Communication Safe Application Parallelisation with Session Types

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Background

- ► Parallel programming difficult to master, error prone
- ► Parallel application = computation + synchronisation



- ► Aim: **Simplify** parallel programming
- ► Minimal effort to develop parallel program from sequential code
- ► Safety guarantees to ensure parallel application is correct
- ► Proposed approach: Separation of concern
 - **▶ Developer** focuses on functional computation code
 - ► Parallel expert focuses on parallelising and communication
- ► Communication safety guaranteed by Session Types

Our proposal: Pabble protocol description language

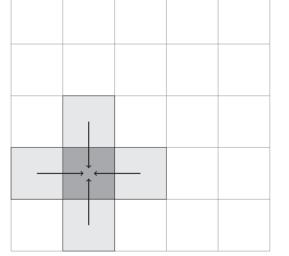
- ► Pabble: Parameterised Scribble [5]
 - ► Scalable communication protocol description language
 - ► Specific for parallel programming
 - ► Use **parameters** on participants to scale protocols
 - Guarantees communication safety and deadlock free
- ► Formal basis: Multiparty Session Types (MPST) [4]
 - **► Typing system** for communication
- ► Idea: Communication interactions are **dual** (Send vs. Receive)
- ▶ Parametric variant: Parameterised MPST [2]
- ▶ Derived from Scribble project [3]
 - Developer-friendly protocol language for distributed systems
 - ► Academia-industry collaboration to make MPST accessible

References

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Developer input: Sequential code

- ▶ Defines functional behaviour
- ► Isolates computation in **kernels**
- ► C source code with annotations
- ▶ e.g. Label a section of code
- ► e.g. Partitioning instructions



Example: 5-point stencil Sequential code

```
int main(int argc, char *argv[])
 for (int h=0; h<H; h++)</pre>
   for (int w=0; w<W; w++)</pre>
     if (1<=h && h<=H-2 && 1<=w && w<=W-2) {
       tmp[h*W+w] = (mtx[(h-1)*W+w] + mtx[(h+1)*W+w]
                    + mtx[h*W+w]
                    + mtx[h*W+(w-1)] + mtx[h*W+(w+1)])/5;
 return EXIT_SUCCESS;
```

Parallel expert input: Communication topology

- ► Parallel interaction structure
- ▶ i.e. Communication topology
- ▶ Pabble protocol language
 - ► Non-application specific
 - ► Scalable parallel protocols
 - **▶** Communication safety for free!

P[0][N] P[0][0] + → P[0][1] **‹**·· P[i][j]→ P[1][N] → P[M][1] ‹··· → P[M][N] P[M][0] +

Example: M-by-N mesh for partitioned subproblems

```
rec Iterate {
          from P[i:1..M][j:0..N] to P[i-1][j];
  Up(int)
  Down(int) from P[i:0..M-1][j:0..N] to P[i+1][j];
  Left(int) from P[i:0..M][j:1..N] to P[i][j-1];
  Right(int) from P[i:0..M][j:0..N-1] to P[i][j+1];
  continue Iterate;
```

Output: MPI Parallel application

- ▶ Code generation by aspect-oriented compilation [1]
- Parallelise for distributed execution by MPI
- ► Computation: analyse & extract from sequential code
- **► Communication**: define with **Pabble protocol**

Example:

```
Parallelised MPI application
#include <mpi.h>
int main(int argc, char *argv[])
{ MPI_Init(&argc, &argv);
 while (1) {
   tmp = calculate_subproblem(mtx, H, W);
   i = rank/W; j = rank%W;
                                  MPI_Recv(rank-W,Up);
   if (1<=i&&i<=M&&O<=j&&j<=N)</pre>
   if (0<=i&&i<=M-1&&0<=j&&j<=N)
                                  MPI_Send(rank+W,Up);
   if (0<=i&&i<=M-1&&0<=j&&j<=N)</pre>
                                  MPI_Recv(rank+W,Down);
   if (1<=i&&i<=M&&O<=j&&j<=N)</pre>
                                   MPI_Send(rank-W,Down);
 MPI_Finalize();
 return EXIT_SUCCESS;
```