

FYS2150

Lab Report: Elasticity

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Abstract

A study on two different methods to determine the Young's modulus of a brass rod.

1 Introduction

2 Theory

2.1 Euler-Bernoulli beam theory

$$h(m) = \frac{mgl^3}{48EI} \quad (1)$$

$$E = \frac{4l^3g}{3\pi|A|d^4} \quad (2)$$

2.2 Errors

When performing arithmetic operations on recorded data, the uncertainty in the data must also carry over to the derived results. How these uncertainties carry over in different operations can be found in Practical Physics [1].

3 Experimental Procedure

3.1 Three-point flexural test

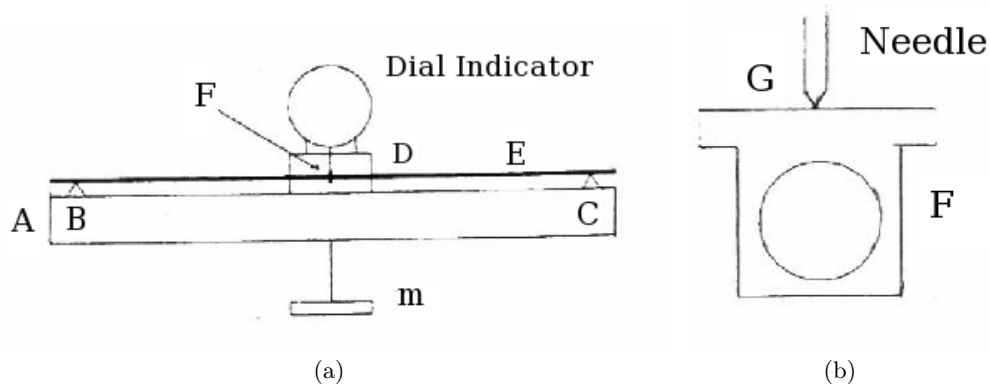


Figure 1: (a) shows the apparatus used for measuring the deflection of a rod and (b) a cross section of the apparatus at point F.

Using 1a as a reference; The brass rod, A, was laid on the "knives" B and C. In the middle of the rod, there was a ring as shown in Fig. 1b. The flat surface of the ring was in contact with the needle of the dial gage at G. In order to ensure that the flat surface of the ring was at right angle with the needle, we turned the rod such that the reading of the dial gage would be at a minimum, as the skewer the surface, the greater the reading. This process was repeated at the start of every attempt of the experiment.

3.2 Measuring the speed of sound in the rod

The brass rod, with a ring attached to it (same as before), was laid to rest on the flat side of the ring on a solid surface such that the rod is held up by the ring. We also made sure that the rod was not to be disturbed in any way while it was vibrating. When hit with a hammer, it will emit a sound consisting of different frequencies. Following are the two different methods we used for determining the root frequency of the rod. During both experiments, we ensured there were no significant noise pollution during our recording (By which i mean people performing the same experiment as us).

3.2.1 By hearing for beats

A speaker was connected to a signal generator. We started the signal generator at 1200Hz and hit the brass rod with a plastic hammer on the the flat surface on one end of the rod. By ear, there was an audible beat due to the superposition of the two signals. We adjusted the signal generator such that the the frequency of the beat was minimized,

and there was essentially no audible difference between the two signals. We did this by trying above and below where we thought the root frequency was, eventually zeroing in on a value.

3.2.2 By Fourier transform

A USB microphone was placed close to the rod, and faced towards it. The microphone was connected to a computer running matlab, with a script that collects audio data from it and Fourier transforms it using FFT. The recordings made were made with a sampling frequency of 8×1024 Hz and varying durations. As before, we hit the rod using a plastic hammer and recorded the data.

4 Results

4.1 Results from Three-point flexural test

Table 1: Deflection of rod

Attempt no.	h(0kg) [mm]	h(0.5kg) [mm]	h(1kg) [mm]	h(1.5kg) [mm]	h(2.0kg) [mm]	h(2.5kg) [mm]	h(3.0kg) [mm]	h(3.5kg) [mm]
1	9.44	8.72	8.00	7.28	6.58	5.84	5.15	4.43
2	9.42	8.70	7.98	7.26	6.53	5.80	5.09	4.39
3	9.42	8.71	7.98	7.26	6.53	5.80	5.09	4.37
4	9.41	8.69	7.97	7.25	6.52	5.79	5.08	4.36
5	9.42	8.70	7.98	7.26	6.70	5.87	5.19	4.51

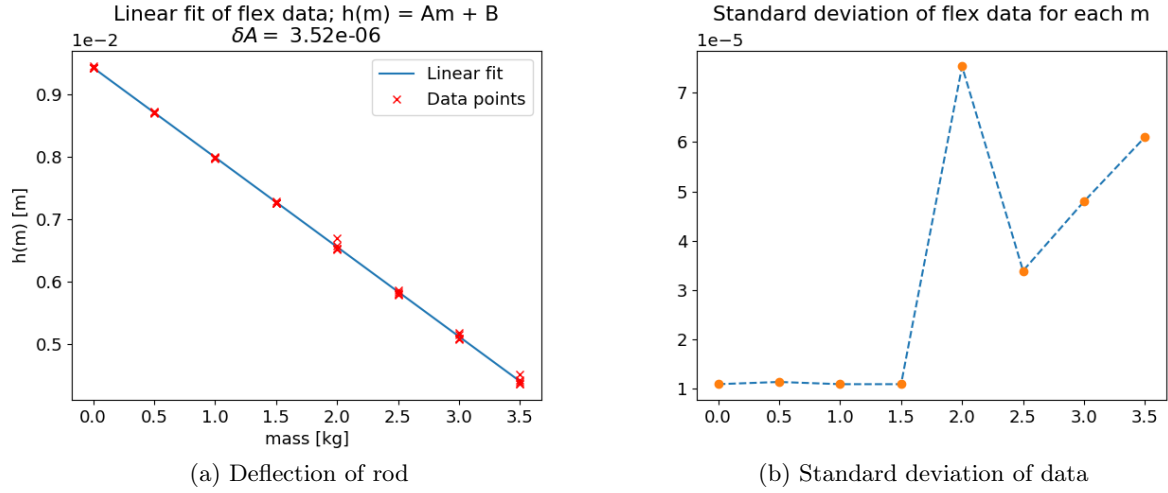


Figure 2: (a) Shows the deflection of the brass rod measured by the dial gague. (b) Shows the standard deviation of the data points in (a) at their respective masses

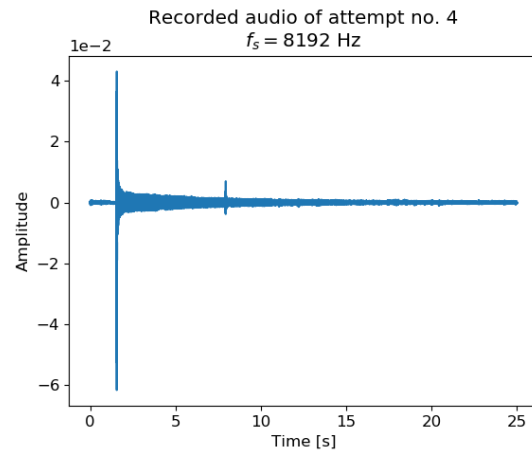
Table 1 contains the deflection data recorded¹ with the dial gague where the loads listed are from the rough, uncalibrated masses. Their corrected value is listed in ??.

Fig. 2a contains all the recorded data, as well as a linear fit on the mean deflection for each load using corrected values for the mass, m . The error of the linear fit, $h(m) = Am + B$, $\delta A = 3.52e - 06$. Fig. 2b contains the standard deviation of the deflection values for each load.

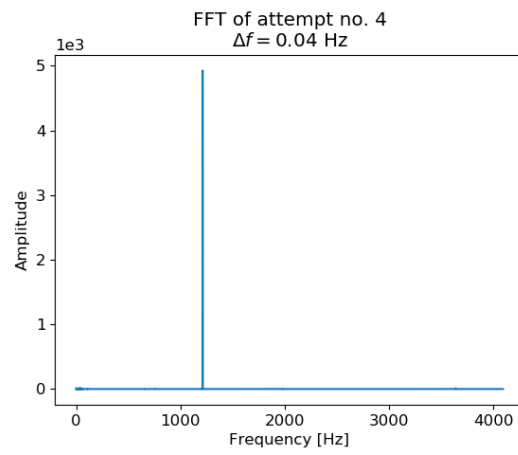
4.2 Results from measuring the speed of sound in the rod

When hearing for beats, me and my lab-partner decided that the root frequency was ≈ 1240 Hz.

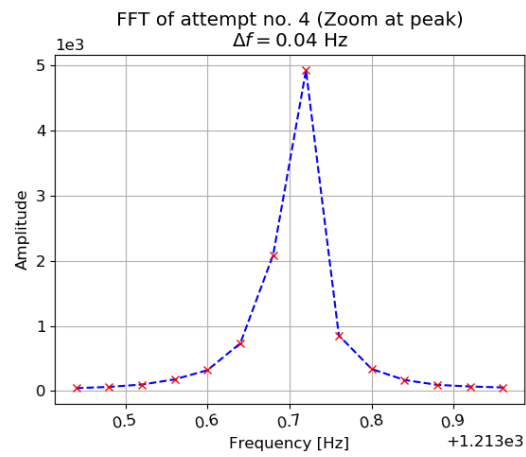
¹I did not take note of the model number of the particular dial gague that was used during the lab. While working on this report, i have become aware that each Baker dial gague is individually calibrated. Therefore, i have no values for the instrumental error in the deflection measurements.



(a) Time domain



(b) Frequency domain



(c) Zoomed frequency domain

Figure 3: All of the plots generated for attempt no. 4

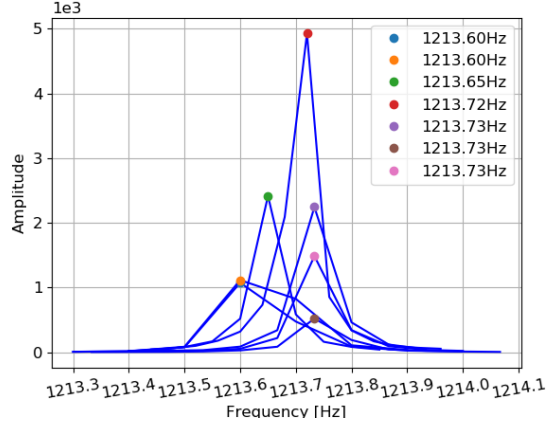


Figure 4: Zoomed frequency plot for all 7 attempts.

Fig. 3 contains the data and derived results from our fourth attempt of the experiment. We performed a total of 7 attempts, which all yielded in similar results to attempt no. 4. The data yielded from all of the attempts is summarized in Fig. 4 which shows the peaks in the frequency domain in one plot. Table 2 contains all of the relevant numbers related to each attempt.

Table 2: FFT data

Attempt no.	f [Hz]	Δf [Hz]	t [s]	f_s [Hz]
1	1213.60	0.10	10	8192
2	1213.60	0.10	10	8192
3	1213.65	0.05	20	8192
4	1213.72	0.04	25	8192
5	1213.72	0.04	25	8192
6	1213.72	0.07	15	8192
7	1213.73	0.07	15	8192

5 Discussion

6 Conclusion

References

- [1] G. L. Squires. *Practical Physics 4th Edition*. Cambridge University Press, 2001.

*

A Code

All of the code used to produce this report. Anything noteworthy should already be mentioned in the main body of the report. Note that when this code was written, readability was not a huge concern, so some of it may not be very easy to interpret.

scripts/FFTlyd.py

```
1 #!/usr/bin/env python
2 # -*- coding: utf-8 -*-
3 """
4 Generates the same figures as FFTlyd.m
5 author: Nicholas Karlsen
6 """
7 import scipy.io as sio
8 import matplotlib.pyplot as plt
9 import numpy as np
10
11
12 # Sets font size of matplotlib
13 plt.rcParams.update({'font.size': 12})
14
15
16 def import_matlab(filename):
17     # Opens .mat file
18     mfile = sio.loadmat(filename)
19     # Fetches data
20     data = mfile.get("data")
21     energi = mfile.get("energi")
22     fut = mfile.get("fut")
23     L = mfile.get("L")
24     t = mfile.get("t")
25
26     return data, energi, fut, L, t
27
28
29 rel_path = "data/"
30 n = 1
31 mat_file = "forsok%i.mat" % n
32
33
```

```

34 def raw_fig(filename):
35     data, energi, fut, L, t = import_matlab(filename)
36     plt.plot(t, data)
37     plt.xlabel("Time [s]")
38     plt.ylabel("Amplitude")
39     plt.ticklabel_format(style='sci', axis='y', scilimits=(0,0))
40
41
42 raw_fig(rel_path + "forsok1.mat")
43 plt.title("Recorded audio of attempt no. 1\n$f_s = 8192$ Hz")
44 plt.savefig("raw_exp2_1.png")
45 plt.close()
46
47 raw_fig(rel_path + "forsok4.mat")
48 plt.title("Recorded audio of attempt no. 4\n$f_s = 8192$ Hz")
49 plt.savefig("raw_exp2_4.png")
50 plt.close()
51
52
53 def figure1(filename):
54     data, energi, fut, L, t = import_matlab(filename)
55     fut = np.transpose(fut)
56     fh = int(len(energi) / 2.0) # half lenght of data
57     # Only plot first half of data, as FF mirrors in half-way point.
58     plt.plot(fut[:fh], energi[:fh])
59     plt.xlabel("Frequency [Hz]")
60     plt.ylabel("Amplitude")
61     plt.ticklabel_format(style='sci', axis='y', scilimits=(0,0))
62
63
64 figure1(rel_path + "forsok1.mat")
65 plt.title("FFT of attempt no. 1\n$\Delta f=0.10$ Hz")
66 plt.savefig("energy_exp2_1.png")
67 plt.close()
68
69 figure1(rel_path + "forsok4.mat")
70 plt.title("FFT of attempt no. 4\n$\Delta f=0.04$ Hz")
71 plt.savefig("energy_exp2_4.png")
72 plt.close()
73
74 eigenfreqs = []
75
76
77 def figure2(filename, style="-", cross=0):
78     data, energi, fut, L, t = import_matlab(filename)
79     fut = np.transpose(fut)
80
81     fh = int(len(energi) / 2.0) # half lenght of data
82     izeak = np.argmax(energi[:fh])
83
84     eigenfreqs.append(fut[izeak])
85
86     i = izeak

```



```

87     while energi[i] > np.amax(energi[:fh]) * 0.01:
88         i -= 1
89
90     j = ipeak
91     while energi[j] > np.amax(energi[:fh]) * 0.01:
92         j += 1
93
94     plt.plot(fut[i:j], energi[i:j], color="blue", linestyle=style)
95     if cross == 1:
96         plt.plot(fut[i:j], energi[i:j], "rx")
97     else:
98         plt.plot(fut[ipeak], energi[ipeak], "o", label="%.2fHz" % fut[ipeak
99 ])
100     plt.grid("on")
101
102 figure2(rel_path + "forsok1.mat", style="—", cross=1)
103 plt.xlabel("Frequency [Hz]")
104 plt.ylabel("Amplitude")
105 plt.ticklabel_format(style='sci', axis='y', scilimits=(0,0))
106 plt.xticks(rotation=10)
107 plt.title("FFT of attempt no. 1 (Zoom at peak)\n$\Delta f=0.10$ Hz")
108 plt.savefig("freq_exp2_1.png")
109 plt.close()
110
111
112 figure2(rel_path + "forsok4.mat", style="—", cross=1)
113 plt.xlabel("Frequency [Hz]")
114 plt.ylabel("Amplitude")
115 plt.ticklabel_format(style='sci', axis='y', scilimits=(0,0))
116 plt.xticks(rotation=10)
117 plt.title("FFT of attempt no. 4 (Zoom at peak)\n$\Delta f=0.04$ Hz")
118 plt.savefig("freq_exp2_4.png")
119 plt.close()
120
121
122 for i in range(1, 8):
123     figure2(rel_path + "forsok%i.mat" % i)
124
125 plt.xlabel("Frequency [Hz]")
126 plt.ylabel("Amplitude")
127 plt.legend()
128 plt.ticklabel_format(style='sci', axis='y', scilimits=(0,0))
129 plt.xticks(rotation=10)
130 plt.savefig("freq_exp2_all.png")
131 plt.close()

```

scripts/FYS2150lib.py

```

1 #!/usr/bin/env python
2 # -*- coding: utf-8 -*-
3 """
4 A collection of commonly used functions in FYS2150.

```

```

5 author: Nicholas Karlsen
6 """
7 import numpy as np
8
9
10 def stddev(x):
11     """
12     Finds the standard deviation, and standard deviation of
13     a 1D array of data x.
14     See. Eqn D. Page 24 squires
15     """
16     n = len(x)
17     sigma = np.sqrt((np.sum(x**2) - 1.0 / n * np.sum(x)**2) / (n - 1))
18     sigma_m = np.sqrt((np.sum(x**2) - 1.0 / n * np.sum(x)**2) / (n * (n - 1)))
19
20     return sigma, sigma_m
21
22
23 def linfit(x, y):
24     """
25     Finds the line of best-fit in the form y=mx+c given two
26     1D arrays x and y.
27     """
28     n = np.size(y)
29     D = np.sum(x**2) - (1.0 / n) * np.sum(x)**2
30     E = np.sum(x * y) - (1.0 / n) * np.sum(x) * np.sum(y)
31     F = np.sum(y**2) - (1.0 / n) * np.sum(y)**2
32
33     dm = np.sqrt(1.0 / (n - 2) * (D * F - E**2) / D**2)
34     dc = np.sqrt(1.0 / (n - 2) * (float(D) / n + np.mean(x)) *
35                     ((D * F - E**2) / (D**2)))
36     m = float(E) / D
37     c = np.mean(y) - m * np.mean(x)
38
39     return m, c, dm, dc

```

scripts/lab_data.py

```

1 #!/usr/bin/env python
2 # -*- coding: utf-8 -*-
3 """
4 Contains all of the data collected in the
5 Elasticity lab, module 2 of FYS2150
6 author: Nicholas Karlsen
7 """
8
9 from pylab import *
10 import scipy.constants as const
11 import FYS2150lib as fys
12
13
14 rcParams.update({'font.size': 13}) # Sets font size of plots

```

```

15
16
17 def E_sound(f, L, d, M):
18     '''
19     Returns youngs modulus given
20     f = root frequency
21     L = lenght of rod
22     d = diameter of rod
23     M = mass of rod
24     '''
25     return (16.0 * M * L * f**2) / (np.pi * d**2)
26
27
28 def E_sound_error(E, sd, sf, sL, sM, d, f, L, M):
29     return E * np.sqrt((2 * sd / d)**2 + (2 * sf / f)**2 +
30                       (2 * sL / L)**2 + (2 * sM / M)**2)
31
32
33 def weight_data(set=1):
34     "set decides which data set the function returns."
35     set = set.lower() # Forces lowercase
36     sets = ["masses", "rod"]
37     # Mass of weights measured with balance
38     m_a_balance = 500.1e-3
39     m_b_balance = 1000.3e-3
40     m_c_balance = 2000.5e-3
41
42     # Mass of reference weights
43     m_reference = array([0.5, 1.0, 2.0])
44     m_reference_balance = array([500.0e-3, 999.9e-3, 2000.1e-3]) # Weighed
45
46     # Using linear fit to correct for error in balance
47     a, b, da, db = fys.linfit(m_reference, m_reference_balance)
48     # Corrected masses
49     m_a = (m_a_balance - b) / a # approx 500g
50     m_b = (m_b_balance - b) / a # approx 1000g
51     m_c = (m_c_balance - b) / a # approx 2000g
52
53     if set == sets[0]: # Return corrected masses
54         return m_a, m_b, m_c
55
56     if set == sets[1]:
57         return
58
59     if set not in sets:
60         print "Invalid set"
61         print "List of valid sets:", sets
62         print "exiting..."
63         exit()
64
65
66 def experiment1_data():
67     m_a, m_b, m_c = weight_data("masses")

```

```

68 mass_dat = array(
69     [0, m_a, m_b, m_a + m_b, m_c, m_a + m_c,
70     m_b + m_c, m_a + m_b + m_c]) # [Kg]
71
72 # Round 1: (in order)
73 h_1 = array([9.44, 8.72, 8.00, 7.28, 6.58, 5.84, 5.15, 4.43]) * 1e-3 #
74     [m]
75 # Round 2: (in order)
76 h_2 = array([9.42, 8.70, 7.98, 7.26, 6.53, 5.80, 5.09, 4.39]) * 1e-3 #
77     [m]
78 # Round 3: (in order)
79 h_3 = array([9.42, 8.71, 7.98, 7.26, 6.53, 5.80, 5.09, 4.37]) * 1e-3 #
80     [m]
81 # Round 4: (in order)
82 h_4 = array([9.41, 8.69, 7.97, 7.25, 6.52, 5.79, 5.08, 4.36]) * 1e-3 #
83     [m]
84 # Round 5: (in order)
85 h_5 = array([9.42, 8.70, 7.98, 7.26, 6.70, 5.87, 5.19, 4.51]) * 1e-3 #
86     [m]
87
88 h_mean = (h_1 + h_2 + h_3 + h_4 + h_5) / 5.0
89
90 m, c, dm, dc = fys.linfit(mass_dat, h_mean)
91
92 mass = linspace(0, 3.5, 8)
93 h_mass = m * mass + c # h(m)
94
95 def plotdata():
96     h_sets = [h_1, h_2, h_3, h_4, h_5]
97     plot(mass, h_mass, label="Linear fit")
98     # errorbar(mass, m * mass + c, yerr=dm, color='blue', fmt='o',
99     label='Error Range')
100
101     for dat in h_sets:
102         plot(mass_dat, dat, "x", color="r")
103         plot(NaN, NaN, "xr", label="Data points")
104         xlabel("mass [kg]")
105         ylabel("h(m) [m]")
106         ticklabel_format(style='sci', axis='y', scilimits=(0,0))
107         legend()
108         title("Linear fit of mean deflection data; h(m) = A m + B \n $ \delta A
109             = $ %.2e" % dm)
110         savefig("figs/h_m_fig.png")
111         close()
112 plotdata()
113
114 def plot_stddev():
115     """Plots the standard deviation of h(m)
116     as m is increased"""
117     deviation = np.zeros(len(h_1))
118     for i in xrange(len(h_1)):
119         deviation[i] = fys.stddev(array([h_1[i],

```

```

114                                     h_2[i],
115                                     h_3[i],
116                                     h_4[i],
117                                     h_5[i]))[0]
118     print i
119     print deviation
120     print len(mass_dat), len(deviation)
121     plot(mass_dat, deviation, linestyle="—")
122     plot(mass_dat, deviation, "o")
123     ticklabel_format(style='sci', axis='y', scilimits=(0,0))
124     plt.title("Standard deviation of deflection for each m\n")
125     savefig("figs/h_m_deviation.png")
126     close()
127 plot_stddev()
128
129 # lengde mellom yttersidene til festepunktene til knivene
130 # PEE WEE 2m Y612CM LUFKIN +- 0.01cm
131 l_AB = 133.9 * 1e-2 # [m]
132 # diameter til festepunkter
133 # Moore & Wright 1965 MI +- 0.01mm
134 l_AB_diameter = 4.09 * 1e-3 # [mm]
135 # anta festepunktet er paa midtten saa trekk fra diameter totalt sett
136 l = l_AB - l_AB_diameter
137
138 #Maalinger av stangens diameter d paa forskjellige punkter
139 # Moore & Wright 1965 MI +- 0.01mm
140 d = array([15.98, 15.99, 15.99, 16.00, 15.99, 15.99, 15.98, 15.99,
15.99, 15.99]) * 1e-3 # [m]
141 d_m = mean(d); #m
142
143 A = abs((h_mass - c) / mass)
144
145 E = mean(4.0 * l**3 * const.g / (3 * pi * A * d_m**4)[1:-1])
146 print E
147
148 def experiment_2():
149     ''' Data pertaining to the audio exp. '''
150
151
152 if __name__ == "__main__":
153     experiment1_data()

```