Capture-mark-recapture methods for abundance estimation





ABUNDANCE ESTIMATION

Same old equation:

$$\hat{N} = \frac{n}{\hat{p}}$$

- N is abundance (population size)
- n is the number of individuals detected
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Most methods differ in how they estimate p

Overview

Estimating p

• Set traps in a study area and mark each captured individual

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 - Most of the captures on subsequent occasions will be recaptures
- And vice versa

ENCOUNTER HISTORIES

n=5 individuals captured over 3 sampling occasions

	Occasion 1	Occasion 2	Occasion 3
Animal 1	0	0	1
Animal 2	1	1	0
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Animal 5	0	1	0

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These data tell us about p and hence N. Estimation is usually acheived using maximum likelihood methods.

LINCOLN-PETERSON METHOD

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Later it was used by Lincoln (shown above) and Peterson to estimate fish and wildlife populations

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LINCOLN-PETERSON STUDY DESIGN

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- ullet On the first, n_1 animals are captured and marked
- \bullet On the second, n_2 animals are captured and m_2 of them are recaptures





LINCOLN-PETERSON ABUNDANCE ESTIMATOR

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And so...

$$\hat{N} = \frac{n_1 n_2}{m_2}$$

LINCOLN-PETERSON ASSUMPTIONS

- (1) Population closure
 - No births
 - No deaths
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- (3) No tag loss or mis-identification

K-Sample $\overline{\mathrm{CMR}}$

Using more than 2 sampling occasions has many advantages, including the ability to account for:

Temporal variation

K-Sample $\overline{\mathrm{CMR}}$

- Temporal variation
- Behavioral effects

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 - Trap happiness
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- Individual heterogeneity
- Combinations of the above

COMMON MODELS

Model	Description
$\overline{M_0}$	The most basic model in which p and c are constant
M_t	p differs among sampling occasions and $p_t = c_t$.
M_b	Behavioral response model in which p and c differ. Can
	describe trap happiness or trap shiness.
M_{tb}	A combination of models M_t and M_b .

where

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p= capture probability p_t= capture probability on occasion t c= recapture probability
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REMOVAL SAMPLING

Suppose you remove individuals on each survey

Removal sampling

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Eventually you should deplete the population

Removal sampling

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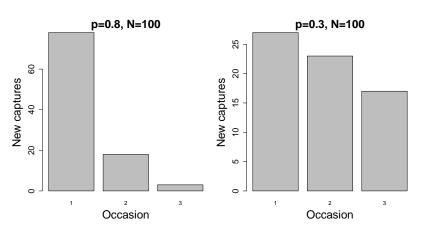
Eventually you should deplete the population

The number of captures you would expect on each occasion:

Occasion	Expected count
1	pN
2	p(1-p)N
3	$p(1-p)^{2}N$
4	$p(1-p)^3N$
<u>:</u>	<u>:</u>
K	$p(1-p)^{K-1}N$

EXAMPLE

The rate at which the population is depleted tells us about p.



Key points

- Capture-recapture methods use information about recapture rates to estimate capture probability and abundance
- More advanced methods can be used to estimate density and vital rates
- Modern field methods use camera traps or DNA sampling techniques to collect non-invasive capture-recapture data

ESTIMATING DENSITY

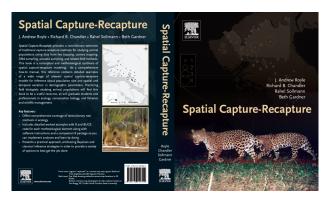
Lingering questions

- How do we convert abundance to density?
- What is the area surveyed?

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Read Chapter 11

Introduction Lincoln-Peterson K-sampler CMR Removal sampling $15 \ / \ 15$