



Multiparty Session C Safe Parallel Programming with Message Optimisation TOOLS 2012

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Motivation

- Parallel architectures
 - Efficient use of hardware resources
 - eg. Multicore processors, computer clusters
 - Difficult to program (correctly)
- One source of error
 - Communication mismatch (send-receive)
 - Communication deadlocks



Motivating example: Deadlock

```
if (rank == 0) { // Program 0
    MPI_Send(a, 5, MPI_INT, 1, TAG, MPI_COMM_WORLD);
    MPI_Recv(b, 5, MPI_INT, 1, TAG, MPI_COMM_WORLD);
} else if (rank == 1) { // Program 1
    MPI_Send(b, 5, MPI_INT, 0, TAG, MPI_COMM_WORLD);
    MPI_Recv(a, 5, MPI_INT, 0, TAG, MPI_COMM_WORLD);
}
```

Program 0	Program 1		
Send a		Send b	_
Recv b	₩	Recv a	





Contribution

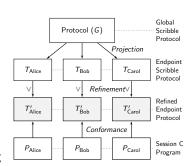
- An intuitive programming framework and toolchain
 - For message-passing parallel programming
 - Based on formal and explicit interaction protocol
- First multiparty session-based programming environment for the low-level C language
 - Focussing on high performance, low latency
- Session type checker
 - Static checks
 - communication safety/deadlock freedom
 - Supports asynchronous subtyping for optimisation
- Evaluation with parallel algorithms implementation





Session C programming: Overview

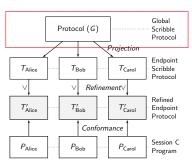
- Top down approach
- Based on multiparty session types (MPST) [Honda et al., POPL'08]
 - Communication should have a dual
 - Communication safety and deadlock freedom by typing





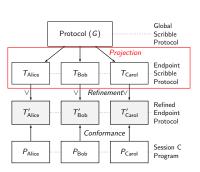


- 1. Design protocol in global view
- Automatic projection to endpoint protocol, algorithm preserves safety
- Write program according to endpoint protocol
- 4. Check program conforms to protocol
- 5. \Rightarrow Safe program by design



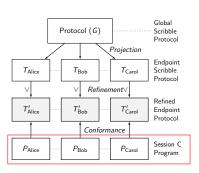


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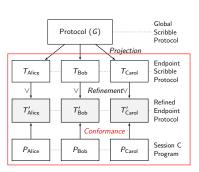


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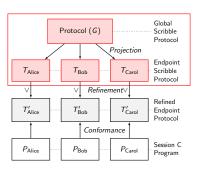
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Scribble protocol specification language

- Developer friendly language to describe communication protocol (Red Hat, www.scribble.org)
- Interaction by message passing
- Captures flow-control elements of communication protocol





Scribble protocol specification language: Example

```
/* Global protocol */
protocol Simple
  (role P1, role P2, role P3) {
  int from P1 to P2;
  char from P3 to P1;
  float from P2 to P3
}
```

```
int
     char
            float
```



Scribble protocol specification language: Example

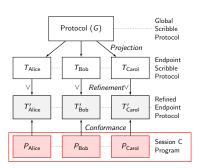
```
/* Endpoint protocol for P2 */
protocol Simple at P2
  (role P1, role P3) {
  int from P1;
  float to P3;
}
```

```
int
      char
             float
```



Session C runtime

- Message passing communication API
- Built on 0MQ socket library
- Aim: simple and lightweight





Session C runtime

- Basic primitives
 - Message passing
 - ▶ Iteration
 - Choice
- Advanced primitives
 - Multicast
 - Multi-channel iteration

- Primitives corresponds to protocol statements
- Most C features allowed with a few exceptions



Session C runtime: Examples

Iteration and message passing

```
while (i<3) {
    send_int(A, 42);
}</pre>
while (i<3) {
    int val; recv_int(B, &val);
}</pre>
```

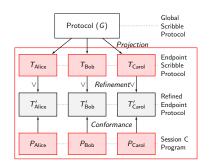
Directed choice

```
if (i<3) { // Choice from
  outbranch(B, LABEL0);
  send_int(B, 12);
} else {
  outbranch(B, LABEL1);
  send_char(B, 'A');
}</pre>
// Choice to
switch (inbranch(A, &label)) {
  case LABEL0:
    recv_int(A, &ival); break;
  case LABEL1:
    recv_char(A, &cval); break;
}
```



Session Type checking

- Static analyser
- Verify source code conforms with specification (endpoint protocol)

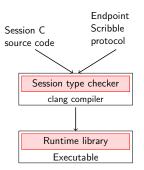






Session Type checking

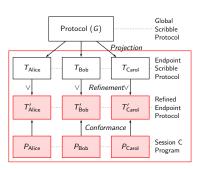
- Implemented as a LLVM/clang compiler plugin
- Part of compilation process
- Session typing extracted based on usage of API





Session Type checking: Asynchronous optimisation

- Protocols designed safe, not necessarily efficient
- Asynchronous communication
 - non-blocking send
 - blocking receive
- Send/receive operation can overlap

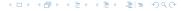




Asynchronous optimisation

- Asynchronous operations can be safely permuted [Mostrous et al., ESOP'09]
- Pipelines impossible in 'strict' multiparty session types, possible with asynchronous subtyping
- Safe pipeline improves performance

A:send B:recv C:recv		
C:recv		
	Α	В





Asynchronous optimisation

- ► Asynchronous operations can be **safely** permuted [Mostrous et al., ESOP'09]
- Pipelines impossible in 'strict' multiparty session types, possible with asynchronous subtyping
- Safe pipeline improves performance

Stage I	Stage II	Stage III			
A:send → B:recv					
	B:send	C:recv			
A:recv					



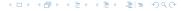


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- Safe pipeline improves performance

```
A:send→B:recv
B:send→C:recv
A:recv
C:send
```

 $\begin{bmatrix} \mathsf{A} \end{bmatrix} \longrightarrow \begin{bmatrix} \mathsf{B} \end{bmatrix} \longrightarrow \begin{bmatrix} \mathsf{C} \end{bmatrix}$





Asynchronous optimisation

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```
Stage I Stage II Stage III

A:send -> B:recv

B:send -> C:recv

-> A:recv

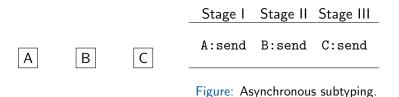
C:send ->
```

 $A \longrightarrow B \longrightarrow C$



Asynchronous optimisation

- Asynchronous operations can be safely permuted [Mostrous et al., ESOP'09]
- Pipelines inefficient in 'strict' multiparty session types
- Efficient pipelines with asynchronous subtyping of MPST

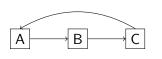






Asynchronous optimisation

- Asynchronous operations can be safely permuted [Mostrous et al., ESOP'09]
- Pipelines inefficient in 'strict' multiparty session types
- Efficient pipelines with asynchronous subtyping of MPST



```
Stage I Stage II Stage III
```

A:send B:send C:send A:recv B:recv C:recv

Figure: Asynchronous subtyping.





Parallel algorithms

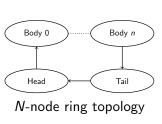
- Demonstrating the expressiveness of MPST
- Performance evaluation: Static session types based approach do not degrade performance
- Example representative topologies
 - 1. N-body simulation: Ring topology
 - 2. Jacobi solution for the DPE: Mesh topology
 - 3. Linear equation solver: Warparound mesh topology
 - 4. Fast Fourier Transformation: Butterfly topology





N-body simulation: Ring topology (1)

- ▶ Input segmented to *n* parts
- Results shifted right until all nodes worked on all segments



```
protocol Nbody /* Global protocol */
   (role Head, role Body, role Tail) {
   rec NrOfSteps {
    rec SubCompute {
     particles from Head to Body;
     particles from Body to Tail;
     particles from Tail to Head;
     SubCompute; }
   NrOfSteps; }
}
```



N-body simulation: Ring topology (2)

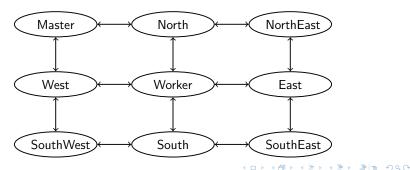
```
/* Endpoint Protocol */
                             /* Implementation of Body worker */
protocol Nbody at Body
                              particle_t *ps, *tmp_ps;
    (role Head, role Tail) { while (iterations ++ < ITERS_NR) {
 rec NrOflters {
                               while (rounds++ < NODES_NR) {
    rec SubCompute {
                                 send_particles( Tail , tmp_ps);
      particles from Head;
                                 // Update veclocities
      particles to Tail;
                                 compute_forces(ps, tmp_parts ,...);
                                 recv_particles (Head, &tmp_ps);
      SubCompute;}
                               } // Update positions
                                 // by received velocities
    NrOfIters;}
                               compute_positions(ps, pvs, ... );
```

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Jacobi solution for the DPE: Mesh topology

- Input segmented to 2D sub-grids
- ► Edge results exchanged between each neighbours
- ► Takes full advantage of asynchronous message optimisation



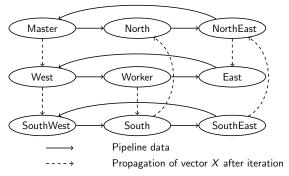
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Linear equation solver: Wraparound mesh

Rows: Ring topology

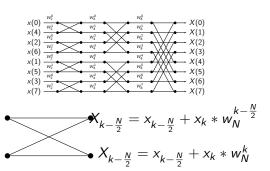
Columns: Diagonal propagates result to all in least distance





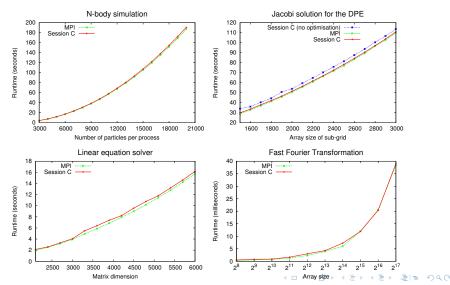
Fast Fourier Transformation: Butterfly topology

- Binary session types cannot efficiently represent
- Butterfly exchange: asynchronous optimisation



 X_k

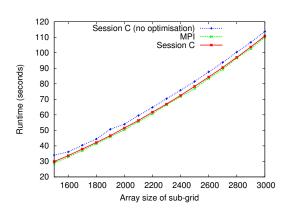






Benchmark results: highlight

- Jacobi method for the Discrete Poisson Equation
- Mesh topology
- Asynchronous optimisation: 8% improvement







Related works

- MPI Deadlock detection by model checking
 - ► ISP/DAMPI [Vo et al., PPoPP'09/SC'10]
 - ► TASS [Siegel et al., PPoPP'11]
- Formally founded HPC languages
 - ▶ Pilot [Carter et al., IPDPSW'10] combines CSP and MPI
 - ▶ Occam-pi language : CSP and π -calculus
 - ► X10 [Lee et al., PPoPP'10] : PGAS
 - Session Java [Hu et al., ECOOP'08] applied in parallel programming setting [Ng et al., COORDINATION'11]





Conclusion

- Introduced a programming framework and toolchain for communication safe parallel programming in C
 - Based on formal and explicit interaction protocol
 - Low-level programming environment (C language)
 - Static type checker to verify implementation matches protocol
 - Type checker supports asynchronous subtyping for optimisation
 - Communication safety and deadlock freedom by type checking
 - Static type checking does not degrade performance





Ongoing and future work

- ► Integrate with heterogeneous cluster with FPGA-acceleration [Ng et al., HEART'12]
- ► Parametrised processes for multiple replicated process [Denielou et al., FoSSaCS'10]
- Ongoing collaboration with Red Hat on Scribble project
- Memory/pointer safety by integrating Cyclone [Jim et al., USENIX ATC'02]





Try it!

Latest version on GitHub http://www.github.com/nickng/sessc