



GAP–Peripheral Demo User’s Guide

GAP_Peripheral_Demo_User's_Guide

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1. Overview

This document explains how to setup a GAP-Peripheral demo using SAML21 Xplained PRO, BM71-XPro, BNO055 Xplained PRO board and Smart phone. This document briefly talks about setting up hardware, building application, programming configuration file, programming firmware, and running a demo.

This demo application showcases a Proof-of-Concept example of using **ble_host_sdk** to setup BM71 as GAP-Peripheral. This demo application uses custom GATT service to share accelerometer and gyroscope sensor data with remote device.

The following table provides the list of supported BLE services and Characteristics in this application.

Name	UUID	Properties	Size (bytes)
Device Orientation Service (Custom)	0xF05ABAC1393611E587A60002A5D5C51B	-	-
Accelerometer Position Characteristic	0x1BC5D5A50200A687E5113639D7BA5AF0	Notify, Read	6
Gyroscope Position Characteristic	0x1BC5D5A50200A687E5113639D4BA5AF0	Notify, Read	6

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2. Configuring and flashing the service, characteristics, and descriptors to BM71 XPRO board

It is necessary to configure the BM71 XPRO board by making changes to the configuration file and flash the modified changes to BM71 XPRO board based on the peripheral application flow. The configuration changes demand the module to configure in Manual mode and add GATT service table.

By default, the BM71 XPro board is configured to operate in Auto mode. The Microchip Studio project, however, requires the module to set up in Manual mode.

The following instructions show how to setup and configure the module to add configuration changes.

1. Connect the BM71 XPro directly to the PC using the MicroUSB on the board. The BM71 XPro board should enumerate a COM port. If not, check if the necessary MCP2200 drivers have been installed.
2. Set up the module to programming mode by configuring the Switch 1 in 3-pin DIP switch to ON state. The switch#1 sets the mode of operation on the module (between application mode and flash write mode). Refer to details on pin P2_0 in the BM70 datasheet for more details. The Blue LED (labeled BT_ACT, LD4) should be solid BLUE now. If not, check the following: a. Press 'Reset' button on the board.
NOTE: Make sure the jumper on J2 is set to USB.
3. Make sure that the BM71 module does have the correct BM71 firmware installed. By default, they should be. However, if you have programmed the module to be RN4871, change the firmware back to BM71. If the module has RN871 firmware, the module will not operate as expected and the Studio project will fail.
4. Open the UI tool for the BM70/71 modules. This tool is available for download from the BM70/71 webpage under the 'Software libraries/firmware' section.
5. Open the UI tool:



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- a. In the example below, the 'BM71 default table' is being used as the base file.
Click on 'Edit' to start editing the memory parameters.
- b. The following changes are made in the first 'System Setup' tab:
 - i. Disable the low power operation.
 - ii. Change the operation mode to 'Manual pattern.'

System Setup | System Setup2 | LE Mode Setup | GATT Service Table | LED Setup | Beacon Setup

Device Information

--- Name Fragment: BM71_BLE [32 characters] Help

Uart Setting

--- HCI Baud Rate Index: 0x03 : 115200 Help

--- H/W Flow Control: Disable

--- Rx Notify Length: 0x05 (0x00~0xFF)

--- UART RX_IND: Disable

--- UART Parity: Disable

--- Parity Mode: 0x00: Odd Parity

--- Stop Bit: 1 stop bit

Operation Mode Setting

--- Operation Pattern: Manual Pattern Help

--- Configure Mode Timeout: 0x00

Previous Next Finish

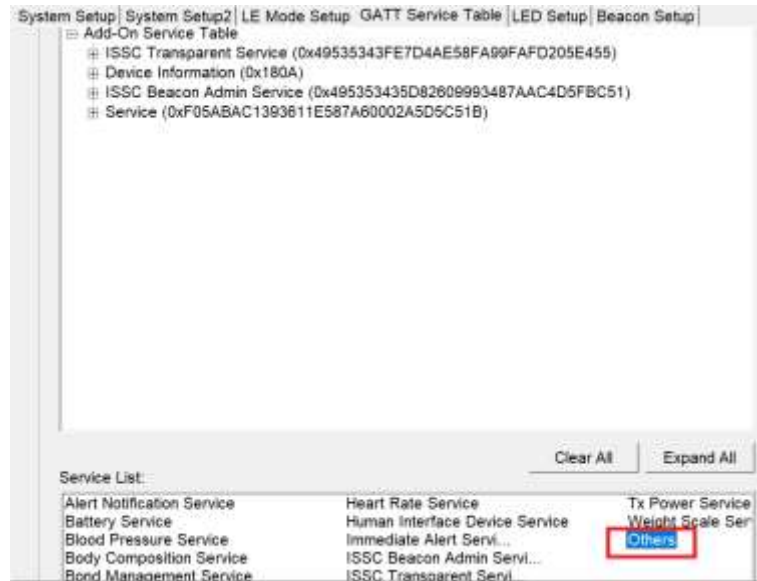
- c. In the 'GATT Service Table' tab, you will need to enter the private service/characteristics for the project.

The following table provides the list of supported BLE services and Characteristics in this application.

Name	UUID	Properties	Size (bytes)
Device Orientation Service (Custom)	0xF05ABAC1393611E587A60002A5D5C51B	-	-
Accelerometer Position Characteristic	0x1BC5D5A50200A687E5113639D7BA5AF0	Notify, Read	6
Gyroscope Position Characteristic	0x1BC5D5A50200A687E5113639D4BA5AF0	Notify, Read	6

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To create the custom GATT table using the UI Tool, select the “others” option in the ‘Service List’.



- i. The 'Others' is the option that allows you to create a User-defined service and characteristics. **Drag this text into the 'Add-On Service Table' field** above. You will get a dialog box to create the private service. Enter the Private service UUID.



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- ii. Click 'Next' and then enter the private characteristic under this service.

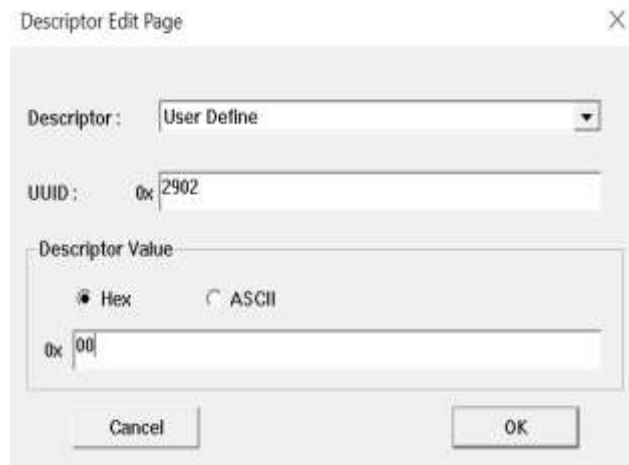
The 'Characteristic Edit Page' dialog box is shown. It has a title bar with a close button. The 'Characteristic' dropdown menu is set to 'User Define'. The 'UUID' field is set to '0x1BC5D5A50200A687E5113639D7BA5AF0'. There are three checkboxes: 'Manual Read Response' (unchecked), 'Manual Write Response' (unchecked), and 'Attribute Permission' (unchecked). The 'Properties' section has two columns of checkboxes: 'Read' (checked), 'Write Without Response' (unchecked), 'Write' (unchecked), 'Notify' (checked), 'Indicate' (unchecked), and 'Extended Properties' (unchecked). The 'Characteristic Value' section has two radio buttons: 'Hex' (selected) and 'ASCII' (unchecked). The 'Value' field is set to '0x000000000000'. Below the field, it says '(MAX: 245 bytes, Current: 6 bytes)'. At the bottom, there are 'Cancel' and 'OK' buttons.

- iii. In the newly created private service in the 'Add-On service' field, right click on the private service to 'Add Characteristic' the second private characteristic. Enter the details of the second private characteristic.

The 'Characteristic Edit Page' dialog box is shown. It has a title bar with a close button. The 'Characteristic' dropdown menu is set to 'User Define'. The 'UUID' field is set to '0x1BC5D5A50200A687E5113639D4BA5AF0'. There are three checkboxes: 'Manual Read Response' (unchecked), 'Manual Write Response' (unchecked), and 'Attribute Permission' (unchecked). The 'Properties' section has two columns of checkboxes: 'Read' (checked), 'Write Without Response' (unchecked), 'Write' (unchecked), 'Notify' (checked), 'Indicate' (unchecked), and 'Extended Properties' (unchecked). The 'Characteristic Value' section has two radio buttons: 'Hex' (selected) and 'ASCII' (unchecked). The 'Value' field is set to '0x000000000000'. Below the field, it says '(MAX: 245 bytes, Current: 6 bytes)'. At the bottom, there are 'Cancel' and 'OK' buttons.

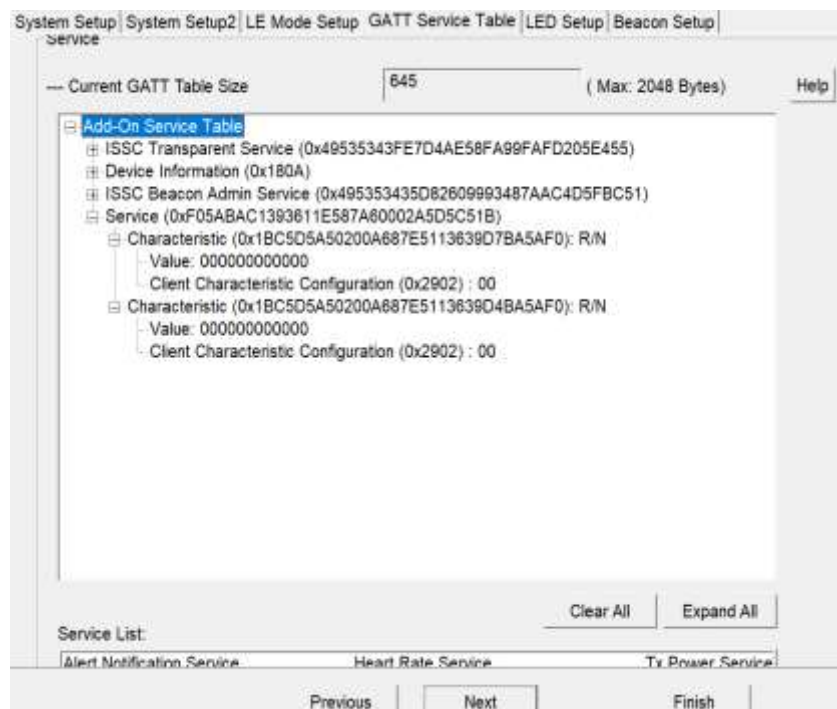
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- iv. Right click on the first Characteristic and select 'Add Descriptor' and enter the UUID as 2902



The image shows a 'Descriptor Edit Page' dialog box. It has a title bar with a close button (X). Inside, there is a 'Descriptor:' dropdown menu set to 'User Define'. Below it is a 'UUID:' text field containing '0x2902'. Underneath is a 'Descriptor Value' section with two radio buttons: 'Hex' (selected) and 'ASCII'. Below the radio buttons is a text field containing '0x00'. At the bottom are 'Cancel' and 'OK' buttons.

- v. Similarly add the descriptor for the second characteristic as well with the same UUID value(2902)
- vi. The final 'Add-On Service Table' should look like below.

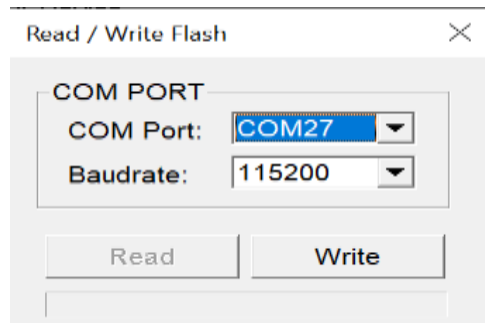


The image shows a screenshot of the 'GATT Service Table' tab in a software interface. The 'Current GATT Table Size' is 645 (Max: 2048 Bytes). The 'Add-On Service Table' is expanded, showing a list of services and characteristics. The services listed are: ISSC Transparent Service (0x49535343FE7D4AE58FA99FAFD205E455), Device Information (0x180A), ISSC Beacon Admin Service (0x495353435D82609993487AAC4D5FBC51), and Service (0xF05ABAC1393611E587A60002A5D5C51B). Under the 'Service' entry, there are two characteristics: 'Characteristic (0x1BC5D5A50200A687E5113639D7BA5AF0): R/N' and 'Characteristic (0x1BC5D5A50200A687E5113639D4BA5AF0): R/N'. Each characteristic has a 'Value: 000000000000' and a 'Client Characteristic Configuration (0x2902): 00'. At the bottom, there is a 'Service List' section with buttons for 'Alert Notification Service', 'Heart Rate Service', and 'Tx Power Service'. There are also 'Clear All', 'Expand All', 'Previous', 'Next', and 'Finish' buttons.

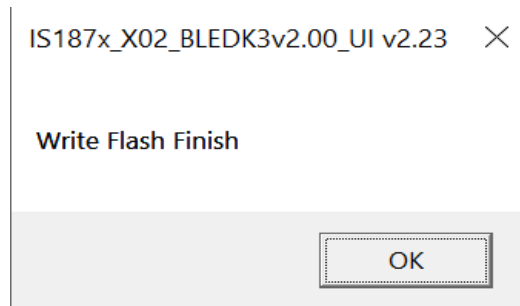
- vii. Click on 'Finish'. All the parameter required are now set and ready to flash to device.

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- viii. Click on 'Write' option in UI tool.
- ix. Select the COM port corresponding to the BM71 XPRO board. Make sure the Blue LED is still Solid ON to make sure the module is 'Write Flash' mode.



- x. Click on 'Write'. After the confirmation acceptance the configuration file will be written into the device memory.



- xi. Now, that the Flash write operation is done, the module needs to be set back to 'Application mode': Set the Switch#1 in the DIP switch to OFF and change the J2 jumper.

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3. Hardware Setup

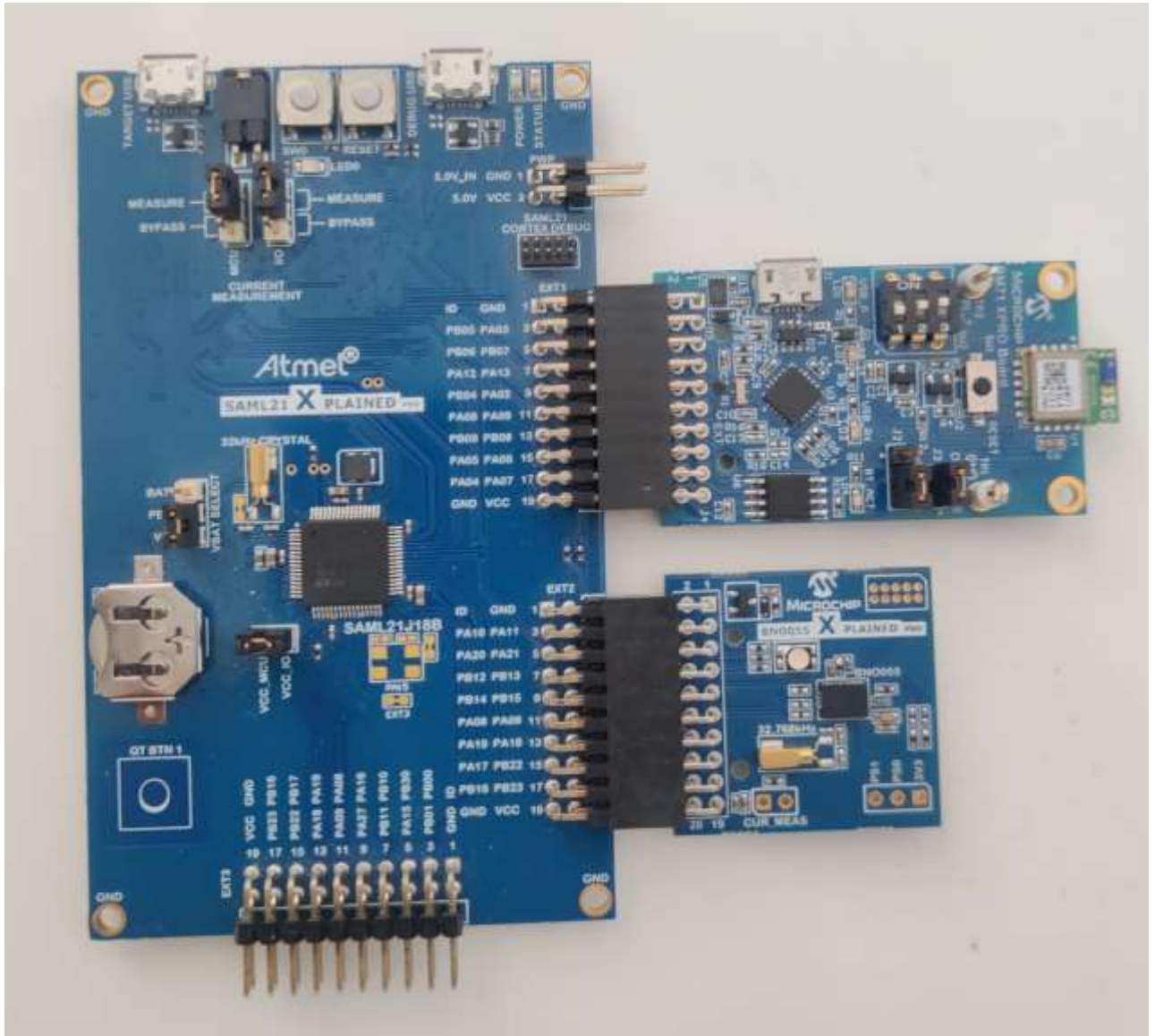


Figure 1: SAML21 Xplained Pro with BM71-XPRO and BNO055 Xplained PRO Board

1. Plugin the BM71-XPRO board into EXT1 of SAML21 Xplained Pro board as shown in Figure 1.
2. BNO055 Xplained PRO Board is used in this demo. Plug-in the BNO055 board into the EXT2 of SAML21 Xplained Pro as shown in Figure 1.
3. Connect the SAML21 Xplained Pro board to the host PC using micro USB cable.

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3.1 Console

The GAP-Peripheral demo application uses the Universal Asynchronous Receiver/Transmitter (UART) interface on SAML21 Xplained Pro to send the status messages like Advertising, Connected, Disconnected ... etc. Any serial application (ex: TeraTerm) can be used to interact with SAML21 Xplained Pro.

UART (COM port) settings,

Baud rate	115200
Data	8 bits
Parity	none
Stop	1 bit
Flow control	none

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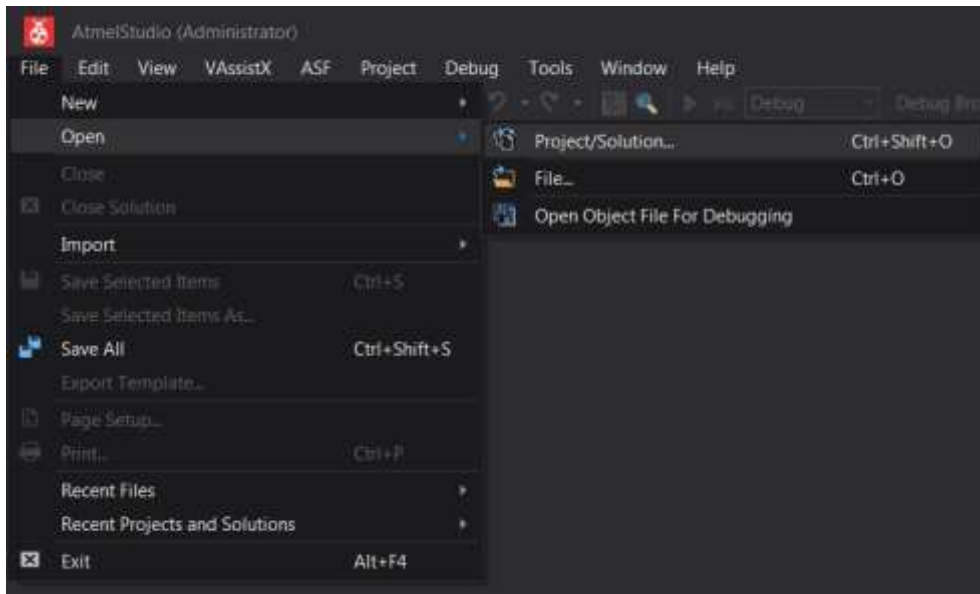
4. Build Procedure

This section describes build procedure of GAP-Peripheral demo application on Microchip Studio 7.

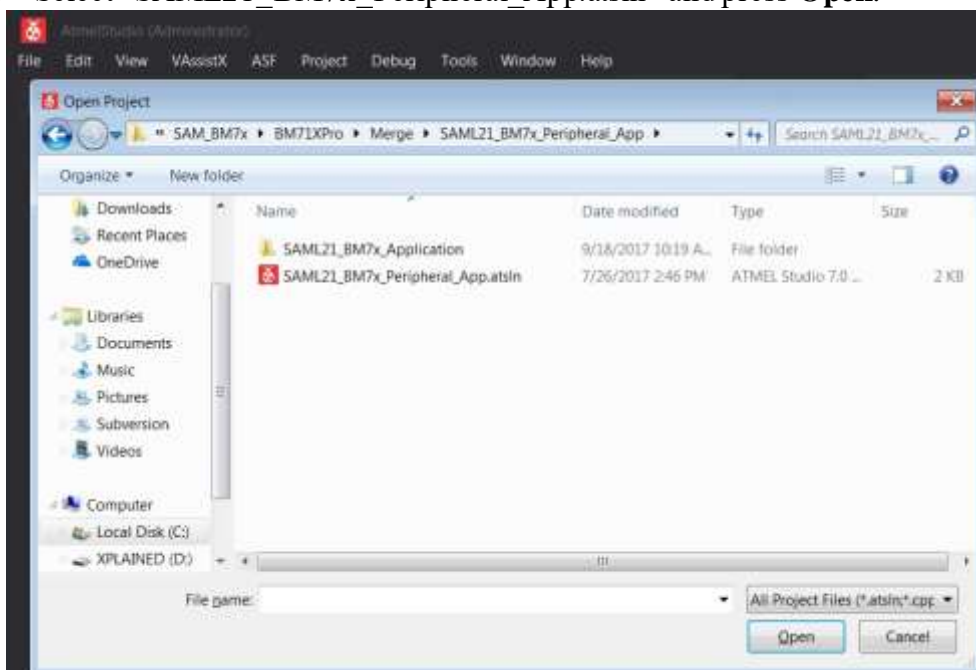
4.1. Open Microchip Studio 7

4.2. Open GAP-Peripheral Demo Application

1. Go to menu **File** → **Open** → **Project/Solution**.



2. Select “SAML21_BM7x_Peripheral_App.atsln” and press **Open**.

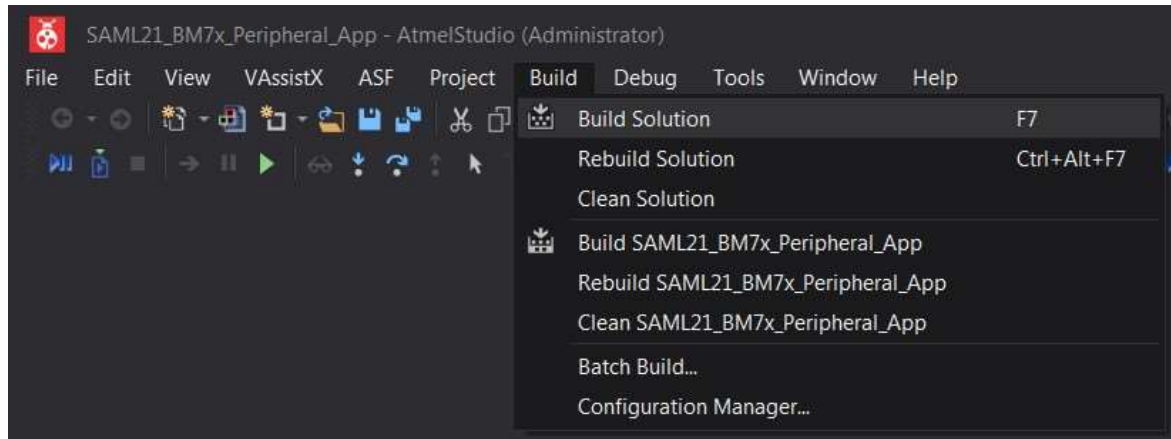


3. Once the project is opened, you can see the files attached to this project in Solution Explorer Window

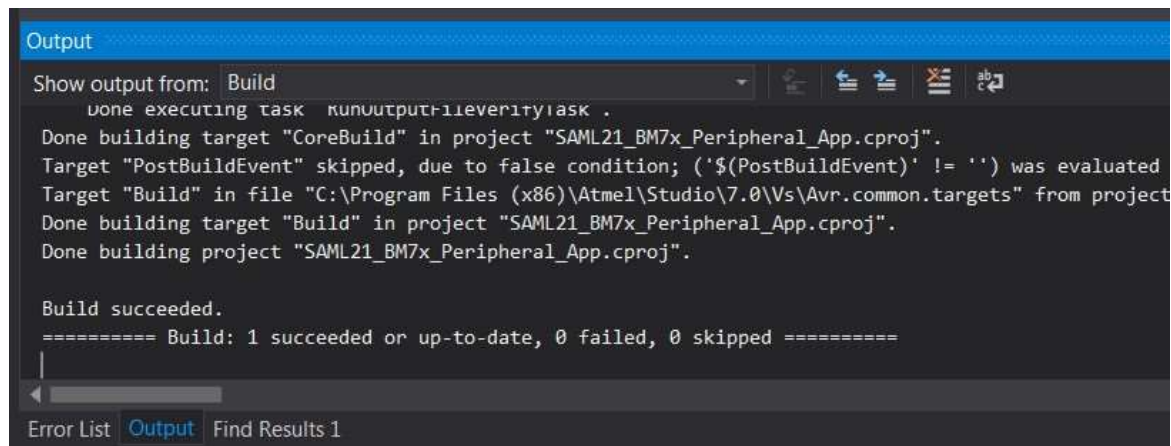
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4.3. Build GAP-Peripheral Demo Application

1. Go to menu **Build** → **Build Solution** or Press **F7**



2. Build status can be checked in **Output** window.



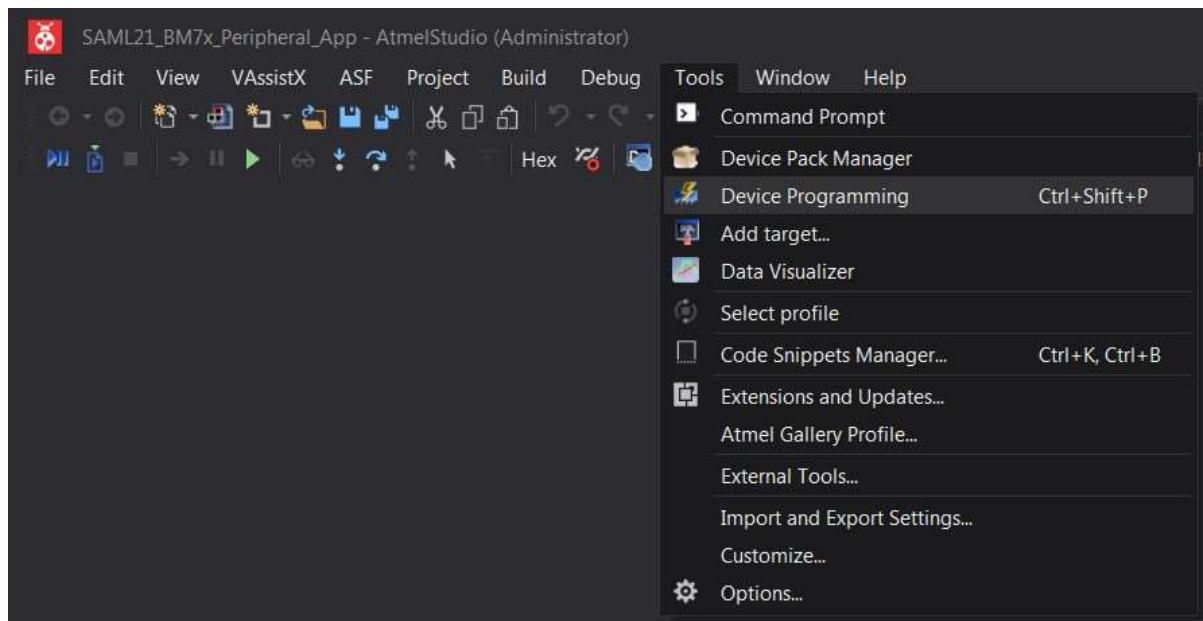
3. You can find the Hex images in “..\SAML21_BM7x_Application\Debug”.

5. Programming Firmware

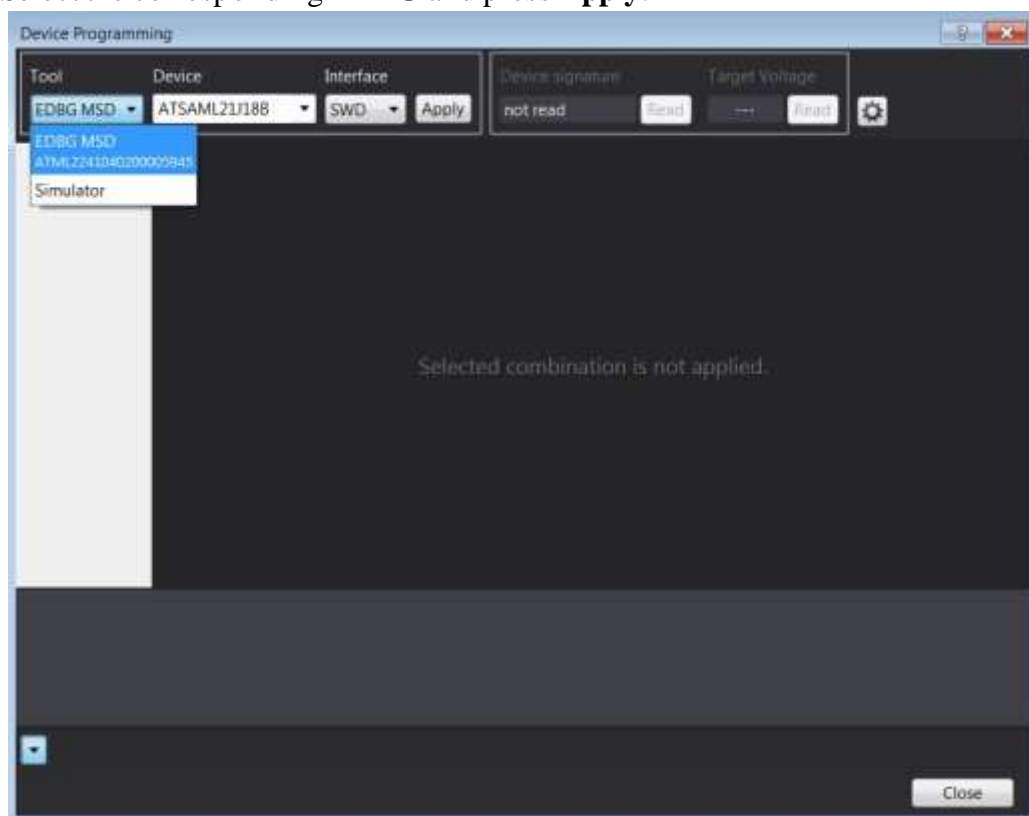
This section describes the procedure to program GAP-Peripheral demo firmware on SAML21 Xplained Pro board.

1. Connect the SAML21 Xplained Pro board to the host PC using micro-USB cable. Perform the following steps:
 - a. Verify that the virtual COM port is enumerated on the host PC.
 - b. Make sure that POWER LED (green) is solid ON.
2. To program the HEX files into the SAML21, go to menu **Tools** → **Device Programming** or Press **Ctrl + Shift + P**.

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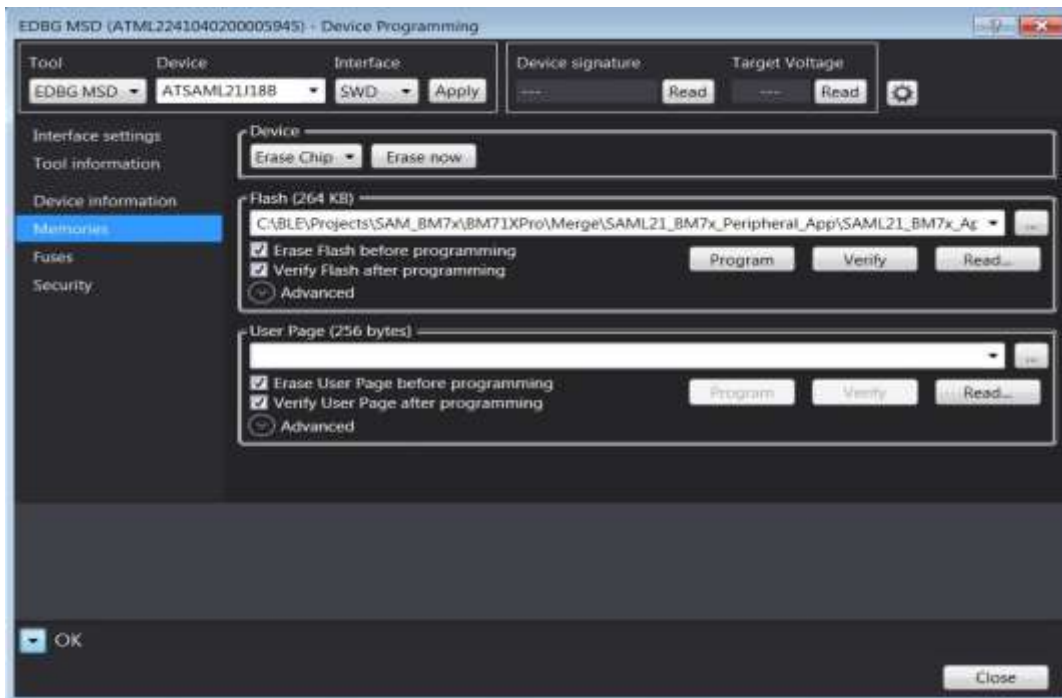


3. Select the corresponding **EDBG** and press **Apply**.

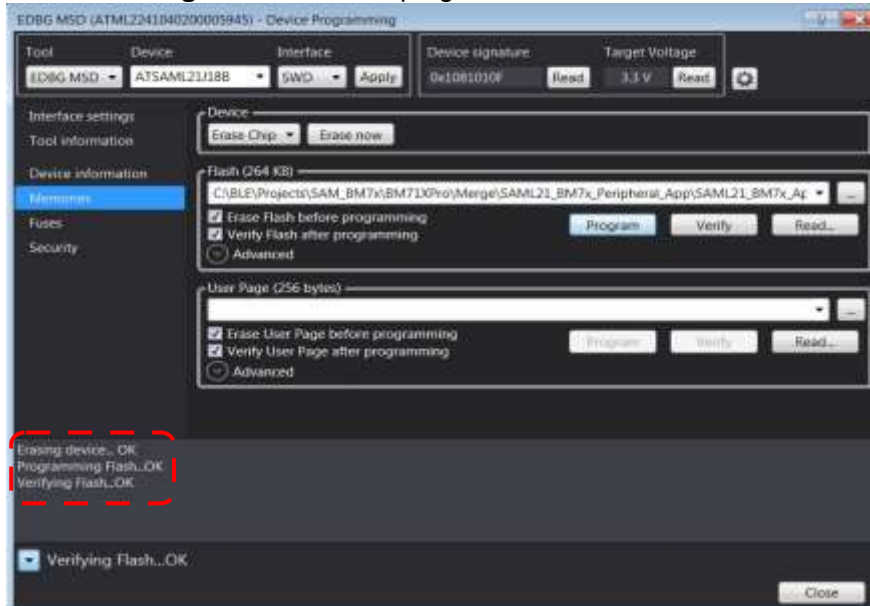


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4. Go to **Memories** Tab and select Hex file.



5. Press **Program**, the tool will program SAML21. You can check the status of programming.



6. Once programming is done, close the Device Programming window.

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6. Running GAP-Peripheral Demo with Microchip Bluetooth Data app

This section describes the GAP-Peripheral Demo procedures to work with Android Microchip Bluetooth Data app.

NOTE: There are differences in the response packet send by the BM71 firmware for the Read_Local_Specific_Primary_Service (0x3C) command in regards to different firmware version. Until the firmware Version 1.11 it follows same pattern and in V2.03 the response data packet structure changes. To make the application compactable with all the firmware version, the read back function is modified with a macro.

```
#define Older_Firmware_Versions
```

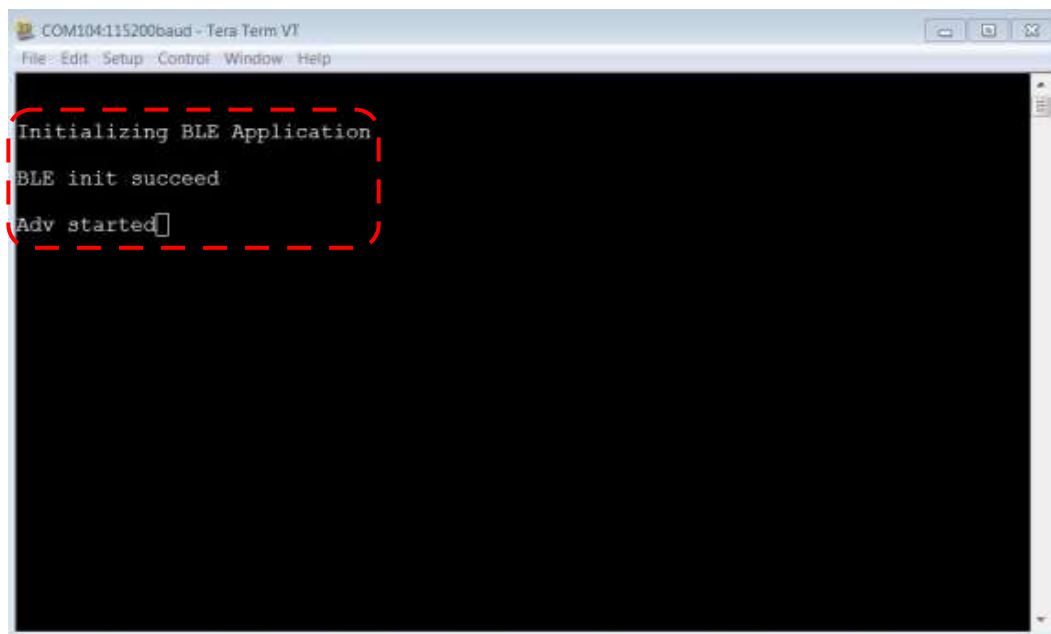
By default, this macro is commented in the code to make is work with the latest released firmware (2.03 at time of creation of this document). If the user is using an earlier firmware version, then it is recommended to uncomment this macro in the code.

1. Connect BM71-XPro on EXT1 of SAML21 Xplained Pro board (GAP-Peripheral device).
2. Connect the GAP-Peripheral device to the host PC using micro-USB cable. Perform the following steps:
 - a. Verify that the virtual COM port is enumerated on the host PC.
 - b. Open the enumerated COM port on a serial terminal application like TeraTerm with the following settings:

Baudrate	115200
Data	8 bits
Parity	none
Stop	1 bit
Flow control	none

- c. Make sure that POWER LED (green) on SAML21 Xplained Pro board is solid ON.
 - d. Press Reset button on SAML21 Xplained Pro board and verify that LD4 (blue) on BM71-XPro is blinking at a regular interval.
3. Ensure that the GAP-Peripheral device is advertising by checking the TeraTerm window for a message “Adv started”.

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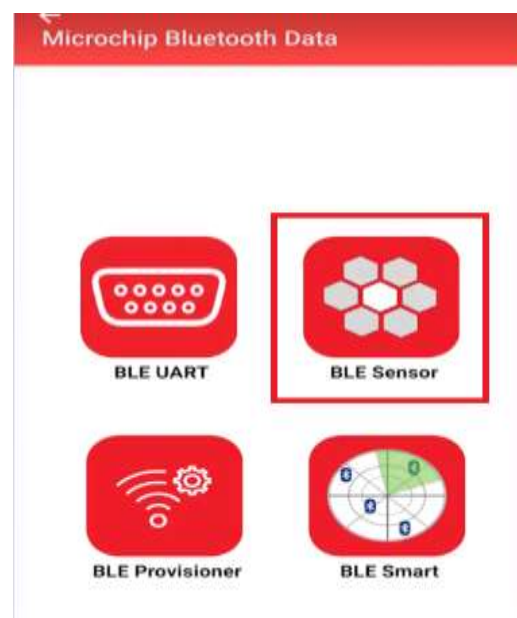


6.1. Smart Phone Application

- i. Download the Microchip Bluetooth Data (MBD) mobile application from the play store.

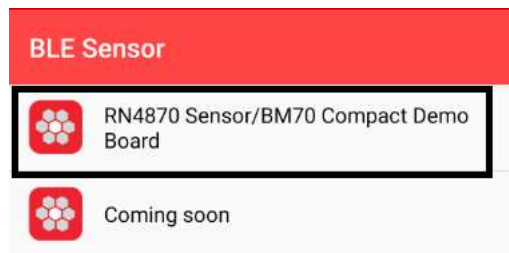


- ii. Select the BLE Sensor tab

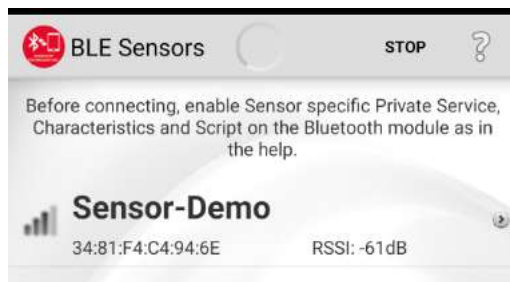


- iii. Select the RN4870 Sensor/BM70 Compact Demo Board option

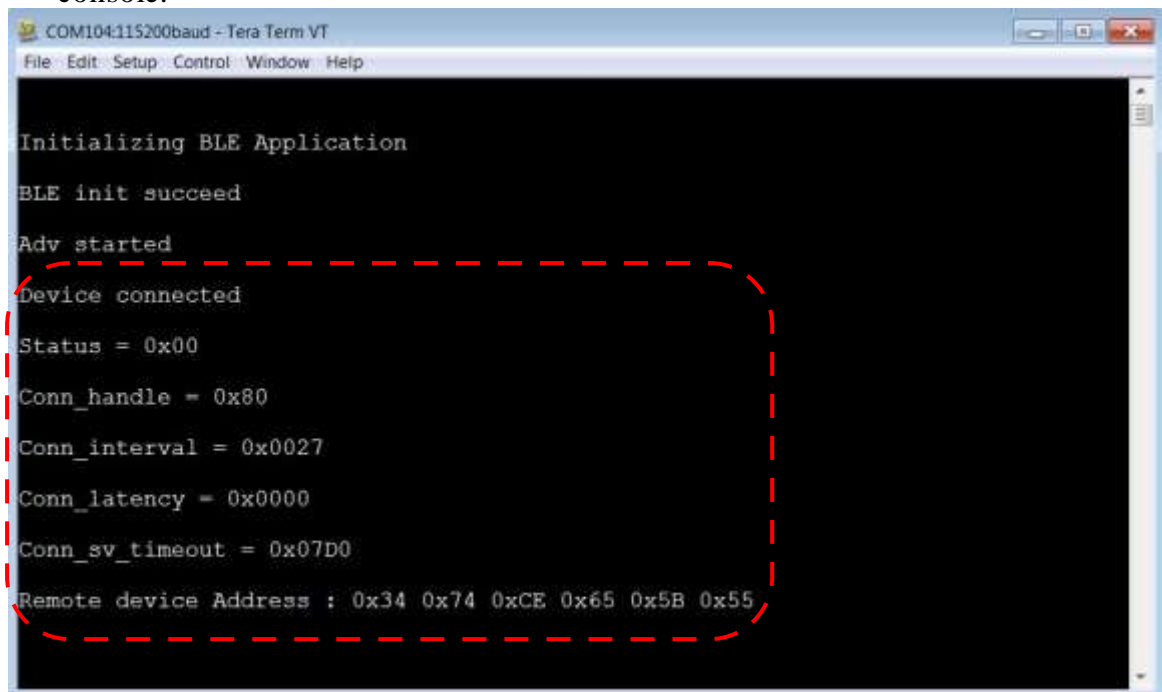
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- iv. Press **SCAN** and click on Sensor-Demo for the scan list to connect to the BM71



- v. After successful connection, GAP-Peripheral device prints the connection details in console.

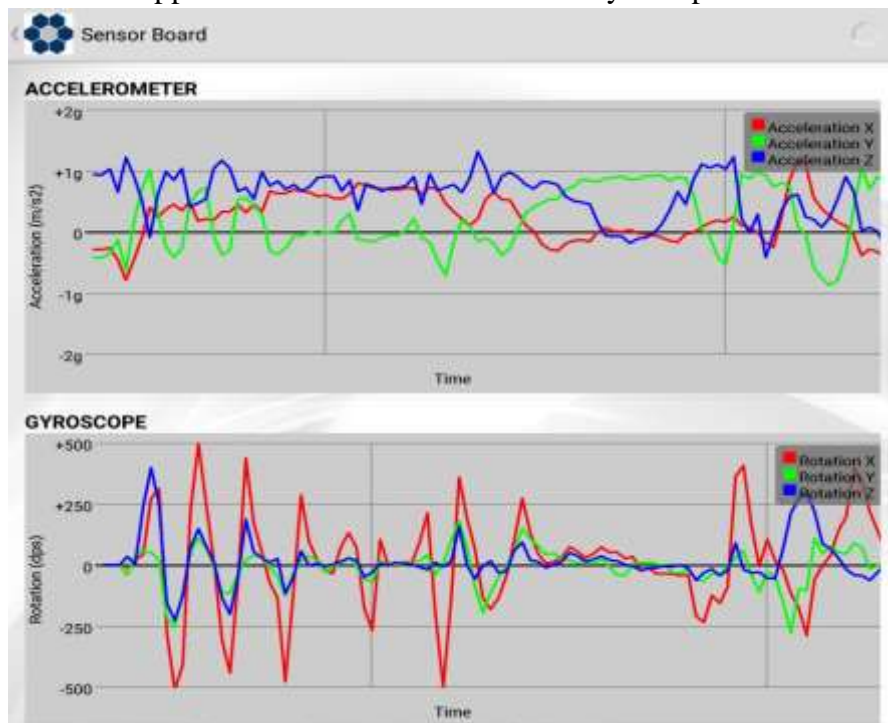


- vi. Once connected, the MBD app discovers the accelerometer and gyroscope sensor characteristics and enable notifications.
- vii. Once notification enabled by MBD app, GAP-Peripheral prints the accelerometer and gyroscope sensor read operation status and data on console.

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```
COM104:115200baud - Tera-Term VT
File Edit Setup Control Window Help
Notification enabled!!!
Status of Accelerometer sensor data read = 0
Acce data x = -4097 || y = -27649 || z = 1796
Acce - value send status = 0x00
Notification enabled!!!
Status of Accelerometer sensor data read = 0
Acce data x = -3841 || y = -27649 || z = 4100
Acce - value send status = 0x00
Status of Gyroscope sensor data read = 0
Gyro data x = -1025 || y = -1793 || z = -257
Gyro - value send status = 0x00
Status of Accelerometer sensor data read = 0
```

- viii. Once connected with GAP-Peripheral (Sensor-Demo) and notifications are enabled, BLESensorApp shows the Accelerometer and Gyroscope sensor data in graph view.



7. Running GAP-Peripheral Demo with GAP-Central Device

This section describes the GAP-Peripheral Demo procedures to work with GAP-Central device.

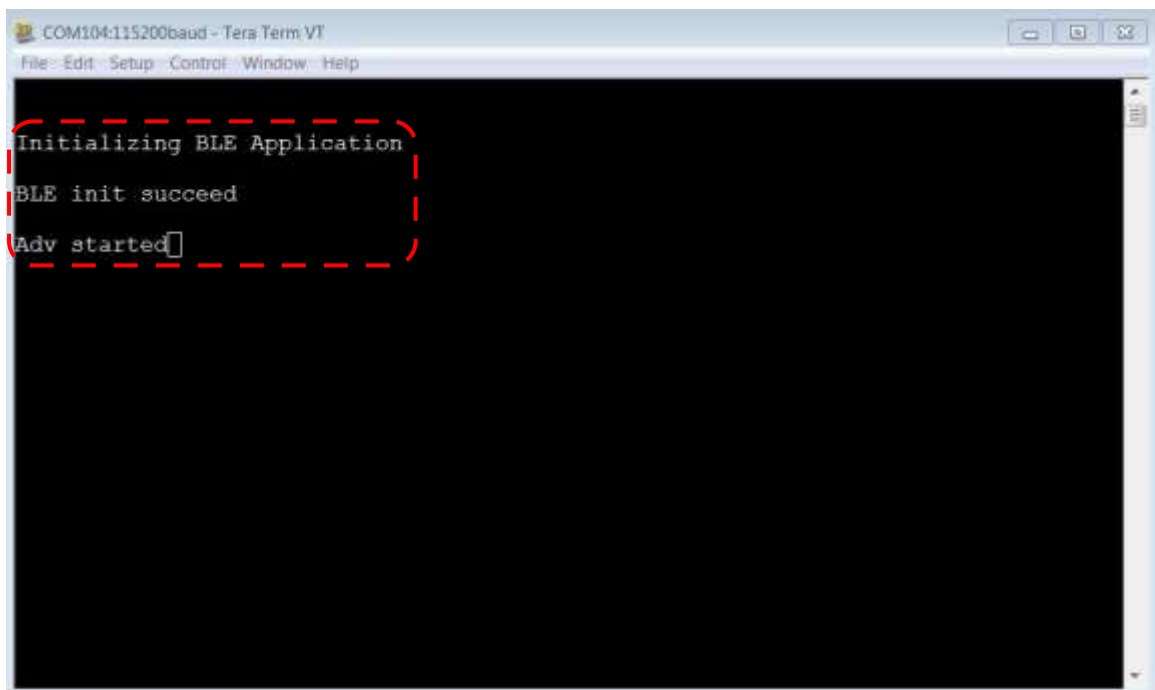
1. Connect BM71-XPro on EXT1 of SAML21 Xplained Pro board (GAP-Peripheral device).
2. Connect the GAP-Peripheral device to the host PC using micro-USB cable. Perform the following steps:
 - a. Verify that the virtual COM port is enumerated on the host PC.

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- b. Open the enumerated COM port on a serial console application like TeraTerm with the following settings:

Baudrate	115200
Data	8 bits
Parity	none
Stop	1 bit
Flow control	none

- c. Make sure that POWER LED (green) on SAML21 Xplained Pro board is solid ON.
- d. Press Reset button on SAML21 Xplained Pro board and verify that LD4 (blue) on BM71-XPro is blinking at a regular interval.
3. Ensure that the GAP-Peripheral device is up and running and start advertising. Check status on a serial console application.

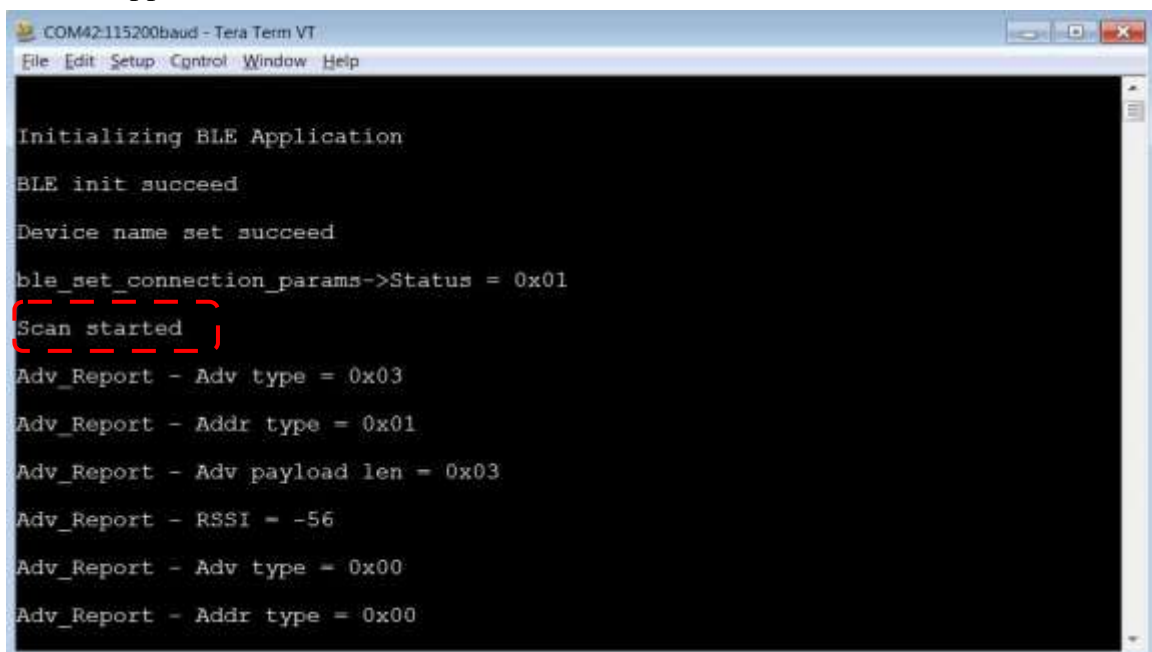


4. Connect BM71-XPro on EXT1 of SAML21 Xplained Pro board (GAP-Central device).
5. Connect the GAP-Central device to the host PC using micro USB cable. Perform the following steps:
- a. Verify that the virtual COM port is enumerated on the host PC.
- b. Open the enumerated COM port on a serial console application like TeraTerm with the following settings:

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Baudrate	115200
Data	8 bits
Parity	none
Stop	1 bit
Flow control	none

- c. Make sure that POWER LED (green) on SAML21 Xplained Pro board is solid ON.
 - d. Press Reset button on SAML21 Xplained Pro board and verify that LD4 (blue) on BM71-XPro is blinking at a regular interval.
6. Ensure GAP-Central device is up and running and start scanning. Check status on a serial console application.



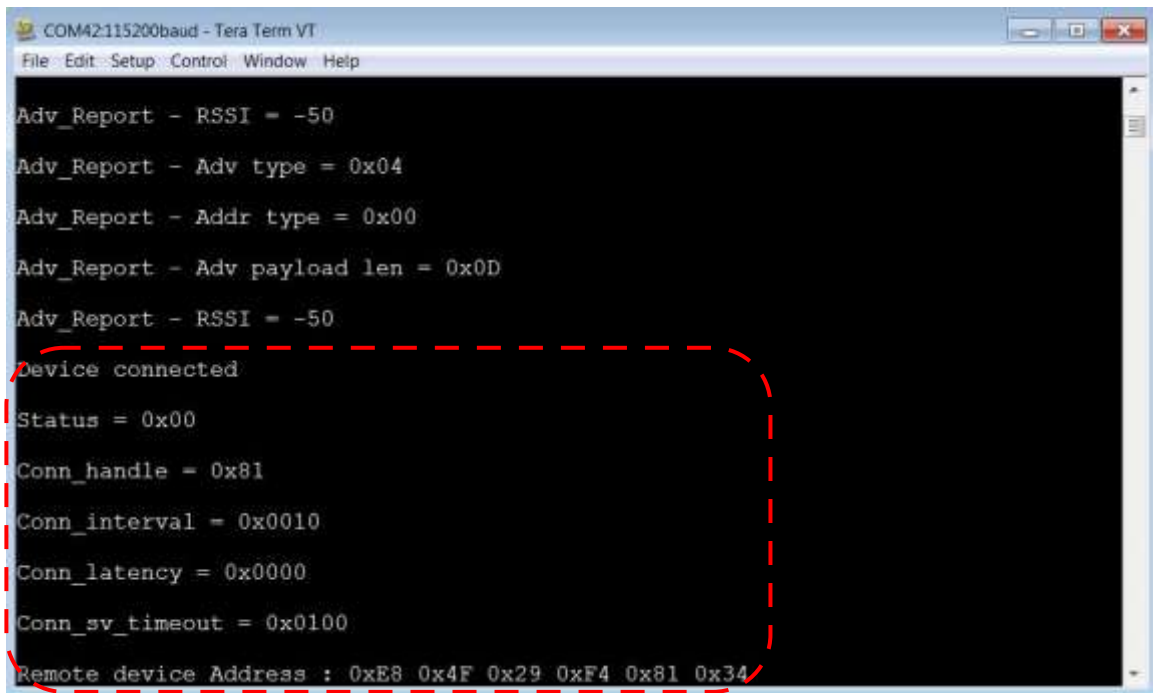
The screenshot shows a Tera Term VT window titled 'COM42-115200baud - Tera Term VT'. The window contains the following text:

```
Initializing BLE Application
BLE init succeed
Device name set succeed
ble_set_connection_params->Status = 0x01
Scan started
Adv_Report - Adv type = 0x03
Adv_Report - Addr type = 0x01
Adv_Report - Adv payload len = 0x03
Adv_Report - RSSI = -56
Adv_Report - Adv type = 0x00
Adv_Report - Addr type = 0x00
```

The text 'Scan started' is highlighted with a red dashed rectangle.

7. As GAP-Central device receives advertisements from devices in vicinity, it prints the advertisement report in serial console.
8. GAP-Central device finds the suitable GAP-Peripheral device based on the advertisement payload and initiates a connection.
9. Once connected the GAP-Central device prints the GAP-Peripheral device address and connection parameters in serial console.

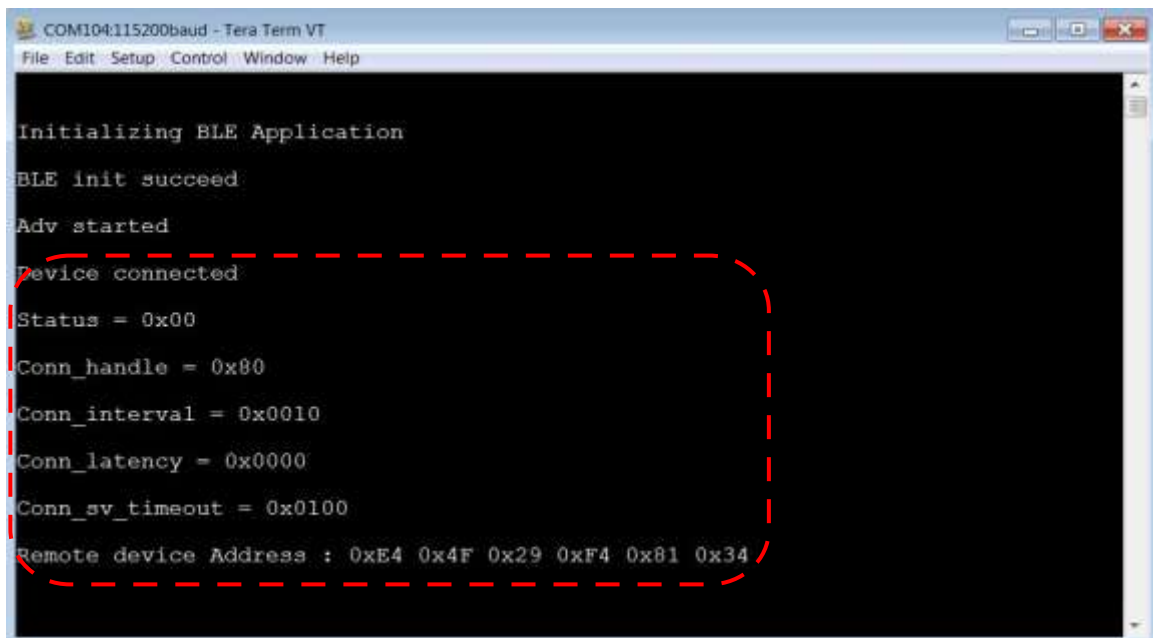
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```
COM42:115200baud - Tera Term VT
File Edit Setup Control Window Help

Adv_Report - RSSI = -50
Adv_Report - Adv type = 0x04
Adv_Report - Addr type = 0x00
Adv_Report - Adv payload len = 0x0D
Adv_Report - RSSI = -50
Device connected
Status = 0x00
Conn_handle = 0x81
Conn_interval = 0x0010
Conn_latency = 0x0000
Conn_sv_timeout = 0x0100
Remote device Address : 0xE8 0x4F 0x29 0xF4 0x81 0x34
```

10. Similarly, once connected GAP-Peripheral device prints the GAP-Central device address and connection parameters in serial console.

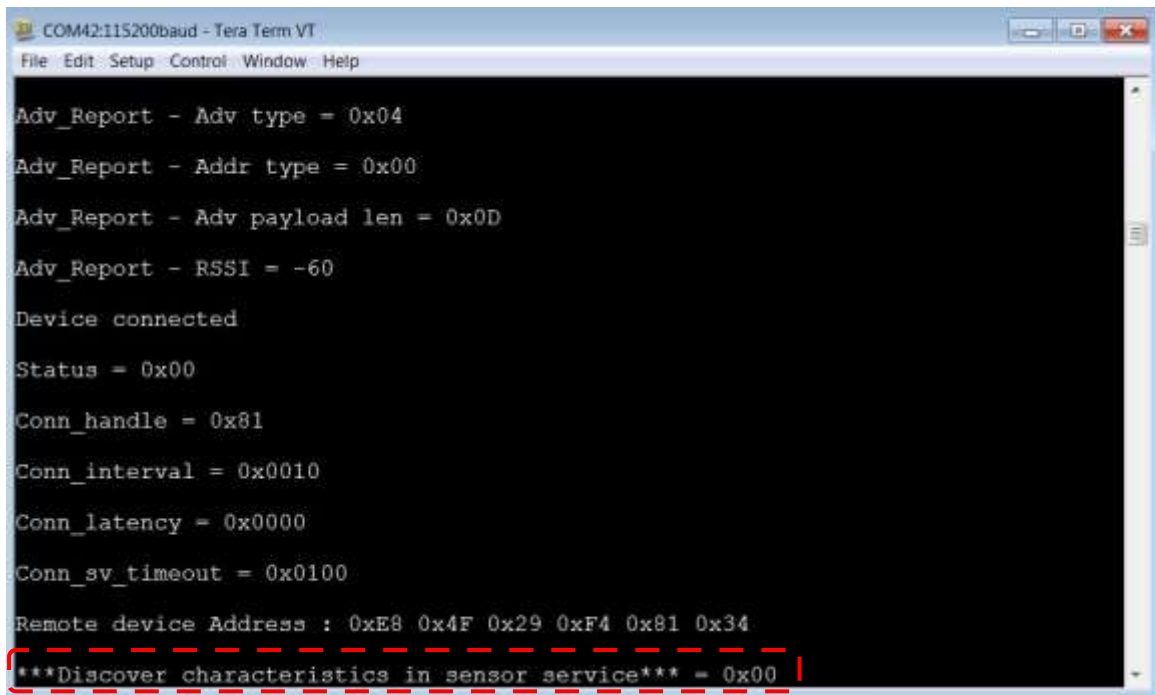


```
COM104:115200baud - Tera Term VT
File Edit Setup Control Window Help

Initializing BLE Application
BLE init succeed
Adv started
Device connected
Status = 0x00
Conn_handle = 0x80
Conn_interval = 0x0010
Conn_latency = 0x0000
Conn_sv_timeout = 0x0100
Remote device Address : 0xE4 0x4F 0x29 0xF4 0x81 0x34
```

11. GAP-Central discovers the characteristics in remote device based on the service UUID.

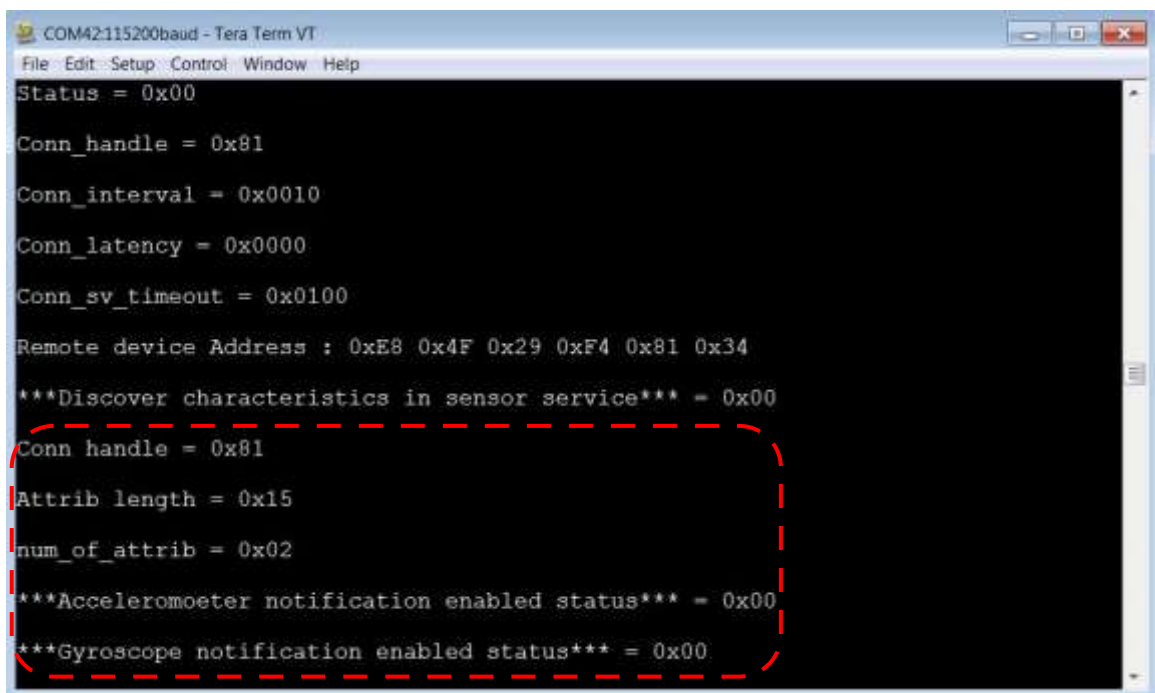
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```
COM42:115200baud - Tera Term VT
File Edit Setup Control Window Help

Adv_Report - Adv type = 0x04
Adv_Report - Addr type = 0x00
Adv_Report - Adv payload len = 0x0D
Adv_Report - RSSI = -60
Device connected
Status = 0x00
Conn_handle = 0x81
Conn_interval = 0x0010
Conn_latency = 0x0000
Conn_sv_timeout = 0x0100
Remote device Address : 0xE8 0x4F 0x29 0xF4 0x81 0x34
***Discover characteristics in sensor service*** = 0x00
```

12. It also discovers the Client Characteristic Configuration Descriptors (CCCD) of accelerometer and gyroscope sensor characteristics and enabled them to receive notifications.



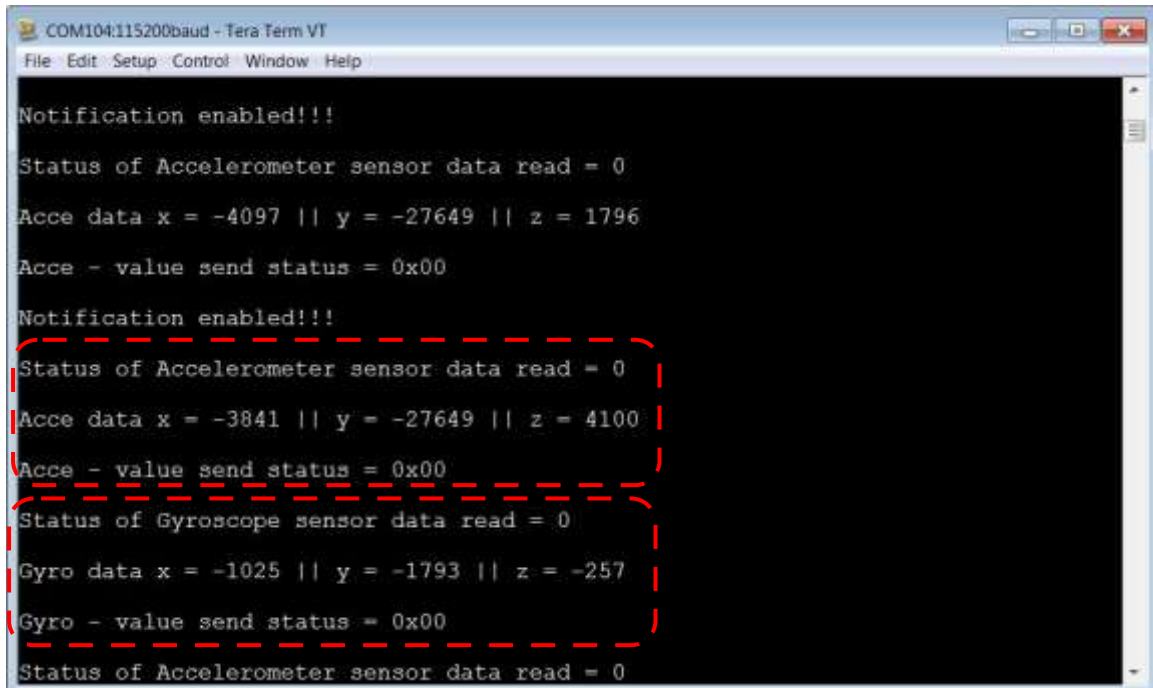
```
COM42:115200baud - Tera Term VT
File Edit Setup Control Window Help

Status = 0x00
Conn_handle = 0x81
Conn_interval = 0x0010
Conn_latency = 0x0000
Conn_sv_timeout = 0x0100
Remote device Address : 0xE8 0x4F 0x29 0xF4 0x81 0x34
***Discover characteristics in sensor service*** = 0x00
Conn handle = 0x81
Attrib length = 0x15
num_of_attrib = 0x02
***Accelerometer notification enabled status*** = 0x00
***Gyroscope notification enabled status*** = 0x00
```

13. Upon notification enabled by GAP-Central device, GAP-Peripheral device start reading accelerometer and gyroscope sensor data and notifies it to GAP-Central device.
14. GAP-Peripheral prints the following in serial console,
- a. Accelerometer and gyroscope sensor read operation status.

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- b. Accelerometer and gyroscope sensor data
- c. Status of notification send to GAP-Central.

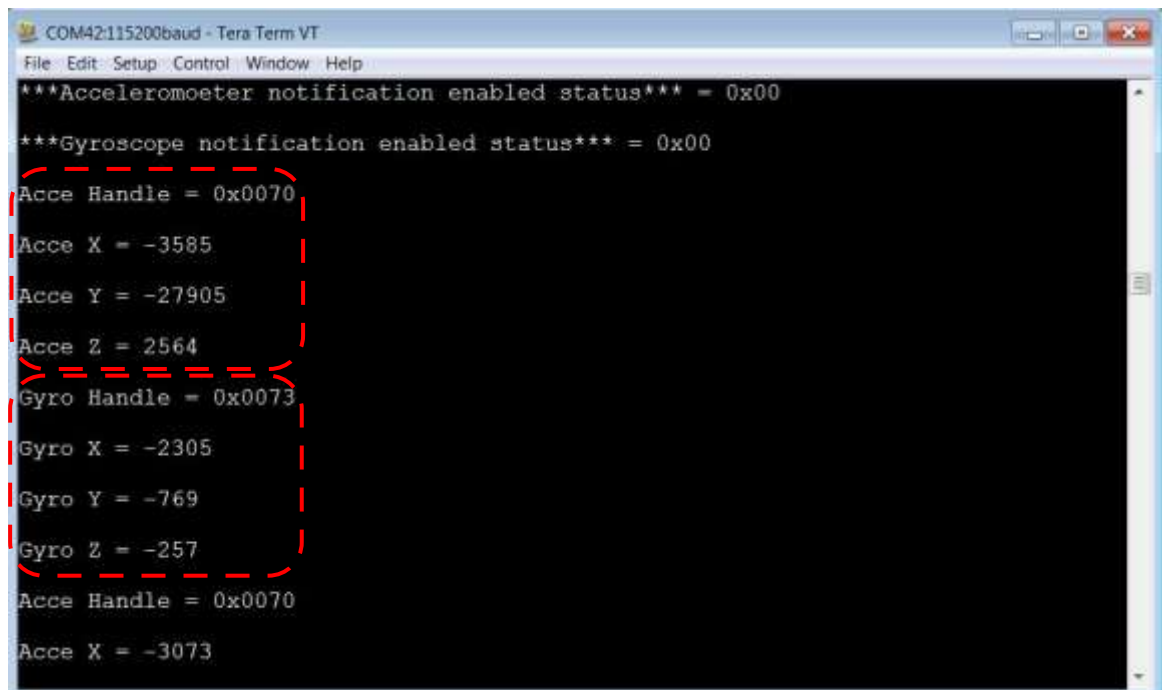


A screenshot of a Tera Term VT terminal window titled 'COM104:115200baud - Tera Term VT'. The terminal displays several lines of text. The first two lines are 'Notification enabled!!!' and 'Status of Accelerometer sensor data read = 0'. The next three lines are 'Acce data x = -4097 || y = -27649 || z = 1796', 'Acce - value send status = 0x00', and another 'Notification enabled!!!'. A red dashed box highlights the following three lines: 'Status of Accelerometer sensor data read = 0', 'Acce data x = -3841 || y = -27649 || z = 4100', and 'Acce - value send status = 0x00'. Below this box, the text continues with 'Status of Gyroscope sensor data read = 0', 'Gyro data x = -1025 || y = -1793 || z = -257', 'Gyro - value send status = 0x00', and finally 'Status of Accelerometer sensor data read = 0'.

```
COM104:115200baud - Tera Term VT
File Edit Setup Control Window Help

Notification enabled!!!
Status of Accelerometer sensor data read = 0
Acce data x = -4097 || y = -27649 || z = 1796
Acce - value send status = 0x00
Notification enabled!!!
Status of Accelerometer sensor data read = 0
Acce data x = -3841 || y = -27649 || z = 4100
Acce - value send status = 0x00
Status of Gyroscope sensor data read = 0
Gyro data x = -1025 || y = -1793 || z = -257
Gyro - value send status = 0x00
Status of Accelerometer sensor data read = 0
```

15. GAP-Central devices receive sensor data notifications and print them on serial console.



A screenshot of a Tera Term VT terminal window titled 'COM42:115200baud - Tera Term VT'. The terminal displays several lines of text. The first two lines are '***Accelerometer notification enabled status*** = 0x00' and '***Gyroscope notification enabled status*** = 0x00'. A red dashed box highlights the following six lines: 'Acce Handle = 0x0070', 'Acce X = -3585', 'Acce Y = -27905', 'Acce Z = 2564', 'Gyro Handle = 0x0073', and 'Gyro X = -2305'. Below this box, the text continues with 'Gyro Y = -769', 'Gyro Z = -257', 'Acce Handle = 0x0070', and 'Acce X = -3073'.

```
COM42:115200baud - Tera Term VT
File Edit Setup Control Window Help

***Accelerometer notification enabled status*** = 0x00
***Gyroscope notification enabled status*** = 0x00
Acce Handle = 0x0070
Acce X = -3585
Acce Y = -27905
Acce Z = 2564
Gyro Handle = 0x0073
Gyro X = -2305
Gyro Y = -769
Gyro Z = -257
Acce Handle = 0x0070
Acce X = -3073
```


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