

Internship Report

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Multi-Plane Light Conversion

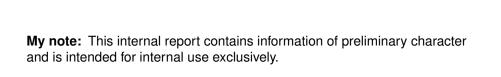
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Multi-Plane Light Conversion

Multi-Plane Light Conversion (MPLC) has emerged as a highly versatile method for manipulating the spatial distribution of optical fields, utilizing repeated phase modulations to precisely reshape light [4]. This approach is essential for applications that leverage specific wave properties, such as spatial coherence, wavefront curvature, and modal structure. These properties are crucial in fields like imaging, optical communication, and quantum optics, where differentiating and exploiting these characteristics allow for enhanced performance and functionality.

For example, spatial decomposition remains relatively underdeveloped compared to spectral or polarization decomposition, which are more established methods for separating light based on frequency or electromagnetic orientation. A common spatial decomposition technique is Fourier decomposition, performed using a lens to separate a beam into its linear momentum components in two dimensions. However, this method is limited because it may not provide the most suitable spatial basis for certain applications, especially those requiring precise transformations between specific orthogonal beam sets [2].

MPLC addresses these challenges by employing a series of phase masks interspaced with free-space propagation. This configuration enables highly accurate transformations between orthogonal beam sets through unitary operations. The ability to achieve such precise spatial control of light is opening new possibilities in applications where control over wave properties is critical. In this report, we present two algorithms for calculating phase masks and offer a comprehensive, step-by-step tutorial for implementing each algorithm in Python.

The Wavefront Matching Algorithm [3]

The Wavefront Matching (WFM) method is a promising approach to designing optical waveguides by generating precise refractive index patterns based on desired optical characteristics. Unlike traditional cut-and-try methods, WFM synthesizes an optimized waveguide structure directly from input and output requirements, leading to efficient designs with reduced computational resources [3].

First, for simplicity, we consider a slab waveguide with a single input and output port. In this setup, the input light propagates along the z-axis, with the waveguide situated on the x-z plane. The y-axis is omitted for simplicity in this 2-D model. The objective is to design a waveguide pattern that accurately guides the input beam to the designated output port [3].

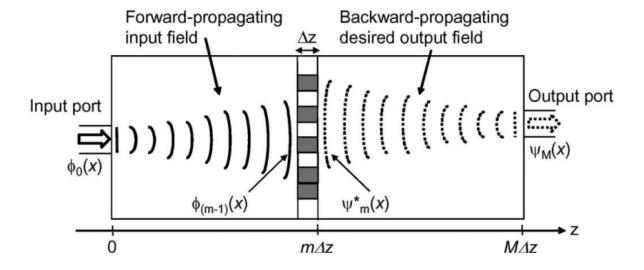


Figure 1 2D Slab waveguide with single input and output port [3]

The input light field is $\phi_0(x)$, and the desired output field is $\psi_M(x)$, where x is the lateral coordinate, and the subscripts 0 and M represent the calculation steps along the z-axis. The optimization region is divided into pixels of size Δz (along z) and Δx (along x), each made of core or cladding material. The coupling efficiency η between the output and target fields is given by the overlap integral:

$$\eta = \left| \int \psi_M^*(x) \phi_M(x) \, dx \right|^2.$$

where $\phi_M(x)$ is the output field after the optimized region.

By dividing the medium into discrete steps along the propagation direction and simulating the behavior of the optical field as it passes through each step, the output field $\phi_M(x)$ is expressed as:

$$\phi_M(x) = (AB_MA) \cdots (AB_mA) \cdots (AB_1A)\phi_0(x),$$

where:

- A: Free-space propagation operator,
- $B_m(x)$: Phase modulation operator,
- n_{ref} : Reference refractive index,
- $n_m(x)$: Refractive index at $z = m\Delta z$.

Since refractive index, n(x), varies spatially we use reference refractive index, n_{ref} , which provides a stable reference, to avoid recalculating the absolute propagation constant at every point. The calculations are then performed on the relative difference, $n(x)-n_{\text{ref}}$, which represents variations that influence the light's behavior.

Hence the coupling efficiency η becomes:

$$\eta = \left| \int \psi_M^*(x) A B_M A \cdots (A B_m A) \cdots A B_1 A \phi_0(x) \, dx \right|^2.$$

Using the reciprocity, that is transmission of light between two points is invariant if the direction of propagation is reversed, the left side of (AB_mA) is equivalent to the backward-propagating field $\psi_m^*(x)$ simplifing η to:

$$\eta = \left| \int \psi_m^*(x) A B_m A \phi_{m-1}(x) \, dx \right|^2.$$

To optimize the waveguide design, the refractive index distribution $n_m(x)$ is adjusted to maximize η . Introducing a small change $\delta n_m(x)$, the phase shift operator becomes:

$$B'_m \approx B_m (1 - jk\delta n_m(x)\Delta z)$$
,

assuming $k\delta n_m(x)\Delta z\ll 1$. The updated coupling coefficient η' is:

$$\eta' \approx \eta + 2k\Delta z \sqrt{\eta} \int \Im \left[\psi_m^*(x)\phi_{m-1}(x)\right] \delta n_m(x) dx.$$

This demonstrates that the coupling efficiency can always be improved by setting $\delta n_m(x)$ proportional to $\Im[\psi_m^*(x)\phi_{m-1}(x)]$. In physical terms, to obtain the optimum waveguide pattern we need to match the wavefronts of the forward-propagating input field and the backward-propagating desired output field, by changing local refractive-index distribution.

The basic algorithm described can be extended to handle systems that involve a higher number of optical modes, such as multimode waveguides. In such cases, instead of optimizing the coupling for a single mode, the algorithm adjusts the refractive index distribution to maximize coupling across multiple modes.

Furthermore, instead of physically altering the refractive index distribution in a waveguide, the same principle can be applied using phase masks. Phase masks are computationally designed elements that impose specific phase shifts on the propagating light. These masks can achieve the desired wavefront matching without requiring changes to the material properties of the waveguide.

The design of phase masks involves a numerical computation process. To determine the optimal phase masks for each plane in the optical system, the desired input basis is numerically propagated through the system in the forward direction. Simultaneously, the desired output basis is propagated in the reverse direction. At each step, the overlap between the forward and backward fields is calculated, and the phase mask for the current plane is adjusted to maximize this overlap.

In other words, at each iteration, the phase mask is updated to align with the phase of the superposition of the overlaps between each pair of input mode (ψ') and output mode (ϕ') . Meaning, the phase mask reflects the average phase error between the forward-propagating modes (ψ^i and the backwardpropagating modes (ϕ^i) . Mathematically, the phase ϕ at a given plane during an iteration is expressed

$$\theta_m = \arg\left(\sum_{i=1}^N (\psi_m^i(x))^* \phi_{m-1}^i(x)\right),\,$$

where N is the total number of modes. The phase masks are iteratively updated until convergence is achieved [2].

In our setup we choose spatially separated Gaussian beam in triangular shape array as a input modes (ϕ) and spatially co-located Hermite-Gaussian(HG) beam as output modes (ϕ) . The reason of our output mode choice stems from the fact that HG modes maintain their characteristic intensity and phase distribution as they propagate through free space. which ensures that the decomposition of a wavefront into HG modes remains consistent over distance, simplifying analysis and correction. For demonstration purposes we choose 10 modes and 10 planes but both these parameters can be changed and tested in simulation easily.

We can initialize the simulation by defining parameters of simulation constrains, input and output basis.

```
1 import Propagation as pg
2 import ModeGeneration as mg
3 import BasicFunctions as bf
4 import numpy as np
5 import matplotlib.pyplot as plt
7 # Simulation parameters
8 N = 128 \# pixel number
_{9} L = 0.0015 # grid size [m]
w = 90e-6 \# width of input [m]
11 w_{prime} = 200e-6 \# width of output [m]
12 delta = L / N # grid spacing [m]
wvl = 633e-9 \# optical wavelength [m]
z = 0.015 \# distance between phase masks [m]
15 angle= 0.05
maskOffset = np.sqrt(1e-3 / (N \star N \star 10)) \star 0.2
18 num_planes =10
19 \text{ num\_modes} = 10
20
22 \times = np.linspace(-N / 2, N / 2 - 1, N) * delta
y = np.linspace(-N / 2, N / 2 - 1, N) * delta * 1/np.cos(angle)
24 x, y = np.meshgrid(x, y)
26 TH, R = bf.cart2pol(x, y)
x0,y0 = bf.pol2cart(TH-np.pi/4,R)
29 #triangular shape array beams parameter
30 d = 2e-4 *2.1 \# Distance between the beams [m]
31 central_shift = 2e-4*2.6 #location of top beam [m]
32
33 def create_gaussian_beams_array(x, y, w, d, central_shift, num_beams):
      beams = []
      beam count = 0
35
      layer = 0
36
37
38
      while beam_count < num_beams:</pre>
        # Calculate the starting position for the current layer
          start_x = x - layer * d / 2
40
41
          start_y = y + central_shift - layer * np.sqrt(3) * d / 2
          # Generate beams in the current layer
43
          for i in range(layer + 1):
              if beam_count >= num_beams:
45
46
                 break
              beam_x = start_x + i * d
```

```
48
              beam_y = start_y
              beams.append(mg.hg_mode(beam_x, beam_y, w, 0, 0))
49
              beam_count += 1
50
51
52
          # Move to the next layer
          layer += 1
53
54
      return beams[:num_beams]
56
57
58 all_gaussian_beams = sum(create_gaussian_beams_array(x, y, w, d, central_shift, num_modes))
60
61
62 # Generate HG modes
  def generate_hg_modes_array(x, y, w_prime, mode_count):
     modes = []
64
      index = 0
65
66
      for m in range (mode_count + 1):
          for n in range(m + 1):
67
              if index >= mode_count:
69
                  return modes
70
              mode = mg.hg_mode(x, y, w_prime, m - n, n)
              modes.append(mode)
71
              index += 1
72
73
    return modes
75
77 input_modes = create_gaussian_beams_array(x, y, w, d, central_shift, num_modes)
output_modes = generate_hg_modes_array(x0, y0, w_prime,num_modes)
80
  #output_modes = mg.sort_and_limit_lg_modes(mg.generate_lg_modes_array(x0, y0, w_prime,3,3),
      num_modes)
81
82
  # Transfer function of free-space propagation
84 HO = bf.transfer_function_of_free_space(x, y, z, wvl)
86 # Phase masks
mask = np.exp(1j * np.angle(np.ones((N, N))))
88 phase_masks = []
89 for i in range(num_planes):
  phase_masks.append(mask)
```

As a result we created input beam basis that is Gaussian beams in triangular shape and output beam basis that is spatially co-located HG modes.

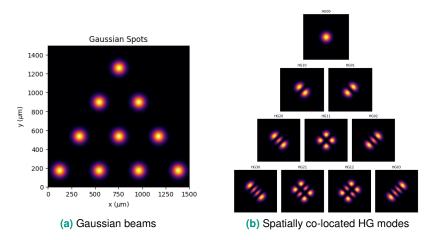


Figure 2 Gaussian beams and spatially co-located HG modes.

After defining all the necessary parameter for simulation we can use WFM algorithm to compute phase mask. We also includes fidelity of the algorithm which represents the overlap (or coupling efficiency)

between the *i*-th output mode and the *j*-th desired mode. Mathematically, it is defined as:

$$F_{ij} = \left| \int_{\text{all space}} \psi_j^*(x, y) \phi_i(x, y) \, dx \, dy \right|^2$$

where $\phi_i(x, y)$ is the optical field of the *i*-th output mode at the output and $\psi_j(x, y)$ is the desired *j*-th mode field. Off-diagonal elements in the coupling matrix F_{ii} indicate coupling between unintended modes, a phenomenon called mode crosstalk. A well-optimized system minimizes these off-diagonal terms, ensuring that each desired mode is produced without contamination by others. The coupling matrix serves as a feedback mechanism for iterative algorithms like the Wavefront Matching Method (WFM). For this reason we also plot diagonal elements of coupling matrix (Fidelity) versus number of iteration to check the performance of WFM algorithm.

```
opt_list=[]
2 num_iterations = 50
  for iteration in range(num_iterations):
     output_modes = generate_hg_modes(x0, y0, w_prime,num_modes) #backward
     input_modes = create_gaussian_beams(x, y, w, d, central_shift, num_modes) #forward
9
     for distance_z in range(len(phase_masks), 0, -1):
         # Reset the output modes for each distance_z
10
         output_modes = generate_hg_modes(x0, y0, w_prime,num_modes) #backward
         # Reverse loop through the phase masks based on the current distance_z
         for i in range(len(phase_masks) - 1, len(phase_masks) - distance_z , -1):
14
             # First, propagate the output modes
             output_modes = [propagate(output_mode, np.conj(H0)) for output_mode in
16
     output_modes]
            # Apply the current phase mask and propagate again
            output_modes = [output_mode * np.exp(1j*np.angle(phase_masks[i])) for output_mode
18
     in output_modes]
19
         # Final propagation for output_modes at the current distance_z
20
         output modesl
         output_modes_at_mask]
23
         # Propagate the input modes
         25
         pwr_input_modes_at_mask = [np.sum(np.abs(modes)**2) for modes in input_modes_at_mask]
26
27
28
         o_v = []
         dphi =[]
30
31
         MSK=0
         for i in range(len(input_modes)):
33
             o_v.append((input_modes_at_mask[i] * np.conj(output_modes_at_mask[i]))/np.sqrt(
     pwr_output_modes_at_mask[i]*pwr_input_modes_at_mask[i]))
35
            dphi.append(np.sum(o_v[i]*np.conj(phase_masks[len(phase_masks)-distance_z])))
         for i in range(len(input_modes)):
36
            MSK = MSK + o_v[i]*np.exp(-1j*np.angle(dphi[i]))
37
38
         phase_masks[len(phase_masks)-distance_z] = MSK + maskOffset
39
40
         # Multiply the input beams by the current updated phase mask
41
         input\_modes = [inputs * np.exp(-1j*np.angle(phase\_masks[len(phase\_masks)-distance\_z])) \\
42
      for inputs in input_modes_at_mask]
43
     output_modes = generate_hg_modes(x0, y0, w_prime,num_modes)
44
45
     input_modes = create_gaussian_beams(x, y, w, d, central_shift, num_modes) #forward
46
47
49
50
     for distance_z in range(len(phase_masks), 0, -1):
         # Reset the input modes for each distance_z
51
         input_modes = create_gaussian_beams(x, y, w, d, central_shift, num_modes) #forward
52
53
         # Loop forward through the phase masks based on the current distance_z
54
         for i in range(0, distance_z - 1, 1):
```

```
56
                             # First, propagate the input modes
                             input_modes = [propagate(input_mode,H0) for input_mode in input_modes]
 57
                             # Apply the current phase mask and propagate again
 58
                             input\_modes = [input\_mode * np.exp(-1j*np.angle(phase\_masks[i])) \\ for input\_mode \\ input\_mode
 59
               input_modes]
 60
                     # Final propagation for input_modes at the current distance_z
 61
                     pwr_input_modes_at_mask = [np.sum(np.abs(modes)**2) for modes in input_modes_at_mask]
 63
 64
                     # Propagate the output modes
                    output_modes_at_mask = [propagate(output_mode, np.conj(H0)) for output_mode in
 66
             output_modes]
 67
                    output_modes_at_mask]
 68
                     ov = []
 69
                     dphi =[]
 70
 71
                     MSK=0
                     for i in range(len(input_modes)):
 72
 73
                            o_v.append((input_modes_at_mask[i] * np.conj(output_modes_at_mask[i]))/np.sqrt(
 74
             pwr_output_modes_at_mask[i]*pwr_input_modes_at_mask[i]))
                            dphi.append(np.sum(o_v[i]*np.conj(phase_masks[distance_z - 1])))
 75
 76
 77
                     for i in range(len(input_modes)):
                            MSK = MSK + o_v[i]*np.exp(-lj*np.angle(dphi[i]))
 78
 79
                     phase_masks[distance_z - 1] = MSK + maskOffset
 81
 82
                     \# Multiply the output beams by the current updated phase mask
                     output_modes = [outputs * np.exp(1j*np.angle(phase_masks[distance_z - 1])) for outputs
 83
               in output_modes_at_mask]
             output_modes = generate_hg_modes(x0, y0, w_prime,num_modes)
 85
 86
             input_modes = create_gaussian_beams(x, y, w, d, central_shift, num_modes) #forward
 88
             for i in range(len(phase_masks),0, -1):
                     output_modes = [ propagate(output_mode,np.conj(H0)) for output_mode in output_modes]
 89
                    output_modes = [output_mode * np.exp(1j*np.angle(phase_masks[i - 1])) for output_mode
 90
             in output_modes]
 91
                    92
 93
                     for i in range(len(output_modes)):
                             output_modes[i] = output_modes[i]/np.sqrt(pwr_output_modes[i])
 94
 95
             final_output = [ propagate(output_mode,np.conj(H0)) for output_mode in output_modes]
 96
97
 98
             tr_matrix=[]
100
             for i in range(len(output_modes)):
                     tr_matrix.append(np.sum(np.abs(input_modes[i]*np.conj(final_output[i]))))
101
             tr_matrix = np.sum(tr_matrix)/len(output_modes)
102
103
         opt_list.append(tr_matrix)
```

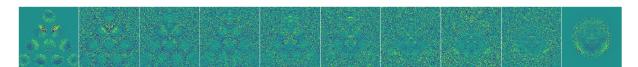
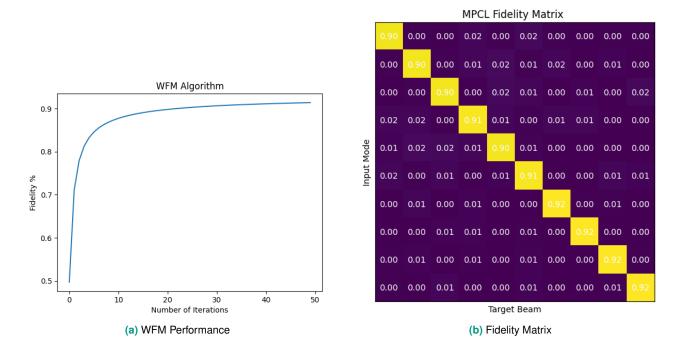


Figure 3 Phase masks generated by Wavefront Matching Algorithm

After running algorithm we were able to get phase masks as shown in Figure 3. Then, we propagate spatially co-located HG modes(2) through these phase mask and got following results:



Figure 4 Spatially co-located HG modes propagated through computed phase masks



As can be seen on fidelity matrix we achieved %90 fidelity and maximum % 2 cross-talk by using 10 modes, 10 phase masks with 50 iteration.

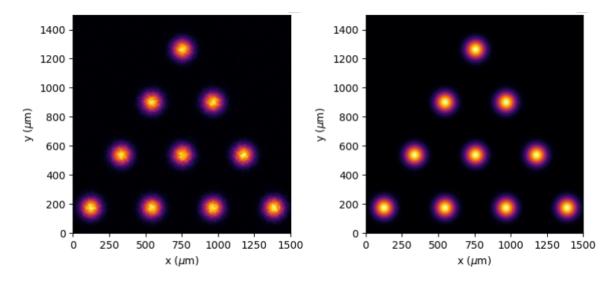


Figure 5 Sum of all the intensities of (on the left) output mode and (on the right) desired output using HG basis

Similarly, the simulation can be compiled with different orthogonal modes. With Laguerre-Gaussian (LG) basis using the same configuration 10 modes, 10 phase mask and 50 iteration we achieved %90 fidelity and maximum % 3 cross-talk.

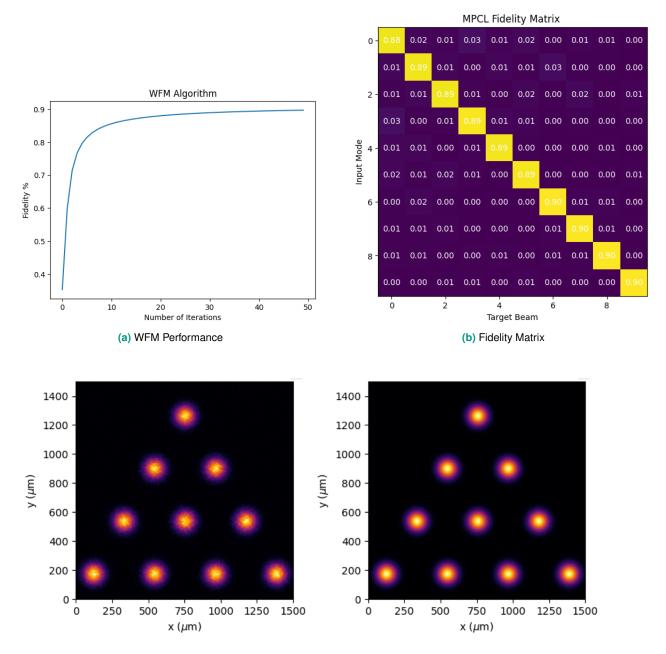


Figure 6 Sum of all the intensities of (on the left) output mode and (on the right) desired output using LG basis

Gradient Ascent-Based Algorithm [1]

The gradient ascent-based (GAB) optimization algorithm is a robust method used to design the phase profiles of phase masks. This algorithm iteratively updates the phase values of the masks to maximize a predefined objective function. By doing so, it ensures high-fidelity mode sorting while accounting for cross-talk and efficiency [1]. The objective function used in this optimization balances fidelity, crosstalk suppression, and efficiency. It is expressed as:

$$F_T = \sum_{i=1}^N F_i,$$

where F_i is the contribution from the *i*-th mode and is defined as:

$$F_{i} = \alpha \left| \psi_{i}^{*} \cdot \phi_{i} \right|^{2} - \beta \Re \left[\psi_{i}^{*} \cdot \psi_{i}^{\text{cr}} \right] + \gamma \Re \left[\psi_{i}^{*} \cdot \psi_{i}^{\text{bk}} \right].$$

Here:

- ψ_i : Forward-propagated field for the *i*-th mode.
- ϕ_i : Target output mode.
- $\psi_i^{cr} = \psi_i \odot \phi_{cr}$: Cross-talk contribution for the *i*-th mode, derived using the mask ϕ_{cr} that defines regions corresponding to incorrect output channels.
- $\psi_i^{bk} = \psi_i \odot \phi_{bk}$: Background light contribution, derived using the mask ϕ_{bk} for regions outside all output channels.
- α, β, γ : Weights for fidelity, cross-talk suppression, and efficiency, respectively.

The term ψ_{bk} represents the portion of light directed into a designated background region outside the defined output channels and is used in the efficiency term of the objective function. It is defined as $\psi_{\rm bk} = \psi_n \odot \phi_{\rm bk}$, where \odot denotes the Hadamard product with a mask $\phi_{\rm bk}$ that defines the background region, having values of 1 in the background and 0 within the output channels. Increasing ψ_{bk} allows deliberate scattering of light to non-output regions, which can improve fidelity or reduce cross-talk. On the other hand, ψ_{cr} represents the portion of light contributing to cross-talk between output channels and is part of the cross-talk penalty term in the objective function. It is defined as $\psi_{cr} = \psi_n \odot \phi_{cr}$, where the mask ϕ_{cr} has values of 1 in regions corresponding to incorrect output channels and 0 in the correct channel and other areas. Minimizing ψ_{cr} reduces light leakage into unintended channels.

The gradient of F_i with respect to ψ_i is calculated as:

$$\frac{\partial F_i}{\partial \psi_i} = \alpha \left(\psi_i^{\dagger} \cdot \phi_i \right) \phi_i^{\dagger} - \frac{\beta}{2} \psi_i^{\text{cr}\dagger} + \frac{\gamma}{2} \psi_i^{\text{bk}\dagger}.$$

where F_i depends on the complex output vector ψ_n and its conjugate transpose ψ_n^* . A small change in the *m*-th phase mask, $P_m \rightarrow P_m + \delta P_m$, induces a change in the transfer matrix:

$$\delta S = (B_M A \cdots B_{m+1} A) \cdot \delta B_m \cdot (A B_{m-1} \cdots A B_1) = S_{>} \cdot \delta B_m \cdot S_{<}.$$

where A is a free-space propagation matrix. This change modifies the output fields as:

$$\delta\psi_i=\delta S\cdot\chi_i,$$

where χ_i is the input field. Consequently, the objective function changes as:

$$\delta F_T = \sum_{i=1}^N \left[\frac{\partial F}{\partial \psi_i} \cdot \delta \psi_i + \delta \psi_i^* \cdot \frac{\partial F}{\partial \psi_i^*} \right].$$

Using the property that $a + a^* = 2\Re(a)$ for a complex number a, this simplifies to:

$$\delta F_T = 2\Re \left[\sum_{i=1}^N \frac{\partial F}{\partial \psi_i} \cdot \delta \psi_i \right].$$

Substituting $\delta \psi_i$ into this expression, we get:

$$\delta F_T = 2\Re \left[\sum_{i=1}^N \left(\frac{\partial F}{\partial \psi_i} \cdot S_{>} \right) \cdot \delta P_m \cdot (S_{<} \cdot \chi_i) \right].$$

Writing this in terms of pixel-by-pixel contributions, the change becomes:

$$\delta F_T = 2 \sum_{p=1}^P \Re \left[(\delta P_m)_{p,p} \sum_{i=1}^N (v_{i,<})_p (v_{i,>})_p \right],$$

where $v_{i,<} = S_{<} \cdot \chi_i$ and $v_{i,>} = \frac{\partial F}{\partial \psi_i} \cdot S_{>}$. Using $P_m = \text{diag}[e^{i\theta_{m,p}}]$, the change in the phase of each pixel is given by:

$$\delta P_m = \text{diag}[i\delta\theta_{m,p}e^{i\theta_{m,p}}],$$

and we have:

$$\delta F_T = -2\sum_{p=1}^P \delta\theta_{m,p} \Im \left[e^{i\theta_{m,p}} \sum_{i=1}^N a_i(v_{i,<})_p(v_{i,>})_p \right].$$

To ensure $\delta F_T > 0$, we choose:

$$\operatorname{sign}(\delta\theta_{m,p}) = -\operatorname{sign}\left\{\Im\left[e^{i\theta_{m,p}}\sum_{i=1}^{N}a_{i}(v_{i,<})_{p}(v_{i,>})_{p}\right]\right\}.$$

An incremental adjustment to the phase plane, δP_m , is made by applying a small phase change of fixed magnitude, $\delta\theta$, to each pixel. The sign of $\delta\theta$ is determined individually for each pixel to ensure that all contributions are positive, thereby increasing the objective function.

We can use this algorithm with previous configuration. The original algorithm can be found in [1]. The following code is modified version so that it matches with previous configuration.

```
n_of_modes = 10 # number of modes to sort
2 Planes = 10 # number of phase masks to design
3 iterations = 50 # number of iterations to run for (number of times each phase mask gets
      updated during the design process)
5 # Alpha, beta and gamma factors to adjust the objective function
6 \text{ alpha} = 1.0
7 \text{ beta} = 2.0
8 \text{ gamma} = 0.0
_{10} first_n_iterations = 10 \# use a bigger step size for the first 10 iterations
11 delta_theta_1 = 2*math.pi/255 # usual step size
12 delta_theta_0 = delta_theta_1*10 # bigger step size
Nx = 128 \# resolution of a field of view in pixels (x)
15 Ny = 128 # resolution of a field of view in pixels (y)
16 pixelSize = 11.72e-6 # pixel pitch, in m (chosen to match a pixel pitch of the Hamamatsu
     X13138-01 SLM)
wavelength = 633.e-9 # wavelength, in m
19 reprW = Nx*pixelSize # physical width of a field of view, in m
20 reprH = Ny*pixelSize # physical height of a field of view, in m
  d_{in} = 0e-3 \text{ \# free-space propagation distance from the plane where all the inputs are
      generated to the first phase mask of the MPLC, in m (used to simulate inputs being
      slightly defocused)
  d = 0.015 # free-space propagation distance between each pair of phase masks, in m
25 calc_perf_every_it = 10 # calculate and print out sorter's performance every 10 iterations
26 crs_delta = 0.0001*calc_perf_every_it # stop the algorithm before the target number of
      iterations has been reached if the cross-talk hasn't improved by this amount since the
      last time it has been calculated
27
  equalize_efficiency = 1 # 1 - on, 0 - off. sometimes the algorithm gets pulled towards sorting
      some of the modes from a set more efficiently than the other ones. use
      equalize_efficiency = 1 to compensate this.
29 plot_eff_distribution = 0 # plot the efficiency distribution every time sorter's performance
      gets calculated during the design process
smoothing_switch = 0 \# 1 - on, 0 - off. mask the regions of the phase masks where there is
      almost no incedent light.
  \# as usually these regions are next to the edge of the field of view, this also allows to
      prevent light being scattered to the outside of the field of view and coming back from the
       other side
33 OffsetMultiplier = 1 # tweak this to adjust the strength of 'masking' the phase masks
34 maskOffset = OffsetMultiplier*np.sqrt(1e-3/(Nx*Ny*n_of_modes))
37 Speckle_basis = np.stack(generate_hg_modes(x0, y0, w_prime,n_of_modes), axis=0)
  Gaussian_basis = np.stack(create_gaussian_beams(x, y, w, d, central_shift, n_of_modes), axis
43 Gaussian_Masks = np.stack([phi_1, phi_2, phi_3,phi_4, phi_5, phi_6,phi_7, phi_8, phi_9,phi_10
45 # take subsets of the basis arrays in case the number of modes sorted is less than 55.
46 Speckle_basis = Speckle_basis[0:n_of_modes,:,:]
47 Gaussian_basis = Gaussian_basis[0:n_of_modes,:,:]
48 Gaussian_Masks = Gaussian_Masks[0:n_of_modes,:,:]
```

```
_{\rm 50} # convert arrays from numpy ndarrays to torch tensors
51 Speckle_basis_torch = torch.from_numpy(Speckle_basis)
52 Gaussian_basis_torch = torch.from_numpy(Gaussian_basis)
53 Gaussian_Masks_torch = torch.from_numpy(Gaussian_Masks)
55 # if the chosen resolution of the field of view Nx, Ny larger than the resolution input/output
       bases were generated in, pad bases with zeros to match the resolution.
   if Nx \text{ or } Ny > 128:
56
57
       Speckle_basis_torch = nn.functional.pad(Speckle_basis_torch, (int((Nx-128)/2),Nx-128-int((
       Nx-128)/2), int((Ny-128)/2), Ny-128-int((Ny-128)/2)), mode='constant', value = 0)
       Gaussian_basis_torch = nn.functional.pad(Gaussian_basis_torch, (int((Nx-128)/2),Nx-128-int
58
       ((Nx-128)/2), int((Ny-128)/2), Ny-128-int((Ny-128)/2)), mode='constant', value = 0)
       Gaussian_Masks_torch = nn.functional.pad(Gaussian_Masks_torch, (int((Nx-128)/2),Nx-128-int
       ((Nx-128)/2), int((Ny-128)/2), Ny-128-int((Ny-128)/2)), mode='constant', value = 0)
# calculate phi bk - the binary mask outlining the backgroud region where there are no target
      output channels
62 phi_bk = 1 - torch.sum(Gaussian_Masks_torch, axis = 0)
64 # calculate phi_cr - the binary mask outlining all the wrong output channels for each mode in
65 phi_cr = torch.zeros((n_of_modes, Ny, Nx), dtype = torch.double)
66 for i in range(n_of_modes):
      phi_cr[i,:,:] = torch.sum(Gaussian_Masks_torch, axis = 0) - Gaussian_Masks_torch[i,:,:]
68
69 phi = Gaussian_basis_torch
72 # calculate wavenumber and its x, y, z components, create XY coordinate grids
73 k = (2 * np.pi) / wavelength
nx = pixelSize*np.linspace(-(Nx-1)/2, (Nx-1)/2, num=Nx)
76 ny= pixelSize*np.linspace(-(Ny-1)/2, (Ny-1)/2, num=Ny)
X,Y = np.meshgrid(nx,ny)
78 X_torch = torch.from_numpy(X)
79 Y_torch = torch.from_numpy(Y)
nx = np.linspace(-(Nx-1)/2, (Nx-1)/2, num=Nx)
ny = np.linspace(-(Ny-1)/2, (Ny-1)/2, num=Ny)
83 kx, ky = np.meshgrid(2*np.pi*nx/(Nx*pixelSize),2*np.pi*ny/(Ny*pixelSize))
kz = np.sqrt(k**2 - (kx**2 + ky**2))
85 kz = kz.astype(np.cdouble)
86 kz_torch = torch.from_numpy(kz)
88 # Transfer function of free-space propagation
89 HO = transfer_function_of_free_space(x, y, z, wvl)
92 Masks = torch.zeros((Planes,Ny,Nx)) \# use zero phases as starting guesses for the phase masks
93 Masks_complex = torch.exp(1j*Masks) # complex representation of the phase masks with amplitude
       = 1 everywhere
95 # create placeholder arrays to store every input and every output field in each plane
96 Modes_in = torch.zeros((Planes, n_of_modes, Ny, Nx), dtype = torch.cdouble)
97 Modes_out = torch.zeros((Planes, n_of_modes, Ny, Nx), dtype = torch.cdouble)
99 overlap = torch.zeros((n_of_modes), dtype = torch.cdouble)
100 eff_distribution = torch.ones((n_of_modes), dtype = torch.double)
101 dFdpsi = torch.zeros((Planes, n_of_modes, Ny, Nx), dtype = torch.cdouble)
102 crs_array_convergence = torch.zeros((iterations//calc_perf_every_it), dtype = torch.double)
103 conv_count = 0
104
_{105} # store input modes directly in front of the 1st phase plane of the MPLC
Modes_in[0, :, :, :] = propagate_HK(Speckle_basis_torch, H0)
  # store output modes straight after the last phase plane of the MPLC. We simulate a system
       where the last plane of the MPLC and the output plane are separated by a Fourier transform
Modes_out[Planes-1, :, :, :] = propagate_HK(Gaussian_basis_torch, H0)
109
110 # iterate
for i in range(1, iterations+1):
112
       # change the step size depending on the current iteration number
113
       if i < first_n_iterations:</pre>
114
         delta_theta = delta_theta_0
115
```

```
116
           else:
                  delta_theta = delta_theta_1
118
            # update all the phase masks on this iteration in an ascending order
119
120
           for mask_ind in range(Planes):
                  # propagate_HK input modes forward up to the last plane
122
                  modes = torch.zeros((n_of_modes, Ny, Nx), dtype = torch.cdouble)
123
                  for pl in range(Planes-1):
124
                         125
            the incoming modes at once
                        modes = propagate_HK(modes, H0) # propagate_HK all the modes at once distance d
126
            through free space
127
                        Modes_in[pl+1, :, :, :] = modes
                  modes_forw_last_plane = Modes_in[Planes-1, :, :, :]*Masks_complex[Planes-1, :, :] #
128
                  psi = modes\_forw\_last\_plane \# go from the last plane of the MPLC to the output plane
129
            in a Fourier plane of it
130
                  # calculate differentials of the objective functions dFdpsi for every input-output
131
            pair of modes
132
                  for j in range(n_of_modes):
133
                         overlap = torch.sum(torch.squeeze(psi[j,:,:])*torch.conj(torch.squeeze(phi[j,:,:])
134
                         a = (phi[j, :, :]) * overlap
                         psi\_cr = (torch.squeeze(psi[j,:,:])) *torch.squeeze(phi\_cr[j,:,:])
135
                         psi_bk = (torch.squeeze(psi[j,:,:]))*phi_bk
136
                          dFdpsi[Planes-1,j,:,:] = - alpha*a + (beta*psi\_cr - gamma*psi\_bk)*0.5 \# store dF/ 
            dpsi in the output plane before propagating it back to the phase plane of interest
138
                  {\tt dFdpsi[Planes-1,:,:,:]} \; = \; {\tt dFdpsi[Planes-1,:,:,:]} \; \# \; {\tt get} \; \; {\tt from} \; \; {\tt the} \; \; {\tt output} \; \; {\tt plane} \; \; {\tt to} \; \; {\tt the} \; \; {\tt the} \; \; {\tt output} \; \; {\tt plane} \; \; {\tt to} \; \; {\tt the} \; \; {\tt output} \; \; {\tt plane} \; \; {\tt to} \; \; {\tt the} \; \; {\tt output} \; \; {\tt plane} \; \; {\tt to} \; \; {\tt the} \; \; {\tt output} \; \; {\tt plane} \; \; {\tt to} \; \; {\tt the} \; \; {\tt output} \; \; {\tt plane} \; \; {\tt to} \; \; {\tt the} \; \; {\tt output} \; \; {\tt plane} \; \; {\tt to} \; \; {\tt the} \; \; {\tt the} \; \; {\tt output} \; \; {\tt the} \; \; {\tt output} \; \; {\tt plane} \; \; {\tt the} \; \; {\tt output} \; \; {\tt the} \; \; {\tt output} \; \; {\tt the} \; \; {\tt output} \; \; {\tt out
139
            last plane of the MPLC
140
                  # propagate_HK dF/dpsi back through the MPLC up to the phase plane of interest and
            store it in every intermediate plane
142
                  for pl in range(Planes-1, mask_ind, -1):
                         dFdpsi_prop = dFdpsi[pl,:,:,:]*torch.conj(Masks_complex[pl,:,:]) # subtract
143
            phase mask from the fields propagate_HKd backwards
                        dFdpsi_prop = propagate_HK(dFdpsi_prop, np.conj(H0)) # propagate_HK fields
            distance -d backwards
145
                         dFdpsi[pl-1, :, :, :] = dFdpsi_prop
                         # do the same not only to the dF/dpsi arrays, but also to the actual output modes
147
            phi as this will be needed to apply smoothing
                         phi_prop = Modes_out[pl, :, :]*torch.conj(Masks_complex[pl, :, :])
148
                         phi_prop = propagate_HK(phi_prop, np.conj(H0))
149
                         Modes_out[pl-1, :, :, :] = phi_prop
150
151
                  # if equalize_efficiency is on, make a sum in (1) a weighted sum, where the weights
152
            are 1/(relative_efficiency_i) for each particular mode
                  if equalize_efficiency == 1:
153
154
                         weighted_overlaps = torch.zeros((Nx,Ny), dtype = torch.cdouble)
                         for mode in range(n_of_modes):
155
156
                                weighted_overlaps = weighted_overlaps + (1/eff_distribution[mode])*torch.
            : ]))
                         delta_P = delta_theta*torch.sign(torch.imag(Masks_complex[mask_ind]*
157
            weighted_overlaps))
158
                        delta_P = delta_theta*torch.sign(torch.imag(Masks_complex[mask_ind]*torch.sum(
            torch.squeeze(Modes_in[mask_ind, :, :, :])*torch.conj(torch.squeeze(dFdpsi[mask_ind, :, :,
              :])), axis = 0)))
160
                  # if smoothing_switch is on, mask the regions of the phase masks where there is
161
            almost no incedent light, based on the overlap of input and output modes at this plane
                  if smoothing_switch == 1:
162
163
                                ovrlp_in_out = torch.abs(torch.sum(torch.squeeze(Modes_in[mask_ind, :, :, :]*
            torch.conj(Modes_out[mask_ind, :, :, :])), axis = 0))
                                # add phase delta_P to a current guess of the certain phase mask.
164
165
                                # for a complex representation, set an overlap of inputs/outputs as an
            amplitude for a resulting phase
                                mask_cmplx = ovrlp_in_out*torch.exp(1j*(Masks[mask_ind, :, :] + delta_P))
166
                                mask\_cmplx = mask\_cmplx + maskOffset \# add a real-valued offset to mask the
            regions with almost no incident light
```

```
Masks[mask_ind, :, :] = torch.angle(mask_cmplx) # take a phase of a result and
168
        store it as a current guess of a certain phase mask
          # if smoothing_switch is off, just add phase delta_P to a current guess of the
       certain phase mask
170
           else:
               Masks[mask_ind, :, :] = Masks[mask_ind, :, :] + delta_P
172
           # store the resulting current guess of the phase mask as a complex array, with
       amplitude = 1 everywhere
174
           Masks_complex[mask_ind, :, :] = torch.exp(1j*torch.squeeze(Masks[mask_ind, :, :]))
175
176
       # calculate and print out sorter's performance after every iteration (or every K
177
       iterations to save time)
       if i % calc_perf_every_it == 0:
178
179
           # propagate_HK all the input modes through the MPLC system after all of the phase
       masks were updated
180
           # on the current iteration to calculate sorter's performance
           for pl in range(Planes-1):
181
               modes = Modes_in[pl, :, :, :]*Masks_complex[pl, :, :]
182
               modes = propagate_HK(modes, H0)
183
               Modes_in[pl+1, :, :, :] = modes
184
185
           modes = modes*Masks_complex[Planes-1,:,:] # add the last phase mask
           psi = modes \# go from the last plane of the MPLC to the output plane
187
           psi_int_only = (torch.abs(psi))**2 # intensities in the output plane
188
           # calculate and print out sorter's performance
190
           # return an average localized fidelity and a full list of localized fidelities
           fid, fid_list = performance_loc_fidelity(psi, Gaussian_Masks_torch, phi)
192
           # return an average cross-talk, a list of average cross-talks for each mode and a
193
       cross-talk matrix
194
           crs, crs_list, crs_matrix = performance_crosstalk(psi_int_only, Gaussian_Masks_torch)
           # return an average efficiency and a full list of efficiencies
           eff, eff_list = performance_efficiency(psi_int_only, Gaussian_Masks_torch)
196
197
          print('iteration', i, ': loc. fidelity =', round(fid.detach().numpy().item(),2), ',
198
       crosstalk =', round(crs.detach().numpy().item(),2), ', efficiency =', round(eff.detach().
       numpy().item(),2))
          crs_array_convergence[conv_count] = crs # store calculated cross-talk to an array to
199
       then plot it against the number of iterations
200
           # stop iterating if the algorithm is no longer improving cross-talk by more than a
201
       certain value after a certain iteration
           if i > (iterations/3) and (crs_array_convergence[conv_count-1] - crs_array_convergence
202
       [conv_count]) < crs_delta:</pre>
203
              break
           conv count = conv count + 1
204
205
           # store a list of a relative efficiency of every output on the current iteration to
206
       try to equalize them on the next run
           if equalize_efficiency == 1:
207
               eff_distribution = eff_list/torch.max(eff_list)
208
               # plot efficiency distribution if plot_eff_distribution is on
209
               if plot_eff_distribution == 1:
                   plt.plot(eff_distribution)
211
                   plt.title('efficiency distribution')
212
213
                   plt.ylim((0,1))
214
                   plt.show()
216 # calculate and print out sorter's performance after the last iteration
217 fid, fid_list = performance_loc_fidelity(psi, Gaussian_Masks_torch, phi)
218 crs, crs_list, crs_matrix = performance_crosstalk(psi_int_only, Gaussian_Masks_torch)
219 eff, eff_list = performance_efficiency(psi_int_only, Gaussian_Masks_torch)
221 print('Final performance: loc. fidelity =', round(fid.detach().numpy().item(),3), ', crosstalk
        =', round(crs.detach().numpy().item(),3),', efficiency =', round(eff.detach().numpy().
```

With same configuration that is 10 HG modes, 10 phase mask plane and 50 iteration we achieved %88 fidelity and maximum % 3 cross-talk.

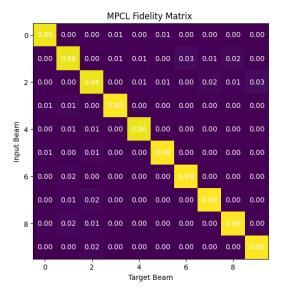


Figure 7 Fidelity Matrix of GAB

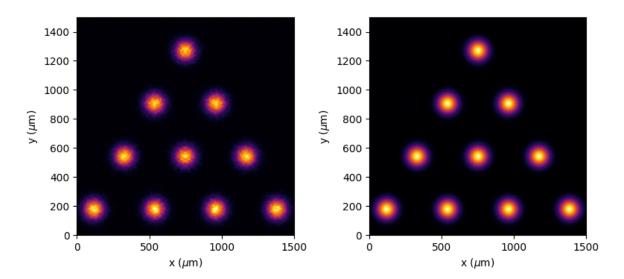


Figure 8 Sum of all the intensities of (on the left) output mode and (on the right) desired output using HG basis with GAB algorithm

Comparison Between Gradient Ascent and Wavefront Matching

The wavefront matching method (WMM) optimizes the overlap between the target output modes ϕ_i and the actual output modes ψ_i . The objective function is defined as

$$F_T = \left| \sum_{i=1}^N \left(\phi_i^* \psi_i \right) \right|^2.$$

Substituting $\psi_n = S \cdot \chi_n$ and factoring S into components that isolate the m-th phase mask, we have

$$F_T = \left| \sum_{i=1}^N \phi_i^* S \chi_i \right|^2 = \left| \sum_{i=1}^N v_{i,>} \cdot P_m \cdot v_{i,<} \right|^2.$$

Expanding this as a sum over pixels p, the function becomes

$$F_T = \left| \sum_{p=1}^P e^{i\theta_{m,p}} \sum_{i=1}^N (v_{i,>})_p (v_{i,<})_p \right|^2.$$

The phase for each pixel is updated as

$$\theta_{m,p} = -\arg \left[\sum_{i=1}^{N} (v_{i,>})_{p} (v_{i,<})_{p} \right].$$

The optimal phase values for all P pixels on plane m can be calculated simultaneously using this method, with the wavefront matching method (WFM) iteratively cycling through all M planes until convergence.

WFM shares similar forward and backward field propagation steps with the gradient ascent optimizer, as both are forms of adjoint optimization. However, unlike gradient ascent, which computes δF_T and incrementally adjusts the phase of each plane, WMM directly computes larger, spatially varying phase changes for each plane in one step. This direct computation allows WFM to converge more rapidly compared to gradient ascent.

It is important to note that this direct calculation of optimal phase adjustments is feasible only for objective functions based on maximizing the overlap integral between output and target spatial modes.

Conclusion

Multi-Plane Light Conversion (MPLC) is a powerful technique for manipulating optical fields, offering precise transformations between spatial modes through phase mask optimization. This report presented two algorithms, the Wavefront Matching Method (WFM) and the Gradient Ascent-Based (GAB) method, for computing the phase masks necessary for spatial mode sorting.

The WFM demonstrated rapid convergence due to its direct computation of optimal phase adjustments, achieving 90% fidelity with minimal cross-talk (<3%) for Hermite-Gaussian (HG) modes. In contrast, the GAB method offered a flexible approach to balancing fidelity, cross-talk suppression, and efficiency, achieving comparable performance (88% fidelity) but requiring more iterations due to its incremental phase update mechanism. Both algorithms underscore the importance of optimizing phase masks to enhance light control for applications in imaging, quantum optics, and optical communications.

By comparing the algorithms, this study highlighted that while WFM is computationally efficient for scenarios prioritizing overlap integral maximization, GAB provides a more customizable framework for diverse objective functions. The findings demonstrate the versatility of MPLC in achieving highperformance mode sorting, paving the way for further innovations in optical system design and implementation.

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