

Math 151B Homework 2

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5.4.3(a)

Consider the initial value problem given by

$$y' = y/t - (y/t)^2, \quad 1 \leq t \leq 2, \quad y(1) = 1$$

along with the actual solution $y(t) = t/(1 + \ln t)$. We want to use Modified Euler's Method with a step size of $h = 0.1$ to approximate the solutions. Hence, we will perform $N = (b - a)/h = (2 - 1)/0.1 = 10$ iterations. Using the code for Modified Euler's Method (modified_euler.py), we obtain as output the table below.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 1.0000000 | 1.0000000 | 0.0000000 |
| 1 | 1.1 | 1.0041322 | 1.0042817 | 0.0001495 |
| 2 | 1.2 | 1.0147137 | 1.0149523 | 0.0002386 |
| 3 | 1.3 | 1.0295197 | 1.0298137 | 0.0002940 |
| 4 | 1.4 | 1.0472044 | 1.0475339 | 0.0003295 |
| 5 | 1.5 | 1.0669093 | 1.0672624 | 0.0003530 |
| 6 | 1.6 | 1.0880637 | 1.0884327 | 0.0003690 |
| 7 | 1.7 | 1.1102751 | 1.1106551 | 0.0003800 |
| 8 | 1.8 | 1.1332657 | 1.1336536 | 0.0003878 |
| 9 | 1.9 | 1.1568349 | 1.1572284 | 0.0003935 |
| 10 | 2.0 | 1.1808345 | 1.1812322 | 0.0003977 |

5.4.3(b)

We are given the initial value problem

$$y' = 1 + y/t + (y/t)^2, \quad 1 \leq t \leq 3, \quad y(1) = 0$$

and the corresponding actual solution $y(t) = t \tan(\ln t)$. To use Modified Euler's Method to approximate the solutions for a step size of $h = 0.2$, we will do $N = (3 - 1)/0.2 = 10$ iterations. We use the code modified_euler.py and obtain the table below as output.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 0.0000000 | 0.0000000 | 0.0000000 |
| 1 | 1.2 | 0.2194444 | 0.2212428 | 0.0017983 |
| 2 | 1.4 | 0.4850495 | 0.4896817 | 0.0046322 |
| 3 | 1.6 | 0.8040116 | 0.8127527 | 0.0087411 |
| 4 | 1.8 | 1.1848560 | 1.1994386 | 0.0145827 |
| 5 | 2.0 | 1.6384229 | 1.6612818 | 0.0228589 |
| 6 | 2.2 | 2.1788772 | 2.2135018 | 0.0346246 |
| 7 | 2.4 | 2.8250651 | 2.8765514 | 0.0514863 |
| 8 | 2.6 | 3.6025247 | 3.6784753 | 0.0759506 |
| 9 | 2.8 | 4.5466136 | 4.6586651 | 0.1120515 |
| 10 | 3.0 | 5.7075699 | 5.8741000 | 0.1665301 |

5.4.7(a)

We will approximate solutions to the initial value problem from 5.4.3(a) using the Runge-Kutta midpoint method with a step size of $h = 0.1$, performing $N = 10$ iterations as found previously. Using the midpoint method code (midpoint_method.py), we obtain as output the following table.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 1.0000000 | 1.0000000 | 0.0000000 |
| 1 | 1.1 | 1.0045351 | 1.0042817 | 0.0002534 |
| 2 | 1.2 | 1.0153257 | 1.0149523 | 0.0003734 |
| 3 | 1.3 | 1.0302470 | 1.0298137 | 0.0004333 |
| 4 | 1.4 | 1.0479982 | 1.0475339 | 0.0004643 |
| 5 | 1.5 | 1.0677427 | 1.0672624 | 0.0004804 |
| 6 | 1.6 | 1.0889214 | 1.0884327 | 0.0004887 |
| 7 | 1.7 | 1.1111478 | 1.1106551 | 0.0004928 |
| 8 | 1.8 | 1.1341481 | 1.1336536 | 0.0004946 |
| 9 | 1.9 | 1.1577236 | 1.1572284 | 0.0004952 |
| 10 | 2.0 | 1.1817275 | 1.1812322 | 0.0004952 |

5.4.7(b)

We approximate the solutions to the initial value problem in 5.4.3(b) using the Runge-Kutta midpoint method with a step size of $h = 0.2$ for $N = 10$ iterations. Using the code for the Python implementation of the midpoint method (midpoint_method.py), our output is the following table.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 0.0000000 | 0.0000000 | 0.0000000 |
| 1 | 1.2 | 0.2198347 | 0.2212428 | 0.0014081 |
| 2 | 1.4 | 0.4861770 | 0.4896817 | 0.0035046 |
| 3 | 1.6 | 0.8061849 | 0.8127527 | 0.0065678 |
| 4 | 1.8 | 1.1884393 | 1.1994386 | 0.0109994 |
| 5 | 2.0 | 1.6438889 | 1.6612818 | 0.0173928 |
| 6 | 2.2 | 2.1868609 | 2.2135018 | 0.0266409 |
| 7 | 2.4 | 2.8364357 | 2.8765514 | 0.0401157 |
| 8 | 2.6 | 3.6184926 | 3.6784753 | 0.0599828 |
| 9 | 2.8 | 4.5688944 | 4.6586651 | 0.0897707 |
| 10 | 3.0 | 5.7386475 | 5.8741000 | 0.1354525 |

5.4.15(a)

For the initial value problem given in 5.4.3(a), we approximate its solutions using the Runge-Kutta Method of order 4 with a step size of $h = 0.1$, hence performing $N = 10$ iterations. Using the runge_kutta_order_4.py code, we obtain as output the table below.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 1.0000000 | 1.0000000 | 0.0000000 |
| 1 | 1.1 | 1.0042815 | 1.0042817 | 0.0000002 |
| 2 | 1.2 | 1.0149520 | 1.0149523 | 0.0000003 |
| 3 | 1.3 | 1.0298133 | 1.0298137 | 0.0000003 |
| 4 | 1.4 | 1.0475336 | 1.0475339 | 0.0000004 |
| 5 | 1.5 | 1.0672620 | 1.0672624 | 0.0000004 |
| 6 | 1.6 | 1.0884323 | 1.0884327 | 0.0000004 |
| 7 | 1.7 | 1.1106547 | 1.1106551 | 0.0000004 |
| 8 | 1.8 | 1.1336532 | 1.1336536 | 0.0000004 |

| | | | | |
|----|-----|-----------|-----------|-----------|
| 9 | 1.9 | 1.1572281 | 1.1572284 | 0.0000004 |
| 10 | 2.0 | 1.1812319 | 1.1812322 | 0.0000004 |

5.4.15(b)

We now redo our approximations for the initial value problem in 5.4.3(a) using the Runge-Kutta method of order 4 with a step size of $h = 0.1$ (meaning that we perform $N = 10$ iterations). Then, using the `runge_kutta_order_4.py` code, we obtain the table below as our code output.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 0.0000000 | 0.0000000 | 0.0000000 |
| 1 | 1.2 | 0.2212457 | 0.2212428 | 0.0000029 |
| 2 | 1.4 | 0.4896842 | 0.4896817 | 0.0000025 |
| 3 | 1.6 | 0.8127522 | 0.8127527 | 0.0000006 |
| 4 | 1.8 | 1.1994320 | 1.1994386 | 0.0000066 |
| 5 | 2.0 | 1.6612651 | 1.6612818 | 0.0000166 |
| 6 | 2.2 | 2.2134693 | 2.2135018 | 0.0000325 |
| 7 | 2.4 | 2.8764941 | 2.8765514 | 0.0000573 |
| 8 | 2.6 | 3.6783790 | 3.6784753 | 0.0000963 |
| 9 | 2.8 | 4.6585063 | 4.6586651 | 0.0001588 |
| 10 | 3.0 | 5.8738386 | 5.8741000 | 0.0002614 |

5.29

Consider the initial value problem

$$y' = -y + t + 1, \quad 0 \leq t \leq 1, \quad y(0) = 1.$$

We want to show that for any choice of step size h , Modified Euler's Method and the Midpoint Method give the same approximations. Recall that Modified Euler's Method can be recursively defined as

$$\begin{aligned} w_0 &= \alpha, \\ w_{i+1} &= w_i + \frac{h}{2} (f(t_i, w_i) + f(t_{i+1}, w_i + hf(t_i, w_i))), \end{aligned}$$

for $i = 0, 1, \dots, N-1$ some initial condition $y(t_0) = \alpha$. For this IVP, we have that $w_0 = 1$ and the approximation at each step is given by

$$\begin{aligned} w_{i+1} &= w_i + \frac{h}{2} (f(t_i, w_i) + f(t_{i+1}, w_i + hf(t_i, w_i))) \\ &= w_i + \frac{h}{2} (-w_i + t_i + 1 - w_i - hf(t_i, w_i) + t_{i+1} + 1) \\ &= w_i + \frac{h}{2} (-w_i + t_i + 1 - w_i - h(-w_i + t_i + 1) + t_{i+1} + 1) \\ &= w_i - \frac{h}{2} w_i + \frac{h}{2} t_i + \frac{h}{2} - \frac{h}{2} w_i + \frac{h^2}{2} w_i - \frac{h^2}{2} t_i - \frac{h^2}{2} + \frac{h}{2} t_{i+1} + \frac{h}{2} \\ &= w_i - \frac{h}{2} w_i + \frac{h}{2} t_i + \frac{h}{2} - \frac{h}{2} w_i + \frac{h^2}{2} w_i - \frac{h^2}{2} t_i - \frac{h^2}{2} + \frac{h}{2} (t_i + h) + \frac{h}{2} \\ &= w_i \left(1 - h + \frac{h^2}{2}\right) + t_i \left(h - \frac{h^2}{2}\right) + h \end{aligned}$$

for $i = 0, 1, \dots, N-1$. Note that $t_{i+1} = t_i + h$. The Midpoint Method can also be defined recursively

$$\begin{aligned} w_0 &= \alpha, \\ w_{i+1} &= w_i + hf\left(t_i + \frac{h}{2}, w_i + \frac{h}{2} f(t_i, w_i)\right), \end{aligned}$$

for $i = 0, 1, \dots, N-1$ and an initial condition $y(t_0) = \alpha$. For the IVP above, we have that $w_0 = 1$ and the approximation at each step is given by

$$\begin{aligned}
w_{i+1} &= w_i + hf\left(t_i + \frac{h}{2}, w_i + \frac{h}{2}f(t_i, w_i)\right) \\
&= w_i + h\left(-w_i - \frac{h}{2}f(t_i, w_i) + t_i + \frac{h}{2} + 1\right) \\
&= w_i + h\left(-w_i - \frac{h}{2}(-w_i + t_i + 1) + t_i + \frac{h}{2} + 1\right) \\
&= w_i - hw_i + \frac{h^2}{2}w_i - \frac{h^2}{2}t_i - \frac{h^2}{2} + ht_i + \frac{h^2}{2} + h \\
&= w_i\left(1 - h + \frac{h^2}{2}\right) + t_i\left(h - \frac{h^2}{2}\right) + h
\end{aligned}$$

for $i = 0, 1, \dots, N-1$. This is exactly the same as Modified Euler's Method for the above problem. Hence, for any choice of h , both methods will give the same approximations for this initial value problem.

5.5.3(a)

Consider the initial value problem given by

$$y' = y/t - (y/t)^2, \quad 1 \leq t \leq 2, \quad y(1) = 1$$

along with the actual solution $y(t) = t/(1 + \ln t)$. We will approximate solutions to this initial value problem using the Runge-Kutta-Fehlberg Method. Using the Python code I wrote for this purpose, rkf.py, we obtain as output the table below.

| i | t_i | w_i | h_i | $y(t_i)$ |
|-----|-----------|-----------|-----------|-----------|
| 0 | 1.0000000 | 1.0000000 | 0.1330513 | 1.0000000 |
| 1 | 1.1101946 | 1.0051237 | 0.1101946 | 1.0051237 |
| 2 | 1.2191314 | 1.0175212 | 0.1089368 | 1.0175211 |
| 3 | 1.3572694 | 1.0396749 | 0.1381381 | 1.0396749 |
| 4 | 1.5290112 | 1.0732757 | 0.1717417 | 1.0732756 |
| 5 | 1.7470584 | 1.1213948 | 0.2180472 | 1.1213947 |
| 6 | 2.0286416 | 1.1881702 | 0.2815832 | 1.1881700 |
| 7 | 2.3994350 | 1.2795396 | 0.3707934 | 1.2795395 |
| 8 | 2.8985147 | 1.4041843 | 0.4990798 | 1.4041842 |
| 9 | 3.3985147 | 1.5285639 | 0.5000000 | 1.5285638 |
| 10 | 3.8985147 | 1.6514963 | 0.5000000 | 1.6514962 |
| 11 | 4.0000000 | 1.6762393 | 0.1014853 | 1.6762391 |

5.5.3(b)

We are given the initial value problem

$$y' = 1 + y/t + (y/t)^2, \quad 1 \leq t \leq 3, \quad y(1) = 0$$

and the corresponding actual solution $y(t) = t \tan(\ln t)$. We will again use the rkf.py Python code to approximate solutions to this IVP using the Runge-Kutta-Fehlberg Method. Doing this gives as output the table below.

| i | t_i | w_i | h_i | $y(t_i)$ |
|-----|-----------|-----------|-----------|-----------|
| 0 | 1.0000000 | 0.0000000 | 0.1450265 | 0.0000000 |
| 1 | 1.1450265 | 0.1560235 | 0.1980582 | 0.1560234 |
| 2 | 1.2822303 | 0.3254972 | 0.1372038 | 0.3254970 |
| 3 | 1.4225752 | 0.5232644 | 0.1403449 | 0.5232641 |

| | | | | |
|----|-----------|-----------|-----------|-----------|
| 4 | 1.5482238 | 0.7234123 | 0.1256486 | 0.7234119 |
| 5 | 1.6655759 | 0.9320288 | 0.1173521 | 0.9320282 |
| 6 | 1.7773654 | 1.1521480 | 0.1117896 | 1.1521473 |
| 7 | 1.8847226 | 1.3851234 | 0.1073571 | 1.3851226 |
| 8 | 1.9881998 | 1.6316951 | 0.1034772 | 1.6316941 |
| 9 | 2.0880997 | 1.8923303 | 0.0998999 | 1.8923290 |
| 10 | 2.1846024 | 2.1673514 | 0.0965027 | 2.1673499 |
| 11 | 2.2778244 | 2.4569949 | 0.0932220 | 2.4569932 |
| 12 | 2.3678493 | 2.7614423 | 0.0900249 | 2.7614402 |
| 13 | 2.4547442 | 3.0808374 | 0.0868949 | 3.0808350 |
| 14 | 2.5385694 | 3.4152978 | 0.0838252 | 3.4152951 |
| 15 | 2.6193834 | 3.7649220 | 0.0808140 | 3.7649189 |
| 16 | 2.6972462 | 4.1297939 | 0.0778628 | 4.1297904 |
| 17 | 2.7722206 | 4.5099869 | 0.0749744 | 4.5099829 |
| 18 | 2.8443728 | 4.9055656 | 0.0721522 | 4.9055611 |
| 19 | 2.9137726 | 5.3165880 | 0.0693998 | 5.3165830 |
| 20 | 2.9804930 | 5.7431068 | 0.0667204 | 5.7431011 |
| 21 | 3.0000000 | 5.8741059 | 0.0195070 | 5.8741000 |

5.6.3(a)

Consider the initial value problem given by

$$y' = y/t - (y/t)^2, \quad 1 \leq t \leq 2, \quad y(1) = 1$$

along with the actual solution $y(t) = t/(1 + \ln t)$. Using the ab3.py code to implement the Adams-Bashforth Three-Step Method with a step size of $h = 0.1$ (requiring $N = 10$ iterations) in Python, our output is given the table below.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 1.0000000 | 1.0000000 | 0.0000000 |
| 1 | 1.1 | 1.0042815 | 1.0042817 | 0.0000002 |
| 2 | 1.2 | 1.0149520 | 1.0149523 | 0.0000003 |
| 3 | 1.3 | 1.0293579 | 1.0298137 | 0.0004558 |
| 4 | 1.4 | 1.0468730 | 1.0475339 | 0.0006609 |
| 5 | 1.5 | 1.0664788 | 1.0672624 | 0.0007836 |
| 6 | 1.6 | 1.0875837 | 1.0884327 | 0.0008490 |
| 7 | 1.7 | 1.1097691 | 1.1106551 | 0.0008859 |
| 8 | 1.8 | 1.1327465 | 1.1336536 | 0.0009070 |
| 9 | 1.9 | 1.1563092 | 1.1572284 | 0.0009193 |
| 10 | 2.0 | 1.1803057 | 1.1812322 | 0.0009265 |

Similarly using ab4.py to implement the Adams-Bashforth Four-Step Method with a step size of $h = 0.1$ for $N = 10$ iterations, we obtain the table below as output.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 1.0000000 | 1.0000000 | 0.0000000 |
| 1 | 1.1 | 1.0042815 | 1.0042817 | 0.0000002 |
| 2 | 1.2 | 1.0149520 | 1.0149523 | 0.0000003 |
| 3 | 1.3 | 1.0298133 | 1.0298137 | 0.0000003 |
| 4 | 1.4 | 1.0477278 | 1.0475339 | 0.0001939 |
| 5 | 1.5 | 1.0675362 | 1.0672624 | 0.0002739 |
| 6 | 1.6 | 1.0887567 | 1.0884327 | 0.0003240 |
| 7 | 1.7 | 1.1109994 | 1.1106551 | 0.0003443 |
| 8 | 1.8 | 1.1340093 | 1.1336536 | 0.0003558 |

| | | | | |
|----|-----|-----------|-----------|-----------|
| 9 | 1.9 | 1.1575899 | 1.1572284 | 0.0003614 |
| 10 | 2.0 | 1.1815967 | 1.1812322 | 0.0003645 |

5.6.3(b)

Consider the initial value problem given by

$$y' = y/t - (y/t)^2, \quad 1 \leq t \leq 2, \quad y(1) = 1$$

along with the actual solution $y(t) = t/(1 + \ln t)$. Using the Adams-Bashforth Three-Step Method with a step size of $h = 0.1$ (for $N = 10$ iterations), we use the Python code ab3.py to obtain the below output.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 0.0000000 | 0.0000000 | 0.0000000 |
| 1 | 1.2 | 0.2212457 | 0.2212428 | 0.0000029 |
| 2 | 1.4 | 0.4896842 | 0.4896817 | 0.0000025 |
| 3 | 1.6 | 0.8124317 | 0.8127527 | 0.0003210 |
| 4 | 1.8 | 1.1982110 | 1.1994386 | 0.0012277 |
| 5 | 2.0 | 1.6584313 | 1.6612818 | 0.0028504 |
| 6 | 2.2 | 2.2079987 | 2.2135018 | 0.0055031 |
| 7 | 2.4 | 2.8667672 | 2.8765514 | 0.0097842 |
| 8 | 2.6 | 3.6617484 | 3.6784753 | 0.0167269 |
| 9 | 2.8 | 4.6305275 | 4.6586651 | 0.0281375 |
| 10 | 3.0 | 5.8268008 | 5.8741000 | 0.0472992 |

Additionally, we implement the Adams-Bashforth Four-Step Method with a step size of $h = 0.1$ (also for $N = 10$ iterations) in Python (ab4.py), obtaining the following table as our output.

| i | t_i | w_i | $y(t_i)$ | $ y(t_i) - w_i $ |
|-----|-------|-----------|-----------|------------------|
| 0 | 1.0 | 0.0000000 | 0.0000000 | 0.0000000 |
| 1 | 1.2 | 0.2212457 | 0.2212428 | 0.0000029 |
| 2 | 1.4 | 0.4896842 | 0.4896817 | 0.0000025 |
| 3 | 1.6 | 0.8127522 | 0.8127527 | 0.0000006 |
| 4 | 1.8 | 1.1990422 | 1.1994386 | 0.0003964 |
| 5 | 2.0 | 1.6603060 | 1.6612818 | 0.0009758 |
| 6 | 2.2 | 2.2117448 | 2.2135018 | 0.0017570 |
| 7 | 2.4 | 2.8735320 | 2.8765514 | 0.0030194 |
| 8 | 2.6 | 3.6733266 | 3.6784753 | 0.0051487 |
| 9 | 2.8 | 4.6498937 | 4.6586651 | 0.0087714 |
| 10 | 3.0 | 5.8589944 | 5.8741000 | 0.0151056 |

5.10.1

Proof. Suppose that the hypotheses of Theorem 5.20 are satisfied. Hence, assume that $\phi(t, w, h)$ is continuous and satisfies a Lipschitz condition in w on

$$D = \{(t, w, h) : a \leq t \leq b, -\infty < w < \infty, 0 \leq h \leq h_0\}$$

with Lipschitz constant L . Now, suppose that sequences $\{u_i\}_{i=1}^N$ and $\{v_i\}_{i=1}^N$ satisfy the difference equation

$$w_{i+1} = w_i + h\phi(t_i, w_i, h).$$

From this assumption, we have that

$$u_{i+1} = u_i + h\phi(t_i, u_i, h) \quad \text{and} \quad v_{i+1} = v_i + h\phi(t_i, v_i, h).$$

It follows that

$$u_{i+1} - v_{i+1} = u_i - v_i + h [\phi(t_i, u_i, h) - \phi(t_i, v_i, h)]$$

from which we also further obtain

$$|u_{i+1} - v_{i+1}| = |u_i - v_i + h [\phi(t_i, u_i, h) - \phi(t_i, v_i, h)]|.$$

By the Triangle Inequality,

$$\begin{aligned} |u_{i+1} - v_{i+1}| &\leq |u_i - v_i| + h |\phi(t_i, u_i, h) - \phi(t_i, v_i, h)| \\ &\leq |u_i - v_i| + hL |u_i - v_i| \\ &= (1 + hL) |u_i - v_i|. \end{aligned}$$

At this point, we observe that

$$\begin{aligned} |u_{i+1} - v_{i+1}| &\leq (1 + hL) |u_i - v_i| \\ &\leq (1 + hL)^2 |u_{i-1} - v_{i-1}| \\ &\leq (1 + hL)^3 |u_{i-2} - v_{i-2}| \\ &\vdots \\ &\leq (1 + hL)^{i+1} |u_0 - v_0|. \end{aligned}$$

Since $h > 0$ and $L > 0$, we have that $(1 + hL)^{i+1} > 0$ for all $i \geq 0$. The chain of inequalities established above implies that

$$(1 + hL) |u_i - v_i| \leq (1 + hL)^{i+1} |u_0 - v_0|.$$

Dividing each side by $1 + hL$ gives

$$|u_i - v_i| \leq (1 + hL)^i |u_0 - v_0|.$$

Thus, if we let $K = (1 + hL)^i > 0$, we have that

$$|u_i - v_i| \leq K |u_0 - v_0|$$

for each $i = 1, 2, \dots, N$. This gives the desired result and we're done. \square

modified_euler.py

This code provides my implementation of Modified Euler's Method in Python. As provided, this is the solution for 5.4.3(b).

```

1 # Imports
2 import numpy as np
3 import pandas as pd
4 import math
5
6 # For more decimal places
7 pd.set_option("display.precision", 7)
8
9 ## Arguments
10
11 # Function
12 f = lambda t, y: 1 + y/t + (y/t)**2
13 # Left endpoint
14 t_0 = 1
15 # Right endpoint
16 t_1 = 3
17 # Step size
18 h = 0.2
19 # Initial condition
20 alpha = 0
21
22 N = int((t_1 - t_0)/h)
23 t = np.arange(t_0, t_1+h, h)

```

```

24 w = np.zeros(len(t))
25 w[0] = alpha
26
27 # Approximations
28 for i in range(0, len(t) - 1):
29     w[i+1] = w[i] + h/2*(f(t[i], w[i]) + f(t[i+1], w[i] + h*f(t[i], w[i])))
30 # Output
31 df = pd.DataFrame({'t_i': t, 'w_i': w})
32 print(df)
33
34 ## Error determination
35
36 # Exact solution
37 y = lambda t: t*np.tan(np.log(t))
38 yt = np.zeros(len(t))
39
40 # Looping to determine actual values
41 for i in range(0, len(t)):
42     yt[i] = y(t[i])
43 # Output
44 df2 = pd.DataFrame({'t_i': t, 'w_i': w,
45                     'y(t_i)': yt, '|y(t_i) - w_i|': abs(w-yt)})
46 print(df2)

```

midpoint_method.py

The code below gives my implementation of the Midpoint Method in Python. This particular instance provides the output for 5.4.7(b).

```

1 # Imports
2 import numpy as np
3 import pandas as pd
4 import math
5
6 # For more decimal places
7 pd.set_option("display.precision", 7)
8
9 ## Arguments
10
11 # Function
12 f = lambda t, y: 1 + y/t + (y/t)**2
13 # Left endpoint
14 t_0 = 1
15 # Right endpoint
16 t_1 = 3
17 # Step size
18 h = 0.2
19 # Initial condition
20 alpha = 0
21
22 N = int((t_1-t_0)/h)
23 t = np.arange(t_0, t_1+h, h)
24 w = np.zeros(len(t))
25 w[0] = alpha
26
27 # Approximations
28 for i in range(0, len(t) - 1):
29     w[i+1] = w[i] + h*f(t[i], w[i] + h/2*f(t[i], w[i]))
30 # Output
31 df = pd.DataFrame({'t_i': t, 'w_i': w})
32 print(df)
33
34 ## Error determination
35
36 # Exact solution
37 y = lambda t: t*np.tan(np.log(t))
38 yt = np.zeros(len(t))
39
40 # Looping to determine actual values

```



```

41 for i in range(0, len(t)):
42     yt[i] = y(t[i])
43 # Output
44 df2 = pd.DataFrame({'t_i': t, 'w_i': w,
45                     'y(t_i)': yt, '|y(t_i) - w_i|': abs(w-yt)})
46 print(df2)

```

runge_kutta_order_4.py

The chunk below provides my Python code for the implementation of the Runge-Kutta Method of order 4. In particular, the code below gives the solution for 5.4.15(b).

```

1  import numpy as np
2  import pandas as pd
3  import math
4
5  # For more decimal places
6  pd.set_option("display.precision", 7)
7
8  ## Arguments
9  # Function
10 f = lambda t, y: 1 + y/t + (y/t)**2
11 # Left endpoint
12 t_0 = 1
13 # Right endpoint
14 t_1 = 3
15 # Step size
16 h = 0.2
17 # Initial condition
18 alpha = 0
19
20 N = int((t_1-t_0)/h)
21 t = np.arange(t_0, t_1+h, h)
22 w = np.zeros(len(t))
23 w[0] = alpha
24
25 # Approximations
26 for i in range(0, len(t) - 1):
27     k1 = h*f(t[i], w[i])
28     k2 = h*f(t[i] + h/2, w[i] + 1/2*k1)
29     k3 = h*f(t[i] + h/2, w[i] + 1/2*k2)
30     k4 = h*f(t[i+1], w[i] + k3)
31     w[i+1] = w[i] + 1/6*(k1 + 2*k2 + 2*k3 + k4)
32 # Output
33 df = pd.DataFrame({'t_i': t, 'w_i': w})
34 print(df)
35
36 ## Error determination
37
38 # Exact solution
39 y = lambda t: t*np.tan(np.log(t))
40 yt = np.zeros(len(t))
41
42 # Looping to determine actual values
43 for i in range(0, len(t)):
44     yt[i] = y(t[i])
45 # Output
46 df2 = pd.DataFrame({'t_i': t, 'w_i': w,
47                     'y(t_i)': yt, '|y(t_i) - w_i|': abs(w-yt)})
48 print(df2)

```

rkf.py

The code below implements the Runge-Kutta-Fehlberg Method in Python using the pseudocode outlined in Algorithm 5.3 of the textbook. The chunk below in particular provides approximations for 5.5.3(a).

```

1  # Imports
2  import numpy as np

```

```

3 import pandas as pd
4 import math
5
6 # For more decimal places
7 pd.set_option("display.precision", 7)
8
9 ## Argument specification
10
11 # Function
12 f = lambda t, y: y/t - (y/t)**2
13 # Left endpoint
14 a = 1
15 # Right endpoint
16 b = 4
17 # Maximum step size
18 hmax = 0.5
19 # Minimum step size
20 hmin = 0.05
21 # Tolerance
22 TOL = pow(10, -6)
23 # Initial condition
24 alpha = 1
25
26 # Maximum number of steps (unknown a priori)
27 N_max = int((b-a)/hmin) + 1
28
29 # Initialize arrays
30 t = np.zeros(N_max)
31 w = np.zeros(N_max)
32 h_out = np.zeros(1)
33
34 # Initial conditions
35 t[0] = a
36 w[0] = alpha
37 h_out[0] = hmax
38 h = hmax
39 i = 0
40 FLAG = 1
41
42 # Implementing the RK4 algorithm for approximations
43 while (FLAG == 1):
44     K1 = h*f(t[i],w[i])
45     K2 = h*f(t[i] + 1/4*h, w[i] + 1/4*K1)
46     K3 = h*f(t[i] + 3/8*h, w[i] + 3/32*K1 + 9/32*K2)
47     K4 = h*f(t[i] + 12/13*h, w[i] + 1932/2197*K1 - 7200/2197*K2 + 7296/2197*K3)
48     K5 = h*f(t[i] + h, w[i] + 439/216*K1 - 8*K2 + 3680/513*K3 - 845/4104*K4)
49     K6 = h*f(t[i] + 1/2*h, w[i] - 8/27*K1 + 2*K2 - 3544/2565*K3 + 1859/4104*K4 - 11/40*K5)
50
51     h_out = np.append(h_out, h)
52     R = (1/h)*abs(1/360*K1 - 128/4275*K3 - 2197/75240*K4 + 1/50*K5 + 2/55*K6)
53     delta = 0.84*pow(TOL/R, 1/4)
54
55     if R <= TOL:
56         t[i+1] = t[i] + h
57         w[i+1] = w[i] + 25/216*K1 + 1408/2565*K3 + 2197/4104*K4 - 1/5*K5
58         i += 1
59
60     delta = 0.84*pow(TOL/R, 1/4)
61
62     if delta <= 0.1:
63         h = 0.1*h
64     elif delta >= 4:
65         h = 4*h
66     else:
67         h = delta*h
68
69     if h > hmax:
70         h = hmax
71
72     if t[i] >= b:

```

```

73     FLAG = 0
74     elif (t[i] + h) > b:
75         h = b - t[i]
76     elif h < hmin:
77         FLAG = 0
78
79 # Posterior update to approximation arrays
80 t = t[:i+1]
81 w = w[:i+1]
82 h_out = h_out[2:]
83
84 # Actual solution
85 y = lambda t: t/(1+np.log(t))
86 yt = np.zeros(len(t))
87
88 # Looping to determine actual values
89 for idx, val in enumerate(t):
90     yt[idx] = y(val)
91
92 # Output
93 df = pd.DataFrame({'t_i': t, 'w_i': w, 'h_i': h_out, 'y(t_i)': yt})
94 print(df)

```

ab3.py

The code snippet below is my Python implementation of the Adams-Bashforth Three-Step Method. This instance provides approximations for the first part of 5.6.3(a) in the textbook.

```

1 # Imports
2 import numpy as np
3 import pandas as pd
4 import math
5
6 # For more decimal places
7 pd.set_option("display.precision", 7)
8
9 ## Argument specification
10
11 # Function
12 f = lambda t, y: y/t - (y/t)**2
13 # Left endpoint
14 a = 1
15 # Right endpoint
16 b = 2
17 # Step size
18 h = 0.1
19 # First initial condition
20 alpha = 1
21
22 N = int((b-a/h))
23 t = np.arange(a, b+h, h)
24 w = np.zeros(len(t))
25 w[0] = alpha
26
27 # For order 4 Runge-Kutta approximations
28 rk = np.zeros(3)
29 rk[0] = alpha
30
31 # Runge-Kutta order 4 approximations for alpha1 and alpha2
32 for i in range(0, 2):
33     k1 = h*f(t[i], rk[i])
34     k2 = h*f(t[i] + h/2, rk[i] + 1/2*k1)
35     k3 = h*f(t[i] + h/2, rk[i] + 1/2*k2)
36     k4 = h*f(t[i+1], rk[i] + k3)
37     rk[i+1] = rk[i] + 1/6*(k1 + 2*k2 + 2*k3 + k4)
38
39 w[0] = alpha
40 w[1] = rk[1]
41 w[2] = rk[2]

```

```

42
43 # Adam-Bashforth 4-step approximations
44 for i in range(2, len(t) - 1):
45     w[i+1] = w[i] + h/12*(23*f(t[i], w[i]) - 16*f(t[i-1], w[i-1]) + 5*f(t[i-2], w[i-2]))
46 # Output
47 df = pd.DataFrame({'t_i': t, 'w_i': w})
48 print(df)
49
50 # Exact solution
51 y = lambda t: t/(1+np.log(t))
52 yt = np.zeros(len(t))
53
54 # Looping to determine actual values
55 for i in range(0, len(t)):
56     yt[i] = y(t[i])
57 # Output
58 df2 = pd.DataFrame({'t_i': t, 'w_i': w, 'y(t_i)': yt, '|y(t_i) - w_i|': abs(yt - w)})
59 print(df2)

```

ab4.py

The code snippet below is my Python implementation of the Adams-Bashforth Four-Step Method. This instance provides approximations for the second part of 5.6.3(a) in the textbook.

```

1 # Imports
2 import numpy as np
3 import pandas as pd
4 import math
5
6 # For more decimal places
7 pd.set_option("display.precision", 7)
8
9 ## Argument specification
10 # Function
11 f = lambda t, y: y/t - (y/t)**2
12 # Left endpoint
13 a = 1
14 # Right endpoint
15 b = 2
16 # Step size
17 h = 0.1
18 # First initial condition
19 alpha = 1
20
21 N = int((b-a)/h)
22 t = np.arange(a, b+h, h)
23 w = np.zeros(len(t))
24 w[0] = alpha
25
26 # For order 4 Runge-Kutta approximations
27 rk = np.zeros(4)
28 rk[0] = alpha
29
30 # Runge-Kutta order 4 approximations for alpha1, alpha2, alpha3
31 for i in range(0, 3):
32     k1 = h*f(t[i], rk[i])
33     k2 = h*f(t[i] + h/2, rk[i] + 1/2*k1)
34     k3 = h*f(t[i] + h/2, rk[i] + 1/2*k2)
35     k4 = h*f(t[i+1], rk[i] + k3)
36     rk[i+1] = rk[i] + 1/6*(k1 + 2*k2 + 2*k3 + k4)
37
38 w[0] = alpha
39 w[1] = rk[1]
40 w[2] = rk[2]
41 w[3] = rk[3]
42
43 # Adam-Bashforth 4-step approximations
44 for i in range(3, len(t) - 1):

```

```

45     w[i+1] = w[i] + h/24*(55*f(t[i], w[i]) - 59*f(t[i-1], w[i-1]) + 37*f(t[i-2], w[i-2]) - 9*f(t[i
    -3], w[i-3]))
46 # Output
47 df = pd.DataFrame({'t_i': t, 'w_i': w})
48 print(df)
49
50 # Exact solution
51 y = lambda t: t/(1+np.log(t))
52 yt = np.zeros(len(t))
53
54 # Looping to determine actual values
55 for i in range(0, len(t)):
56     yt[i] = y(t[i])
57 # Output
58 df2 = pd.DataFrame({'t_i': t, 'w_i': w, 'y(t_i)': yt, 'y(t_i) - w_i': abs(yt - w)})
59 print(df2)

```