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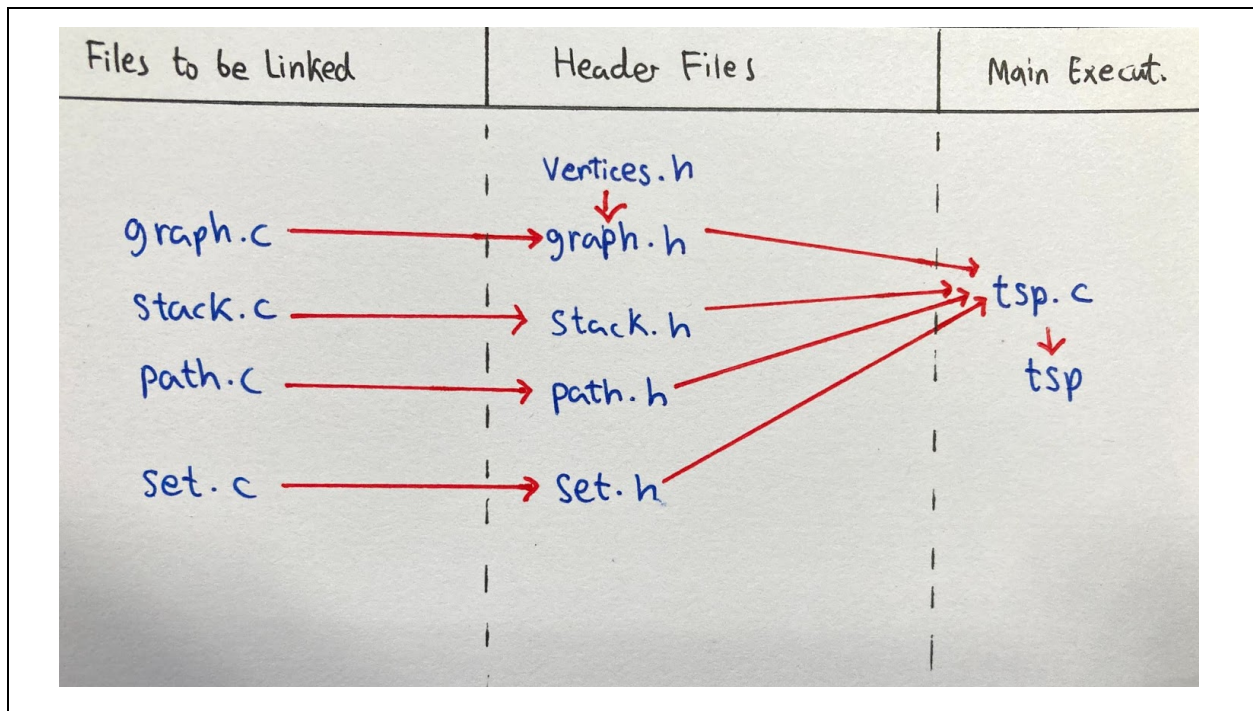
Design Document:
Assignment 4:

Graphs are abstract data types that can be broken down into vertices and edges. The information that graphs convey is similar to the information that waypoints on a map do because of how between two connected waypoints (vertices) there exists a route (edge) with a certain length or magnitude (edge weight). A road trip plotted out on a map that starts and ends in the same place is synonymous to a hamiltonian path in a graph, as long as the condition of never revisiting a once visited waypoint (vertex) is satisfied.

In assignment 4 I have been given the task of implementing graph, path and stack ADTs to be utilized by a recursive function for depth first searching. The depth first search implemented in this assignment will be used to find the shortest hamiltonian path given an input file containing information about a graph, its vertices, its edges and edgeweights. Additionally, this program will have the option to specify whether or not the graph will be undirected or directed. A directed graph would only allow for edges to be traversed in one direction (the way that they are written on the input file) while an undirected graph would allow for edges to be traversed in the direction specified by the input file as well as in the reverse direction (if an edge were written as $\langle 1, 2, 10 \rangle$ and the graph were undirected, it could be traversed from vertex 1 to 2 as well as vertex 2 to 1 with an edge weight of 10. However this is just an example as you cannot revisit an already visited vertex.

Top Level:

How my files will interact



Pseudo Code:

Note: Adapted and inspired from provided pseudo code.

Graphs:

Contains

- Integer indicating number of vertices
- Bool specifying if the graph is undirected (true if yes, false if no)
- Array of bools to specify which vertex has been visited (Index=vertex number)
- 2D matrix of integers to assign edge weights to edges (idx1=prev vertex, idx2=next vertex, value=edge weight)

Call to generate graph

- Allocate memory for graph structure
- Fill vertex array with false bools
- Fill matrix with 0's

Add Edge (stack pointer, integer to insert into stack item array)

- If vertex i and j of edge are within graph bounds
 - Assign weight to matrix[i][j]
 - return true
- else
 - return false

graph has edge

- if matrix[i][j] != 0
 - return true
- else
 - return false

graph edge weight

- if graph has edge
 - return weight at matrix[i][j]

graph mark visited

- if vertex is within graph bounds
 - mark visited[vertex] as true

graph mark visited

- if vertex is within graph bounds and is visited
 - mark visited[vertex] as false

Destructor(pointer to the graph pointer)

- Free graph pointer
- Set graph pointer to NULL

Stacks:

Contains

- Integer indicating top position
- Integer indicating capacity
- Pointer to an array of integers

Call to generate stack

Allocate memory for stack structure

- Allocate memory for array of items that will be pointed to by the pointer in each stack

Push (stack pointer, integer to insert into stack item array)

If stack does not have enough memory

- Reallocate original stack structure pointer to a block with twice as much memory

Add item into stack item array

Pop (stack pointer, new variable to assign popped item)

Move top/head pointer from item in array

- Set new variable equal to popped item

Peek (stack pointer, new variable to assign peeked item)

- Set new variable equal to peeked item (item at items[top-1])

stack copy(destination, source)

- Note: destination is an initialized stack (I'm assuming capacity is same as source's)

- Turns destination's items into a copy of source's items

- Turns destination's top into a copy of source's top

Destructor(pointer to the stack pointer)

- Free items array pointer in the stack structure and set that pointer to null

- Free pointer to stack structure and set that pointer to null

Path:

Contains

- Stack called vertices which holds visited vertices

- Integer called length which is the sum of all edge weights from visited vertices

Call to generate path

Allocate memory for path structure

- Initializes path stack with capacity of size VERTICES (26)

- Initializes length to a value of 0

path push vertex (Path *p, int v, Graph *g)

- push vertex v onto stack of path p

- increase path length by edge weight of inputted vertex and vertex from peeking stack

- weight will be accessed through `g->matrix[peek][push]`

path pop vertex (Path *p, int *v, Graph *g)

- pops vertex from stack of path p and gives value to pointer v

- decrease path length by edge weight of popped vertex and top vertex after pop

- weight will be accessed through `g->matrix[v][peek]`

path copy (Path *dst, Path *src)

- Note: destination is a properly initialized path struct\

- copy src's path stack over to dst's path stack

- copy src's path length over to dst's path length

Depth First Search:

Note: Eugene's section helped me, I haven't finished the pseudocode though

dfs (Graph g, int v, Path current, Path shortest, char *cities[], FILE *outfile)

- if vertex v is visited

- for all the edges linked to vertex v

- call recursively dfs(g,w) where w is a vertex linked to v through an edge

- for every vertex up till g->vertices

- if graph_has_edge(v,w) and vertex w !visited

- call dfs(g,w) recursively

- pop w off of stack

Revised DFS Pseudocode:

```
dfs(g, v=0, curr, shortest, cities)
  markvisited(g,v)
  pathpush(v)
  For possible edge(s) w for v
    If !visited(g,w) and edge exists
      dfs(w)
      markunvisited
    Elif w==0 and edge exists and number of path vertices == number of graph vertices
      dfs(w)
      If curr<shortest
        pathcopy(shortest,curr)
        pathprint(shortest)
  pop(v)
[END dfs call]
```

Design Process:

Before beginning this lab, I had to familiarize myself with the travelling salesperson problem and refresh myself on recursion as well as graphs. I did this by watching some videos and doing some drawings to visualize the movements of the sorts and then moved onto reading the descriptions of each sort provided in the asgn3 instructions pdf. After this I moved onto setting up the graph, path and stack ADTs, making sure each of them reliably functioned before moving onto the actual depth first search function to be used in solving the tsp problem. I believe that all this preparation was necessary to be able to know how to implement the dfs function in c.

1. Beginning the programming process, I created the graph structure which acted as the setting where the dfs function would act upon
 - a. This graph struct took in and stored information for all the vertices as well as all the edges that existed between them
 - b. The graph struct also came with the option to mirror itself diagonally if the condition that it was marked as unvisited was specified
2. I then worked on the stack structure
 - a. In stack.c I drew some figures of a stack going through pushing and popping to keep track of the movements of the top pointer, size and array items.
 - i. After finishing up a draft of stack.c, I ran the print_stack function to test if pushing, popping and the rest of accompanying functions for stack.c worked
 1. Stack worked much like it did in asgn3 with the additions of a new function called stack_peek which was set up almost the same way

- as `stack_pop` was, with the exception that `stack->top` was left unchanged in `stack_peek`
2. `Stack_print` was a function based around `fprintf` and would print output wherever was specified when it would eventually be called in `path_print`
 3. I then worked on the path structure.
 - a. This was the last structure that I worked on because of its dependencies on stacks and graphs
 - b. The path was essentially a stack with the extra parameter of a stored path length
 - c. The path struct also had a `print_path` function tied to it which would call on `stack_print` to print out the shortest known (at least at the time of execution) hamiltonian paths in a graph, given a valid set of vertices
 4. I then worked on setting up the recursive dfs function
 - a. I first drew the function out on paper and made drawings to fully understand the actions necessary for dfs.
 - b. The logic for dfs was something I spent quite a bit on
 - c. Some important things to consider which I learned from finishing dsf were to make a call to free for every malloc/calloc and to match every push call in a dfs call with a pop call.
 - d. I also realized that a way to shorten the needed recursive calls for a function was to end the dfs function immediately if a path length was already $>$ that the shortest path length recorded.
 5. Finally I created a Makefile to properly compile the source code of my test harness and source files.
 - a. This called for `-lm` to link my files for compilation

I thought this assignment was pretty challenging especially with the need for memory management and recursion, but finishing was satisfying. I also really liked working with graphs on this assignment. The freedom we were allowed for modifying the source and some header files was pretty fun at times as I could freely modify some of the given prototyped functions in the `asn4.pdf`. If there were something I would do differently the next time around for this assignment, I would set up a path and stack print function specifically for debugging as the path and stack print functions used in this assignment were actually used to write output after finishing a depth first search on a graph.

References:

- <https://www.youtube.com/watch?v=c8P9kB1eun4>
- [https://en.wikipedia.org/wiki/Graph_\(abstract_data_type\)#:~:text=In%20a%20computer%20science%2C%20a,graph%20theory%20within%20a%20math.&text=These%20pairs%20are%20known%20as,are%20also%20known%20as%20arrows.](https://en.wikipedia.org/wiki/Graph_(abstract_data_type)#:~:text=In%20a%20computer%20science%2C%20a,graph%20theory%20within%20a%20math.&text=These%20pairs%20are%20known%20as,are%20also%20known%20as%20arrows.)