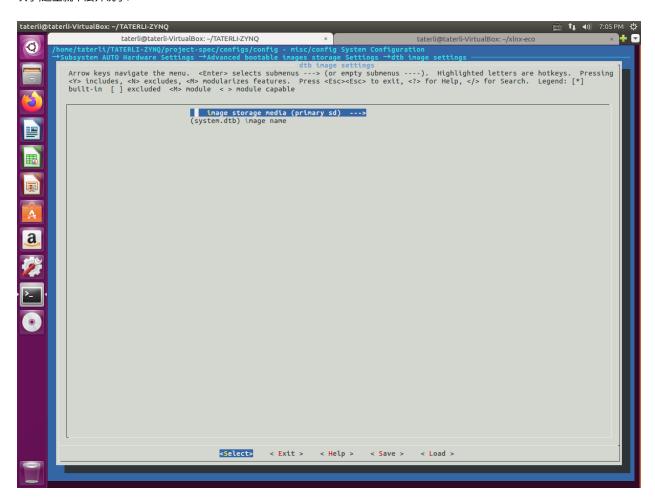
[L24]手动编译ZYNQ镜像

之前我们都用PYNQ或者PetaLinux进行试验,实际上除了这个方法还有一个手动方法,这个方法大家觉得怎样就见仁见智了,毕竟每个人习惯不同.这个毕竟是拆散开任何一步,这样改任何一步都代价最小.

首先需要创建工程,创建过程可以顺便选择源码路径,然后根据运行目标引导目标,这些应该难不倒大家了,毕竟前面的教程已经折腾很多次了,这里就不展开说了.



```
taterli@taterli-VirtualBox:-$ petalinux-create -t project --template zyng -n TATERLI-ZYNQ
INFO: Create project: TATERLI-ZYNQ
INFO: New project successfully created in /home/taterli/TATERLI-ZYNQ
taterli@taterli-VirtualBox:-$ cd TATERLI-ZYNQ/
taterli@taterli-VirtualBox:-\TATERLI-ZYNQ\S petalinux-config --get-hw-description -/zynq_project/hello_pynq/hello_pynq.sdk
INFO: Rename design_1_wrapper.hdf to system.hdf
[INFO] generating Kconfig for project
[INFO] menuconfig project
configuration written to /home/taterli/TATERLI-ZYNQ/project-spec/configs/config

**** End of the configuration.

**** Execute 'make' to start the build or try 'make help'.

[INFO] sourcing bitbake
[INFO] generating plnxtool conf

# 省略更多
```

然后编译uboot和BOOT.BIN:

```
taterli@taterli-VirtualBox:~/TATERLI-ZYNQ$ petalinux-build -c u-boot
[INFO] building u-boot
[INFO] sourcing bitbake
INFO: bitbake virtual/bootloader
Loaded 3442 entries from dependency cache.
Parsing of 2569 .bb files complete (2530 cached, 39 parsed). 3445 targets, 149 skipped, 0 masked, 0 errors.
NOTE: Resolving any missing task gueue dependencies
NOTE: Executing SetScene Tasks
NOTE: Executing RunQueue Tasks
NOTE: linux-xlnx: compiling from external source tree /home/taterli/xlnx-eco
WARNING: petalinux-user-image-1.0-r0 do_rootfs: [log_check] petalinux-user-image: found 1 warning message in the logfile:
[log_check] warning: %post(sysvinit-inittab-2.88dsf-r10.plnx_zynq7) scriptlet failed, exit status 1
NOTE: Tasks Summary: Attempted 2361 tasks of which 2124 didn't need to be rerun and all succeeded.
Summary: There was 1 WARNING message shown.
INFO: Copying Images from deploy to images
INFO: Creating images/linux directory
NOTE: Successfully copied built images to tftp dir: /tftpboot
[INFO] successfully built u-boot
taterli@taterli-VirtualBox:~/TATERLI-ZYNO$ petalinux-package --boot --fsbl --u-boot --force
INFO: File in BOOT BIN: "/home/taterli/TATERLI-ZYNO/images/linux/zyng_fsbl.elf"
INFO: File in BOOT BIN: "/home/taterli/TATERLI-ZYNQ/images/linux/u-boot.elf"
INFO: Generating Zynq binary package BOOT.BIN...
***** Xilinx Bootgen v2018.3
 **** Build date : Dec 6 2018-23:41:49
  ** Copyright 1986-2018 Xilinx, Inc. All Rights Reserved.
INFO: Binary is ready.
```

现在的BOOT.bin只有fsbl和u-boot,除非我们要针对u-boot开发,否则这个文件是不用动的,现在已经根据硬件生成了合适的device-tree.

```
taterli@taterli-VirtualBox: {\tt ~/TATERLI-ZYNQ/components/plnx\_workspace/device-tree/device-tree}\ ls\ -alh\ -alh
drwxr-xr-x 2 taterli taterli 4.0K Mar 16 19:08 .
drwxr-xr-x 3 taterli taterli 4.0K Mar 16 19:08 ..
-rw-r--r-- 1 taterli taterli 2.0M Mar 16 19:08 design 1 wrapper.bit
-rw-r--r-- 1 taterli taterli 3.3K Mar 16 19:08 device-tree.mss
-rw-r--r-- 1 taterli taterli 602K Mar 16 19:08 hardware_description.hdf
-rw-r--r-- 1 taterli taterli 756 Mar 16 19:08 pcw.dtsi # 重点
-rw-r--r-- 1 taterli taterli 1.5K Mar 16 19:08 pl.dtsi # 重点
-rw-r--r-- 1 taterli taterli 521K Mar 16 19:08 ps7_init.c
-rw-r--r-- 1 taterli taterli 521K Mar 16 19:08 ps7 init qpl.c
-rw-r--r-- 1 taterli taterli 4.2K Mar 16 19:08 ps7_init_gpl.h
-rw-r--r-- 1 taterli taterli 4.8K Mar 16 19:08 ps7_init.h
-rw-r--r-- 1 taterli taterli 2.7M Mar 16 19:08 ps7_init.html
-rw-r--r-- 1 taterli taterli 35K Mar 16 19:08 ps7_init.tcl
-rw-r--r-- 1 taterli taterli 297 Mar 16 19:08 skeleton.dtsi
-rw-r--r-- 1 taterli taterli 265 Mar 16 19:08 system-conf.dtsi # 重点
-rw-r--r-- 1 taterli taterli 428 Mar 16 19:08 system-top.dts # 重点
-rw-r--r-- 1 taterli taterli 11K Mar 16 19:08 zynq-7000.dtsi # 重点
tater li@tater li-Virtual Box: {\tt ~/TATERLI-ZYNQ/components/plnx\_work space/device-tree} \\
```

如果下次要生成新的设备树这么做就可以了.

注:网上也有说可以用hsi等工具,但是步骤比较多,我实际试过每次构建也就一分钟不到,不至于说等待很久,编译u-boot只是为了随便构建一个依赖dts的东西.

```
petalinux-config --get-hw-description ~/zynq_project/hello_pynq/hello_pynq.sdk
petalinux-build -c u-boot
```

做一份内核的副本,把上面重点的dts/dtsi复制过去,并新建system-user.dtsi并放入适当的内容,比如之前我们用的内容.

```
cp ~/TATERLI-ZYNQ/components/plnx_workspace/device-tree/device-tree/pcw.dtsi ~/xlnx-eco-bak/arch/arm/boot/dts/
cp ~/TATERLI-ZYNQ/components/plnx_workspace/device-tree/device-tree/pl.dtsi ~/xlnx-eco-bak/arch/arm/boot/dts/
cp ~/TATERLI-ZYNQ/components/plnx_workspace/device-tree/device-tree/system-conf.dtsi ~/xlnx-eco-bak/arch/arm/boot/dts/
cp ~/TATERLI-ZYNQ/components/plnx_workspace/device-tree/device-tree/system-top.dts ~/xlnx-eco-bak/arch/arm/boot/dts/
cp ~/TATERLI-ZYNQ/components/plnx_workspace/device-tree/device-tree/zynq-7000.dtsi ~/xlnx-eco-bak/arch/arm/boot/dts/
vim ~/xlnx-eco-bak/arch/arm/boot/dts/system-user.dtsi
vim ~/xlnx-eco-bak/arch/arm/boot/dts/Makefile
```

关于dts的Makefile中要添加system-top.dtb.

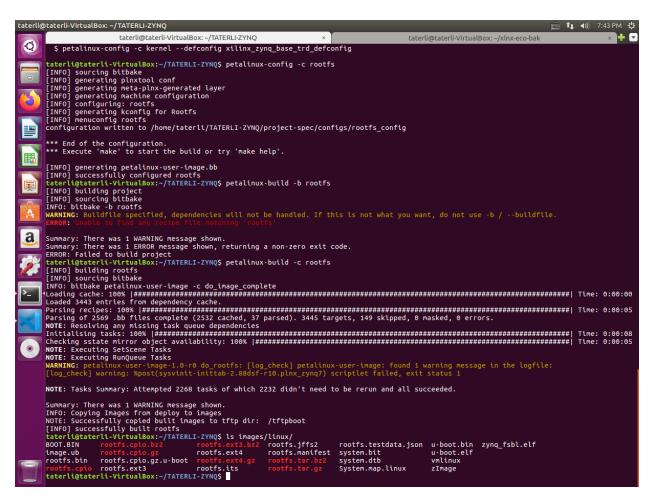
回到内核主目录开始编译.

```
make ARCH=arm CROSS_COMPILE=arm-linux-gnueabihf- xilinx_zynq_defconfig
make ARCH=arm CROSS_COMPILE=arm-linux-gnueabihf- menuconfig
make ARCH=arm CROSS_COMPILE=arm-linux-gnueabihf- zImage -j 64
make ARCH=arm CROSS_COMPILE=arm-linux-gnueabihf- system-top.dtb
```

单独构建rootfs.

```
petalinux-config -c rootfs # 配置,为了方便一般打开Image Features的debug-tweaks,会做很多方便调试的预设.
petalinux-build -c rootfs # 单纯构建不配置可以省略上一步.
```

然后就看到构建出来的rootfs的多种格式,当然选择合适的释放到rootfs分区.



当然也可以不用这里的roofs,现在探讨一下image.ub是怎么来的,我这里是从PYNQ镜像中看.

```
taterli@taterli-VirtualBox:/media/taterli/6D21-54E9$ mkimage -l image.ub
FIT description: U-Boot fitImage for PYNQ arm kernel
                Wed Mar 16 00:20:08 2022
 Image 0 (kernel@0)
 Description: Linux Kernel
 Created:
               Wed Mar 16 00:20:08 2022
               Kernel Image
  Compression: uncompressed
  Data Size: 4482000 Bytes = 4376.95 kB = 4.27 MB
  Architecture: ARM
  0S:
              Linux
  Load Address: 0x00080000
  Entry Point: 0x00080000
 Hash algo: sha1
Hash value: 4ef51adc7d169b16475dd05f94fb86c054ce75ec
 Image 1 (fdt@0)
 Description: Flattened Device Tree blob
 Created:
               Wed Mar 16 00:20:08 2022
               Flat Device Tree
  Type:
 Compression: uncompressed
 Data Size: 16597 Bytes = 16.21 kB = 0.02 MB
 Architecture: ARM
 Hash algo: sha1
 Hash value: 64c58fd816259cae2f2dff4282c49ebcb8413c44
 Default Configuration: 'conf@1'
 Configuration 0 (conf@1)
 Description: Boot Linux kernel with FDT blob
  Kernel:
               kernel@0
  FDT:
               fdt@0
```

可见他只包含了内核和配置,因此完全可以不要他,直接我们拆开来.

```
taterli@taterli-VirtualBox:/media/taterli/6D21-54E9$ cp ~/xlnx-eco-bak/arch/arm/boot/zImage .
taterli@taterli-VirtualBox:/media/taterli/6D21-54E9$ cp ~/xlnx-eco-bak/arch/arm/boot/dts/system-top.dtb system.dtb
taterli@taterli-VirtualBox:/media/taterli/6D21-54E9$ cp ~/TATERLI-ZYNQ/images/linux/system.bit .
taterli@taterli-VirtualBox:/media/taterli/6D21-54E9$ cp ~/TATERLI-ZYNQ/images/linux/BOOT.BIN .
taterli@taterli-VirtualBox:/media/taterli/6D21-54E9$ ls -alh
总用量 6.5M
drwxr-xr 3 taterli taterli 16K Mar 16 19:48 .
drwxr-xr-+4 root root 4.0K Mar 16 19:45 .
-rw-r--r- 1 taterli taterli 601K Mar 16 19:49 BOOT.BIN
-rw-r--r- 1 taterli taterli 2.0M Mar 16 19:48 system.bit
-rw-r--r- 1 taterli taterli 12K Mar 16 19:48 system.dtb
-rw-r--r- 1 taterli taterli 3.8M Mar 16 19:48 zTmage
taterli@taterli-VirtualBox:/media/taterli/6D21-54E9$
```

现在插入然后应该启动不了的.因为启动方法和传统已经不一样了.

```
COM4 - PuTTY
 -Boot 2018.01 (Mar 17 2022 - 02:08:44 +0000) Xilinx Zyng ZC702
Board: Xilinx Zynq
DRAM: ECC disabled 512 MiB
      mmc@e0100000: 0 (SD)
** No device specified **
Using default environment
## Error: flags type check failure for "serverip" <= "AUTO" (type: i)
himport_r: can't insert "serverip=AUTO" into hash table
      _
serial@e0001000
     serial@e0001000
Err:
      serial@e0001000
Board: Xilinx Zynq
Silicon: v3.1
Net: ZYNQ GEM: e000b000, phyaddr ffffffff, interface rgmii-id
eth0: ethernet@e000b000
U-BOOT for TATERLI-ZYNQ
ethernet@e000b000 Waiting for PHY auto negotiation to complete...... TIMEOUT
Hit any key to stop autoboot: 0
Zynq>
```

设置一下启动环境(命令很简单,大家不懂就网上学习一些U-Boot常用命令):

```
setenv bitstream_load_address 0x1000000
setenv bitstream_size 0x3000000
setenv bitstream_size 0x3000000
setenv kernel_img zImage
setenv dtbnetstart 0x20000000
setenv netstart 0x20800000
setenv netstart 0x20800000
setenv default_bootcmd 'if mmcinfo; then run uenvboot; echo Copying Linux from SD to RAM... && load mmc
0 ${bitstream_load_address} ${bitstream_image} && fpga loadb 0 ${bitstream_load_address} ${bitstream_size}
&& run cp_kernel2ram && run cp_dtb2ram && bootz ${netstart} - ${dtbnetstart}; fi;'
saveenv
```

测试效果和正常启动一样.