# **FYS2150** Lab Report: Elasticity

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A study on two different methods to determine the Young's modulus of a brass rod.

#### INTRODUCTION

#### II. THEORY

#### Euler-Bernoulli beam theory

$$h(m) = \frac{mgl^3}{48EI} \tag{1}$$

$$E = \frac{4l^3g}{3\pi |A|d^4}$$
 (2)

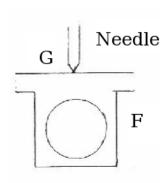


FIG. 2. Cross-section of apparatus where the dial indicator meets the ring in Fig. 1

[1]

#### В. Errors

[2]

#### EXPERIMENTAL PROCEDURE

#### Three-point flexural test

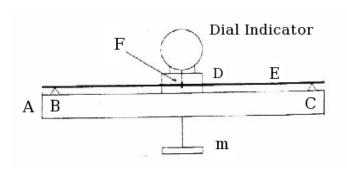


FIG. 1. Apparatus for measuring the deflection of a rod

The brass rod was placed in an apparatus similar to that which is depicted in Fig. 1.

## Measuring the speed of sound in the rod

The brass rod, with a ring attached to it (same as before), was laid to rest on the flat side of the ring on a solid surface such that the rod is held up by the ring. We also made sure that the rod was not to be disturbed in any way while it was vibrating. When hit with a hammer, it will emit a sound consisting of different frequencies. Following are the two different methods we used for determining the root frequency of the rod. During both experiments, we ensured there were no significant noise pollution during our recording (By which i mean people performing the same experiment as us).

# 1. By hearing for beats

A speaker was connected to a signal generator. We started the signal generator at 1200Hz and hit the brass rod with a plastic hammer on the flat surface on one end of the rod. By ear, there was an audible beat. We adjusted the signal generator such that the frequency of the beat was minimized, and there was essentially no audible difference between the two signals. We did this by trying above and below where we thought the root frequency was, eventually zeroing in on a value.

## 2. By Fourier transform

A USB microphone was placed close to the rod, and faced towards it. The microphone was connected to a computer running matlab, with a script that collects audio data from it and Fourier transforms it using FFT. The recordings made were made with a sampling frequency of  $8 \times 1024$  Hz and varying durations.

# IV. RESULTS

- V. DISCUSSION
- VI. CONCLUSION

[1] Wikipedia contributors. Eulerbernoulli beam theory — wikipedia, the free encyclopedia, 2018. [Online; accessed 8-April-2018].

[2] G. L. Squires. *Practical Physics 4th Edition*. Cambridge University Press, 2008.

#### CODE

All of the code used to produce this report. Anything noteworthy should already be mentioned in the main body of the report.

### scripts/lab\_data.py

```
#!/usr/bin/env python
   \# -*- coding: utf-8 -*-
 3
   Contains all of the data collected in the
   Elacticity \ lab \ , \ module \ 2 \ of \ FYS2150
 5
   author: Nicholas Karlsen
 7
 8
 9
   from pylab import *
10
  import scipy.constants as const
   import FYS2150lib as fys
11
12
13
14
   def weight_data(set=1):
        "set decides which data set the function returns."
15
        set = set.lower()  # Forces lowercase
sets = ["masses", "rod"]
16
17
        # Mass of weights measured with balance
18
19
        m_abalance = 500.1e-3
20
        m_b_balance = 1000.3e-3
21
        m_cbalance = 2000.5e-3
22
23
        # Mass of reference weights
24
        m_reference = array([0.5, 1.0, 2.0])
25
        m_reference_balance = array([500.0e-3, 999.9e-3, 2000.1e-3]) # Weight
26
27
        # Using linear fit to correct for error in balance
28
        a, b, da, db = fys.linfit(m_reference, m_reference_balance)
29
        # Corrected masses
       m_a = (m_a\_balance - b) / a

m_b = (m_b\_balance - b) / a
30
                                             # approx 500g
31
                                             # approx 1000g
        m_c = (m_c balance - b) / a
32
                                             # approx 2000g
33
34
        if set == sets[0]: # Return corrected masses
35
            return m_a, m_b, m_c
36
37
        if set = sets[1]:
38
            return
39
40
        if set not in sets:
            print "Invalid set"
41
            print "List of valid sets:", sets
42
            print "exiting ..."
43
44
            exit()
45
46
   def experiment1_data():
47
48
        m_a, m_b, m_c = weight_data("masses")
        mass_dat = array(
49
50
             [0, m_a, m_b, m_a + m_b, m_c, m_a + m_c,
                                                               # [Kg]
51
             m_b + m_c, m_a + m_b + m_c
52
53
        # Round 1: (in order)
        h_1 = array([9.44, 8.72, 8.00, 7.28, 6.58, 5.84, 5.15, 4.43]) * 1e-3 # [m]
54
55
        # Round 2: (in order)
56
        h_{-2} = \text{array}([9.42, 8.70, 7.98, 7.26, 6.53, 5.80, 5.09, 4.39]) * 1e-3 # [m]
57
        # Round 3: (in order)
        \mathtt{h\_3} \, = \, \mathtt{array} \, ( \, [ \, 9.42 \, , \, \, 8.71 \, , \, \, 7.98 \, , \, \, 7.26 \, , \, \, 6.53 \, , \, \, 5.80 \, , \, \, 5.09 \, , \, \, 4.37 \, ] \, ) \, \, * \, \, 1e-3 \, \, \# \, [m]
58
59
        # Round 4: (in order)
        h_{-4} = \operatorname{array}([9.41, 8.69, 7.97, 7.25, 6.52, 5.79, 5.08, 4.36]) * 1e-3 # [m]
60
61
        # Round 5: (in order)
        h_{-5} = array([9.42, 8.70, 7.98, 7.26, 6.70, 5.87, 5.19, 4.51]) * 1e-3 # [m]
62
63
```

```
64
        h_{mean} = (h_1 + h_2 + h_3 + h_4 + h_5) / 5.0
65
        m, c, dm, dc = fys.linfit(mass_dat, h_mean)
66
67
68
        mass = linspace(0, 3.5, 8)
        h_{-mass} = m * mass + c \# h(m)
69
70
71
72
        def plotdata():
73
            h_{-sets} = [h_{-1}, h_{-2}, h_{-3}, h_{-4}, h_{-5}]
            plot(mass, h_mass, label="Linear fit")
74
 75
            # errorbar(mass, m * mass + c, yerr=dm, color='blue', fmt='o', label='Error Range')
76
77
            for dat in h_sets:
                 plot(mass_dat, dat, "x", color="r", label="data points")
78
            xlabel("mass [kg]")
79
80
            ylabel("h(m) [m]")
81
            plt.legend()
82
            show()
83
        plotdata()
84
85
        \#\ lengte\ mellom\ yttersidene\ til\ festepunktene\ til\ knivene
86
        \# PEE WEE 2m Y612CM LUFKIN \leftarrow 0.01cm
        l_AB = 133.9 * 1e-2 \# [m]
87
        \# diameter til festepunkter
88
89
        # Moore & Wright 1965 MI + 0.01mm
90
        l_AB_diameter = 4.09 * 1e-3 \# [mm]
        # anta festepunktet er p
91
                                    midtden s
                                                 trekk fra diameter totalt sett
92
        l = l_AB - l_AB_diameter
93
94
        \#M\ linger\ av\ stangens\ diameter\ d\ p\ forskjellige\ punkter
        # Moore & Wright 1965 MI + 0.01mm
95
96
        d = \operatorname{array}([15.98, 15.99, 15.99, 16.00, 15.99, 15.99, 15.99, 15.99, 15.99, 15.99]) * 1e-3 \# [m]
97
        d_m = mean(d); \#m
98
99
        A = abs((h_mass - c) / mass)
100
101
        E = mean(4.0 * 1**3 * const.g / (3 * pi * A * d_m**4)[1:-1])
102
        print E
103
104
105 if __name__ = "__main__":
106
        experiment1_data()
```

### scripts/FYS2150lib.py

```
#!/usr/bin/env python
 2
   \# -*- coding: utf-8 -*-
 3
 4 A collection of commonly used functions in FYS2150.
 5
   author: Nicholas Karlsen
 6
 7
   import numpy as np
 8
 9
   \mathbf{def} \ \mathrm{stddev} \, (\, \mathrm{x} \,) :
10
11
12
        Finds the standard deviation, and standard deviation of
13
       a 1D array of data x.
14
        See. Eqn D. Page 24 squires
15
16
       n = len(x)
17
       sigma = np. sqrt ((np.sum(x**2) - 1.0 / n * np.sum(x)**2) / (n - 1))
18
       sigma_m = np. sqrt((np.sum(x**2) - 1.0 / n * np.sum(x)**2) / (n * (n - 1)))
19
20
       return sigma, sigma_m
21
22
23
   def linfit(x, y):
24
```

```
25
         Finds the line of best-fit in the form y=mx+c given two
         1D_{"""} arrays x and y.
26
27
28
         n \, = \, np \, . \, size \, (\, y \, )
29
         D = np.sum(x**2) - (1.0 / n) * np.sum(x)**2
        E = \text{np.sum}(x * y) - (1.0 / n) * \text{np.sum}(x) * \text{np.sum}(y)
F = \text{np.sum}(y**2) - (1.0 / n) * \text{np.sum}(y)**2
30
31
32
        33
34
35
36
37
38
39
         \mathbf{return}\ \mathbf{m},\ \mathbf{c}\ ,\ \mathbf{dm},\ \mathbf{dc}
```