

Midterm 2

In the 1980's, the Department of Energy's Civilian Radioactive Waste Management Program surveyed a number of potential sites for a new high-level nuclear waste disposal site, one of which was located in the Palo Duro Basin in Deaf Smith county, Texas¹ (Figure 1, left). Radioactive waste containers run the risk of leaking, especially in the corrosive salty environment in which they are stored, and the potential consequences of radioactive waste leakage are especially severe if the leakage has the potential to come into contact with a populated area. The potential nuclear waste site is located about 60 km southwest of Amarillo, Texas, and both locations overlie the Wolfcamp aquifer. This report is concerned with assessing the patterns of water movement within this aquifer to determine whether there is a risk of radioactive waste leakage diffusing towards this nearby populated area.

This will be achieved by estimating a two-dimensional potentiometric surface of pressure within the Wolfcamp aquifer. At 85 scattered locations in the aquifer, the water pressure is measured indirectly by measuring piezometric head, which involves boring a narrow hole and measuring the height above the surface of the aquifer that the water reaches in a piezometer (a narrow tube)²; the pressure data are therefore reported in meters. The data have been preprocessed by the contracting company that collected them by deleting depressured and locally overpressured or underpressured data to more accurately represent the potentiometric surface¹. The potentiometric surface will be estimated by performing kriging on the available data. This surface will be used as an estimate of water flow patterns in the aquifer (by assuming that water diffuses from areas of higher pressure to areas of lower pressure) to determine whether water flows from the potential nuclear waste site in Deaf Smith county towards Amarillo.

As shown in the left panel of Figure S1 (Supplemental Figure 1), the piezometric head data appear to follow a bimodal distribution. Although the distribution appears to differ from Gaussian, the sample size of 85 measurements is rather small, and using larger bins as in the right panel, the data might reasonably be approximated as Gaussian. Additionally, the data do not have an obvious skew, and for these reasons it is doubtful whether a log transformation would be beneficial. (Indeed, a log transformation does not remove the bimodality of the distribution; see appendix, "Log transform.")

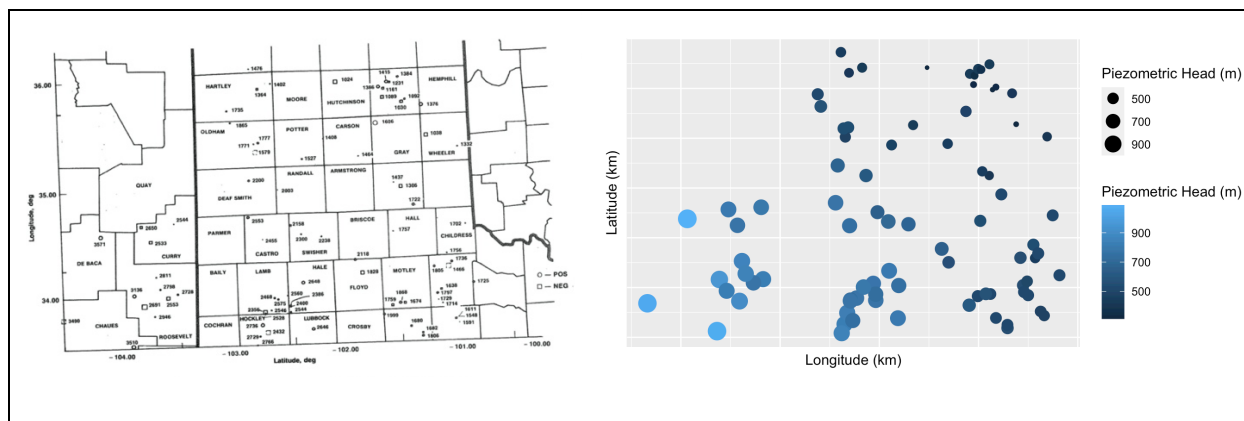


Figure 1: Visualization of the wolfcamp dataset, including the location of the sampled sites in the Texas panhandle and eastern New Mexico (left) and a bubble plot (right). Top left figure reproduced from Harper & Furr, 1986¹.

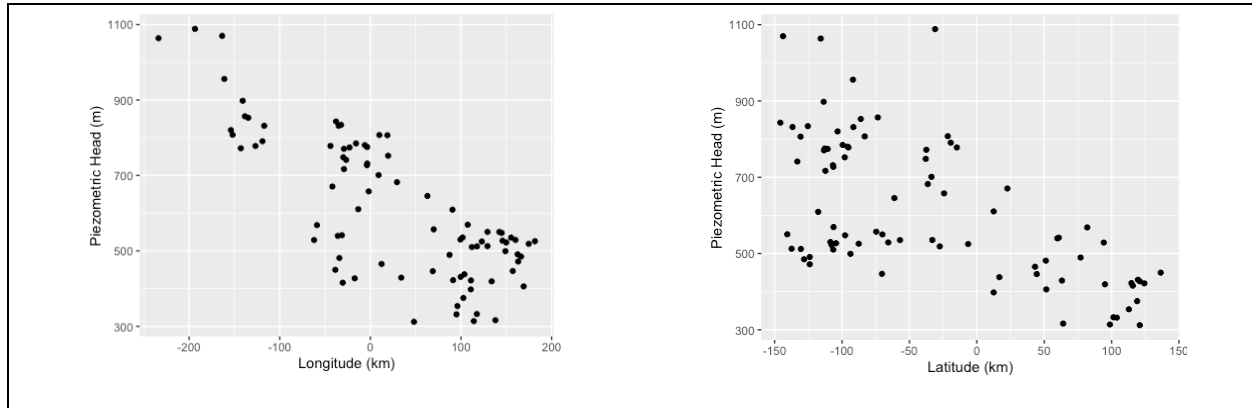


Figure 2: Plot of piezometric head data against longitude (left) and latitude (right).

The data are visualized with their locations on a map and with a bubble plot in Figure 1. A visual inspection of the bubble plot suggests that values of piezometric head are largest in the southwest and smallest in the northeast, and vary somewhat smoothly between. A plot of the piezometric head values against longitude and latitude (Figure 2) confirms this visual intuition. There appears to be a strong negative correlation between piezometric head and both longitude and latitude; piezometric head values tend to decrease when moving north or east. This spatial dependence is fortunate because of the lack of other potential covariates, so the data is detrended by fitting a linear regression on the longitudinal and latitudinal coordinates.

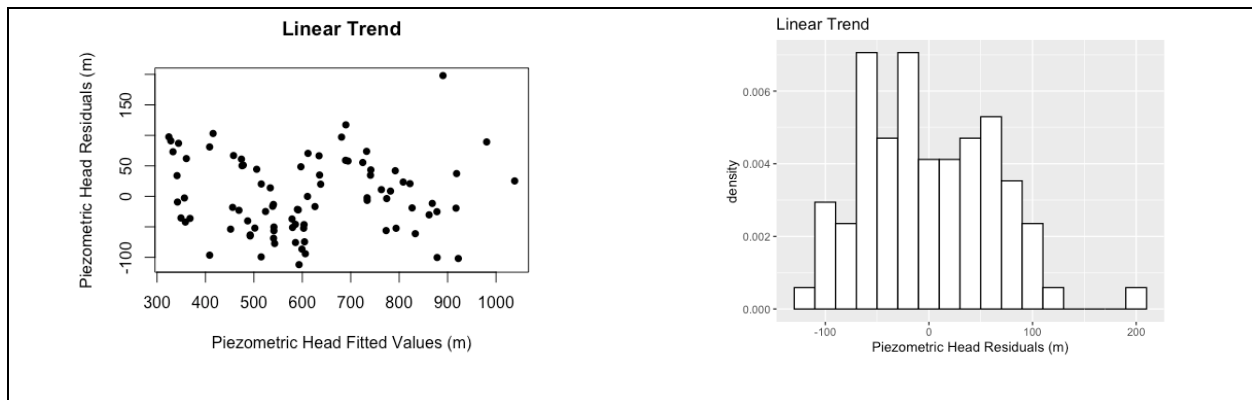


Figure 3: Residual analysis of fitting a linear model for piezometric head on x and y coordinates, including a plot of fitted values against residuals (left) and a histogram of the residuals (right).

Residual analysis upon fitting a linear trend to the data is shown in Figure 3. There are no obvious patterns in the plot of fitted values against residuals on the left, indicating that there is not significant information in the residuals left to be captured. There is, however, an outlier (the point with a fitted value of around 900 m and a residual value of nearly 200 m), which is also apparent in the histogram of residuals on the right. The outlier occurs at site 78, the site with the highest piezometric head value. The histogram suggests two noteworthy features. First, the residuals appear to be somewhat right-skewed. In order to make accurate statistical inferences based on this model, they should follow a Gaussian distribution, so this skewness might cast doubt on the accuracy of any predictions. Performing a log transform on the data does not significantly improve the Gaussianity of the residuals of a linear model based on the linearity of a Q-Q plot (see appendix, “Log-transformed linear model”), so a log transform is not applied. Second, the outlier is very apparent in the histogram. Removing the outlier is not a suitable option: not using all available information to detrend the data simply leads to a larger residual value at this site on which to perform

kriging (see appendix, “Linear trend without the outlier”), and thus simply puts off the problem of the outlier to a later part of the analysis instead of addressing it. The outlier is left in the model.

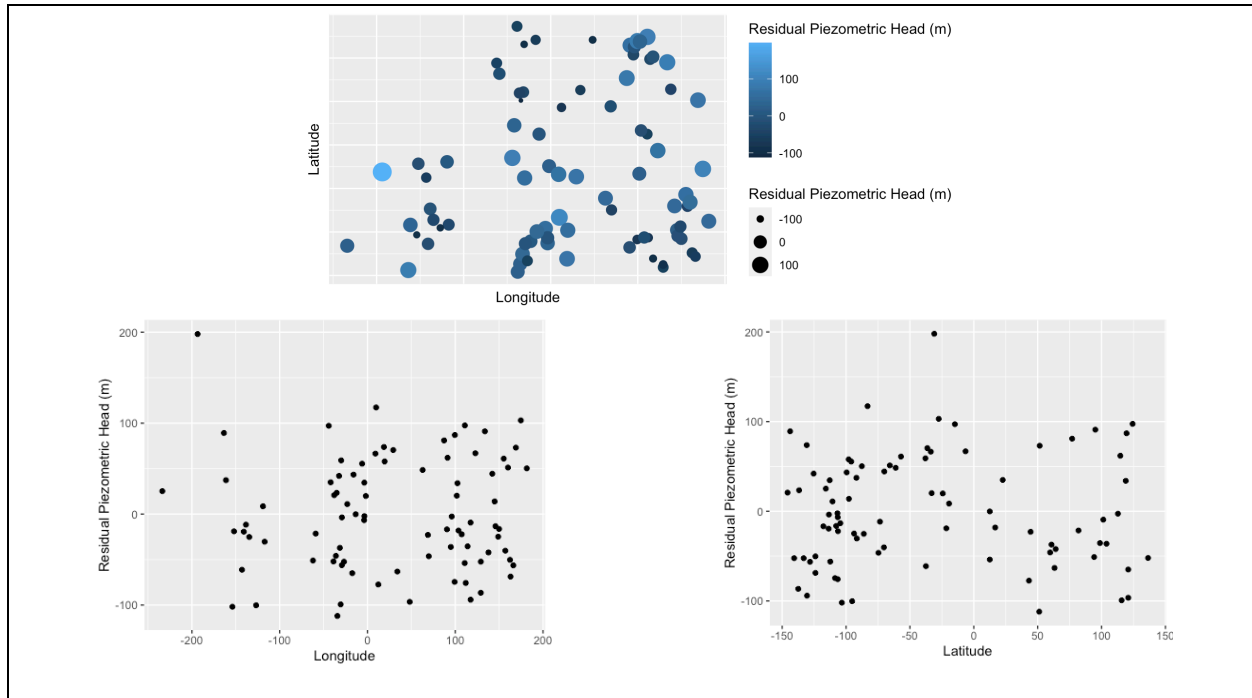


Figure 4: Visualization of the detrended data, including a bubble plot (top) and plot of the detrended data against longitude (bottom left) and latitude (bottom right).

Figure 4 confirms a lack of spatial dependence in the residuals; there are no trends apparent in the bubble plot of the residuals or scatter plot against longitude or latitude. Therefore, detrending was performed with a linear model of the form $z_s = \beta_0 + \beta_1 x_s + \beta_2 y_s + \varepsilon_s$, where s is a specific observation with longitude x_s , latitude y_s , and piezometric head z_s , and ε_s are the residuals for each observation which will be analyzed further.

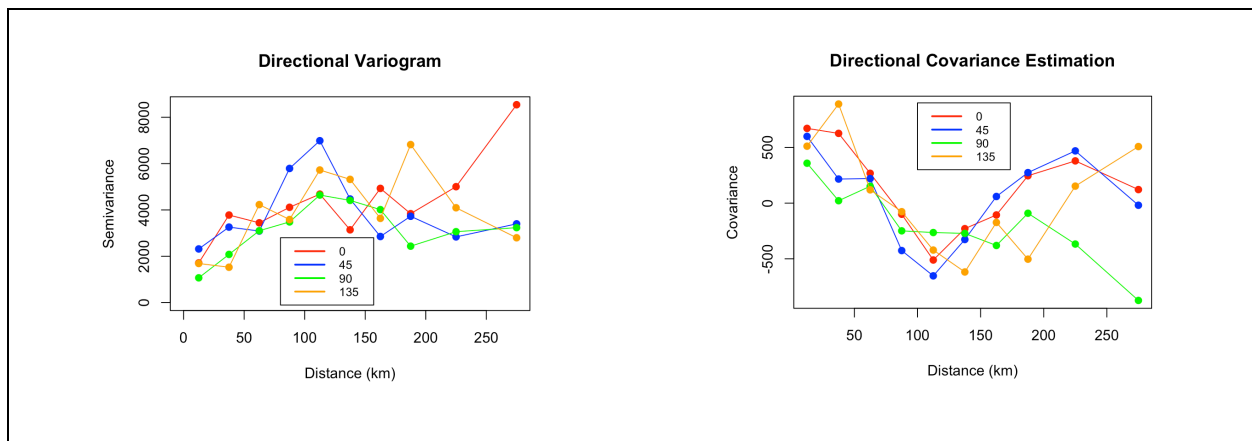


Figure 5: Plot of directional variogram (left) and directional covariance (right) for the detrended data.

The directional variogram and covariance for the detrended data are shown in Figure 5. A discussion of general features of the variogram and covariance is included below. Considering only directional dependence, no trends are readily apparent. From the directional variogram, observations at 90°

appear to be slightly more correlated at short distances than in other directions. However, this effect is very slight, and disappears when decreasing the tolerance angle (see appendix, “Effect of decreasing tolerance angle”), suggesting that it may be due in large part to the cluster of observations in the central south that are angled somewhere between 90° and 135° relative to each other. Overall, the residuals do not appear to contain any obvious directional dependence.

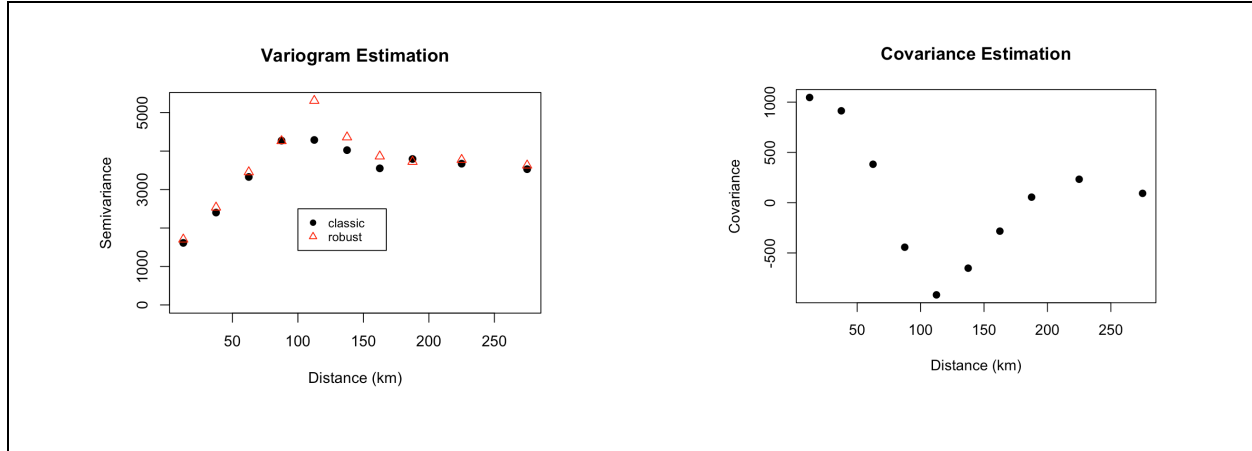


Figure 6: Plot of classic and robust empirical variogram (left) and empirical covariance (right) for the detrended data.

For fitting a variogram, a maximum distance of 300 km was used; past 300 km, values become quite noisy and numbers of available points become small. Bins were chosen to keep the variogram reasonably smooth while keeping the number of pairs of points in each bin reasonably consistent (see appendix, “Empirical variogram”). The empirical variogram fit to the residuals is shown in the left panel of Figure 6; the classic and robust variograms give quite different values for several points, reflecting non-Gaussianity in the data as discussed previously. It is likely that the distances at which these methods give differing values, around 100-150 km, corresponds to the distance between the two bimodal centers. In acknowledgment of the fact that the data is not exactly Gaussian, the robust variogram is used. The variogram follows the usual shape: it has a nugget of around $1,500 \text{ m}^2$, then increases before leveling off at around $4,000 \text{ m}^2$ for distances of 150 km or greater.

The empirical covariance, shown in the right panel of Figure 6, shows that observations are positively correlated at short distances, negatively correlated at intermediate distances, and nearly uncorrelated at large distances. The presence of positive correlation at short distances is expected, as nearby points are likely to be subject to the same patterns in pressure that the linear model was unable to capture. Uncorrelation at large distances is also expected. The negative correlation at intermediate distances however suggests the existence of one or more “pockets” of correlated points separated by a distance of about 100-150 km from another “pocket” of correlated points with residuals of the opposite sign. This observation is also consistent with the presence of a bimodal distribution.

To the empirical variogram, a linear, spherical, Matérn, and wave variogram (in an attempt to capture the “hump” in the semivariance) were each fit with non-weighted least squares, weighted least squares, and Cressie-style weights (Figure 7) using the optim minimization function. Of these variograms, the spherical variogram with Cressie-style weights was found to have the lowest sum of squared errors across the first three points (see appendix, “Variogram fitting”). With this variogram, the nlm optimization function was found to perform slightly better than optim, so the final variogram was chosen to be a spherical variogram of the form $\gamma(u) = \tau^2 + \sigma^2 \left[\frac{3}{2} \phi u - \frac{1}{2} (\phi u)^3 \right]$.

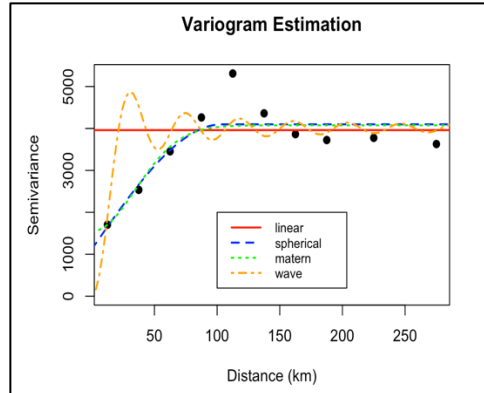


Figure 7: Plot of linear, spherical, Matérn, and wave variograms with Cressie-style weights fit to the robust empirical variogram. The spherical variogram was chosen as the best based on its fit to the first three points.

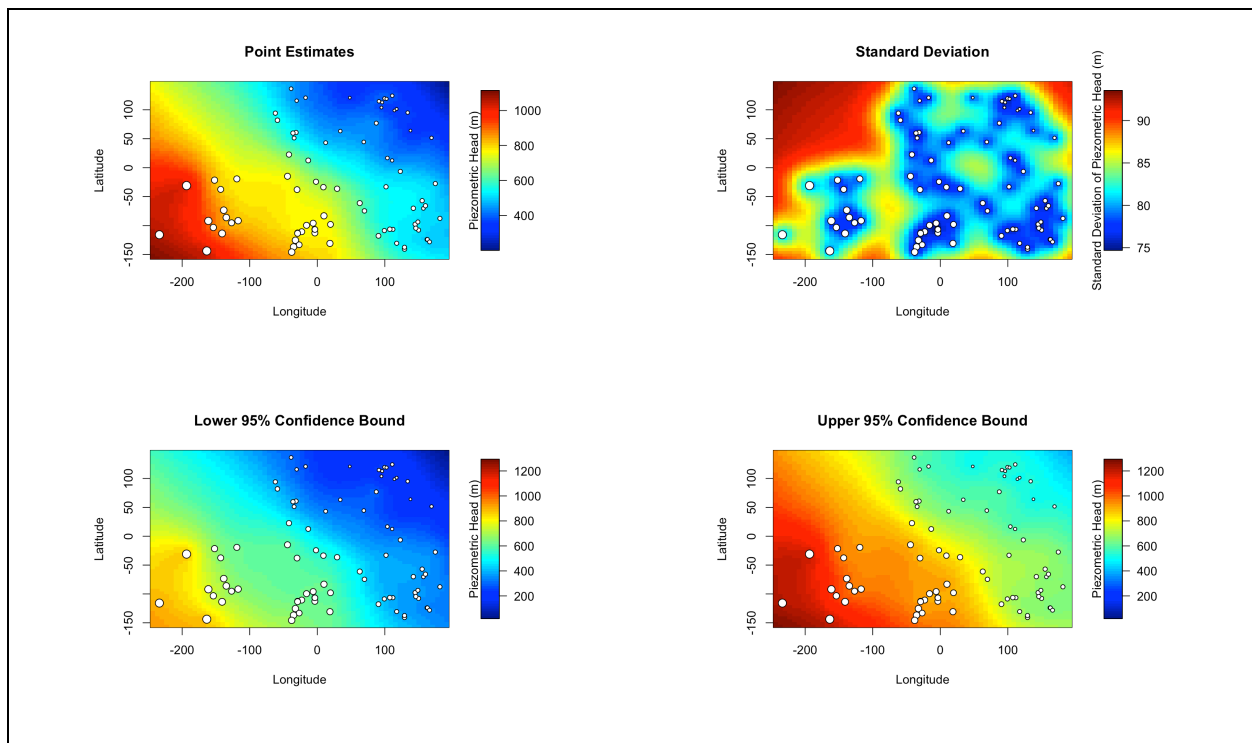


Figure 8: Results of kriging on the original scale, including point estimates (top left), standard deviations (top right), and lower and upper bounds for a 95% confidence interval (bottom left and right). The grid for prediction consists of 100 evenly spaced points spanning 10 km below the lowest x or y value to 10 km above the highest.

Using this variogram, kriging was performed on the residuals (see appendix, “Kriging,” for residual point estimates, standard deviations, and confidence intervals) and was converted to the original scale by adding the point estimates and variances of the linear trend to the residual kriging estimates. Figure 8 shows point estimates, standard deviation, and lower and upper 95% confidence intervals for piezometric head values on the original scale. As one would expect, the standard deviation is smallest near points for which data was collected, and increases moving away from those points. The standard deviation does not increase dramatically moving away from those points – the scale ranges from about 75 m to 95 m. Thankfully, the points in which we are most interested, sites 15 and 59 (see Figure S2), are near several other points and have relatively low standard deviation, which should allow conclusions to be drawn about them more easily.

From the maps of point estimates and confidence intervals, several features are noticeable. First, the trend is the dominant feature; piezometric head values tend to be highest in the southwest and lowest in the northeast. Bands of equal pressure therefore run between the northwest and southeast, and kriging is able to capture several nonlinearities in these bands. Notably, it is able to capture a curved high-pressure region that includes the point that was a large outlier in the linear trend (site 78, at approximately (-200 km, -30 km)). There appears to be an additional nonlinear pressure feature around (100 km, -50 km).

The validity of these prediction intervals relies on several assumptions. Most notably is the assumption of Gaussianity in the data. The advantage of assuming Gaussianity is that it is possible to construct confidence intervals on the original scale. However, as we have seen, the piezometric head data are only very approximately Gaussian, and instead appear to follow a bimodal distribution. Standard transformations (such as the log transformation) work well for normalizing skewed data but do not significantly improve the normality of this bimodal data; a more complex transformation might be more successful. The same is true for the residuals of the linear model fit to capture the trend in piezometric head; to produce accurate confidence intervals, it is necessary to assume the residuals follow a Gaussian distribution, when in fact they appear slightly right-skewed and there is an outlier (Figure 3). Further, representing the pressure distribution of the aquifer as a static two-dimensional potentiometric surface is a simplification of the true hydrologic and geological processes that shape water movement in an aquifer. A statistical analysis such as this is unable to provide an explanation, for example, of the cause of the two nonlinearities in equipotential lines discussed above, or of some geological feature that might represent some sort of “split” in the aquifer that causes the data to be distributed bimodally, and such information is likely to be informative in assessing water movement patterns in the aquifer. Finally, any conclusions drawn rely on the quality of the data obtained: essentially, whether the contracting company quantified the uncertainty in their measurements well enough to report all useful data, exclude all erroneous data, and to report data representative of the true potentiometric surface.

Figure S2 shows the location of the potential nuclear waste site (site 15, lower left point in right panel) and the city of Amarillo, Texas (site 59, upper right point in right panel) in relation to all the points surveyed. Based on the sample measurements, the potential nuclear waste site is at higher pressure than Amarillo, so if nuclear waste were to leak out of the storage site there is concern that it would diffuse to a populated area. Based on the kriging results, the predicted difference in pressure between the two sites is 202.4 m with a standard deviation of 111.9 m; the p-value for testing whether this value is greater than 0 m is 0.035, indicating marginal significance. Further, this result is based on a one-tailed test (only a positive gradient is of interest, as only a positive gradient could carry water from the waste site to Amarillo); a two-tailed test would give a p-value of 0.07, outside of the standard range for significance. There is an argument to be made for conducting a two-tailed test, as *any* movement of nuclear waste away from the storage site is likely to come into contact with civilization in some way. However, given the nature of the problem, it is desirable to minimize the probability of a type II error (of concluding that there is no pressure differential and therefore no risk of nuclear contamination of a residential area when in fact there is) at the expense of an increased risk of type I error, so a large α value is desired. The conclusion is therefore that a pressure differential does exist between sites 15 and 59.

Based on this conclusion, the recommendation is that the potential site in Deaf Smith county, Texas is not suitable for nuclear waste storage. The potential for contamination of the groundwater of nearby Amarillo, Texas should leakage occur is too great. Historically, Congress ultimately came to the same conclusion and dropped the Deaf Smith county site from consideration due to concerns of aquifer contamination³. Of the potential sites under study, only one at Yucca Mountain, Nevada remained under consideration, and this site was eventually chosen for nuclear waste storage in 2002⁴.

References

1. Harper, W.V. & Furr, J.M. (1986) *Geostatistical analysis of potentiometric data in the Wolfcamp Aquifer of the Palo Duro Basin, Texas*, vol. 587. , BMI/ONWI. Springfield, VA: Office of Nuclear Waste Isolation, Battelle Memorial Institute.
2. Blaettler, K.G. (2019) How to Calculate the Piezometric Head. Sciencing. URL <https://sciencing.com/calculate-piezometric-head-8710823.html>.
3. Nuclear Waste Management: An Inventory of the Records, 1972-1990, at the Southwest Collection/Special Collections Library (2020) Texas Archival Resources Online. URL <https://legacy.lib.utexas.edu/taro/ttsw/00079/tsw-00079.html>.
4. President Signs Yucca Mountain Bill (2002) The White House.

Supplemental Figures

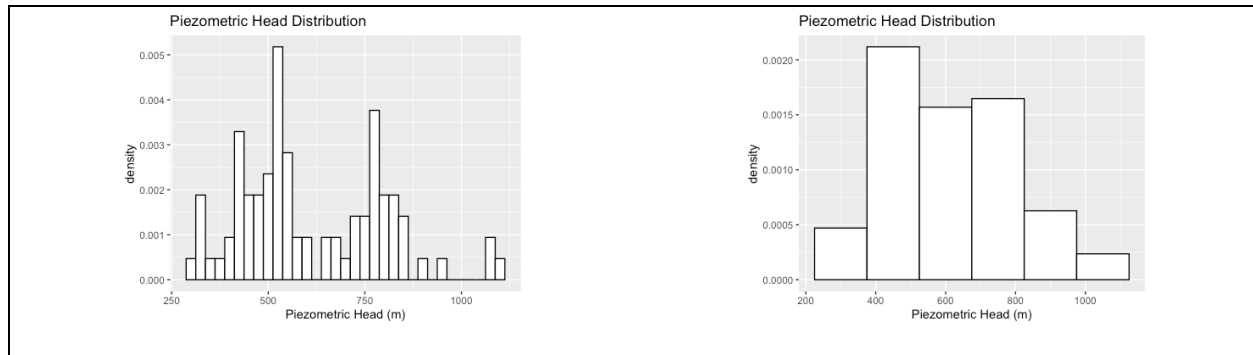


Figure S1: Exploratory data analysis: histograms of piezometric head distribution with different bin widths.

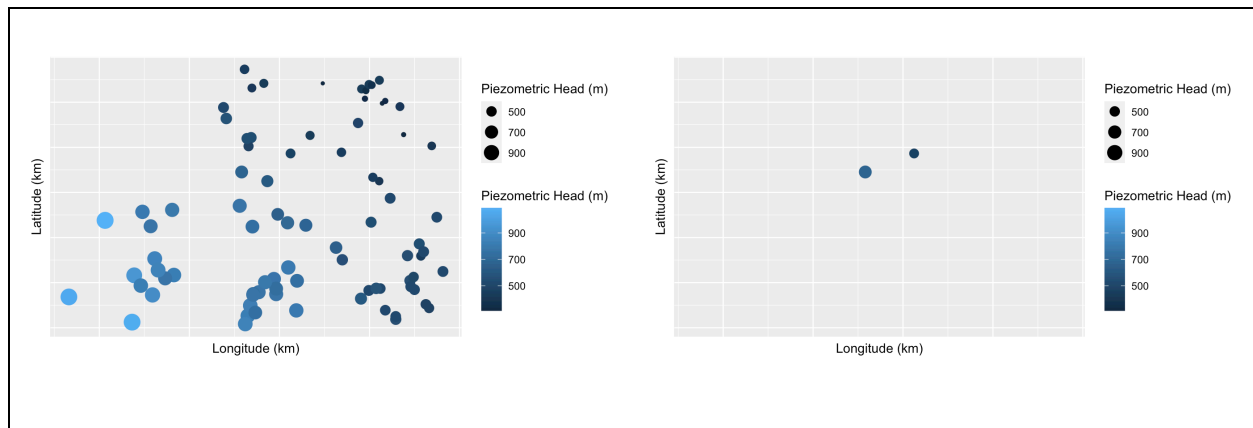
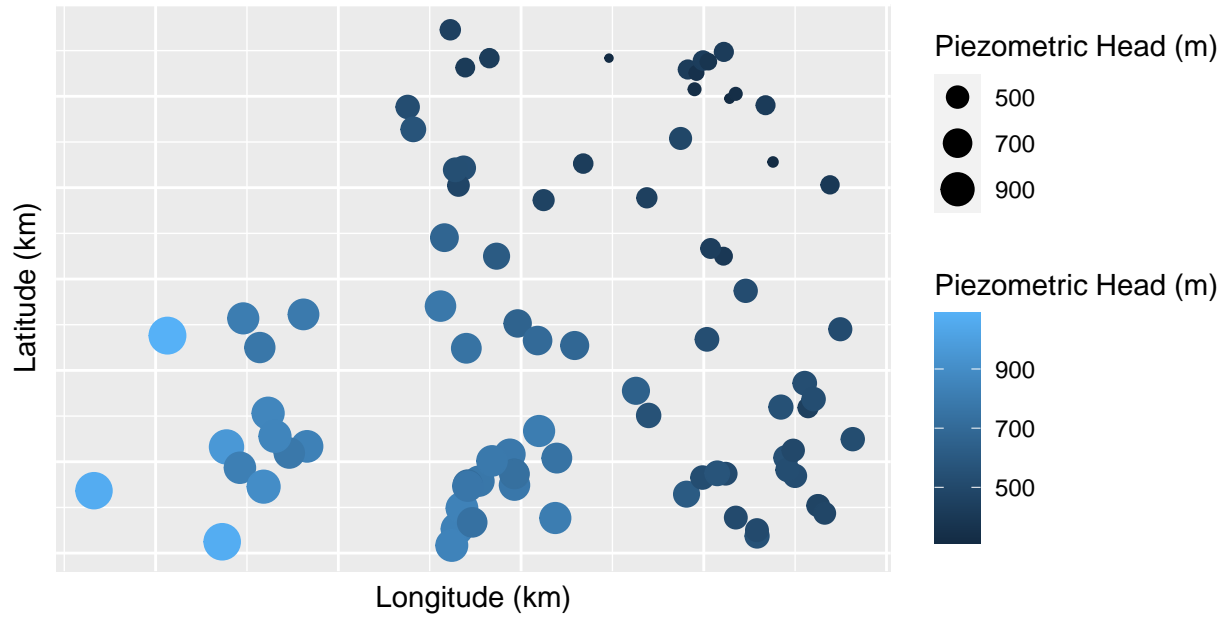


Figure S2: (Right panel) Location of the potential nuclear waste site (lower left point) and Amarillo, Texas (upper right point) relative to all locations surveyed (left panel).

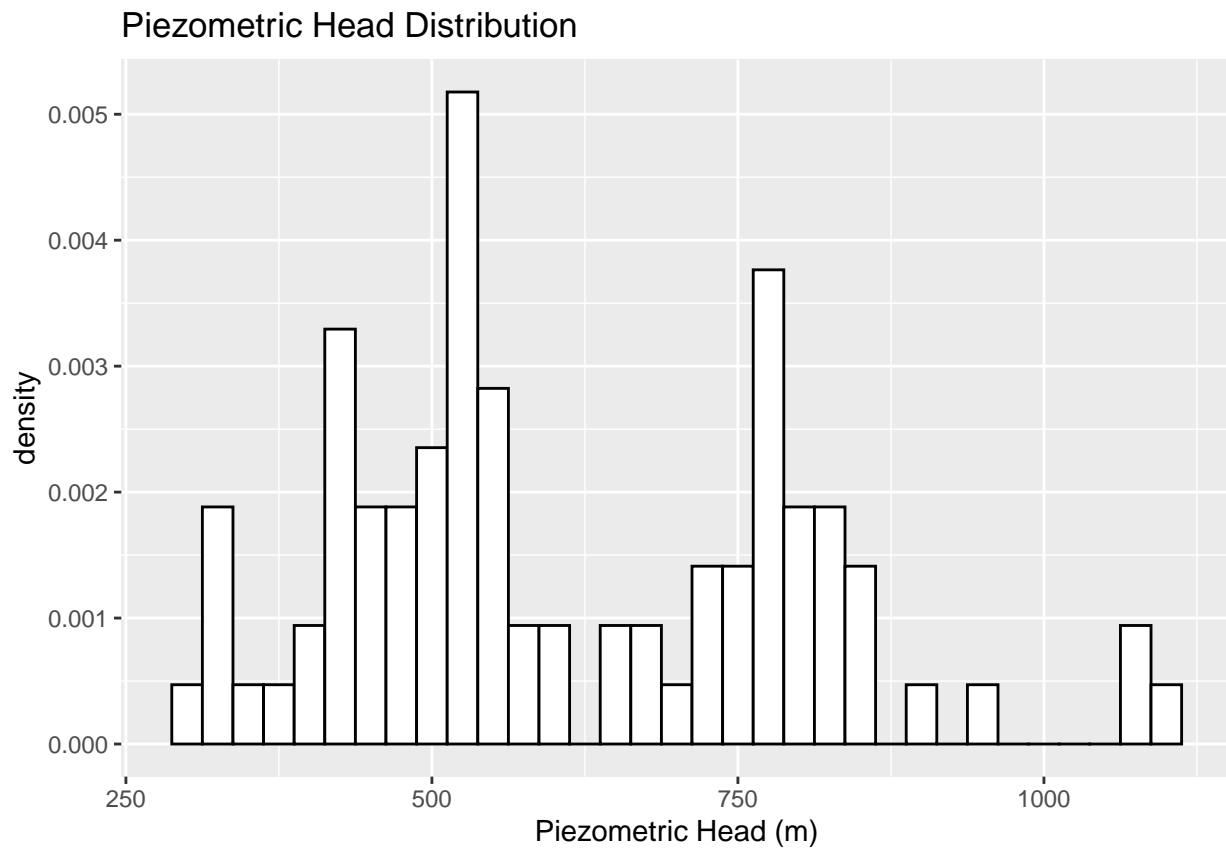
Appendix: All R Codes and Outputs

```
#####  
# Data Exploration  
#####  
  
# Loading Data  
  
library(geostatsp)  
library(geoR)  
library(fields)  
library(ggplot2)  
  
data(wolfcamp)  
  
x = wolfcamp$coords[,1]  
y = wolfcamp$coords[,2]  
z = wolfcamp$data  
  
# Setting up grid for later  
  
grid = NULL  
for (i in seq(min(x) - 10, max(x) + 10, length = 100))  
  for (j in seq(min(y) - 10, max(y) + 10, length = 100))  
    grid = rbind(grid, c(i, j))  
colnames(grid) = c("LONGITUDE", "LATITUDE")  
  
# Exploratory Analysis/Visualization  
  
  # Bubble plot  
  
df = data.frame(lat = y, long = x, Z = z)  
p = ggplot() + geom_point(data = df, aes(x = long, y = lat, size = Z, color = Z))  
p = p + labs(x = "Longitude (km)", y = "Latitude (km)", size = "Piezometric Head (m)",  
  colour = "Piezometric Head (m)") + coord_fixed()  
p = p + theme(axis.text.x = element_blank(), axis.text.y = element_blank(), axis.ticks =  
  element_blank())  
p
```

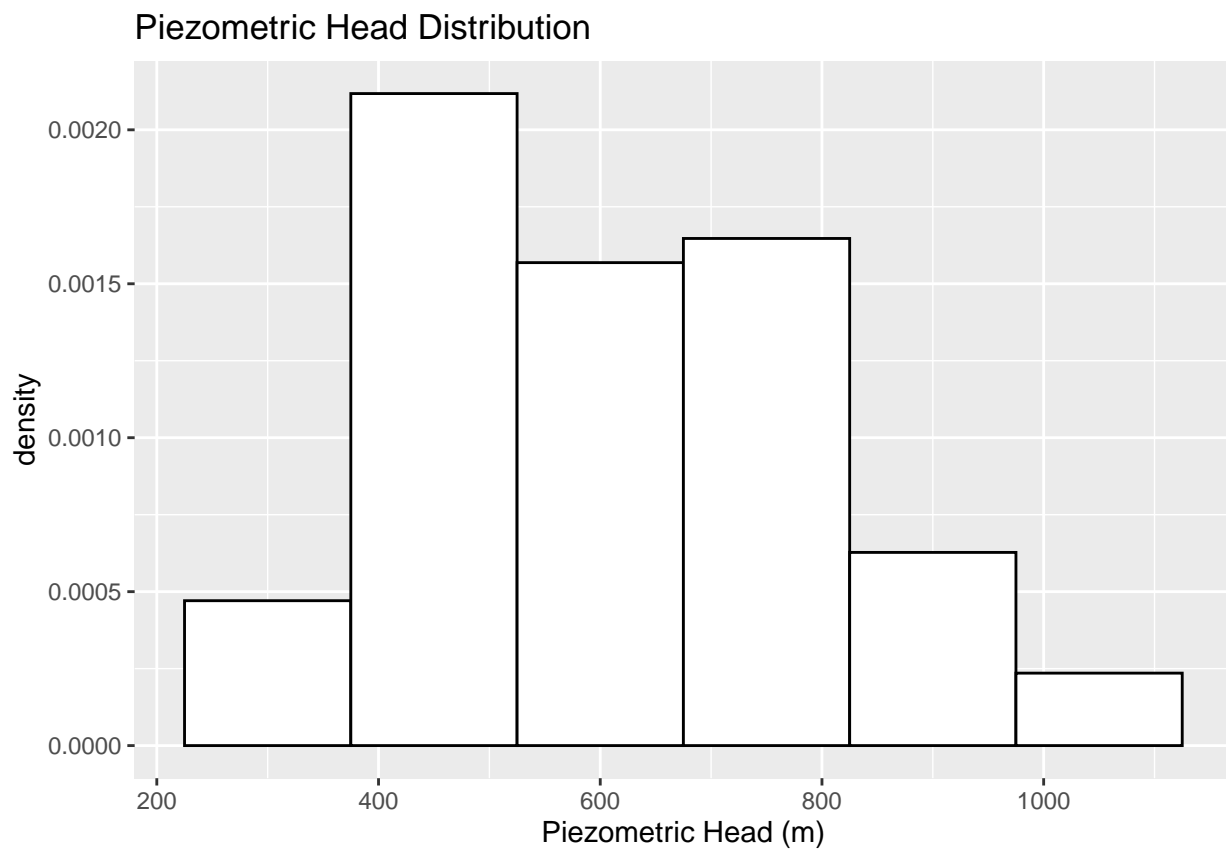


```
# Histograms

df = data.frame(X = z)
ggplot() + geom_histogram(data = df, aes(x = X, y = ..density..), binwidth = 25, color =
"black", fill = "white") + ggtitle("Piezometric Head Distribution") +
xlab("Piezometric Head (m)")
```

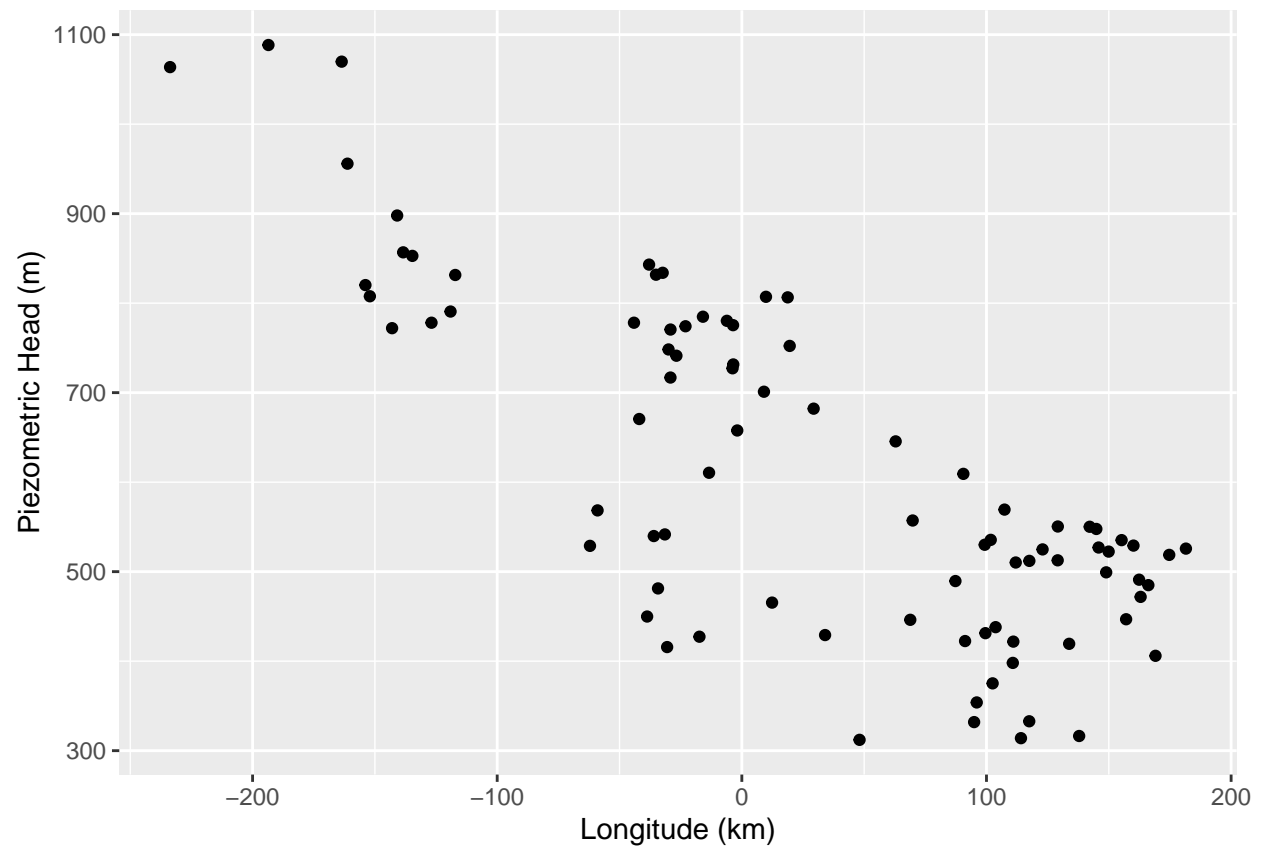


```
ggplot() + geom_histogram(data = df, aes(x = X, y = ..density..), binwidth = 150, color =
  "black", fill = "white") + ggtitle("Piezometric Head Distribution") +
  xlab("Piezometric Head (m)")
```

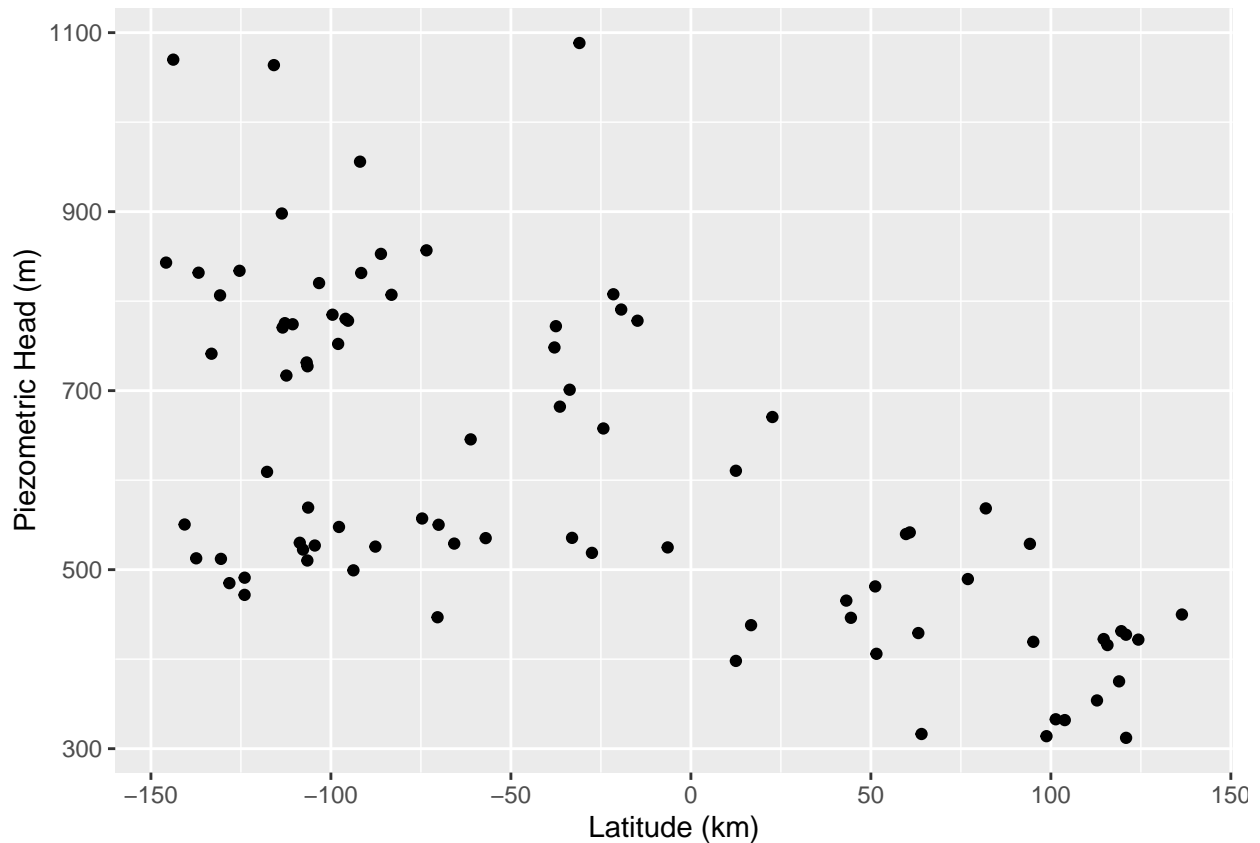


```
# Plot against latitude and longitude

df = data.frame(X = x, Y = y, Z = z)
ggplot(df, aes(X, Z)) + geom_point() + ylab("Piezometric Head (m)") +
  xlab("Longitude (km)")
```



```
ggplot(df, aes(Y, Z)) + geom_point() + ylab("Piezometric Head (m)") +  
  xlab("Latitude (km)")
```



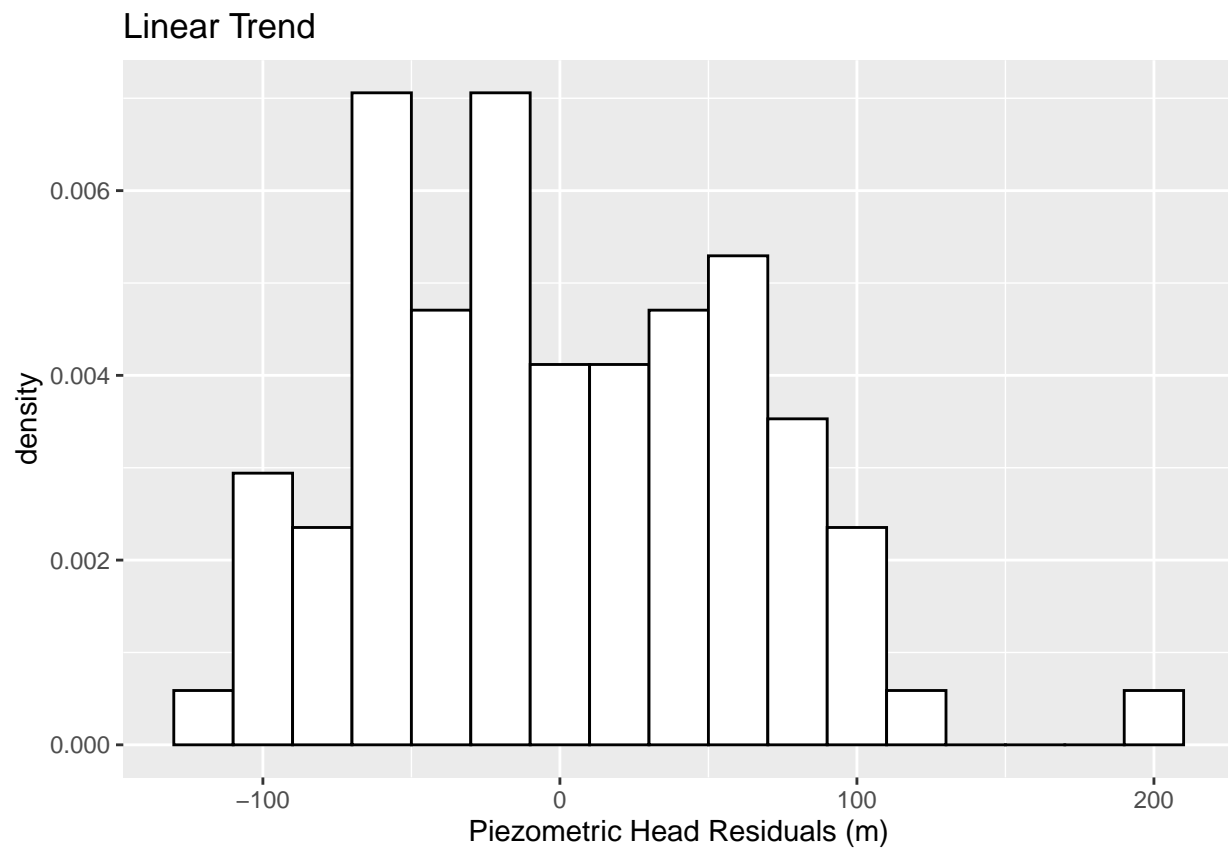
```
# Fit a linear trend

mod.z = lm(z ~ x + y)
summ.z = summary(mod.z)
summ.z

##
## Call:
## lm(formula = z ~ x + y)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -111.989  -50.297   -9.326   48.510  197.986
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  607.77066    7.52219   80.80  <2e-16 ***
## x            -1.27844    0.06552  -19.51  <2e-16 ***
## y            -1.13874    0.07739  -14.71  <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 62.29 on 82 degrees of freedom
## Multiple R-squared:  0.8909, Adjusted R-squared:  0.8882
## F-statistic: 334.8 on 2 and 82 DF,  p-value: < 2.2e-16

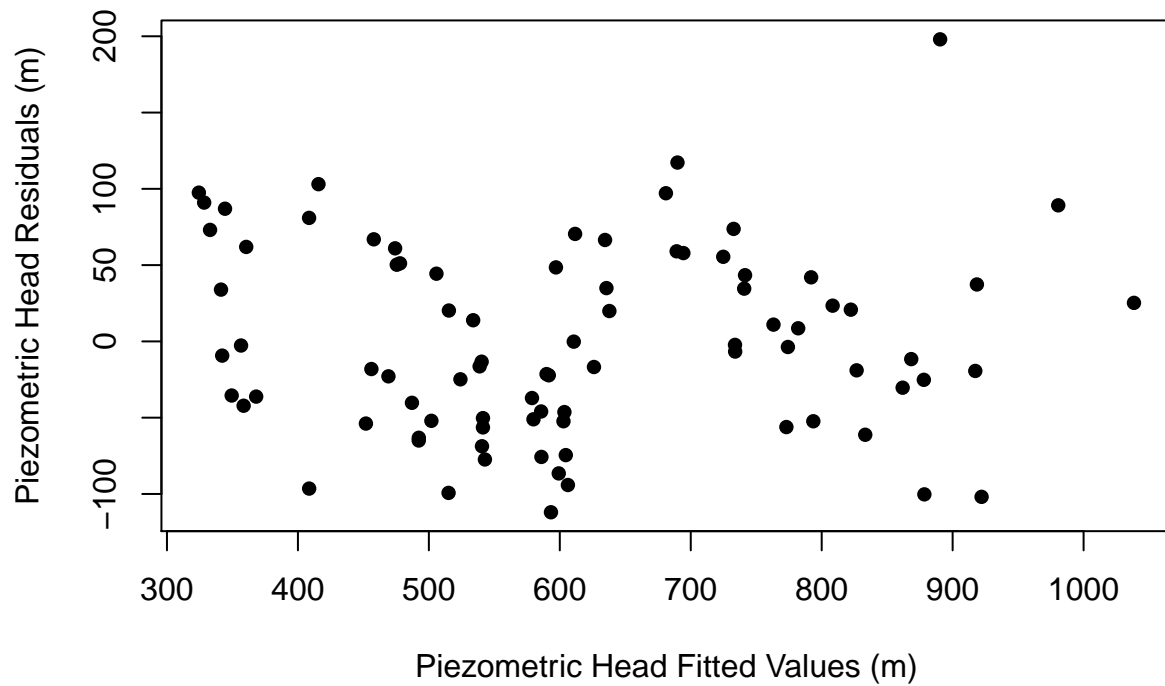
ggplot() + geom_histogram(data = df, aes(x = summ.z$residuals, y = ..density..),
  binwidth = 20, color = "black", fill = "white") + ggtitle("Linear Trend") +
```

```
xlab("Piezometric Head Residuals (m)")
```



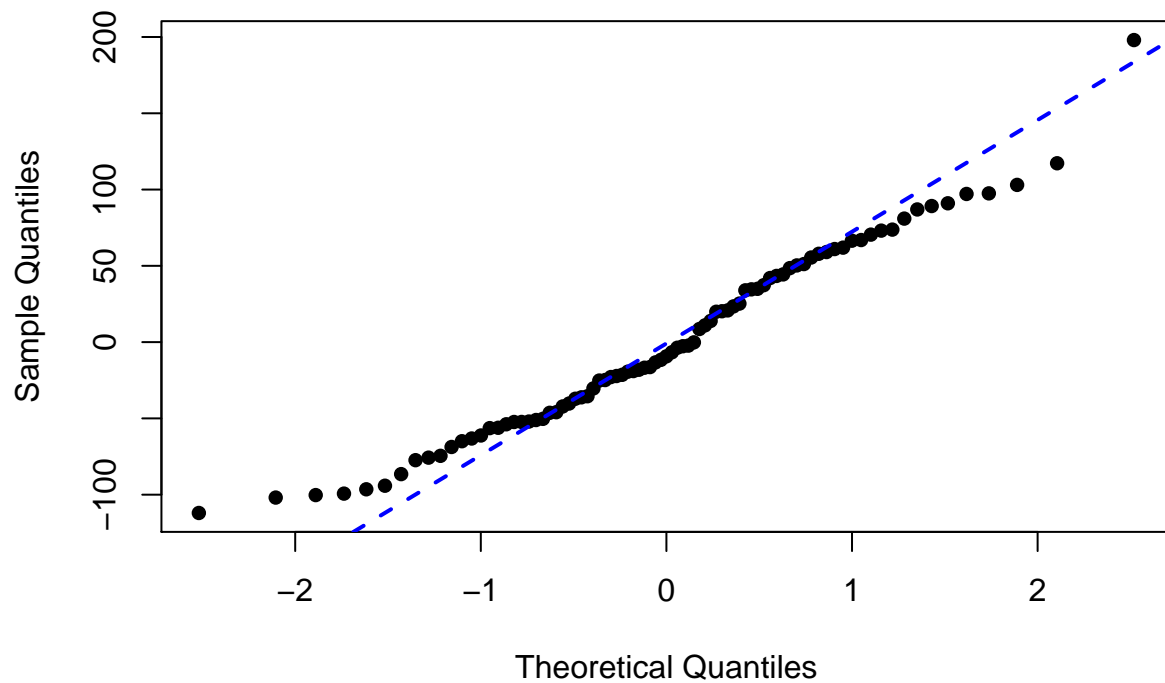
```
plot(x = mod.z$fitted.values, y = summ.z$residuals, pch = 16, main = "Linear Trend",  
xlab = "Piezometric Head Fitted Values (m)", ylab = "Piezometric Head Residuals (m)")
```

Linear Trend



```
qqnorm(summ.z$residuals, pch = 16, main = "Linear Trend Normal Q-Q Plot")
qqline(summ.z$residuals, lwd = 2, lty = 2, col = "blue")
```

Linear Trend Normal Q-Q Plot



```
# Linear trend without the outlier
```

```
cbind(x, y, z, summ.z$residuals)
```

##	x	y	z	
## 1	68.851186	44.453990	446.2190	-22.9078072
## 2	-44.090428	-14.826161	778.1401	97.1192701
## 3	-1.871464	-24.307187	657.7464	19.9035400
## 4	-29.962712	-37.896311	748.2703	59.0399579
## 5	155.243957	-57.001223	535.2190	61.0090994
## 6	174.711819	-27.481976	518.7601	103.0535097
## 7	142.205349	-70.080337	550.1539	44.3811979
## 8	144.906708	-97.753066	547.7156	13.8843026
## 9	149.940455	-107.744054	522.4176	-16.3554284
## 10	157.085841	-70.375616	446.8286	-40.2565094
## 11	145.836686	-104.477132	526.9895	-13.3097641
## 12	148.942676	-93.742959	499.2533	-24.8517851
## 13	160.095272	-65.740771	529.1231	51.1632536
## 14	-38.720268	136.406064	449.8766	-52.0645427
## 15	-41.938910	22.643149	670.5477	34.9452726
## 16	90.556503	-117.737938	609.2840	-16.7884035
## 17	117.528726	-130.548135	512.0546	-94.1228962
## 18	129.164119	-140.638579	550.4587	-52.3340263
## 19	129.115839	-137.419936	512.6642	-86.5250568
## 20	110.769577	12.504426	398.0615	-53.8573709
## 21	122.936046	-6.453378	524.8560	66.9032025
## 22	103.736844	16.720847	437.9896	-18.1188327
## 23	69.828446	-74.656410	557.1642	-46.3491649
## 24	62.876179	-61.170298	645.5546	48.5103336
## 25	181.531430	-87.643632	525.7704	50.2737146
## 26	87.305674	76.941646	489.4998	80.9610183
## 27	9.865139	-83.169719	807.0956	117.2281917
## 28	-6.115421	-95.915543	780.2737	55.4618712
## 29	-3.588786	-112.797322	775.3970	34.5913436
## 30	-3.797998	-106.504876	727.2395	-6.6681736
## 31	-3.508320	-106.730181	731.5066	-2.2872791
## 32	101.741286	-33.007178	535.5238	20.2368343
## 33	-17.332389	120.876114	427.3218	-64.9607576
## 34	-30.544916	115.726287	415.7396	-99.2987133
## 35	-62.071518	94.177476	528.8183	-51.0634321
## 36	133.798964	95.126975	419.3971	91.0056579
## 37	-35.083202	-136.760115	831.7840	23.4271114
## 38	-37.915607	-145.788406	843.0614	20.8025538
## 39	-32.363449	-125.382214	833.9175	41.9942013
## 40	-26.746918	-133.171328	741.2600	-52.3526760
## 41	48.118704	120.892208	312.1095	-96.4792933
## 42	162.396601	-123.966011	491.0238	-50.2974007
## 43	163.008143	-123.982104	471.8218	-68.7359535
## 44	166.178506	-128.198526	484.9279	-56.3780809
## 45	-23.029386	-110.624738	774.1778	10.9924965
## 46	-29.176993	-112.362805	716.8765	-56.1474207
## 47	-29.160900	-113.408864	770.5203	-3.6742200
## 48	-15.900093	-99.552609	784.8456	43.3829763
## 49	19.569346	-97.991567	752.2326	57.8932165
## 50	18.748592	-130.789533	806.4860	73.7489475
## 51	99.279024	-108.645273	530.0375	-74.5295238


```
## 52 111.960475 -106.537063 510.2259 -75.7279560
## 53 107.373910 -106.327851 569.3560 -22.2232591
## 54 -58.981622 81.930542 568.4416 -21.4359911
## 55 -31.462229 60.800154 541.6197 -37.1379904
## 56 -34.262448 51.208600 481.2704 -111.9894987
## 57 -35.984422 59.754096 539.7909 -45.9393080
## 58 34.021050 63.181950 429.1505 -63.1783072
## 59 12.359587 43.178087 465.4211 -77.3799153
## 60 -13.405645 12.504426 610.5032 -0.1664825
## 61 91.248511 114.680228 422.4451 61.9214063
## 62 94.949950 103.865589 331.9211 -36.1855334
## 63 110.978789 124.303969 421.8355 97.4947819
## 64 114.100872 98.780135 313.9382 -35.4760753
## 65 117.480447 101.355048 332.8355 -9.3260726
## 66 96.012102 112.813415 353.8663 -2.6931794
## 67 99.568702 119.572564 431.2841 86.9684296
## 68 102.513760 118.944929 375.2019 33.9366287
## 69 9.044385 -33.666999 701.0272 66.4812252
## 70 29.354018 -36.386752 682.1299 70.4515648
## 71 137.886639 64.067077 316.3766 -42.1581790
## 72 169.091377 51.546558 405.9862 73.0871984
## 73 -163.571406 -143.792848 1069.8284 89.1983720
## 74 -233.721716 -115.838939 1063.7325 25.2516424
## 75 -119.073675 -19.360134 790.6367 8.5910886
## 76 -152.048666 -21.532717 807.7052 -18.9710474
## 77 -142.972094 -37.497184 772.0443 -61.2075166
## 78 -193.520873 -30.963340 1088.4209 197.9857612
## 79 -138.433809 -73.449419 856.7771 -11.6130184
## 80 -117.142489 -91.586469 831.4792 -30.3446401
## 81 -161.205703 -91.908333 955.8353 37.3126986
## 82 -126.862789 -95.239628 778.1401 -100.2705048
## 83 -134.684090 -86.098684 852.8148 -25.1857848
## 84 -153.867199 -103.286234 820.2018 -101.8954470
## 85 -140.896070 -113.634169 897.9244 -19.3736527
```

```
mod.z.dim = lm(z[-78] ~ x[-78] + y[-78])
summ.z.dim = summary(mod.z.dim)
summ.z.dim
```

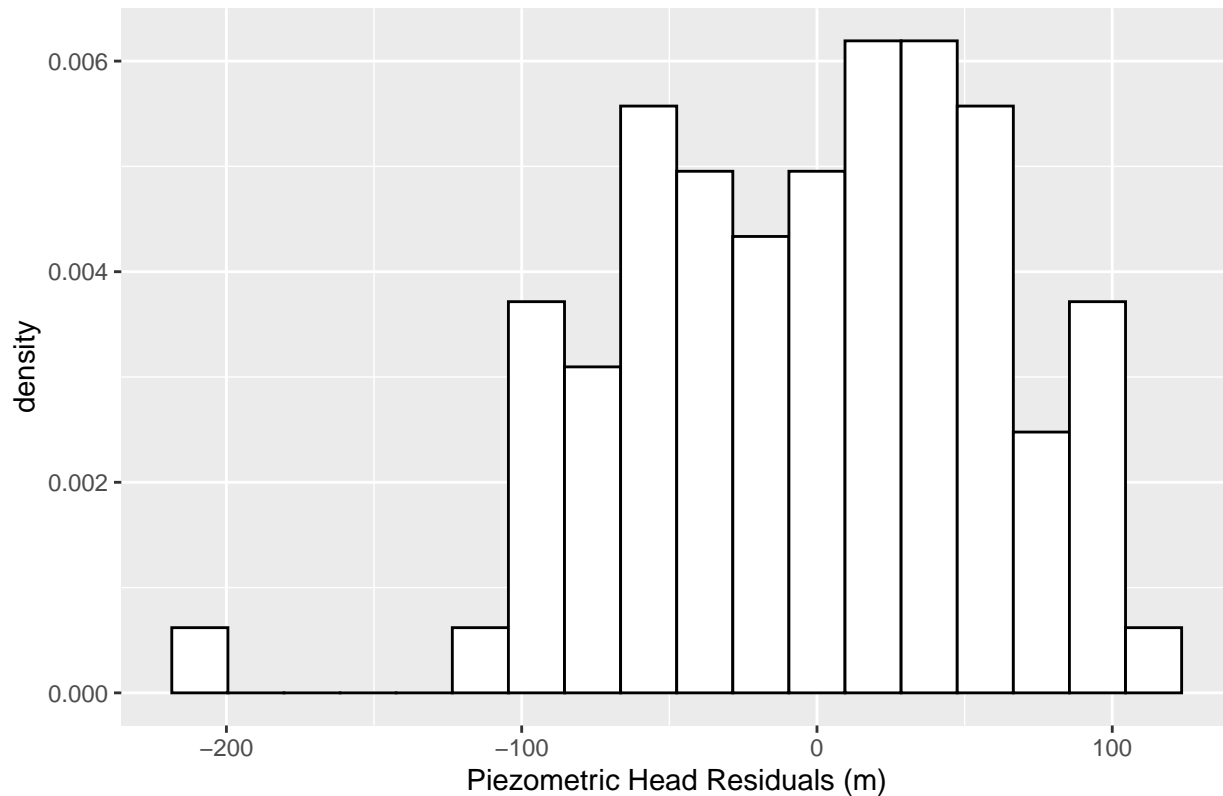
```
##
## Call:
## lm(formula = z[-78] ~ x[-78] + y[-78])
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -105.641  -45.220   -5.076   47.089  120.267
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  603.58977    7.15170   84.40  <2e-16 ***
## x[-78]       -1.22650    0.06319  -19.41  <2e-16 ***
## y[-78]       -1.14632    0.07258  -15.79  <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
```

```
## Residual standard error: 58.4 on 81 degrees of freedom
## Multiple R-squared:  0.8971, Adjusted R-squared:  0.8946
## F-statistic: 353.2 on 2 and 81 DF,  p-value: < 2.2e-16
```

```
pred = cbind(1, x, y) %*% mod.z.dim$coefficients
resid = pred - z
```

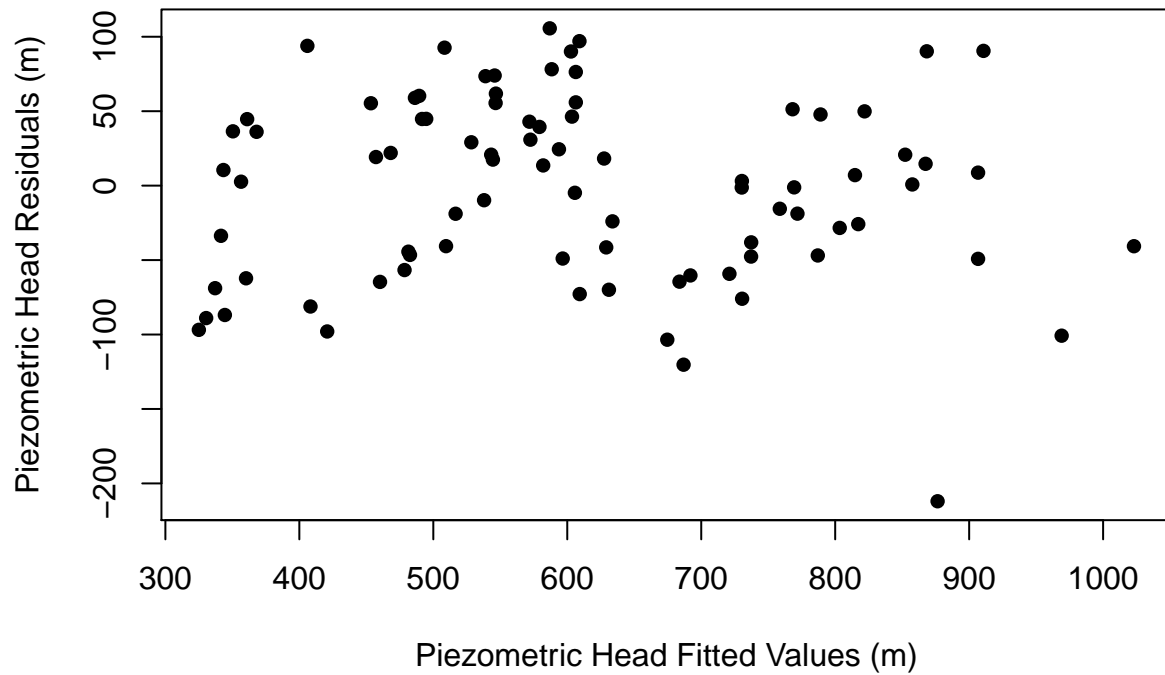
```
ggplot() + geom_histogram(data = df, aes(x = resid, y = ..density..), binwidth = 19,
  color = "black", fill = "white") + ggtitle("Linear Trend without Outlier") +
  xlab("Piezometric Head Residuals (m)")
```

Linear Trend without Outlier



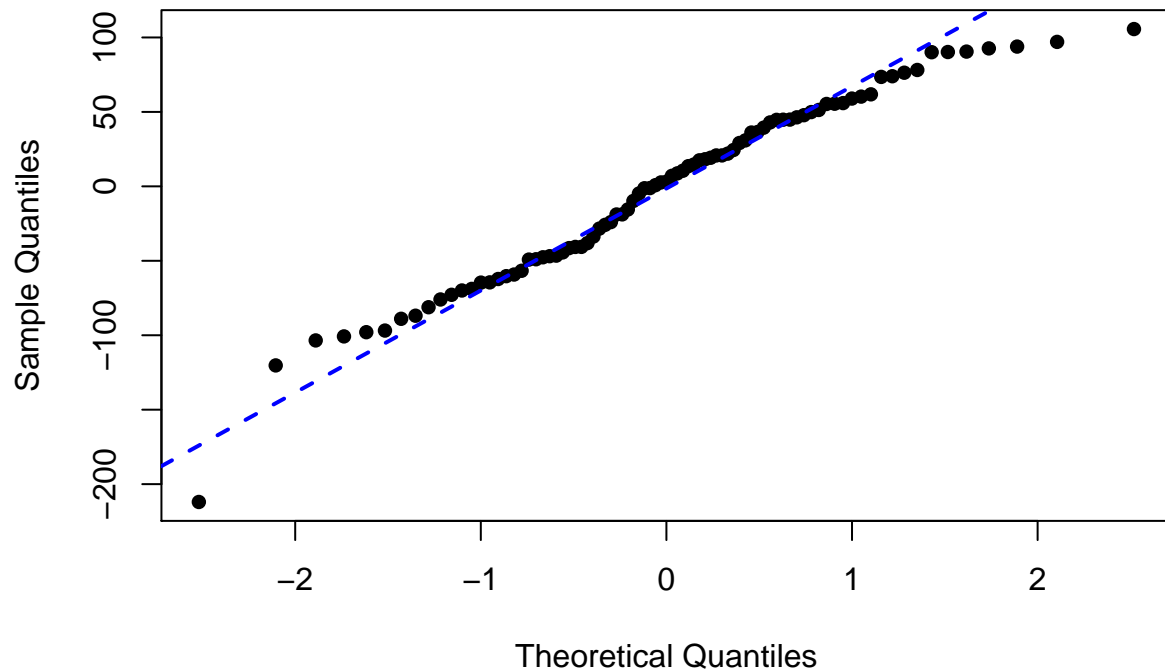
```
plot(x = pred, y = resid, pch = 16, main = "Linear Trend without Outlier", xlab =
  "Piezometric Head Fitted Values (m)", ylab = "Piezometric Head Residuals (m)")
```

Linear Trend without Outlier



```
qqnorm(resid, pch = 16, main = "Linear Trend without Outlier Normal Q-Q Plot")  
qqline(resid, lwd = 2, lty = 2, col = "blue")
```

Linear Trend without Outlier Normal Q-Q Plot



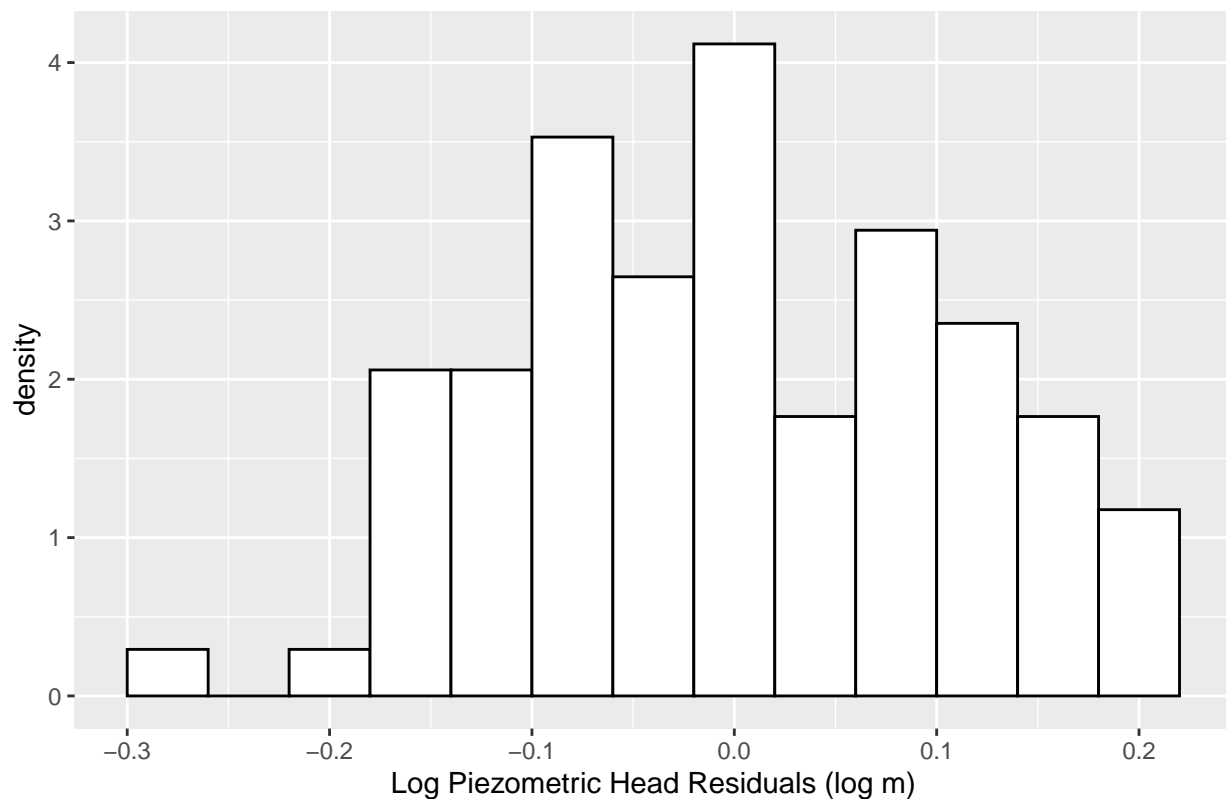
```
# Log-transformed linear model
```

```
mod.z.log = lm(log(z) ~ x + y)
summ.z.log = summary(mod.z.log)
summ.z.log
```

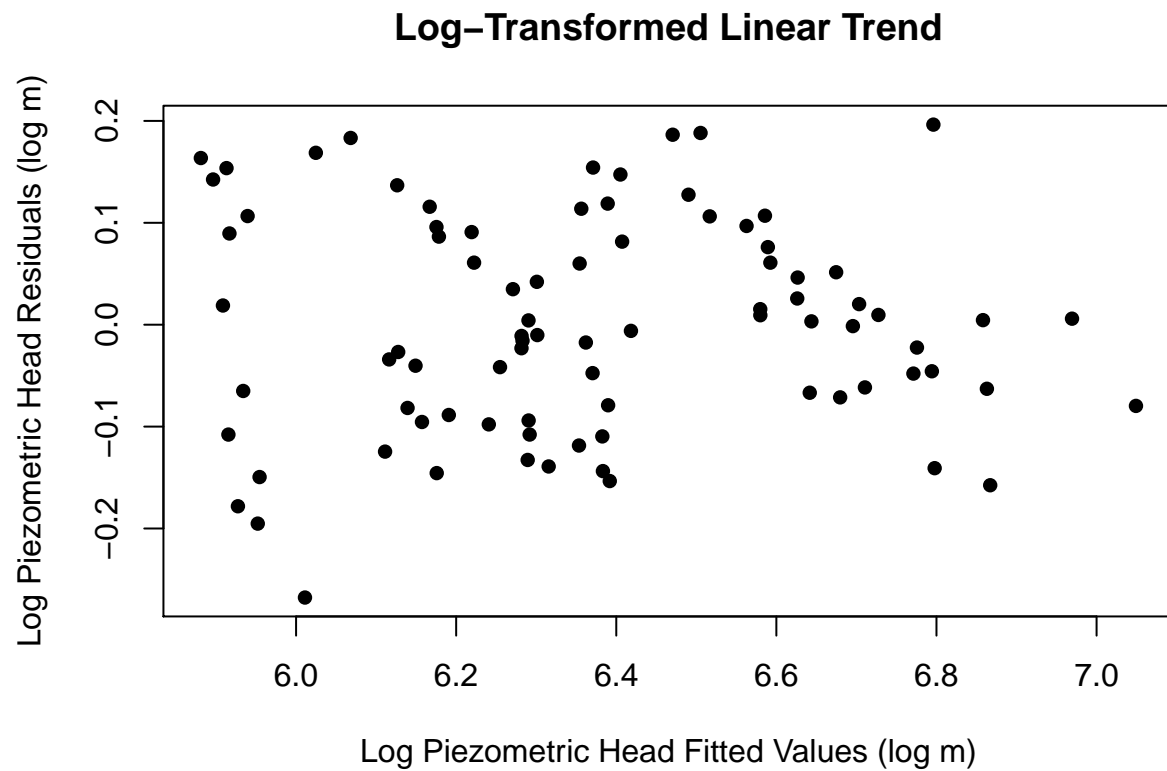
```
##
## Call:
## lm(formula = log(z) ~ x + y)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -0.267750 -0.079684 -0.001379  0.089537  0.196348
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  6.3536945  0.0129129  492.04  <2e-16 ***
## x           -0.0019575  0.0001125  -17.40  <2e-16 ***
## y           -0.0020547  0.0001328  -15.47  <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.1069 on 82 degrees of freedom
## Multiple R-squared:  0.8815, Adjusted R-squared:  0.8786
## F-statistic: 304.9 on 2 and 82 DF,  p-value: < 2.2e-16
```

```
ggplot() + geom_histogram(data = df, aes(x = summ.z.log$residuals, y = ..density..),
  binwidth = 0.04, color = "black", fill = "white") +
  ggtitle("Log-Transformed Linear Trend") + xlab("Log Piezometric Head Residuals (log m)")
```

Log-Transformed Linear Trend

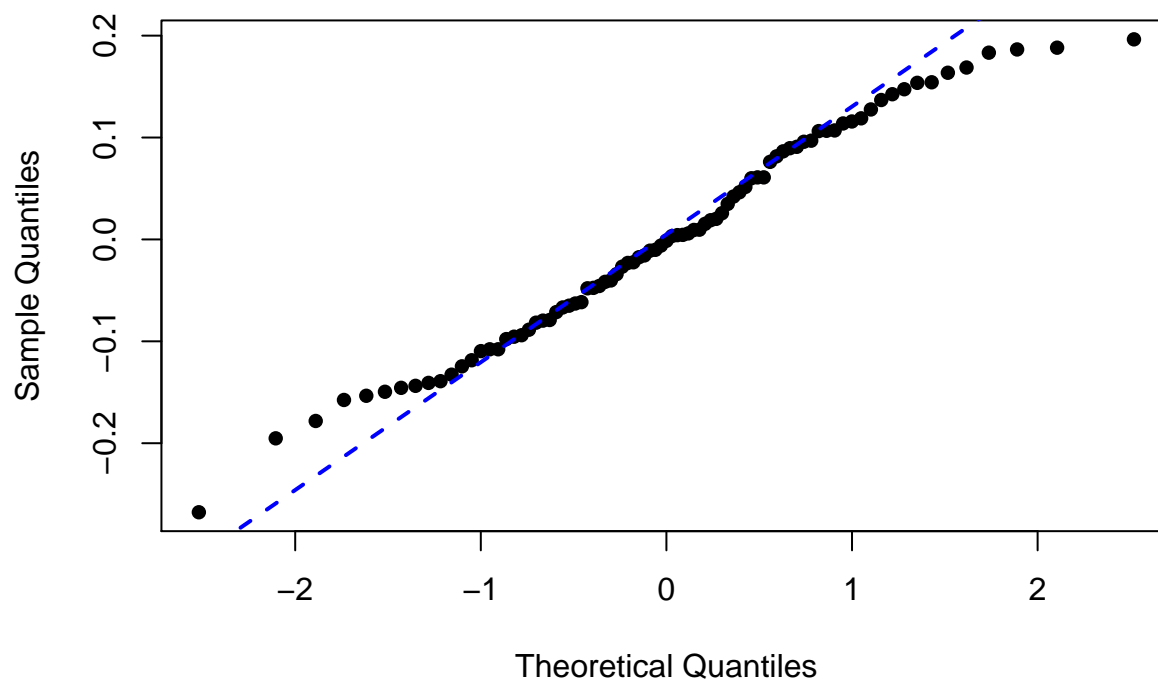


```
plot(x = mod.z.log$fitted.values, y = summ.z.log$residuals, pch = 16, main =
"Log-Transformed Linear Trend", xlab = "Log Piezometric Head Fitted Values (log m)",
ylab = "Log Piezometric Head Residuals (log m)")
```

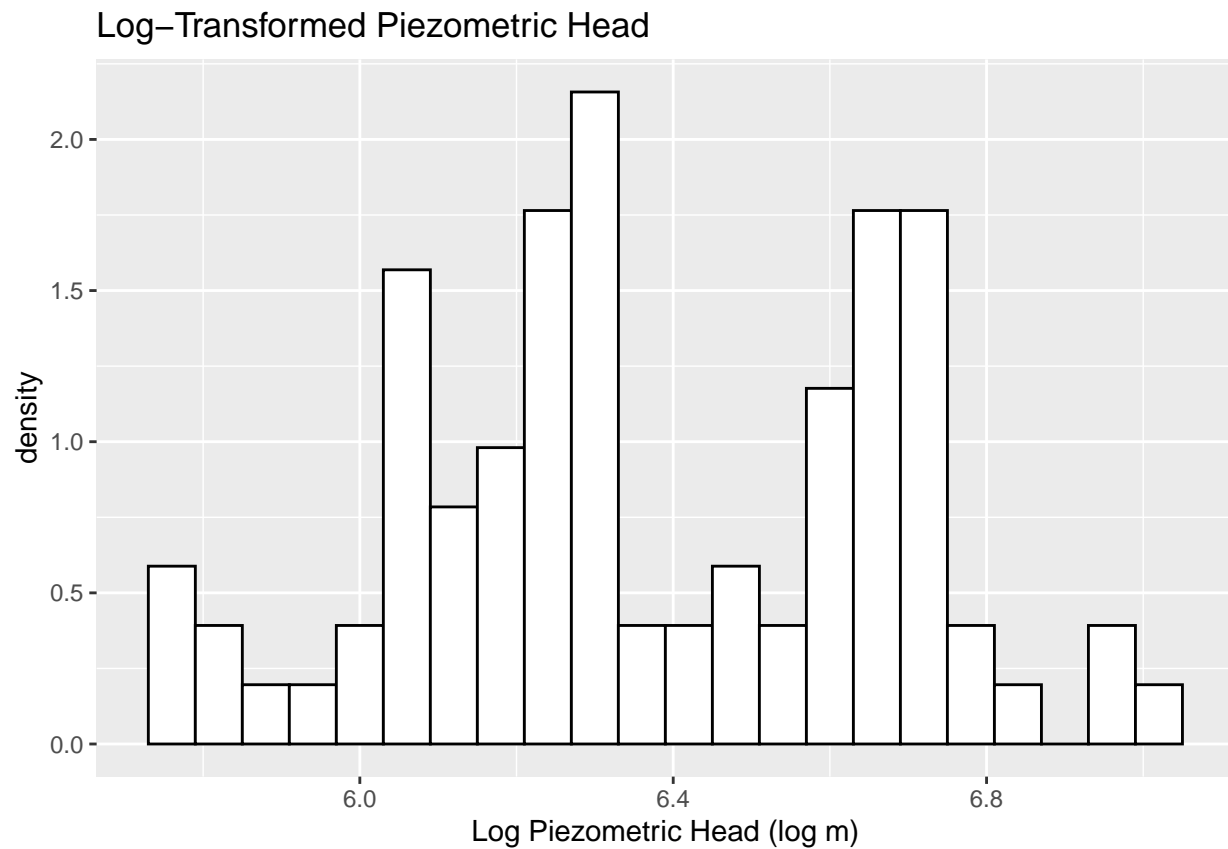


```
qqnorm(summ.z.log$residuals, pch = 16, main =
"Log-Transformed Linear Trend Normal Q-Q Plot")
qqline(summ.z.log$residuals, lwd = 2, lty = 2, col = "blue")
```

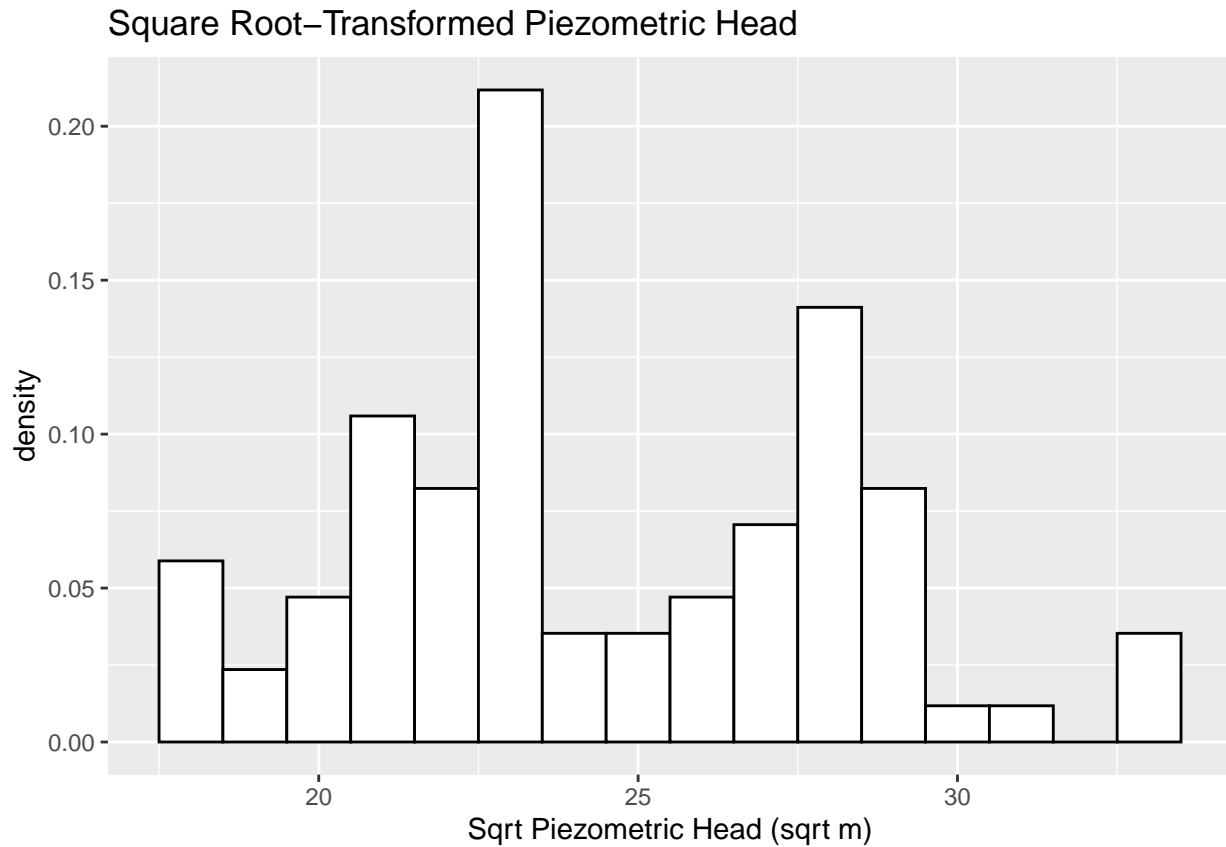
Log-Transformed Linear Trend Normal Q-Q Plot



```
# Log transform  
ggplot() + geom_histogram(data = df, aes(x = log(z), y = ..density..), binwidth = 0.06,  
  color = "black", fill = "white") + ggtitle("Log-Transformed Piezometric Head") +  
  xlab("Log Piezometric Head (log m)")
```



```
# Square root transform  
ggplot() + geom_histogram(data = df, aes(x = sqrt(z), y = ..density..), binwidth = 1,  
  color = "black", fill = "white") + ggtitle("Square Root-Transformed Piezometric Head") +  
  xlab("Sqrt Piezometric Head (sqrt m)")
```

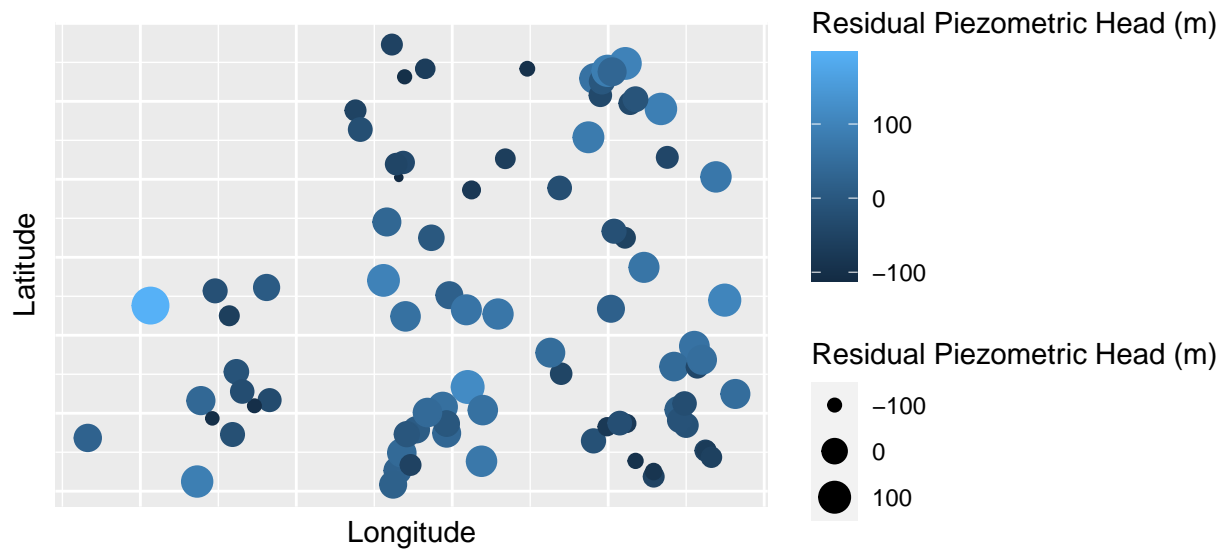


```
#####
# Residual Analysis
#####

# Spatial plot of the residuals

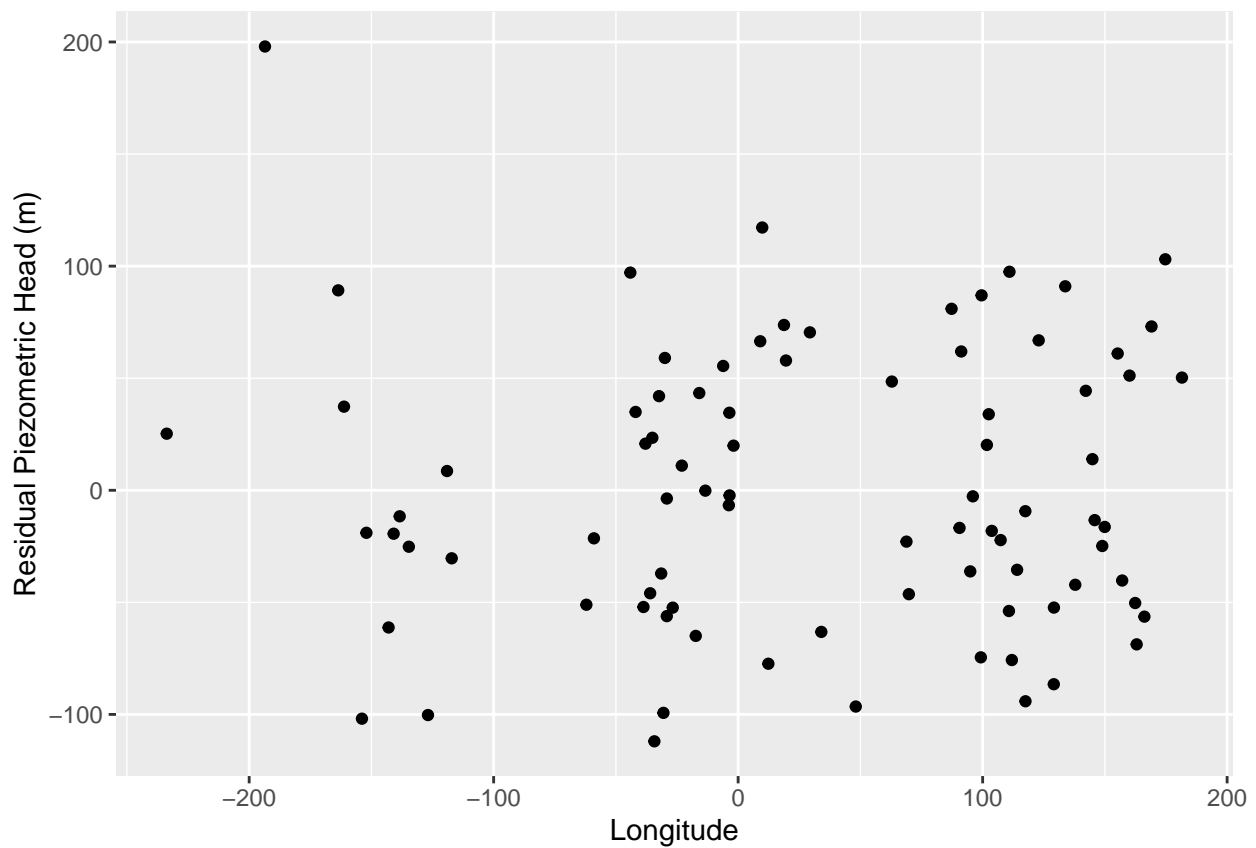
z.trend = mod.z$fitted.values
z.resid = summ.z$residuals

df = data.frame(lat = y, long = x, Z = z.resid)
p = ggplot() + geom_point(data = df, aes(x = long, y = lat, size = Z, color = Z))
p = p + labs(x = "Longitude", y = "Latitude", size = "Residual Piezometric Head (m)",
  colour = "Residual Piezometric Head (m)") + coord_fixed()
p = p + theme(axis.text.x = element_blank(), axis.text.y = element_blank(), axis.ticks =
  element_blank())
p
```

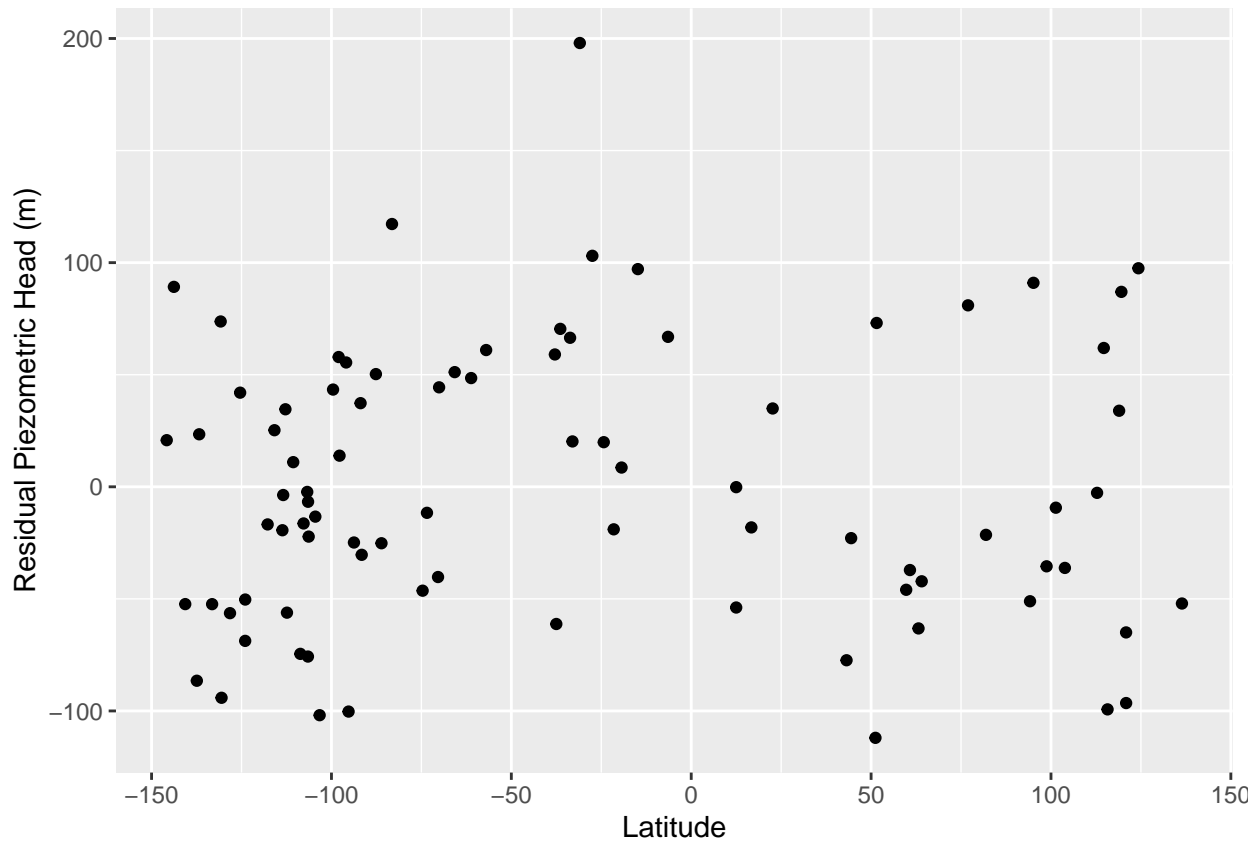



```
# Plot the residuals against latitude and longitude
```

```
df = data.frame(X = x, Y = y, Z = z.resid)
ggplot(df, aes(X, Z)) + geom_point() + ylab("Residual Piezometric Head (m)") +
  xlab("Longitude")
```



```
ggplot(df, aes(Y, Z)) + geom_point() + ylab("Residual Piezometric Head (m)") +
  xlab("Latitude")
```



```
# Storing the data

wolfcamp.orig = wolfcamp
wolfcamp$data = z.resid

# Prediction intervals for linear trend

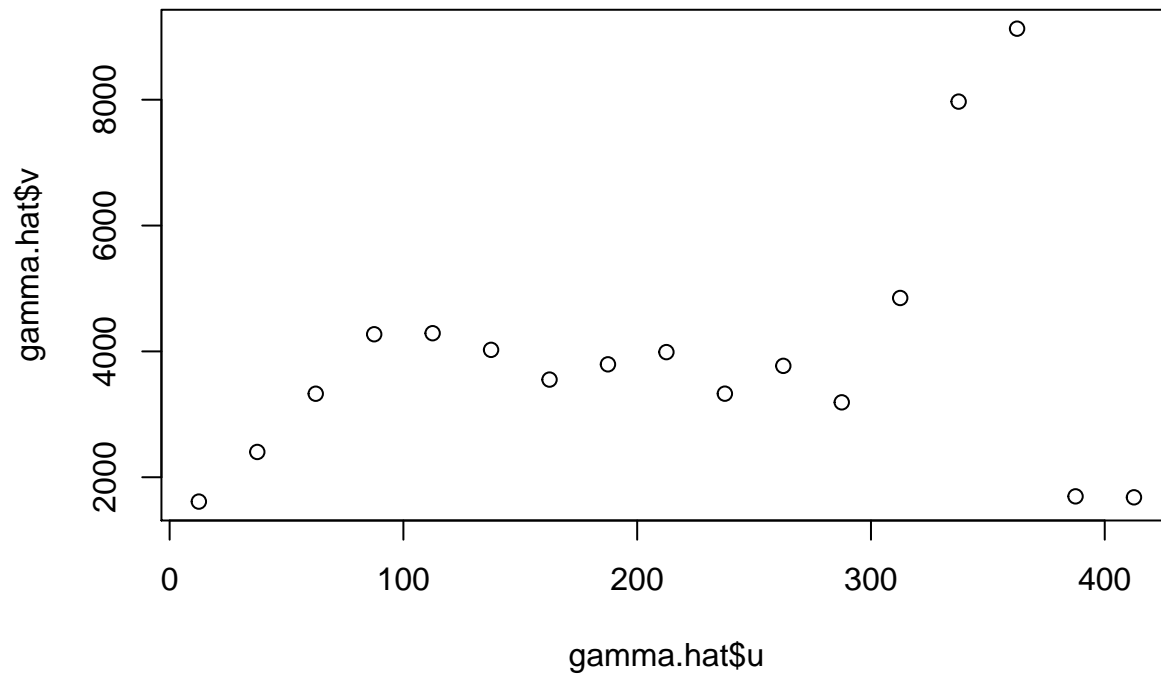
pred = predict(mod.z, newdata = data.frame(x = grid[,1], y = grid[,2]), interval =
  "prediction", level = 0.95)
pred.point = pred[,1]
pred.sd = (pred[,3] - pred[,1]) / qnorm(0.975)

#####
# Empirical Variogram & Covariance
#####

# Empirical Variogram

breaks = seq(0, 500, 25)
gamma.hat = variog(wolfcamp, breaks = breaks, estimator.type = "classical")

## variog: computing omnidirectional variogram
plot(x = gamma.hat$u, y = gamma.hat$v)
```



```
gamma.hat$n
```

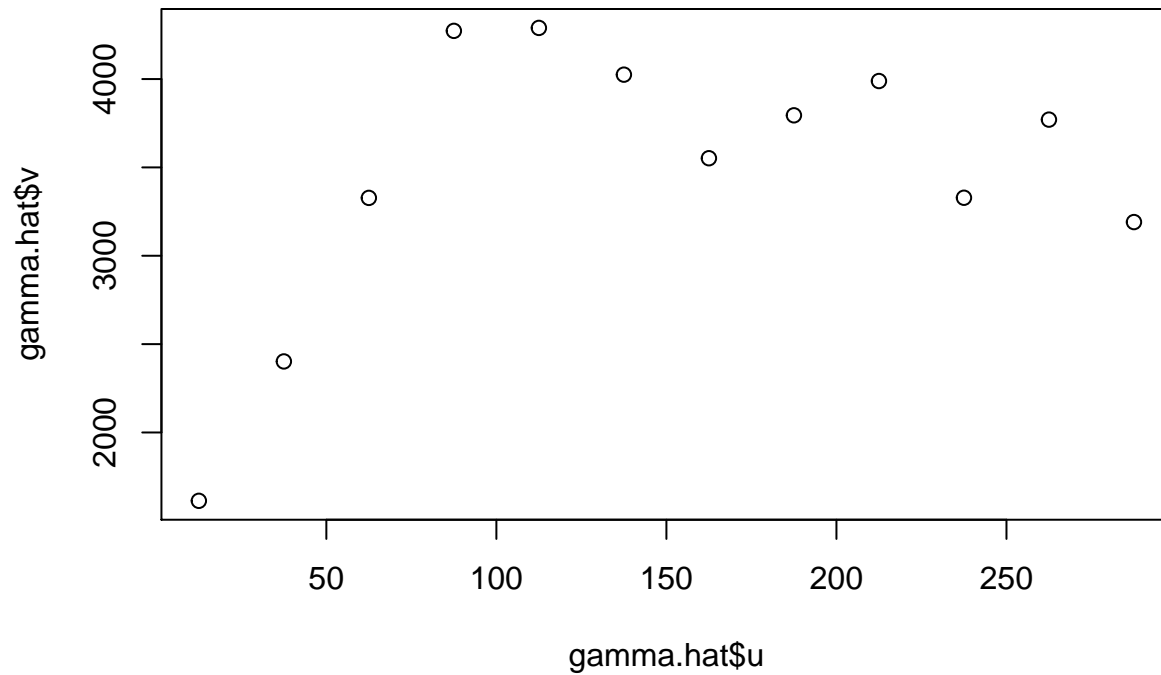
```
## [1] 110 213 205 243 292 347 451 391 307 282 262 186 148 76 29 16 11
```

```
breaks = seq(0, 300, 25)
```

```
gamma.hat = variog(wolfcamp, breaks = breaks, estimator.type = "classical")
```

```
## variog: computing omnidirectional variogram
```

```
plot(x = gamma.hat$u, y = gamma.hat$v)
```



```
gamma.hat$n
```

```
## [1] 110 213 205 243 292 347 451 391 307 282 262 186
breaks = c(seq(0, 200, 25), 250, 300)

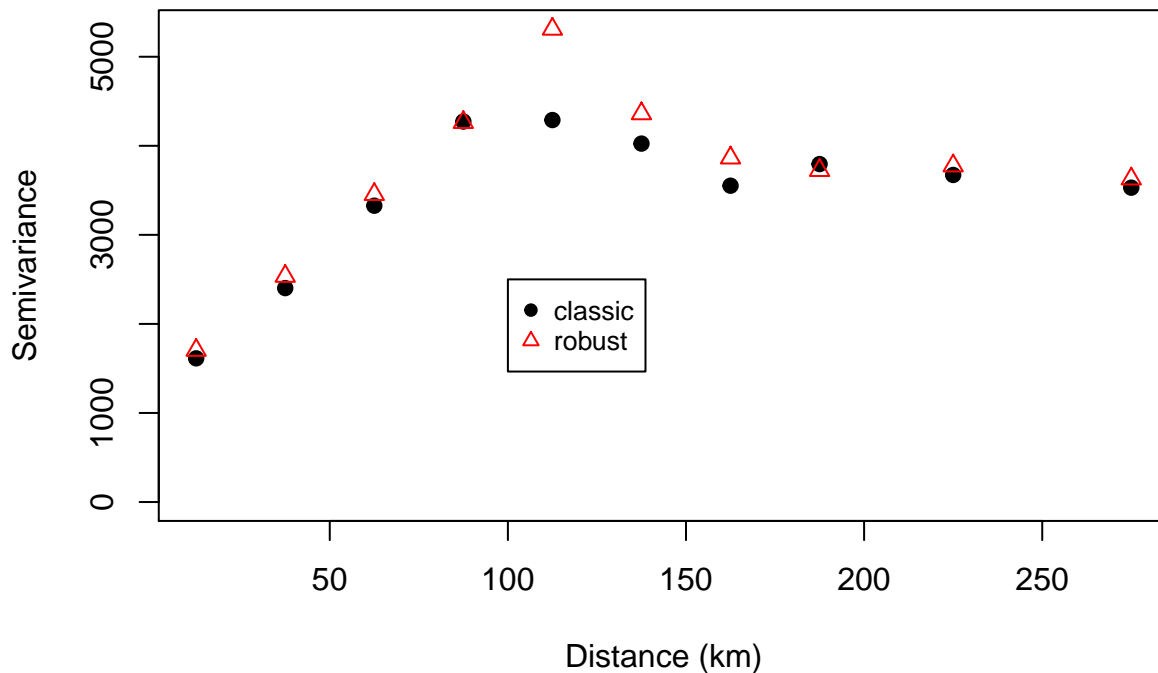
gamma.hat = variog(wolfcamp, breaks = breaks, estimator.type = "classical")

## variog: computing omnidirectional variogram
gamma.bar = variog(wolfcamp, breaks = breaks, estimator.type = "modulus")

## variog: computing omnidirectional variogram
gamma.hat$n

## [1] 110 213 205 243 292 347 451 391 589 448
plot(x = gamma.hat$u, y = gamma.hat$v, pch = 19, ylim = c(0, max(gamma.hat$v,
gamma.bar$v)), main = "Variogram Estimation", xlab = "Distance (km)", ylab =
"Semivariance")
points(x = gamma.bar$u, y = gamma.bar$v, pch = 2, col = "red")
legend(100, 2500, pch = c(19,2), c("classic", "robust"), cex = 0.8, col = c("black",
"red"))
```

Variogram Estimation



```
# Empirical covariance
get.points.indices = function(x, y, min.dist, max.dist)
{
  pts.1 = NULL
  pts.2 = NULL

  for (i in 1:length(x))
  {
    for (j in i:length(x))
```

```

    {
      dist = sqrt((x[i] - x[j])**2 + (y[i] - y[j])**2)
      if (min.dist < dist & dist <= max.dist)
      {
        pts.1 = c(pts.1, i)
        pts.2 = c(pts.2, j)
      }
    }
  }

  return(cbind(pts.1, pts.2))
}

compute.c.hat = function(x, y, z, breaks)
{
  if (breaks[1] > 0)
    breaks = c(0, breaks)

  n = NULL
  c = NULL

  for (i in 1:(length(breaks)-1))
  {
    points = get.points.indices(x, y, breaks[i], breaks[i+1])
    n = c(n, length(points[,1]))
    c = c(c, sum(z[points[,1]] * z[points[,2]]) / n[i])
  }

  u = NULL
  for (i in 1:(length(breaks)-1))
    u = c(u, (breaks[i] + breaks[i+1]) / 2)

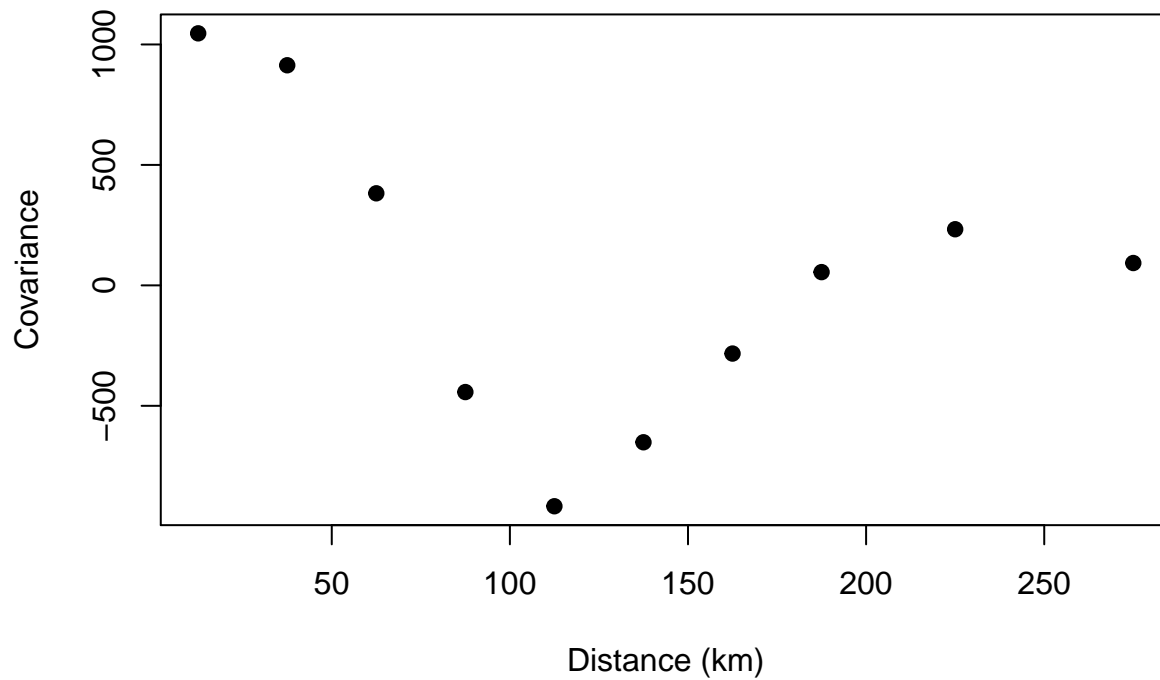
  ret = list(u = u, c = c, n = n)
  return(ret)
}

# Compute & plot covariance

c.hat = compute.c.hat(x, y, wolfcamp$data, breaks)
plot(x = c.hat$u, y = c.hat$c, pch = 19, ylim = c(min(c.hat$c), max(c.hat$c)), main =
  "Covariance Estimation", xlab = "Distance (km)", ylab = "Covariance")

```

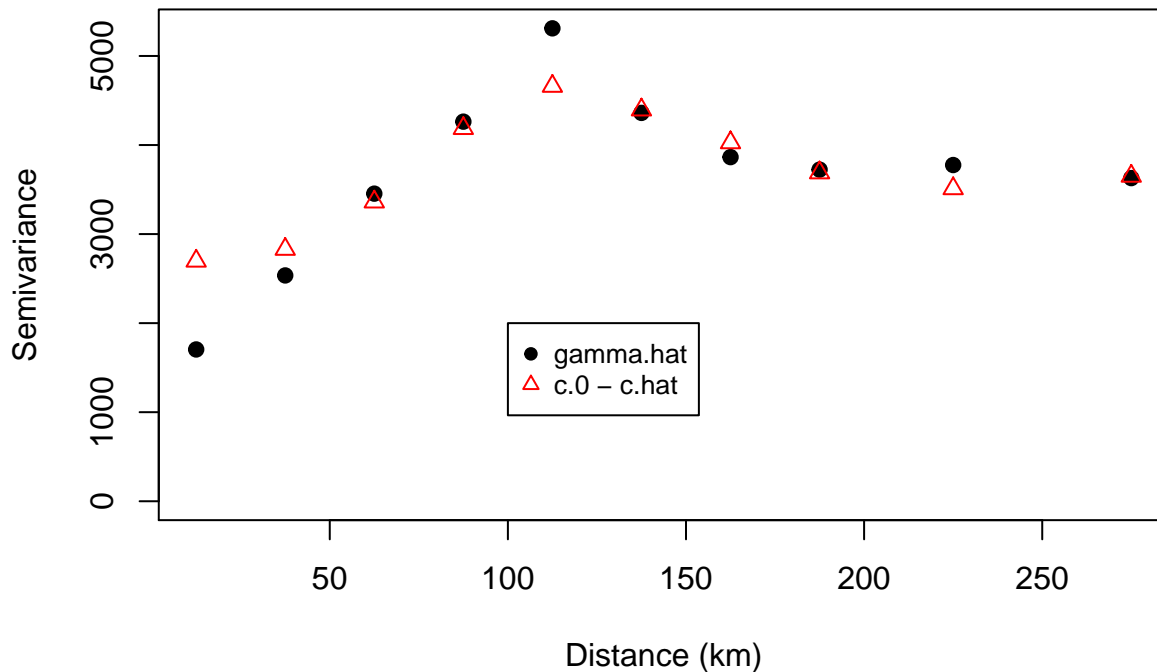
Covariance Estimation



Compute & plot methods of estimating variogram

```
c.0 = sum(wolfcamp$data**2) / length(wolfcamp$data)
plot(x = gamma.bar$u, y = gamma.bar$v, pch = 19, ylim = c(0, max(gamma.bar$v, c.0 -
  c.hat$c)), main = "Estimation of Variogram", xlab = "Distance (km)", ylab = "Semivariance")
points(x = c.hat$u, y = c.0 - c.hat$c, pch = 2, col = "red")
legend(100, 2000, pch = c(19,2), c("gamma.hat", "c.0 - c.hat"), cex = 0.8, col =
  c("black", "red"))
```

Estimation of Variogram



```
#####
# Directional Variogram & Covariance
#####

# Compute directional variogram

par(mfrow = c(1,1))
gamma.hat.a0 = variog(wolfcamp, estimator.type = "modulus", breaks = breaks,
  direction = 0)

## variog: computing variogram for direction = 0 degrees (0 radians)
##      tolerance angle = 22.5 degrees (0.393 radians)

gamma.hat.a45 = variog(wolfcamp, estimator.type = "modulus", breaks = breaks,
  direction = pi/4)

## variog: computing variogram for direction = 45 degrees (0.785 radians)
##      tolerance angle = 22.5 degrees (0.393 radians)

gamma.hat.a90 = variog(wolfcamp, estimator.type = "modulus", breaks = breaks,
  direction = pi/2)

## variog: computing variogram for direction = 90 degrees (1.571 radians)
##      tolerance angle = 22.5 degrees (0.393 radians)

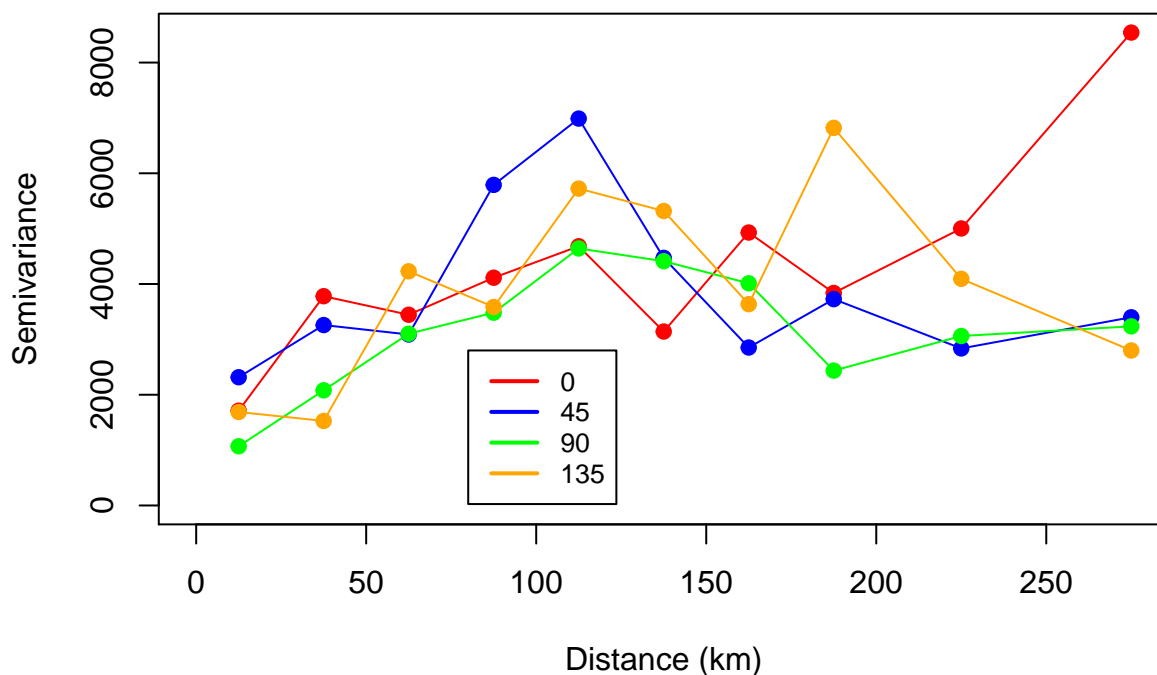
gamma.hat.a135 = variog(wolfcamp, estimator.type = "modulus", breaks = breaks,
  direction = 3/4*pi)

## variog: computing variogram for direction = 135 degrees (2.356 radians)
##      tolerance angle = 22.5 degrees (0.393 radians)
```

```
# Plot directional variogram
```

```
par(mfrow = c(1,1))
max.x = max(c(gamma.hat.a0$u, gamma.hat.a45$u, gamma.hat.a90$u, gamma.hat.a135$u))
min.y = min(c(gamma.hat.a0$v, gamma.hat.a45$v, gamma.hat.a90$v, gamma.hat.a135$v))
max.y = max(c(gamma.hat.a0$v, gamma.hat.a45$v, gamma.hat.a90$v, gamma.hat.a135$v))
plot(gamma.hat.a0, col = "red", pch = 19, type = "o", xlim = c(0, max.x), ylim =
     c(0, max.y), main = "Directional Variogram", xlab = "Distance (km)", ylab =
     "Semivariance")
lines(gamma.hat.a45, col = "blue", pch = 19, type = "o")
lines(gamma.hat.a90, col = "green", pch = 19, type = "o")
lines(gamma.hat.a135, col = "orange", pch = 19, type = "o")
legend(80, 2800, col = c("red", "blue", "green", "orange"), c(0, 45, 90, 135), lwd =
     c(2, 2, 2, 2), cex = 0.8)
```

Directional Variogram



```
# Effect of decreasing tolerance angle
```

```
gamma.hat.a0 = variog(wolfcamp, estimator.type = "modulus", breaks = breaks,
     direction = 0, tolerance = pi/16)
```

```
## variog: computing variogram for direction = 0 degrees (0 radians)
##      tolerance angle = 11.25 degrees (0.196 radians)
```

```
gamma.hat.a45 = variog(wolfcamp, estimator.type = "modulus", breaks = breaks,
     direction = pi/4, tolerance = pi/16)
```

```
## variog: computing variogram for direction = 45 degrees (0.785 radians)
##      tolerance angle = 11.25 degrees (0.196 radians)
```

```
gamma.hat.a90 = variog(wolfcamp, estimator.type = "modulus", breaks = breaks,
     direction = pi/2, tolerance = pi/16)
```



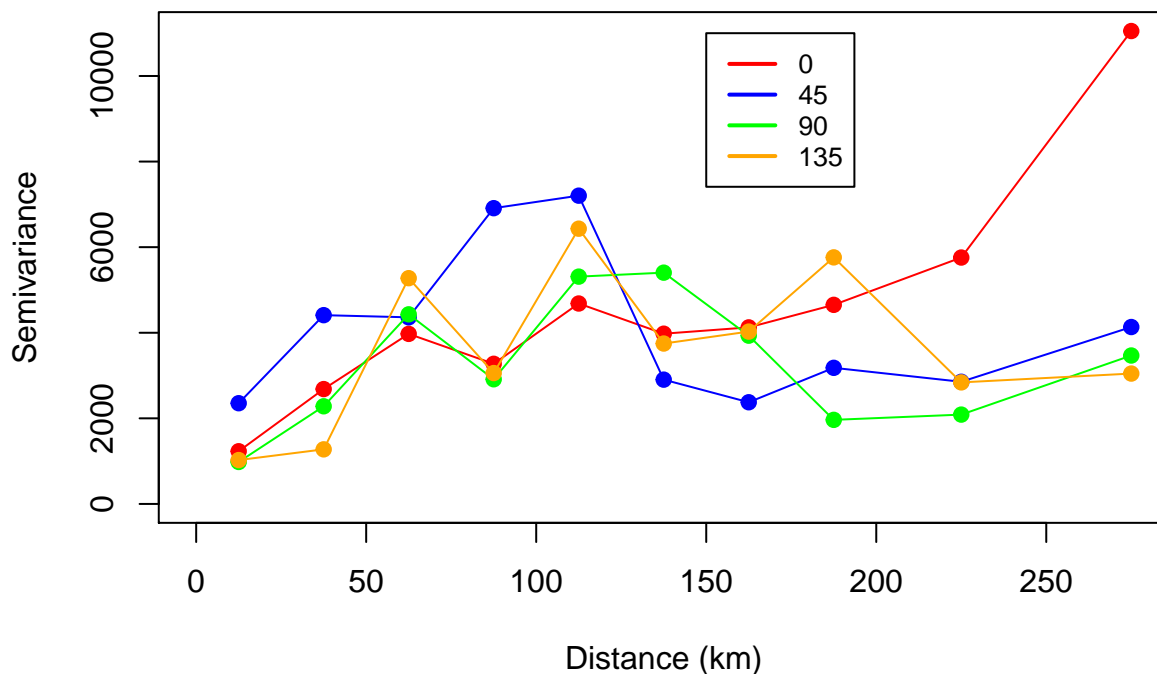
```
## variog: computing variogram for direction = 90 degrees (1.571 radians)
##      tolerance angle = 11.25 degrees (0.196 radians)

gamma.hat.a135 = variog(wolfcamp, estimator.type = "modulus", breaks = breaks,
  direction = 3/4*pi, tolerance = pi/16)

## variog: computing variogram for direction = 135 degrees (2.356 radians)
##      tolerance angle = 11.25 degrees (0.196 radians)

max.x = max(c(gamma.hat.a0$u, gamma.hat.a45$u, gamma.hat.a90$u, gamma.hat.a135$u))
min.y = min(c(gamma.hat.a0$v, gamma.hat.a45$v, gamma.hat.a90$v, gamma.hat.a135$v))
max.y = max(c(gamma.hat.a0$v, gamma.hat.a45$v, gamma.hat.a90$v, gamma.hat.a135$v))
plot(gamma.hat.a0, col = "red", pch = 19, type = "o", xlim = c(0, max.x), ylim =
  c(0, max.y), main = "Directional Variogram", xlab = "Distance (km)", ylab =
  "Semivariance")
lines(gamma.hat.a45, col = "blue", pch = 19, type = "o")
lines(gamma.hat.a90, col = "green", pch = 19, type = "o")
lines(gamma.hat.a135, col = "orange", pch = 19, type = "o")
legend(150, 11000, col = c("red", "blue", "green", "orange"), c(0, 45, 90, 135),
  lwd = c(2, 2, 2, 2), cex = 0.8)
```

Directional Variogram



```
# Manual function for directional covariance

get.points.indices.directional = function(x, y, min.dist, max.dist, angle,
  tolerance = pi/8)
{
  pts.1 = NULL
  pts.2 = NULL

  for (i in 1:(length(x)-1))
  {
```

```

for (j in (i+1):length(x))
{
  dist = sqrt((x[i] - x[j])**2 + (y[i] - y[j])**2)
  ang = atan((y[j] - y[i]) / (x[j] - x[i]))
  if (ang < 0)
    ang = ang + pi
  if (angle - tolerance < 0)
    angle.cond = (angle - tolerance <= ang & ang <= angle + tolerance) |
      (angle - tolerance + pi <= ang & ang <= angle + tolerance + pi)
  else if (angle + tolerance > pi)
    angle.cond = (angle - tolerance <= ang & ang <= angle + tolerance) |
      (angle - tolerance - pi <= ang & ang <= angle + tolerance - pi)
  else
    angle.cond = angle - tolerance <= ang & ang <= angle + tolerance
  if (angle.cond & min.dist < dist & dist <= max.dist)
  {
    pts.1 = c(pts.1, i)
    pts.2 = c(pts.2, j)
  }
}
}

return(cbind(pts.1, pts.2))
}

compute.c.hat.directional = function(x, y, z, breaks, angle, tolerance = pi/8,
  angle.type = "radian")
{
  if (angle.type == "degree")
  {
    angle = angle * pi / 180
    tolerance = tolerance * pi / 180
  }

  if (breaks[1] > 0)
    breaks = c(0, breaks)

  n = NULL
  c = NULL

  for (i in 1:(length(breaks)-1))
  {
    points = get.points.indices.directional(x, y, breaks[i], breaks[i+1], angle,
      tolerance)
    n = c(n, length(points[,1]))
    c = c(c, sum(z[points[,1]] * z[points[,2]]) / n[i] / 2)
  }

  u = NULL
  for (i in 1:(length(breaks)-1))
    u = c(u, (breaks[i] + breaks[i+1]) / 2)

  ret = list(u = u, c = c, n = n)

```

```

return(ret)
}

# Compute directional covariance

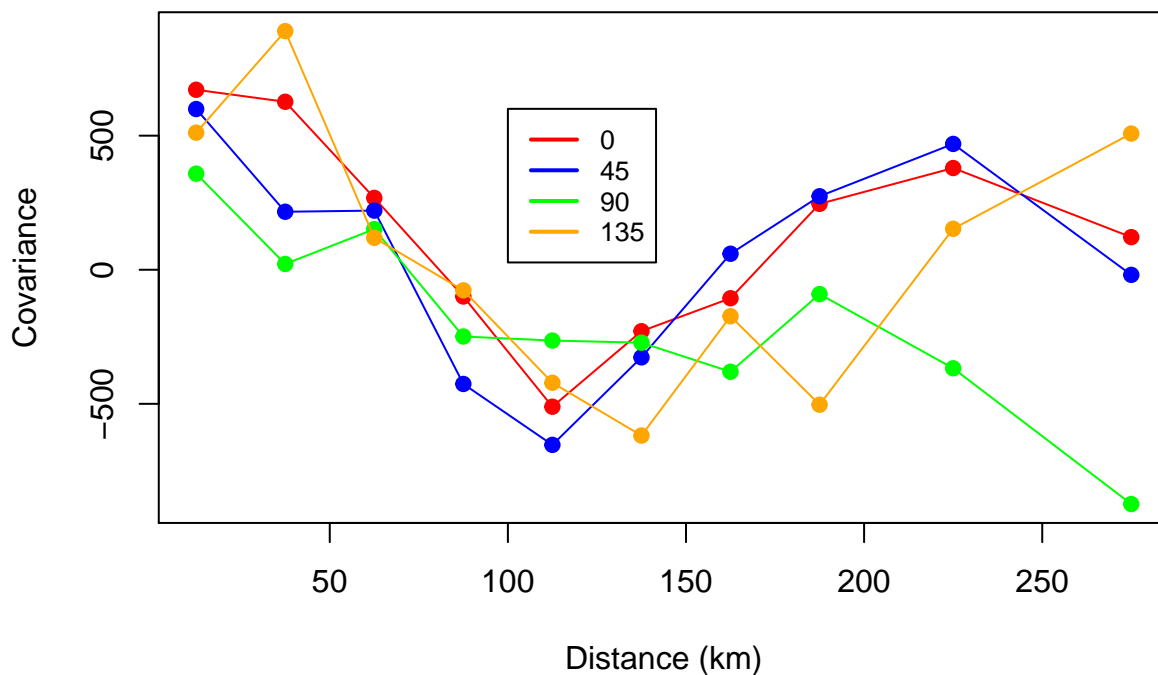
c.hat.a0 = compute.c.hat.directional(x, y, wolfcamp$data, breaks, 0)
c.hat.a45 = compute.c.hat.directional(x, y, wolfcamp$data, breaks, pi/4)
c.hat.a90 = compute.c.hat.directional(x, y, wolfcamp$data, breaks, pi/2)
c.hat.a135 = compute.c.hat.directional(x, y, wolfcamp$data, breaks, pi*3/4)

# Plot directional covariance

min.val = min(na.omit(c(c.hat.a0$c, c.hat.a45$c, c.hat.a90$c, c.hat.a135$c)))
max.val = max(na.omit(c(c.hat.a0$c, c.hat.a45$c, c.hat.a90$c, c.hat.a135$c)))
plot(x = c.hat.a0$u, y = c.hat.a0$c, pch = 19, type = "o", col = "red", ylim =
     c(min.val, max.val), main = "Directional Covariance Estimation", xlab = "Distance (km)",
     ylab = "Covariance")
lines(x = c.hat.a45$u, y = c.hat.a45$c, pch = 19, type = "o", col = "blue")
lines(x = c.hat.a90$u, y = c.hat.a90$c, pch = 19, type = "o", col = "green")
lines(x = c.hat.a135$u, y = c.hat.a135$c, pch = 19, type = "o", col = "orange")
legend(100, 600, col = c("red", "blue", "green", "orange"), c(0, 45, 90, 135), lwd =
      c(2, 2, 2, 2), cex = 0.8)

```

Directional Covariance Estimation



```

#####
# Variogram Fitting
#####

# Computes the sum of squared errors for the first three points for a given
# variogram

```

```

sse3 = function(v, u, points)
{

  u = u[1:3]
  points = points[1:3]

  tausq = v$nugget
  sigmasq = v$cov.pars[1]
  phi = 1/v$cov.pars[2]

  if (v$cov.model == "linear")
    pred = tausq + sigmasq * u
  else
  {
    if (v$cov.model == "spherical")
      pred = tausq + sigmasq * (3/2*phi*u - 1/2*(phi*u)**3)
    else
    {
      if (v$cov.model == "matern")
      {
        nu = v$kappa
        pred = tausq + sigmasq * (1 - ((phi * u)**nu)/(2**(nu-1) * gamma(nu)) *
          besselK(phi * u, nu))
      }
      else
      {
        if (v$cov.model == "wave")
          pred = tausq + sigmasq * (1 - sin(phi * u) / (phi * u))
        }
      }
    }

    return(sum((points-pred)**2))
  }

}

# Cressie-style weights

gamma.hat.lin = variofit(gamma.bar, cov.model = "linear", fix.nugget = FALSE, weights =
  "cressie")

## variofit: covariance model used is linear
## variofit: weights used: cressie
## variofit: minimisation function used: optim
## variofit: searching for best initial value ... selected values:
##           sigmasq  phi  tausq    kappa
## initial.value "3982.66" "0"  "2655.11" "0.5"
## status        "est"    "est" "est"    "fix"
## loss value: 180.495668104337

gamma.hat.sph = variofit(gamma.bar, cov.model = "spherical", fix.nugget = FALSE, weights =
  "cressie")

## variofit: covariance model used is spherical
## variofit: weights used: cressie

```

```

## variofit: minimisation function used: optim
## variofit: searching for best initial value ... selected values:
##          sigmasq  phi   tausq   kappa
## initial.value "2655.11" "88"  "1327.55" "0.5"
## status        "est"    "est" "est"    "fix"
## loss value: 49.5154401042739

gamma.hat.mat = variofit(gamma.bar, cov.model = "matern", fix.nugget = FALSE, kap = 1.5,
  fix.kappa = FALSE, weights = "cressie")

## variofit: covariance model used is matern
## variofit: weights used: cressie
## variofit: minimisation function used: optim
## variofit: searching for best initial value ... selected values:
##          sigmasq  phi   tausq kappa
## initial.value "3982.66" "44"  "0"    "0.25"
## status        "est"    "est" "est"  "est"
## loss value: 66.1405408022394

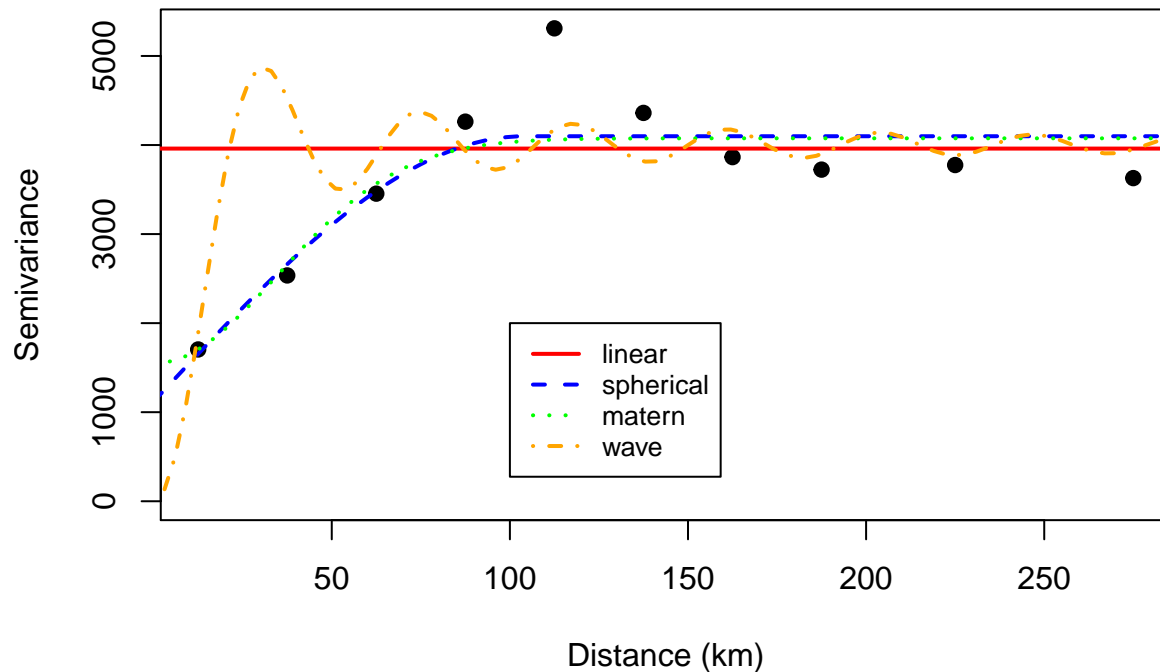
gamma.hat.wav = variofit(gamma.bar, cov.model = "wave", fix.nugget = FALSE, weights =
  "cressie")

## variofit: covariance model used is wave
## variofit: weights used: cressie
## variofit: minimisation function used: optim
## variofit: searching for best initial value ... selected values:
##          sigmasq  phi   tausq kappa
## initial.value "3982.66" "0"    "0"    "0.5"
## status        "est"    "est" "est"  "fix"
## loss value: 111.687695012793

plot(x = gamma.bar$u, y = gamma.bar$v, ylim = c(0, max(gamma.bar$v)), pch = 19, main =
  "Variogram Estimation", xlab = "Distance (km)", ylab = "Semivariance")
lines(gamma.hat.lin, col = "red", lwd = 2, lty = 1)
lines(gamma.hat.sph, col = "blue", lwd = 2, lty = 2)
lines(gamma.hat.mat, col = "green", lwd = 2, lty = 3)
lines(gamma.hat.wav, col = "orange", lwd = 2, lty = 4)
legend(100, 2000, col = c("red", "blue", "green", "orange"), c("linear", "spherical",
  "matern", "wave"), lty = c(1,2,3,4), cex = 0.8, lwd = 2)

```

Variogram Estimation



```
sse3(gamma.hat.lin, gamma.bar$u, gamma.bar$v)
```

```
## [1] 7375242
```

```
sse3(gamma.hat.sph, gamma.bar$u, gamma.bar$v)
```

```
## [1] 19263.89
```

```
sse3(gamma.hat.mat, gamma.bar$u, gamma.bar$v)
```

```
## [1] 27655.26
```

```
sse3(gamma.hat.wav, gamma.bar$u, gamma.bar$v)
```

```
## [1] 4193901
```

```
# npairs weights
```

```
gamma.hat.lin = variofit(gamma.bar, cov.model = "linear", fix.nugget = FALSE, weights =  
"npairs")
```

```
## variofit: covariance model used is linear
```

```
## variofit: weights used: npairs
```

```
## variofit: minimisation function used: optim
```

```
## variofit: searching for best initial value ... selected values:
```

```
##          sigmasq  phi  tausq    kappa
```

```
## initial.value "2655.11" "0"  "2655.11" "0.5"
```

```
## status       "est"    "est" "est"    "fix"
```

```
## loss value: 2223265315.2117
```

```
gamma.hat.sph = variofit(gamma.bar, cov.model = "spherical", fix.nugget = FALSE, weights =  
"npairs")
```

```

## variofit: covariance model used is spherical
## variofit: weights used: npairs
## variofit: minimisation function used: optim
## variofit: searching for best initial value ... selected values:
##          sigmasq  phi   tausq   kappa
## initial.value "2655.11" "88"  "1327.55" "0.5"
## status        "est"    "est" "est"    "fix"
## loss value: 743331518.638569

gamma.hat.mat = variofit(gamma.bar, cov.model = "matern", fix.nugget = FALSE, kap = 1.5,
  fix.kappa = FALSE, weights = "npairs")

## variofit: covariance model used is matern
## variofit: weights used: npairs
## variofit: minimisation function used: optim
## variofit: searching for best initial value ... selected values:
##          sigmasq  phi   tausq  kappa
## initial.value "3982.66" "44"   "0"   "0.25"
## status        "est"    "est" "est"  "est"
## loss value: 930429289.904966

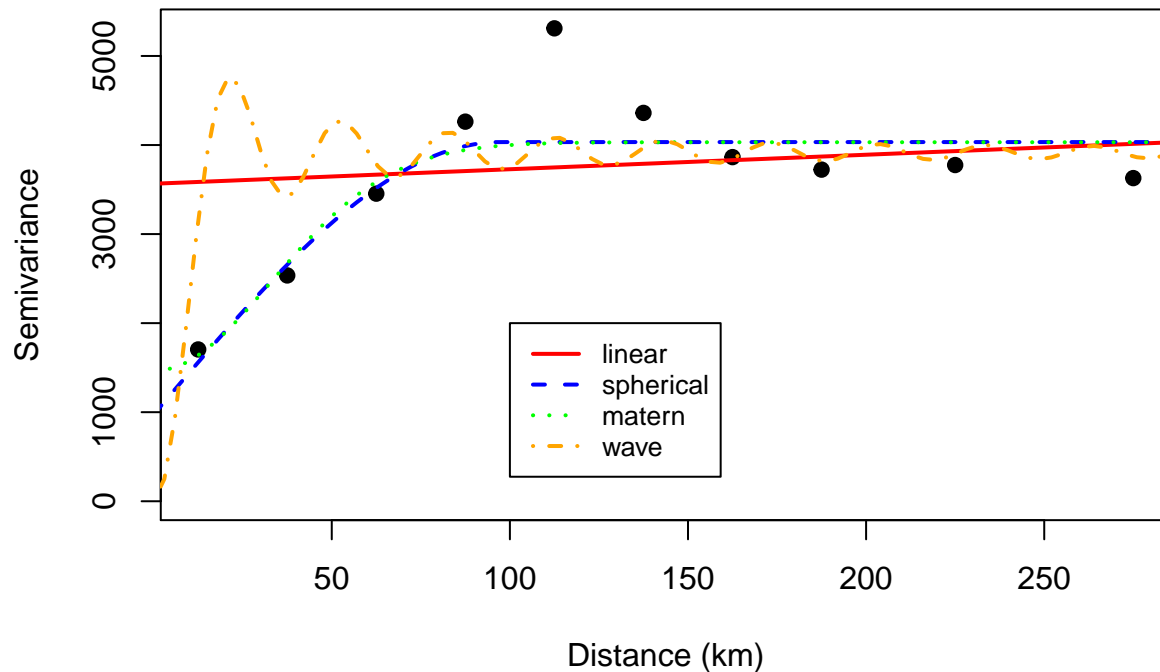
gamma.hat.wav = variofit(gamma.bar, cov.model = "wave", fix.nugget = FALSE, weights =
  "npairs")

## variofit: covariance model used is wave
## variofit: weights used: npairs
## variofit: minimisation function used: optim
## variofit: searching for best initial value ... selected values:
##          sigmasq  phi   tausq  kappa
## initial.value "3982.66" "0"    "0"   "0.5"
## status        "est"    "est" "est"  "fix"
## loss value: 1771543383.49173

plot(x = gamma.bar$u, y = gamma.bar$v, ylim = c(0, max(gamma.bar$v)), pch = 19, main =
  "Variogram Estimation", xlab = "Distance (km)", ylab = "Semivariance")
lines(gamma.hat.lin, col = "red", lwd = 2, lty = 1)
lines(gamma.hat.sph, col = "blue", lwd = 2, lty = 2)
lines(gamma.hat.mat, col = "green", lwd = 2, lty = 3)
lines(gamma.hat.wav, col = "orange", lwd = 2, lty = 4)
legend(100, 2000, col = c("red", "blue", "green", "orange"), c("linear", "spherical",
  "matern", "wave"), lty = c(1,2,3,4), cex = 0.8, lwd = 2)

```

Variogram Estimation



```
sse3(gamma.hat.lin, gamma.bar$u, gamma.bar$v)
```

```
## [1] 4774109
```

```
sse3(gamma.hat.sph, gamma.bar$u, gamma.bar$v)
```

```
## [1] 39309.48
```

```
sse3(gamma.hat.mat, gamma.bar$u, gamma.bar$v)
```

```
## [1] 40557.29
```

```
sse3(gamma.hat.wav, gamma.bar$u, gamma.bar$v)
```

```
## [1] 2976865
```

```
# equal weights
```

```
gamma.hat.lin = variofit(gamma.bar, cov.model = "linear", fix.nugget = FALSE, weights =  
"equal")
```

```
## variofit: covariance model used is linear
```

```
## variofit: weights used: equal
```

```
## variofit: minimisation function used: optim
```

```
## variofit: searching for best initial value ... selected values:
```

```
##          sigmasq  phi  tausq  kappa
```

```
## initial.value "2655.11" "0"  "2655.11" "0.5"
```

```
## status       "est"    "est" "est"    "fix"
```

```
## loss value: 7897271.1287311
```

```
gamma.hat.sph = variofit(gamma.bar, cov.model = "spherical", fix.nugget = FALSE, weights =  
"equal")
```



```

## variofit: covariance model used is spherical
## variofit: weights used: equal
## variofit: minimisation function used: optim
## variofit: searching for best initial value ... selected values:
##          sigmasq  phi   tausq   kappa
## initial.value "2655.11" "88"  "1327.55" "0.5"
## status        "est"    "est" "est"    "fix"
## loss value: 2467946.84838859

gamma.hat.mat = variofit(gamma.bar, cov.model = "matern", fix.nugget = FALSE, kap = 1.5,
  fix.kappa = FALSE, weights = "equal")

## variofit: covariance model used is matern
## variofit: weights used: equal
## variofit: minimisation function used: optim
## variofit: searching for best initial value ... selected values:
##          sigmasq  phi   tausq  kappa
## initial.value "3982.66" "44"   "0"   "0.25"
## status        "est"    "est" "est"  "est"
## loss value: 3173972.67459355

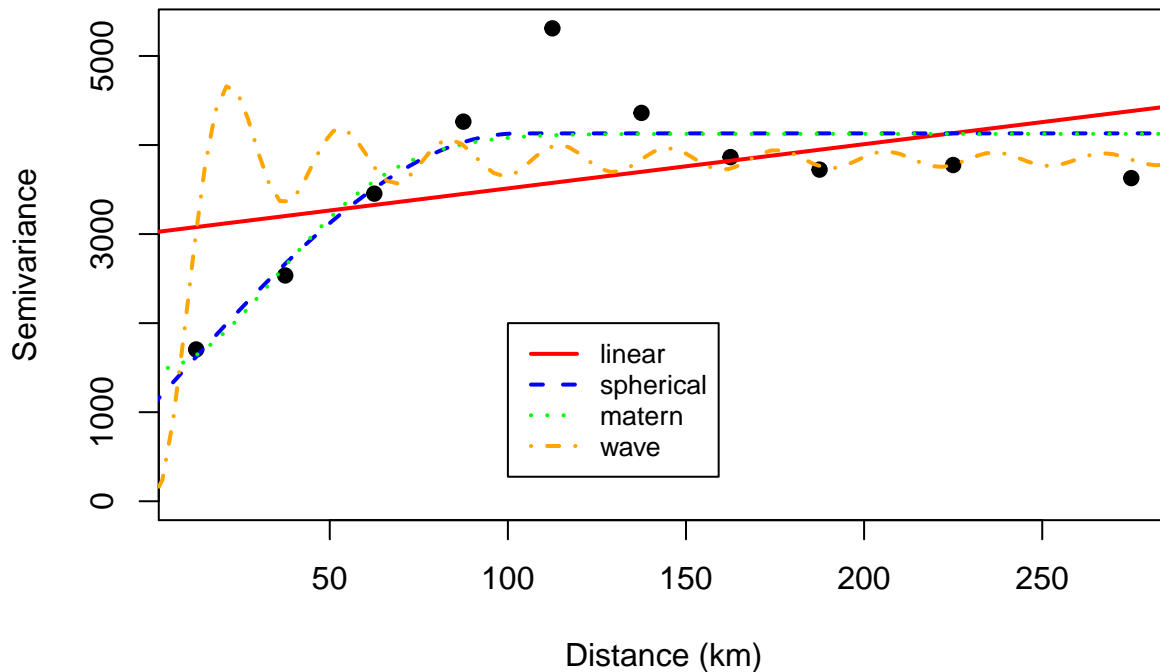
gamma.hat.wav = variofit(gamma.bar, cov.model = "wave", fix.nugget = FALSE,
  ini.cov.pars = c(3919, 4.8), weights = "equal")

## variofit: covariance model used is wave
## variofit: weights used: equal
## variofit: minimisation function used: optim

plot(x = gamma.bar$u, y = gamma.bar$v, ylim = c(0, max(gamma.bar$v)), pch = 19, main =
  "Variogram Estimation", xlab = "Distance (km)", ylab = "Semivariance")
lines(gamma.hat.lin, col = "red", lwd = 2, lty = 1)
lines(gamma.hat.sph, col = "blue", lwd = 2, lty = 2)
lines(gamma.hat.mat, col = "green", lwd = 2, lty = 3)
lines(gamma.hat.wav, col = "orange", lwd = 2, lty = 4)
legend(100, 2000, col = c("red", "blue", "green", "orange"), c("linear", "spherical",
  "matern", "wave"), lty = c(1,2,3,4), cex = 0.8, lwd = 2)

```

Variogram Estimation



```
sse3(gamma.hat.lin, gamma.bar$u, gamma.bar$v)
```

```
## [1] 2350404
```

```
sse3(gamma.hat.sph, gamma.bar$u, gamma.bar$v)
```

```
## [1] 27458.41
```

```
sse3(gamma.hat.mat, gamma.bar$u, gamma.bar$v)
```

```
## [1] 35531.02
```

```
sse3(gamma.hat.wav, gamma.bar$u, gamma.bar$v)
```

```
## [1] 2510289
```

```
# Lowest sse3 - spherical variogram, Cressie-style weights, optim minimization  
# Try with nlm minimization
```

```
gamma.hat.sph = variofit(gamma.bar, cov.model = "spherical", fix.nugget = FALSE,  
  minimisation.function = "nlm", weights = "cressie")
```

```
## variofit: covariance model used is spherical
```

```
## variofit: weights used: cressie
```

```
## variofit: minimisation function used: nlm
```

```
## variofit: searching for best initial value ... selected values:
```

```
##           sigmasq  phi  tausq    kappa
```

```
## initial.value "2655.11" "88" "1327.55" "0.5"
```

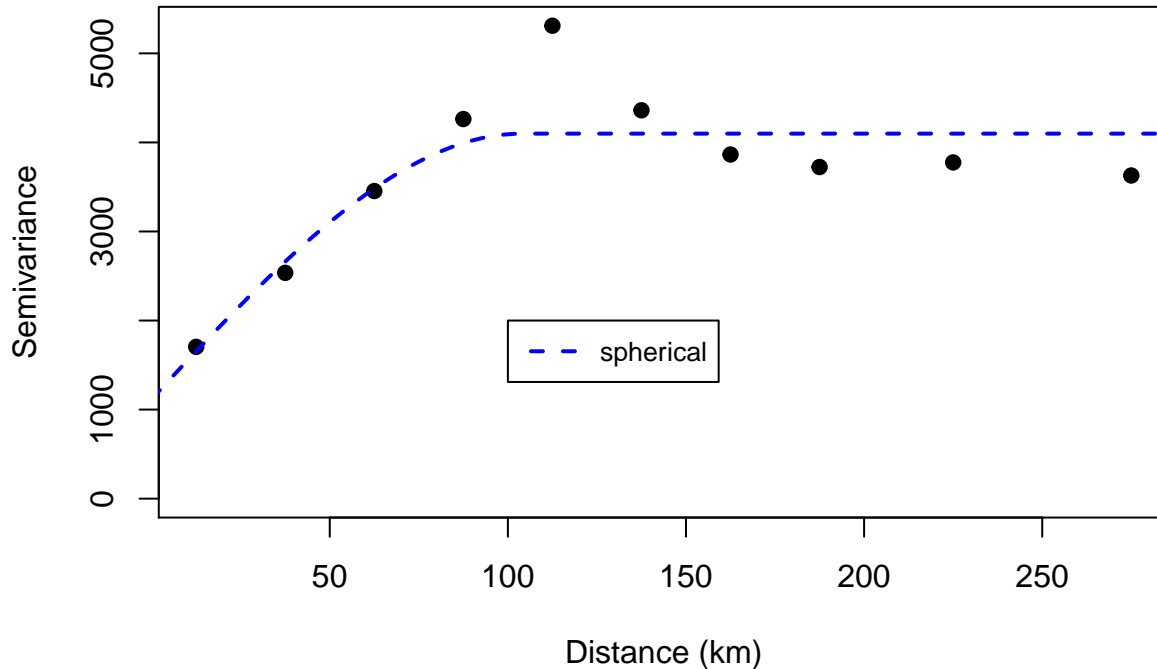
```
## status      "est"    "est" "est"    "fix"
```

```
## loss value: 49.5154401042739
```

```
plot(x = gamma.bar$u, y = gamma.bar$v, ylim = c(0, max(gamma.bar$v)), pch = 19, main =  
  "Variogram Estimation", xlab = "Distance (km)", ylab = "Semivariance")
```

```
lines(gamma.hat.sph, col = "blue", lwd = 2, lty = 2)
legend(100, 2000, col = "blue", "spherical", lty = 2, cex = 0.8, lwd = 2)
```

Variogram Estimation



```
sse3(gamma.hat.sph, gamma.bar$u, gamma.bar$v)
```

```
## [1] 19263.85
```

```
# This sse3 is slightly lower, so this is the final variogram
```

```
# Checking parameter estimates
gamma.hat.sph
```

```
## variofit: model parameters estimated by WLS (weighted least squares):
## covariance model is: spherical
## parameter estimates:
##      tausq   sigmasq      phi
## 1119.7552 2978.8657 103.9361
## Practical Range with cor=0.05 for asymptotic range: 103.9361
##
## variofit: minimised weighted sum of squares = 42.9362
```

```
#####
# Kriging
#####
```

```
kc = krige.control(type = "sk", obj.model = gamma.hat.sph)
sk = krige.conv(wolfcamp, locations = grid, krige = kc)
```

```
## krige.conv: model with constant mean
## krige.conv: Kriging performed using global neighbourhood
```

```

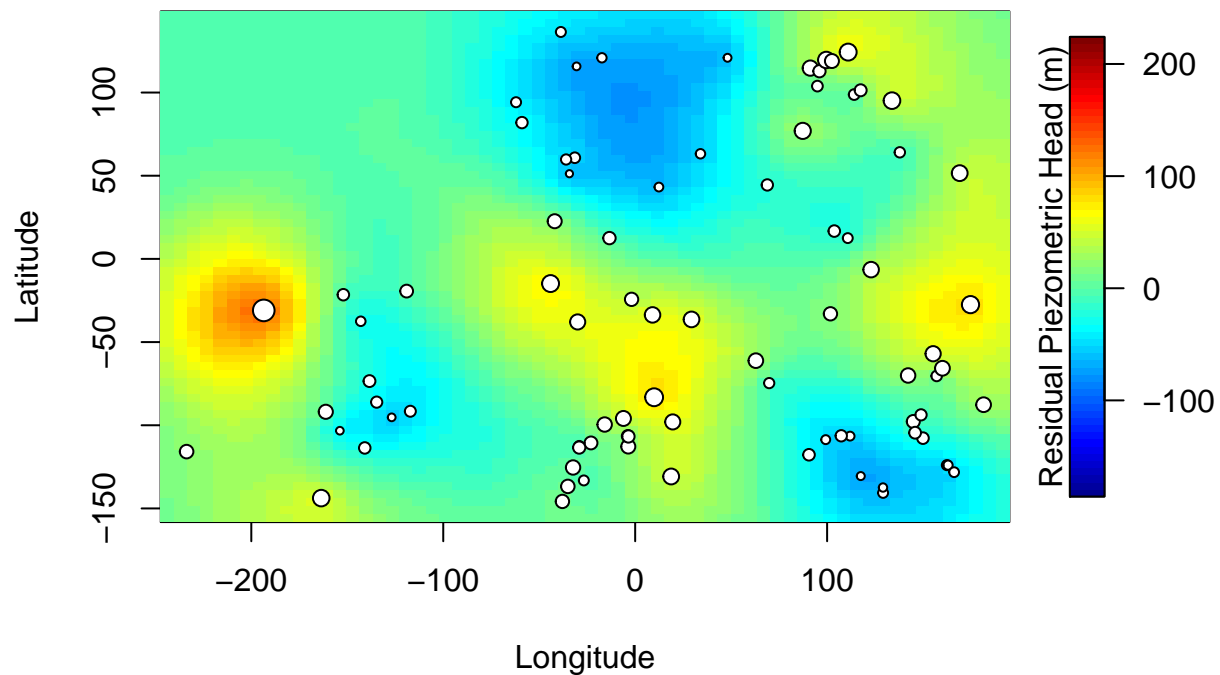
# Fixing scale for plots
min.val = min(sk$predict - qnorm(0.975) * sqrt(sk$krige.var))
max.val = max(sk$predict + qnorm(0.975) * sqrt(sk$krige.var))

# Plotting point estimates of residuals

quilt.plot(grid, sk$predict, zlim = c(min.val, max.val), main =
  "Residual Point Estimates", xlab = "Longitude", ylab = "Latitude", legend.args =
  list(text = "Residual Piezometric Head (m)", side = 2))
points(wolfcamp, pch = 21, col = "white", add = TRUE)

```

Residual Point Estimates

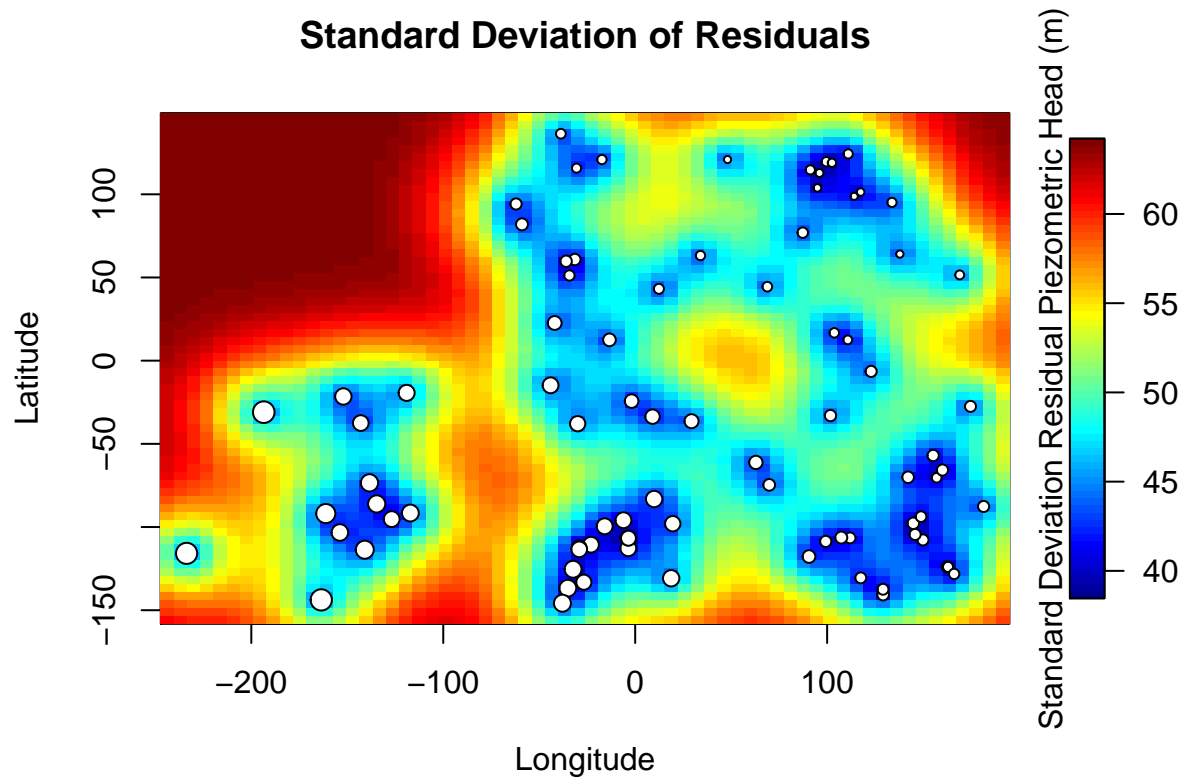


```

# Plotting the kriging standard deviation of residuals

quilt.plot(grid, sqrt(sk$krige.var), main = "Standard Deviation of Residuals", xlab =
  "Longitude", ylab = "Latitude", legend.args = list(text =
  "Standard Deviation Residual Piezometric Head (m)", side = 2))
points(wolfcamp.orig, pch = 21, col = "white", add = TRUE)

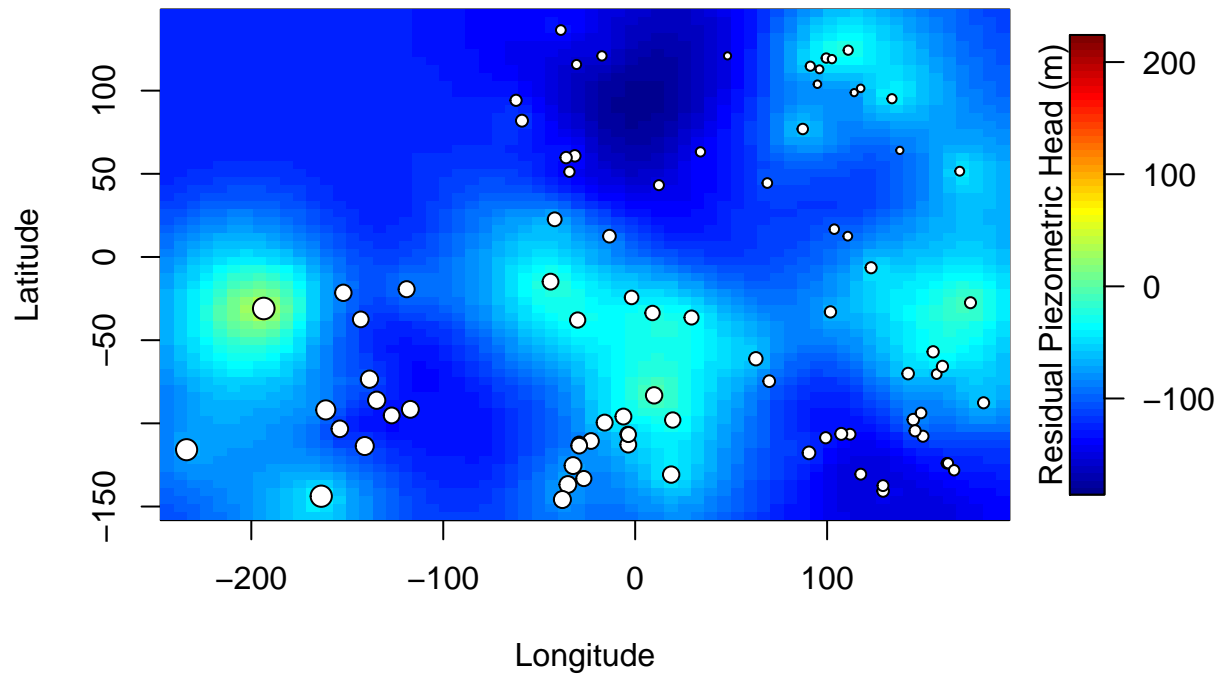
```



```
# Plotting lower 95% confidence estimates of residuals

quilt.plot(grid, sk$predict - qnorm(0.975) * sqrt(sk$krige.var), zlim =
  c(min.val, max.val), main = "Residual Lower 95% Confidence Bound", xlab = "Longitude",
  ylab = "Latitude", legend.args = list(text = "Residual Piezometric Head (m)", side = 2))
points(wolfcamp.orig, pch = 21, col = "white", add = TRUE)
```

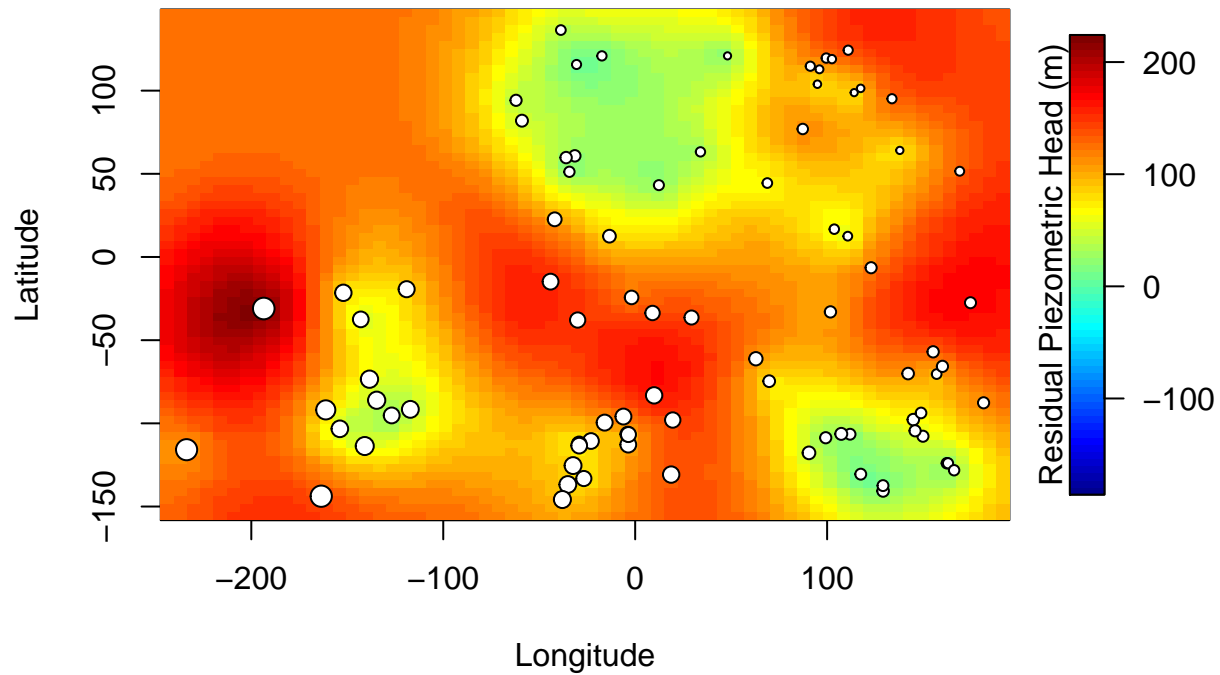
Residual Lower 95% Confidence Bound



```
# Plotting upper 95% confidence estimates of residuals

quilt.plot(grid, sk$predict + qnorm(0.975) * sqrt(sk$krige.var), zlim =
  c(min.val, max.val), main = "Residual Upper 95% Confidence Bound", xlab = "Longitude",
  ylab = "Latitude", legend.args = list(text = "Residual Piezometric Head (m)", side = 2))
points(wolfcamp.orig, pch = 21, col = "white", add = TRUE)
```

Residual Upper 95% Confidence Bound

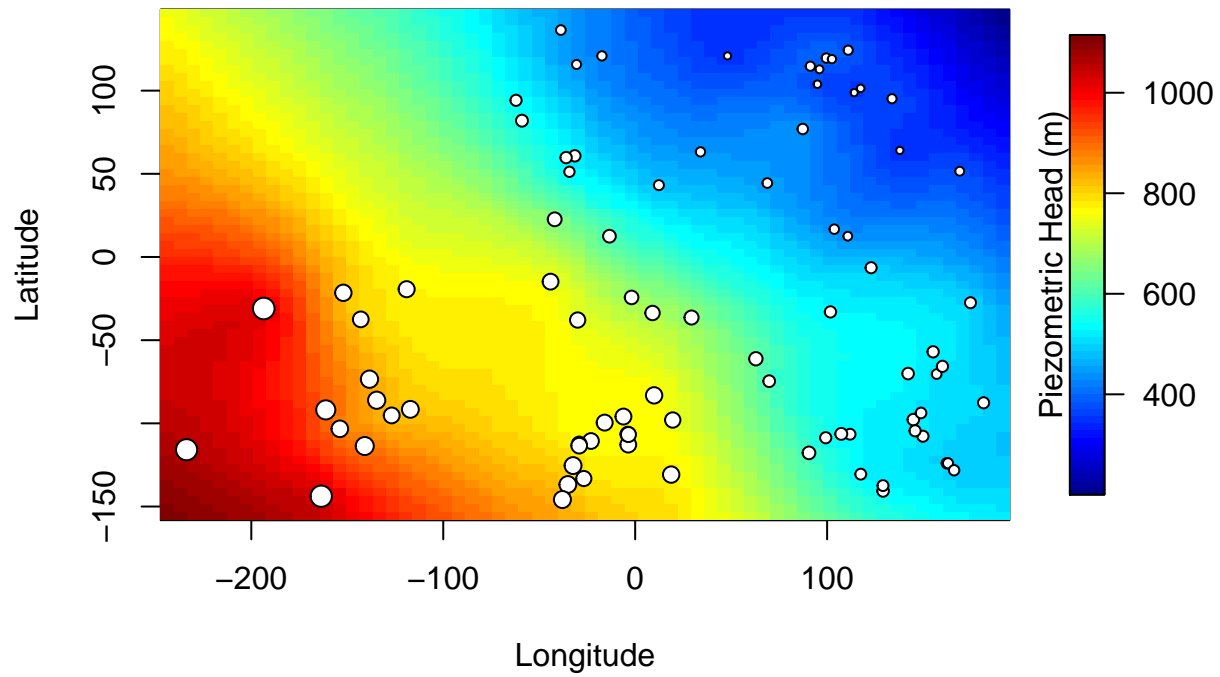


```
# Fixing scale for plots
min.val = min((pred.point + sk$predict) - (qnorm(0.975) * sqrt(sk$krige.var +
  pred.sd**2)))
max.val = max((pred.point + sk$predict) + (qnorm(0.975) * sqrt(sk$krige.var +
  pred.sd**2)))

# Plotting point estimates on the original scale

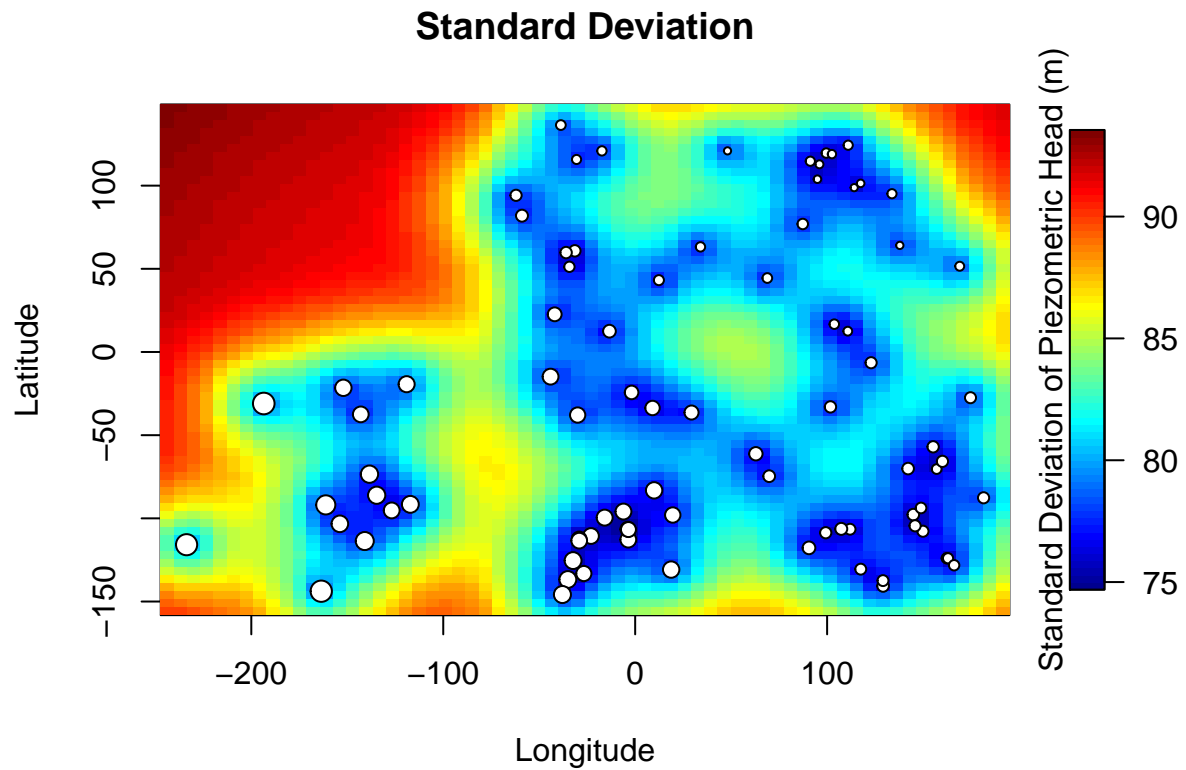
quilt.plot(grid, pred.point + sk$predict, main = "Point Estimates", xlab = "Longitude",
  ylab = "Latitude", legend.args = list(text = "Piezometric Head (m)", side = 2))
points(wolfcamp.orig, pch = 21, col = "white", add = TRUE)
```

Point Estimates



Plotting the kriging standard deviation on the original scale

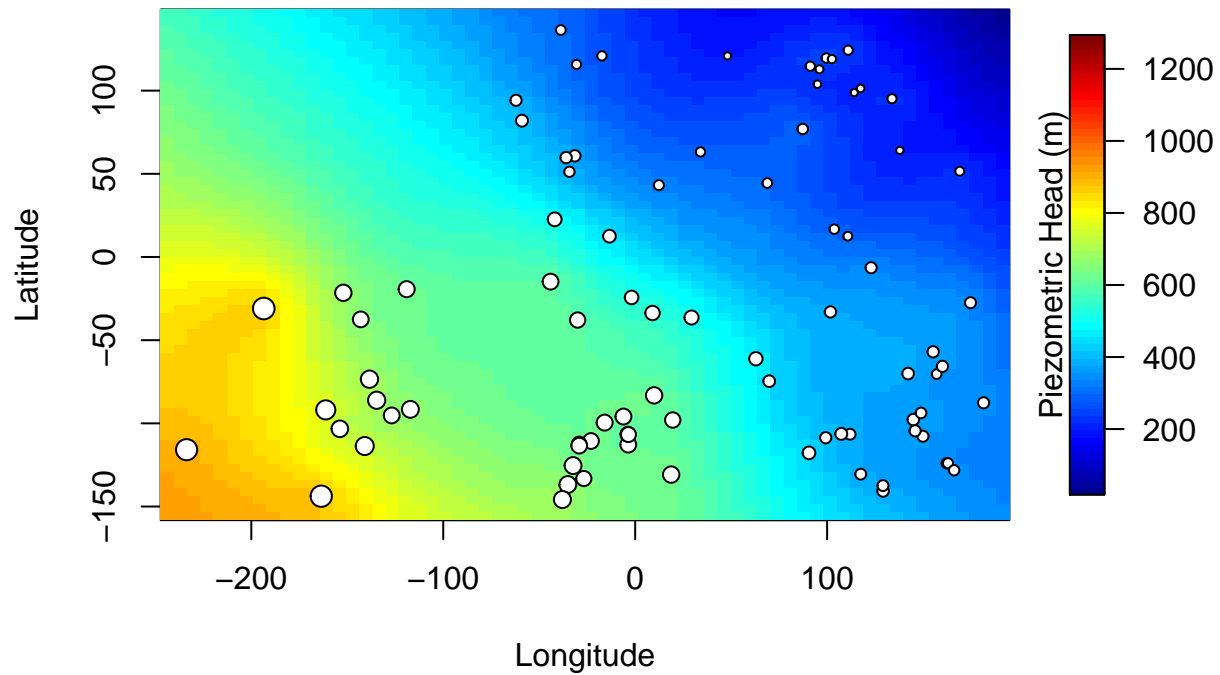
```
quilt.plot(grid, sqrt(pred.sd**2 + sk$krige.var), main = "Standard Deviation",  
  xlab = "Longitude", ylab = "Latitude", legend.args = list(text =  
    "Standard Deviation of Piezometric Head (m)", side = 2))  
points(wolfcamp.orig, pch = 21, col = "white", add = TRUE)
```

```
# Plotting lower 95% confidence estimates on original scale

quilt.plot(grid, (pred.point + sk$predict) - (qnorm(0.975) * sqrt(sk$krige.var +
  pred.sd**2)), zlim = c(min.val, max.val), main = "Lower 95% Confidence Bound", xlab =
  "Longitude", ylab = "Latitude", legend.args = list(text = "Piezometric Head (m)",
    side = 2))
points(wolfcamp.orig, pch = 21, col = "white", add = TRUE)
```

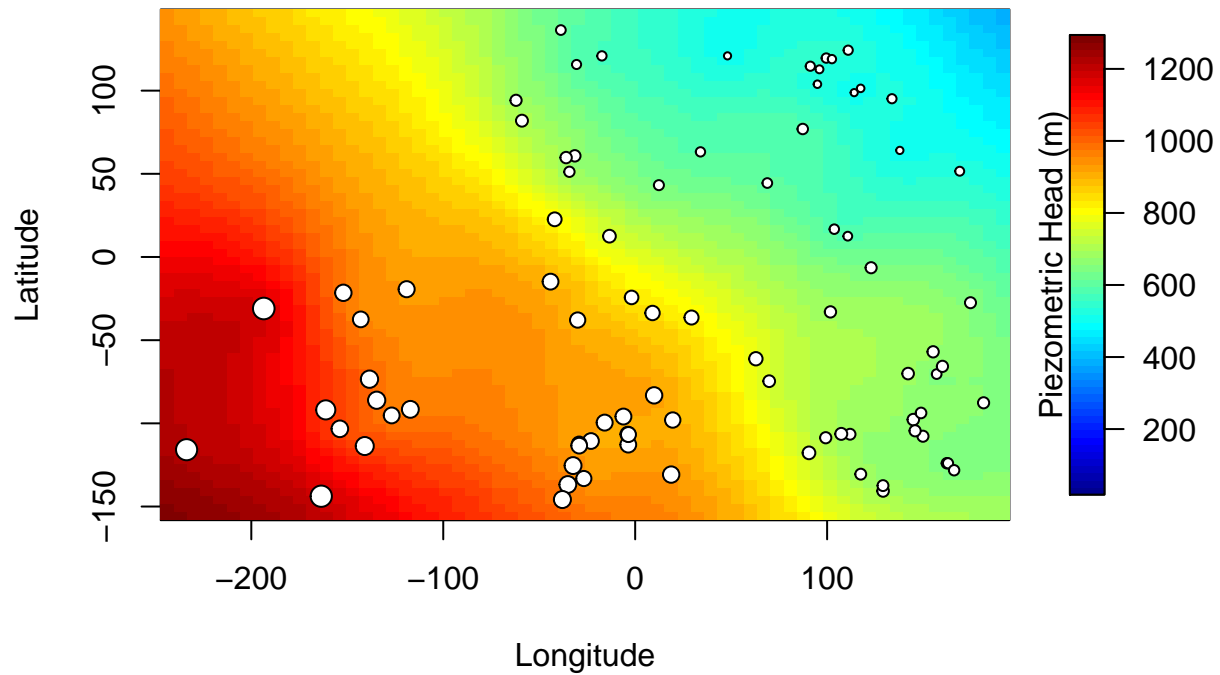
Lower 95% Confidence Bound



Plotting upper 95% confidence estimates on original scale

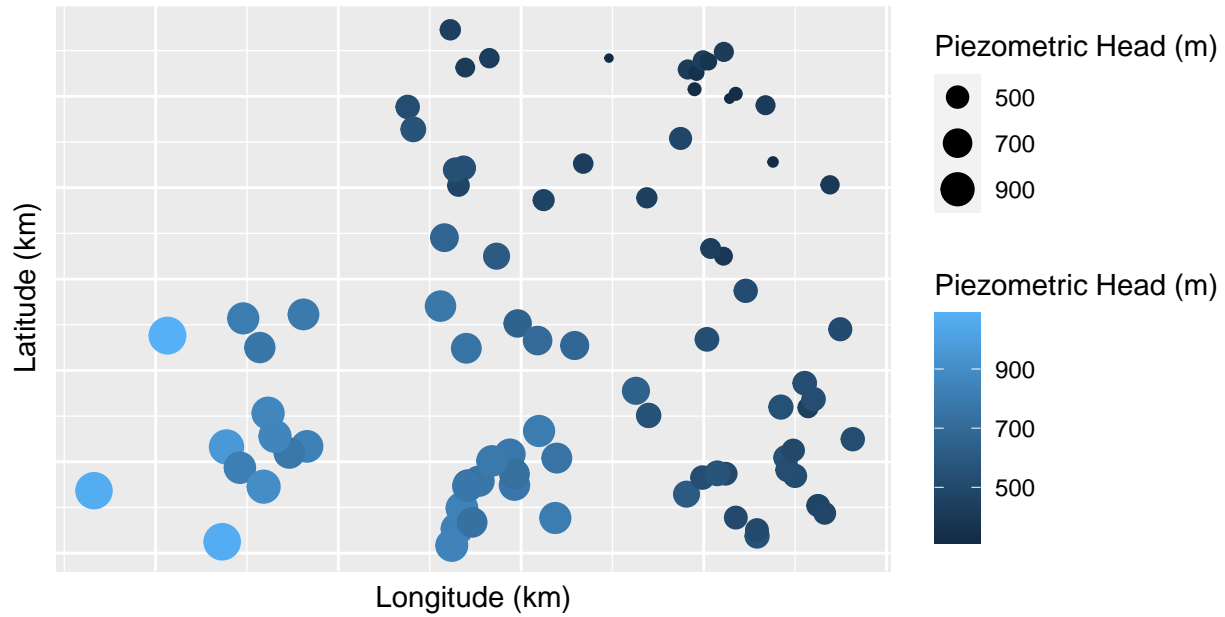
```
quilt.plot(grid, (pred.point + sk$predict) + (qnorm(0.975) * sqrt(sk$krige.var +
  pred.sd**2)), zlim = c(min.val, max.val), main = "Upper 95% Confidence Bound", xlab =
  "Longitude", ylab = "Latitude", legend.args = list(text = "Piezometric Head (m)",
    side = 2))
points(wolfcamp.orig, pch = 21, col = "white", add = TRUE)
```

Upper 95% Confidence Bound

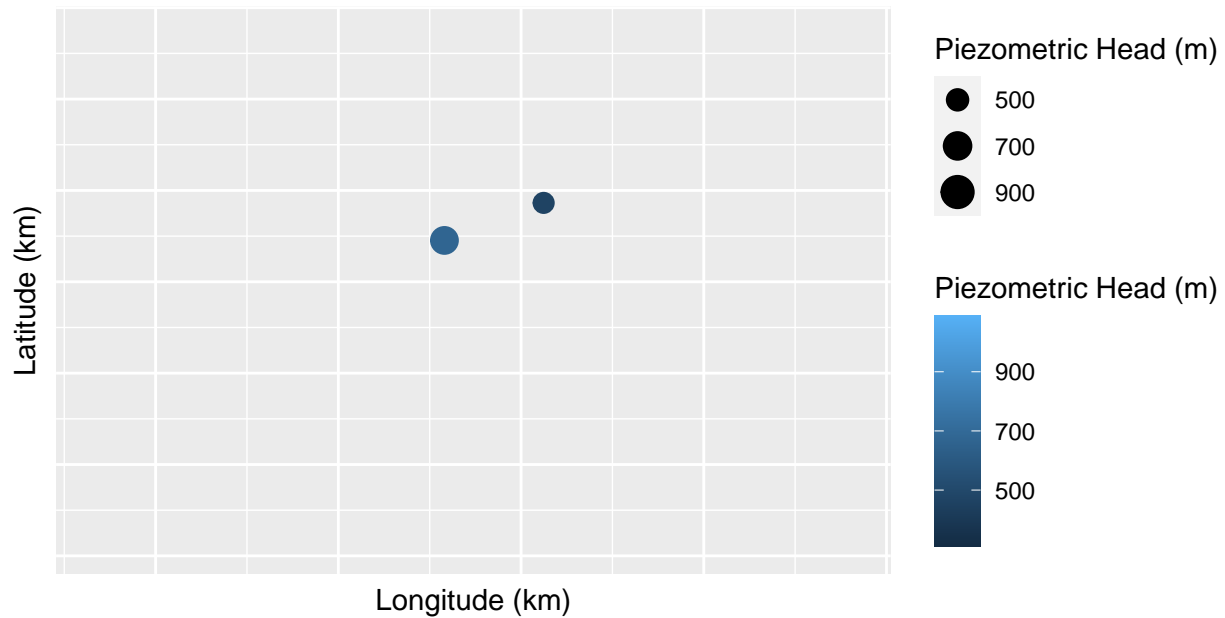


```
#####
# Pressure Difference
#####

# Plot of two points
df = data.frame(lat = y, long = x, Z = z)
p = ggplot() + geom_point(data = df, aes(x = long, y = lat, size = Z, color = Z))
p = p + labs(x = "Longitude (km)", y = "Latitude (km)", size = "Piezometric Head (m)",
  colour = "Piezometric Head (m)") + coord_fixed()
p = p + theme(axis.text.x = element_blank(), axis.text.y = element_blank(), axis.ticks =
  element_blank())
p
```



```
df = df[c(15,59),]
p = ggplot() + geom_point(data = df, aes(x = long, y = lat, size = Z, color = Z))
p = p + labs(x = "Longitude (km)", y = "Latitude (km)", size = "Piezometric Head (m)",
  colour = "Piezometric Head (m)") + coord_fixed()
p = p + theme(axis.text.x = element_blank(), axis.text.y = element_blank(), axis.ticks =
  element_blank())
p = p + xlim(min(x), max(x)) + ylim(min(y), max(y))
p = p + expand_limits(z = min(z))
p = p + lims(size = c(min(z), max(z)), color = c(min(z), max(z)))
p
```



```
true.diff = wolfcamp.orig$dat[15] - wolfcamp.orig$dat[59]
true.diff
```

```
## [1] 205.1266
```

```

loc1 = wolfcamp.orig$coords[15,]
loc2 = wolfcamp.orig$coords[59,]
locs = cbind(loc1, loc2)
sk = krige.conv(wolfcamp, locations = cbind(loc1, loc2), krige = kc)

## krige.conv: model with constant mean
## krige.conv: Kriging performed using global neighbourhood

pred = predict(mod.z, newdata = data.frame(x = locs[,1], y = locs[,2]), interval =
  "prediction", level = 0.95)
pred.point = pred[,1]
pred.sd = (pred[,3] - pred[,1]) / qnorm(0.975)

pred.diff = (pred.point[1] + sk$predict[1]) - (pred.point[2] + sk$predict[2])
pred.sd = sqrt(pred.sd[1]**2 + sk$krige.var[1] + pred.sd[2]**2 + sk$krige.var[2])
pred.diff

##          1
## 202.4221

pred.sd

##          1
## 111.9034

p = 1 - pnorm(pred.diff / pred.sd)
p

##          1
## 0.03523322

```