Math 164 Homework 6

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Problem 7.5

Proof. Let P(k) be the statement " $F_{k-2}F_{k+1} - F_{k-1}F_k = (-1)^k$." We will first show that the base case is satisfied, that is, P(2) holds. We have that

$$F_0F_3 - F_1F_2 = (1)(3) - (1)(2)$$
$$= 3 - 2$$
$$= (-1)^2.$$

The base case therefore holds. We will now proceed to the inductive step. Assume that P(k) holds. We want to show that P(k+1) also holds where $k \ge 2$. Thus, using the recursive definition of the Fibonacci sequence, we have that

$$\begin{split} F_{k-1}F_{k+2} - F_kF_{k+1} &= F_{k-1}(F_k + F_{k+1}) - (F_{k-2} + F_{k-1})F_{k+1} \\ &= F_{k-1}F_k + F_{k-1}F_{k+1} - F_{k-2}F_{k+1} - F_{k-1}F_{k+1} \\ &= F_{k-1}F_k - F_{k-2}F_{k+1} \\ &= -1 \times (-1)^k \\ &= (-1)^{k+1}. \end{split}$$

We have thus shown that P(k+1) is true. By the Principle of Mathematical Induction, P(k) is true for $k \ge 2$.

Problem 7.6

Let $a_k = F_k$ and $b_k = F_{k-1}$. We have that

$$\begin{bmatrix} a_{k+1} \\ b_{k+1} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a_k \\ b_k \end{bmatrix}.$$

subject to the initial condition

$$\begin{bmatrix} a_k \\ b_k \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

Let

$$M = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$
.

We see that

$$F_n = a_n = \begin{bmatrix} 1,0 \end{bmatrix} \begin{bmatrix} a_n \\ b_n \end{bmatrix} = \begin{bmatrix} 1,0 \end{bmatrix} M^n \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

Since M is a symmetric matrix and therefore diagonalizable, we can express it as

$$\boldsymbol{M} = \begin{bmatrix} \boldsymbol{v}^\top \\ \boldsymbol{w}^\top \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} \boldsymbol{v} & \boldsymbol{w} \end{bmatrix}$$

where $\lambda_1 = (1 + \sqrt{5})/2$ and $\lambda_2 = (1 - \sqrt{5})/2$ are the eigenvalues of M. We correspondingly find that

$$v = -\frac{1}{5^{1/4}} \begin{bmatrix} \sqrt{2/(\sqrt{5} - 1)} \\ \sqrt{(\sqrt{5} - 1)/2} \end{bmatrix}$$

and

$$w = -\frac{1}{5^{1/4}} \begin{bmatrix} \sqrt{(\sqrt{5} - 1)/2} \\ -\sqrt{2/(\sqrt{5} - 1)} \end{bmatrix}$$

It therefore follows that

$$F_{n} = v^{\top} \begin{bmatrix} \lambda_{1} & 0 \\ 0 & \lambda_{2} \end{bmatrix}^{n} v$$

$$= \lambda_{1}^{n} v_{1}^{2} + \lambda_{2}^{n} v_{2}^{2}$$

$$= \frac{1}{\sqrt{5}} \left(\left(\frac{1 + \sqrt{5}}{2} \right)^{n+1} - \left(\frac{1 - \sqrt{5}}{2} \right)^{n+1} \right).$$

Problem 7.7

The number $\ln 2$ is the root of the equation $f(x) = e^x - 2$. As such, applying Newton's Method to this root-finding problem, we have

$$x^{(k+1)} = x^{(k)} - \frac{e^{x^{(k)}} - 2}{e^{x^{(k)}}}$$

for $k \ge 0$. Performing 2 iterations of Newton's Method for an initial guess of $x^{(0)} = 1$ with the attached MATLAB script (see Appendix A), we obtain approximations $x^{(1)} = 0.7357588823$ and $x^{(2)} = 0.6940422999$.

Problem 7.8

(a) We first compute $g'(x) = 2e^x/(e^x + 1)^2$. Hence, the algorithm for Newton's Method is

$$x^{(k+1)} = x^{(k)} - \frac{(e^{x^{(k)}} - 1)/(e^{x^{(k)}} + 1)}{2e^{x^{(k)}}/(e^{x^{(k)}} + 1)^2}$$
$$= x^{(k)} - \frac{e^{2x^{(k)}} - 1}{2e^{x^{(k)}}}$$
$$= x^{(k)} - \sinh x^{(k)}$$

for $k \ge 0$.

(b) For the algorithm to cycle, we require that $x^{(1)} = -x^{(0)}$, which is clear by symmetry. This means that $x^{(0)}$ must satisfy

 $-x^{(0)} = x^{(0)} - \sinh x^{(0)}.$

By rearranging this expression, we find that the algorithm cycles for $x^{(0)} = k$, where k is the solution to $2k = \sinh k$.

(c) Using the result from part (b), we have that the algorithm cycles for $x^{(0)} \in (-k, k)$, where k is again the solution to $2k = \sinh k$. We motivate this argument by symmetry as before.

Problem 7.9

The quadratic function that agrees with the given points $(x^{(k-i)}, f(x^{(k-i)}))$ for each i = 0, 1, 2 satisfy the following 3 quadratic formulas:

$$a(x^{(k)})^{2} + bx^{(k)} + c = f(x^{(k)}),$$

$$a(x^{(k-1)})^{2} + bx^{(k-1)} + c = f(x^{(k-1)}),$$

$$a(x^{(k-2)})^{2} + bx^{(k-2)} + c = f(x^{(k-2)}),$$

where we solve for a, b, c using this system of equations. Since these are quadratic formulas, we have by the axis of symmetry that $x^{(k+1)} = -b/2a$. From this, we can find a and b to get that

$$x^{(k+1)} = \frac{\sigma_{12} f(x^{(k)}) + \sigma_{20} f(x^{(k-1)}) + \sigma_{01} f(x^{(k-2)})}{2(\delta_{12} f(x^{(k)}) + \delta_{20} f(x^{(k-1)}) + \delta_{01} f(x^{(k-2)}))}$$

where we let $\sigma_{ij} = (x^{(k-i)})^2 - (x^{(k-j)})^2$ and $\delta_{ij} = x^{(k-i)} - x^{(k-j)}$.

Problem 7.10

%% Secant Method

(a) The code below provides a MATLAB implementation of the Secant Method (secant_method.m). The corresponding .m file can be be found on my GitHub, @nickmonozon.

% This code approximates a solution to f(x) = 0 given initial approximations p0 and p1. % INPUTS: % = initial approximation pn1 p1 = another initial approximation % tolerance epsilon % OUTPUTS: % = approximate solution р %% Information and set up $f = 0(x) (2*x-1)^2 + 4*(4-1024*x)^4;$ % function whose root we want to approximate pn1 = 0;% first initial approximation p0 = 1;% second initial approximation epsilon = 1e-5; % tolerance, e.g. $1e-4 = 10^{-4}$ %% Secant Method qn1 = f(pn1);q0 = f(p0);while true % get p_i p = p0 - ((p0 - pn1) * q0)/(q0 - qn1);% check stopping condition if(abs(p - p0) < abs(p0)*epsilon)break; end % prepare for next iteration pn1 = p0;qn1 = q0;p0 = p;q0 = f(p);end %% Display Information

(b) We want to find the "root" of the equation $g(x) = (2x-1)^2 = 4(4-1024x)^4$ with initial guesses $x^{(-1)} = 0$ and $x^{(0)} = 1$ with tolerance $\epsilon = 10^{-5}$. Using secant_method.m, we obtain an approximation of p = 0.0038664095, where g(p) = 0.9846. Clearly, this is not a root, but it may be a minimizer. In fact, the function g(x) actually has no root. To formalize this, we have that $(2x-1)^2 \ge 0$ for all $x \in \mathbb{R}$, but $(2x-1)^2 = 0$ only for x = 1/2. Additionally, $(4-1024x)^4 \ge 0$ for all $x \in \mathbb{R}$, but

fprintf('\nSecant Method approximated the solution p = %.10f.\n\n',p);

 $(4-1024x)^4 = 0$ only when x = 4/1024 = 1/256. Since both values of x cannot be obtained simultaneously, we conclude that g(x) has no roots.

Problem 7.11

The following code provides a MATLAB implementation of the line search algorithm using the Secant Method. Note that we also need a file grad.m with contains the gradient. This code can also be found on my GitHub, @nickmonozon.

%% Line search using the Secant Method

```
% Information and set up
% INPUTS:
%
    'grad'
                = .m file with gradient
%
                = starting line search point
    X
%
                   search direction
%
                = tolerance, e.g. 1e-4 = 10^{-4}
    epsilon
                    maximum number of iterations
    max
% OUTPUTS:
%
    alpha
                    value returned by function
alpha_curr = 0;
alpha = 0.001;
dphi_zero = feval(grad,x)'*d;
dphi_curr=dphi_zero;
epsilon = 1e-4;
max = 100;
i = 0;
while abs(dphi_curr) > epsilon*abs(dphi_zero),
    alpha_o = alpha_curr;
    alpha_curr = alpha;
    dphi_o = dphi_curr;
    dphi_curr = feval(grad, x+alpha_curr*d)'*d;
    alpha = (dphi_curr*alpha_o-dphi_o*alpha_curr)/(dphi_curr-dphi_o);
    i = i + 1;
    if (i >= max) & (abs(dphi_curr)>epsilon*abs(dphi_zero)),
        fprintf('\nLine search algorithm converges after %d iterations.\n\n',i);
        break:
    end
end
```

Appendix A

The code below provides a MATLAB implementation of Newton's Method (newtons_method.m). The .m file can be found on my GitHub, @nickmonozon.

```
%% Newton's Method

% This code approximates a solution to f(x) = 0 given an initial
% approximation p0.

% INPUTS:
% p0 = initial approximation
% epsilon = tolerance
```

```
max_iter
                = maximum number of iterations
% OUTPUTS:
                = approximate solution
    or error message
%% Information and set up
f = 0(x) exp(x) - 2;
                            % function whose root we want to approximate
fprime = 0(x) \exp(x);
                             \% derivative of function whose root we want to approximate
p0 = 1;
tol = 1e-4;
                            \% tolerance, 1e-4 = 10^{-4}
max_iter = 30;
                             % max number of iterations
%% Newton's Method
i = 1;
                                               % iteration count
                                               % for display
fprintf('i\tp_i\t\tf(p_i)\n');
fprintf('%d\t%.10f\t%.10f\n',0,p0,f(p0));
                                               % displays iteration i, p_i, f(p_i)
while( i <= max_iter)</pre>
    % get p_i
    p = p0 - f(p0)/fprime(p0);
                                 % p_i
    % display information
    fprintf('%d\t%.10f\t%.10f\n',i,p,f(p));  % displays iteration i, p_i, f(p_i)
    % check stopping condition
    if(abs(p - p0) < epsilon)</pre>
        break;
    end
    % increase iteration count
    i = i + 1;
    % prepare for next iteration
    p0 = p;
end
%% Display Information
if( i <= max_iter )</pre>
    fprintf('\nNewton''s Method approximated the solution p = %.10f after %d iterations.\n\n',p,i);
else
    fprintf('\nNewton''s Method did not converge within the tolerance in %d iterations.\n\n', max_iter)
end
```