-varying effect of one covariate

We can fit models that include random effects, nonlinear effects and complex multidimensional smooth functions. All these effects can operate *on both process and observation models*

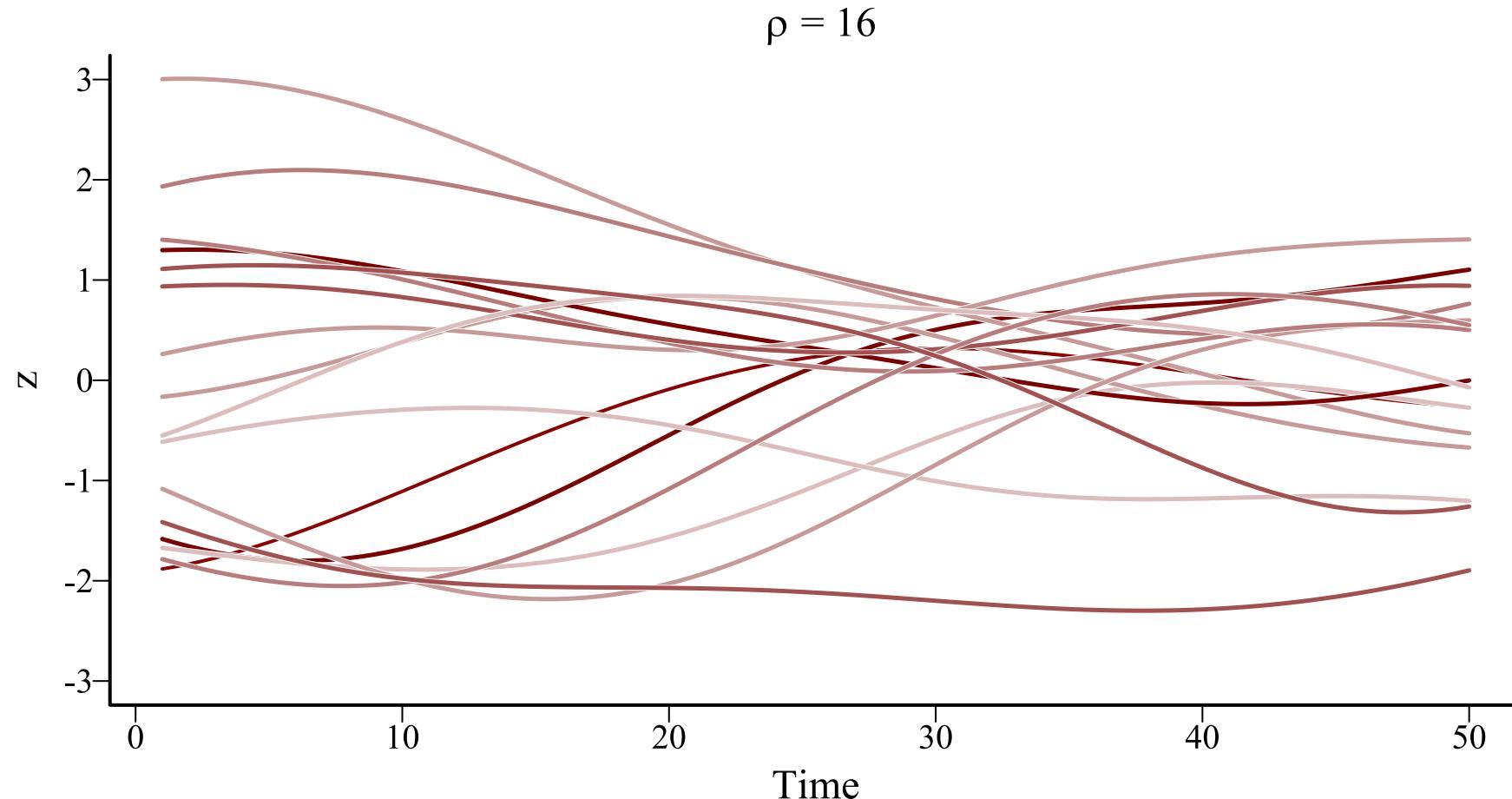
Can incorporate unobserved temporal dynamics; do not need to regress the outcome on its own past values

Very advantageous for ecological time series. But what kinds of dynamic processes are available in the `mgvam`  ?

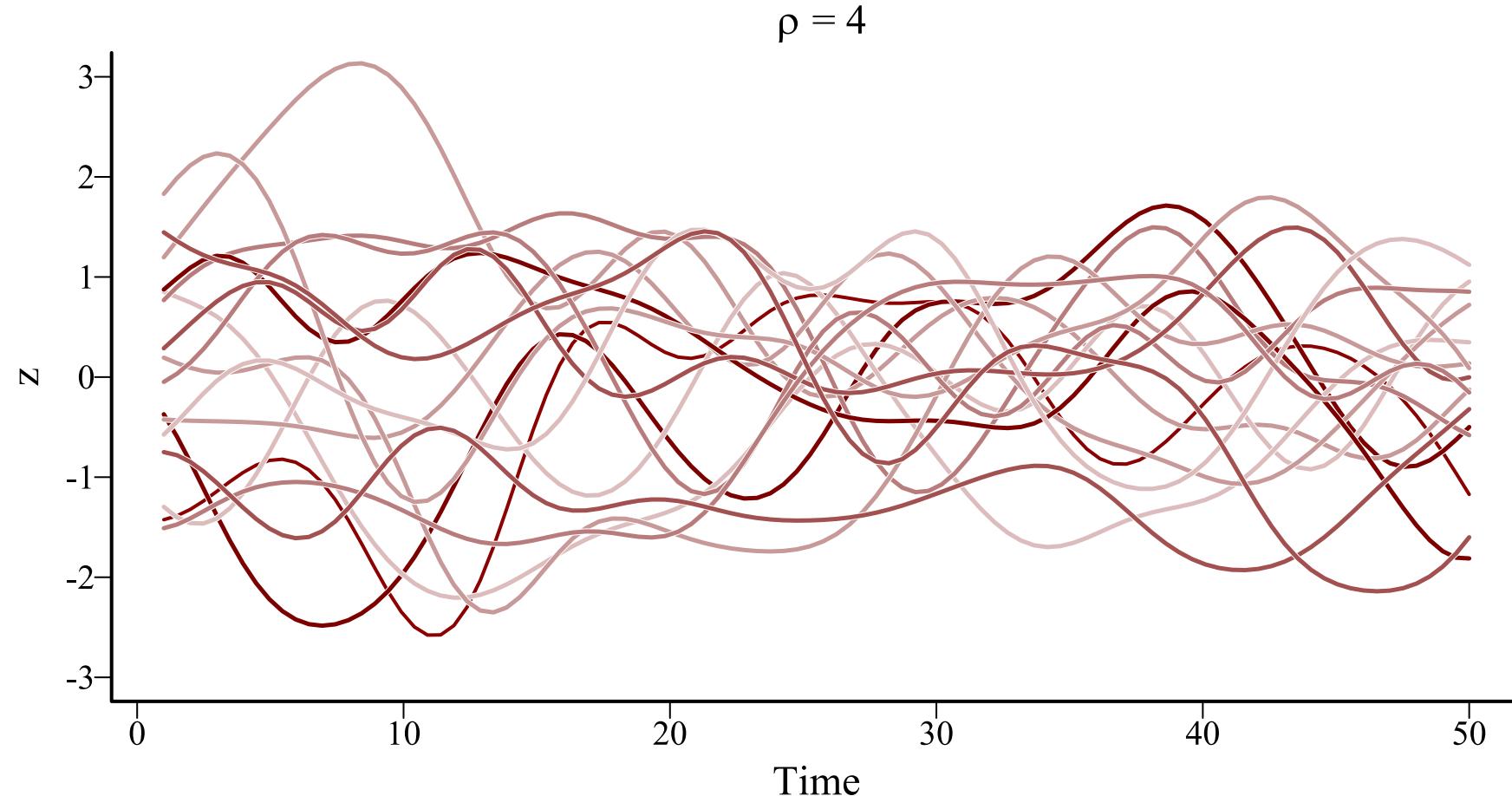
Random Walk or AR(1-3)



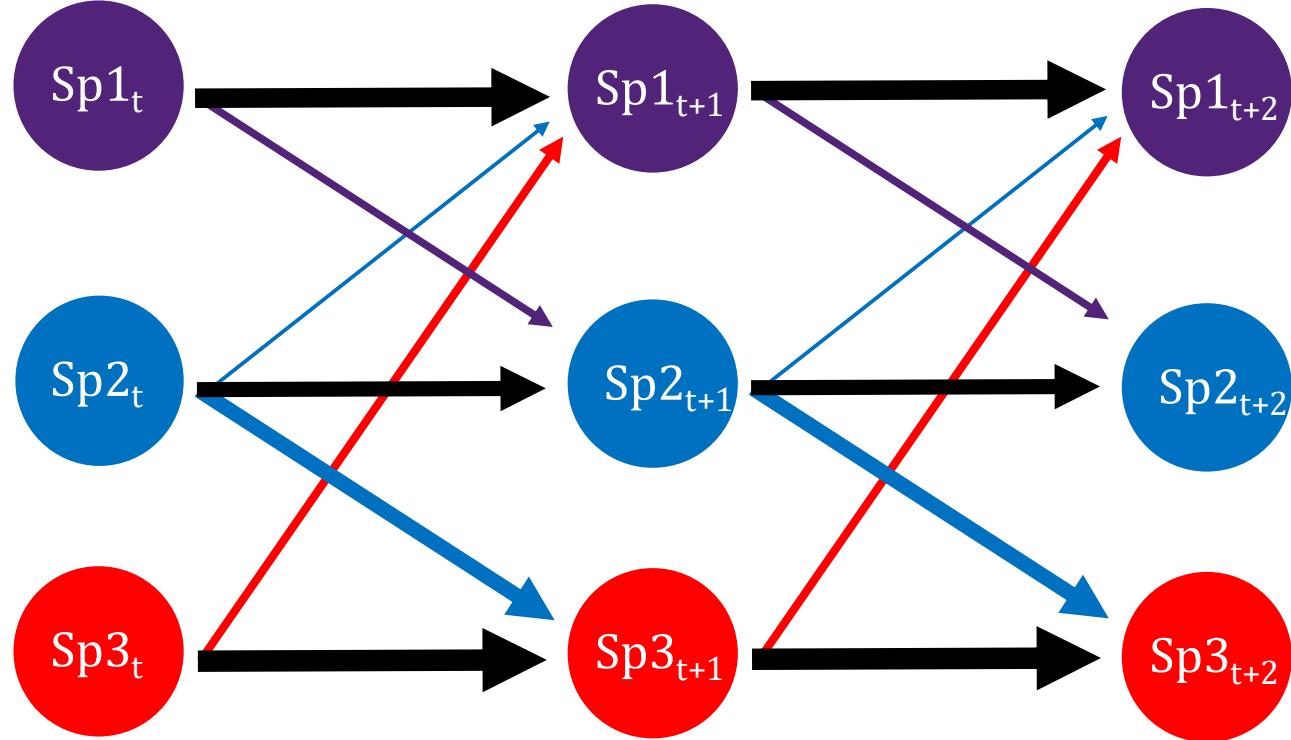
Gaussian Process...



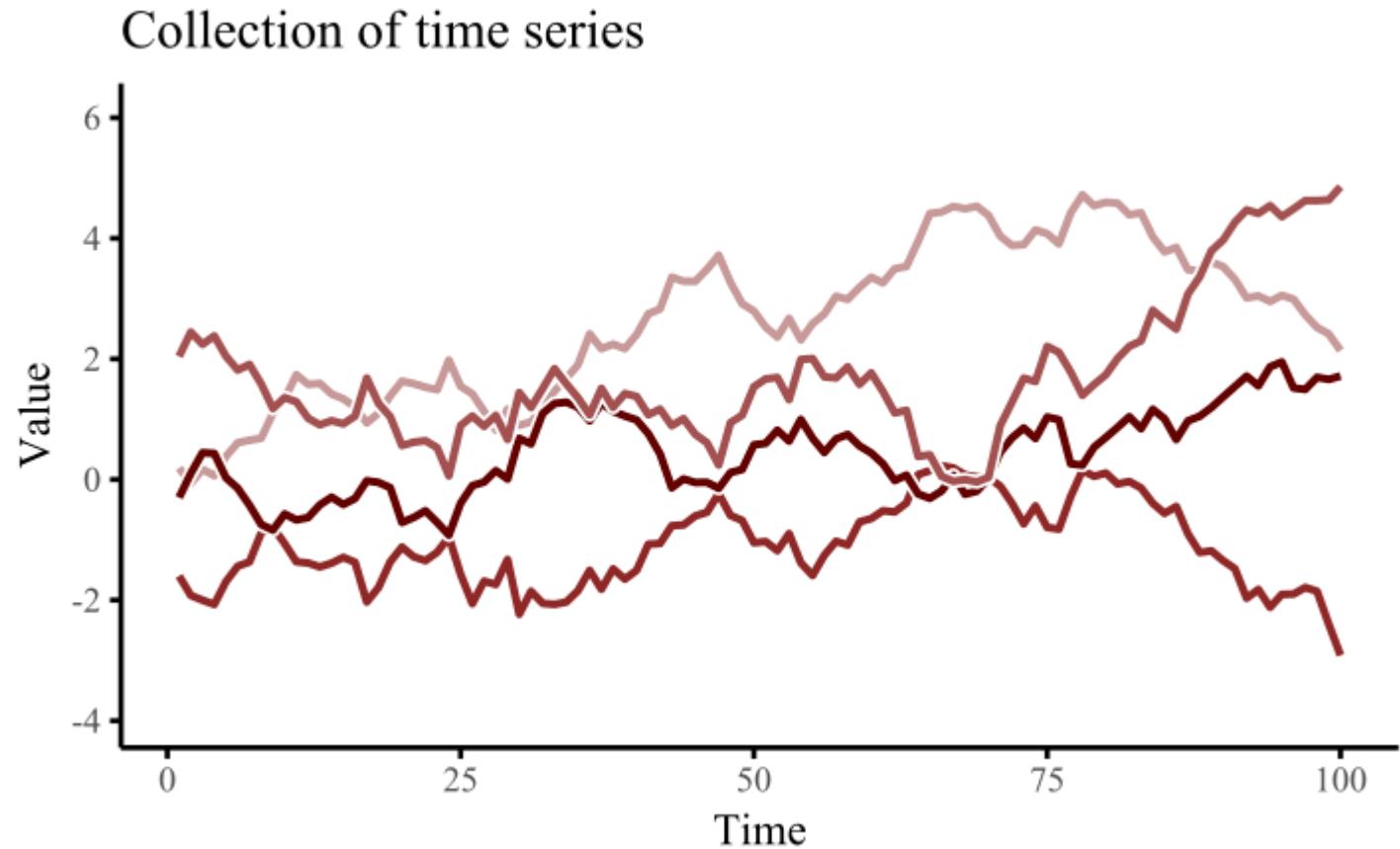
...where length scale \Rightarrow memory



VAR1 \Rightarrow Granger causality



Factors \Rightarrow induced correlations



Example of the interface

```
model ← mvgam(  
    formula = y ~  
        s(series, bs = 're') +  
        s(x0, series, bs = 're') +  
        x1 +  
        gp() +  
        te(x3, x4, bs = c('cr', 'tp')),  
    data = data,  
    family = poisson(),  
    trend_model = 'AR1',  
    burnin = 500,  
    samples = 500,  
    chains = 4,  
    parallel = TRUE  
)
```

Example data (long format)

y	series	time
2	species_1	1
0	species_2	1
NA	species_3	1
NA	species_4	1
1	species_1	2
0	species_2	2
3	species_3	2
5	species_4	2

Response (NAs allowed)

y	series	time
2	species_1	1
0	species_2	1
NA	species_3	1
NA	species_4	1
1	species_1	2
0	species_2	2
3	species_3	2
5	species_4	2

Series indicator (as factor)

y	series	time
2	species_1	1
0	species_2	1
NA	species_3	1
NA	species_4	1
1	species_1	2
0	species_2	2
3	species_3	2
5	species_4	2

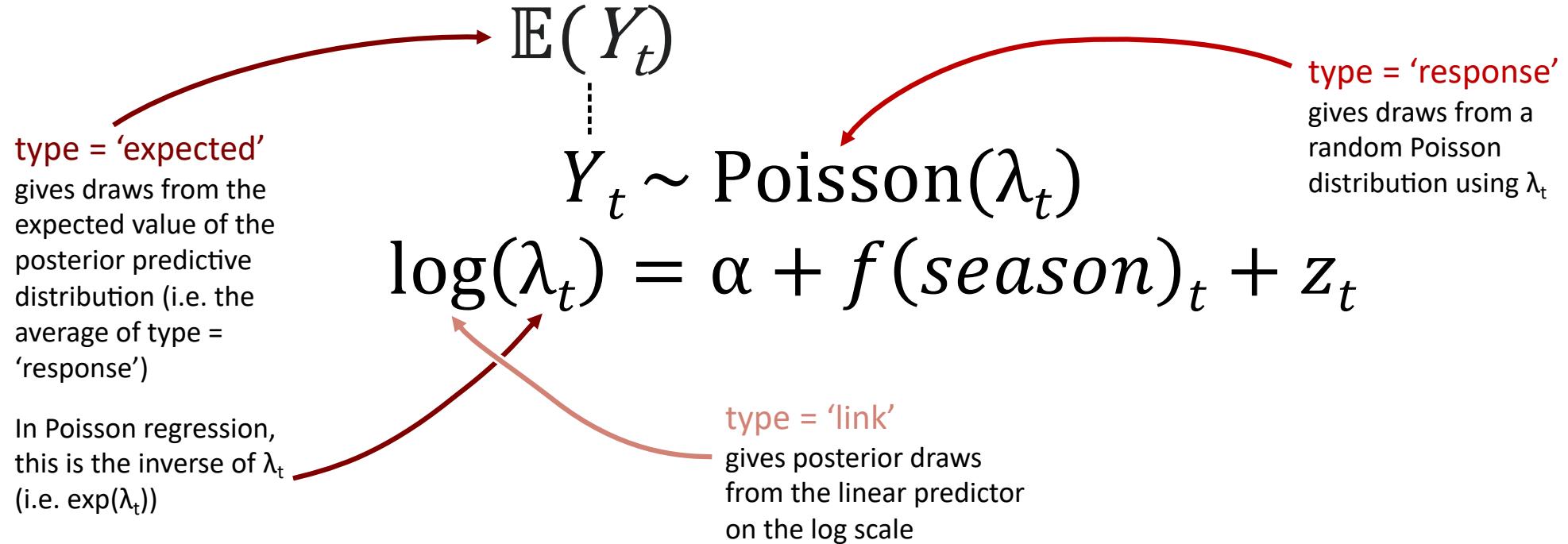
Time indicator

y	series	time
2	species_1	1
0	species_2	1
NA	species_3	1
NA	species_4	1
1	species_1	2
0	species_2	2
3	species_3	2
5	species_4	2

Any other predictors

y	series	time	x0	x1	x2	x3	x4
2	species_1	1	-0.38	A	0.20	1.18	-0.72
0	species_2	1	-0.71	A	-2.67	1.02	0.67
NA	species_3	1	0.05	B	-0.33	0.12	1.50
NA	species_4	1	0.77	B	0.65	0.86	-0.49
1	species_1	2	0.29	A	-0.25	1.18	-0.82
0	species_2	2	0.34	A	-0.15	2.12	0.20
3	species_3	2	-0.38	B	-0.81	1.33	-1.15
5	species_4	2	1.32	B	0.22	-0.72	1.36

Types of mvgam predictions



modified from [Heiss 2022](#)

Workflow in mvgam



Fit models that can include nonlinear splines, GPs, and multivariate dynamic processes to ecological time series

Use posterior predictive checks and Randomized Quantile (Dunn-Smyth) residuals to assess model failures

Use `marginaleffects` to generate interpretable (and reportable) model predictions

Produce probabilistic forecasts

Evaluate forecasts from competing models with proper scoring rules

More resources

Vignette ⇒ [Overview of the package](#)

Vignette ⇒ [Formatting data for use in mvgam](#)

Vignette ⇒ [Shared latent process models](#)

Vignette ⇒ [Time-varying effects](#)

Vignette ⇒ [Multivariate State-Space models](#)

Motivating publication ⇒ Clark & Wells 2023 [Methods in Ecology and Evolution](#)

Example







Long-term rodent monitoring

Monthly trapping in Portal, AZ, from 1977

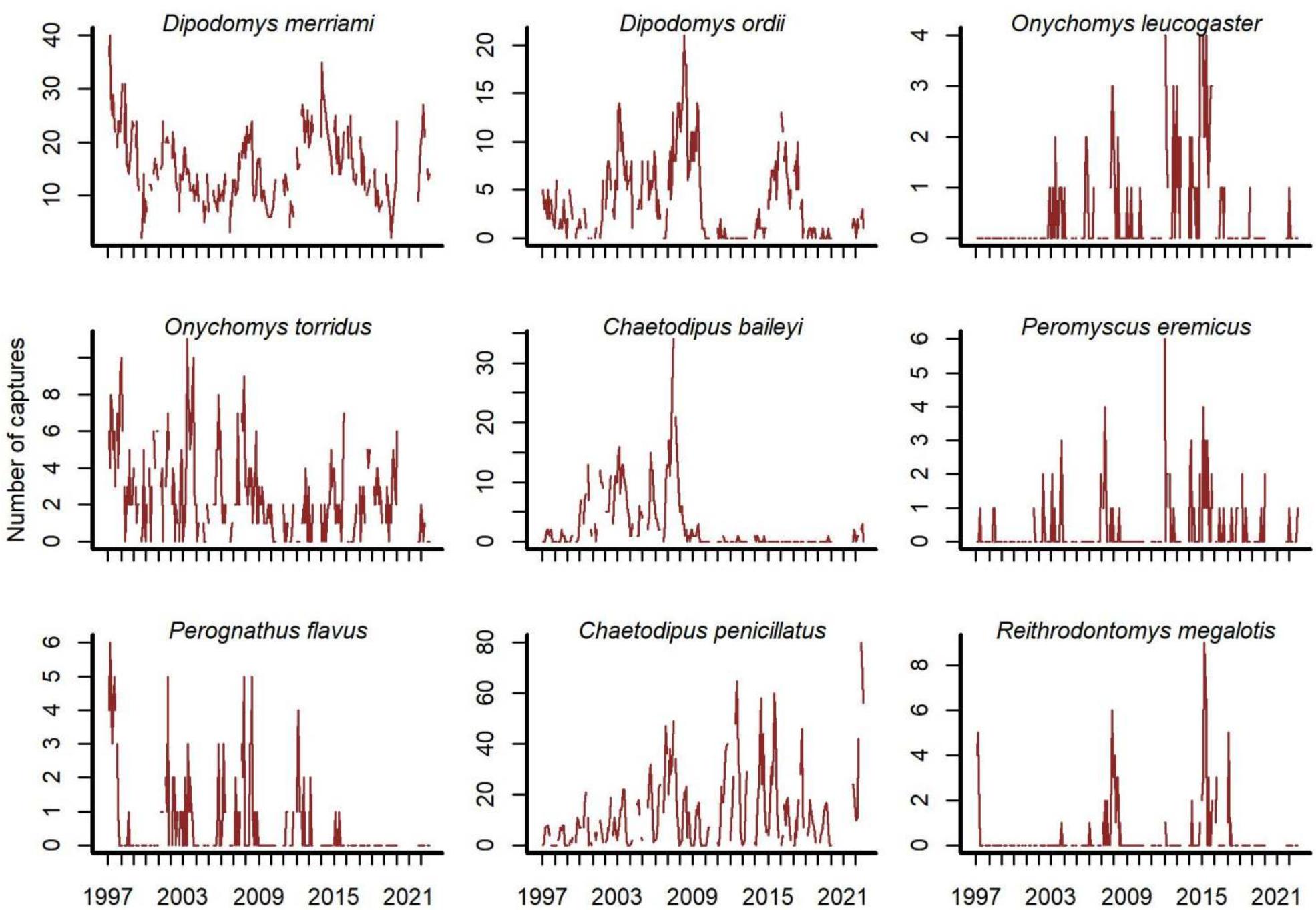
20 rodent species recorded

Experimental evidence for interactions

Both gradual and sudden regime transitions

What drives community dynamics?





$for i = 1, \dots, 9 \text{ species}$
 $for t = 1, \dots, 319 \text{ time points}$
 $Y_{1:9,t} \sim Poisson(\exp(X_{1:9,t}))$

$$X_{1:9,t} \sim MVNormal(\mu_{1:9,t} + A * (X_{1:9,t-1} - \mu_{1:9,t-1}), \sigma * C * \sigma)$$

$$\mu_{i,t} = \beta_{NDVI[i]} * NDVI_{MA\ 12[t]} + f_{global}[t](\text{lag, temp}) + f_{species[i,t]}(\text{lag, temp})$$

$$\beta_{NDVI} \sim Normal(\mu_{NDVI}, \sigma_{NDVI})$$

$$\mu_{NDVI} \sim Normal(0, 1)$$

$$\sigma_{NDVI} \sim InvGamma(2.37, 0.73)$$

Random slopes for species' responses
to NDVI moving average

$$f_{global} = \sum(\beta_{global} * b_{global})$$

$$\beta_{global} \sim MVNormal(0, (\sum(S_{global} * \lambda_{global}))^{-1})$$

$$\lambda_{global} \sim Normal(30, 25)$$

Distributed lag for community
response to lagged minimum
temperature

$$f_{species[i]} = \sum(\beta_{species[i]} * b_{species[i]})$$

$$\beta_{species[i]} \sim MVNormal(0, (\sum(S_{species[i]} * \lambda_{species[i]}))^{-1})$$

$$\lambda_{species} \sim Normal(30, 25)$$

Distributed lags for species'
responses to lagged
minimum temperature

$$A \in P(\mathbb{R})$$

$$P \sim Normal(0, 0.67)$$

$$\sigma \sim Beta(10, 10)$$

$$C \sim LKJcorr(2)$$

Vector autoregression for lagged
multispecies dependence

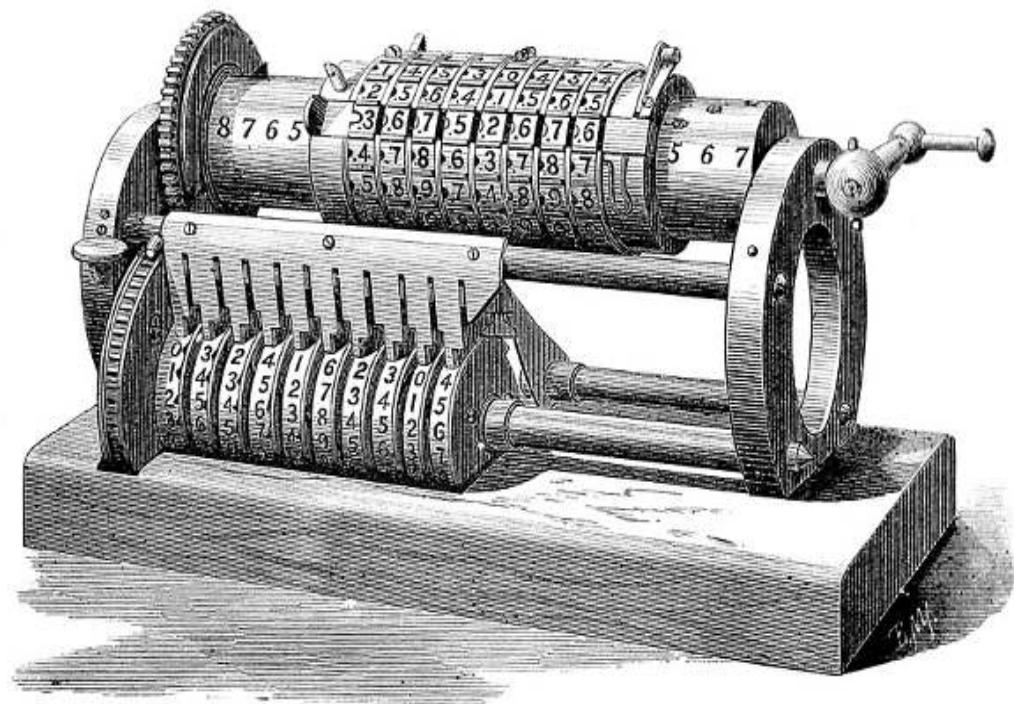
Temporally correlated process errors

GAM component

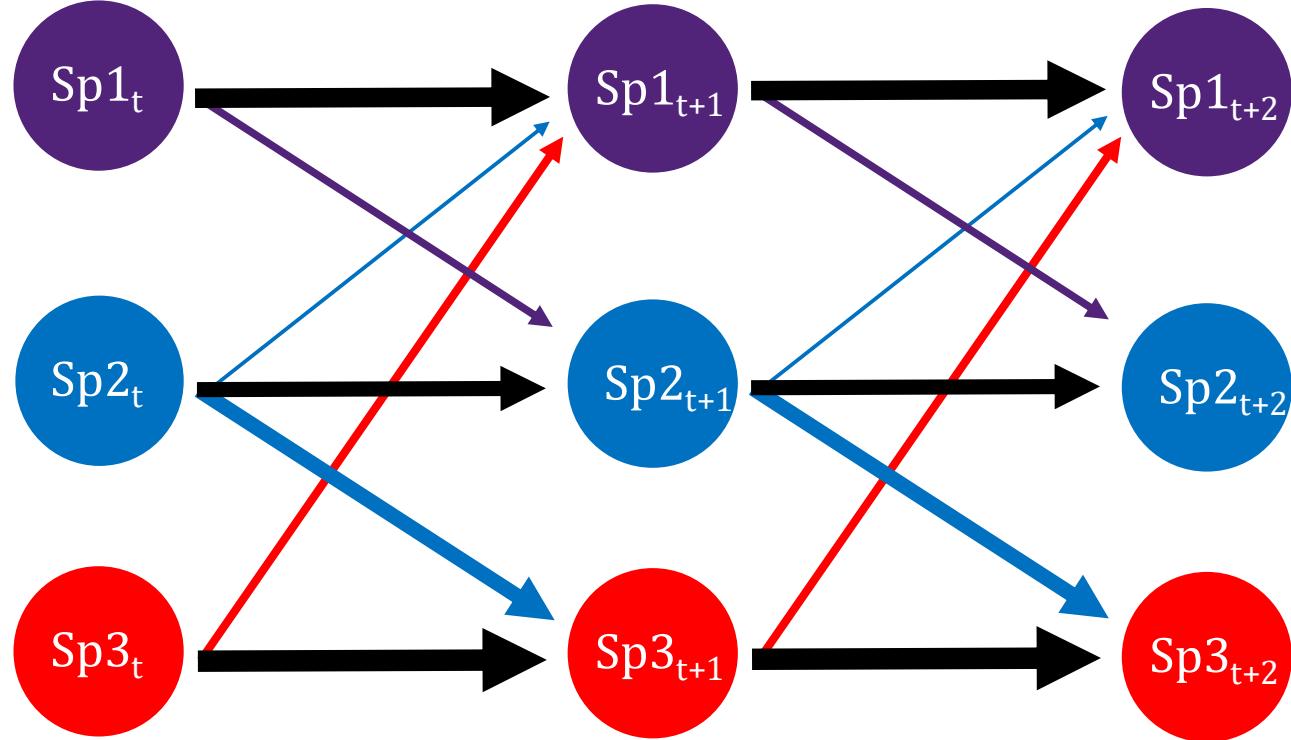
Multivariate dynamic
component

Model components

1. Multispecies temporal dynamics



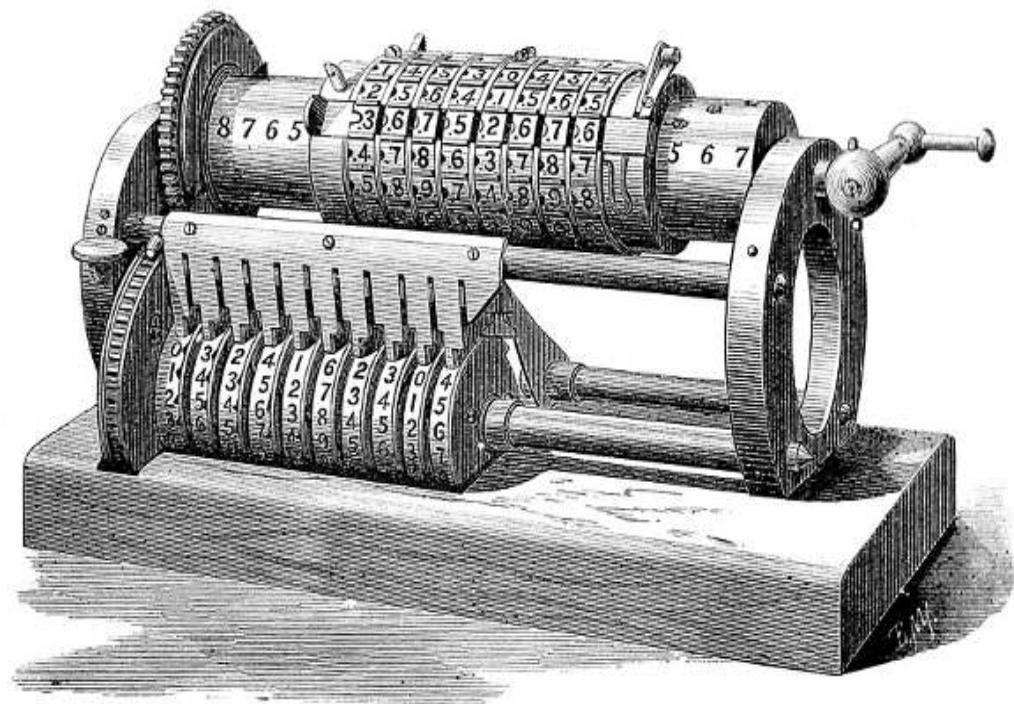
VAR1 \Rightarrow Granger causality

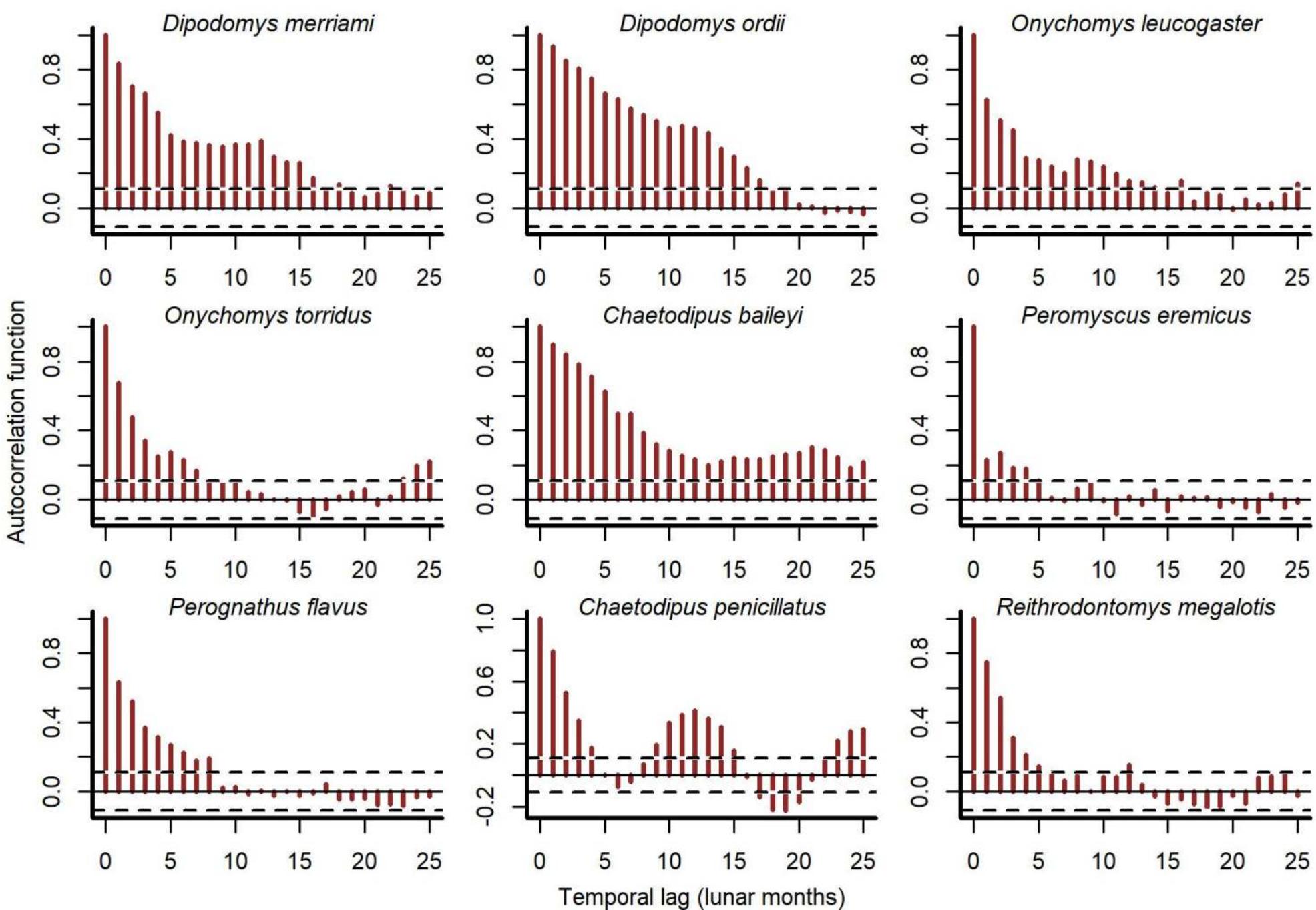


Model components

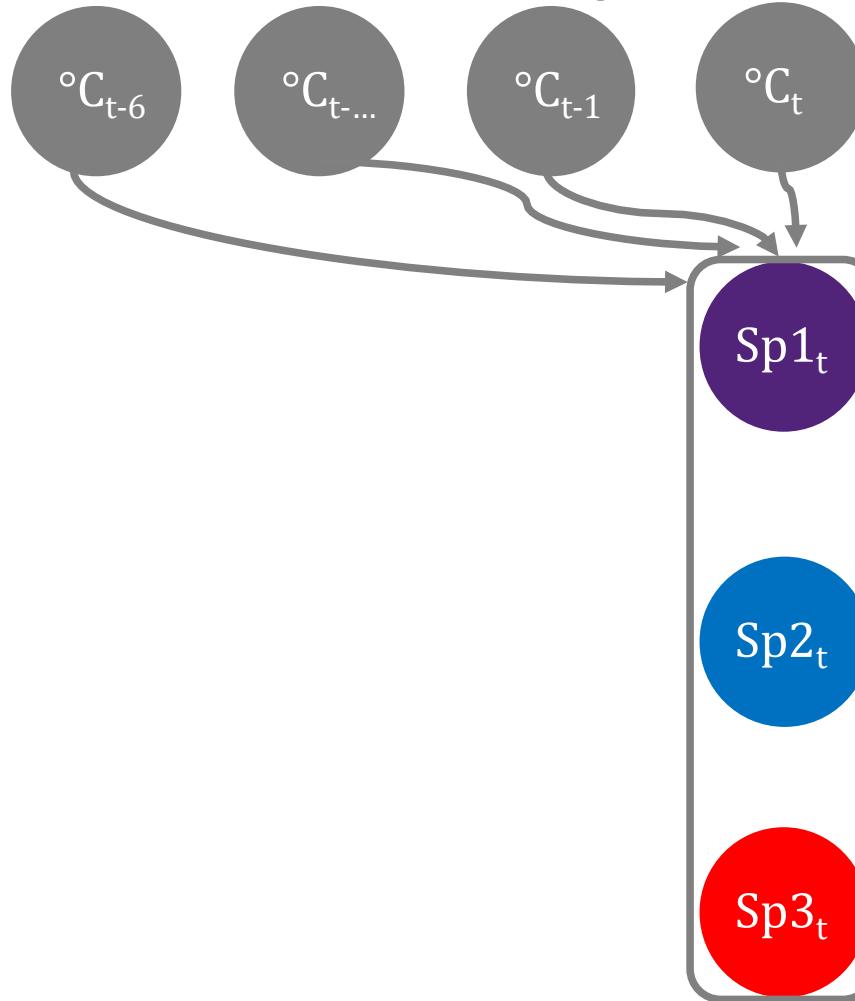
1. Multispecies temporal dynamics

2. Seasonal variation

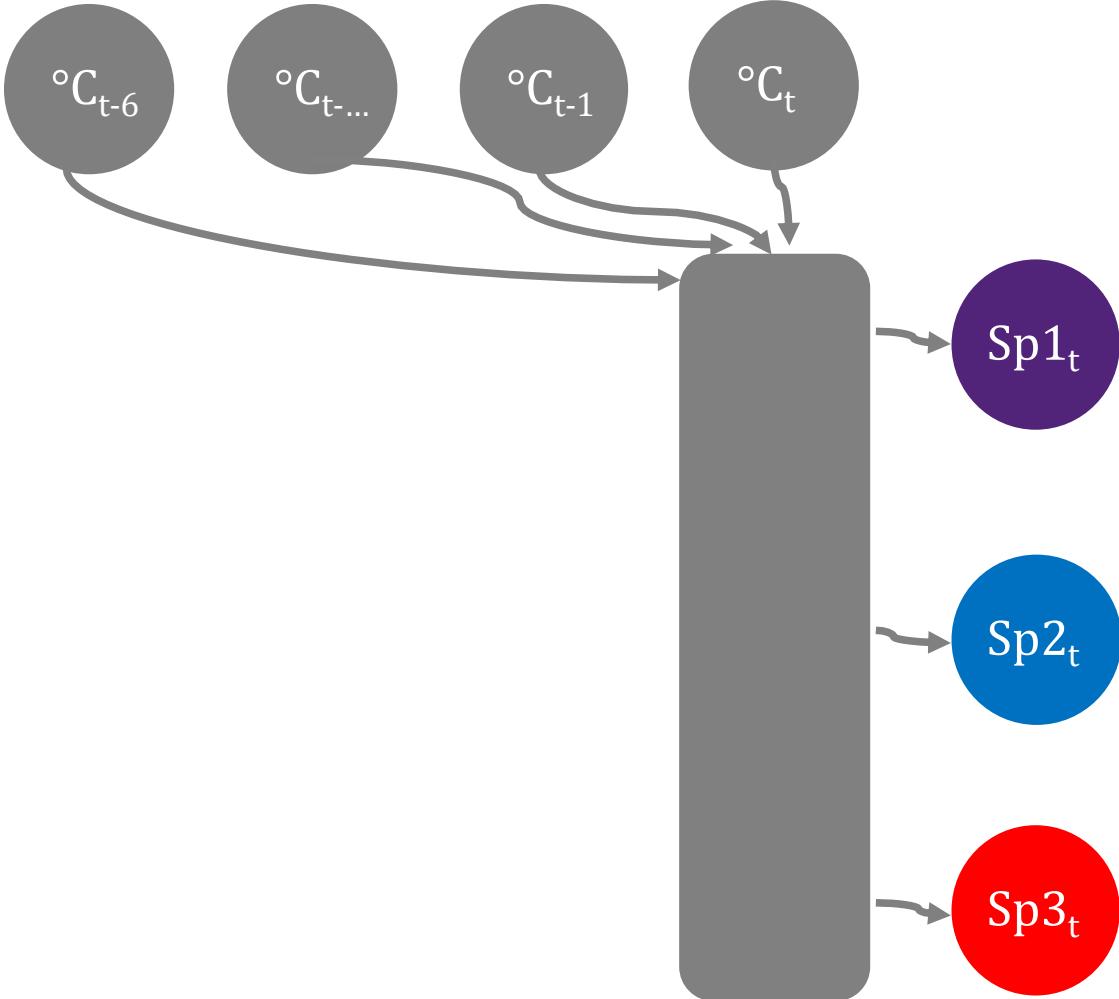




Community mintemp effect changes smoothly over lags



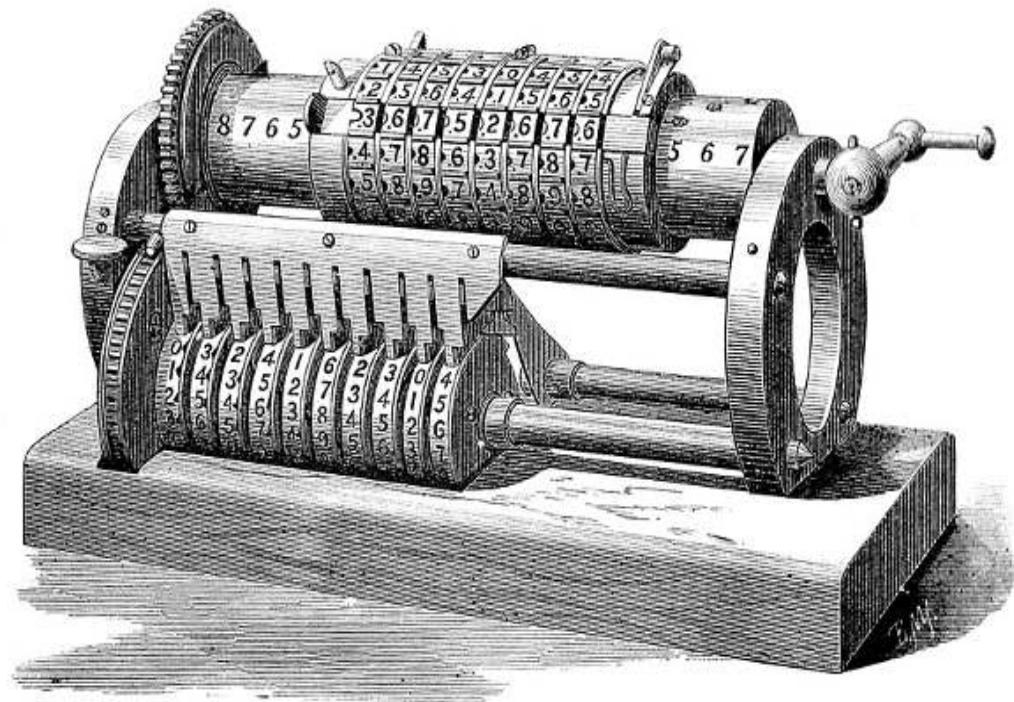
Community mintemp effect changes smoothly over lags



Species mintemp effects deviate smoothly from the community effect

Model components

1. Multispecies temporal dynamics
2. Seasonal variation
- 3. Vegetation associations***

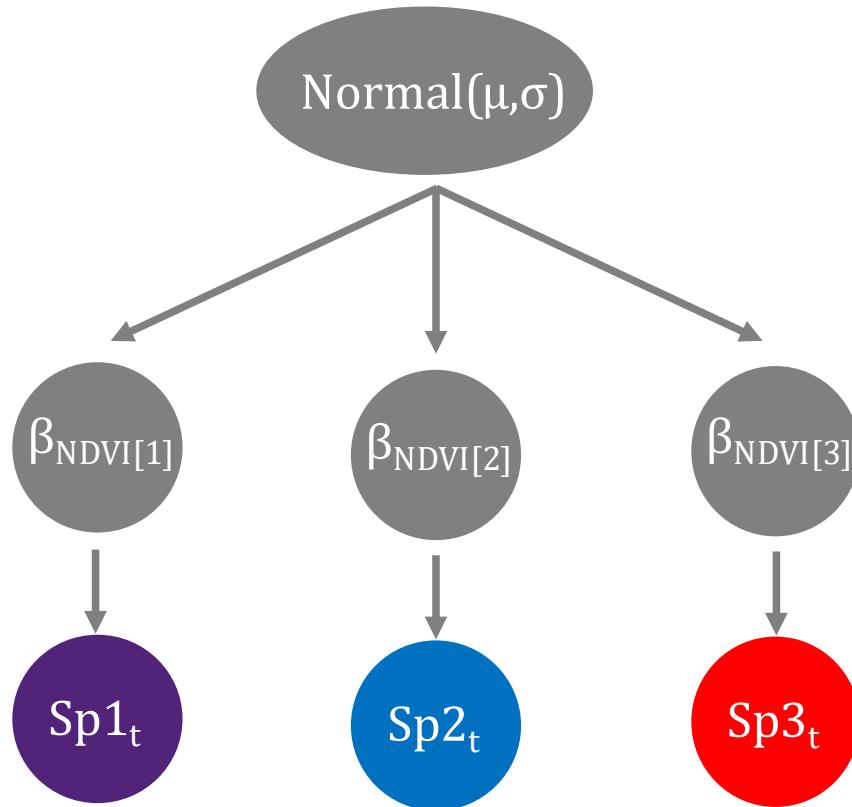




Sunrise in Cave Creek Canyon

Debra Davison

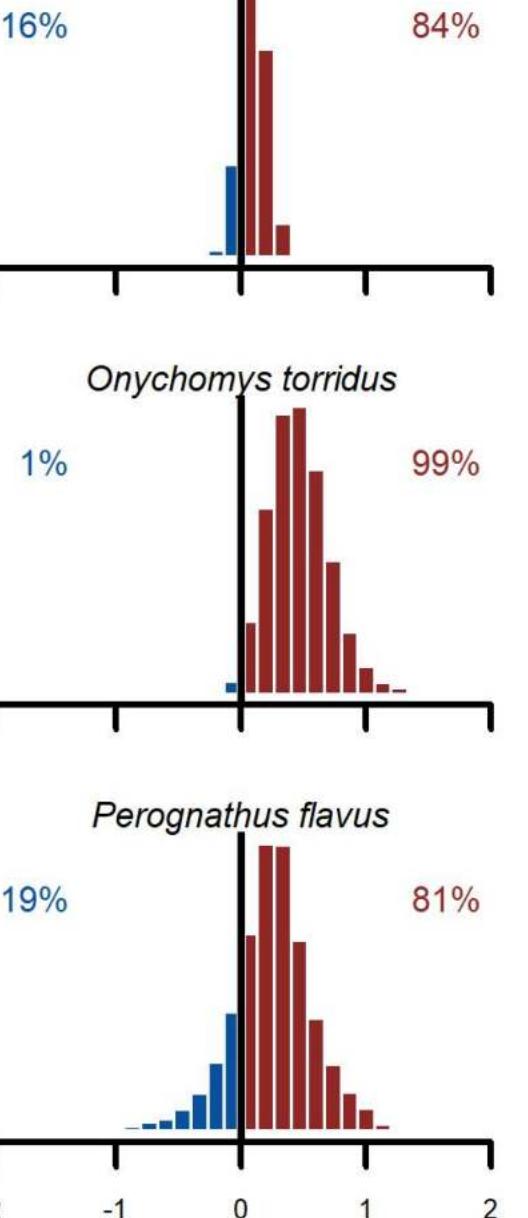
Hierarchical slopes for associations with NDVI moving average



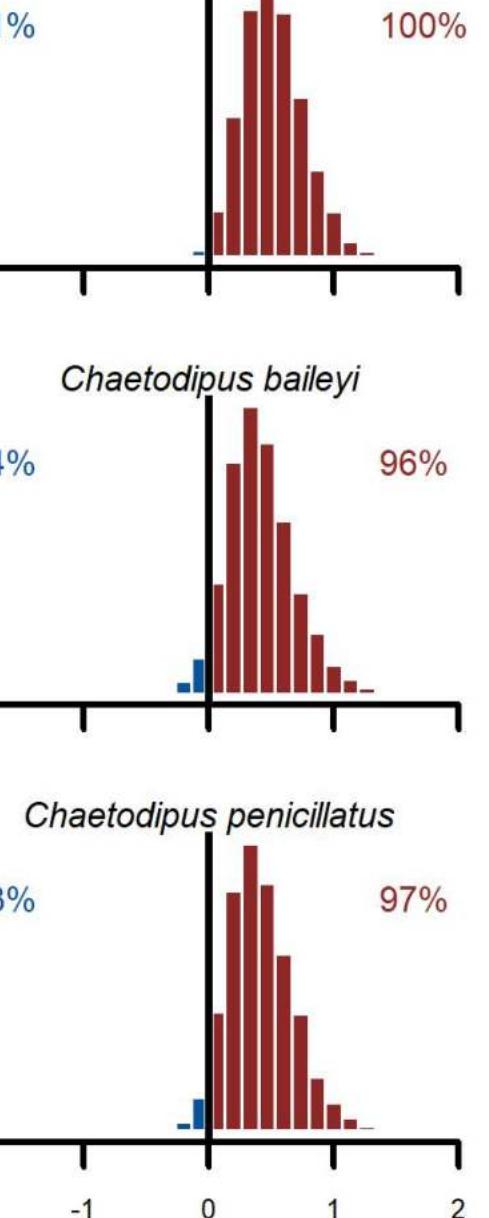
What did we find?



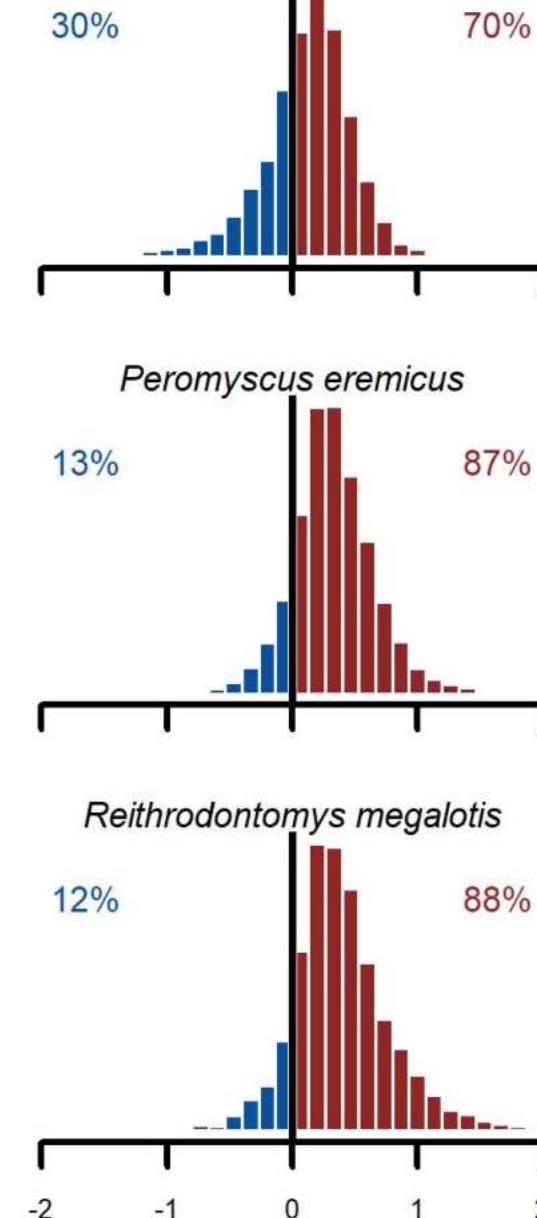
Dipodomys merriami



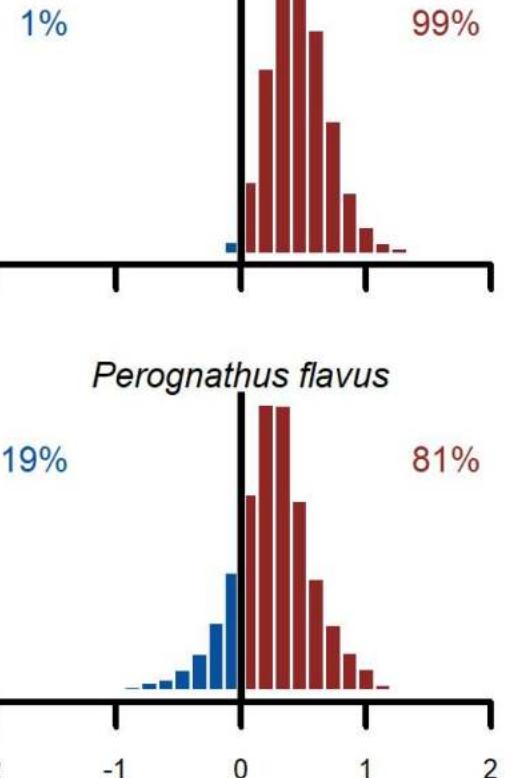
Dipodomys ordii



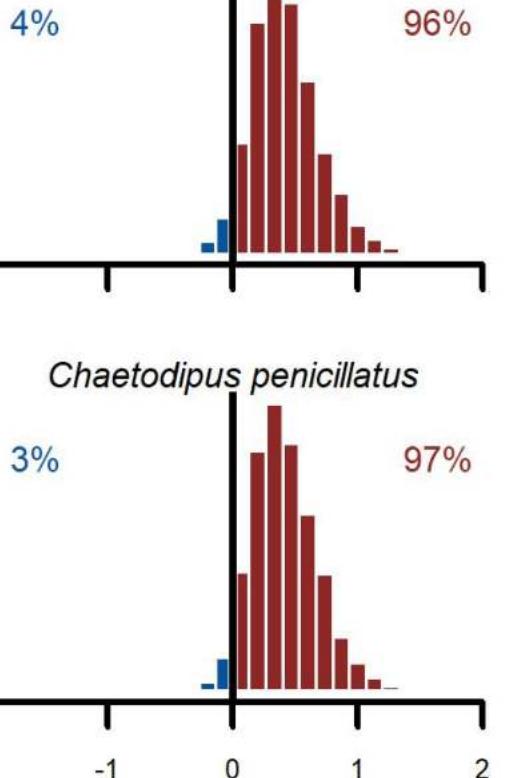
Onychomys leucogaster



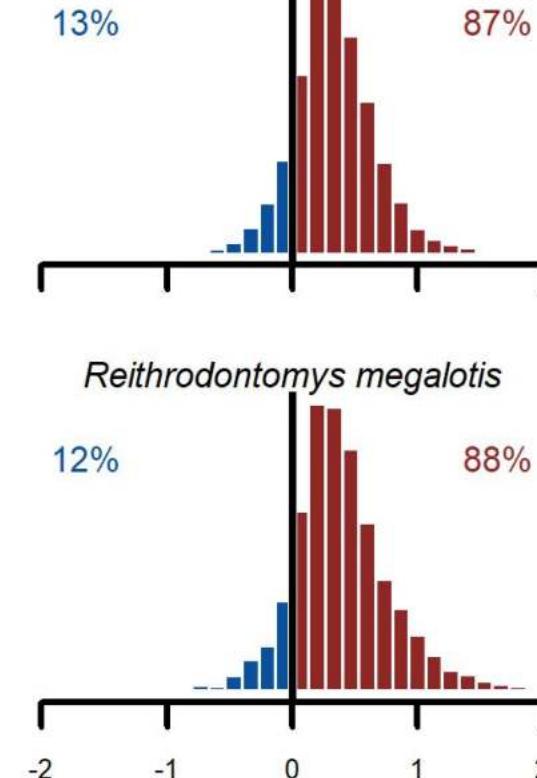
Onychomys torridus



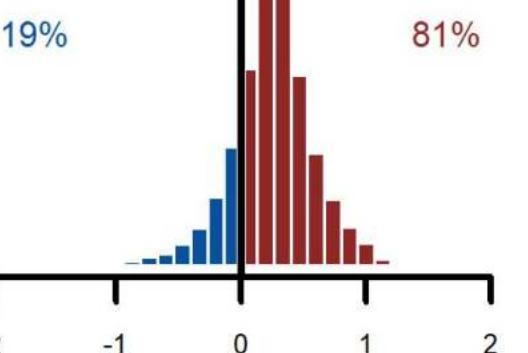
Chaetodipus baileyi



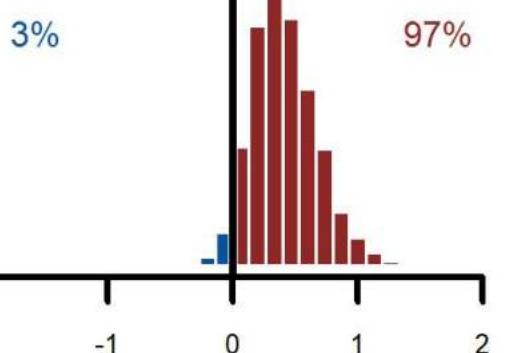
Peromyscus eremicus



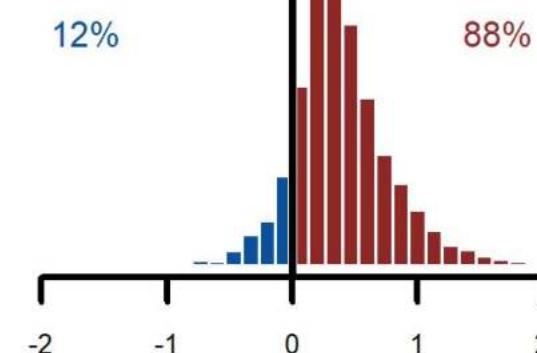
Perognathus flavus



Chaetodipus penicillatus



Reithrodontomys megalotis

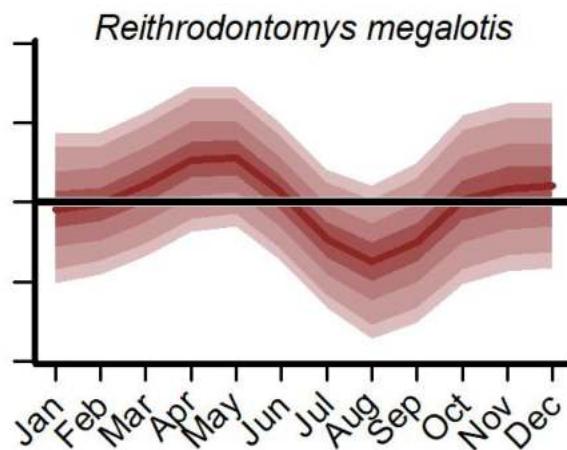
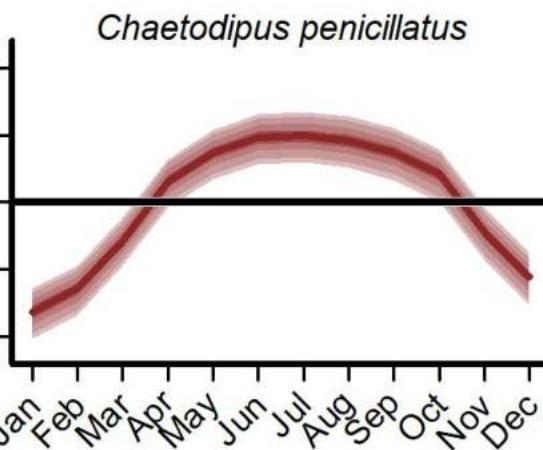
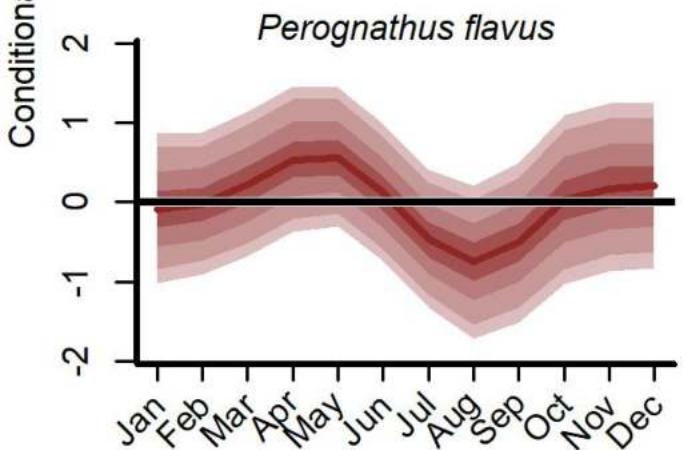
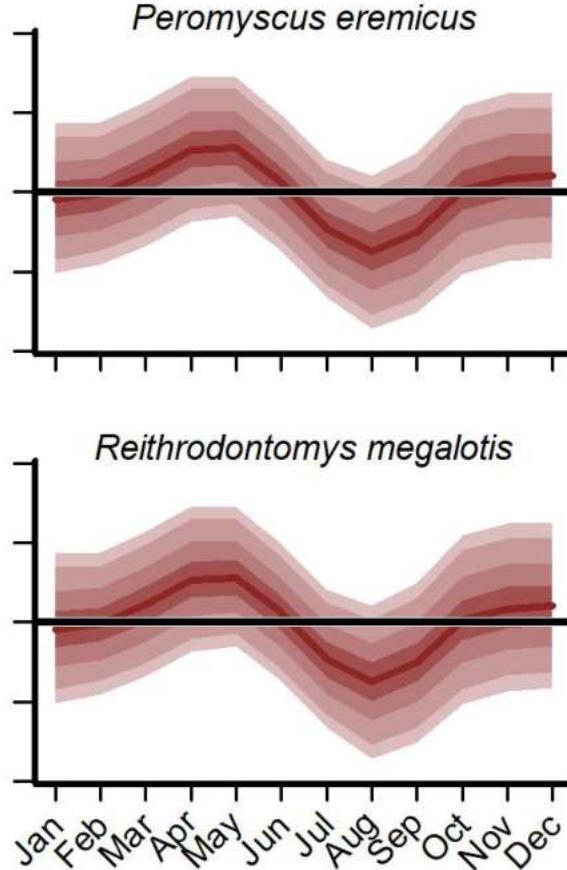
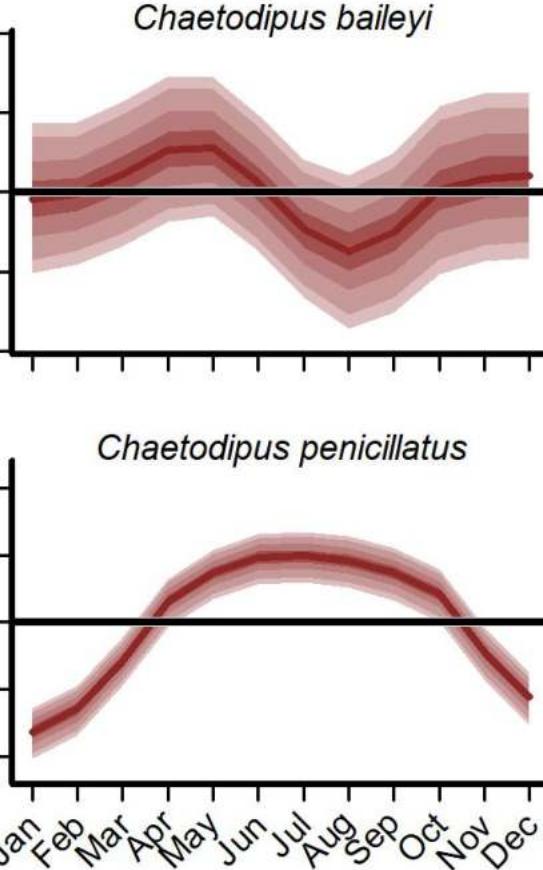
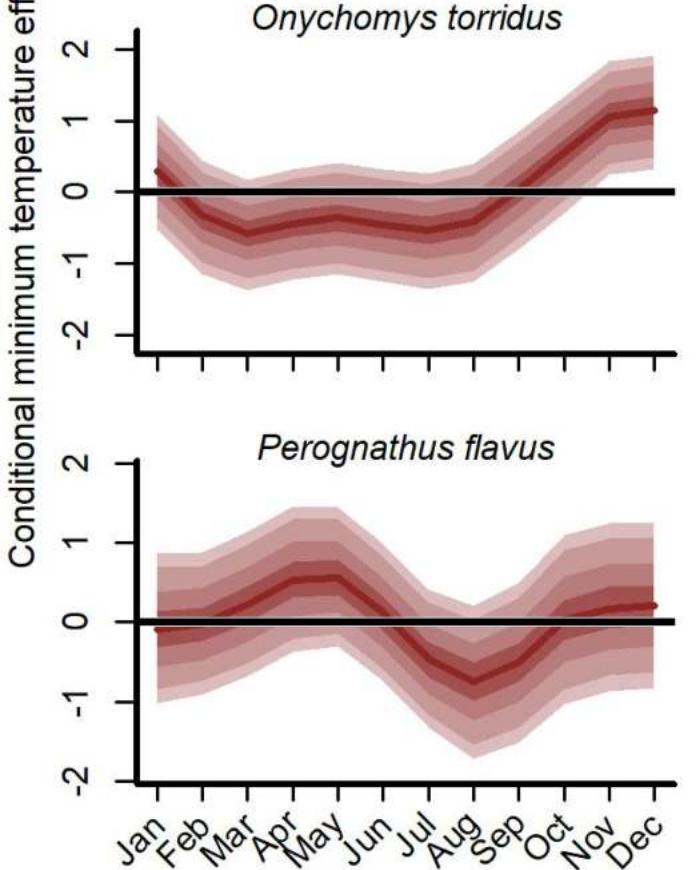
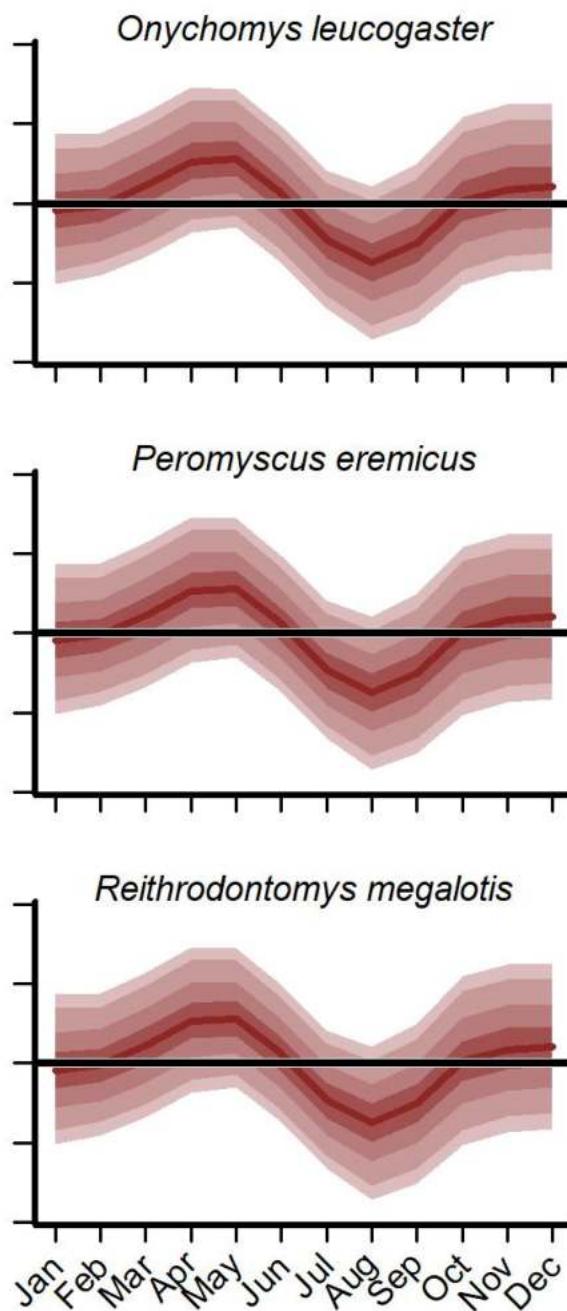
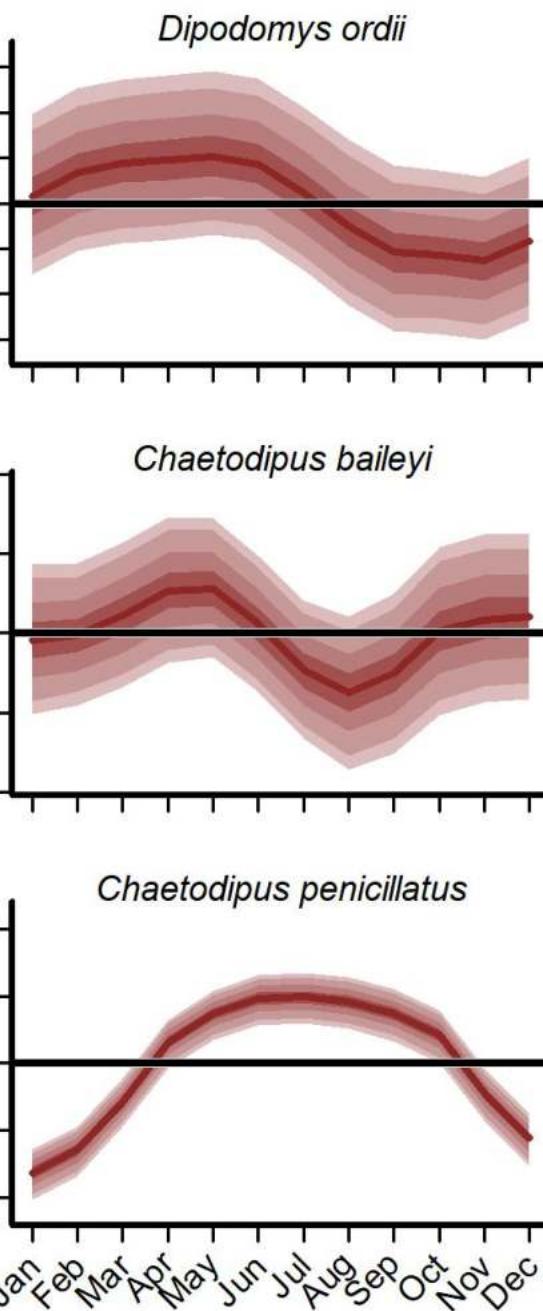
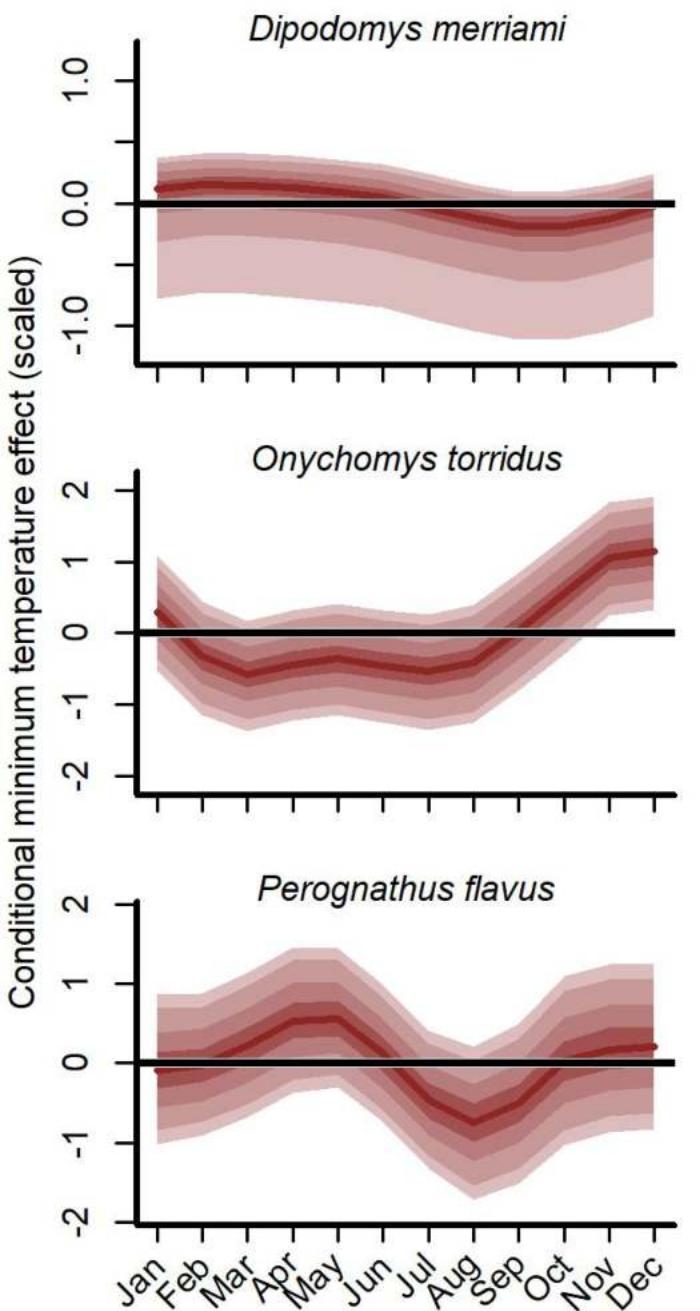


Expected change in captures with higher NDVI

What did we find?

1. Higher NDVI = more captures



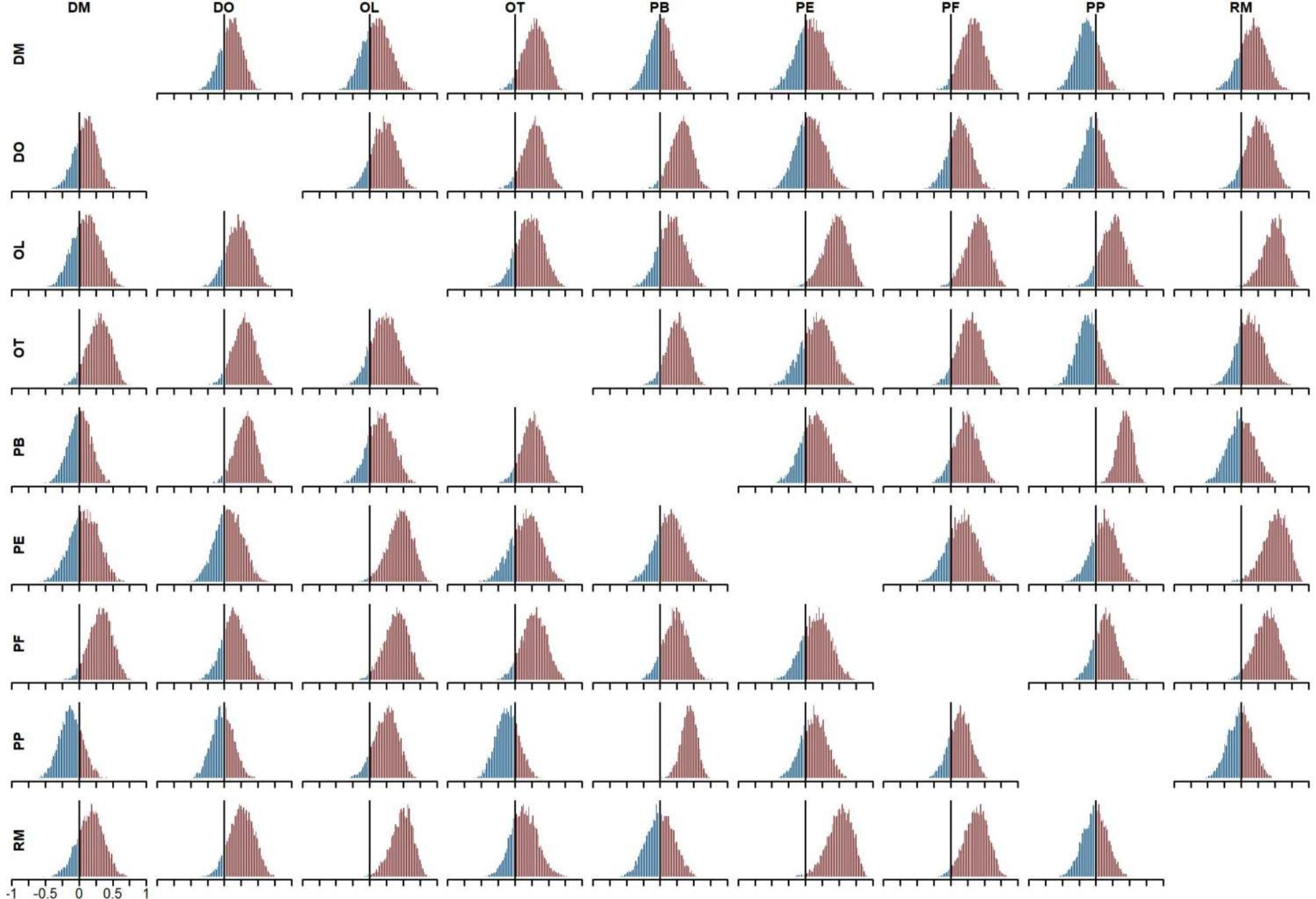


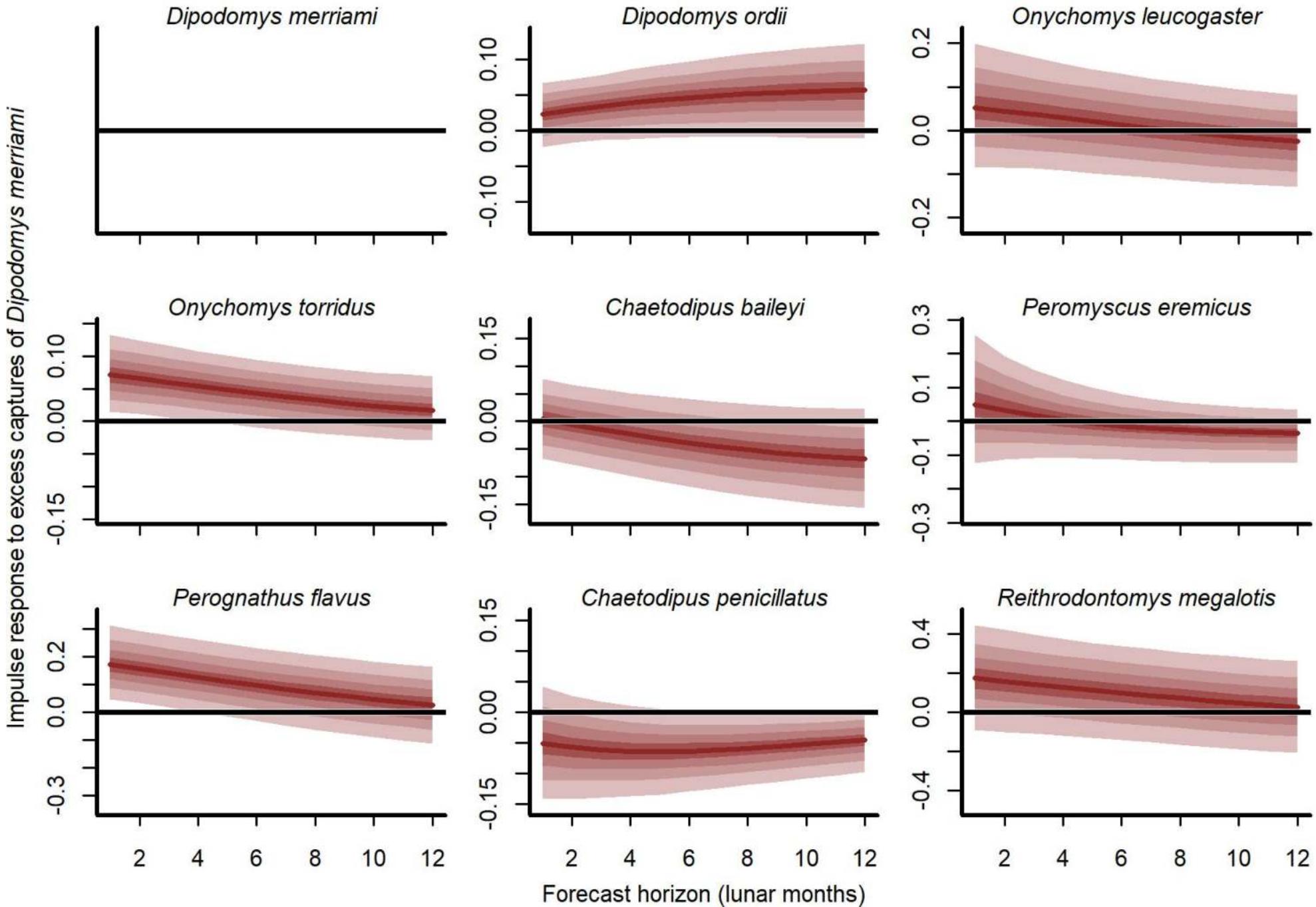
What did we find?

1. Higher NDVI = more captures

2. Varying seasonal effects



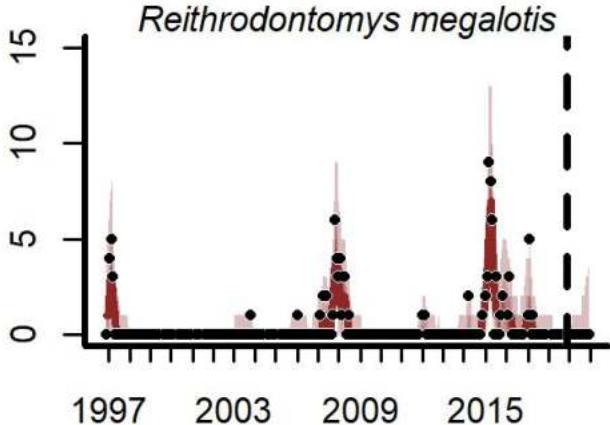
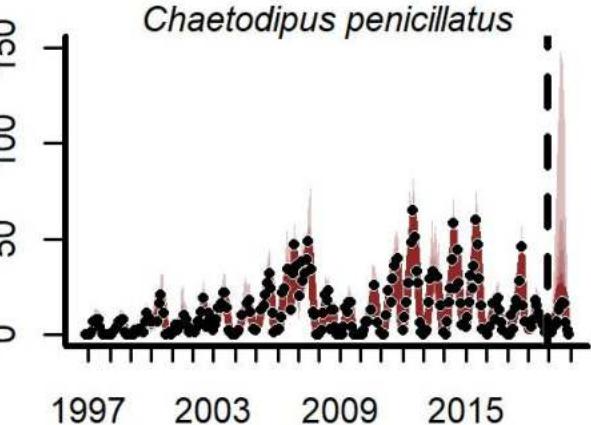
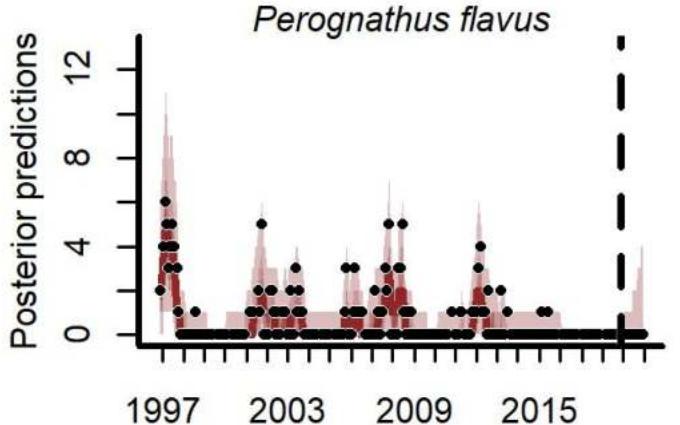
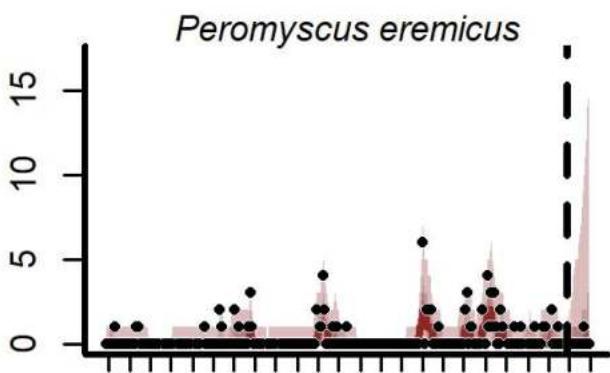
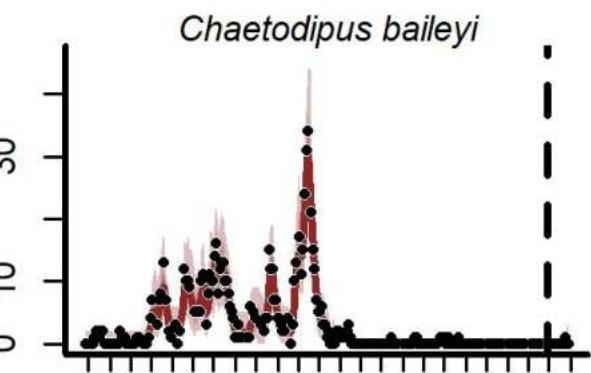
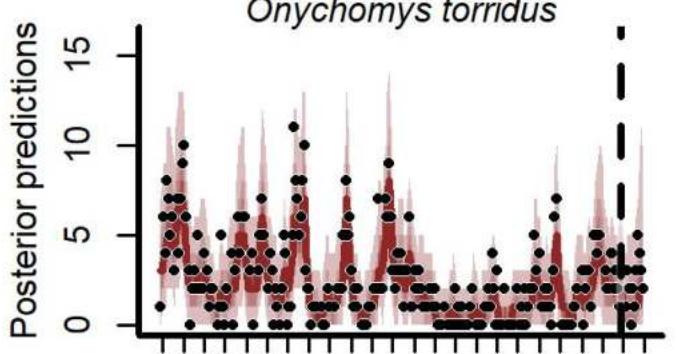
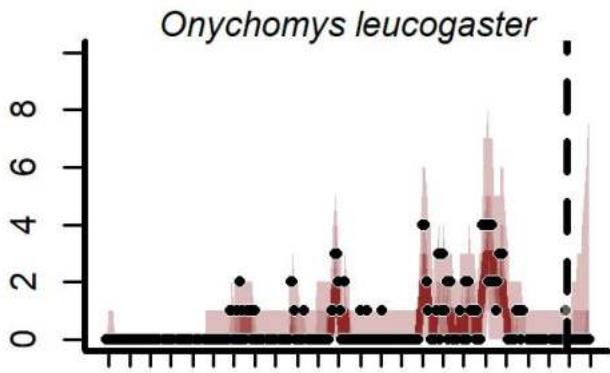
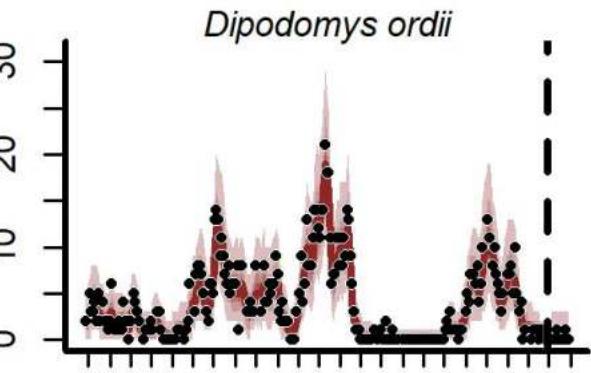
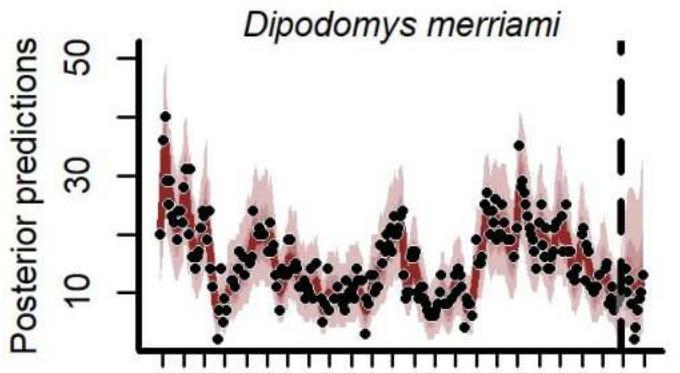


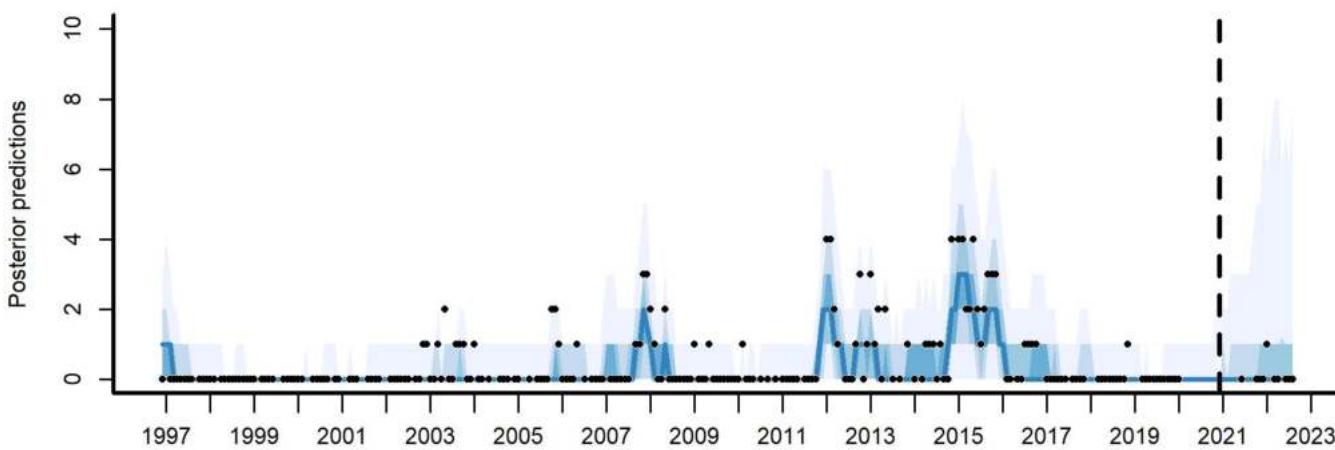
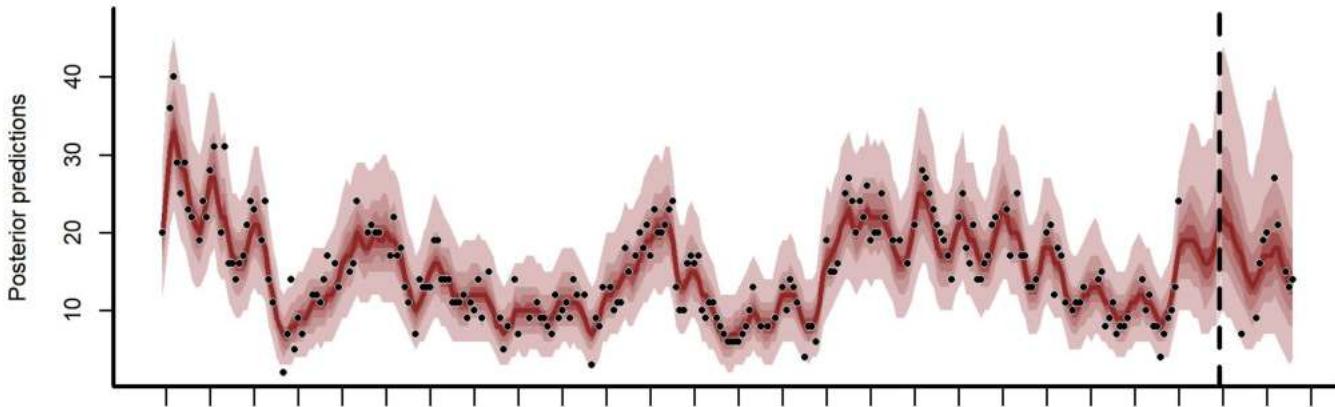
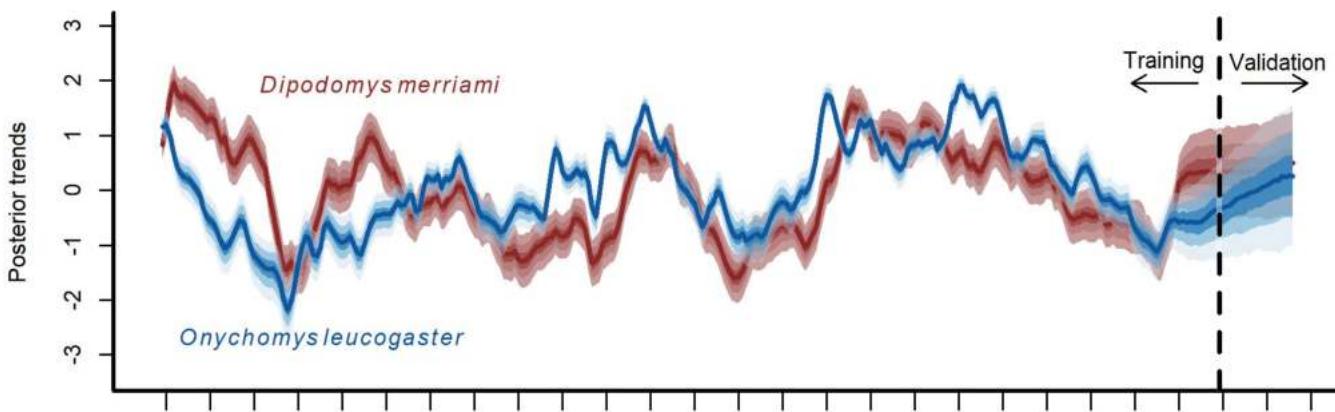


What did we find?

1. Higher NDVI = more captures
2. Varying seasonal effects
- 3. Complex dependencies***







What did we find?

1. Higher NDVI = more captures
2. Varying seasonal effects
3. Complex dependencies
- 4. Improved forecasts***



Thank you.
Questions?