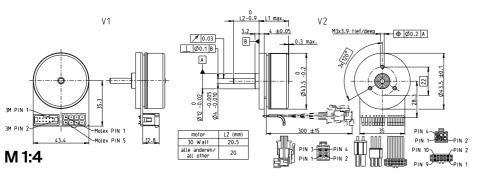
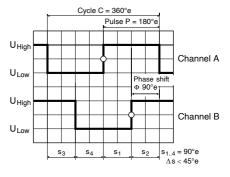
Encoder MILE 256–2048 CPT, 2 channels, with line driver Integrated into motor





Direction of rotation cw (definition cw p. 78)

	Article Numbe	rs			
V1 with connector	673024	673025	673026	673027	
V2 with cable and connector	673028	673029	673030	673031	
	256	512	1024	2048	
	2	2	2	2	
	1000	1000	1000	1000	
	10 000	10 000	10 000	10 000	
	V1 with connector	V1 with connector 673024 V2 with cable and connector 673028 256 2 1000	Article Numbers V1 with connector 673024 673025 V2 with cable and connector 673028 673029 256 512 2 2 1000 1000	Article Numbers V1 with connector V2 with cable and connector 673024 673025 673026 256 512 1024 2 2 2 1000 1000 1000	VI with connector V2 with cable and connector 673024 673025 673026 673027 256 512 1024 2048 2 2 2 2 1000 1000 1000 1000

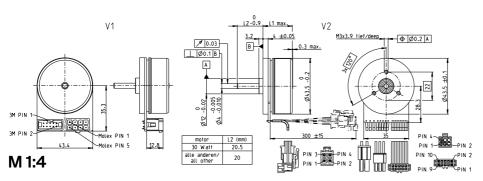


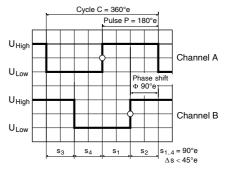


maxon Modular Sys	stem									
+ Motor	Page	+ Gearhead	Page	+ Brake	Page	Overall length	L1 max. [mm] /	see Gearhead	l	
EC 45 flat, 30 W, A	295					18.6	18.6	18.6	18.6	
EC 45 flat, 30 W, A	295	GP 32, 0.75-4.5 Nm	394			•	•	•	•	
EC 45 flat, 30 W, A	295	GP 32, 1.0 - 6.0 Nm	398			•	•	•	•	
EC 45 flat, 30 W, A	295	GP 42, 3.0 - 1.05 Nm	407			•	•	•	•	
EC 45 flat, 30 W, A	295	GS 45, 0.5 - 2.0 Nm	409			•	•	•	•	
EC 45 flat, 50 W, A	296					22.6	22.6	22.6	22.6	
EC 45 flat, 50 W, A	296	GP 32, 0.75 - 4.5 Nm	394			•	•	•	•	
EC 45 flat, 50 W, A	296	GP 32, 1.0 - 6.0 Nm	398			•	•	•	•	
EC 45 flat, 50 W, A	296	GP 42, 3.0 - 15.0 Nm	407			•	•	•	•	
EC 45 flat, 50 W, A	296	GS 45, 0.5 - 2.0 Nm	409			•	•	•	•	
EC 45 flat, 60 W, A	297					22.8	22.8	22.8	22.8	
EC 45 flat, 60 W, A	297	GP 32, 0.75 - 4.5 Nm	394			•	•	•	•	
EC 45 flat, 60 W, A	297	GP 32, .1.0 - 6.0 Nm	398			•	•	•	•	
EC 45 flat, 60 W, A	297	GP 42, 3.0 - 15.0 Nm	407			•	•	•	•	
EC 45 flat, 60 W, A	297	GS 45, 0.5 - 2.0 Nm	409			•	•	•	•	
EC 45 flat, 90 W, A	298					28.8	28.8	28.8	28.8	
EC 45 flat, 90 W, A	298	GP 32, 0.75 - 4.5 Nm	394			•	•	•	•	
EC 45 flat, 90 W, A	298	GP 32, 1.0 - 6.0 Nm	398			•	•	•	•	
EC 45 flat, 90 W, A	298	GP 42, 3.0 - 15.0 Nm	407			•	•	•	•	
EC 45 flat, 90 W, A	298	GS 45, 0.5 - 2.0 Nm	409			•	•	•	•	

Technical Data	Pin Allocation		Pin Allocation
Supply voltage V_{CC} 5 B \pm 10% Typical current draw 15 mA Output signal CMOS compatible State length s_n 90°e (1000 rpm) 45135°e Signal rise time (typically, at $C_L = 25$ pF, $R_L = 1$ k Ω , 25°C) 100 ns Signal fall time (typically, at $C_L = 25$ pF, $R_L = 1$ k Ω , 25°C) 100 ns Operating temperature range -40+100°C Moment of inertia of code wheel ≤ 3.5 gcm² Output current per channel max. 4 mA Open collector output of the Hall sensors with integrated pull-up resistor 10 k $\Omega \pm 20\%$ Wiring diagram for Hall sensors see p. 59	Connection V1	Connection V2 Sensors (AWG 24) Pin 1 Hall sensor 1 Pin 2 Hall sensor 2 Pin 3 Hall sensor 2 Pin 3 Hall sensor 3 Pin 4 GND Pin 5 V _{Hall} 4.518 VDC Pin 6 N.C. Pin 1 Motor winding 1 Pin 1 Motor winding 2 Pin 1 Motor winding 2 Pin 3 Motor winding 3 Pin 4 Not connected Encoder (AWG 28) Pin 1 N.C. Pin 2 V _{CC} Pin 3 GND Pin 4 N.C. Pin 6 Channel Ā Pin 6 Channel Ā Pin 7 Channel B Pin 9 Do not connect Pin 10 Do not connect 330-01-2040 Molex DIN 41651/EN 60603-13	Line receiver Recommended IC's: -MC 3486 -SN 75175 -AM 26 LS 32 Channel A Channel B Channel B

Encoder MILE 256–2048 CPT, 2 channels, with line driver Integrated into motor





Direction of rotation cw (definition cw p. 59)

		Control of the contro				
Stock program Standard program		Article Numbe	ers			
Special program (on request)	V1 with connector	673024	673025	673026	673027	
	V2 with cable and connector	673028	673029	673030	673031	
Туре						
Counts per turn		256	512	1024	2048	
Number of channels		2	2	2	2	
Max. operating frequency (kHz)		1000	1000	1000	1000	
Max. speed (rpm)		10 000	10 000	10 000	10 000	





moven Meduler S	votom									
maxon Modular System + Motor Page + Gearhead Page + Brake Page Overall length L1 max. [mm] / • see Gearhead										
EC 45 flat, 70 W, A	•				. 3	28.4	28.4	28.4	28.4	
EC 45 flat, 70 W, A	299	GP 32, 0.75 - 4.5 Nm	394			•	•	•	•	
EC 45 flat, 70 W, A	299	GP 32, 1.0 - 6.0 Nm	398			•	•	•	•	
EC 45 flat, 70 W, A	299	GP 42, 3.0 - 15.0 Nm	407			•	•	•	•	
EC 45 flat, 70 W, A	299	GS 45, 0.5 - 2.0 Nm	409			•	•	•	•	
EC 45 flat, 80 W,	4 300					27.8	27.8	27.8	27.8	
EC 45 flat, 80 W,	4 300	GP 32, 0.75 - 4.5 Nm	394			•	•	•	•	
EC 45 flat, 80 W,	4 300	GP 32, 1.0 - 6.0 Nm	398			•	•	•	•	
EC 45 flat, 80 W,	4 300	GP 42, 3 - 15 Nm	407			•	•	•	•	
EC 45 flat, 80 W,	4 300	GS 45, 0.5 - 2.0 Nm	409			•	•	•	•	
EC 45 flat, 120 W,	A 301					33.8	33.8	33.8	33.8	
EC 45 flat, 120 W,	A 301	GP 32, 0.75 - 4.5 Nm	394			•	•	•	•	
EC 45 flat, 120 W,	A 301	GP 32, 1.0 - 6.0 Nm	398			•	•	•	•	
EC 45 flat, 120 W,	A 301	GP 42, 3 - 15 Nm	407			•	•	•	•	
EC 45 flat, 120 W,	A 301	GS 45, 0.5 - 2.0 Nm	409			•	•	•	•	

Technical Data	Pin Allocation	Pin Allocation
Output signal CMOS compa State length s_n 90°e (1000 rpm) 451 Signal rise time (typically, at C_L = 25 pF, R_L = 1 k Ω , 25 °C) 10 Signal fall time	Motor + Sensors Sensors (AWG 24)	Pin Allocation Line receiver Recommended IC's: - MC 3486 - SN 75175 - AM 26 LS 32 Channel A Channel B Channel B
Additional information can be found under 'Downloads' in the maxon online shop.	DIN 41031/EN 00003-13	Opt. terminal resistance R = typical 120 Ω Capacitor C \geq 0.1 nF per m line length

maxon sensor 461 March 2021 edition / subject to change