

Math 164 Homework 2

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- 3.3** Consider two bases of \mathbb{R}^3 , $\{e_1, e_2, e_3\}$ and $\{e'_1, e'_2, e'_3\}$, where $e_1 = 2e'_1 + e'_2 - e'_3$, $e_2 = 2e'_1 - e'_2 + 2e'_3$, and $e_3 = 3e'_1 + e'_3$. Suppose that a linear transformation has a matrix representation in $\{e_1, e_2, e_3\}$ of the form

$$A = \begin{bmatrix} 2 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}.$$

Find the matrix representation of this linear transformation in the basis $\{e'_1, e'_2, e'_3\}$.

Solution. Firstly, we have that

$$[e_1 \ e_2 \ e_3] = [e'_1 \ e'_2 \ e'_3] \begin{bmatrix} 2 & 2 & 3 \\ 1 & -1 & 0 \\ -1 & 2 & 1 \end{bmatrix}.$$

So the transformation matrix from $\{e'_1, e'_2, e'_3\}$ to $\{e_1, e_2, e_3\}$ is given by

$$T = \begin{bmatrix} 2 & 2 & 3 \\ 1 & -1 & 0 \\ -1 & 2 & 1 \end{bmatrix}.$$

Consider the linear transformation $\mathcal{T} : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by the matrix A with respect to the basis $\{e_1, e_2, e_3\}$ and B with respect to the basis $\{e'_1, e'_2, e'_3\}$. Let $y = Ax$ and $\tilde{y} = B\tilde{x}$. Then, we have that

$$\tilde{y} = Ty = T(Ax) = TA(T^{-1}\tilde{x}) = (TAT^{-1})\tilde{x}.$$

So it follows that

$$B = TAT^{-1} = \begin{bmatrix} 3 & -10 & -8 \\ -1 & 8 & 4 \\ 2 & -13 & -7 \end{bmatrix}$$

is the matrix representation of \mathcal{T} with respect to $\{e'_1, e'_2, e'_3\}$.

- 3.4** Consider two bases of \mathbb{R}^4 , $\{e_1, e_2, e_3, e_4\}$ and $\{e'_1, e'_2, e'_3, e'_4\}$, where $e'_1 = e_1$, $e'_2 = e_1 + e_2$, $e'_3 = e_1 + e_2 + e_3$, and $e'_4 = e_1 + e_2 + e_3 + e_4$. Suppose that a linear transformation has a matrix representation in $\{e_1, e_2, e_3, e_4\}$ of the form

$$A = \begin{bmatrix} 2 & 0 & 1 & 0 \\ -3 & 2 & 0 & 1 \\ 0 & 1 & -1 & 2 \\ 1 & 0 & 0 & 3 \end{bmatrix}.$$

Find the matrix representation of this linear transformation in the basis $\{e'_1, e'_2, e'_3, e'_4\}$.

Solution. We have that

$$[e_1 \ e_2 \ e_3 \ e_4] = [e'_1 \ e'_2 \ e'_3 \ e'_4] \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

So the transformation matrix from $\{e'_1, e'_2, e'_3, e'_4\}$ to $\{e_1, e_2, e_3, e_4\}$ is given by

$$T = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

Consider the linear transformation $\mathcal{T} : \mathbb{R}^4 \rightarrow \mathbb{R}^4$ given by the matrix A with respect to the basis $\{e_1, e_2, e_3, e_4\}$ and by the matrix B with respect to the basis $\{e'_1, e'_2, e'_3, e'_4\}$. Let $y = Ax$ and $\tilde{y} = B\tilde{x}$. It follows that

$$\tilde{y} = Ty = T(Ax) = TA(T^{-1}\tilde{x}) = (TAT^{-1})\tilde{x}.$$

Hence, we have that

$$B = TAT^{-1} = \begin{bmatrix} 5 & 3 & 4 & 3 \\ -3 & -2 & -1 & -2 \\ -1 & 0 & -1 & -2 \\ 1 & 1 & 1 & 4 \end{bmatrix}$$

is the matrix representation of \mathcal{T} with respect to $\{e'_1, e'_2, e'_3, e'_4\}$.

- 3.6** Let $\lambda_1, \dots, \lambda_n$ be the eigenvalues of the matrix $A \in \mathbb{R}^{n \times n}$. Show that the eigenvalues of the matrix $I_n - A$ are $1 - \lambda_1, \dots, 1 - \lambda_n$.

Proof. Let $A \in \mathbb{R}^{n \times n}$. Suppose that v_1, v_2, \dots, v_n are eigenvectors of A with corresponding eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$. Then for each i such that $1 \leq i \leq n$, we have that

$$(I_n - A)v_i = v_i - Av_i = v_i - \lambda_i v_i = (1 - \lambda_i)v_i.$$

As such, we have shown that $1 - \lambda_1, 1 - \lambda_2, \dots, 1 - \lambda_n$ are the eigenvalues of the matrix $I_n - A$. \square

- 3.11** Let \mathcal{V} be a subspace. Show that $(\mathcal{V}^\perp)^\perp = \mathcal{V}$. *Hint:* Use Exercise 3.10.

Proof. We first show that $\mathcal{V} \subset (\mathcal{V}^\perp)^\perp$. Let $x \in \mathcal{V}$ and $y \in \mathcal{V}^\perp$. By definition, we have that

$$\langle x, y \rangle = 0.$$

Since $(\mathcal{V}^\perp)^\perp$ contains all vectors which are orthogonal to every vector in \mathcal{V}^\perp , it follows that $\mathcal{V} \subset (\mathcal{V}^\perp)^\perp$. We will now show that $(\mathcal{V}^\perp)^\perp \subset \mathcal{V}$. Let $\{a_1, a_2, \dots, a_l\}$ be a basis for \mathcal{V} and $\{b_1, b_2, \dots, b_k\}$ be a basis for $(\mathcal{V}^\perp)^\perp$. Define the matrix A such that a_i is the i th column of A for each $i = 1, 2, \dots, l$ and also B such that b_i is the i th column of B for each $i = 1, 2, \dots, k$. We clearly have that $\mathcal{R}(A) = \mathcal{V}$ and $\mathcal{R}(B) = (\mathcal{V}^\perp)^\perp$. From Exercise 3.10, we want to show that $\mathcal{R}(B) \subset \mathcal{R}(A)$, so we must show that $\mathcal{N}(A^\top) \subset \mathcal{N}(B^\top)$. Let $x \in \mathcal{N}(A^\top)$. We know that by definition

$$x \in \mathcal{N}(A^\top) = \mathcal{R}(A)^\perp = \mathcal{V}^\perp.$$

From this, for any $w \in (\mathcal{V}^\perp)^\perp$,

$$(Bw)^\top x = w^\top B^\top x = 0 \Rightarrow B^\top x = 0,$$

so $x \in \mathcal{N}(B^\top)$. Hence $(\mathcal{V}^\perp)^\perp \subset \mathcal{V}$. We therefore have shown that $\mathcal{V} \subset (\mathcal{V}^\perp)^\perp \subset \mathcal{V}$, so $\mathcal{V} = (\mathcal{V}^\perp)^\perp$. \square

- 3.13** Let \mathcal{V} be a subspace of \mathbb{R}^n . Show that there exist matrices V and U such that $\mathcal{V} = \mathcal{R}(V) = \mathcal{N}(U)$.

Proof. Let $m = \dim \mathcal{V}$. We fix a basis $\{v_1, v_2, \dots, v_m\}$ and let the i th column of the matrix V be v_i for each $i = 1, 2, \dots, m$. Clearly then $\mathcal{R}(V) = \mathcal{V}$, as the number of linearly independent columns of V is equal to the dimension of \mathcal{V} . Now suppose that we let $\{w_1, w_2, \dots, w_{n-m}\}$ be a basis for \mathcal{V}^\perp . Let the i th row of the matrix U be w_i^\top for each $i = 1, 2, \dots, n - m$. We then have that $\mathcal{R}(U^\top) = \mathcal{V}^\perp$. Hence, using the results of Exercise 3.11 and Theorem 3.4, it follows that

$$(\mathcal{V}^\perp)^\perp = \mathcal{V} = \mathcal{R}(U^\top)^\perp = \mathcal{N}((U^\top)^\top) = \mathcal{N}(U).$$

So we have constructed matrices V and U such that $\mathcal{V} = \mathcal{R}(V) = \mathcal{N}(U)$. \square

- 3.14** Let P be an orthogonal projector onto a subspace \mathcal{V} . Show that

- (a) $Px = x$ for all $x \in \mathcal{V}$.

Proof. Note that for any $x \in \mathcal{V}$, we can write $x = Px + (I - P)x$, which is an orthogonal decomposition of x with respect to \mathcal{V} where $Px \in \mathcal{V}$ and $(I - P)x \in \mathcal{V}^\perp$. However, $x = x + 0$ is also an orthogonal decomposition. Since orthogonal decompositions are unique, this implies that $x = Px$ for all $x \in \mathcal{V}$. \square

(b) $\mathcal{R}(\mathbf{P}) = \mathcal{V}$.

Proof. Let \mathbf{P} be an orthogonal projector onto \mathcal{V} . By definition, we have that $\mathcal{R}(\mathbf{P}) \subset \mathcal{V}$. From part (a), we showed that $\mathbf{P}\mathbf{x} = \mathbf{x}$ for all $\mathbf{x} \in \mathcal{V}$, so we also have that $\mathcal{V} \subset \mathcal{R}(\mathbf{P})$. Combining these, we have that $\mathcal{V} \subset \mathcal{R}(\mathbf{P}) \subset \mathcal{V}$, and therefore $\mathcal{R}(\mathbf{P}) = \mathcal{V}$. \square

3.18 For each of the following quadratic forms, determine if it is positive definite, negative definite, positive semidefinite, negative semidefinite, or indefinite.

(a) $f(x_1, x_2, x_3) = x_2^2$

Solution. We have that

$$f(x_1, x_2, x_3) = x_2^2 = \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}.$$

Hence

$$\mathbf{Q} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

where the eigenvalues of \mathbf{Q} are $\lambda_1 = 0$, $\lambda_2 = 0$, and $\lambda_3 = 1$. So this quadratic form is positive semidefinite.

(b) $f(x_1, x_2, x_3) = x_1^2 + 2x_2^2 - x_1x_3$

Solution. We have that

$$f(x_1, x_2, x_3) = x_1^2 + 2x_2^2 - x_1x_3 = \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 1 & 0 & -\frac{1}{2} \\ 0 & 2 & 0 \\ -\frac{1}{2} & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}.$$

Therefore

$$\mathbf{Q} = \begin{bmatrix} 1 & 0 & -\frac{1}{2} \\ 0 & 2 & 0 \\ -\frac{1}{2} & 0 & 0 \end{bmatrix},$$

where the eigenvalues of \mathbf{Q} are $\lambda_1 = 2$, $\lambda_2 = (1 - \sqrt{2})/2$, and $\lambda_3 = (1 + \sqrt{2})/2$. This quadratic form is indefinite.

(c) $f(x_1, x_2, x_3) = x_1^2 + x_3^2 + 2x_1x_2 + 2x_1x_3 + 2x_2x_3$

Solution. We have that

$$f(x_1, x_2, x_3) = x_1^2 + x_3^2 + 2x_1x_2 + 2x_1x_3 + 2x_2x_3 = \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}.$$

Therefore

$$\mathbf{Q} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix},$$

where the eigenvalues are $\lambda_1 = 0$, $\lambda_2 = 1 - \sqrt{3}$, and $\lambda_3 = 1 + \sqrt{3}$. This quadratic form is therefore indefinite.

3.20 Consider the quadratic form

$$f(x_1, x_2, x_3) = x_1^2 + x_2^2 + 5x_3^2 + 2\xi x_1x_2 - 2x_1x_3 + 4x_2x_3.$$

Find the values of the parameter ξ for which this quadratic form is positive definite.

Solution. This quadratic form can be written as

$$f(\mathbf{x}) = \mathbf{x}^\top \mathbf{Q} \mathbf{x}$$

where we have that

$$Q = \begin{bmatrix} 1 & \xi & -1 \\ \xi & 1 & 2 \\ -1 & 2 & 5 \end{bmatrix}$$

for some $\xi \in \mathbb{R}$. The leading principal minors of Q are $\Delta_1 = 1$, $\Delta_2 = 1 - \xi^2$, and $\Delta_3 = -5\xi^2 - 4\xi$. By Sylvester's Criterion, Q is positive definite if and only if all leading principal minors of Q are positive. Hence we want to find the values of ξ such that $1 - \xi^2 > 0$ and $-5\xi^2 - 4\xi > 0$. We know that $1 - \xi^2 > 0$ for $\xi \in (-1, 1)$. Furthermore, we have that

$$\xi = -\frac{4 \pm 4}{10} \Rightarrow \xi = 0, -\frac{4}{5},$$

meaning that since $-5\xi^2 - 4\xi$ has a negative leading coefficient, $-5\xi^2 - 4\xi > 0$ when $\xi \in (-\frac{4}{5}, 0)$. Therefore, since $(-1, 1) \cup (-\frac{4}{5}, 0) = (-\frac{4}{5}, 0)$, Q is positive definite when $\xi \in (-\frac{4}{5}, 0)$.