

Thm: Let P be a G -operad. Then the following equip \underline{P} w/ a ps-comm structure.

$$1) \forall (m, n) \in \mathbb{N}_+^2 \quad (no \ 0 \text{ in } M_+), t_{m,n} \in G(m, n)$$

$$s.t. \quad \pi(t_{m,n}) = t_{m,n}$$

$$2) \forall p \in P(n), q \in P(m), a \text{ natural } i \geq 0$$

$$\mu(p; q, m, i) \cdot t_{m,n} \cong \mu(q; p, i, n) \cdot P.$$

these must satisfy Isomorphisms (plus other ones) \rightarrow

$$\begin{aligned} & \bullet t_{i,n} = e_n = t_{n,i} + \mu(p; id, n, i) \cdot t_{n,n} \cong \mu(id; p, i, n) \cdot t_{n,n} \\ & \bullet \mu(e_i; t_{m_1, n_1}, \dots, t_{m_k, n_k}) \cdot \mu(t_{m_1, n_1}, \dots, t_{m_k, n_k}, e_n) \end{aligned}$$

are identities

$$= t_{n, M} \quad \text{Plus axiom on } n \neq 2 \text{ case}$$

this holds for any $L, M, n, m_1, \dots, m_k, n, M = \sum m_i$

+ two μ -axioms (another case).

(Gr.) the ps-comm is symmetric if $t_{m,n} = t_{n,m}$.

Cor: If P is contractible (each $P(n) \cong *$) and we have $t_{m,n}$ as above, then \underline{P} acquires a ps-comm. which is sym if $t_{m,n} = t_{n,m}$.

Cor: Any contractible symmetric operad is ps-comm. (+sym)

Cor: Let \underline{P} be a non-symmetric operad. Then

\underline{P} is never ps-comm.

PF: there is no iso $(x, y) \cong (y, x)$. \square

Section 24

1) Def on \underline{P} 's

2) Def of ps-comm (copy HP)

3) Consequences: ps-comm \Rightarrow pre-brad ps-comm 2-ent

+ sym \Rightarrow +sym

(explain from HP)

4) Main Thm + Cor's

5) Calculations for braided / ~~at least~~ ~~braided~~ cases

Need Lemma: $A \otimes B \cong A \otimes B$ where

$$(a, b) \sim (a, b)$$

Symmetry: If $t_{m,n} = t_{n,m}$?

$$\mu(p; q) \cdot t_{m,n} = \mu(p; q) \cdot t_{n,m}$$

iso-1 \downarrow

$$\mu(q; p) \cdot t_{m,n} \rightarrow \mu(p; q)$$

|| , then symmetric

μ axiom $\neq 1$

$$\mu(p; \underbrace{\mu(q_1; \underline{e}), \dots, \mu(q_n; \underline{e})}_{//}) \cdot \mu(e; t_{n,m}, \dots, t_{n,e}) \mu(t_{n,e}; \underbrace{e_{m+1}, \dots, e_n}_{n \text{ times}})$$

$$\mu(p; \mu(q_1; \underline{e}) \cdot t_{n,m}, \dots, \mu(q_n; \underline{e}) \cdot t_{n,e}) \mu(t_{n,e}; \underline{e})$$

$$\mu(1; iso; 1) \downarrow$$

$$\mu(p; \mu(r; q_1), \dots, \mu(r; q_n)) \cdot \mu(t_{n,e}; \underline{e})$$

//

$$\mu(\mu(p; \underline{e}); q_1, \dots, q_n) \cdot \mu(t_{n,e}; \underline{e})$$

//

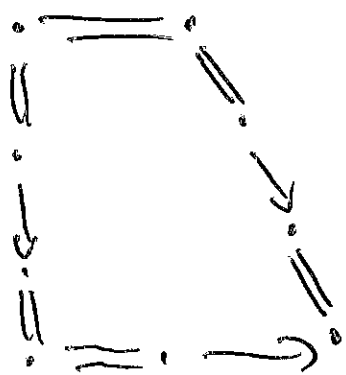
$$\mu(\mu(p; \underline{e}) \cdot t_{n,e}; \underline{q_1, \dots, q_n})$$

$$\mu(iso; 1) \downarrow$$

$$\mu(\mu(r; \underline{e}); \underline{q_1, \dots, q_n})$$

//

$$\mu(r; \underline{\mu(p; q_1, \dots, q_n)})$$



$$\mu(p; \mu(q_1; \underline{e}), \dots, \mu(q_n; \underline{e})) \cdot t_{n,m}$$

//

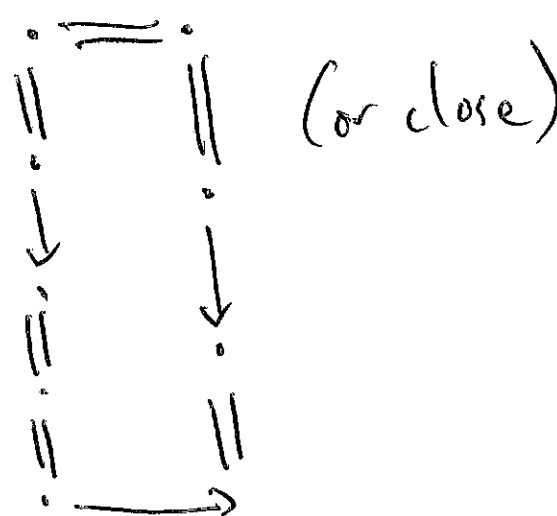
$$\mu(\mu(p; q_1, \dots, q_n); \underline{e}) \cdot t_{n,m}$$

$\downarrow iso$

~~$\mu(r; \underline{e})$~~

Draw diagrams as

OR



(or close)

μ axiom #2 :

★ Additional equation -

$$\mu(t_{n,e}; \underline{e}_1, \dots, \underline{e}_m) \mu(e_n; t_{n,e}, \dots, t_{n,e}) = t_{N,e}$$

for any l, m, n, \dots, n where $N = \sum n_i$

$$\mu(p; \underbrace{\mu(q; r_1, \dots, r_m)}_{\parallel}) \cdot \underbrace{\mu(t_{n,e}; \underline{e}_1, \dots, \underline{e}_m) \mu(e_n; t_{n,e}, \dots, t_{n,e})}_{\parallel}$$

$$\mu(\mu(p; q); \underline{r}_1, \dots, \underline{r}_m) \cdot \mu \mu$$

$$\mu(p; \mu(q; r_1, \dots, r_m)) \cdot t_{N,e}$$

$$\mu(\mu(p; q) \cdot t_{n,e}; \underline{r}_1, \dots, \underline{r}_m) \cdot \mu(e_n; t_{n,e}, \dots, t_{n,e})$$

$$\mu(1; 1) \cdot 1 \downarrow$$

$$\mu(q; \mu(p; \underline{r}_1, \dots, \underline{r}_m)) \cdot \mu$$

$$\mu(q; \mu(p; \underline{r}_1), \dots, \mu(p; \underline{r}_m)) \cdot \mu$$

$$\mu(q; \mu(p; \underline{r}_1) \cdot t_{n_1,e}, \dots, \mu(p; \underline{r}_m) \cdot t_{n_m,e})$$

$$\mu(1; 1) \downarrow$$

$$\mu(q; \mu(r_1; p), \dots, \mu(r_m; p))$$

$$\mu(\mu(q; r_1, \dots, r_m); p)$$

iso

$$\underline{P}(x) = \underline{1} \otimes \underline{P(x)} \otimes x^n$$

$$X \times \underline{P}(Y) = X \times \underline{1} \otimes \underline{P(x)} \otimes Y^n \quad (x, [p_1, \dots, p_n])$$

$$\underline{P}(X \times Y) = \underline{1} \otimes \underline{P(x)} \otimes (X \times Y)^n \quad [p_1(x, y), \dots, (x, y_n)]$$

$$\underline{P}(X \times Y) \xrightarrow{\underline{P}(x)} \underline{P}(X \times Y)$$

$$([p_1, \dots, p_n], y) \xrightarrow{(\underline{P}(x))} [p_1(x, y), \dots, (x, y_n)]$$

$$\underline{P}(X \times \underline{P}(Y)) \xrightarrow{\underline{P}(x)} \underline{P}(X \times \underline{P}(Y)) \xrightarrow{\underline{P}(x)} \underline{P}(X \times Y)$$

$$\downarrow \quad \quad \quad \downarrow$$

$$\underline{P}(\underline{P}(X \times Y)) \xrightarrow{\underline{P}(x)} \underline{P}^2(X \times Y) \xrightarrow{\mu} \underline{P}(X \times Y)$$

$$\xrightarrow{\mu} ([p_1, \dots, p_n], [q_1, \dots, q_n]) \xrightarrow{(\underline{P}(x))} [p_1(x, [q_1, \dots, q_n]), \dots, (x, [q_n, \dots, q_n])] \xrightarrow{\underline{P}(x)} [p_1([q_1(x, y_1), \dots, [q_n(x, y_n)]]], \dots, [p_n([q_n(x, y_n)]])]$$

$$\downarrow \quad \quad \quad \downarrow$$

$$[q_1([p_1(x, y_1), \dots, [p_n(x, y_n)]]], \dots, [q_n([p_n(x, y_n)]])] \xrightarrow{\mu} [\mu(q_1, q_2), \dots, (x, y)]$$

Isomorphisms: Swapped notation

$$[\mu(p_1, q_2), \dots, (x, y)] \cong [\mu(q_1, p_2), \dots, (x, y)]$$

#1

$$\underline{C} \text{ is } A \text{ - right } G\text{-act} \quad B \text{ - left } G\text{-act}$$

$$A \times_B B \xrightarrow{\text{any}} [a, b] \longrightarrow [a', b'] \text{ is } f \text{ the form } [a, b] = [a, s, b] \xrightarrow{[r, s]} [a', b']$$

$$\text{where } r: a \rightarrow a', \quad s: b \rightarrow b'$$

PF: (see equalizer defn (did on board)). \square

Claim #2:

Let X_0, Y_0 be the sets of x, y . Then $\underline{P}(X_0) \times \underline{P}(Y_0) \hookrightarrow \underline{P}(X \times Y) \xrightarrow{\mu} \underline{P}(X \times Y)$

"

$$\underline{P}(X_0) \times \underline{P}(Y_0) \xrightarrow{\mu} \underline{P}(X \times Y) \hookrightarrow \underline{P}(X \times Y)$$

PF. γ is a modification. \square

$G=1$: Does it follow that
 $\mu(q; p, \dots, p) \circ h \circ h^{-1} \approx \mu(q; p, \dots, p)$

$\downarrow F=1$

$\downarrow F$

$\mu(q'; p', \dots, p') \circ h \circ h^{-1} \approx \mu(q'; p', \dots, p')$?

Probably not: * what is bottom iso?

- h, h' depended on a, b, p, q

- now have a, b, p', q' along the bottom

1st strength axiom:

- $h((a, b), c, p, q) = h(b, c, p, q)$

- * iso for $(a, b), c, p, q$ = iso for b, c, p, q

3rd: $h(a, (b, c), p, q) = h(a, b, p, q)$

- * same for iso

2nd: $h((a, b), c, p, q) = h(a, (b, c), p, q)$

- * same for iso

1st unit axiom:

- $h \in \text{ker}(\pi)$

- $\mu(q; 1, \dots, 1) \circ h = \mu(1; q)$

$\Leftrightarrow q \circ h = q$

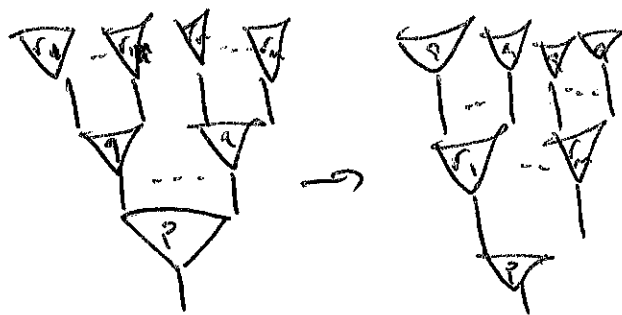
If $G(h)$ acts freely, then $h = \text{id} \in G(h)$

2nd unit axiom is redundant

$$p \in P(\mathcal{A}), \quad r_i \in P(\mathcal{A}_i), \quad r \in P(\mathcal{A}) \quad M = \{m_i\}$$

$$\mu(p; z) \cdot t_{z,n} \approx \mu(q; p)$$

$$\mu(q; z) \cdot t_{n,r} \approx \mu(r; z)$$



$$([p; [q_1; x_1], \dots, [q_n; x_n]], [r; y])$$

$$\downarrow$$

$$[r; ([p; [q_1; x_1], y_1], \dots, [p; [q_n; x_n], y_n])]$$

$$\downarrow$$

$$[r; [p; ([q_1; x_1], y_1), \dots, ([q_n; x_n], y_n)], [p; [q_1; (x_1, r, y_1), \dots, (x_n, r, y_n)], \dots, [q_n; (x_n, r, y_n)]]]$$

$$\downarrow$$

$$[\mu(r; p), [q_1, \dots, q_n]]$$

$$\downarrow$$

$$[p; [q_1; [r; (x_1, y)]]]$$

$$\downarrow$$

$$[p; [\mu(q_1; z), \dots, \mu(q_n; z)]]$$

$$\downarrow$$

$$\mu(\mu(r; p), q_1, \dots, q_n)$$

$$\downarrow$$

$$\mu(p; \mu(q_1; z), \dots, \mu(q_n; z))$$

$$\mu^p(p; \mu(q_1; z) \cdot t_{n,n}, \dots, \mu(q_n; z) \cdot t_{n,n}) = \mu^p(p; \mu(q_1; z), \dots, \mu(q_n; z)) \cdot \mu^G(e, t_{n,n}, t_{n,n})$$

$$\downarrow$$

$$\mu^p(p; \mu(r; z), \dots, \mu(r; z))$$

$$\mu^p(\mu^p(p; z), q_1, \dots, q_n)$$

$$\mu(\mu(p; z) \cdot t_{z,n}, q_1, \dots, q_n) =$$

$$\mu(\mu(p; z), \underbrace{q_1^{-1} \omega_1, \dots, q_n^{-1} \omega_n}_{= q_1, \dots, q_n}) \cdot \mu(t_{z,n}; z)$$

Thm: Let P be a Hopf-algebra. Then the following provide \underline{P} w/ a pre-algebra structure.

1) For each (m, n) an elt $t_{m,n} \in G(m, n)$ s.t.

$$\pi(t_{m,n}) = \tau_{m,n}.$$

2) For each $p \in P(n), q \in P(n)$, a natural iso

$$\mu^p(p; q, \dots, 1) \cdot t_{m,n} \cong \mu^p(q; p, \dots, p).$$

These satisfy:

$$\bullet t_{1,n} = e_n = t_{n,1}$$

• axiom about operadic comp of t 's

• axiom about associativity for iso's in (2)

$$\text{traction guess: } \mu(e_3; t_{m_1, n_1}, \dots, t_{m_k, n_k}) \mu(t_{m_1}, \underbrace{e_{n_1}, \dots, e_{n_1}}_n, \dots, \underbrace{e_{n_k}, \dots, e_{n_k}}_n)$$

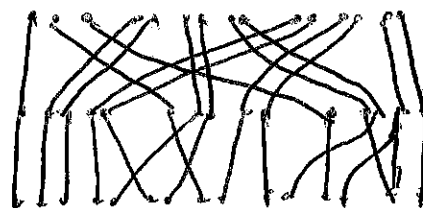
$$= t_{m, n} \quad m = \sum m_i$$

Check w/ calculation in Σ :

$$\begin{aligned} l=3 \\ m_1=1 \\ m_2=2 \\ m_3=2 \\ n=3 \end{aligned}$$

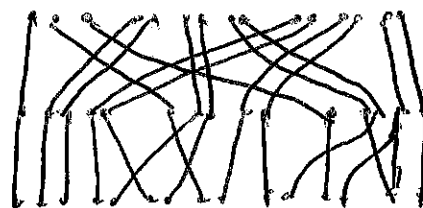
$$\tau_{3,3} =$$

$$\mu(\tau_{3,3}; e_1, e_2, e_2) =$$

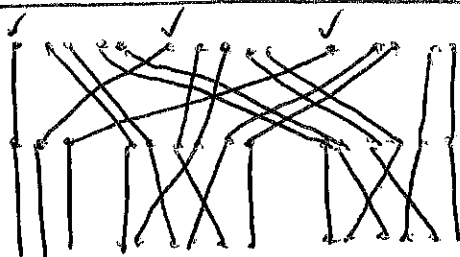


Not equal

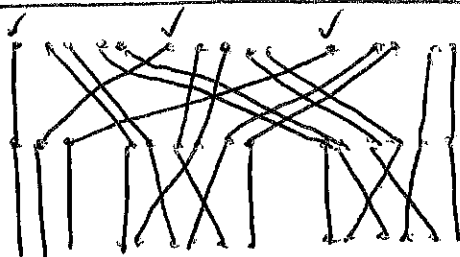
$$\mu(e_3; \tau_{1,3}, \tau_{2,3}, \tau_{2,3}) =$$



$$\mu(\tau_{3,1}; e_2, e_2, e_2, e_2, e_2) =$$



$$\mu(e_3; \tau_{1,3}, \tau_{2,3}, \tau_{2,3}) =$$



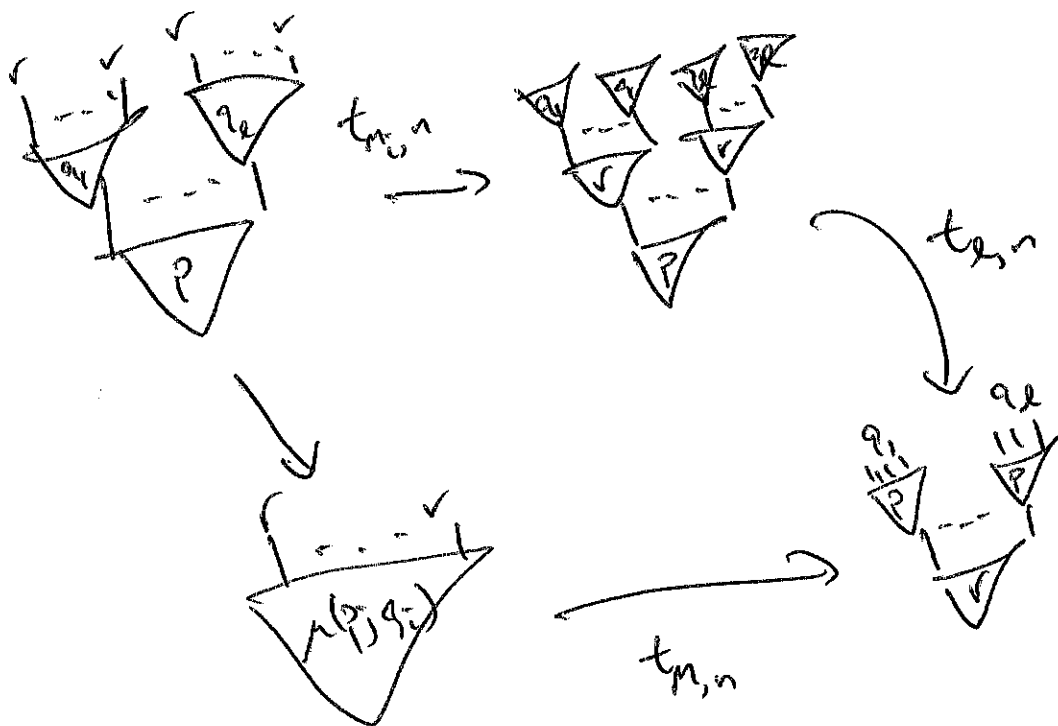
$$\mu(p; \mu(q_1; \varepsilon), \dots, \mu(q_n; \varepsilon)) = \mu(\mu(p; q_1, \dots, q_n); \varepsilon)$$

$$\mu(\mu(p; \varepsilon); \varepsilon) \cdot t_{m,n} \rightarrow \mu(r; \underline{\mu(p; \varepsilon)}) = \mu(\mu(r; \varepsilon); \underline{q_1, \dots, q_n})$$

~~$$\mu(p; \mu(q_1; \varepsilon), \dots, \mu(q_n; \varepsilon)) \cdot \mu(\varepsilon; t_{m,n}, \dots, t_{m,n})$$~~

$$\mu(\mu(r; \varepsilon); \underline{q_1, \dots, q_n}) \leftarrow \mu(\mu(p; \varepsilon); \overset{t_{m,n}}{\underline{q_1, \dots, q_n}})$$

$\mu(\mu(p; \varepsilon); q_1)$



$$\mu(p; \mu(q_1; \varepsilon), \dots, \mu(q_n; \varepsilon)) \cdot \mu(\varepsilon; t_{m,n}, \dots, t_{m,n}) \cdot \mu(t_{m,n}; \underline{q_1, \dots, q_n})$$

$$\begin{aligned} & \mu(p; \mu(q_1; \varepsilon) \cdot t_{m,n}, \dots, \mu(q_n; \varepsilon) \cdot t_{m,n}) \cdot \mu(t_{m,n}; \varepsilon) \\ & \downarrow \\ & \mu(p; \mu(r; q_1), \dots, \mu(r; q_n)) \cdot \mu(t_{m,n}; \varepsilon) \\ & \downarrow \\ & \mu(\mu(p; \varepsilon); q_1, \dots, q_n) \cdot \mu(t_{m,n}; \varepsilon) \\ & \downarrow \\ & \mu(\mu(p; \varepsilon) \cdot t_{m,n}; \underline{q_1, \dots, q_n}) \\ & \downarrow \\ & \mu(\mu(r; \varepsilon); \underline{q_1, \dots, q_n}) = \mu(r; \underline{\mu(p; q_1, \dots, q_n)}) \end{aligned}$$