

# Cryptanalysis of Round Reduced KECCAK

Nikhil Mittal

Under supervision of

Prof. Manindra Agrawal and Dr. Shashank Singh

IIT Kanpur

*nickedes@cse.iitk.ac.in*

June 13, 2019

# Hash Function

- A hash function is of the form  $H: \{0, 1\}^* \rightarrow \{0, 1\}^n$ .

# Hash Function

- A hash function is of the form  $H: \{0, 1\}^* \rightarrow \{0, 1\}^n$ .
- It is a deterministic function.
- It takes as input an arbitrary size string and outputs a fixed size ( $n$ ) string.

# Hash Function

- A hash function is of the form  $H: \{0, 1\}^* \rightarrow \{0, 1\}^n$ .
- It is a deterministic function.
- It takes as input an arbitrary size string and outputs a fixed size ( $n$ ) string.
- It is used in cryptographic applications such as Authentication, Digital Signatures and Integrity etc..

# Cryptographic Hash Functions

- Cryptographic applications require hash functions to satisfy the following conditions:

# Cryptographic Hash Functions

- Cryptographic applications require hash functions to satisfy the following conditions:
  - **Efficiency:** Given a message  $m$ , it is easy to compute its hash i.e.  $H(m)$ .

# Cryptographic Hash Functions

- Cryptographic applications require hash functions to satisfy the following conditions:
  - **Efficiency:** Given a message  $m$ , it is easy to compute its hash i.e.  $H(m)$ .
  - **Preimage Resistance:** Given  $H(m)$ , it is computationally hard to find the message  $m$ .

# Cryptographic Hash Functions

- Cryptographic applications require hash functions to satisfy the following conditions:
  - **Efficiency:** Given a message  $m$ , it is easy to compute its hash i.e.  $H(m)$ .
  - **Preimage Resistance:** Given  $H(m)$ , it is computationally hard to find the message  $m$ .
  - **Second-preimage Resistance:** Given a message  $m$ , it is computationally hard to find another message  $m'$  such that  $H(m) = H(m')$ .



# Cryptographic Hash Functions

- Cryptographic applications require hash functions to satisfy the following conditions:
  - **Efficiency:** Given a message  $m$ , it is easy to compute its hash i.e.  $H(m)$ .
  - **Preimage Resistance:** Given  $H(m)$ , it is computationally hard to find the message  $m$ .
  - **Second-preimage Resistance:** Given a message  $m$ , it is computationally hard to find another message  $m'$  such that  $H(m) = H(m')$ .
  - **Collision Resistance:** It is computationally hard to find two messages  $m$  and  $m'$  such that  $H(m) = H(m')$ .

# Cryptographic Hash Functions

- Cryptographic applications require hash functions to satisfy the following conditions:
  - **Efficiency:** Given a message  $m$ , it is easy to compute its hash i.e.  $H(m)$ .
  - **Preimage Resistance:** Given  $H(m)$ , it is computationally hard to find the message  $m$ .
  - **Second-preimage Resistance:** Given a message  $m$ , it is computationally hard to find another message  $m'$  such that  $H(m) = H(m')$ .
  - **Collision Resistance:** It is computationally hard to find two messages  $m$  and  $m'$  such that  $H(m) = H(m')$ .
- Hash functions having the above properties are referred to as cryptographic hash functions.

# Need For SHA-3

- MD5, SHA-1, SHA-2 are very popular hash functions and are widely used.

# Need For SHA-3

- MD5, SHA-1, SHA-2 are very popular hash functions and are widely used.
- In year 2005, first practical collision attacks were found on:
  - MD5, SHA-0 and SHA-1 by Xiaoyun Wang *et al.*

# Need For SHA-3

- MD5, SHA-1, SHA-2 are very popular hash functions and are widely used.
- In year 2005, first practical collision attacks were found on:
  - MD5, SHA-0 and SHA-1 by Xiaoyun Wang *et al.*
- National Institute of Standards and Technology (NIST) was worried about the security of hash functions.
- Though by that time SHA-2 family of hash functions was standardized.

# Need For SHA-3

- MD5, SHA-1, SHA-2 are very popular hash functions and are widely used.
- In year 2005, first practical collision attacks were found on:
  - MD5, SHA-0 and SHA-1 by Xiaoyun Wang *et al.*
- National Institute of Standards and Technology (NIST) was worried about the security of hash functions.
- Though by that time SHA-2 family of hash functions was standardized.
- SHA-2 was also based on Merkle-Damgard construction like SHA-0, SHA-1.
- There was a possibility that it could also be attacked in a similar fashion.

# SHA-3 Competition

- With this thought, in the year 2006, NIST decided to hold a competition for the next secure hash function.

# SHA-3 Competition

- With this thought, in the year 2006, NIST decided to hold a competition for the next secure hash function.
- In 2008, NIST announced a competition for the Secure Hash Algorithm-3 (SHA-3).



# SHA-3 Competition

- With this thought, in the year 2006, NIST decided to hold a competition for the next secure hash function.
- In 2008, NIST announced a competition for the Secure Hash Algorithm-3 (SHA-3).
- In the year 2012, NIST announced KECCAK as the winner of the competition among the five finalists viz. BLAKE, Grøstl, JH, KECCAK and Skein.

# SHA-3 Competition

- With this thought, in the year 2006, NIST decided to hold a competition for the next secure hash function.
- In 2008, NIST announced a competition for the Secure Hash Algorithm-3 (SHA-3).
- In the year 2012, NIST announced KECCAK as the winner of the competition among the five finalists viz. BLAKE, Grøstl, JH, KECCAK and Skein.
- Since 2015, KECCAK has been standardized as SHA-3 by NIST.

- KECCAK hash function is based on sponge construction.
- SHA-3 family of hash functions is based on KECCAK.
- The SHA-3 family provides four hash functions:
  - SHA3-224, SHA3-256, SHA3-384 and SHA3-512.

- KECCAK hash function is based on sponge construction.
- SHA-3 family of hash functions is based on KECCAK.
- The SHA-3 family provides four hash functions:
  - SHA3-224, SHA3-256, SHA3-384 and SHA3-512.
- KECCAK's excellent resistance towards crypt-analytic attacks is one of the main reasons for its selection by NIST.
- The algorithm is a good mixture of linear as well as non-linear operations.

# Sponge Construction

- A sponge construction consists of:
  - Permutation function  $f$ ,
  - Parameter “rate”  $r$ , and
  - Padding rule  $\text{pad}$ .

# Sponge Construction

- A sponge construction consists of:
  - Permutation function  $f$ ,
  - Parameter “rate”  $r$ , and
  - Padding rule  $\text{pad}$ .
  - This construction produces a sponge function that takes as input a bit string  $M$  and generates a string of length  $l$ .

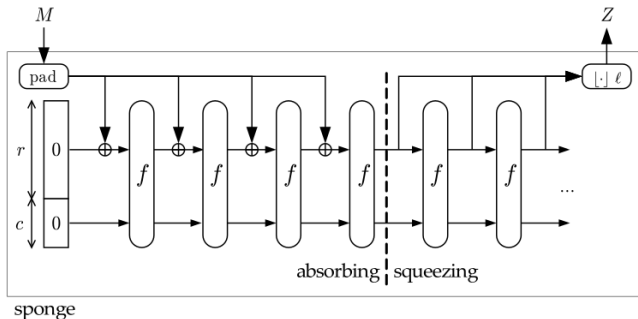


Figure: The sponge construction

# KECCAK- $p$ Permutation

- The function  $f$  in the sponge construction is denoted by  $\text{KECCAK-}f[b]$ .
- $b$  is the length of input string.
- Internally,  $\text{KECCAK-}f[b]$  consists of a round function  $p$  which is applied  $n_r$  number of times.
- $\text{KECCAK-}f[b]$  function is specialization of  $\text{KECCAK-}p[b, n_r]$ .

# KECCAK State

- The state input to  $\text{KECCAK-}f[b]$  consists of  $b$  bits.
- The state is divided into slices.
- Each slice is of fixed size i.e., 25 bits.
- A state  $S$ , which is a  $b$ -bit string, in KECCAK is usually denoted by a 3-dimensional grid of size  $(5 \times 5 \times w)$ .

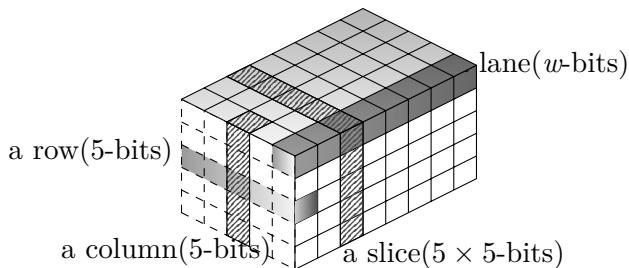


Figure: The KECCAK State



# Round Function of KECCAK- $p$

- The round function  $p$  in KECCAK comprises of 5 step mappings.
- The KECCAK state undergoes some transformations specified by the step mapping.
- These step mappings are called  $\theta$ ,  $\rho$ ,  $\pi$ ,  $\chi$  and  $\iota$ .
- These transformations are applied in sequence.
- Now, we will describe these 5 step mappings in detail.

## $\theta$ step mapping

- XOR each bit in the state with the parities of two neighboring columns.

## $\theta$ step mapping

- XOR each bit in the state with the parities of two neighboring columns.
- For bit position  $(x, y, z)$ , one column is  $((x - 1) \bmod 5, z)$  and the other is  $((x + 1) \bmod 5, (z - 1) \bmod w)$ .

## $\theta$ step mapping

- XOR each bit in the state with the parities of two neighboring columns.
- For bit position  $(x, y, z)$ , one column is  $((x - 1) \bmod 5, z)$  and the other is  $((x + 1) \bmod 5, (z - 1) \bmod w)$ .
- If we have  $A$  as the input state to  $\theta$ , then the output state  $B$  is:

$$B[x, y, z] = A[x, y, z] \bigoplus P[(x - 1) \bmod 5, z] \\ \bigoplus P[(x + 1) \bmod 5, (z - 1) \bmod w] \quad (1)$$

## $\theta$ step mapping

- XOR each bit in the state with the parities of two neighboring columns.
- For bit position  $(x, y, z)$ , one column is  $((x - 1) \bmod 5, z)$  and the other is  $((x + 1) \bmod 5, (z - 1) \bmod w)$ .
- If we have  $A$  as the input state to  $\theta$ , then the output state  $B$  is:

$$B[x, y, z] = A[x, y, z] \bigoplus P[(x - 1) \bmod 5, z] \bigoplus P[(x + 1) \bmod 5, (z - 1) \bmod w] \quad (1)$$

- $P[x, z]$  represents the parity of the column  $(x, z)$ .

$$P[x, z] = \bigoplus_{y=0}^4 A[x, y, z]$$

# $\rho$ step mapping

- $\rho$  (**rho**): This step rotates each lane by a constant value towards the MSB.

# $\rho$ step mapping

- $\rho$  (**rho**): This step rotates each lane by a constant value towards the MSB.
- If we have  $A$  as the input state to  $\rho$ , then the output state  $B$  is:
  - $B[x, y, z] = A[x, y, z + \rho(x, y) \bmod w]$

# $\rho$ step mapping

- $\rho$  (**rho**): This step rotates each lane by a constant value towards the MSB.
- If we have  $A$  as the input state to  $\rho$ , then the output state  $B$  is:
  - $B[x, y, z] = A[x, y, z + \rho(x, y) \bmod w]$
- $\rho(x, y)$  is the constant for lane  $(x, y)$ .
- The constant value  $\rho(x, y)$  is specified for each lane in the construction of KECCAK.



# $\rho$ step mapping

- $\rho$  (**rho**): This step rotates each lane by a constant value towards the MSB.
- If we have  $A$  as the input state to  $\rho$ , then the output state  $B$  is:
  - $B[x, y, z] = A[x, y, z + \rho(x, y) \bmod w]$
- $\rho(x, y)$  is the constant for lane  $(x, y)$ .
- The constant value  $\rho(x, y)$  is specified for each lane in the construction of KECCAK.
- $\rho$  is a linear step mapping.

# $\pi$ step mapping

- $\pi$  (**pi**): It permutes the position of lanes.
- The new position of a lane is determined by a matrix,

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 2 & 3 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix}, \quad (2)$$

where  $(x', y')$  is the position of lane  $(x, y)$  after  $\pi$  step.

- $\pi$  is a linear step mapping.

# $\chi$ step mapping

- $\chi$  (**chi**): Each bit in the original state is XOR-ed with a non-linear function of next two bits in the same row.

$$B[x, y, z] = A[x, y, z] \oplus ((A[(x+1) \bmod 5, y, z] \oplus 1) \cdot A[(x+2) \bmod 5, y, z]).$$

(3)

# $\chi$ step mapping

- $\chi$  (**chi**): Each bit in the original state is XOR-ed with a non-linear function of next two bits in the same row.

$$B[x, y, z] = A[x, y, z] \oplus ((A[(x+1) \bmod 5, y, z] \oplus 1) \cdot A[(x+2) \bmod 5, y, z]).$$

(3)

- $\chi$  is the only non-linear operation among the 5 step mappings in KECCAK.

## $\iota$ step mapping

- $\iota$  (**iota**): This step mapping only modifies the (0, 0) lane depending on the round number.
- If we have  $A$  as the input state to  $\iota$ , then the output state  $B$  is:

$$B[0, 0] = A[0, 0] \oplus RC_i, \quad (4)$$

where  $RC_i$  is round constant that depends on the round number.

## $\iota$ step mapping

- $\iota$  (**iota**): This step mapping only modifies the (0, 0) lane depending on the round number.
- If we have  $A$  as the input state to  $\iota$ , then the output state  $B$  is:

$$B[0, 0] = A[0, 0] \oplus RC_i, \quad (4)$$

where  $RC_i$  is round constant that depends on the round number.

- The remaining 24 lanes remain unaffected.

## $\iota$ step mapping

- $\iota$  (**iota**): This step mapping only modifies the  $(0, 0)$  lane depending on the round number.
- If we have  $A$  as the input state to  $\iota$ , then the output state  $B$  is:

$$B[0, 0] = A[0, 0] \oplus RC_i, \quad (4)$$

where  $RC_i$  is round constant that depends on the round number.

- The remaining 24 lanes remain unaffected.
- All the rounds are identical but the symmetry is destroyed by this step due to the addition of a round constant to a particular lane.

# Specification of KECCAK- $p[b, n_r]$

- Round in KECCAK is given by:
  - $\text{Round}(A, i_r) = \iota(\chi(\pi(\rho(\theta(A))))), i_r)$
- It consists of  $n_r$  number of iterations of  $\text{Round}(A, i_r)$ .
- $\text{KECCAK-}p[b, n_r](S)$ 
  - Convert  $S$  into a state array  $A$
  - For  $i_r$  from 0 to  $n_r - 1$ , let  $A = \text{Round}(A, i_r)$
  - Convert  $A$  into string  $S'$  of length  $b$
  - Return  $S'$



# SHA-3 Hash Function

- The SHA-3 hash function is  $\text{KECCAK-}p[b, 12 + 2 \cdot l]$ .
- $w = b/25$  and  $l = \log_2(w)$

# SHA-3 Hash Function

- The SHA-3 hash function is  $\text{KECCAK-}p[b, 12 + 2 \cdot l]$ .
- $w = b/25$  and  $l = \log_2(w)$
- When the value of  $b = 1600$ , we have  $l = 6$ .
- Thus, the  $f$  function in SHA-3 is  $\text{KECCAK-}p[1600, 24]$ .

# SHA-3 Hash Function

- The SHA-3 hash function is  $\text{KECCAK-}p[b, 12 + 2 \cdot l]$ .
- $w = b/25$  and  $l = \log_2(w)$
- When the value of  $b = 1600$ , we have  $l = 6$ .
- Thus, the  $f$  function in SHA-3 is  $\text{KECCAK-}p[1600, 24]$ .
- Instances of KECCAK are denoted by  $\text{KECCAK}[r, c]$ .
- Where  $r = 1600 - c$  and the capacity  $c$  is chosen to be twice the size of hash output  $d$ .

# SHA-3 Hash Function

- The SHA-3 hash function is  $\text{KECCAK-}p[b, 12 + 2 \cdot l]$ .
- $w = b/25$  and  $l = \log_2(w)$
- When the value of  $b = 1600$ , we have  $l = 6$ .
- Thus, the  $f$  function in SHA-3 is  $\text{KECCAK-}p[1600, 24]$ .
- Instances of KECCAK are denoted by  $\text{KECCAK}[r, c]$ .
- Where  $r = 1600 - c$  and the capacity  $c$  is chosen to be twice the size of hash output  $d$ .
- We set  $c = 2 \cdot d$ , to avoid generic attacks with expected cost below  $2^d$ .
- The hash function with output length  $d$  is denoted by:

$$\text{KECCAK-}d = \text{KECCAK}[r := 1600 - 2 \cdot d, c := 2 \cdot d] \quad (5)$$

- The padding rule followed by KECCAK is **pad10\*1**.
- According to the rule, the input string is appended with a 1 bit followed by some number of 0 bits and followed by 1 bit.
- The asterisk in the padding rule indicates that 0 bit is either not present or is repeated as required so that the length of output string after padding is a multiple of the block length (i.e.  $r$ ).

- $\text{KECCAK}[r := 800 - 384, c := 384] = \text{KECCAK-}p[800, 24][r := 800 - 384, c := 384].$

- $\text{KECCAK}[r := 800 - 384, c := 384] = \text{KECCAK-}p[800, 24][r := 800 - 384, c := 384]$ .
- 2-round  $\text{KECCAK}[r := 800 - 384, c := 384] = \text{KECCAK-}p[800, 2][r := 800 - 384, c := 384]$ .

# Observations

- **Observation 1:** If we know all the bits of a row, then we can invert  $\chi$  for that row. It is depicted below.

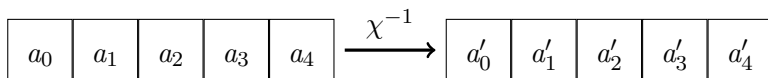


Figure: Computation of  $\chi^{-1}$  for full row

$$a'_i = a_i \oplus (a_{i+1} \oplus 1) \cdot (a_{i+2} \oplus (a_{i+3} \oplus 1) \cdot a_{i+4}) \quad (6)$$

- **Observation 2:** When only one output bit is known after  $\chi$  step, then we can fix the first output bit to be the same as the input bit and the second bit as 1.

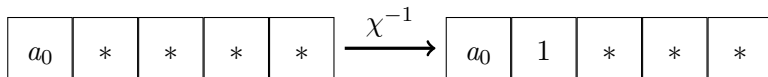


Figure: Computation of  $\chi^{-1}$  when only 1-bit is known in row



- **Observation 3:**

- $a'_i, a_i$  are the input and output bits of  $\chi$  respectively.
- Guo *et al.* observed that when 4 out of 5 output bits of  $\chi$  are known, then we can obtain 4 linear relations in terms of  $a'_i$ .

$$a'_i = a_i \oplus (a_{i+1} \oplus 1) \cdot (a_{i+2} \oplus (a_{i+3} \oplus 1) \cdot a_{i+4}) \quad (7)$$

- If the values of  $a_0, a_1, a_2, a_3$  are known using the Equation 7, we can eliminate the expression  $a_4$  from the rest of the equations.
- Hence, we obtain 4 linear equations on the input bits.

# Notations

- The KECCAK state is represented by 25 lanes.
- Each lane is represented by a variable which is a 32-bit array.
- A variable with a number in round bracket “ $(\cdot)$ ” represents the shift of the bits in array towards MSB.
- A variable with a number in square bracket “ $[\cdot]$ ” represents the bit value of the variable at that index.
- If there are multiple numbers in the square bracket, then it represents the corresponding bit values.

# 2 rounds of KECCAK[r:=800-384, c:=384]

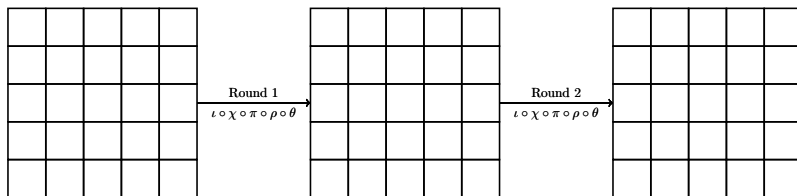


Figure: Two rounds of KECCAK[r := 800 − 384, c := 384]

- We will discuss a preimage attack on above structure.

# Final State of 2-round KECCAK[r:=800-384, c:=384]

- $c = 384 \rightarrow d = 192 \rightarrow$  hash of 6 lanes

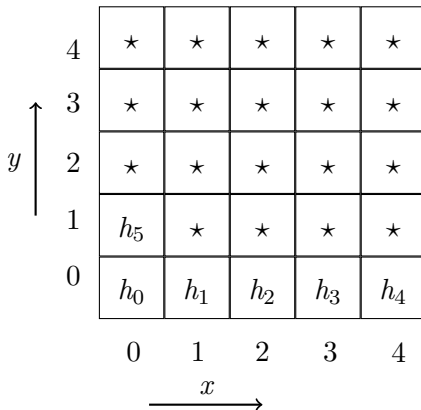


Figure: The Final Hash State for KECCAK[r := 800 − 384, c := 384]

# Initial State of 2-round KECCAK[r:=800-384, c:=384]

- $r = 800 - 384 \rightarrow r = 416 \rightarrow$  Message block of 13 lanes

0	0	0	0	0
0	0	0	0	0
$a_1$	$b_1$	$c_2$	0	0
$a_2$	$b_2$	$c_1$	$d_1$	$e_1$
$a_0$	$b_0$	$c_0$	$d_0$	$e_0$

Figure: Setting of Initial State in the Attack

- Our aim is to find the values of  $a_0, a_1, a_2, b_0, b_1, b_2, c_0, c_1, c_2, d_0, d_1$  and  $e_0, e_1$  variables in the initial state.

# Attack

- Our aim is to find the values of  $a_0, a_1, a_2, b_0, b_1, b_2, c_0, c_1, c_2, d_0, d_1$  and  $e_0, e_1$  variables in the initial state.
- Such that, they lead to a final state having first six lanes as  $h_0, h_1, h_2, h_3, h_4$  and  $h_5$ .

# Attack

- Our aim is to find the values of  $a_0, a_1, a_2, b_0, b_1, b_2, c_0, c_1, c_2, d_0, d_1$  and  $e_0, e_1$  variables in the initial state.
- Such that, they lead to a final state having first six lanes as  $h_0, h_1, h_2, h_3, h_4$  and  $h_5$ .
- We follow the basic idea of the attack given by Naya *et al.* in 2011.



# Attack

- Our aim is to find the values of  $a_0, a_1, a_2, b_0, b_1, b_2, c_0, c_1, c_2, d_0, d_1$  and  $e_0, e_1$  variables in the initial state.
- Such that, they lead to a final state having first six lanes as  $h_0, h_1, h_2, h_3, h_4$  and  $h_5$ .
- We follow the basic idea of the attack given by Naya *et al.* in 2011.
- 2 rounds of KECCAK[ $r := 800 - 384, c := 384$ ]
  - Best-known attack, has a time complexity of  $O(2^{64})$ .
  - It is based on the idea of linear structures given by Jian Guo *et al.* in 2016.

# First round $\theta$ step mapping

- $\theta$  step mapping diffuses message bits to full state.

# First round $\theta$ step mapping

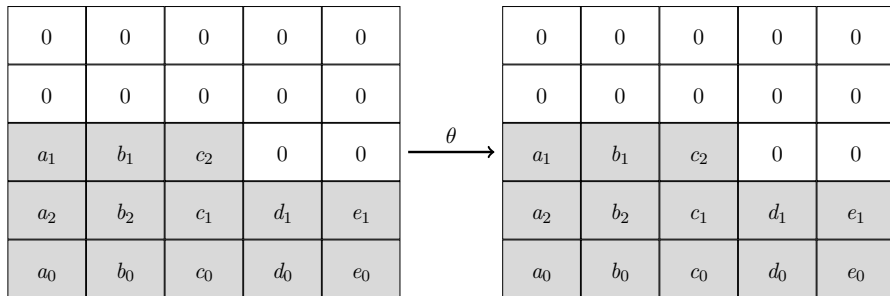
- $\theta$  step mapping diffuses message bits to full state.
- In this step, our aim is to control the diffusion by  $\theta$ .
- This can be done by adding constraints on message bits.

# First round $\theta$ step mapping

- $\theta$  step mapping diffuses message bits to full state.
- In this step, our aim is to control the diffusion by  $\theta$ .
- This can be done by adding constraints on message bits.
- We add the following conditions to make column parity zero:

$$\begin{aligned} a_2 &= a_0 \oplus a_1, & b_2 &= b_0 \oplus b_1, & c_2 &= c_0 \oplus c_1 \\ d_1 &= 0, & d_0 &= 0 & \text{ and } & e_1 = e_0. \end{aligned} \tag{8}$$

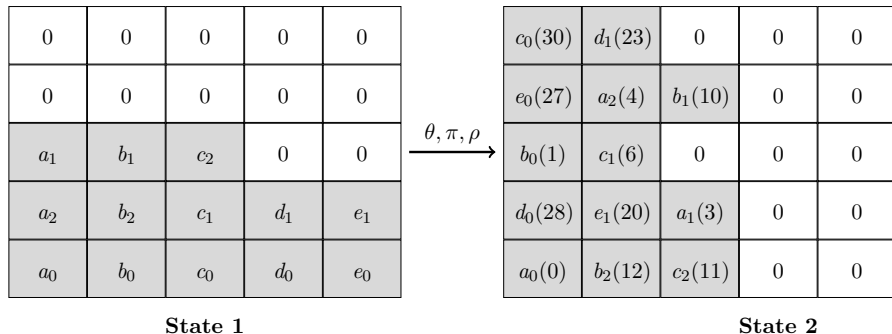
# Effect of $\theta$



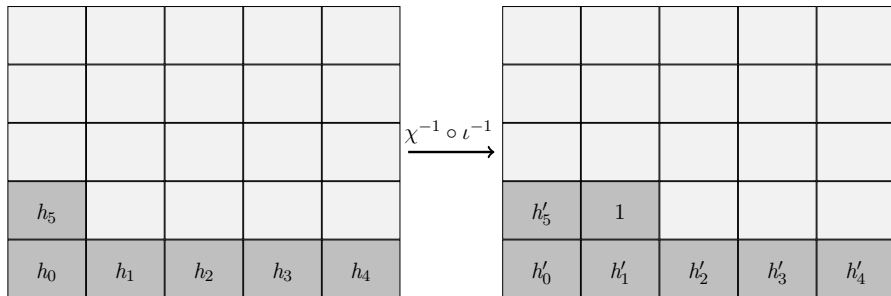
State 1

Figure: Effect of  $\theta$  on initial state

# State 1 to State 2



**Figure:** Preimage attack on 2-round KECCAK[ $r := 800 - 384$ ,  $c := 384$ ]



**State 4**

**Figure:** Inversion of hash through  $\chi^{-1} \circ \iota^{-1}$

# State 4 to State 3

$h_5$				
$h_0$	$h_1$	$h_2$	$h_3$	$h_4$

State 4

$$\xrightarrow[\pi^{-1}, \rho^{-1}]{\iota^{-1}, \chi^{-1}}$$

				$h'_4(18)$
			$h'_3(11)$	
		$h'_2(21)$		
	$h'_1(20)$			1
$h'_0(0)$			$h'_5(4)$	

State 3



# State 1 to 4

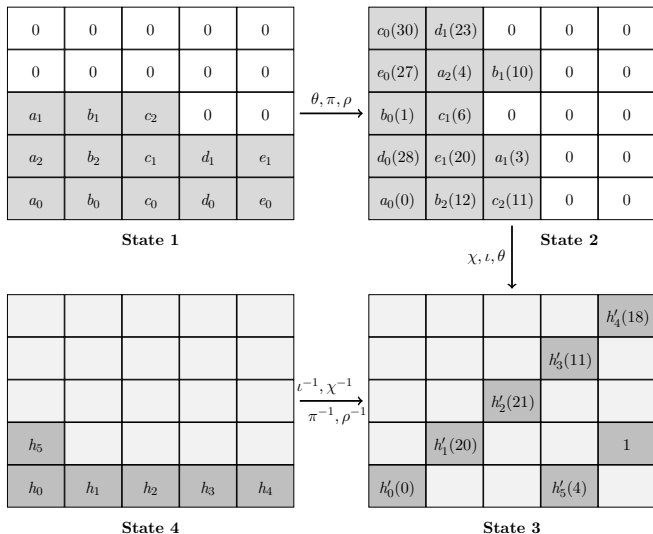
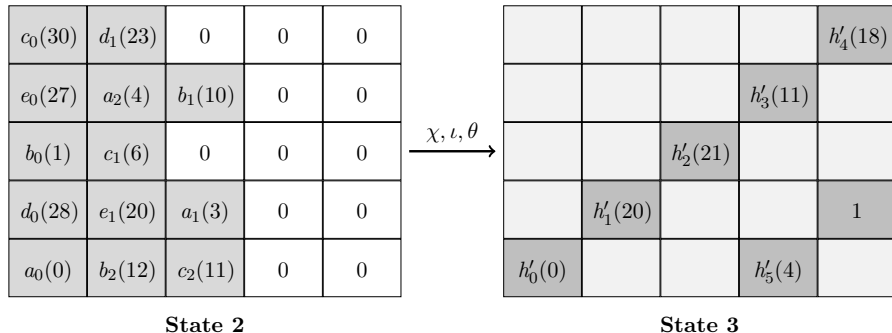


Figure: Preimage attack on 2-round KECCAK[ $r := 800 - 384$ ,  $c := 384$ ]

# State 2 to State 3



**Figure:** Intermediate States in 2-round preimage attack on  
 $\text{KECCAK}[r := 800 - 384, c := 384]$

# Description of Attack

- Fix  $d_0, d_1$  as constants (with condition that  $d_0 = d_1$ ).

# Description of Attack

- Fix  $d_0, d_1$  as constants (with condition that  $d_0 = d_1$ ).
- In state 2, we initially have  $13 \cdot 32$  variables.

# Description of Attack

- Fix  $d_0, d_1$  as constants (with condition that  $d_0 = d_1$ ).
- In state 2, we initially have  $13 \cdot 32$  variables.
- In the state 3, there are 7 lanes whose values are fixed, this will impose a total of  $7 \cdot 32$  conditions.
- We also set 6 conditions on the initial state (Equation 8). This will further add  $6 \cdot 32$  conditions.

# Description of Attack

- Fix  $d_0, d_1$  as constants (with condition that  $d_0 = d_1$ ).
- In state 2, we initially have  $13 \cdot 32$  variables.
- In the state 3, there are 7 lanes whose values are fixed, this will impose a total of  $7 \cdot 32$  conditions.
- We also set 6 conditions on the initial state (Equation 8). This will further add  $6 \cdot 32$  conditions.
- The number of variables and the number of conditions are equal.

# Description of Attack

- Fix  $d_0, d_1$  as constants (with condition that  $d_0 = d_1$ ).
- In state 2, we initially have  $13 \cdot 32$  variables.
- In the state 3, there are 7 lanes whose values are fixed, this will impose a total of  $7 \cdot 32$  conditions.
- We also set 6 conditions on the initial state (Equation 8). This will further add  $6 \cdot 32$  conditions.
- The number of variables and the number of conditions are equal.
- So, we expect a solution.

# Description of Attack

- In state 3, the values of  $i^{\text{th}}$ -slice depend on the  $(i-1)^{\text{th}}$  and  $i^{\text{th}}$ -slice of state 2.



# Description of Attack

- In state 3, the values of  $i^{\text{th}}$ -slice depend on the  $(i-1)^{\text{th}}$  and  $i^{\text{th}}$ -slice of state 2.
- First, we find the set of input message bits which satisfy the small collection of consecutive slices of state 3.

# Description of Attack

- In state 3, the values of  $i^{\text{th}}$ -slice depend on the  $(i - 1)^{\text{th}}$  and  $i^{\text{th}}$ -slice of state 2.
- First, we find the set of input message bits which satisfy the small collection of consecutive slices of state 3.
- Then, we merge the solutions to find message bits which satisfy large collection of consecutive slices.

# Attack Layout

- We need to find values of variables in initial state for all the 32 slices.

# Attack Layout

- We need to find values of variables in initial state for all the 32 slices.
- We solve for first 24 slices and then solve for the remaining 8 slices.

# Attack Layout

- We need to find values of variables in initial state for all the 32 slices.
- We solve for first 24 slices and then solve for the remaining 8 slices.
- Solving for first 24 slices:
  - Find solutions for 8 groups of 3 slices.

# Attack Layout

- We need to find values of variables in initial state for all the 32 slices.
- We solve for first 24 slices and then solve for the remaining 8 slices.
- Solving for first 24 slices:
  - Find solutions for 8 groups of 3 slices.
  - Merge consecutive 3 slices to get solutions for 6 slices i.e. 4 groups of 6 slices.

# Attack Layout

- We need to find values of variables in initial state for all the 32 slices.
- We solve for first 24 slices and then solve for the remaining 8 slices.
- Solving for first 24 slices:
  - Find solutions for 8 groups of 3 slices.
  - Merge consecutive 3 slices to get solutions for 6 slices i.e. 4 groups of 6 slices.
  - Merge consecutive 6 slices to get solutions for 12 slices i.e. 2 groups of 12 slices.

# Attack Layout

- We need to find values of variables in initial state for all the 32 slices.
- We solve for first 24 slices and then solve for the remaining 8 slices.
- Solving for first 24 slices:
  - Find solutions for 8 groups of 3 slices.
  - Merge consecutive 3 slices to get solutions for 6 slices i.e. 4 groups of 6 slices.
  - Merge consecutive 6 slices to get solutions for 12 slices i.e. 2 groups of 12 slices.
  - Merge the two groups of 12 slices to get solutions for 24 slices.



# Attack Layout

- Solving for remaining 8 slices:

# Attack Layout

- Solving for remaining 8 slices:
  - Find solutions for the first 6 slices.

- Solving for remaining 8 slices:
  - Find solutions for the first 6 slices.
  - Find solutions for the remaining 2 slices.

- Solving for remaining 8 slices:
  - Find solutions for the first 6 slices.
  - Find solutions for the remaining 2 slices.
  - Merge the above two groups to obtain solutions for the 8 slices.

- Solving for remaining 8 slices:
  - Find solutions for the first 6 slices.
  - Find solutions for the remaining 2 slices.
  - Merge the above two groups to obtain solutions for the 8 slices.
- The last step of the attack is to merge solutions of the 24 slices and 8 slices.

- Solving for remaining 8 slices:
  - Find solutions for the first 6 slices.
  - Find solutions for the remaining 2 slices.
  - Merge the above two groups to obtain solutions for the 8 slices.
- The last step of the attack is to merge solutions of the 24 slices and 8 slices.
- Finally, we obtain a solution for all the 32 slices.

# Possible solutions for groups of 3 slices

- Consider a group of 3 slices (for example take the first 3 slices).

# Possible solutions for groups of 3 slices

- Consider a group of 3 slices (for example take the first 3 slices).
- It contains the following message bits:
  - $a_0[0, 1, 2]$ ,  $a_1[3, 4, 5]$ ,  $a_2[4, 5, 6]$
  - $b_0[1, 2, 3]$ ,  $b_1[10, 11, 12]$ ,  $b_2[12, 13, 14]$
  - $c_0[30, 31, 0]$ ,  $c_1[6, 7, 8]$ ,  $c_2[11, 12, 13]$
  - $e_0[27, 28, 29]$ ,  $e_1[20, 21, 22]$



# Possible solutions for groups of 3 slices

- Consider a group of 3 slices (for example take the first 3 slices).
- It contains the following message bits:
  - $a_0[0, 1, 2]$ ,  $a_1[3, 4, 5]$ ,  $a_2[4, 5, 6]$
  - $b_0[1, 2, 3]$ ,  $b_1[10, 11, 12]$ ,  $b_2[12, 13, 14]$
  - $c_0[30, 31, 0]$ ,  $c_1[6, 7, 8]$ ,  $c_2[11, 12, 13]$
  - $e_0[27, 28, 29]$ ,  $e_1[20, 21, 22]$
- Once we fix these message bits in the state 2, the slice 1 and slice 2 of state 3 get fixed.

# Possible solutions for groups of 3 slices

- Consider a group of 3 slices (for example take the first 3 slices).
- It contains the following message bits:
  - $a_0[0, 1, 2]$ ,  $a_1[3, 4, 5]$ ,  $a_2[4, 5, 6]$
  - $b_0[1, 2, 3]$ ,  $b_1[10, 11, 12]$ ,  $b_2[12, 13, 14]$
  - $c_0[30, 31, 0]$ ,  $c_1[6, 7, 8]$ ,  $c_2[11, 12, 13]$
  - $e_0[27, 28, 29]$ ,  $e_1[20, 21, 22]$
- Once we fix these message bits in the state 2, the slice 1 and slice 2 of state 3 get fixed.
- Furthermore, there is no dependency between these message bits.

# Possible solutions for groups of 3 slices

- Consider a group of 3 slices (for example take the first 3 slices).
- It contains the following message bits:
  - $a_0[0, 1, 2]$ ,  $a_1[3, 4, 5]$ ,  $a_2[4, 5, 6]$
  - $b_0[1, 2, 3]$ ,  $b_1[10, 11, 12]$ ,  $b_2[12, 13, 14]$
  - $c_0[30, 31, 0]$ ,  $c_1[6, 7, 8]$ ,  $c_2[11, 12, 13]$
  - $e_0[27, 28, 29]$ ,  $e_1[20, 21, 22]$
- Once we fix these message bits in the state 2, the slice 1 and slice 2 of state 3 get fixed.
- Furthermore, there is no dependency between these message bits.
- Thus, the total number of possible solutions for this 3-slice are  $2^{33-2\cdot 7} = 2^{19}$ .

# Possible solutions for groups of 6 slices

- This is obtained by merging two groups of 3 slices.

# Possible solutions for groups of 6 slices

- This is obtained by merging two groups of 3 slices.
- Consider, for example, the first two 3-slices (first 6 slices).
- It contains the following message bits:
  - $a_0[0 - 5]$ ,  $a_1[3 - 8]$ ,  $a_2[4 - 9]$
  - $b_0[1 - 6]$ ,  $b_1[10 - 15]$ ,  $b_2[12 - 17]$
  - $c_0[30 - 3]$ ,  $c_1[6 - 11]$ ,  $c_2[11 - 16]$
  - $e_0[27 - 0]$ ,  $e_1[20 - 25]$

# Possible solutions for groups of 6 slices

- This is obtained by merging two groups of 3 slices.
- Consider, for example, the first two 3-slices (first 6 slices).
- It contains the following message bits:
  - $a_0[0 - 5]$ ,  $a_1[3 - 8]$ ,  $a_2[4 - 9]$
  - $b_0[1 - 6]$ ,  $b_1[10 - 15]$ ,  $b_2[12 - 17]$
  - $c_0[30 - 3]$ ,  $c_1[6 - 11]$ ,  $c_2[11 - 16]$
  - $e_0[27 - 0]$ ,  $e_1[20 - 25]$
- During merging, we get to compute the bit values of slice 3 of the state 3 as well.

# Possible solutions for groups of 6 slices

- This is obtained by merging two groups of 3 slices.
- Consider, for example, the first two 3-slices (first 6 slices).
- It contains the following message bits:
  - $a_0[0 - 5]$ ,  $a_1[3 - 8]$ ,  $a_2[4 - 9]$
  - $b_0[1 - 6]$ ,  $b_1[10 - 15]$ ,  $b_2[12 - 17]$
  - $c_0[30 - 3]$ ,  $c_1[6 - 11]$ ,  $c_2[11 - 16]$
  - $e_0[27 - 0]$ ,  $e_1[20 - 25]$
- During merging, we get to compute the bit values of slice 3 of the state 3 as well.
- We already have the correct bit values of slice 3 of the state 3, and there is dependency between the above message bit variables.

# Possible solutions for groups of 6 slices

- This is obtained by merging two groups of 3 slices.
- Consider, for example, the first two 3-slices (first 6 slices).
- It contains the following message bits:
  - $a_0[0 - 5]$ ,  $a_1[3 - 8]$ ,  $a_2[4 - 9]$
  - $b_0[1 - 6]$ ,  $b_1[10 - 15]$ ,  $b_2[12 - 17]$
  - $c_0[30 - 3]$ ,  $c_1[6 - 11]$ ,  $c_2[11 - 16]$
  - $e_0[27 - 0]$ ,  $e_1[20 - 25]$
- During merging, we get to compute the bit values of slice 3 of the state 3 as well.
- We already have the correct bit values of slice 3 of the state 3, and there is dependency between the above message bit variables.
- The total number of possible solutions are  $2^{2 \cdot 19 - 2 - 7} = 2^{29}$ .
- There is dependency between bits  $a_0[4, 5]$ ,  $a_1[4, 5]$  and  $a_2[4, 5]$ .



# Possible solutions for groups of 12 slices

- Similar to the case of 6-slice, the solution for a 12-slice is obtained by merging two 6-slices.

# Possible solutions for groups of 12 slices

- Similar to the case of 6-slice, the solution for a 12-slice is obtained by merging two 6-slices.
- Consider, for example, the first 12 slices. It contains the following message bits:
  - $a_0[0 - 11], a_1[3 - 14], a_2[4 - 15]$
  - $b_0[1 - 12], b_1[10 - 21], b_2[12 - 23]$
  - $c_0[30 - 9], c_1[6 - 17], c_2[11 - 22]$
  - $e_0[27 - 6], e_1[20 - 31]$

# Possible solutions for groups of 12 slices

- Similar to the case of 6-slice, the solution for a 12-slice is obtained by merging two 6-slices.
- Consider, for example, the first 12 slices. It contains the following message bits:
  - $a_0[0 - 11]$ ,  $a_1[3 - 14]$ ,  $a_2[4 - 15]$
  - $b_0[1 - 12]$ ,  $b_1[10 - 21]$ ,  $b_2[12 - 23]$
  - $c_0[30 - 9]$ ,  $c_1[6 - 17]$ ,  $c_2[11 - 22]$
  - $e_0[27 - 6]$ ,  $e_1[20 - 31]$
- As before, here we again get the values of slice 6 of state 3.

# Possible solutions for groups of 12 slices

- Similar to the case of 6-slice, the solution for a 12-slice is obtained by merging two 6-slices.
- Consider, for example, the first 12 slices. It contains the following message bits:
  - $a_0[0 - 11]$ ,  $a_1[3 - 14]$ ,  $a_2[4 - 15]$
  - $b_0[1 - 12]$ ,  $b_1[10 - 21]$ ,  $b_2[12 - 23]$
  - $c_0[30 - 9]$ ,  $c_1[6 - 17]$ ,  $c_2[11 - 22]$
  - $e_0[27 - 6]$ ,  $e_1[20 - 31]$
- As before, here we again get the values of slice 6 of state 3.
- Similar to 6-slice, the bit variables are dependent.
- The bit variables  $a_0, a_1, a_2[6 - 9], b_0, b_1, b_2[12]$ , and  $e_0, e_1[27 - 31]$  are dependent.

# Possible solutions for groups of 12 slices

- Similar to the case of 6-slice, the solution for a 12-slice is obtained by merging two 6-slices.
- Consider, for example, the first 12 slices. It contains the following message bits:
  - $a_0[0 - 11], a_1[3 - 14], a_2[4 - 15]$
  - $b_0[1 - 12], b_1[10 - 21], b_2[12 - 23]$
  - $c_0[30 - 9], c_1[6 - 17], c_2[11 - 22]$
  - $e_0[27 - 6], e_1[20 - 31]$
- As before, here we again get the values of slice 6 of state 3.
- Similar to 6-slice, the bit variables are dependent.
- The bit variables  $a_0, a_1, a_2[6 - 9], b_0, b_1, b_2[12]$ , and  $e_0, e_1[27 - 31]$  are dependent.
- Hence, the total number of possible solutions are  $2^{2 \cdot 29 - 10 - 7} = 2^{41}$ .

# Possible solutions for groups of 24 slices

- This is obtained by merging two groups of 12 slices.

# Possible solutions for groups of 24 slices

- This is obtained by merging two groups of 12 slices.
- For example, consider the first 24 slices i.e.,
  - $a_0[0 - 23]$ ,  $a_1[3 - 26]$ ,  $a_2[4 - 27]$
  - $b_0[1 - 24]$ ,  $b_1[10 - 1]$ ,  $b_2[12 - 3]$
  - $c_0[30 - 21]$ ,  $c_1[6 - 29]$ ,  $c_2[11 - 2]$
  - $e_0[27 - 18]$ ,  $e_1[20 - 11]$

# Possible solutions for groups of 24 slices

- This is obtained by merging two groups of 12 slices.
- For example, consider the first 24 slices i.e.,
  - $a_0[0 - 23], a_1[3 - 26], a_2[4 - 27]$
  - $b_0[1 - 24], b_1[10 - 1], b_2[12 - 3]$
  - $c_0[30 - 21], c_1[6 - 29], c_2[11 - 2]$
  - $e_0[27 - 18], e_1[20 - 11]$
- This is very much similar to the 12 slice solution.
- In this case, we get 34 dependencies.
- The total number of possible solutions are  $2^{2 \cdot 41 - 34 - 7} = 2^{41}$ .



# Final solutions

- Using the same method, we find the possible solutions for the remaining 6 slices and 2 slices.

# Final solutions

- Using the same method, we find the possible solutions for the remaining 6 slices and 2 slices.
- For finding the solution for the last consecutive 8 slices, we merge possible solution of its constituent 6-slice and 2-slice.

# Final solutions

- Using the same method, we find the possible solutions for the remaining 6 slices and 2 slices.
- For finding the solution for the last consecutive 8 slices, we merge possible solution of its constituent 6-slice and 2-slice.
- Final solution space is obtained by merging the solution space of first 24 slices and the last 8 slices.

# Final solutions

- Using the same method, we find the possible solutions for the remaining 6 slices and 2 slices.
- For finding the solution for the last consecutive 8 slices, we merge possible solution of its constituent 6-slice and 2-slice.
- Final solution space is obtained by merging the solution space of first 24 slices and the last 8 slices.
- In merging, we can compute the  $\theta$  mapping of the remaining two slices, in turn, we get the additional restriction of  $2 \cdot 7$  bits.

# Final solutions

- Using the same method, we find the possible solutions for the remaining 6 slices and 2 slices.
- For finding the solution for the last consecutive 8 slices, we merge possible solution of its constituent 6-slice and 2-slice.
- Final solution space is obtained by merging the solution space of first 24 slices and the last 8 slices.
- In merging, we can compute the  $\theta$  mapping of the remaining two slices, in turn, we get the additional restriction of  $2 \cdot 7$  bits.
- In this case, we get 61 dependencies.
- Total number of solutions are  $2^{41+34-61-2 \cdot 7} = 2^0 = 1$ .

# Attack Complexity

- Space complexity of the attack =  $2^{42}$
- Time complexity of the attack =  $2^{44}$
- Also, we can find second preimages by setting  $d_0, d_1$  to a constant such that it satisfies  $d_0[i] = d_1[i]$  and then repeating the attack for this setting.

# Conclusion

- We have presented a preimage attack on the 2 rounds of round reduced KECCAK[ $r := 800 - 384$ ,  $c := 384$ ].

# Conclusion

- We have presented a preimage attack on the 2 rounds of round reduced KECCAK[ $r := 800 - 384$ ,  $c := 384$ ].
- This is a practical attack with attack complexity of  $2^{44}$ .



# Conclusion

- We have presented a preimage attack on the 2 rounds of round reduced KECCAK[ $r := 800 - 384, c := 384$ ].
- This is a practical attack with attack complexity of  $2^{44}$ .
- Future work: Variant(s) of this attack for more rounds of KECCAK.

Thank You