# Models of interspecific interactions Predator-prey dynamics and competition



 Lotka and Volterra developed models for both predator-prey dynamics and competitive interactions.

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- Lotka and Volterra developed models for both predator-prey dynamics and competitive interactions.
- As usual, these models were developed as continuous-time models.
- We will focus on discrete-time versions (t = 1, 2, ...).
- We will ignore potential extensions with stochasticity, age structure, spatial structure, etc. . .

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# QUESTION

How should predator-prey dynamics operate?

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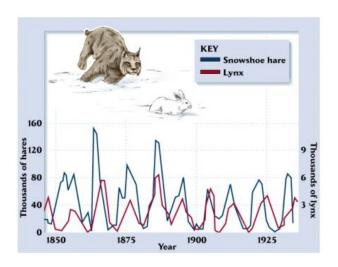
# How should predator-prey dynamics operate?





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#### LYNX-HARE CYCLES



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#### LOTKA-VOLTERRA PREDATOR-PREY MODEL

# Model for prey

$$N_{t+1}^{prey} = N_t^{prey} + N_t^{prey} (r^{prey} - d^{prey} N_t^{pred})$$

#### Lotka-Volterra Predator-Prey Model

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# Model for predator

$$N_{t+1}^{pred} = N_t^{pred} + N_t^{pred} (b^{pred} N_t^{prey} - d^{pred})$$

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#### Lotka-Volterra predator-prey model

#### Model for prey

$$N_{t+1}^{prey} = N_t^{prey} + N_t^{prey} (r^{prey} - d^{prey} N_t^{pred})$$

# Model for predator

$$N_{t+1}^{pred} = N_t^{pred} + N_t^{pred} (b^{pred} N_t^{prey} - d^{pred})$$

- Model is based on geometric growth
- $\bullet$   $r^{prey}$  is the growth rate of the prey in the absence of predators
- ullet  $d^{prey}$  is the predation rate
- ullet  $b^{pred}$  is the birth rate of the predators
- $d^{pred}$  is the mortality rate of the predator

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# Equilibrium

Equilibrium for prey occurs when...

$$N^{pred} = \frac{r^{prey}}{d^{prey}}$$

# EQUILIBRIUM

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Equilibrium for predators occurs when...

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# EQUILIBRIUM

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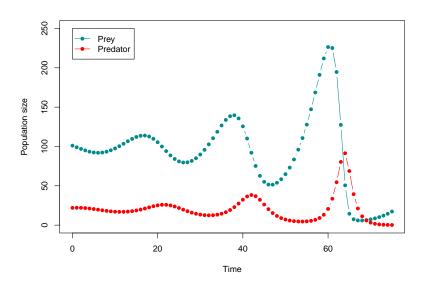
Equilibrium for predators occurs when...

$$N^{prey} = \frac{d^{pred}}{b^{pred}}$$

However, it is rare that both equilibrium conditions will be met at the same time, and so the populations will cycle.

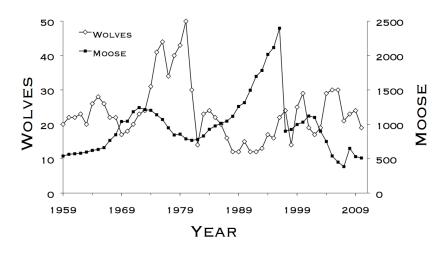
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# Model Predicts Population Cycles



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#### ISLE ROYALE WOLVES AND MOOSE



http://www.youtube.com/watch?v=PdwnfPurXcs https://isleroyalewolf.org/

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# Competition



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#### LOTKA-VOLTERRA COMPETITION MODEL

#### Model for species A

$$N_{t+1}^{A} = N_{t}^{A} + r^{A} N_{t}^{A} (K^{A} - N_{t}^{A} - \alpha^{B} N_{t}^{B}) / K^{A}$$

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#### LOTKA-VOLTERRA COMPETITION MODEL

# Model for species A

$$N_{t+1}^{A} = N_{t}^{A} + r^{A} N_{t}^{A} (K^{A} - N_{t}^{A} - \alpha^{B} N_{t}^{B}) / K^{A}$$

# Model for species B

$$N_{t+1}^{B} = N_{t}^{B} + r^{B} N_{t}^{B} (K^{B} - N_{t}^{B} - \alpha^{A} N_{t}^{A}) / K^{B}$$

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#### LOTKA-VOLTERRA COMPETITION MODEL

# Model for species A

$$N_{t+1}^{A} = N_{t}^{A} + r^{A} N_{t}^{A} (K^{A} - N_{t}^{A} - \alpha^{B} N_{t}^{B}) / K^{A}$$

# Model for species B

$$N_{t+1}^B = N_t^B + r^B N_t^B (K^B - N_t^B - \alpha^A N_t^A) / K^B$$

- Model based on logistic growth
- The  $\alpha$  parameters are competition coefficients determining how strongly each species affects the other

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# Equilibrium

# Equilibrium for species A

$$N^A = \frac{K^A - \alpha^B K^B}{1 - \alpha^A \alpha^B}$$

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# EQUILIBRIUM

# Equilibrium for species A

$$N^A = \frac{K^A - \alpha^B K^B}{1 - \alpha^A \alpha^B}$$

# Equilibrium for species B

$$N^B = \frac{K^B - \alpha^A K^A}{1 - \alpha^A \alpha^B}$$

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#### THREE POSSIBLE OUTCOMES

#### Outcomes depend on the sign of the numerators

- (1) Stable coexistence
- (2) Competitive exclusion
- (3) Unstable equilibrium

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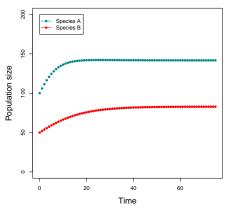
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**Competitive exclusion principle**: Two species with the same niche cannot coexist on the same limiting resource

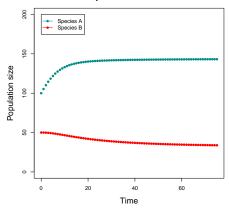
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# OUTCOMES

#### Stable coexistence



#### Competitive exclusion



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# Don't forget about intraspecific competition



https://youtu.be/KQLPL1qRhn8

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#### SUMMARY

Predator-prey model is extension of geometric growth

• Predators and prey limit each other's growth potential

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Predator-prey model is extension of geometric growth

Predators and prey limit each other's growth potential

Competition model is extension of logistic growth

 Competitors influence each other's density-dependent regulation process

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#### SUMMARY

Predator-prey model is extension of geometric growth

Predators and prey limit each other's growth potential

Competition model is extension of logistic growth

 Competitors influence each other's density-dependent regulation process

These models could be extended to include:

- More species
- Stochasticity
- Age structure
- Harvest
- Spatial structure
- Additional forms of density dependence

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