## CONTACT

in nick-lafarge

Nicholas-Lafarge

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www.nicklafarge.space

### **SUMMARY**

- Ph.D. candidate in aerospace engineering seeking full time employment starting Spring 2023.
- Diverse skills in astrodynamics, autonomy, machine learning, GN&C, and low-thrust systems.
- Experienced software engineer, passion for numerical methods.
- Creative problem-solver; proven collaboration and sership skills.

### **DISTINCTIONS**

NASA Space Technology Research Fellowship (NSTRF/NSTGRO)

Proposal selected in 2019 to support Ph.D. studies (4 years).

### **NASA Pathways Intern Award**

Awarded for performance as a Pathways intern at Johnson Space Center (2018).

## **EXPERTISE**

**Astrodynamics** 

**Software Engineering** 

**Numerical Analysis** 

**Machine Learning** 

Spacecraft GN&C

# **NICK LAFARGE**

Astrodynamics Researcher | Software Engineer

## **EDUCATION**

### Ph.D. - Aeronautics & Astronautics Engineering

Exp. May 2023

**Purdue University - West Lafayette (IN)** 

- · NASA Space Technology Research Fellow (NSTRF/NSTGRO). GPA: 4.0
- · Major area: Astrodynamics, Advisor: Prof. Kathleen Howell

Research title: "Reinforcement Learning Approaches for Autonomous Guidance and Control in a Low-Thrust, Multi-Body Dynamical Environment"

# M.S. - Aeronautics & Astronautics Engineering Purdue University - West Lafayette (IN)

May 2020

· Major area: Astrodynamics, Advisor: Prof. Kathleen Howell, GPA: 3.74.

# B.A. - Mathematics (Computational) and Japanese University of Colorado Boulder - Boulder (CO)

May 2014

• Minor in computer science, academic year (2011-12) in Osaka, Japan.

### WORK EXPERIENCE

## Graduate Pathways Intern NASA Johnson Space Center, Houston (TX)

2018 - Present

GN&C Autonomous Flight Systems Branch (three 10-17 week tours)

- Developed prototype flight software supporting state estimation for Orion. Integrated component into onboard navigation filter simulation.
- Implemented a distributed optimization library in Julia for LIDAR retroreflector pattern generation for Orion rendezvous and docking.
- Collaborated with Orion flight software team in investigating anomalous trajectory targeting behavior at entry interface for Artemis 1.

## Flight Path Control Intern NASA Jet Propulsion Laboratory, Pasadena (CA)

Summer 2017

- Developed an automated trajectory design tool for multi-body orbits and introduced a novel tree partitioning approach for Poincaré maps.
- · Supported MONTE software development for mission design.

# Founder / Software Engineer TookTech LLC, Boulder (CO)

2015 - 2017

- Led Android app development for OpenSnow meteorologist team, helping client surpass 20,000 active Android users.
- Supported client needs and business growth via creative custom software solutions within an allocated budget.

#### **Software Engineer**

2014 - 2016

**Amadeus Consulting, Boulder (CO)** 

- Built custom software for numerous clients in Python and Java.
- Engineered data science solutions for Google and VidVita, supporting web scraping, data processing, and data analytics tools.

### **PROGRAMMING**

Python Expert

MATLAB Advanced

Java Advanced

Julia Intermediate

C++ Beginner

## **LANGUAGES**

English Native

**Japanese** Intermediate

**Spanish** Beginner

**Latvian** Beginner

## **ACTIVITIES**

#### Journal Peer Reviewer

#### 2020, 2022

Reviewed for Acta Astronautica and the Journal of Spacecraft and Rockets

#### **Conference Session Chair**

#### 2022 AIAA SciTech Forum

<u>Session</u>: Al and Machine Learning for Astrodynamics

#### **Private Pilot License**

#### 2016

Airplane Single Engine Land

## CO/WY Japanese Speech Contest

#### 2013

Fist place in highest category for non-native speakers

### RESEARCH EXPERIENCE

## Graduate Researcher Purdue University, West Lafayette (IN)

2016 - Present

- Introduced novel onboard guidance and control techniques for lowthrust spacecraft under multi-body dynamics via machine learning.
- · Researched low-thrust trajectory design for libration point orbits.
- · Managed a multi-year, inter-university engineering research project.
- · Presented research at four international conferences.

## Visiting Technologist (NSTRF/NSTGRO) NASA Goddard Space Flight Center, Greenbelt (MD)

2020 - 2022

Collaborated with the Navigation and Mission Design Branch (three tours)

- Consulted with mission design engineers to apply research in higherfidelity simulation in a mission recovery scenario (Summer 2022).
- Spearheaded investigation into autonomous low-thrust maneuver planning for multi-body orbit stationkeeping (*Winter 2020-21*).
- Led research team in evaluating reinforcement learning efficacy for low-thrust guidance and control in cislunar space (*Summer 2020*).

### **TECHNICAL SKILLS**

- **Specialties**: High-performance scientific computing, data visualization.
- Software development: Object-oriented design, parallel processing.
- · Communication: LaTeX (expert), technical presenting.
- Tools & Platforms: Linux, Git, SQL, Android app development.

## **PUBLICATIONS**

#### **JOURNAL PUBLICATIONS**

• LaFarge, N. B., Miller, D., Howell, K. C., & Linares, R., "Autonomous Closed-Loop Guidance using Reinforcement Learning in a Low-Thrust, Multi-Body Dynamical Environment". *Acta Astronautica*, vol. 186, 1–23, 2021.

#### **CONFERENCE PUBLICATIONS**

- LaFarge, N. B., Howell, K. C., and Folta, D. C., "Adaptive Closed-Loop Maneuver Planning for Low-Thrust Spacecraft using Reinforcement Learning", *International Astronautical Congress*, Paris, France, 2022.
- LaFarge, N. B., Howell, K. C., and Folta, D. C., "An Autonomous Stationkeeping Strategy for Multi-Body Orbits Leveraging Reinforcement Learning," *AIAA SciTech Forum*, San Diego, CA, 2022.
- LaFarge, N. B., Howell, K. C., and Linares, R., "A Hybrid Closed-Loop Guidance Strategy for Low-Thrust Spacecraft Enabled by Neural Networks,"
   *AAS Spaceflight Mechanics Meeting*, Charlotte, NC (Virtual), 2021.
- LaFarge, N. B., Miller, D., Howell, K. C., and Linares, R., "Guidance for Closed-Loop Transfers using Reinforcement Learning with Application to Libration Point Orbits," *AIAA SciTech Forum*, Orlando, FL, 2020.