# Swap

April 10, 2020

## 1 Entanglement Swapping

This script swaps entanglement between two spatially seperated qbits that do not come into direct contact with each other. Two qbit tomography and readout calibration are used to find the resulting state, before calculating the fidelity of the output to the expected output.

```
[1]: #importing necessary modules
     import numpy as np
     import pandas as pd
     import random
     %config InlineBackend.figure_format = 'svg' # Saves plots in svg format
     # qiskit modules
     import qiskit
     from qiskit import ClassicalRegister, QuantumRegister, QuantumCircuit, Aer
     from qiskit.tools.visualization import plot_state_city, plot_state_paulivec
     from qiskit.tools.monitor import job_monitor
     from qiskit.quantum_info import state_fidelity, concurrence, DensityMatrix
     # tomography functions
     from qiskit.ignis.verification.tomography import state_tomography_circuits, __
      \rightarrowStateTomographyFitter
     # readout calibration
     from qiskit.ignis.mitigation.measurement import complete_meas_cal, u
      \hookrightarrowCompleteMeasFitter
```

```
[2]: # importing IBMQ backends
from qiskit import IBMQ
ibmq_provider = IBMQ.load_account() # credentials stored on disk
device = ibmq_provider.get_backend('ibmqx2')

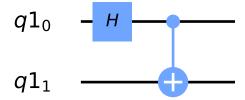
# necessary imports for noise modelling
from qiskit.providers.aer.noise import NoiseModel
noise_model = NoiseModel.from_backend(device)
coupling_map = device.configuration().coupling_map
basis_gates = noise_model.basis_gates
```

### 1.1 Defining the expected state

```
[3]: # creating a random initial state for 0th qbit
R = []
for i in range(3):
    R.append(10*random.random())

qreg = QuantumRegister(4)
qreg_exp = QuantumRegister(2)
qc_expected = QuantumCircuit(qreg_exp)
# qc_expected.rx((np.pi*R[0])/10,0)
# qc_expected.ry((np.pi*R[1])/10,0)
# qc_expected.rz((np.pi*R[2])/10,0)
qc_expected.h(0)
qc_expected.cx(0,1)
qc_expected.draw(output='mpl')
```

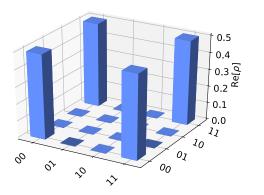
[3]:

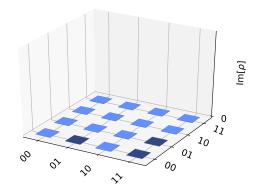


```
[4]:    job = qiskit.execute(qc_expected, Aer.get_backend('statevector_simulator'))
    psi_expected = job.result().get_statevector(qc_expected)
    print('The expected state is:', psi_expected)
    plot_state_city(psi_expected, title='Expected state')

The expected state is: [0.70710678+0.j 0. +0.j 0. +0.j
    0.70710678+0.j]
[4]:
```

#### Expected state

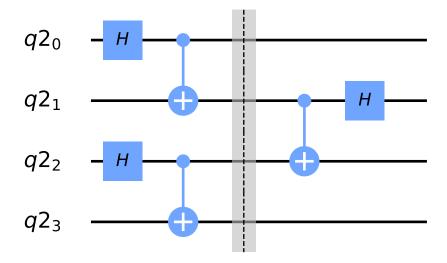




# 1.2 Defining the circuit

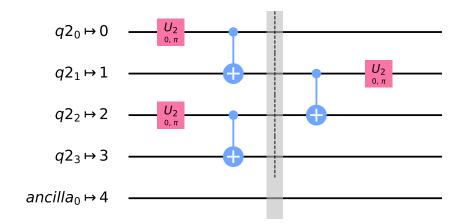
```
[5]: qr = QuantumRegister(4)
    cr = ClassicalRegister(4)
    qc = QuantumCircuit(qr)
    # qc.rx((np.pi*R[0])/10,0)
# qc.ry((np.pi*R[1])/10,0)
# qc.rz((np.pi*R[2])/10,0)
    qc.h(0)
    qc.h(2)
    qc.cx(0,1)
    qc.cx(2,3)
    qc.barrier()
    qc.cx(1,2)
    qc.h(1)
    qc.draw(output='mpl')
```

[5]:



```
[6]: # what does this circuit look like on the device?
transpile_qc = qiskit.compiler.transpile(qc,device)
transpile_qc.draw(output='mpl')
```

[6]:



### 1.3 Readout correction

Calibration is performed on the first and last qbit of the circuit only.

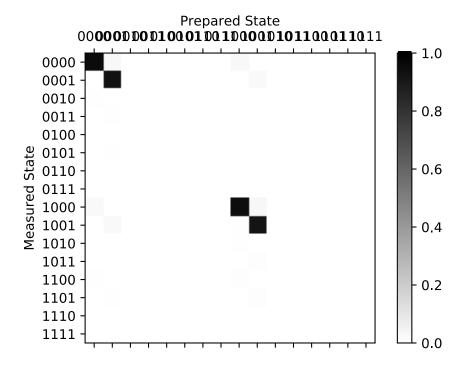
```
[7]: #readout calibration measurements

clz, state_labels = complete_meas_cal(qr = qc.qregs[0], circlabel =

→'measerrormitcal')

# doing calibration only for qbit 0 and 3, for 00, 10, 01, 11
```

Job Status: job has successfully run



```
m_ZZ = [0,0,0,0]
for i in range(4):
   for num, bit in enumerate(bits):
        if num % 4 == 0 or num % 4 == 1:
            m_IZ[i] += float(counts[i][bit]) / 8192
        if num % 4 == 2 or num % 4 == 3:
            m IZ[i] -= float(counts[i][bit]) / 8192
        if num % 4 == 0 or num % 4 == 2:
            m ZI[i] += float(counts[i][bit]) / 8192
        if num % 4 == 1 or num % 4 == 3:
            m_ZI[i] -= float(counts[i][bit]) / 8192
        if num % 4 == 0 or num % 4 == 3:
            m ZZ[i] += float(counts[i][bit]) / 8192
        if num % 4 == 1 or num % 4 == 2:
            m_ZZ[i] -= float(counts[i][bit]) / 8192
M = [[1, 1, 1, 1],
     [1, 1, -1, -1],
     [1, -1, 1, -1],
     [1, -1, -1, 1]
Minv = np.linalg.inv(M)
beta_IZ = np.dot(Minv, m_IZ)
beta ZI = np.dot(Minv, m ZI)
beta_ZZ = np.dot(Minv, m_ZZ)
b_vec = [beta_IZ[0], beta_ZI[0], beta_ZZ[0]]
B = [beta_IZ[1:], beta_ZI[1:], beta_ZZ[1:]]
Binv = np.linalg.inv(B)
```

#### 1.4 State Tomography

In order to reconstruct the output state of the circuit, it is necessary to perform 2 qbit tomography to build an arbitrary state from the outcomes of a series of measurements that together give the full state. For 2 qbits, that is 9 (3^n) circuits.

```
[9]: # defining tomography circuits
qcz = state_tomography_circuits(qc,qr)
# qiskit creates all 81 tomography circuits for 4 qbits, we want just a subsetu
→ of that:
# the nine circuits are in the order [XZZX, XZZY, XZZZ, YZZX, YZZY, YZZZ, ZZZX, u]
→ ZZZY, ZZZZ]
qst_circuit = u
→ [qcz[24],qcz[25],qcz[26],qcz[51],qcz[52],qcz[53],qcz[78],qcz[79],qcz[80]]
```

```
[10]: backends = ['simulator', 'simulator_noise', device]
      paulis = [('X','Z','Z','X'),('Y','Z','Z','X'),('Z','Z','Z','X'),
                ('X', 'Z', 'Z', 'Y'), ('Y', 'Z', 'Y'), ('Z', 'Z', 'Z', 'Y'),
                ('X','Z','Z','Z'),('Y','Z','Z','Z'),('Z','Z','Z','Z')]
      basis = ['XX','YX','ZX',
               'XY', 'YY', 'ZY',
               'XZ','YZ','ZZ']
      for num, backend in enumerate(backends):
          state ={}
          for bas in basis:
              state.update({bas: {'00': 0, '01': 0, '10': 0, '11': 0}})
          state_df = pd.DataFrame(data=[state,state,state])
          if num == 0:
              job_sim = qiskit.execute(qst_circuit, Aer.
       tom = StateTomographyFitter(job_sim.result(), qst_circuit)
          if num == 1:
              job_sim = qiskit.execute(qst_circuit, Aer.

→get_backend('qasm_simulator'), shots=8192,
                                       noise_model=noise_model,
                                       coupling_map=coupling_map,
                                       basis_gates=basis_gates)
              tom = StateTomographyFitter(job_sim.result(), qst_circuit)
          if num == 2:
              job_dev = qiskit.execute(qst_circuit, backend, shots=8192)
              job monitor(job dev)
              tom = StateTomographyFitter(job_dev.result(), qst_circuit)
          for pauli in paulis:
              for bit in bits:
                  if bit not in tom.data[pauli]:
                      tom.data[pauli][bit] = 0
          # 4 possible outcomes of teleport protocol, where the final state is either
          # psi, IX @ psi, IZ @ psi, IZ @ IX @ psi. We store all 4 seperately, to_{\square}
       \hookrightarrow then transform
          # the resulting density matrices appropriately before finding fidelity
          for i in range(4):
              for j in range(9):
                  state_df.loc[i][basis[j]] = {'00': tom.data[(paulis[j])][bits[4*i]],
                                               '01': tom.
       \rightarrowdata[(paulis[j])][bits[4*i+2]],
```

```
'10': tom.

data[(paulis[j])][bits[4*i+1]],

'11': tom.

data[(paulis[j])][bits[4*i+3]]}

if num == 0:
    state_sim = state_df
    print('Simulator done.')

if num == 1:
    state_sim_noise = state_df
    print('Noisy simulator done.')

if num == 2:
    state_dev = state_df
    print('Device done.')
```

Simulator done. Noisy simulator done.

Job Status: job has successfully run Device done.

```
[11]: # defining the matrices to construct the density matrices
      I_matrix = np.matrix('1, 0; 0, 1')
      X_matrix = np.matrix('0, 1; 1, 0')
      Y_{matrix} = np.matrix('0, 0-1j; 0+1j, 0')
      Z_{matrix} = np.matrix('1, 0; 0, -1')
      Iden = np.kron(I_matrix,I_matrix)
      IXPaul = np.kron(I_matrix,X_matrix)
      IYPaul = np.kron(I_matrix,Y_matrix)
      IZPaul = np.kron(I_matrix,Z_matrix)
      XIPaul = np.kron(X_matrix,I_matrix)
      YIPaul = np.kron(Y_matrix,I_matrix)
      ZIPaul = np.kron(Z_matrix,I_matrix)
      XXPaul = np.kron(X_matrix,X_matrix)
      XYPaul = np.kron(X_matrix,Y_matrix)
      XZPaul = np.kron(X_matrix,Z_matrix)
      YXPaul = np.kron(Y_matrix,X_matrix)
      YYPaul = np.kron(Y_matrix,Y_matrix)
      YZPaul = np.kron(Y_matrix,Z_matrix)
      ZXPaul = np.kron(Z_matrix,X_matrix)
      ZYPaul = np.kron(Z_matrix,Y_matrix)
      ZZPaul = np.kron(Z_matrix,Z_matrix)
```

```
[12]: # there are 4 density matrices to calculate for each of sim, sim noise and dev
      # XX, XY, XZ etc are 9 total r_xx etc terms to calculate
      r_{exp} = np.zeros((4, 9))
      # there are three IX type terms and each can be calculated three ways (from XX, ___
      \hookrightarrow YX, ZX for IX)
      r IP = np.zeros((4, 9))
      r_PI = np.zeros((4, 9))
      r_{IPavg} = np.zeros((4, 3))
      r_PIavg = np.zeros((4, 3))
      m = np.zeros((4,9,3))
      r_{corr} = np.zeros((4,9,3))
      r_IPavg_corr = np.zeros((4, 3))
      r_PIavg_corr = np.zeros((4, 3))
      state tot=[state sim,state sim noise,state dev]
      rho=[0,0,0,0]
      for stat, states in enumerate(state tot):
         rhof = [0,0,0,0]
         for i in range(4):
              for j in range(9):
                  r_{exp}[i,j] = (states[basis[j]][i]['00']*1 +_{L}
       ⇒states[basis[j]][i]['10']*(-1) + states[basis[j]][i]['01']*(-1) +
       \hookrightarrowstates[basis[j]][i]['10']*(1) + states[basis[j]][i]['01']*(1) +
      →states[basis[j]][i]['11']*1)
                  r_IP[i,j] = (states[basis[j]][i]['00']*1 +_{\square}
      →states[basis[j]][i]['10']*(1) + states[basis[j]][i]['01']*(-1) +
       →states[basis[j]][i]['10']*(1) + states[basis[j]][i]['01']*(1) + _ _
      \rightarrowstates[basis[j]][i]['11']*1)
                  r_PI[i,j] = (states[basis[j]][i]['00']*1 +_{i}
      \hookrightarrowstates[basis[j]][i]['10']*(-1) + states[basis[j]][i]['01']*(1) +
       →states[basis[j]][i]['11']*(-1))/(states[basis[j]][i]['00']*1 +__
      →states[basis[j]][i]['10']*(1) + states[basis[j]][i]['01']*(1) + _ _
      →states[basis[j]][i]['11']*1)
         for i in range(4):
              for j in range(3):
                      r_{IPavg[i,j]} = (r_{IP[i,j]} + r_{IP[i,j+3]} + r_{IP[i,j+6]})/3
                      r_{PIavg[i,j]} = (r_{PI[i,3*j]} + r_{PI[i,3*j+1]} + r_{PI[i,3*j+2]})/3
         for i in range(4):
              rhof[i] = (1/4)*(Iden + r_exp[i,0]*XXPaul + r_exp[i,1]*XYPaul +_{\sqcup}
       \rightarrowr_exp[i,2]*XZPaul
```

```
+ r_{exp}[i,3]*YXPaul + r_{exp}[i,4]*YYPaul + 
 \rightarrowr_exp[i,5]*YZPaul
                                + r_{exp}[i,6]*ZXPaul + r_{exp}[i,7]*ZYPaul + 
 \rightarrowr_exp[i,8]*ZZPaul
                                + r_IPavg[i,0]*IXPaul + r_PIavg[i,0]*XIPaul
                                + r_IPavg[i,1]*IYPaul + r_PIavg[i,1]*YIPaul
                                + r_IPavg[i,2]*IZPaul + r_PIavg[i,2]*ZIPaul)
        rho[stat] = rhof
# performing corrections for readout error and storing result in another.
\rightarrow density matrix
for i in range(4):
    for num, bas in enumerate(basis):
        m[i,num,:] = [r_IP[i,num], r_PI[i, num], r_exp[i,num]]
        r_corr[i,num] = np.dot(Binv, np.subtract(m[i,num,:],b_vec))
rho_corr = [0,0,0,0]
for i in range(4):
    for j in range(3):
             r_{IPavg\_corr[i,j]} = (r_{corr[i,j][0]} + r_{corr[i,j+3][0]} + 
 \rightarrowr_corr[i,j+6][0])/3
             r_{PIavg\_corr[i,j]} = (r_{corr[i,3*j][1]} + r_{corr[i,3*j+1][1]} + r_{corr[i,3*j+1][1]}
 \rightarrowr_corr[i,3*j+2][1])/3
    rho_corr[i] = (1/4)*(Iden + r_corr[i,0][2]*XXPaul + r_corr[i,1][2]*XYPaul +
 \rightarrowr_corr[i,2][2]*XZPaul
                                + r_corr[i,3][2]*YXPaul + r_corr[i,4][2]*YYPaul +
 →r_corr[i,5][2]*YZPaul
                                + r_corr[i,6][2]*ZXPaul + r_corr[i,7][2]*ZYPaul +
 \rightarrowr_corr[i,8][2]*ZZPaul
                                + r_IPavg_corr[i,0]*IXPaul +_
 →r_PIavg_corr[i,0]*XIPaul
                                + r_IPavg_corr[i,1]*IYPaul +
 →r_PIavg_corr[i,1]*YIPaul
                                + r IPavg corr[i,2]*IZPaul +
→r_PIavg_corr[i,2]*ZIPaul)
rho[3] = rho_corr
# applying the corrections for the 3 outcomes for which an X, Z or both gates \Box
\rightarrow are required
for ind in range(4):
    rho[ind][1] = ZIPaul @ rho[ind][1] @ ZIPaul
    rho[ind][2] = XIPaul @ rho[ind][2] @ XIPaul
    rho[ind][3] = XIPaul @ IZPaul @ rho[ind][3] @ IZPaul @ XIPaul
```

### 1.5 Calculating Fidelities

Simulator Fidelity: 1.0

Noisy Simulator Fidelity: 0.8441699725577938

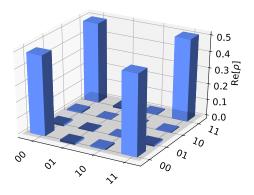
Device Fidelity: 0.7268206191645346

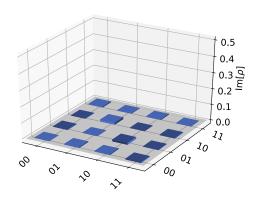
Calibrated Device Fidelity 0.7786803968028719

```
[15]: plot_state_city(rho[0][0], title='Simulator Density Matrix')
```

[15]:

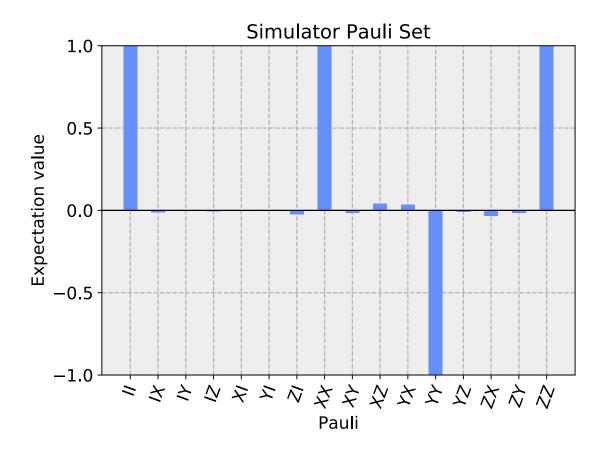
Simulator Density Matrix

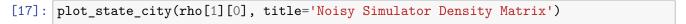




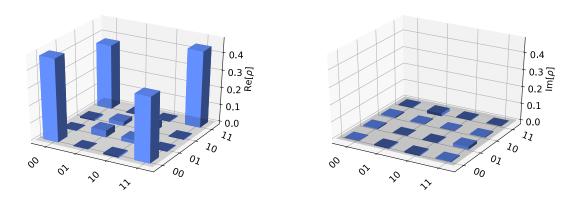
```
[16]: plot_state_paulivec(rho[0][0], title='Simulator Pauli Set')
```

[16]:



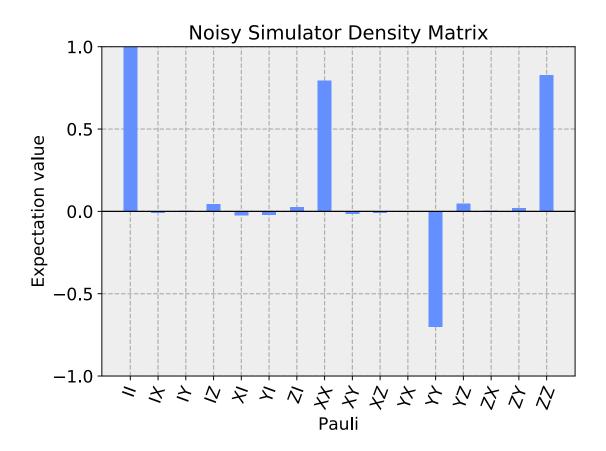


[17]: Noisy Simulator Density Matrix



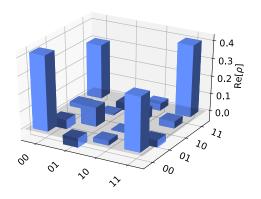
```
[18]: plot_state_paulivec(rho[1][0], title='Noisy Simulator Density Matrix')
```

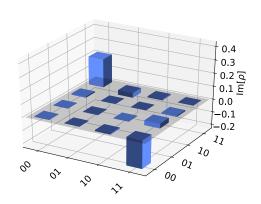
[18]:





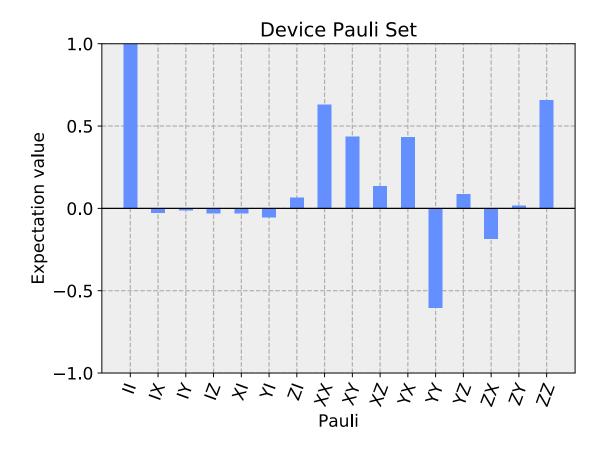
[19]: Device Density Matrix

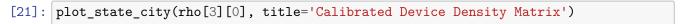




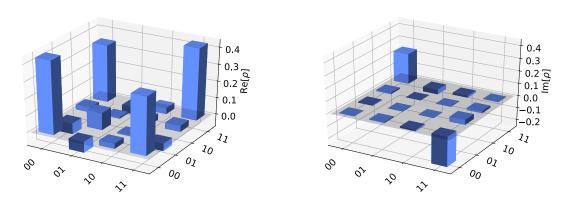
```
[20]: plot_state_paulivec(rho[2][0], title='Device Pauli Set')
```

[20]:





[21]: Calibrated Device Density Matrix



[22]: plot\_state\_paulivec(rho[3][0], title='Calibrated Device Pauli Set')

[22]:

